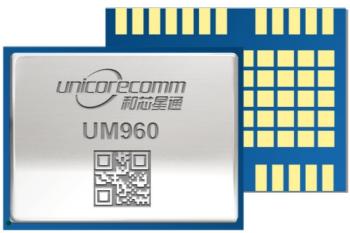


# unicorecomm UM960L All Constellation Multi Frequency High Precision RTK Positioning Module User Manual

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### **Revision History**

Version	Revision History	Date
R1.0	First release	Aug., 2022

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### **Foreword**

This document describes the information of the hardware, package, specification and the use of Unicore UM960L modules.

### **Target Readers**

This document applies to technicians who possess the expertise on GNSS receivers.

#### **Contents**

- 1 Introduction
- 2 Hardware
- 3 Hardware Design
- **4 Production**

Requirement

- 5 Packaging
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### Introduction

UM960L is a new generation of GNSS high precision positioning RTK module from Unicore. It supports all constellations and multiple frequencies, and can simultaneously track GPS L1/L2/L5 + BDS B1I/B2I/B3I + GLONASS L1/L2+Galileo E1/E5a/E5b + QZSS L1/L2/L5. The module is mainly used in geological hazard monitoring, deformation monitoring, and high precision GIS.

UM960L is based on NebulasIVTM, a GNSS SoC which integrates RF-baseband and high precision algorithms. Besides, the SoC integrates a 2 GHz dual CPU, a high speed floating point processor and a RTK co-processor with 22 nm low power design, and it supports 1408 super channels. All these above enable stronger signal processing.

UM960L features a compact size of 16.0 mm  $\times$  12.2 mm. It adopts SMT pads, supports standard pick-and-place, and supports fully automated integration of reflow soldering.

Furthermore, UM960L supports interfaces such as UART, I2C, which meets the customers' needs in different applications.

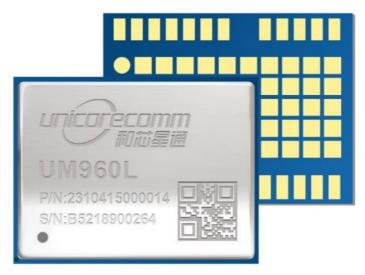


Figure 1-1 UM960L Module

Reserved interface, not supported currently.

### **Key Features**

- High precision, compact size and low power consumption
- Based on the new generation GNSS SoC -NebulasIVTM, with RF-baseband and high precision algorithms integrated
- 16.0 mm × 12.2 mm × 2.4 mm, surface-mount device
- Supports all-constellation multi-frequency on-chip RTK positioning solution
- Supports GPS L1/L2/L5 + BDS B1I/B2I/B3I + GLONASS L1/L2 + Galileo E1/E5b/E5a + QZSS L1/L2/L5
- All constellations and multiple frequencies RTK engine, and advanced RTK processing technology
- Independent track of each frequency, and 60 dB narrowband anti-jamming

### **Key Specifications**

**Table 1-1 Technical Specifications** 

#### **Basic Information**

Channels	1408 channels, based on NebulasIVTM
Constellations	GPS/BDS/GLONASS/Galileo/QZSS
Frequency	GPS: L1C/A, L2P(W), L2C, L5 BDS: B1I, B2I, B3IGLONASS: L 1C/A, L2C/AGalileo: E1, E5b, E5a QZSS: L1, L2, L5

### **Power**

Voltage	+3.0 V to +3.6 V DC	
Power Consumption	410 mW Typical	

### **Performance**

	Single Point Positioning (RMS)		Horizontal: 1.5 m		
			Vertical: 2.5 m		
Positioning Accuracy	DGPS (RMS)		Horizontal: 0.4 m		
1 Ostiloning Accuracy	Dai o (riivio)		Vertical: 0.8 m		
	RTK (RMS)		Horizontal: 0.8 cr	m + 1 ppm	
	TTTTC (TIIVIO)		Vertical: 1.5 cm + 1 ppm		
Observation Accuracy RMS	BDS	GPS	GLONASS	Galileo	
B1I/ L1C/A /G1/E1 Pseudorange	10 cm	10 cm	10 cm	10 cm	
B1I/ L1C/A /G1/E1 Carrier Phase	1 mm	1 mm	1 mm	1 mm	
B2I/L2P/G2/E5b Pseudorange	10 cm	10 cm	10 cm	10 cm	
B2I/L2P/G2/E5b Carrier Phase	1 mm	1 mm	1 mm	1 mm	
Time Accuracy (RMS)	20 ns				
Velocity Accuracy (RMS)	0.03 m/s				
Time to First Fix (TTFF)	Cold Start < 30 s				
Initialization Time	< 5 s (Typical)				
Initialization Reliability	> 99.9%				
Data Update Rate	5 Hz Positioning				
Differential Data	RTCM 3.0, 3.2, 3.3				
Data Format	NMEA-0183; Unicore				

### **Physical Specifications**

Package	24 pin LGA
Dimensions	16.0 mm × 12.2 mm × 2.4 mm

### **Environmental Specifications**

Operating Temperature	-40 ° C to +85 ° C
Storage Temperature	-55 ° C to +95 ° C
Humidity	95% No condensation
Vibration	GJB150.16A-2009; MIL-STD-810F
Shock	GJB150.18A-2009; MIL-STD-810F

### **Functional Ports**

- UART x 3
- I2C x 1

#### **Interfaces**

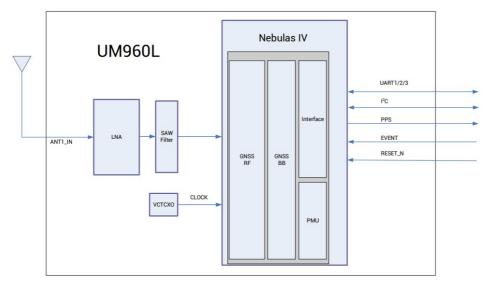


Figure 1-2 UM960L Block Diagram

### RF Part

The receiver gets filtered and enhanced GNSS signal from the antenna via a coaxial cable. The RF part converts the RF input signals into the IF signal, and converts IF analog signal into digital signals required for NebulasIVTM chip.

#### NebulasIVTM SoC

NebulasIVTM is UNICORECOMM's new generation high precision GNSS SoC with 22 nm low power design, supporting all constellations, multiple frequencies and 1408 super channels. It integrates a 2 GHz dual CPU, a

high speed floating point processor and an RTK co-processor, which can fulfill the high precision baseband processing and RTK positioning independently.

### • 1PPS

UM960L outputs 1 PPS with adjustable pulse width and polarity.

### Event

UM960L provides 1 Event Mark Input with adjustable frequency and polarity.

### • Reset (RESET\_N)

Active LOW, and the active time should be no less than 5 ms.

### Hardware

### **Dimensions**

**Table 2-1 Dimensions** 

Symbol	Min. (mm)	Typ. (mm)	Max. (mm)
Α	15.80	16.00	16.50
В	12.00	12.20	12.70
С	2.20	2.40	2.60
D	0.90	1.00	1.10
Е	0.20	0.30	0.40
F	1.40	1.50	1.60
G	1.00	1.10	1.20
Н	0.70	0.80	0.90
N	2.90	3.00	3.10
Р	1.30	1.40	1.50
R	0.99	1.00	1.10
Х	0.72	0.82	0.92
φ	0.99	1.00	1.10

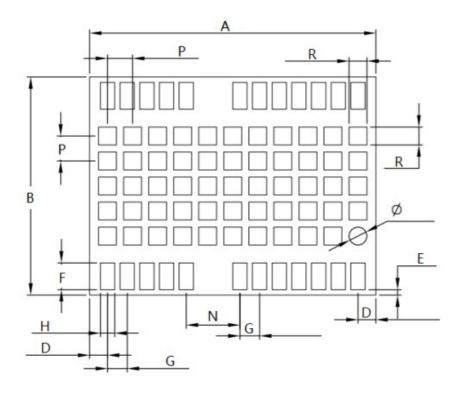




Figure 2-1 UM960L Mechanical Dimensions

### **Pin Definition**

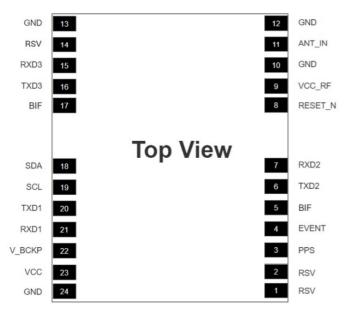


Figure 2-2 UM960L Pin Definition

**Table 2-2 Pin Definition** 

No.	Pin	I/O	Description
1	RSV	_	Reserved, must be floating; cannot connectground or power su pply or peripheral I/O
2	RSV	_	Reserved, must be floating; cannot connectground or power su pply or peripheral I/O
3	PPS	0	Pulse per second
4	EVENT	1	Event Mark
5	BIF	_	Built-in function; recommended to add a through-hole testing p oint and a 10 k $\Omega$ pull-up resistor; cannot connect ground or po wersupply or peripheral I/O, but can be floating.
6	TXD2	0	UART2 transmitting data
7	RXD2	I	UART2 receiving data
8	RESET_N	I	System resetActive Low
9	VCC_RF1	0	External LNA power supply
10	GND	_	Ground
11	ANT_IN	I	GNSS antenna signal input
12	GND	_	Ground
13	GND	_	Ground
14	RSV	_	Reserved, must be floating; cannot connectground or power su pply or peripheral I/O
15	RXD3	I	UART3 receiving data
16	TXD3	0	UART3 transmitting data
17	BIF	_	Built-in function; recommended to add a through-hole testing p oint and a 10 k $\Omega$ pull-up resistor; cannot connect ground or po wersupply or peripheral I/O, but can be floating.
18	SDA	I/O	I2C data
19	SCL	I/O	I2C clock

20	TXD1	0	UART1 transmitting data
21	RXD1	I	UART1 receiving data
22	V_BCKP2	I	When the main power supply VCC is cut off, V_BCKP supplies power to RTC and relevant register. Level requirements: 2.0 V ~ 3.6 V, and the working current is less than 60 µA at25 °C. If y ou do not use the hot start function, connect V_BCKP to VCC. Do NOT connect it toground or leave it floating.
23	VCC	I	Supply voltage
24	GND	_	Ground

- 1. Not recommended to take VCC\_RF as ANT\_BIAS to feed the antenna See section 3.1 for more details.
- 2. Not supported currently, and keep this pin floating.

### **Electrical Specifications**

### **Absolute Maximum Ratings**

**Table 2-3 Absolute Maximum Ratings** 

Parameter	Symbol	Min.	Max.	Unit
Power Supply (VCC)	VCC	-0.3	3.6	V
Voltage Input	Vin	-0.3	3.6	V
GNSS Antenna Signal Input	ANT_IN	-0.3	6	V
RF Input PowerConsumption of A ntenna	ANT_IN inputpower		+10	dBm
External LNA Power Supply	VCC_RF	-0.3	3.6	V
VCC_RF Output Current	ICC_RF		100	mA
Storage Temperature	Tstg	-55	95	°C

### **Operational Conditions**

### **Table 2-4 Operational Conditions**

Parameter	Symbol	Min.	Тур.	Max.	Unit	Condition
Power Supply (VCC)	VCC	3.0	3.3	3.6	V	
Maximum Ripple Voltage	Vrpp	0		50	mV	
Working Current3	lopr		109	218	mA	VCC = 3.3 V
VCC_RF Output Voltage	VCC_RF		VCC-0.1		V	
VCC_RF Output Current	ICC_RF			50	mA	
Operating Temperature	Topr	-40		85	°C	
Power Consumption	Р		410		mW	

### **IO Threshold**

### Table 2-5 IO Threshold

Parameter	Symbol	Min.	Тур.	Max.	Unit	Condition
Low Level InputVoltag e	Vin_low	0		VCC × 0.2	V	
High Level InputVoltag e	Vin_high	VCC × 0.7		VCC + 0.2	V	
Low Level OutputVolta ge	Vout_low	0		0.45	V	lout= 4 mA
High Level OutputVolt age	Vout_high	VCC - 0.45		VCC	V	lout =4 mA

### **Antenna Feature**

### **Table 2-6 Antenna Feature**

Parameter	Symbol	Min.	Тур.	Max.	Unit	Condition
Optimum Input Gain	Gant	18	30	36	dB	

Since the product has capacitors inside, inrush current occurs during power-on. You should evaluate in the actual environment in order to check the effect of the supply voltage drop caused by inrush current in the system.

### **Hardware Design**

### **Antenna Feed Design**

UM960L just supports feeding the antennal from the outside of the module rather than the inside. It is

recommended to use devices with high power and that can withstand high voltage. Gas discharge tube, varistor, TVS tube and other high-power protective devices may also be used in the power supply circuit to further protect the module from lighting strike and surge.

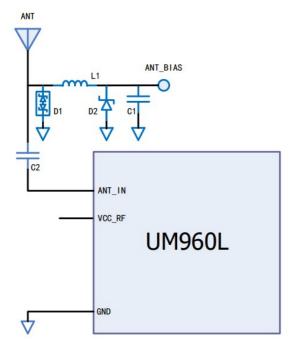
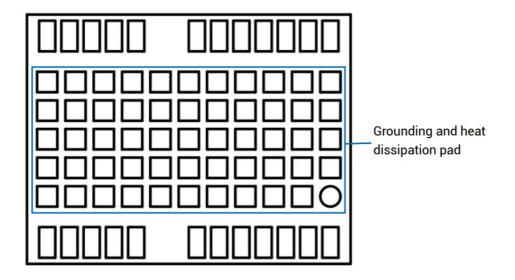


Figure 3-1 UM960L External Antenna Feed Reference Circuit

#### Remarks:

- L1: feed inductor, 68nH RF inductor in 0603 package is recommended;
- C1: decoupling capacitor, it is recommended to connect two capacitors of 100nF/100pF in parallel;
- C2: DC blocking capacitor, recommended 100pF capacitor;
- Not recommended to take VCC\_RF as ANT\_BIAS to feed the antenna (VCC\_RF is not optimized for the antilighting strike and anti-surge due to the compact size of the module)
- D1: ESD diode, choose the ESD protection device that supports high frequency signals (above 2000 MHz)
- **D2:** TVS diode, choose the TVS diode with appropriate clamping specification according to the requirement of feed voltage and antenna voltage

### **Grounding and Heat Dissipation**



### Figure 3-2 Grounding and Heat Dissipation Pad

The 55 pads in the rectangle in Figure 3-2 are for grounding and heat dissipation.

In the PCB design, they must connect to a large sized ground to strengthen the heat dissipation.

#### Power-on and Power-off

### **VCC**

- The VCC initial level when power-on is less than 0.4 V and it has good monotonicity. The voltages of undershoot and ringing are within 5% VCC.
- VCC power-on waveform: The time interval from 10% rising to 90% must be within 100 µs to 1 ms.
- Power-on time interval: The time interval between the VCC < 0.4 V (after power-off) to the next power-on must be larger than 500 ms.

### V BCKP

- The V\_BCKP initial level when power-on is less than 0.4 V and it has good monotonicity. The voltages of undershoot and ringing are within 5% V\_BCKP.
- V\_BCKP power-on waveform: The time interval from 10% rising to 90% must be within 100 μs to 1 ms.
- Power-on time interval: The time interval between the V\_BCKP < 0.4 V (after poweroff) to the next power-on must be larger than 500 ms.

### **Production Requirement**

Recommended soldering temperature curve is as follows:

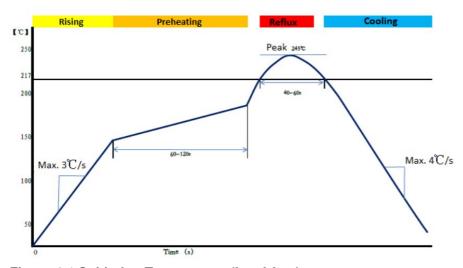


Figure 4-1 Soldering Temperature (Lead-free)

### **Temperature Rising Stage**

• Rising slope: Max. 3 °C/s

Rising temperature range: 50 °C to 150 °C

### **Preheating Stage**

• Preheating time: 60 s to 120 s

Preheating temperature range: 150 ° C to 180 °C

### **Reflux Stage**

• Over melting temperature (217 °C) time: 40 s to 60 s

• Peak temperature for soldering: no higher than 245 ° C

### **Cooling Stage**

• Cooling slope: Max. 4 °C/s

- Lin order to prevent falling off during soldering of the module, do not solder it on the back of the board during design, that is, better not go through soldering cycle twice.
- The setting of soldering temperature depends on many factors of the factory, such as board type, solder paste type, solder paste thickness, etc. Please also refer to the relevant IPC standards and indicators of solder paste.
- Since the lead soldering temperature is relatively low, if using this method, please give priority to other components on the board.
- The opening of the stencil needs to meet your design requirement and comply to the examine standards. The thickness of the stencil is recommended to be 0.15 mm.

### **Packaging**

### **Label Description**



Figure 5-1 Label Description

### **Product Packaging**

The UM960L module uses carrier tape and reel (suitable for mainstream surface mount devices), packaged in vacuum-sealed aluminum foil antistatic bags, with a desiccant inside to prevent moisture. When using reflow soldering process to solder modules, please strictly comply with IPC standard to conduct humidity control. As packaging materials such as the carrier tape can only withstand the temperature of 55 °C, modules shall be removed from the package during baking.



Figure 5-2 UM960L Package

**Table 5-1 Package Description** 

Item	Description
Module Number	500 pieces/reel
Reel Size	Tray: 13"External diameter: 330 mm Internal diameter: 100 mm Width: 24 mmThickness : 2.0 mm
Carrier Tape	Space between (center-to-center distance): 20 mm

The UM960L is rated at MSL level 3. Refer to the relevant IPC/JEDEC J-STD-033 standards for the package and operation requirements. You may access to the website <a href="https://www.jedec.org">www.jedec.org</a> to get more information.

The shelf life of the UM960L module packaged in vacuum-sealed aluminum foil antistatic bags is one year.



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**Documents / Resources** 



## unicorecomm UM960L All Constellation Multi Frequency High Precision RTK Positioning Module [pdf] User Manual

UM960L, All Constellation Multi Frequency High Precision RTK Positioning Module, UM960L All Constellation Multi Frequency High Precision RTK Positioning Module, Multi Frequency High Precision RTK Positioning Module, High Precision RTK Positioning Module, RTK Positioning Module, Positioning Module, Module

### References

- **\*** -200
- <u>U</u> OEM
- **U**\_ OEM

Manuals+,