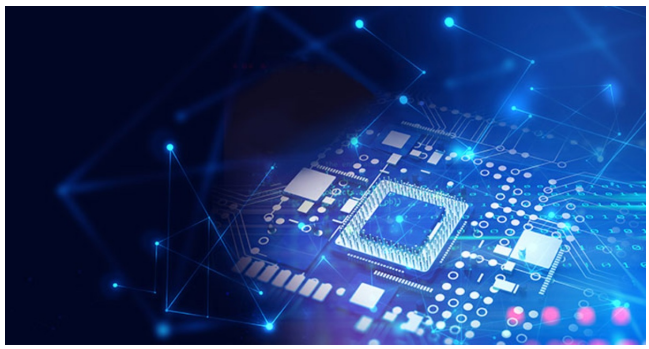

unicore UM960L All Constellation Multi Frequency High Precision Positioning Module User Manual

Contents [hide

1 unicore UM960L All Constellation Multi Frequency High Precision Positioning Module
2 UM960L GPS/BDS/GLONASS/Galileo/QZSS All-constellation Multi-frequency High Precision Positioning Module
2.1 Product Information
2.2 Key Features
2.3 Key Specifications
2.4 Product Usage Instructions
3 Introduction
4 Hardware
4.1 Electrical Specifications
5 Hardware Design
6 Production Requirement
7 Packaging
7.1 Product Packaging
8 Documents / Resources
8.1 References
9 Related Posts

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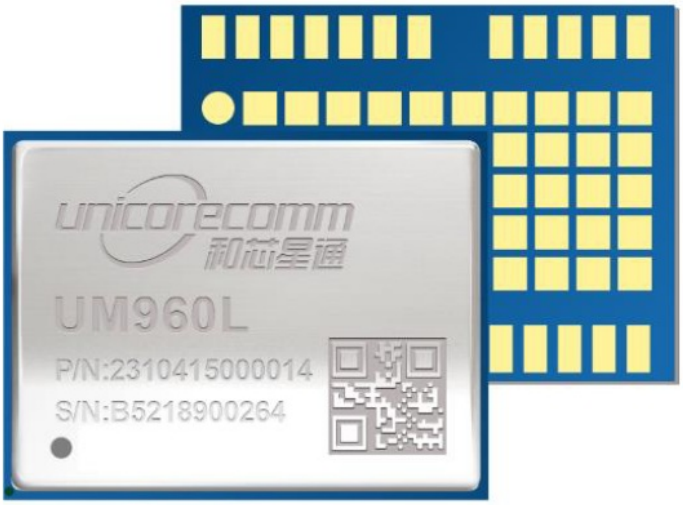

UM960L GPS/BDS/GLONASS/Galileo/QZSS All-constellation Multi-frequency High Precision Positioning Module

Product Information

The UM960L is a high precision positioning module that supports multiple GNSS constellations including GPS, BDS, GLONASS, Galileo, and QZSS. It is based on the new generation GNSS SoC – NebulasIVTM and has 1408 channels. The module is compact in size, low in power consumption and has a high level of accuracy. It supports independent tracking of each frequency and has 60 dB narrowband anti-jamming.

Key Features

- High precision
- Compact size
- Low power consumption
- Supports multiple GNSS constellations including GPS, BDS, GLONASS, Galileo, and QZSS
- Independent track of each frequency
- 60 dB narrowband anti-jamming

Key Specifications

Channels	Constellations	Frequency	Power Voltage	Power Consumption	Positioning Accuracy	Observation Accuracy RMS	Time to First Fix (TTFF)
1408 channels, based on NebulasIVTM	GPS/BDS/GLONASS/Galileo/QZSS	GPS: L1C/A, L2P(W), L2C, L5 BDS: B1I, B2I, B3I, B1C, B2a GLONASS: L1C/A, L2C/A Galileo: E1, E5b, E5a QZSS: L1, L2, L5	3.3V – 5.5V	Max 350 mA	2.5m CEP (GPS/BDS/GLONASS/Galileo/QZSS)	B1I/ L1C/A / G1/E1 Pseudorange B1I/ L1C/A / G1/E1 Carrier Phase B2I/L2P/G2/E5b Pseudorange B2I/L2P/G2/E5b Carrier Phase	<25s (cold start), <3s (hot start)

Product Usage Instructions

The UM960L module can be used in various applications that require high precision positioning such as surveying, mapping and navigation. The following steps can guide you on how to use the module:

1. Connect the module to the power source with a voltage range of 3.3V to 5.5V.
2. Connect the antenna to the module using the interface provided.
3. Configure the module settings to match your application requirements using the interfaces provided.
4. Start collecting data from the module as per your application requirements.

Revision History

Version	Revision History	Date
R1.0	First release	Aug., 2022

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Disclaimer

The information contained in this manual is provided “as is” and is believed to be true and correct at the time of its publication or revision. This manual does not represent, and in any case, shall not be construed as a commitments or warranty on the part of Unicode with respect to the fitness for a particular purpose/use, the accuracy, reliability and correctness of the information contained herein.

Information, such as product specifications, descriptions, features and user guide in this manual, are subject to change by Unicode at any time without prior notice, which may not be completely consistent with such information of the specific product you purchase.

Should you purchase our product and encounter any inconsistency, please contact us or our local authorized distributor for the most up-to-date version of this manual along with any addenda or corrigenda.

Foreword

This document describes the information of the hardware, package, specification and the use of Unicode UM960L modules.

Target Readers

This document applies to technicians who possess the expertise on GNSS receivers.

Introduction

UM960L is a new generation of GNSS high precision positioning RTK module from Unicode. It supports all constellations and multiple frequencies, and can simultaneously track GPS L1/L2/L5 + BDS B1I/B2I/B3I + GLONASS L1/L2+Galileo E1/E5a/E5b + QZSS L1/L2/L5. The module is mainly used in geological hazard monitoring, deformation monitoring, and high precision GIS.

UM960L is based on Nebulas IVTM, a GNSS SoC which integrates RF-baseband and high precision algorithms. Besides, the SoC integrates a 2 GHz dual CPU, a high speed floating point processor and a RTK co-processor with 22 nm low power design, and it supports 1408 super channels. All these above enable stronger signal processing.

UM960L features a compact size of 16.0 mm × 12.2 mm. It adopts SMT pads, supports standard pick-and-place, and supports fully automated integration of reflow soldering.

Furthermore, UM960L supports interfaces such as UART, I2C, which meets the customers’ needs in different applications.

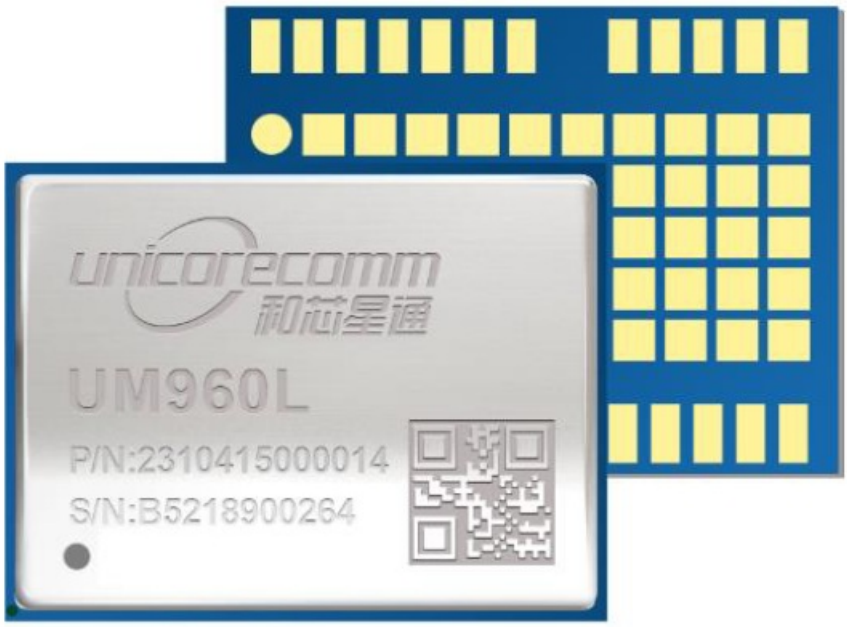


Figure 1 1 UM960L M odule

Reserved interface, not supported currently.

Key Features

- High precision, compact size and low power consumption
- Based on the new generation GNSS SoC -Nebulas IVTM, with RF-baseband and high precision algorithms integrated
- 16.0 mm × 12.2 mm × 2.4 mm, surface-mount device
- Supports all-constellation multi-frequency on-chip RTK positioning solution
- Supports GPS L1/L2/L5 + BDS B1I/B2I/B3I + GLONASS L1/L2 + Galileo E1/E5b/E5a + QZSS L1/L2/L5
- All constellations and multiple frequencies RTK engine, and advanced RTK processing technology
- Independent track of each frequency, and 60 dB narrowband anti-jamming

Key Specifications

Table 1-1 Technical Specifications

Basic Information				
Channels	1408 channels, based on Nebulas IVTM			
Constellations	GPS/BDS/GLONASS/Galileo/QZSS			
Frequency	GPS: L1C/A, L2P(W), L2C, L5 BDS: B1I, B2I, B 3I GLONASS: L1C/A, L2C/A Galileo: E1, E5b, E5a QZSS: L1, L2, L5			
Power				
Voltage	+3.0 V to +3.6 V DC			
Power Consumption	410 mW Typical			
Performance				
	Single Point Positioning (RMS)		Horizontal: 1.5 m	
			Vertical: 2.5 m	
Positioning Accuracy	DGPS (RMS)		Horizontal: 0.4 m	
			Vertical: 0.8 m	
	RTK (RMS)		Horizontal: 0.8 cm + 1 ppm	
			Vertical: 1.5 cm + 1 ppm	
Observation Accuracy RMS	BDS	GPS	GLONASS	Galileo
B1I/ L1C/A /G1/E1 Pseud orange	10 cm	10 cm	10 cm	10 cm
B1I/ L1C/A /G1/E1 Carrier Phase	1 mm	1 mm	1 mm	1 mm

B2I/L2P/G2/E5b Pseud orange	10 cm	10 cm	10 cm	10 cm
B2I/L2P/G2/E5b Carrier Phase	1 mm	1 mm	1 mm	1 mm
Time Accuracy (RMS)	20 ns			
Velocity Accuracy (RMS)	0.03 m/s			
Time to First Fix (TTFF)	Cold Start < 30 s			
Initialization Time	< 5 s (Typical)			
Initialization Reliability	> 99.9%			
Data Update Rate	5 Hz Positioning			
Differential Data	RTCM 3.0, 3.2, 3.3			
Data Format	NMEA-0183; Unicode			
Physical Specifications				
Package	24 pin LGA			
Dimensions	16.0 mm × 12.2 mm × 2.4 mm			
Environmental Specifications				
Operating Temperature	-40 °C to +85 °C			
Storage Temperature	-55 °C to +95 °C			
Humidity	95% No condensation			
Vibration	GJB150.16A-2009; MIL-STD-810F			
Shock	GJB150.18A-2009; MIL-STD-810F			
Functional Ports				
UART x 3				
I2C* x 1				

Interfaces

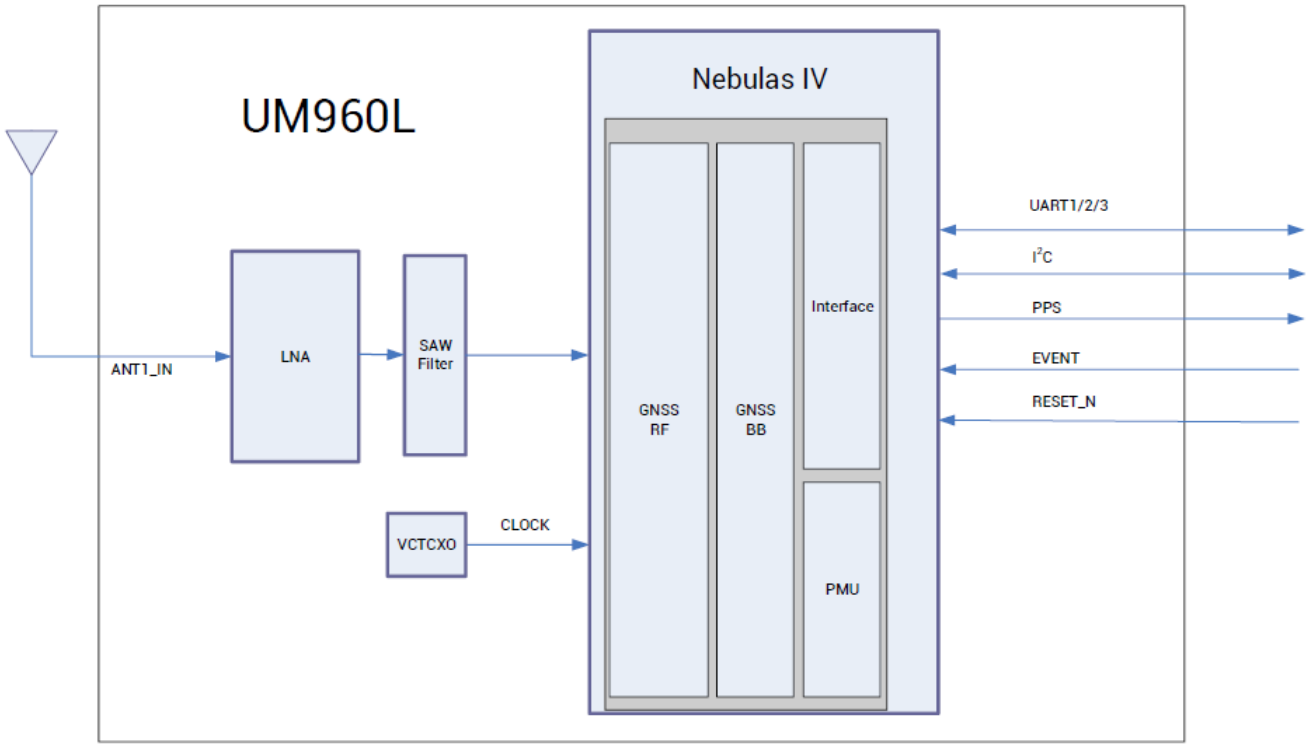


Figure 1-2 UM960L Block Diagram

- RF Part

  The receiver gets filtered and enhanced GNSS signal from the antenna via a coaxial cable. The RF part converts the RF input signals into the IF signal, and converts IF analog signal into digital signals required for NebulasIVTM chip.
- NebulasIVTM SoC

  NebulasIVTM is UNICORECOMM's new generation high precision GNSS SoC with 22 nm low power design, supporting all constellations, multiple frequencies and 1408 super channels. It integrates a 2 GHz dual CPU, a high speed floating point processor and an RTK co-processor, which can fulfill the high precision baseband processing and RTK positioning independently.
- 1PPS

  UM960L outputs 1 PPS with adjustable pulse width and polarity.
- Event

  UM960L provides 1 Event Mark Input with adjustable frequency and polarity.
- Reset (RESET_N)

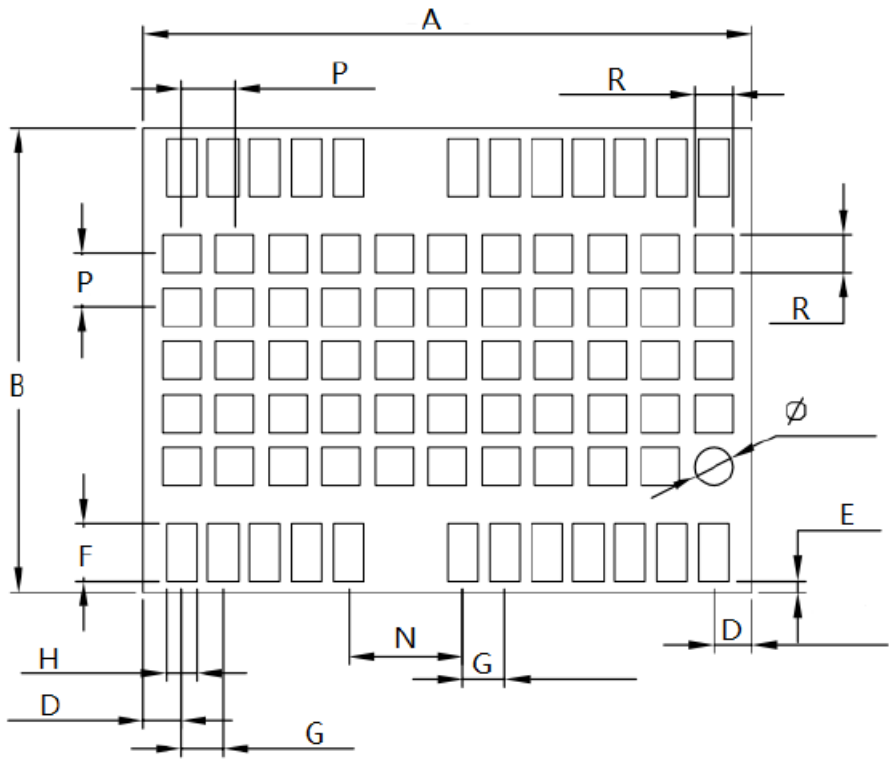
  Active LOW, and the active time should be no less than 5 ms.

Hardware

Dimensions

Table 2-1 Dimensions

Symbol	Min. (mm)	Typ. (mm)	Max. (mm)
A	15.80	16.00	16.50
B	12.00	12.20	12.70
C	2.20	2.40	2.60
D	0.90	1.00	1.10
E	0.20	0.30	0.40
F	1.40	1.50	1.60
G	1.00	1.10	1.20
H	0.70	0.80	0.90
N	2.90	3.00	3.10
P	1.30	1.40	1.50
R	0.99	1.00	1.10
X	0.72	0.82	0.92
φ	0.99	1.00	1.10



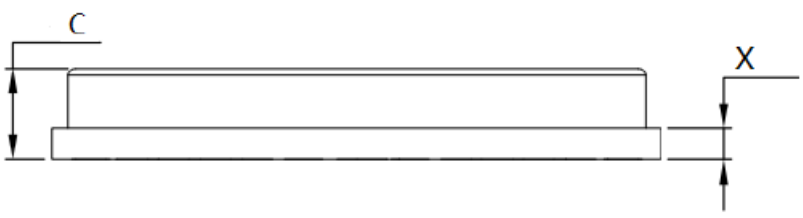


Figure 2 1 UM960L Mechanical Dimensions

Pin Definition

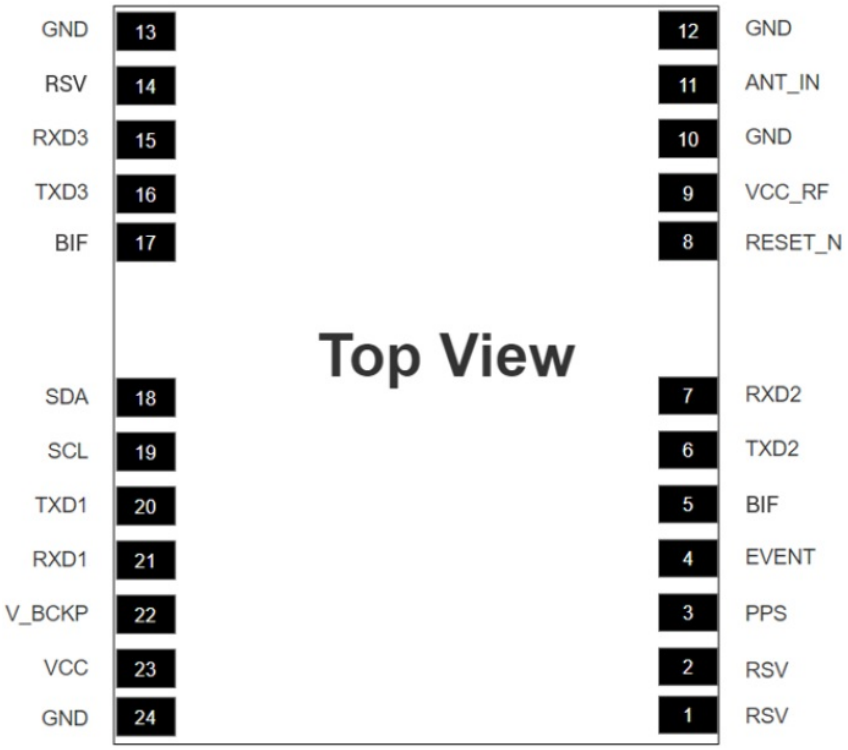


Figure 2 2 UM960L Pin Definition

Table 2-2 Pin Definition

No.	Pin	I/O	Description
1	RSV	—	Reserved, must be floating; cannot connect ground or power s upply or peripheral I/O
2	RSV	—	Reserved, must be floating; cannot connect ground or power s upply or peripheral I/O
3	PPS	O	Pulse per second
4	EVENT	I	Event Mark
5	BIF	—	Built-in function; recommended to add a through-hole testing p oint and a 10 kΩ pull-up resistor; cannot connect ground or po wer supply or peripheral I/O, but can be floating.
6	TXD2	O	UART2 transmitting data
7	RXD2	I	UART2 receiving data

No.	Pin	I/O	Description
8	RESET_N	I	System reset Active Low

9	VCC_RF1	O	External LNA power supply
10	GND	—	Ground
11	ANT_IN	I	GNSS antenna signal input
12	GND	—	Ground
13	GND	—	Ground
14	RSV	—	Reserved, must be floating; cannot connect ground or power s upply or peripheral I/O
15	RXD3	I	UART3 receiving data
16	TXD3	O	UART3 transmitting data
17	BIF	—	Built-in function; recommended to add a through-hole testing p oint and a 10 kΩ pull-up resistor; cannot connect ground or po wer supply or peripheral I/O, but can be floating.
18	SDA	I/O	I2C data
19	SCL	I/O	I2C clock
20	TXD1	O	UART1 transmitting data
21	RXD1	I	UART1 receiving data
22	V_BCKP2	I	When the main power supply VCC is cut off, V_BCKP supplies power to RTC and relevant register. Level requirements: 2.0 V ~ 3.6 V, and the working current is less than 60 μA at 25 °C. If you do not use the hot start function, connect V_BCKP to VCC. Do NOT connect it to ground or leave it floati ng.
23	VCC	I	Supply voltage
24	GND	—	Ground

- Not recommended to take VCC_RF as ANT_BIAS to feed the antenna See section 3.1 for more details.
- Not supported currently, and keep this pin floating.

Electrical Specifications

Absolute Maximum Ratings

Table 2-3 Absolute Maximum Ratings

Parameter	Symbol	Min.	Max.	Unit
Power Supply (VCC)	VCC	-0.3	3.6	V
Voltage Input	Vin	-0.3	3.6	V
GNSS Antenna Signal Input	ANT_IN	-0.3	6	V
RF Input Power Consumption of Antenna	ANT_IN input power		+10	dBm
External LNA Power Supply	VCC_RF	-0.3	3.6	V
VCC_RF Output Current	ICC_RF		100	mA
Storage Temperature	Tstg	-55	95	°C

Operational Conditions

Table 2-4 Operational Conditions

Parameter	Symbol	Min.	Typ.	Max.	Unit	Condition
Power Supply (VCC)	VCC	3.0	3.3	3.6	V	
Maximum Ripple Voltage	Vrpp	0		50	mV	
Working Current3	Iopr		109	218	mA	VCC = 3.3 V
VCC_RF Output Voltage	VCC_RF		VCC-0.1		V	
VCC_RF Output Current	ICC_RF			50	mA	
Operating Temperature	Topr	-40		85	°C	
Power Consumption	P		410		mW	

IO Threshold

Table 2-5 IO Threshold

Parameter	Symbol	Min.	Typ.	Max.	Unit	Condition
Low Level Input Voltage	Vin_low	0		VCC × 0.2	V	
High Level Input Voltage	Vin_high	VCC × 0.7		VCC + 0.2	V	
Low Level Output Voltage	Vout_low	0		0.45	V	Iout= 4 mA
High Level Output Voltage	Vout_ high	VCC – 0.45		VCC	V	Iout =4 mA

Antenna Feature
Table 2-6 Antenna Feature

Parameter	Symbol	Min.	Typ.	Max.	Unit	Condition
Optimum Input Gain	Gant	18	30	36	dB	

- Since the product has capacitors inside, inrush current occurs during power-on. You should evaluate in the actual environment in order to check the effect of the supply voltage drop caused by inrush current in the system.

Hardware Design

Antenna Feed Design
UM960L just supports feeding the antennal from the outside of the module rather than the inside. It is recommended to use devices with high power and that can withstand high voltage. Gas discharge tube, varactor, TVS tube and other high-power protective devices may also be used in the power supply circuit to further protect the module from lighting strike and surge.

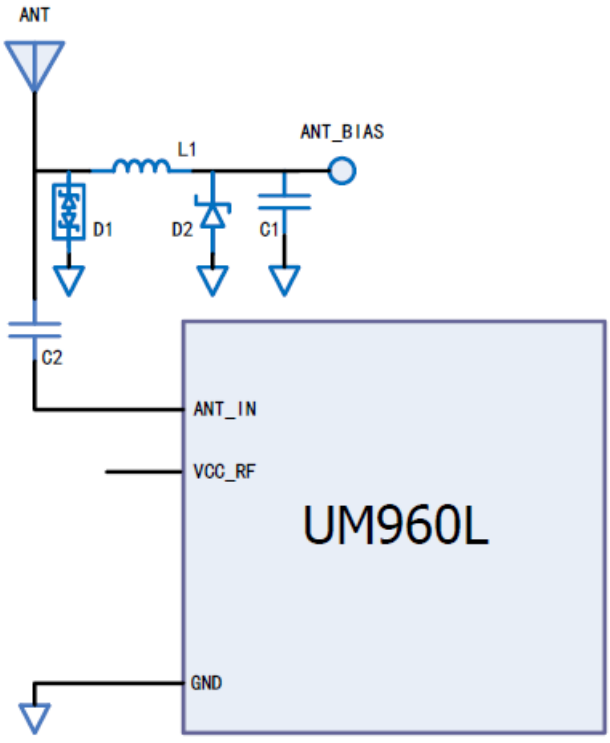


Figure 3-1 UM960L External Antenna Feed Reference Circuit

Remarks:

- L1: feed inductor, 68nH RF inductor in 0603 package is recommended;
- C1: decoupling capacitor, it is recommended to connect two capacitors of 100nF/100pF in parallel;
- C2: DC blocking capacitor, recommended 100pF capacitor;
- Not recommended to take VCC_RF as ANT_BIAS to feed the antenna (VCC_RF is not optimized for the anti-lighting strike and anti-surge due to the compact size of the module)
- D1: ESD diode, choose the ESD protection device that supports high frequency signals (above 2000 MHz)
- D2: TVS diode, choose the TVS diode with appropriate clamping specification according to the requirement of feed voltage and antenna voltage

Grounding and Heat Dissipation

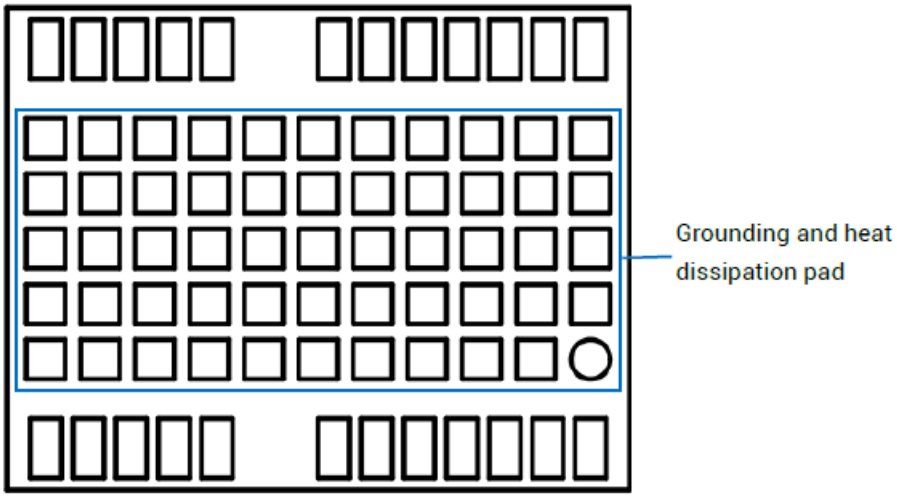


Figure 3-2 Grounding and Heat Dissipation Pad

The 55 pads in the rectangle in Figure 3-2 are for grounding and heat dissipation.
In the PCB design, they must connect to a large sized ground to strengthen the heat dissipation.

Power-on and Power-off
VCC

- The VCC initial level when power-on is less than 0.4 V and it has good monotonicity. The voltages of undershoot and ringing are within 5% VCC.
- VCC power-on waveform: The time interval from 10% rising to 90% must be within 100 μs to 1 ms.
- Power-on time interval: The time interval between the VCC < 0.4 V (after power-off) to the next power-on must be larger than 500 ms.

V_BCKP

- The V_BCKP initial level when power-on is less than 0.4 V and it has good monotonicity. The voltages of undershoot and ringing are within 5% V_BCKP.
- V_BCKP power-on waveform: The time interval from 10% rising to 90% must be within 100 μs to 1 ms.

- Power-on time interval: The time interval between the V_BCKP < 0.4 V (after power-off) to the next power-on must be larger than 500 ms.

Production Requirement

Recommended soldering temperature curve is as follows:

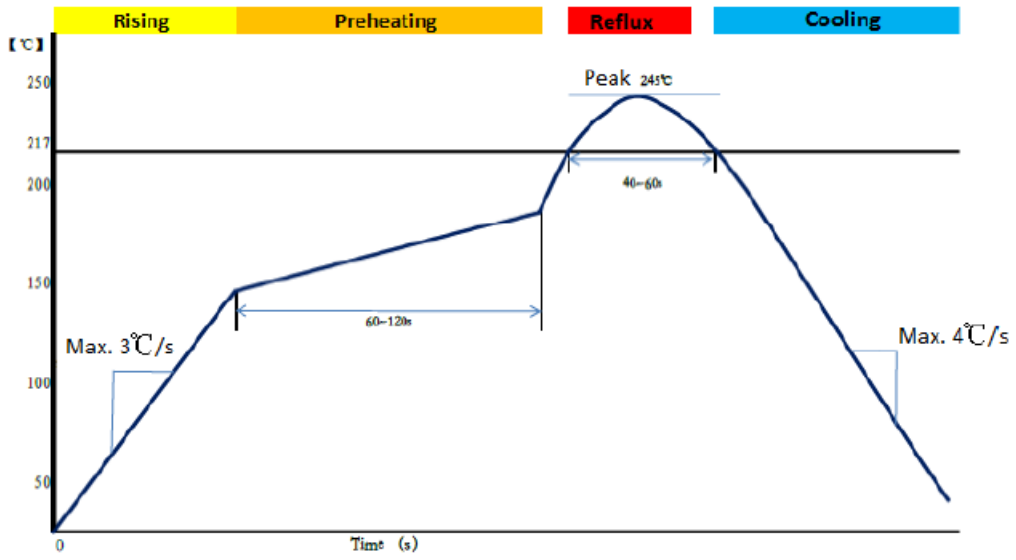


Figure 4-1 Soldering Temperature (Lead-free)

Temperature Rising Stage

- Rising slope: Max. 3 °C/s
- Rising temperature range: 50 °C to 150 °C

Preheating Stage

- Preheating time: 60 s to 120 s
- Preheating temperature range: 150 °C to 180 °C

Reflux Stage

- Over melting temperature (217 °C) time: 40 s to 60 s
- Peak temperature for soldering: no higher than 245 °C

Cooling Stage

- Cooling slope: Max. 4 °C/s
- In order to prevent falling off during soldering of the module, do not solder it on the back of the board during design, that is, better not go through soldering cycle twice.
- The setting of soldering temperature depends on many factors of the factory, such as board type, solder paste type, solder paste thickness, etc. Please also refer to the relevant IPC standards and indicators of solder

paste.

- Since the lead soldering temperature is relatively low, if using this method, please give priority to other components on the board.
- The opening of the stencil needs to meet your design requirement and comply to the examine standards. The thickness of the stencil is recommended to be 0.15 mm.

Packaging

Label Description

Figure 5-1 Label Description

Product Packaging

The UM960L module uses carrier tape and reel (suitable for mainstream surface mount devices), packaged in vacuum-sealed aluminum foil antistatic bags, with a desiccant inside to prevent moisture. When using reflow soldering process to solder modules, please strictly comply with IPC standard to conduct humidity control. As packaging materials such as the carrier tape can only withstand the temperature of 55 °C, modules shall be removed from the package during baking.

Figure 5 2 UM960L Package

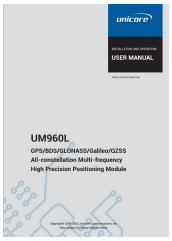
Table 5-1 Package Description

Item	Description
Module Number	500 pieces/reel
Reel Size	Tray: 13″ External diameter: 330 mm Internal diameter: 100 mm Width: 24 mm Thickness: 2.0 mm
Carrier Tape	Space between (center-to-center distance): 20 mm

The UM960L is rated at MSL level 3. Refer to the relevant IPC/JEDEC J-STD-033 standards for the package and operation requirements.
You may access to the website www.jedec.org to get more information.
The shelf life of the UM960L module packaged in vacuum-sealed aluminum foil antistatic bags is one year.

Unicore Communications, Inc.
F3, No.7, Fengxian East Road, Haidian, Beijing, P.R.China, 100094
www.unicorecomm.com
Phone: 86-10-69939800
Fax: 86-10-69939888
info@unicorecomm.com
www.unicorecomm.com

Documents / Resources

	unicore UM960L All Constellation Multi Frequency High Precision Positioning Module [pdf] User Manual UM960L All Constellation Multi Frequency High Precision Positioning Module, UM960L, All Constellation Multi Frequency High Precision Positioning Module, High Precision Positioning Module, Positioning Module

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