



TRINAMIC

**TMCM-1076 2-
Phase 3A 10 to
30 Vdc
Stepper Motor
Driver**



TRINAMIC TMCM-1076 2-Phase 3A 10 to 30 Vdc Stepper Motor Driver User Manual

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TRINAMIC TMCM-1076 2-Phase 3A 10 to 30 Vdc Stepper Motor Driver



TMCM-1076 Hardware Manual

The TMCM-1076 is an easy-to-use stepper motor driver module. The module is controlled via a step and direction interface. One configuration pin selects the current control mode between Stealth-Chop™ for absolute silent motor control and SpreadCycle™ for high speed. A TTL UART interface allows for more advanced configuration and permanent parameter storage via TMCL™-IDE.

Features

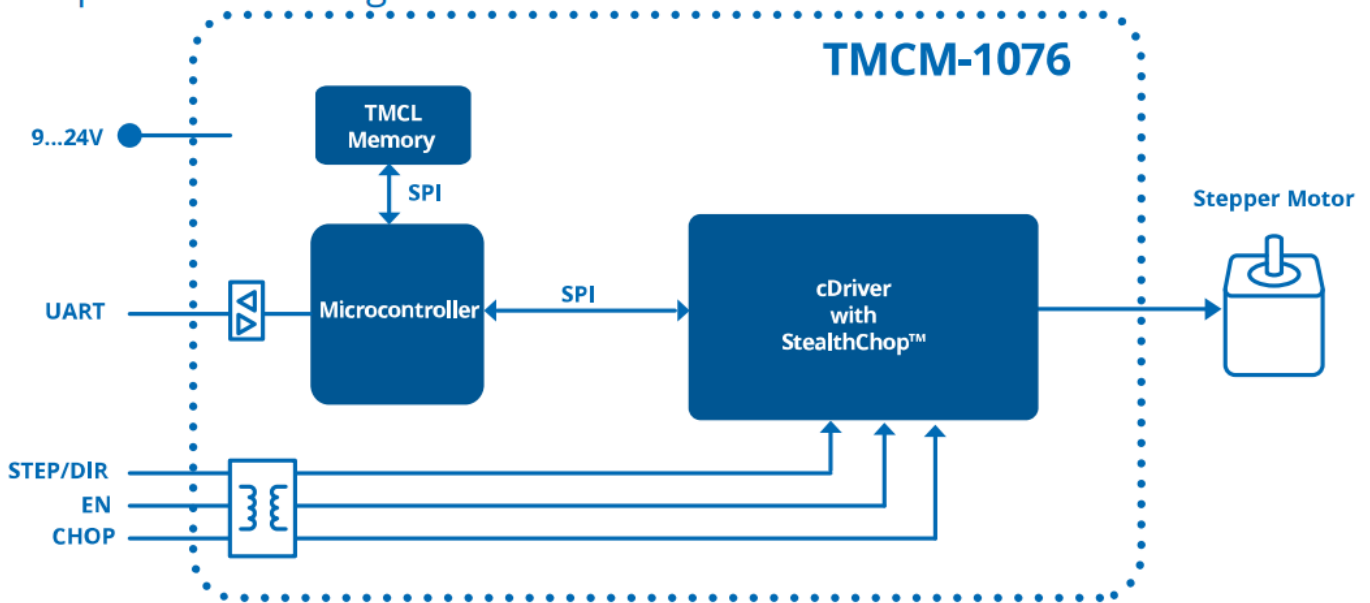
- Supply Voltage +10. . . +30V DC
- Up to 3A RMS motor current
- Step and direction interface
- MicroPlyer™ to 256 micro steps
- StealthChop™ silent PWM mode
- SpreadCycle™ smart mixed decay
- StallGuard2™ load detection
- CoolStep™ auto. current scaling
- UART configuration interface

Applications

- Lab-Automation
- Manufacturing
- Robotics
- Factory Automation
- CNC

Simplified Block Diagram

Simplified Block Diagram



Features

The TMC1076 is an easy-to-use stepper driver unit with state of the art feature set. It is highly integrated and offers convenient handling. TMC1076 can be used with a simple step and direction interface and can be configured using a TTL UART interface. stallGuard2 and coolStep can be configured via TTL UART interface and are disabled by default.

General Features

Main Characteristics

- Supply Voltage +10V to +30V DC
- 3A RMS phase current (ca. 4.2A peak phase current)
- Highest micro step resolution, up to 256 micro steps per full step
- MicroPlyer™ micro step interpolator for obtaining increased smoothness of micro stepping over a low-frequency STEP/DIR interface
- With housing and motor mounted
- Permanent onboard parameter storage
- Simple step & direction mode
- Noiseless StealthChop™ chopper mode for slow to medium velocities
- High-performance SpreadCycle™ chopper mode
- High-precision sensorless load measurement with StallGuard2™
- Automatic current scaling algorithm CoolStep™ to save energy and keep your drive cool

Optically Isolated Inputs

- Step & direction interface with up to 45kHz input frequency
- Enable input to power-on/-off driver H-bridges
- Mode select input to switch between the two chopper modes

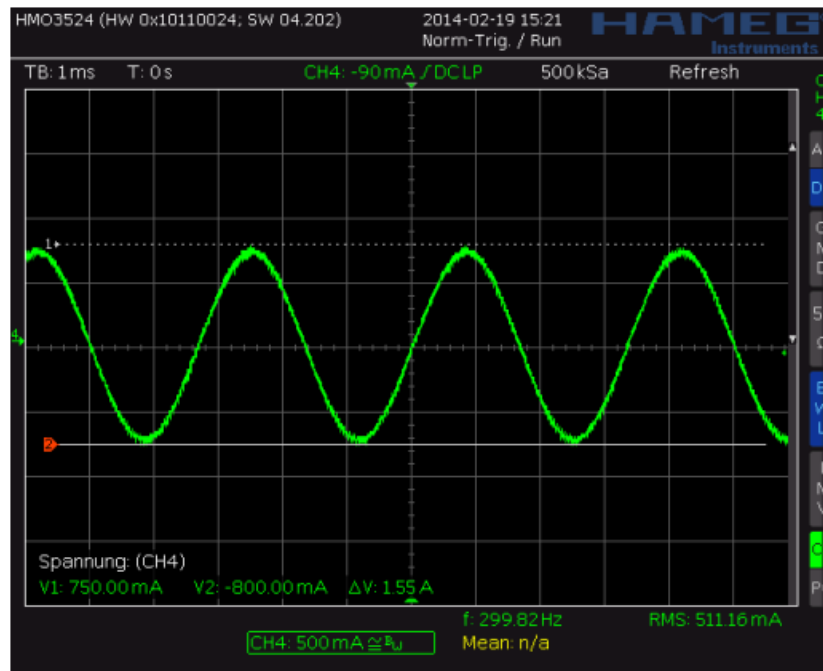
TTL UART Interface

- TTL-level UART interface for parameter configuration
- Interface speed 9600-115200 bps (default 9600 bps)
- TMCL-based protocol for online configuration and permanent parameter settings
- Bootloader for firmware updates

TRINAMIC's Unique Features

stealthChop™

stealthChop is an extremely quiet mode of operation for low and medium velocities. It is based on a voltage mode PWM. During standstill and at low velocities, the motor is absolutely noiseless. Thus, stealth-Chop-operated stepper motor applications are very suitable for indoor or home use. The motor operates absolutely free of vibration at low velocities. With stealthChop, the motor current is applied by driving a certain effective voltage into the coil, using a voltage mode PWM. There are no more configurations required except for the regulation of the PWM voltage to yield the motor target current.



spreadCycle™

The spreadCycle chopper is a high-precision, hysteresis-based, and simple-to-use chopper mode, which automatically determines the optimum length for the fast-decay phase. Several parameters are available to optimize the chopper to the application. spreadCycle offers optimal zero crossing performance compared to other current-controlled chopper algorithms and thereby allows for the highest smoothness. The true target current is powered into the motor coils.

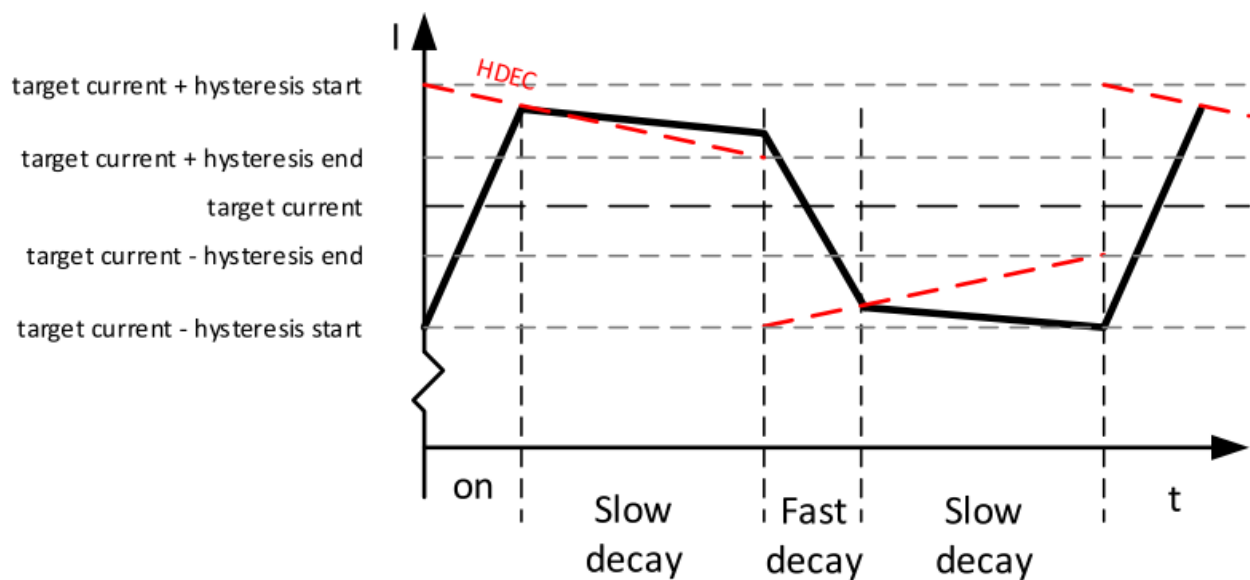


Figure 2: *spreadCycle principle*

stallGuard2

stallGuard2 is a high-precision sensorless load measurement using the back EMF of the motor coils. It can be used for stall detection as well as other uses at loads below those that stall the motor. The stallGuard2 measurement value changes linearly over a wide range of load, velocity, and current settings. At maximum motor load, the value reaches zero or is near zero. This is the most energy-efficient point of operation for the motor.

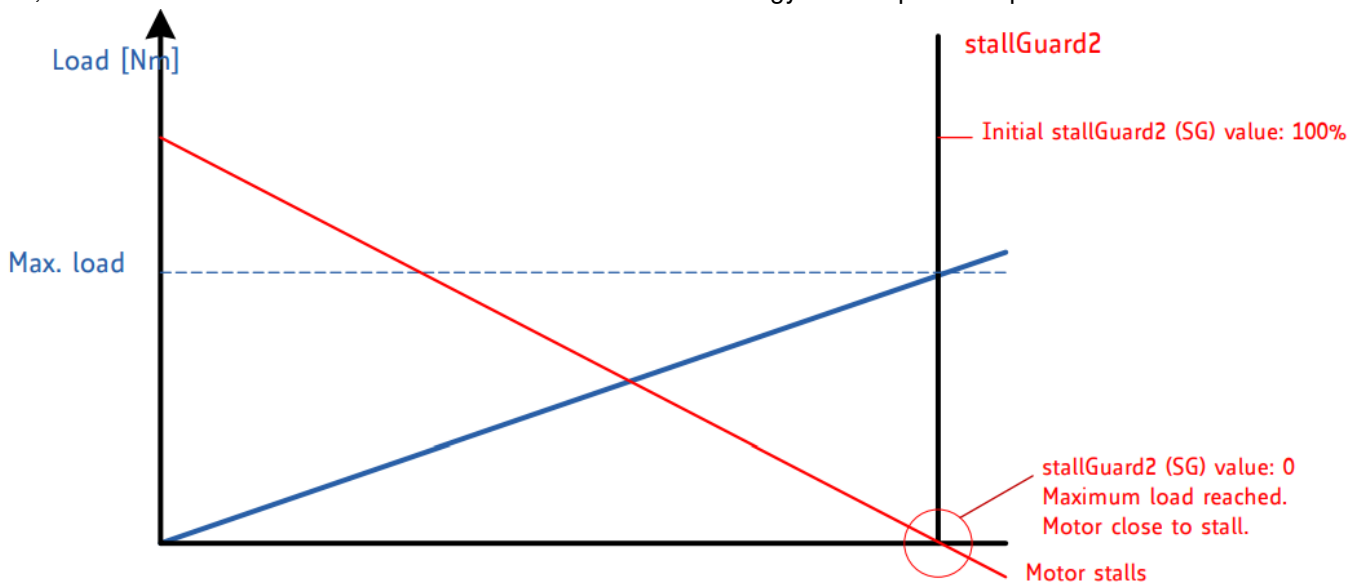


Figure 3: *stallGuard2 Load Measurement as a Function of Load*

cool step

coolStep is a load-adaptive automatic current scaling based on the load measurement via stallGuard2. coolStep adapts the required current to the load. Energy consumption can be reduced by as much as 75%. coolStep allows substantial energy savings, especially for motors that see varying loads or operate at a high-duty cycle. Because a stepper motor application needs to work with a torque reserve of 30% to 50%, even a constant-load application allows significant energy savings because coolStep automatically enables torque reserve when required. Reducing power consumption keeps the system cooler, increases motor life, and allows for cost reduction.

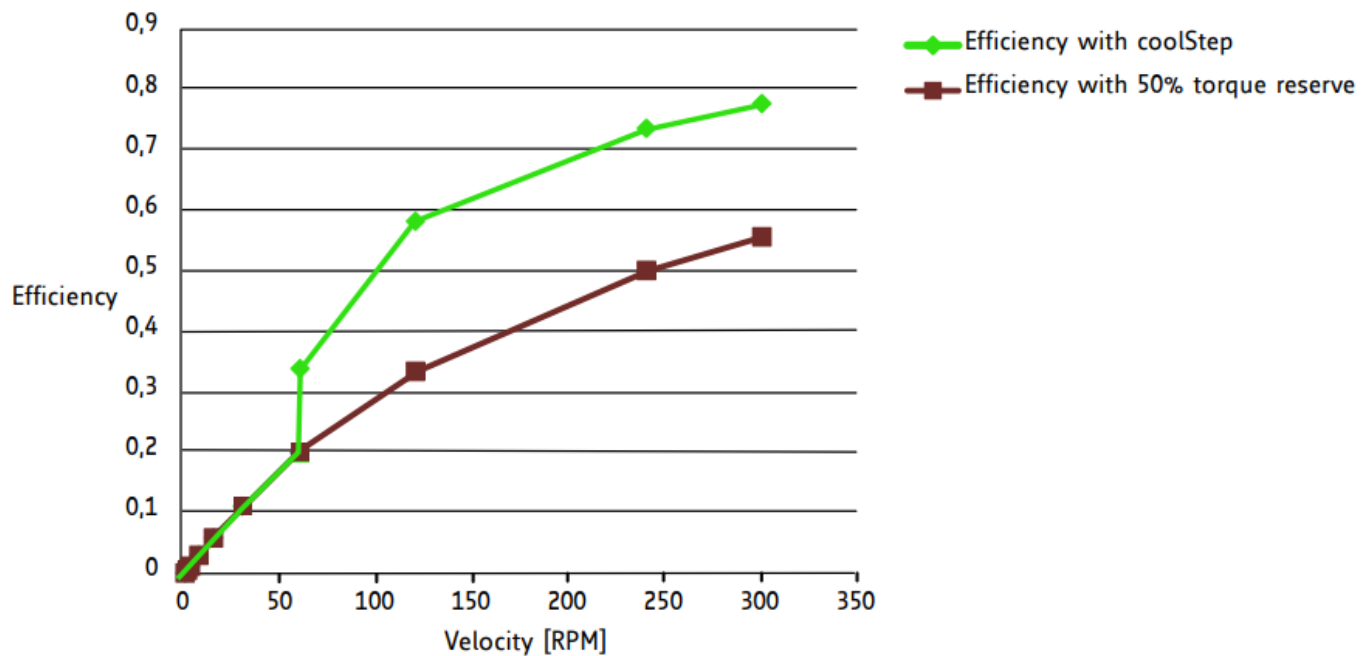


Figure 4: Energy Efficiency Example with coolStep

Order Codes

Order Code	Description	Size (LxWxH)
TMCM-1076	Controller/Driver Module without motor, +24V DC, 3A RMS, TTL UART interface (9600bps default), S/D interface, Enable, Mode Select	60mm x 60mm x 13mm

Table 1: Order codes modules

Order Code	Description
TMCM-1076-CABLE	Cable loom for TMCM-1076. Contains: <ul style="list-style-type: none"> 1x cable loom for motor connector with 4-pin JST EH female connector 1x cable loom for Power + I/O connector with 9-pin JST EH female connector

Table 2: Order codes cable loom

Mechanical and Electrical Interfacing

TMCM-1076 Dimensions and Weight

The dimensions of the TMCM-1076 are approximately 60mm x 60mm x 13mm. There are four mounting holes for M3 screws for mounting the TMCM-1076. These mounting holes are located in the bottom /base plate and

accessible after removing the top cover (see 5, right figure, mounting holes marked red). Two of them at opposite positions can be used for mounting the module to the backside of our NEMA23 stepper motors (screw/thread length depends on motor size). The other two can be used for mounting the module to the backside of our NEMA24 stepper motors (screw/thread length depends on motor size).

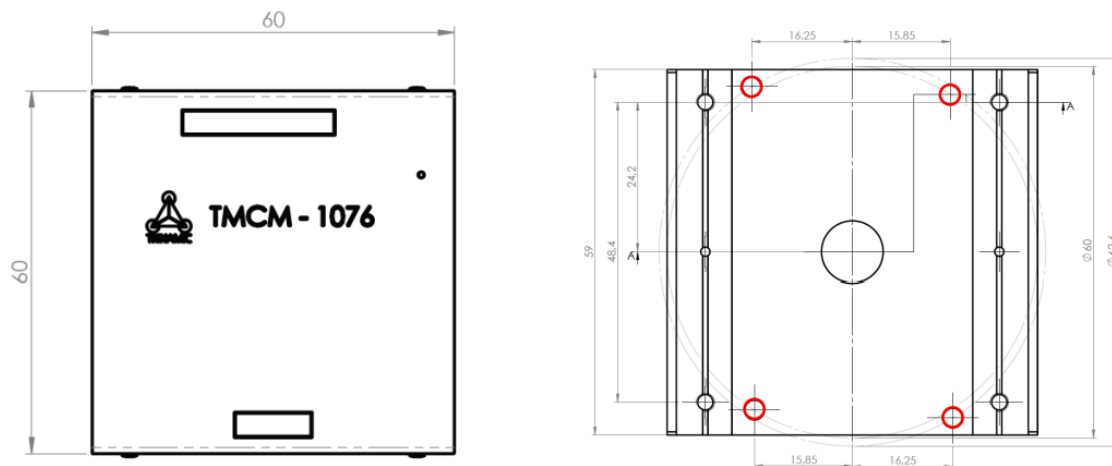


Figure 5: TCM-1076 top view mechanical dimensions (left) and position of mounting holes (marked red / right). All dimensions in mm

Order Code	Dimension in mm	Weight in g
TCM-1076	60mm x 60mm x 13mm	≈ 68

Table 3: TCM-1076 dimensions and weight

Mounting Considerations

TCM-1076 is designed to be mountable on the back of our NEMA23 and NEMA24 motors. Alternatively, it can be mounted standalone.

Connectors and LEDs

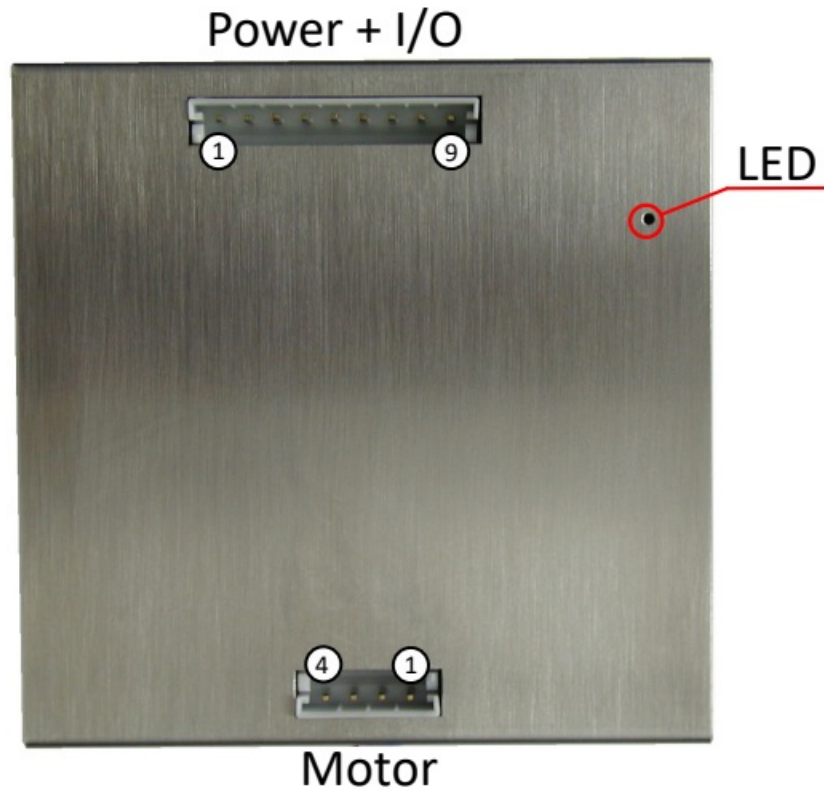


Figure 6: TMCM-1076 connectors

Motor Connector

Pin no.	Pin name	Description
1	B1	Motor phase B pin 1
2	B2	Motor phase B pin 2
3	A1	Motor phase A pin 1
4	A2	Motor phase A pin 2

Table 4: Motor connector pinning

NOTICE Do not connect or disconnect the motor during operation! Motor cable and motor inductivity might lead to voltage spikes when the motor is (dis)connected while energized. These voltage spikes might exceed voltage limits of the driver MOSFETs and might permanently damage them. Therefore, always switch off or disconnect the power supply before (dis)connecting the motor.

Power + I/O Connector

Pin no.	Pin name	Description
1	GND	Supply ground connection, also used for USB serial converter ground connection
2	V+	Supply voltage (V_{DD}) +10V to +30V DC
3	DIR	Optically isolated direction input of S/D interface
4	STEP	Optically isolated step input of S/D interface
5	EN	Optically isolated enable input of motor driver H-bridges
6	CHOP	Optically isolated chopper mode selection input
7	COMM	Opto-coupler common anode or cathode, connect to ground or VCCIO (3.3V to 6V – higher voltages possible with additional external resistors)
8	RXD	TTL-level UART receive line, use with USB serial converter TXD line to connect to PC
9	TXD	TTL-level UART transmit line, use with USB serial converter RXD line to connect to PC

Table 5: Power + I/O connector pinning

NOTICE Supply Voltage Buffering / Add External Power Supply Capacitors A sufficiently buffered power supply or an external electrolyte capacitor connected between V+ and GND is recommended for stable operation. It is recommended to connect an electrolytic capacitor of significant size to the power supply lines next to the TMCM-1076. Rule of thumb for size of electrolytic capacitor: $C = 1000 \mu F \cdot I_{SUPPLY}$ A The TMCM-1076 comes with approximately 40 μ F of onboard ceramic capacitors.

NOTICE There is no reverse polarity protection on the supply input! The module will short any reversed supply voltage and board electronics will get damaged.

NOTICE Power Up Sequence The TMCM-1076 must be powered up with a disabled driver stage only. Depending on your configuration the EN input should be logically OFF (EN input either open or at the same voltage level as the COMM input).

TTL UART Connection

To connect via the TTL UART interface to a host PC, we suggest using a USB serial converter from TTL-UART (5V) to the USB interface. Communication with the host PC, for example, when using TRINAMIC's TMCL-IDE, is done via the Virtual COM port installed by the converter driver. More information on the TMCL-IDE and the latest release can be found here: www.trinamic.com The converter cable must be connected to pins 1, 8, and 9 (GND, RXD, TXD) of the I/O connector.

Note Default Baud Rates The default baud rate is 9600 bps. In bootloader mode, the baud rate is 115200 bps.

Info USB to UART converter For example, the TTL-232R-5V from FTDI is working with the module and has been tested. More information on this converter is available on the FTDI website: www.ftdichip.com

NOTICE 5V TTL UART Level The TTL UART interface works with a 5V level. Take special care when selecting a converter cable for a USB connection.

Status LEDs

The TMCM-1076 has one green status LED. See figure 6 for its location.

State	Description
Blinking	MCU active, normal operation
Permanent on	Bootloader mode
Off	Power Off

Table 6: LED state description

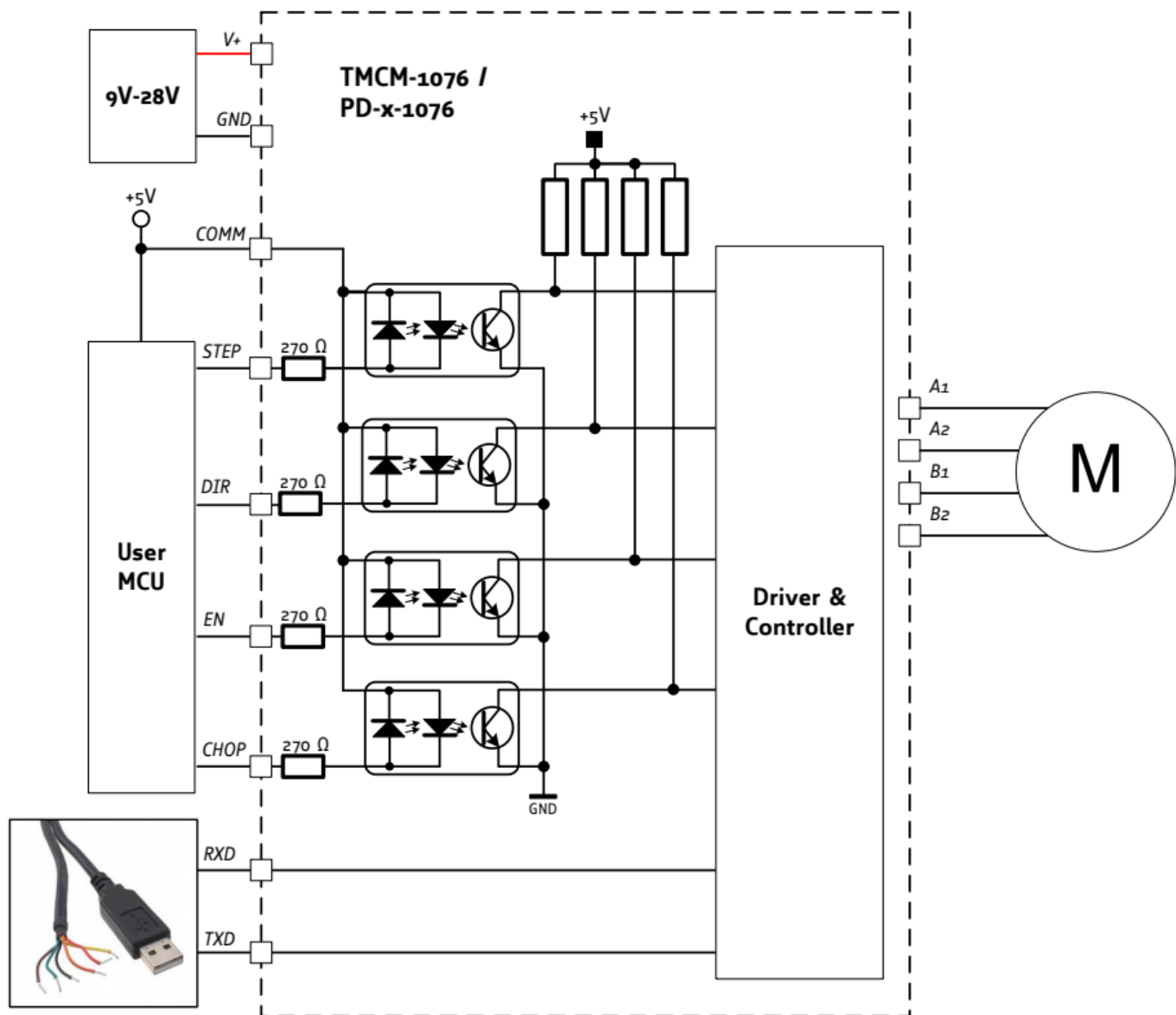
Functional Description

Typical Application Wiring

Wire the TMCM-1076 as shown in the following figures.

- Connect the power supply to V+ and GND.
- Connect the Step and Direction signals to your motion controller.
- At power-up time, the EN input must be logically 0 (= driver stage disabled)!
- Optional: Connect UART to a TTL UART interface with 5V logic levels. To configure your TMCM-1076 start the TMCL-IDE and use the parameterization tools. For detailed instructions refer to the TMCM-1076-firmware-manual.

Note The TTL UART interface is not optically isolated. It has and requires 5V level signals. Nevertheless, it provides basic ESD and rail-to-rail signal line protection for the TMCM-1076.



Optically Isolated Inputs with Common Anode Input

The control inputs of the TCMC-1076 are optically isolated (not the TTL UART interface). All optocouplers share one common anode (COMM) input as shown in the figure above.

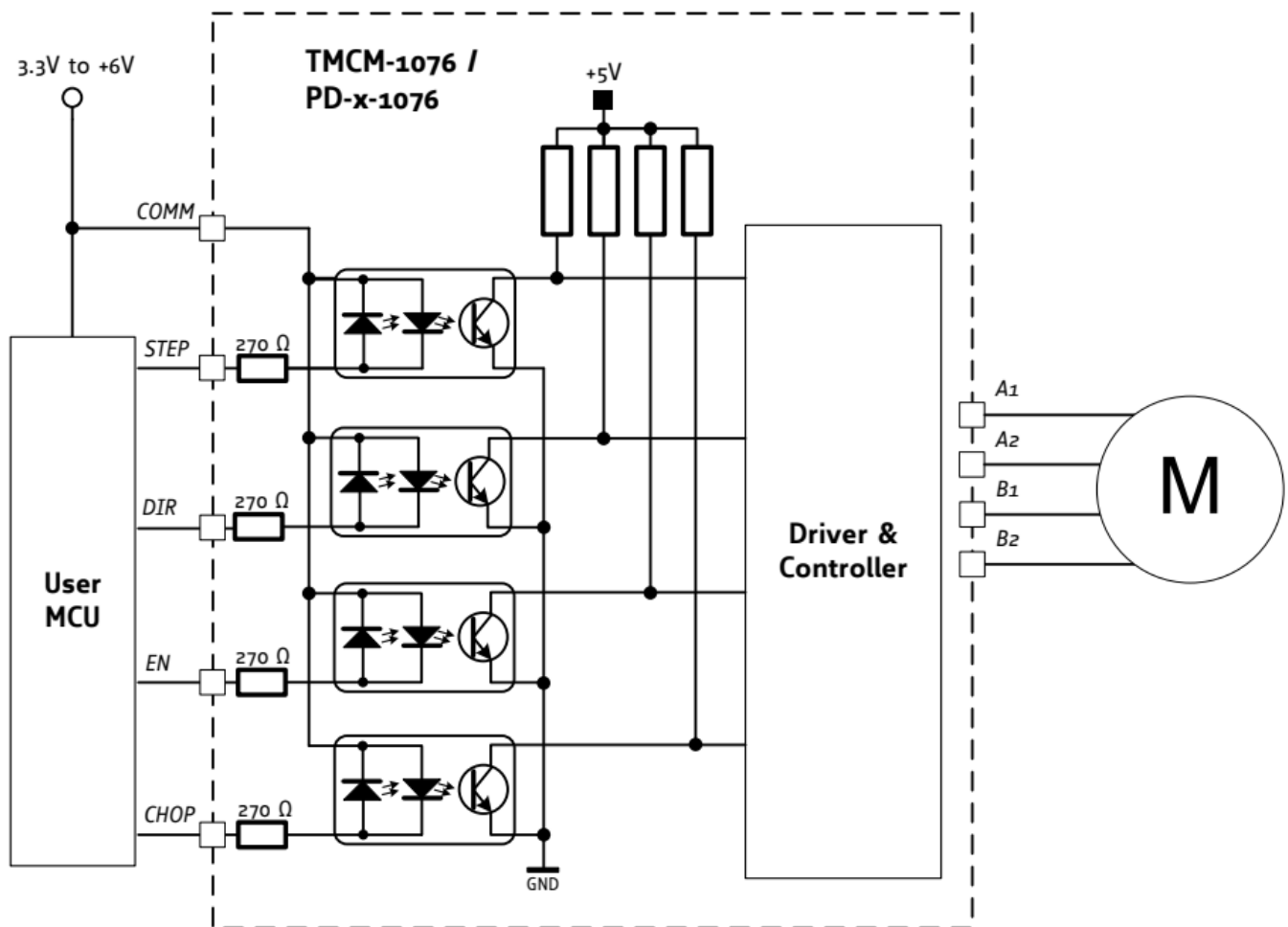


Figure 8: Inputs with common anode input with 3.3V to 6V

The typical voltage at COMM input is 5V. Nevertheless, 3.3V or voltages higher than 5V can also be used as long as the current through the optocouplers' emitter is between 5mA to 20mA. For 3.3V operation the controller must be carefully selected with respect to its I/O ports, its actual output voltage, and the series resistor of the I/O ports. The user must make sure that the current through the optocouplers' emitter is between 5mA to 20mA.

Note Step pulse width With the COMM input connected to the ground, the width of the step pulses should be between 2μs and 4μs, for maximum step frequency. With a larger step pulse width, for example, 50% duty cycle coming from a frequency generator, the maximum input frequency will be lower at ca. 9kHz. With the COMM input connected to +5V, longer step pulses are necessary.

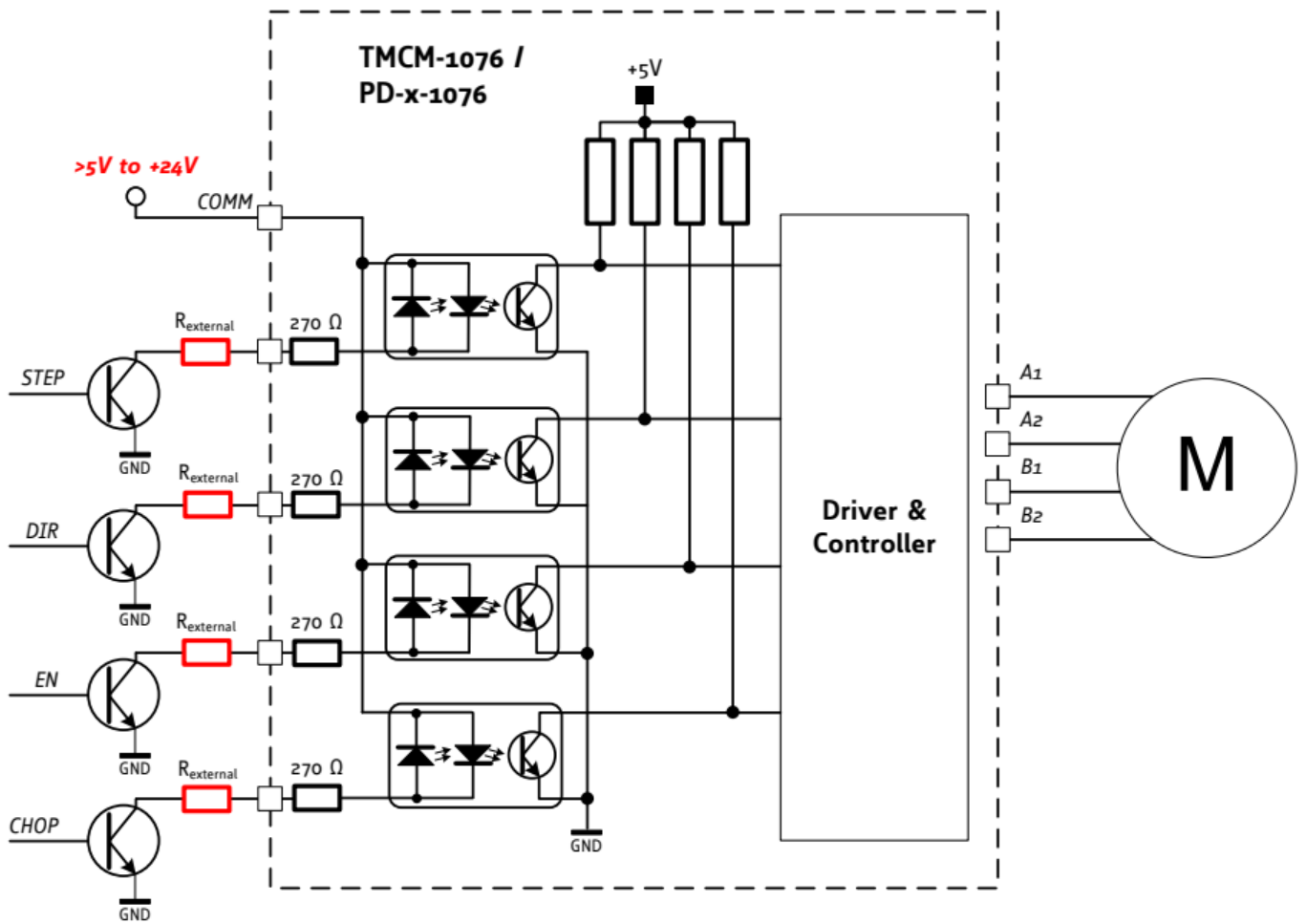


Figure 9: Inputs with common anode input with >5V to 24V

The series resistors in the TCM-1076 are 270mOhms. For operation with voltages higher than 5V, an additional external resistor $R_{external}$ is required per input to limit the current. See Table 7 as a reference for additional external resistor values.

COMM Voltage (V)	Value of $R_{external}$ (Ω)
3.3	—
5	—
9	300
12	500
15	700
24	1K5

Note $R_{external}$ Selection Take care when selecting an additional external resistor. The resistor type must have a rating power rating. This depends on the voltage used at COMM input.

Optically Isolated Inputs with Common Cathode Input

The optocouplers inside TMCM-1076 are bidirectional types (AC/DC). Thus, COMM can also be used as a common cathode connection with high-side (pnp style) switches instead of low-side (npn style) as shown in previous figures 9, 8, or 7.

Input Logic

The logic of the optically isolated inputs depends on the usage of common anode input or common cath-ode input. The following table shows the logic of the CHOP input and the logic of the EN input.

	COMM=3.3. . . 5V (Common anode)	COMM=GND (Common cathode)
CHOP=GND	SpreadCycle	StealthChop
CHOP=3.3. . . 5V	StealthChop	SpreadCycle
EN=GND	Motor enable	Motor disable
EN=3.3. . . 5V	Motor disable	Motor enable

Table 7: Additional resistor reference values

Thermal Behavior

The motor current may be set to the specified maximum current of 3A RMS / 4.2A peak for the TMCM-1076 which is slightly above the maximum specified current for the stepper motor options (available as PD57/PD60-x-1076). Typically, at this nominal current setting, the stepper motor and the driver electronics will get hot. Continuous operation at maximum current is not guaranteed without cooling the motor.

Note Operation with Maximum Current Setting For table-top testing and application bring-up the current should be reduced or the coolStep feature should be configured to keep heating on a reasonable level. Especially, when there is no other cooling option for the motor. For proper and continuous operation at maximum current, the motor range must be mounted to the application’s mechanical interface with good contact.

Operational Ratings and Characteristics

Absolute Maximum Ratings

Parameter	Min	Max	Unit
Supply voltage	+10	+30	V
Working temperature	-30	+40	° C
Motor coil current/sine wave peak		4.2	A
Continuous motor current (RMS)		3	A

NOTICE Never Exceed the absolute maximum ratings! Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability. Keep the power supply voltage below the upper limit of +30V! Otherwise, the board electronics will seriously be damaged! Especially, when the selected operating voltage is near the upper limit a regulated power supply is highly recommended.

Electrical Characteristics (Ambient Temperature 25° C)

Parameter	Symbol	Min	Typ	Max	Unit
Supply voltage	V_{DD}	10	24	30	V
Motor coil current/sine wave peak (chopper regulated, adjustable via TTL UART interface)	$I_{COILpeak}$	0		4.2	A
Continuous motor current (RMS)	$I_{COILRMS}$	0		3	A
Power supply current	I_{DD}		I_{COIL}	$1.4 * I_{COIL}$	A

Table 9: Electrical Characteristics

I/O Ratings (Ambient Temperature 25° C)

Parameter	Symbol	Min	Typ	Max	Unit
COMM input voltage	<i>V_{COMM}</i>	3.3	5	6	V
Input frequency of optically isolated I/Os	<i>f_{in}</i>			45	kHz
TTL UART input voltage	<i>V_{TTL_IN}</i>		5	5.5	V
TTL UART low-level voltage	<i>V_{TLL_L}</i>	0		1.75	V
TTL UART high-level voltage	<i>V_{TTL_H}</i>	3.25		5	V
TTL UART output voltage	<i>V_{TTL_OUT}</i>		5		V

Table 10: Operational ratings of optically isolated inputs and TTL UART interface

Functional Characteristics

Parameter	Description / Value
Control	4-wire interface with Step, Direction, Enable, and Chopper Mode Switch
Step Pulse Width	The step pulse width should be between 2 μ s and 4 μ s for maximum frequency. With a larger step pulse width, for example, a 50% duty cycle coming from a frequency generator, the maximum input frequency will be lower at ca. 9kHz.
Communication	2-wire TTL UART interface for configuration, 9600-115200 bps (default 9600 bps)
Driving Mode	spreadCycle and stealthChop chopper modes (selectable with CHOP input), adaptive automatic current reduction using stallGuard2 and cool step
Stepping Resolution	Full, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256 step, default is 1/16 with internal interpolation to 1/256

Table 11: Functional Characteristics

Other Requirements

Specifications	Description or Value
Cooling	Free air
Working environment	Avoid dust, water, oil mist, and corrosive gases, no condensation, no frosting
Working temperature	-30° C to +40° C

Table 12: Other Requirements and Characteristics

Abbreviations used in this Manual

Abbreviation	Description
COMM	Common Anode or common cathode
IDE	Integrated Development Environment
LED	Light Emmitting Diode
RMS	Root Mean Square value
TMCL	TRINAMIC Motion Control Language
TTL	Transistor Transistor Logic
UART	Universal Asynchronous Receiver Transmitter
USB	Universal Serial Bus

Table 13: Abbreviations Used in this Manual

Supplemental Directives

Producer Information

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Collateral Documents & Tools

This product documentation is related and/or associated with additional tool kits, firmware, and other items, as provided on the product page at: www.trinamic.com.

Revision History

Hardware Revision

Version	Date	Author	Description
1.00	2018-FEB-28	GE	First prototype version.
1.10	2018-APR-09	GE	Pull-ups for the opto-isolator changed to lower values (to be compatible with TCM-1070).

Table 14: Hardware Revision

Document Revision

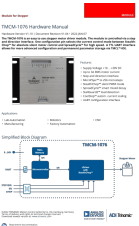
Version	Date	Author	Description
1.00	2018-JUN-25	GE	First release.
1.01	2019-AUG-01	OK	The product picture updated.
1.02	2021-JUN-03	OK	Notice about EN input corrected.
1.03	2021-SEP-03	OK	Notice about step pulse length extended.
1.04	2022-JAN-07	OK	New section 5.4.

Table 15: Document Revision

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Documents / Resources

	TRINAMIC TCM-1076 2-Phase 3A 10 to 30 Vdc Stepper Motor Driver [pdf] User Manual TCM-1076 2-Phase 3A 10 to 30 Vdc Stepper Motor Driver, TCM-1076, 2-Phase 3A 10 to 30 Vdc Stepper Motor Driver, 3A 10 to 30 Vdc Stepper Motor Driver, 30 Vdc Stepper Motor Driver, Stepper Motor Driver, Motor Driver, Driver
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