

TOSHIBA TOSVERT Transistor Inverter User Guide

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Braking setting functions

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Function

Setting functions to control braking timing.

Parameter setting for braking setting function

Title	Function	Setting range	Default settin
F342	Braking mode selection	0: Disabled 1:Enabled (forward run) 2:Enabled (reverse run) 3:Enabled (operating direction)	0
F343	Release frequency	F 2 4 0 _ 20.0 [Hz]	3.0
F344	Release time	0.00 - 2.50 [s]	0.05
F345	Creeping frequency	F 2 4 0 _ 20.0 [Hz]	3.0
F 3 4 6	Creeping time	0.00 – 2.50 [s]	0.10

Title	Function	Setting range	Setting value
F 130	Output terminal selection 1A (RY-RC)	0 – 255	46:BR (Braking sequence output) or 47:BRN (Inversion of braking sequence ou tput)

Note) In case of others output terminal, it is deferent from parameter title.

RY-RC: F 13 1

FLA-FLB-FLC: F. 132

Explanation of braking setting function

At starting the motor:

When the operation signal is 'ON', the brake release signal is 'ON' after getting the flux of magnetic induction before brake releasing.

The output torque of inverter is generated before the brake is released by outputting 'the frequency of the $F \exists \forall \exists$ setting' to 'the direction of the $F \exists \forall \exists$ setting'.

The motor is able to accelerate smoothly at the same time as releasing the brake because $F \exists Y Y$ function provides 'the delay of acceleration beginning'.

At stop the motor:

When the operation signal is 'OFF', the brake close signal is 'ON' after reaching the creeping frequency of $F \ 3 \ 4 \ 5$ setting. After that, the VF-S11 outputs creeping frequency while setting time of $F \ 3 \ 4 \ 5$, and stops after delayed time of mechanical brake.

F 3 4 2 Braking mode selection

0: Disabled

1: Enabled (forward run)

The rise operation is forward rotation of motor at RISE/DESCENT action.

The direction of inverter output frequency $(F \ni Y \ni)$ is forward direction regardless of FORWARD/REVERSE drive.

2: Enabled (reverse run)

The rise operation is reverse rotation of motor at RISE/DESCENT action.

The direction of inverter output frequency $(F \ni " \ni")$ is reverse direction regardless of FORWARD/REVERSE drive.

3: Enabled (operating direction)

This value is for the horizontal operation.

The direction of inverter output frequency $(F \ni \forall \exists)$ is same as direction of drive.

F 3 4 3 Release frequency

The inverter outputs $^{F \, \exists \, \forall \, \exists \, '}$'s frequency to $^{F \, \exists \, \forall \, \exists \, '}$'s direction. This function is for generating motor torque by slipping of the restrained motor. By this, the motor starts smoothly when the brake is released.

The $F \ni Y \ni$ setting value depends on load condition. The standard setting is 'the slipping frequency' at rated output of applied motor.

F344 Release time

The release time is time to maintain frequency of F 3 4 4 setting at start.

The standard setting is delayed time of mechanical brake.

F 3 4 5 Creeping frequency

The 'close brake signal' outputs $F \ni 45$'s frequency while $F \ni 45$'s setting time at stop.

The F345 setting value depends on load condition. The standard setting is

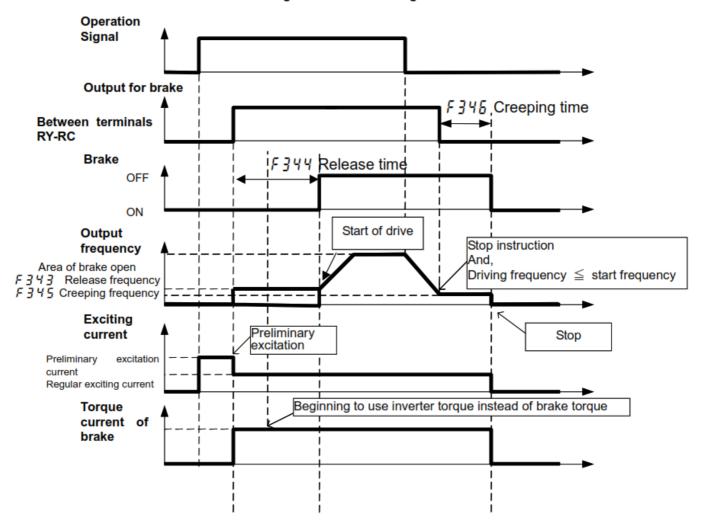
The F345 setting value depends on load condition. The standard setting is 'the slipping frequency' at rated output of applied motor

F346 Creeping time

The creeping time is time to maintain frequency of *F 3 4 5*.

The standard setting is a little more than delayed time of mechanical brake.

Timing chart of brake setting function



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Documents / Resources



Manuals+,