



TOPCNC TC55H CNC Controller Instruction Manual

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Product Introduction

TC55H is an upgrading version of TC55. It can control 4 feeding axes, 1 analog spindle. It is equipped with 16 input ports and 8 output ports, supporting importing files from a USB stick.

Technical Specifications

Minimum data unit 0.001 mm

Maximum data size $\pm 99999.999\text{mm}$

Maximum Speed: 9000mm/min (pulse is 0.001mm)

Maximum pulse output frequency 150KHz

Axis 1-4 (X,Y, Z,C)

X, Y, Z, C axis can conduct linear interpolation, X, Y can do circular interpolation.

Electric Gear: numerator :1-99999 denominator: 1-99999

USB: Importing program and boot picture

Isolated I/O port

1000

99

Maximum Program Line:

Maximum Program:

RAM: 128M

External Manual Operation: motor clockwise and counter-clockwise spinning, start, pause, alert and stop

G code and M code

One panel MPG

3.5-inch color LCD, pixel 320*240

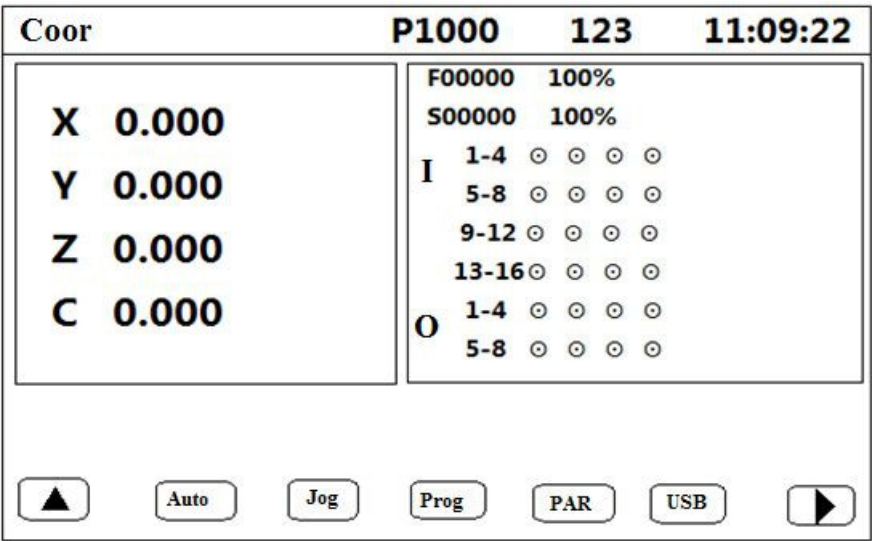
Analog Spindle Output: 1 0-10v analog spindle

Definition of external Switch

Please contact us if you need to change the boot picture before buying

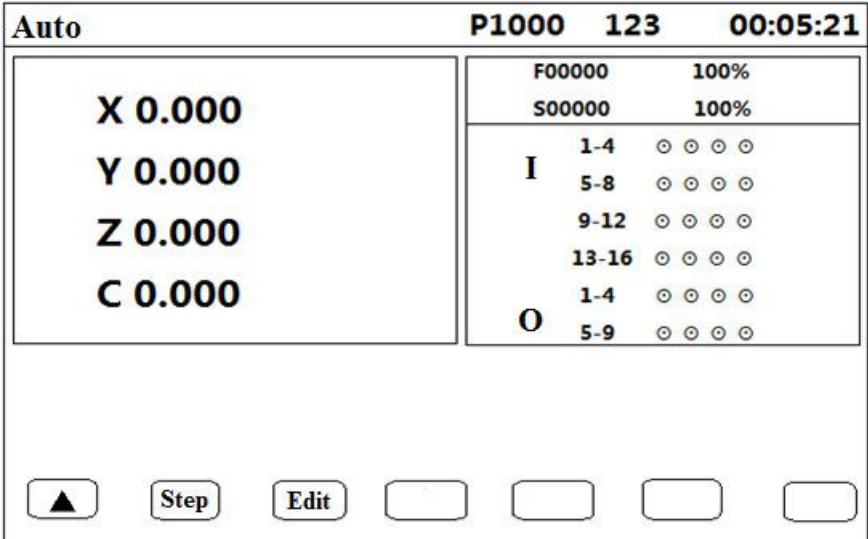
Operation

Main Interface



This is the interface showing after booting without a boot picture. It shows the coordinates of each axis, F speed and rate, S speed and rate, as well as the condition of input and output port. P1000 means the program currently running; 123 means the input method. You can get into the AUTO, JOG, PROG, PAR, USB as well as password interface from here.

Auto



In Auto Interface, Press start to run the last read program, Press Pause to Stop.

Step

Positive display means consecutive operation. A negative display means operating command by command. When it is the negative display, press Start once, one program line will be executed.

Edit

Edit	P1000	123	11:08:10									
<div style="display: flex; justify-content: space-between;"> 4/4 No Mistake! </div> <table border="1" style="width: 100%; border-collapse: collapse;"> <tr><td>N001 G00 X100.988 Y211.456 Z988</td></tr> <tr><td>N002 G01 X122.998 Y879.112 Z666.987 F122</td></tr> <tr><td>N003 G01 X500</td></tr> <tr><td> </td></tr> <tr><td> </td></tr> <tr><td> </td></tr> <tr><td> </td></tr> <tr><td> </td></tr> <tr><td> </td></tr> </table>				N001 G00 X100.988 Y211.456 Z988	N002 G01 X122.998 Y879.112 Z666.987 F122	N003 G01 X500						
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N003 G01 X500												
<div style="display: flex; justify-content: space-around; align-items: center;"> ▲ Top BTM Test Save Auto </div>												

- Press Enter to insert a new line.
- Long press DEL to delete a line.
- Press ← → ↑ ↓ to move the cursor
- Top: To the first line
- BTM: to the last line
- Test: See if there are any mistake
- Save: Save program
- Auto: Into Auto Interface.

Jog

JOG	X1	P1000	123	14:15:22																				
<div style="display: flex; flex-direction: column; align-items: center;"> <div>X 0.000</div> <div>Y 0.000</div> <div>Z 0.000</div> <div>C 0.000</div> </div>		<table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 30%;">F00000</td> <td style="width: 70%;">100%</td> </tr> <tr> <td>S00000</td> <td>100%</td> </tr> <tr> <td>I</td> <td></td> </tr> <tr> <td>1-4</td> <td><input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/></td> </tr> <tr> <td>5-8</td> <td><input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/></td> </tr> <tr> <td>9-12</td> <td><input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/></td> </tr> <tr> <td>13-16</td> <td><input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/></td> </tr> <tr> <td>O</td> <td></td> </tr> <tr> <td>1-4</td> <td><input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/></td> </tr> <tr> <td>5-8</td> <td><input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/></td> </tr> </table>			F00000	100%	S00000	100%	I		1-4	<input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/>	5-8	<input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/>	9-12	<input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/>	13-16	<input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/>	O		1-4	<input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/>	5-8	<input type="radio"/> <input type="radio"/> <input type="radio"/> <input type="radio"/>
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<div style="display: flex; justify-content: space-around; align-items: center;"> ▲ Speed MPG BPZ ALL 0 BMZ </div>																								

- Press X, Y, Z, and C to choose the relevant axis.
- S for feeding rate gaining, N for feeding rate decreasing. (10%-150%)
- G for spindle rate gaining, M for spindle rate decreasing. (10%-150%)
- Press Shift to change output port, press Enter to change from ON or OFF.
- Press ← and → for consecutive running.
- Press ↑ and ↓ for jogging, define the jog distance in PAR-Ctrl-Jog+Distance; define jog speed in PAR-Speed-

Jog.

Speed

Speed: Negative display means manual high speed, positive display means manual low speed. Press ← and → for consecutive running.

MPG

Press MPG, then move the wheel up, the axis chosen move positively, move the wheel down, the chosen axis move negatively. Press X10X100 to change the cardinal number shown on the top of the screen.

Status	Cardinal Number
X1	0.001mm
X10	0.01mm
X100	0.1mm

BPZ

Press this key on the chosen axis go back to the reference point at highest speed. Define the highest speed in Parameters-Speed.

All 0

Press this key the chosen axis go back to the reference point at highest speed. Define the highest speed in Parameters-Speed. F is the combined speed of all axis.

BMZ

Return to machine zero. The chosen axis will move at BMZ High Speed to go back to machine zero, then touch the switch and move at BMZ Low Speed, finally stop on the switch. In order to use this function, the X 0/Y 0/Z 0/C 0 has to be set as "On" in Parameters-Ctrl; Set BMZ High and BMZ Low in Parameters-Speed; Set the direction in Parameters-Ctrl-X BMZ
Dir

PAR

Ctrl

Control parameters setting area, Long press ↑ and ↓ to change page.

- X/Y/Z/C Numerator: Electric gear ratio (1-99999)
- X/Y/Z/C Denominator: Electric gear ratio(1-99999)
- X/Y/Z/C Reference:In manual operation, long press X/Y/Z/C to clear the coordinates and show this value; or in machine zero, after hit the switch, it will show this value.
- X/Y/Z/C Backlash: Backlash to make it more precise
- X/Y/Z/C Boot Zero: 0 means the axis will not go back to machine zero after booting; 1 means the axis will go

back to machine zero after booting

- X/Y/Z/C BMZ Dir: 0 means the axis go back to machine zero towards negative direction; 1 means the axis go back to machine zero towards a positive direction
- Speed+Time(ms): time use for the motor to reach F speed
- Jog+Distance: in manual operation, increment for jogging. Unit of it is dependent on the electric gear ratio.
- Language: English (0)or Chinese(1)

The setting of Electronic Gear Ratio

Setting the electronic gear is to set different data unit for different machines. The different axis of the same machine can be set based on a different unit. For example, axis A can be set as mm, axis B can be set as angle, and axis C can be set as round.

How to set the numerator and denominator of electronic gear ratio:

Pulse needed for the motor to turn one round to the same direction

Distance moved when the motor turn one round to the same direction(μm)

The numerator and denominator both should be an integer between 1 and 99999.

Ex. 1 Screw Transmission

Stepper motor stepping is 5000, or servo motor 5000 pulse/round, screw pitch is 6mm, reduction ratio is 1:1, then,
 $5000 \rightarrow 5$

$6 \times 1000 \times 1.0 \rightarrow 6$

Ex. 2 Rack and Pinion

Stepper motor stepping is 6000, or servo motor 6000 pulse/round, gear teeth number is 20, $m = p/\pi = 2$, then

$6000 \rightarrow 1 \rightarrow 107 \rightarrow 107$

$1000 \times 20 \times 2 \times 3.14159265 \rightarrow 20.943951 \rightarrow 2241.00276 \rightarrow 2241$

Ex. 3 Rotary Angle

Stepper motor stepping is 5000, or servo motor 5000 pulse/round, the reduction ratio is 1:30, then,

$5000 \times 30 \rightarrow 5$

$360 \times 1000 \rightarrow 12$

Speed

- X/Y/Z/C Highest: The highest speed of x-axis motor. When the system is operating, speed will not exceed this number no matter what F you set.
- Start(mm/min)Speed during Spd+Time
- Man High: Manual high speed
- Man Low: Manual low speed
- BMZ High: Go to machine zero at high speed.
- BMZ low: Go back to machine zero first at high speed, through zero switches,es and move back at low speed. Finally, slider will stop on the switch.
- BMZ Mode: two modes to go back to machine zero, through the switch or not. Through switch(0): slider will stop on the switch. Not trough switch(1): Slider will stop before the switch.
- S High Speed: The highest speed of the spindle

Input

This function enables user to set various kind of switches easily. Define the I/O port according to the following form.

External Big switch is needed to finish external control. An external switch is connected in the way of normal open. Press R to change off into on, and S to choose N.O.(Normal Open). Then choose the IO Port number in the blank.

Note: For safety consideration, limit and emergency stop input is usually set as N.C.(Normal Close).

Function	Explanation
Alert	Alert Input
Stop	Emergency Stop Input
Run	Outside(External) Run Switch Setting
Pause	Outside(External) Pause Switch Setting
Speed+	Feed rate increase Switch Setting
Speed-	Feed rate decrease Switch Setting
X Lim+	X-axis Positive limit setting
X Lim-	X-axis Negative limit setting
X 0	X-axis zero switch setting
Man X+	X axis clockwise spinning outside manual switch
Man X-	X-axis counter-clockwise spinning outside manual switch
X Boot Zero	X-axis go back to Machine zero after booting external manual switch
Y Lim+	Y-axis Positive limit setting
Y Lim-	Y-axis Negative limit setting
Y 0	Y-axis zero switch setting
Man Y+	Y axis clockwise spinning outside manual switch
Man Y-	Y-axis counter-clockwise spinning outside manual switch
Y Boot Zero	Y-axis go back to Machine zero after booting external manual switch
Z Lim+	Z-axis Positive limit setting
Z Lim-	Z-axis Negative limit setting
Z 0	Z-axis zero switch setting
Man Z+	Z axis clockwise spinning outside manual switch
Man Z-	Z-axis counter-clockwise spinning outside manual switch
Z Boot Zero	Z-axis go back to Machine zero after booting external manual switch
C Lim+	C axis Positive limit setting
C Lim-	C axis Negative limit setting
C 0	C axis zero switch setting
Man C+	C axis clockwise spinning outside manual switch
Man C-	C axis counter-clockwise spinning outside manual switch
C Boot Zero	C axis go back to Machine zero after booting external manual switch

Output

PAR	P1000	123
M51:Output 0 Off	M59:Output 0 Off	
M52:Output 0 Off	M60:Output 0 Off	
M53:Output 0 Off	M61:Output 0 Off	
M54:Output 0 Off	M62:Output 0 Off	
M55:Output 0 Off	M63:Output 0 Off	
M56:Output 0 Off	M64:Output 0 Off	
M57:Output 0 Off	M65:Output 0 Off	
M58:Output 0 Off	M66:Output 0 Off	
M03:Output 0 Off		
M04:Output 0 Off		
Press Enter to choose on/off		
1/1		
<input type="button" value="▲"/>	<input type="button" value="Ctrl"/>	<input type="button" value="Speed"/>
<input type="button" value="Input"/>	<input type="button" value="Output"/>	<input type="button" value="FTY"/>

In this interface to define the open and close of 1-8 output ports, then you can directly use in programming. M03-M04 is a spindle interlock.

FTY

Go back to factory value.

Operation

- Press ←→↑↓to move the cursor
- Long Press ↑↓to change page
- After changing the parameters, press ESC, here appears the window ask whether save the parameters or not, press Enter and save, press ESC or Not to give up saving.

Prog

In this interface to edit, read, delete, save and create program files.

PROG	P1000	123	00:01:21																								
SD Volume																											
<table border="1"> <thead> <tr> <th>Name</th> <th>Size</th> <th>Time</th> </tr> </thead> <tbody> <tr> <td>P1000</td> <td>5581</td> <td>2014-03-21</td> </tr> <tr> <td>P1234</td> <td>17882</td> <td>2014-09-28</td> </tr> <tr><td> </td><td> </td><td> </td></tr> <tr><td> </td><td> </td><td> </td></tr> <tr><td> </td><td> </td><td> </td></tr> <tr><td> </td><td> </td><td> </td></tr> <tr><td> </td><td> </td><td> </td></tr> </tbody> </table>			Name	Size	Time	P1000	5581	2014-03-21	P1234	17882	2014-09-28																Left : 233104KB
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USB

USB	P1000	123	13 : 10 : 08																
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K0005.BMP	230454																		
K0006.BMP	230454																		
<div style="display: flex; justify-content: space-around; align-items: center;"> ▲ Import Prog Pic </div>																			

- Program Name: P123.TXT or P1234. TXT
- Boot Picture Name: K123.bmp or K1234.bmp Pixel: 320*240

13811674107 jiafengqi.xtf@hotmail.com

Documents / Resources

	<p>TOPCNC TC55H CNC Controller [pdf] Instruction Manual TC55H, CNC Controller</p>
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