



## thermokon PDI1- Series Air Velocity and Temperature Sensor Instructions

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Ti3230en  
PDH- Series (V&T),



**Technical Instruction**  
**Air Velocity and Temperature Sensor**  
**with Active Output**

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**PDI1- Series Air Velocity and Temperature Sensor**

The PDI1-Series (V&T) is designed to measure air velocity and temperature in HVAC systems

Field selected measuring ranges and sensor outputs

Field select Multiple Velocity measuring ranges

Optional with LCD and relay output available

Optional LCD display available.

The sensor works with low power supply

The control outputs are active.

**USE**

Compatible to all common HVAC DDC and Analog Controls systems, with/without Building Automation System

Differential pressure measurement in HVAC systems

Monitoring the air dampers in the primary or secondary controls systems

Supervision of the status of heating / cooling coils, preventing overheating / freezing

**Featured**

Sensor with active outputs

Internal selectable measuring ranges and sensor outputs

Optional with LCD- backlit display

Optional with field adjustable relay output

Professional and practical product design, withstands rough environmental conditions

Easy to use, install and maintain

**Product Range**

Order Codes	Power Supply	Sensor Outputs	Measuring Ranges	Display	Relay Output	Protection
PD11.AA	AC/DC 24V ±10%	0....10V* or 4....20mA	0...50°C 0...2m/s 0...10m/s* 0...20m/s	n/a	n/a	IP54
PD11.BA				LCD	n/a	
PD11.CA				LCD	Relay (STDP)	

\* default Value

## Sensor Specification

Sensor Specification	Measured	Temperature / Air Flow
	Sensor Characteristics	Active / Active
	Sensor Output (s)	0..10V (min 1k Q) or 4...20mA (min. 0.4kQ)
	Accuracy (T)	<0.2m/s +5% of actual value
	Accuracy (v=0...2m/s)	<0.5m/s +5% of actual value
	Measuring Range (v)	0...10m/s /0..50°C
	Optional Measuring Range (v)	0...2m/s; 0...20m/s
	Temperature Sensor	0...50°C

## Technical Information

Electrical Information	Power Supply	AC/DC 24V (10%)
	Frequency	50/60 Hzat AC 24V
	Terminal Clamp	Screw terminal, max. 1.5mm?
	Power Consumption	max. 125mA
	Relay Rating	AC 250V, max 6A; DC 30V, max. 6A
Mechanical Information	Immersion Rod Diameter	@10mm
	Immersion Rod Length	195mm
	Cable Entry	Dual entry, 2 x M16, @6...28mm cables
	Sensing Element Position	external, top of the immersion rod
	Range Selection	Jumper switches inside the housing
User Interface	Display	LCD- backlit (45.7×12.7mm)

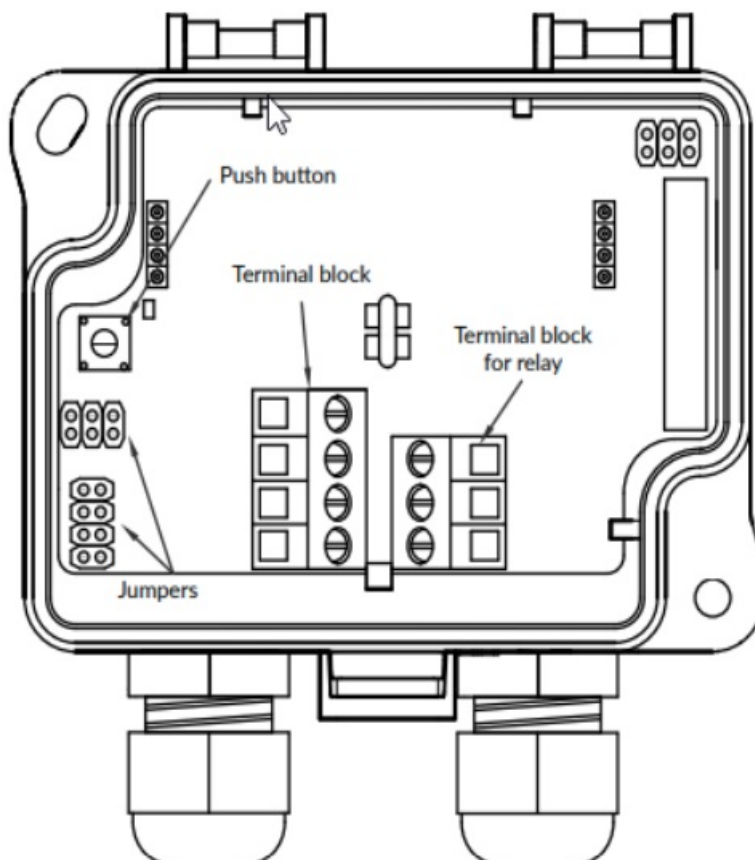
Color and Materials	Housing Cover	PC, grey
	Housing Bottom	ABS, grey
	Lock	Snap Connector
	Cable Glanc	Grey ABS
	Gland Rubber S	Black Rubber
	User element	Removable Jumpers
	Immersion Rod	US:AISI 304; EU: EN X 6 CrNi 18 10; GER: W. N. 1.301
Environmental Conditions	Operation Temperature	0°C...+50°C
	Operation Humidity	<95% r.h., no condensation
	Transport Temperature	-35°C...+70°C
	Transport Humidity	<95%rh.
	Storage Temperature	-10°C...+70°C
	Storage Humidity	< 85% r.h., no condensation
Norms and Directives	IP- Rating	IP54 to IEC6052
	Safety Class	1I to EN 60 730
	Product Standard 1	Automatic Electric. Controls for household and similar use
	Product Standard 2	2009/EN 60 730-1
	CE Conformities to	2004/108/EG Electromagnetic Compatibility E MV'
	LVD Directive	2014/35/EU
	RoHS Compatibility	RoHS 3, Directive 2015/863
	WEEE Directive	2012/19/EU
	Operation Climatic Condition	IEC 60721-3-3
	Operation Mechanical Condition	IEC 60 721-3-2 to class2M2
	Transport to Climatic Condition	IEC 60 721-3-2
	Transport Mechanical Condition	IEC 60 721-3-2 to class2M2
	Storage Climatic Condition	IEC 60 721-3-1
	Storage Mechanical Condition	IEC 60 721-3-1 to class2M2

## Miscellaneous

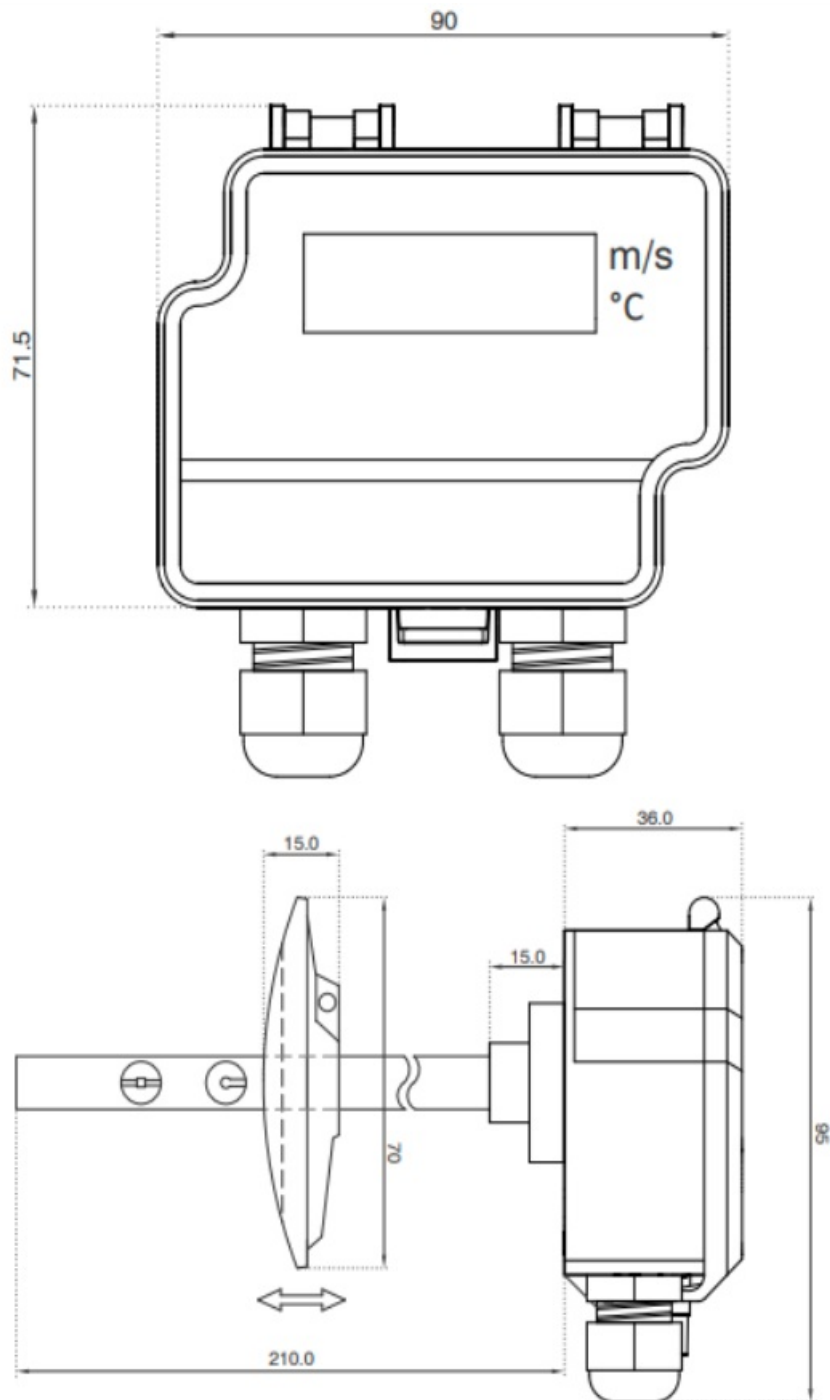
Accessories	Mounting Kit, Included in delivery	Duct Mounting flange
Shipping & Handling	Minimum Order	1 box with 1 piece
	Package Material	Rigid Cardboards Packaging
Order Notes	Order Code	See Product Range, Page 1, e.g. PDI1.AA

## Mounting Instruction

### SCHEMATICS



### DIMENSIONAL DRAWINGS



## INSTALLATION

1. Mount the device in the desired location (see step 1).
2. Open the lid and route the cable through the strain relief and connect the wires to the terminal block (see step 2). Use a separate strain relief for each cable.
3. The device is now ready for configuration.



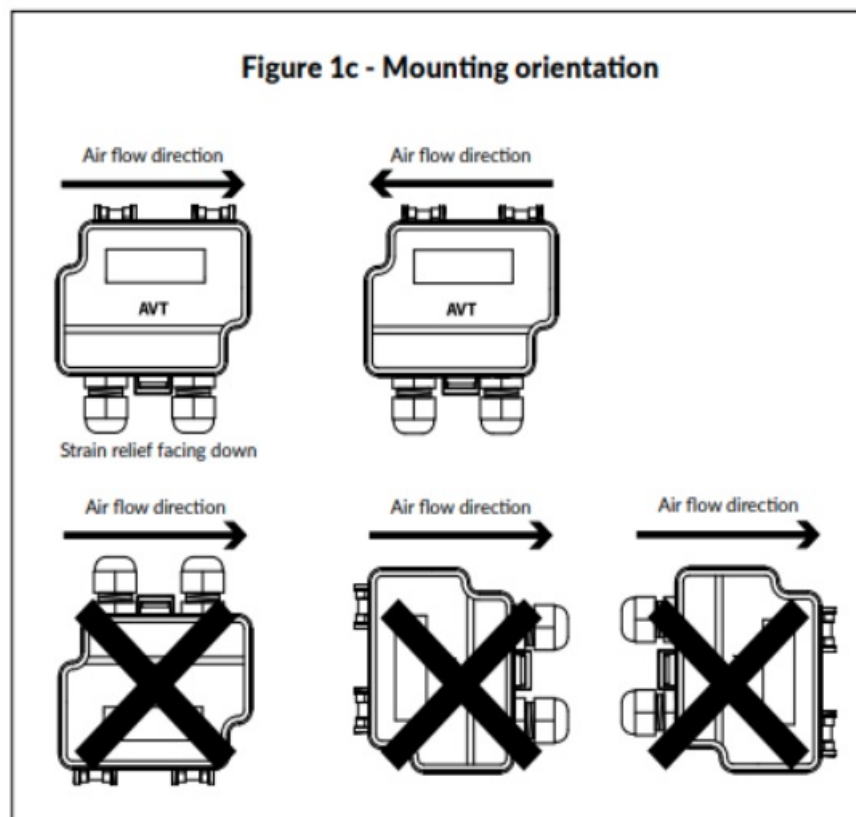
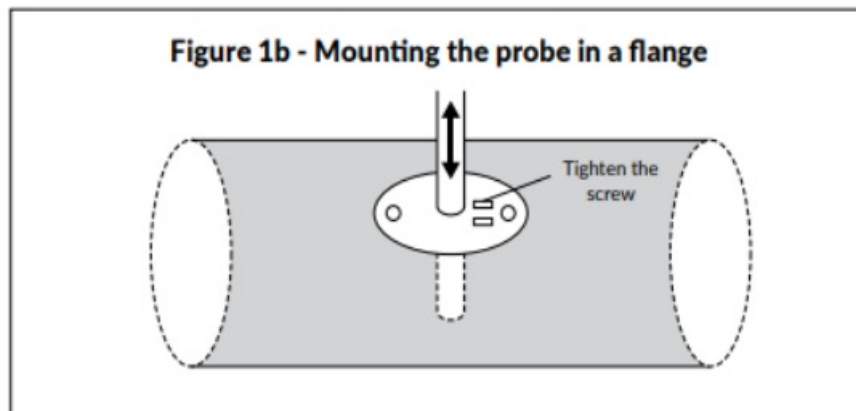
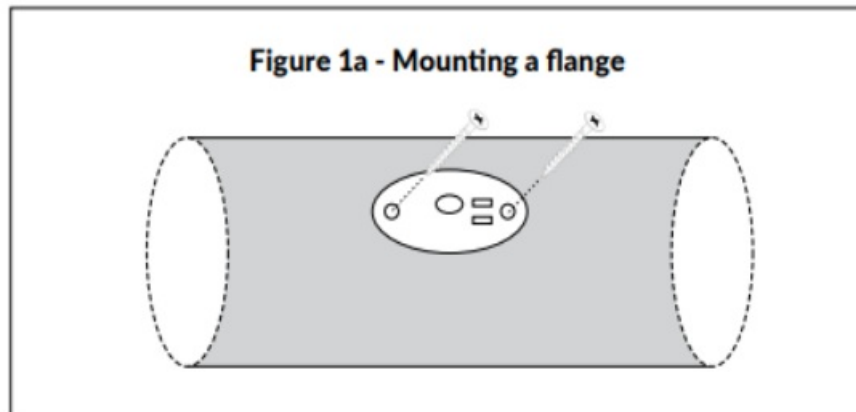
**WARNING:** Apply power only after the device is properly wired.

### STEP 1: MOUNTING THE DEVICE

1. Select the mounting location (on a duct).
2. Use the mounting flange of the device as a template and mark the screw holes.
3. Mount the flange on the duct with screws (not included). (Figure 1a)
4. Adjust the probe to the desired depth. Ensure that the end of the probe reaches the middle of the duct. (Figure

1b)

5. Tighten the screw on the flange to hold the probe in position.

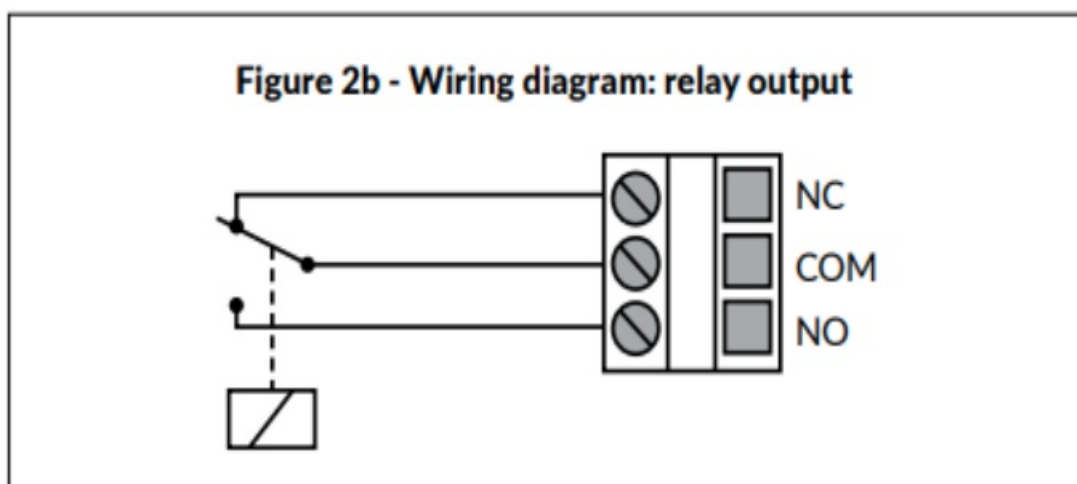
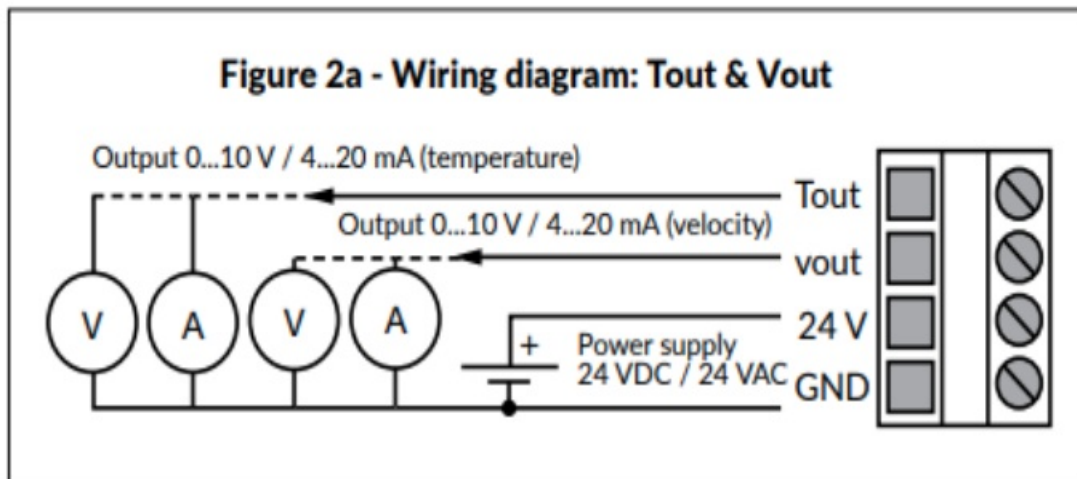


## STEP 2: WIRING DIAGRAMS

For CE compliance a properly grounded shielding cable is required.

1. Unscrew the strain relief and route the cable(s). Use the strain relief on the left for power in and signal out (Tout/vout) and the strain relief on the right for relay.

2. Connect the wires as shown in figure 2a and 2b.
3. Tighten the strain relief.



### CONFIGURATION

1. Select the desired measurement range (see step 3).
2. Select the desired measurement mode (see step 4).
3. Configure the relay (optional) (see step 5).

The device is now ready to be used.

### STEP 3: SELECTING THE MEASUREMENT RANGE

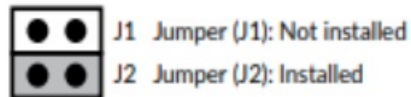
Select the measurement range by installing jumpers as shown in Figure 3a. (See Figure 3a-3b – Jumper settings)

**Figure 3a**

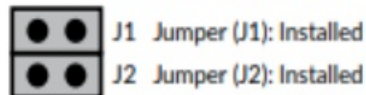
Range 2 (0–2 m/s)



Range 10 (0–10 m/s)

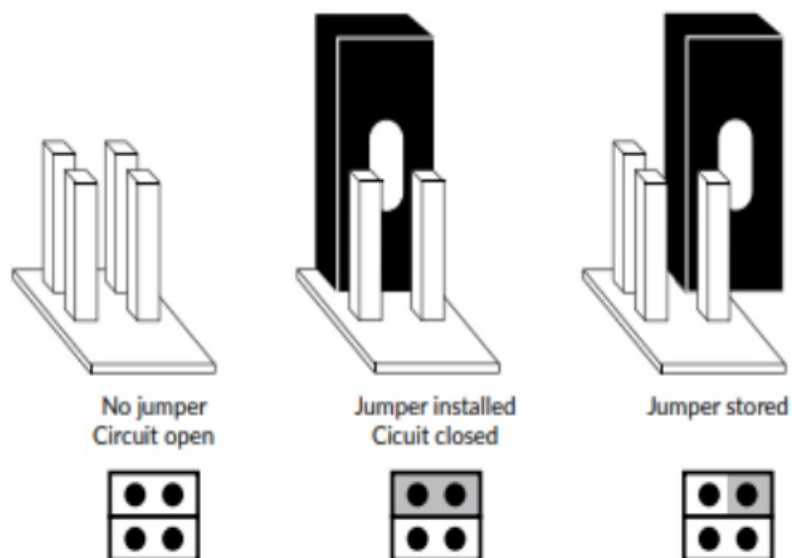


Range 20 (0–20 m/s)



#### SELECTING THE MEASUREMENT RANGE CONTINUED

**Figure 3b - Jumper installation**



(Grey colour indicates that a jumper is installed)

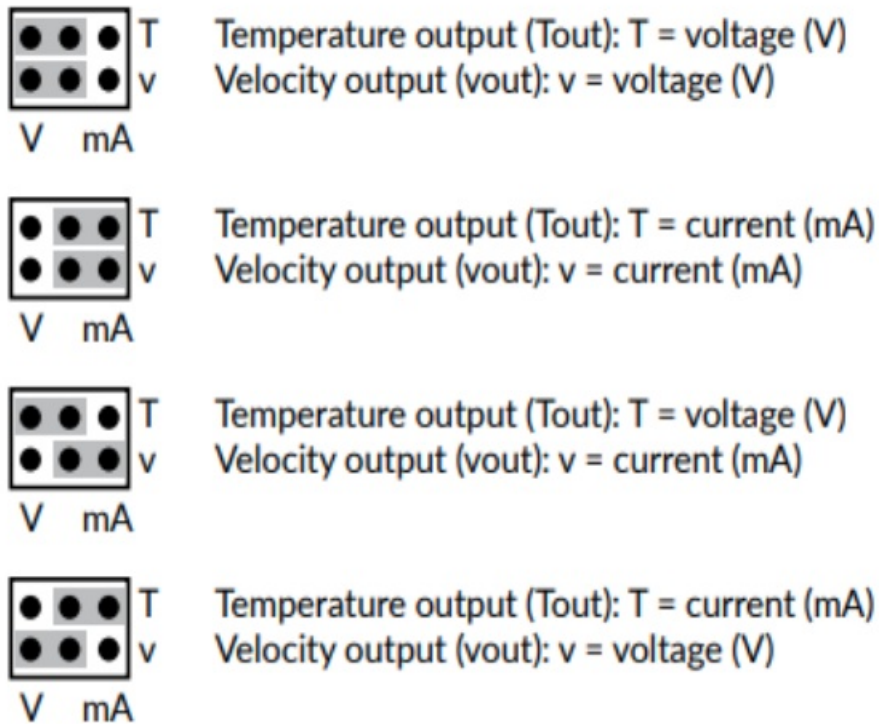
#### STEP 4: SELECTING THE MEASUREMENT MODE

Configure the outputs:

- Temperature output (Tout)
- Velocity output (vout)

Select the output mode current (mA) or voltage (V), by installing jumpers as shown in Figure 4. Both outputs, temperature (T) and velocity (v), are configured separately.

**Figure 4**



**STEP 5: CONFIGURING THE RELAY RELAY MODEL ON**

**1. Switching point (display required)**

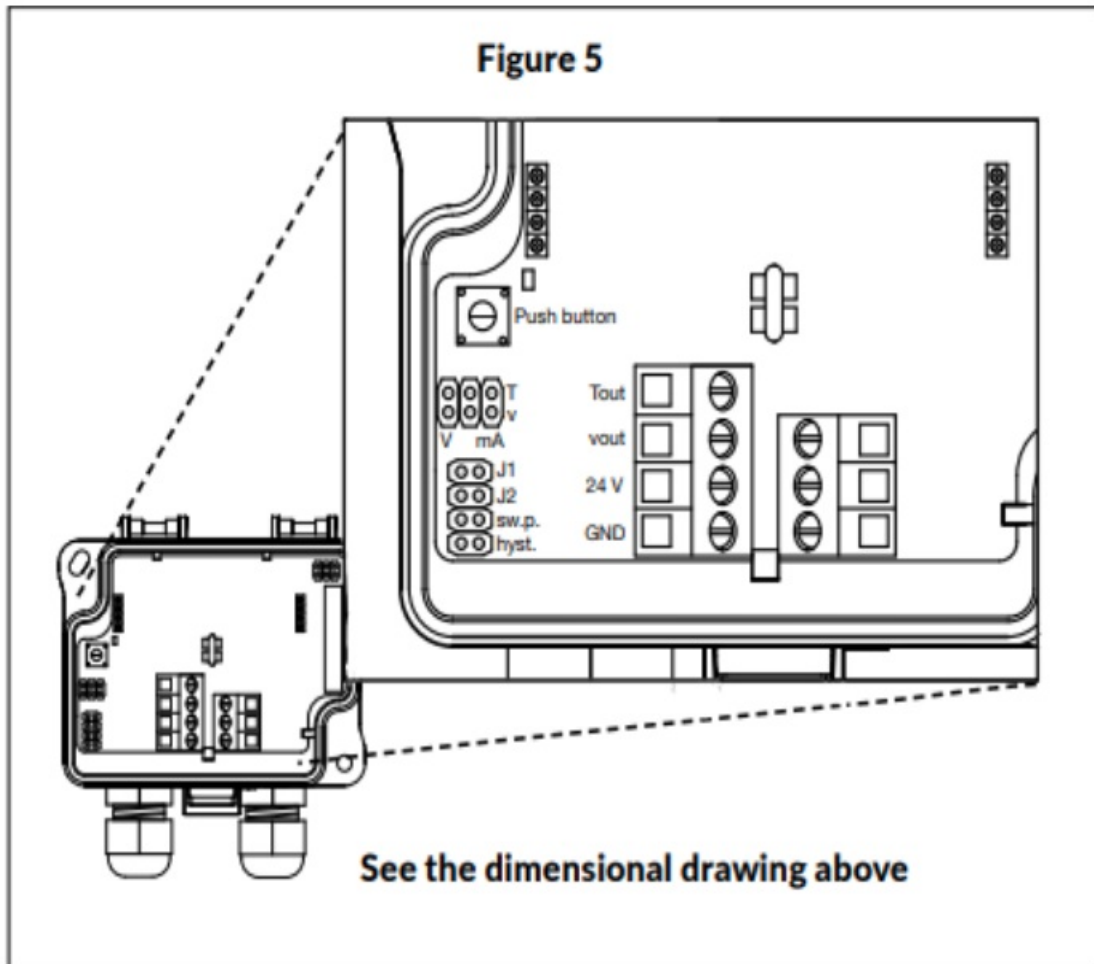
- Install a jumper to pins labeled sw.p. (switching point). (See Figure 5)
- Press down on the pushbutton to select the switching point (e.g. 5,05 m/s = NC) of the relay. The chosen value (m/s) is shown on the display.
- Remove and store the jumper after the configuration is completed.

**2. Hysteresis (display required)**

- Install a jumper to pins labeled hyst. (hysteresis). (See Figure 5)
- Press down on the pushbutton to select the hysteresis of the relay switching point. The chosen value (/) is shown on the display.
- Remove and store the jumper after the configuration is completed.

**NOTE!** Relay configuration jumpers must be removed and stored for proper **operation**.

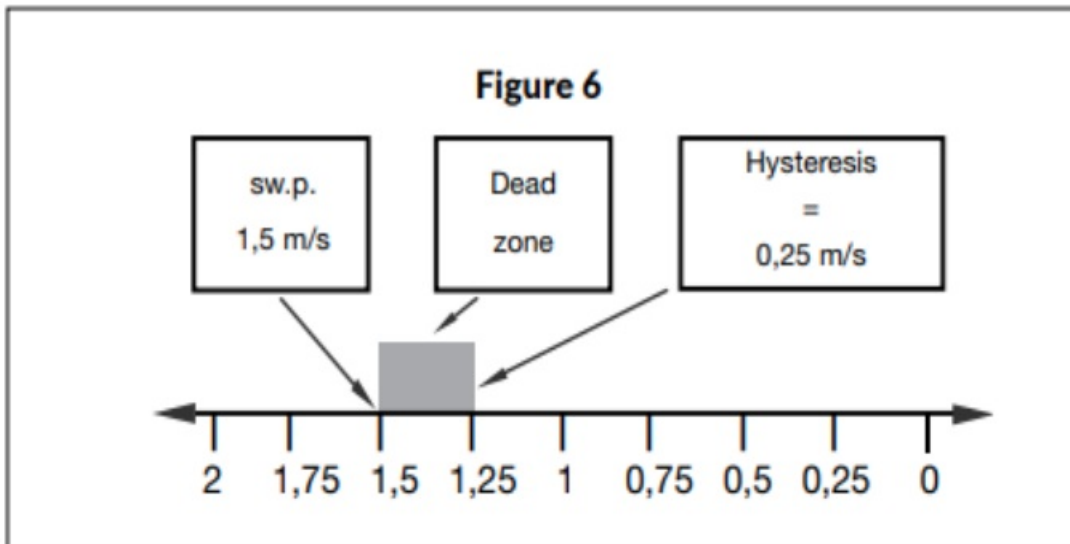
**Figure 5**



### **HSTERESIS**

Hysteresis represents a dead-zone less than or equal to 20 % of the range selected. The hysteresis is anchored at the switching point (sw.p), extending to the hysteresis range selected.

**Figure 6**



In the above example switching point is set at 1,5 m/s, and hysteresis is set at 0,25 m/s. As the velocity increases over 1,5 m/s, the relay will open/close. As velocity reduces, the relay will not close/open until the velocity passes 1,25 m/s, thus preventing rapid cycling.

### **HYSTERESIS CONTINUED**

**Figure 7**

Range	Maximum Hysteresis
m/s	m/s
0 – 2	0.4
0 – 10	2
0 – 20	4

The hysteresis maximum setting is based on the range selected.

#### **RECYCLING/DISPOSAL**

The parts left over from installation should be recycled according to your local instructions.

Decommissioned devices should be taken to a recycling site that specializes in electronic waste.



#### **WARRANTY POLICY**

The seller is obligated to provide a warranty of five years for the delivered goods regarding material and manufacturing. The warranty period is considered to start on the delivery date of the product. If a defect in raw materials or a production flaw is found, the seller is obligated, when the product is sent to the seller without delay or before expiration of the warranty, to amend the mistake at his/her discretion either by repairing the defective product or by delivering free of charge to the buyer a new flawless product and sending it to the buyer. Delivery costs for the repair under warranty will be paid by the buyer and the return costs by the seller. The warranty does not comprise damages caused by accident, lightning, flood or other natural phenomenon, normal wear and tear, improper or careless handling, abnormal use, overloading, improper storage, incorrect care or reconstruction, or changes and installation work not done by the seller. The selection of materials for devices prone to corrosion is the buyer's responsibility, unless otherwise is legally agreed upon. Should the manufacturer alter the structure of the device, the seller is not obligated to make comparable changes to devices already purchased. Appealing for warranty requires that the buyer has correctly fulfilled his/her duties arisen from the delivery and stated in the contract. The seller will give a new warranty for goods that have been replaced or repaired within the warranty, however only to the expiration of the original product's warranty time. The warranty includes the repair of a defective part or device, or if needed, a new part or device, but not installation or exchange costs. Under no circumstance is the seller liable for damages compensation for indirect damage.

Themokon Asia Pacific  
All Formations and Technical data are subject to alteration  
PDI- Series (vaT) V231

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asia pacific

**Documents / Resources**



[thermokon PDI1- Series Air Velocity and Temperature Sensor](#) [pdf] Instructions  
PDI1- Series Air Velocity and Temperature Sensor, PDI1- Series, Air Velocity and Temperature  
Sensor, Temperature Sensor, Sensor