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TELTONIKA FMB140 Advanced Tracker with CAN Data Reading Feature User Manual

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TELTONIKA FMB140 Advanced Tracker with CAN Data Reading Feature



Know your device

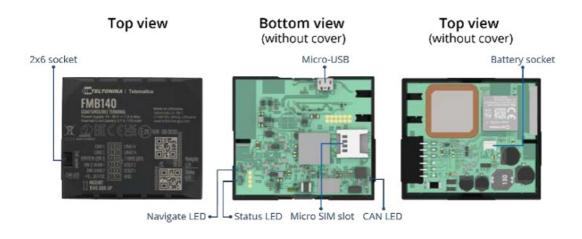


Figure 1 FMB140 device view

Pinout

Table 1 FMB140 2×6 socket pinout

Pin number	Pin name	Description
1	VCC (10-30) V DC (+)	Power supply (+10-30 V DC).
2	DIN 3 / AIN 2	Analog input, channel 2. Input range: 0- 30 V DC / Digital input, channel 3.
3	DIN2-N / AIN1	Digital input, channel 2 / Analog input, channel 2. Input range: 0-30 V DC /GND Sense input
4	DIN1	Digital input, channel 1.
5	CAN2L	CAN LOW, 2nd line
6	CAN1L	CAN LOW, 1st line
7	GND (-)	Ground pin. (10-30) V DC (—)
8	DOUT 1	Digital output, channel 1. Open collector output. Max. 0,5 A DC.
9	DOUT 2	Digital output, channel 2. Open collector output. Max. 0,5 A DC.
10	1WIRE DATA	Data for 1-Wire devices.
11	CAN2H	CAN HIGH, 2nd line
12	CAN1H	CAN HIGH, 1st line



Figure 2 FMB140 2x6 socket pinout

Wiring scheme

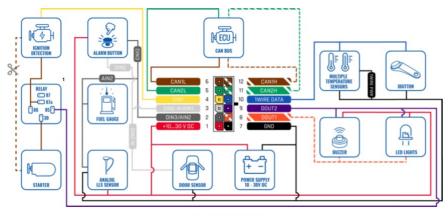


Figure 3 FMB140 Wiring scheme

Set up your device

How to insert Micro-SIM card and connect the battery

1. Gently remove FMB140 cover using plastic pry tool from both sides.

- 2. Insert Micro-SIM card as shown with PIN request disabled or read our Wiki how to enter it later in Teltonika Configurator. Make sure that Micro-SIM card cut-off corner is pointing forward to slot.
- 3. Connect battery as shown to device. Position the battery in place where it does not obstruct other components.
- 4. After configuration, see "PC Connection (Windows)", attach device cover back.

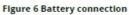












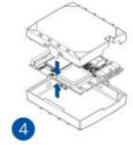


Figure 7 Attaching cover back

PC Connection (Windows)

- 1. Power-up FMB140 with DC voltage (10 30 V) power supply using supplied power cable. LED's should start blinking, see "LED indications".
- 2. Connect device to computer using Micro-USB cable or Bluetooth connection:
 - Using Micro-USB cable
 - You will need to install USB drivers, see "How to install USB drivers (Windows)"
 - Using Bluetooth
 - FMB140 Bluetooth is enabled by default. Turn on Bluetooth on your PC, then select Add Bluetooth or other device > Bluetooth. Choose your device named - "FMBxxx_last_7_imei_digits", without LE in the end. Enter default password 5555, press Connect and then select Done.
- 3. You are now ready to use the device on your computer.

How to install USB drivers (Windows)

- 1. Please download COM port drivers from here.
- 2. Extract and run TeltonikaCOMDriver.exe.
- 3. Click Next in driver installation window.
- 4. In the following window click Install button.

Setup will continue installing the driver and eventually the confirmation window will appear. Click Finish to complete the setup.

Configuration (Windows)

At first FMB140 device will have default factory settings set. These settings should be changed according to the user's needs. Main configuration can be performed via Teltonika Configurator software. Get the latest Configurator version from here. Configurator operates on Microsoft Windows OS and uses prerequisite MS .NET Framework. Make sure you have the correct version installed.

Table 2 MS .NET requirements

MS .NET Framework Operating system Version Links version

Windows Vista Windows 7

Windows 8.1 MS .NET Framework 4.6.2 32 and 64 bit www.microsoft.com

Windows 10

Downloaded Configurator will be in compressed archive. Extract it and launch Configurator.exe. After launch software language can be changed by clicking in the right bottom corner (Figure 8 Language selection).



Figure 8 Language selection

Configuration process begins by pressing on connected device (Figure 9 Device connected via USB).



Figure 9 Device connected via USB

After connection to Configurator Status window will be displayed (Figure 10 Configurator Status window).



Figure 10 Configurator Status window

Various Status window tabs display information about GNSS, GSM, I/O, Maintenance and etc. FMB140 has one user editable profile, which can be loaded and saved to the device. After any modification of configuration, the changes need to be saved to device using Save to device button. Main buttons offer following functionality:

- 1. Load from device loads configuration from device.
- 2. Save to device saves configuration to device.
- 3. Load from file loads configuration from file.
- 4. Save to file saves configuration to file.
- 5. Update firmware updates firmware on device.
- 6. Read records reads records from the device.
- 7. Reboot device restarts device.
- 8. Reset configuration sets device configuration to default.

Most important configurator section is GPRS – where all your server and GPRS settings can be configured and Data Acquisition – where data acquiring parameters can be configured.

More details about FMB140 configuration using Configurator can be found in our Wiki.

Quick SMS configuration

Default configuration has optimal parameters present to ensure best performance of track quality and data usage. Quickly set up your device by sending this SMS command to it:



Note: Before SMS text, two space symbols should be inserted.

GPRS settings:

- 2001 APN
- 2002 APN username (if there are no APN username, empty field should be left)
- 2003 APN password (if there are no APN password, empty field should be left)

Server settings:

- 2004 Domain
- 2005 Port
- 2006 Data sending protocol (0 TCP, 1 UDP)

Default configuration settings Movement and ignition detection:

- · Vehicle movement will be detected by accelerometer
- Ignition will be detected by vehicle power voltage between 13,2 30 V

After successful SMS configuration, FMB140 device will synchronize time and update records to configured server. Time intervals and default I/O elements can be changed by using Teltonika Configurator or SMS parameters.

Mounting recommendations

- · Connecting wires
 - Wires should be connected while the module is not plugged in.
 - Wires should be fastened to stable wires or other non-moving parts. Any heat emitting and/or moving objects should be kept away from the wires.
 - There should be no exposed wires. If factory isolation was removed while connecting the wires, the isolation material should be applied.
 - If the wires are placed in the exterior or in places where they can be damaged or exposed to heat, humidity, dirt, etc., additional isolation should be applied and the wires should not be loose.
 - Wires cannot be connected to the board computers or control units.
- · Connecting power source
 - Be sure that after the car computer goes to sleep mode, power might be still available on the power wires. Depending on the car model, this may happen in 5 to 30 minutes period.
 - When the module is connected, measure the voltage again to make sure it did not decrease.
 - It is recommended to connect to the main power cable in the fuse box.
- Connecting ignition wire
 - Be sure to check if it is a real ignition wire i. e. power does not disappear after starting the engine.
 - Check if this is not an ACC wire (when key is in the first position, most of the vehicle electronics are available).
 - Check if power is still available when you turn off any of vehicles devices.

- Ignition is connected to the ignition relay output. As alternative, any other relay, which has power output when ignition is on, may be chosen.
- · Connecting ground wire
 - Ground wire is connected to the vehicle frame or metal parts that are fixed to the frame.
 - If the wire is fixed with the bolt, the loop must be connected to the end of the wire.
 - For better contact scrub paint from the spot where loop is going to be connected.

LED indications

Table 3 Navigation LED indications

Behavior Meaning

Permanently switched on GNSS signal is not received

Blinking every second Normal mode, GNSS is working

GNSS is turned off because:

Off Device is not working or Device is

in sleep mode

Blinking fast constantly Device firmware is being flashed

Table 4 Status LED indications

Behavior Meaning

Blinking every second Normal mode

Blinking every two seconds Sleep mode

Blinking fast for a short time Modem activity

Device is not working or Device is

in boot mode

Table 5 CAN Status LED indications

Behavior Meaning

Blinking fast constantly Reading CAN data from vehicle

Permanently switched on Wrong program number or

wrong wire connection
Wrong connection or CAN

processor

Off

in sleep mode

Characteristics

Off

Basic characteristics

Table 6 Basic characteristics

Name Teltonika TM2500

GSM, GPRS, GNSS,

Technology BLUETOOTH

GNSS GPS, GLONASS, GALILEO,

BEIDOU, QZSS, AGPS

Receiver Tracking: 33
Tracking sensitivity -165 dBM

 Accuracy
 < 3 m</td>

 Hot start
 < 1 s</td>

 Warm start
 < 25 s</td>

 Cold start
 < 35 s</td>

 Technology
 GSM

Data transfer

2G bands Quad-band 850/900/1800/1900

MHz

GPRS Multi-Slot Class 12 (up to 240 kbps), GPRS Mobile Station

Class B

Data support SMS (text/data)

Input voltage range 10-30 V DC with overvoltage

protection

Back-up battery 170 mAh Li-lon battery 3.7 V (0.63

Wh)

Internal fuse 3 A, 125 V

At 12V < 6 mA (<u>Ultra Deep Sleep</u>) At 12V < 8 mA (<u>Deep Sleep</u>)

At 12V < 11 mA (<u>Online Deep</u> <u>Sleep</u>) At 12V < 20 mA (<u>GPS</u>

Sleep)

Power consumption At 12V < 35 mA (nominal with no

load) At 12V < 1.5 A Max. (with full

Load / Peak)

Digital Inputs 3

Negative Inputs 1 (Digital input 2)

Digital Outputs 2
Analog Inputs 2
CAN interfaces 2

1-Wire data)
GNSS antenna Internal High Gain
GSM antenna Internal High Gain
USB 2.0 Micro-USB
LED indication 3 status LED lights
SIM Micro-SIM + eSIM

Memory 128MB internal flash memory

Fuel Level (Dashboard), Total fuel consumption, Vehicle speed (wheel), Vehicle driven distance,

CAN Data Engine speed

(RPM), Accelerator pedal position

Sensors Accelerometer

Green Driving, Over Speeding detection, Jamming detection, GNSS Fuel Counter, DOUT Control Via Call, Excessive Idling detection, Immobilizer, iButton Read Notification, Unplug detection, Towing detection, Crash detection, Aut

Scenarios <u>detection, Crash detection, Auto</u>

Geofence, Manual Geofence,

Trip

GPS Sleep, Online Deep Sleep,

Deep

Sleep modes

Sleep, Ultra Deep Sleep

FOTA Web, FOTA, Teltonika Configurator (USB, Bluetooth),

FMBT

Configuration and firmware

update

mobile application

(Configuration)

Configuration, Events, DOUT

control,

SMS

Debug

GPRS commands Configuration, DOUT control,

Debug

Time Synchronization GPS, NITZ, NTP

Digital Input 1, Accelerometer,

External

Ignition detection

Power Voltage, Engine

Value

Electrical characteristics

Table 7 Electrical characteristics

Static Drain-Source resistance

Characteristic description	Min.	Тур.	Max.	Unit
Drain current (Digital Output OFF)			120	μΑ
Drain current (Digital Output ON, Recommended Operating Conditions	s)	0.1	0.5	Α

(Digital Output ON)

400 600 mΩ

Input resistance (DIN1)	47			kΩ
Input resistance (DIN2)	38.45			kΩ
Input resistance (DIN3)	150			kΩ
Input voltage (Recommended	0		Supply	V
Operating Conditions)	U		voltage	V
Input Voltage threshold (DIN1)		7.5		٧
Input Voltage threshold (DIN2)		2.5		٧
Input Voltage threshold (DIN3)		2.5		٧
Input voltage (Recommended	0		+10	V
Operating Conditions), Range 1	Ū		110	•
Input resistance, Range 1		38.45		kΩ
Measurement error on 12V, Range 1		0.9		%
Additional error on 12 V, Range 1		108		mV
Measurement error on 30 V, Range 1		0.33		%
Additional error on 30 V, Range 1		88		mV
Input Voltage (Recommended	0		+30	٧
Operating Conditions), Range 2		450		
Input resistance, Range 2		150		kΩ
Measurement error on 12 V, Range 2		0.9		%
Additional error on 12 V, Range 2		108		mV
Measurement error on 30 V, Range 2		0.33		%
Additional error on 30 V, Range 2		88		mV
Input resistance	38.45			kΩ
Input voltage (Recommended	0		Supply	٧
Operating Conditions)		٥.	voltage	V
Input voltage threshold Sink current		0.5	100	•
			180	nA
Internal terminal resistors CAN bus (no internal termination resistors)				Ω
Differential input resistance	19	30	52	kΩ
Recessive output voltage	2	2.5	3	V
Differential receiver threshold voltage		0.7	0.9	V
Common mode input voltage	-30	0.7	30	V
				V
Supply voltage	+4.5	7	+4.7	
Output inner resistance		7		Ω ~ ^
Output current (Uout > 3.0 V)		30 75		mA m^
Short circuit current (Uout = 0)		75		mΑ

Safety information

This message contains information on how to operate FMB140 safely. By following these requirements and recommendations, you will avoid dangerous situations. You must read these instructions carefully and follow them strictly before operating the device!

- The device uses SELV limited power source. The nominal voltage is + 12 V DC. The allowed voltage range is +10...+30 V DC.
- To avoid mechanical damage, it is advised to transport the device in an impact-proof package. Before usage, the device should be placed so that its LED indicators are visible. They show the status of device operation.
- When connecting the 2×6 connector wires to the vehicle, the appropriate jumpers of the vehicle power supply should be disconnected.
- Before unmounting the device from the vehicle, the 2×6 connector must be disconnected. The device is designed to be mounted in a zone of limited access, which is inaccessible to the operator. All related devices must meet the requirements of EN 62368-1 standard. The device FMB140 is not designed as a navigational device for boats.

Do not disassemble the device. If the device is damaged, the power supply cables are not isolated or the isolation is damaged, DO NOT touch the device before unplugging the power supply.

All wireless data transferring devices produce interference that may affect other devices which are placed nearby.

The device must be connected only by qualified personnel.

The device must be firmly fastened in a predefined location.

The programming must be performed using a PC with autonomic power supply.

The device is susceptible to water and humidity.

CAUTION: Risk of explosion if battery is replaced by an incorrect type. Dispose of used batteries according to the instructions.

Battery should not be disposed of with general household waste. Bring damaged or worn-out batteries to your local recycling center or dispose them to battery recycle bin found in stores.

Certification and Approvals

- FMB140 CE / RED
- FMB140 E-Mark
- FMB140 EAC
- FMB140 RoHS
- FMB140 REACH
- FMB140 Declaration of IMEI assignment
- FMB140 Anatel certificate

This sign on the package means that it is

necessary to read the User's Manual before your start using the device. Full User's

Manual version can be found in our Wiki.

This sign on the package means that all used electronic and electric equipment should not be mixed with general household waste.

Hereby, Teltonika declare under our sole responsibility that the above described product is in conformity with the relevant Community harmonization: European Directive 2014/53/EU (RED).

For more information, see the ANATEL website www.anatel.gov.br

This equipment is not entitled to protection against harmful interference and must not cause interference in duly authorized systems.

Warranty

TELTONIKA guarantees its products to be free of any manufacturing defects for a period of 24 months. With additional agreement we can agree on a different warranty period, for more detailed information please contact our sales manager.

Contact us teltonika-qps.com/about-us/contacts/

All batteries carry a reduced 6 month warranty period.

If a product should fail within this specific warranty time, the product can be:

- Repaired
- · Replaced with a new product
- Replaced with an equivalent repaired product fulfilling the same functionality
- TELTONIKA can also repair products that are out of warranty at an agreed cost.

Warranty Disclaimer

TELTONIKA PRODUCTS ARE INTENDED TO BE USED BY PERSONS WITH TRAINING AND EXPERIENCE. ANY OTHER USE RENDERS THE LIMITED WARRANTIES EXPRESSED HEREIN AND ALL IMPLIED WARRANTIES NULL AND VOID AND SAME ARE HEREBY EXCLUDED. ALSO EXCLUDED FROM THIS LIMITED WARRANTY ARE ANY AND ALL INCIDENTAL OR CONSEQUENTIAL DAMAGES INCLUDING BUT NOT LIMITED TO, LOSS OF USE OR REVENUE, LOSS OF TIME, INCONVENIENCE OR ANY OTHER ECONOMIC LOSS.

More information can be found at teltonika-gps.com/warranty-repair

Documents / Resources



TELTONIKA FMB140 Advanced Tracker with CAN Data Reading Feature [pdf] User Manual FMB140 Advanced Tracker with CAN Data Reading Feature, FMB140, FMB140 Advanced Tracker, Advanced Tracker, Advanced Tracker with CAN Data Reading Feature, Tracker with CAN Data Reading Feature

References

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- O Anatel Agência Nacional de Telecomunicações
- Microsoft Cloud, Computers, Apps & Gaming
- **Teltonika Telematics**
- **Teltonika Telematics**
- Cara Telematics
- C Expand The Usage Of GPS Trackers With Handy Our Accessories
- C Expand The Usage Of GPS Trackers With Handy Our Accessories
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- <u>wiki.teltonika-gps.com/view/Teltonika_Configurator_versions</u>

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