



neptronic TM220FN Non Spring Return Damper Actuator Instruction Manual

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Features:

- Clutch for manual adjustments.
- Maintenance free.
- Position indicator.
- Control signal fully programmable.
- Brushless DC driven motor.
- Fail safe by Enerdrive System1 (on model 260 & 280).
- Auxiliary switches (on model 260 & 280).

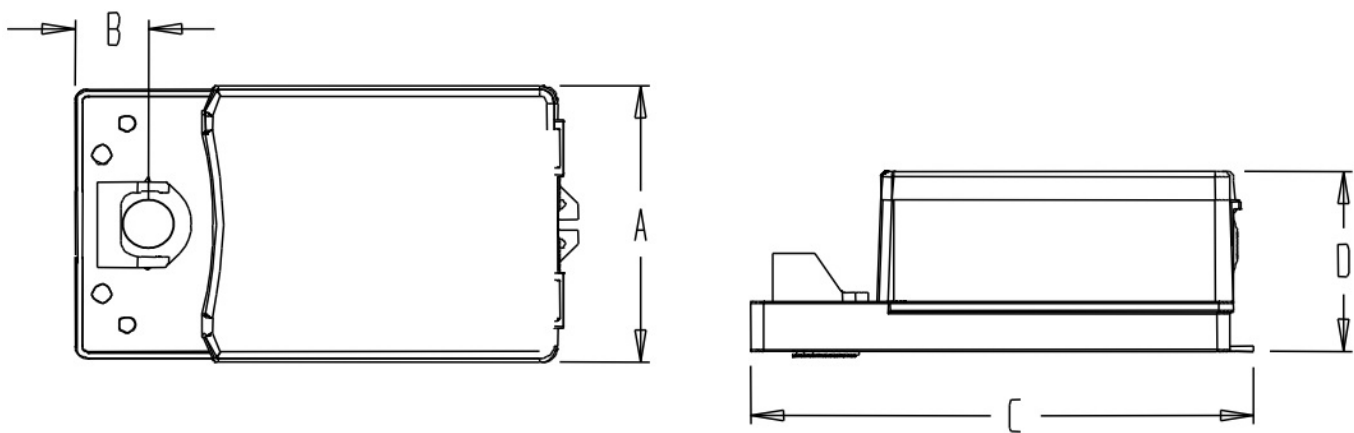
Technical Data

	TM200F N	TM220F N	TM260FN	TM280F N	RM200F N	RM220F N	RM260F N	RM280F N
Auxiliary switches	No	Yes (2)	No	Yes (2)	No	Yes (2)	No	Yes (2)
Fail safe – <i>Enerdrive</i>	No		Yes		No		Yes	
Power consumption	30 VA		50 VA Peak, 30 VA		30 VA		50 VA Peak, 30 VA	

Torque	120 in.lb. [13.5 Nm] at rated voltage	240 in.lb. [27 Nm] at rated voltage
Running time through 90°	20 sec torque dependant	
Power supply	28 to 32 Vdc or 22 to 26 Vac, 220 to 250 Vac 50/60Hz	
Feedback	4 to 20 mA or 2 to 10 Vdc adjustable	
Electrical connection	18 AWG [0.8 mm ²] minimum	
Inlet bushing	2 inlet bushing of 7/8 in [22.2 mm]	
Control signal	Analog, Digital or PWM programmable (factory set with analog control signal)	
Angle of rotation	0 to 90 degrees, electronically adjustable (factory set with 90° stroke)	
Direction of rotation	Reversible, Clockwise (CW) or Counterclockwise (CCW) (factory set with CW direction)	
Operating temperature	0°F to 122°F [-18°C to 50°C]	
Storage temperature	-22°F to 122°F [-30°C to 50°C]	

Relative Humidity	5 to 95 % non condensing.	
Weight	5 lbs. [2.3 kg]	8 lbs. [3.5 kg]
Warning: Do not press the clutch when actuator is powered		

Dimensions



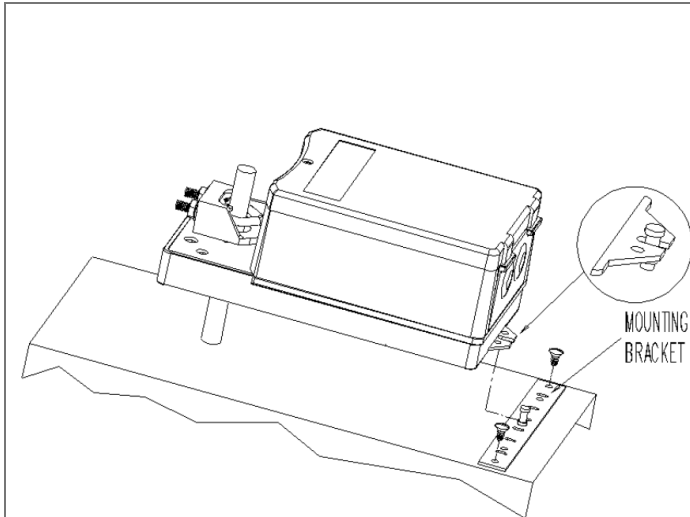
Dimension	Imperial (in)	Metric (mm)
A	5.20	132.1
B	1.33	33.8
C	9.13	231.9
D	3.55	90.2

Caution

We strongly recommend that all Neutronic® products be wired to a separate transformer and that transformer shall service only Neutronic® products. This precaution will prevent interference with, and/or possible damage to incompatible equipment.

When multiple actuators are wired on a single transformer, polarity must be observed. Long wiring runs create voltage drop which may affect the actuator performance.

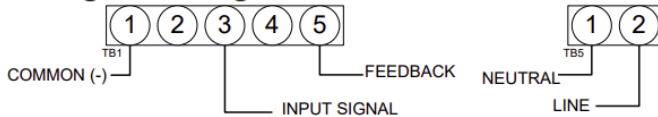
Mechanical Installation



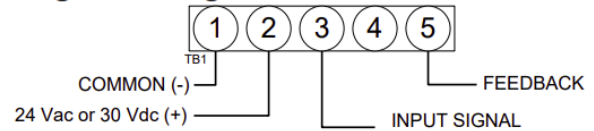
1. Manually close the damper blades and positioned the actuator at 0° or 90°.
2. Slide the actuator onto the shaft.
3. Tighten the nuts on the “U” bolt to the shaft with a 10mm wrench to a torque of 150 in.lb. [17 Nm].
4. Slide the mounting bracket under the actuator. Ensure free movement of the slot at the base of the actuator. The bracket pin must be placed in the mid distance of the slot
5. Fix the bracket to the ductwork with #8 self-tapping screws.

Wiring Diagrams

Analog line voltage

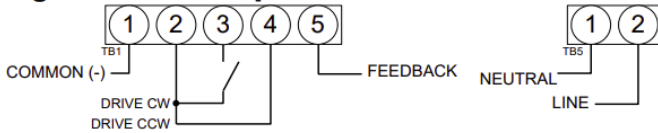


Analog low voltage

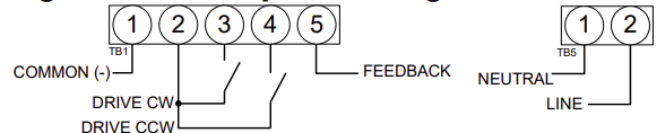


Digital signal from internal source

Digital – 3 wire / 2 position

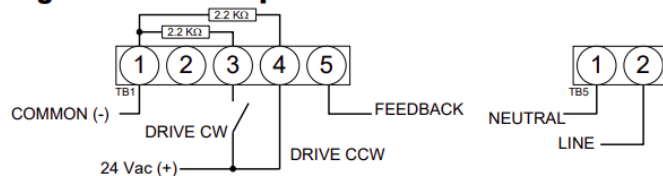


Digital – 4 wire / 3 point floating

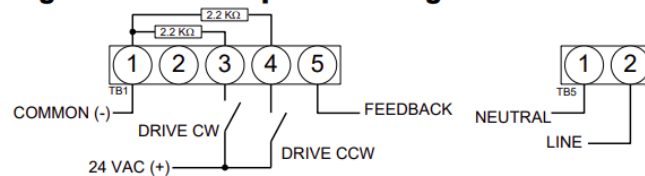


Digital signal

Digital – 3 wire / 2 position




Digital – 4 wire / 3 point floating



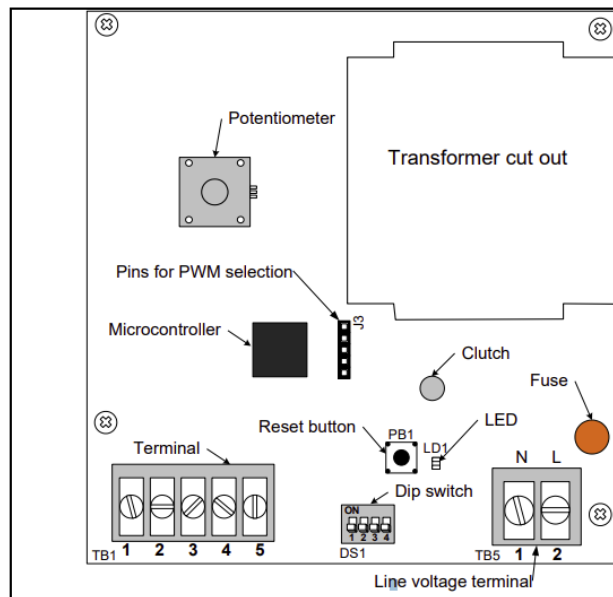
Special consideration for Digital control

In this mode, the actuator is sensitive to induced electrical voltages **from external sources**. To prevent such interference, if the signal on pins 4 and 3 on TB1 are from an **external 24 Vac source**, install a resistor 2.2kohm, 0.5W between pins 4 and 1 and another of 2.2kohms, 0.5W between pins 3 and 1 of TB1. These resistors are included.

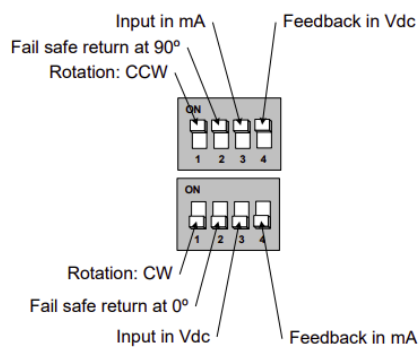
Input Signal and Feedback setup

	Input Signal	Feedback
Analog Mode	Input Signal is set with Dipswitch # 3 DS1 -3 at OFF = 2 – 10Vdc (default setting) D S1-3 at ON = 4 – 20mA	Feedback is set with Dipswitch #4 DS1-4 a t OFF = 4 – 20mA (default setting) DS1-4 a t ON = 2 – 10Vdc
Digital & PWM Mode	No Input Signal Setting  <i>DS1-3 MUST be at OFF</i>	

PC Board



Dip switch settings



Default Setting = All dipswitches at OFF

Stroke adjustment – No control signal change

1. Apply power and, WAIT FOR LED TO BE OFF (around 10 seconds).
2. Press and release the reset button to start the auto-stroke process.

The LED should be illuminated.

- **First option:**

The actuator will then travel in both directions to find its limit and position itself according to the demand.
The LED will extinguish, the process is complete.

- **Second option:**

When the desired start position is reached, press and release the reset button. The actuator will now go the end position. (you can also press and release the reset button when it reaches the end position)

The LED will extinguish, the process is complete

Programming – Change of control signal & PWM pulse setting

1. Remove power and put all dip switches “OFF”. (factory preset).
2. Apply power and, within 10 seconds, press and release the reset button. The LED should be blinking.
3. Select the control signal with dip switches:

	Digital or Analog Modes	PWM Mode
Move switch No1 “ON” and then “OFF” ”.	Digital (On/Off or 3 point floating)	5 sec. pulse (factory preset)
Move switch No2 “ON” and then “OFF” ”.	Analog (Default)	25 sec. pulse

4. Stroke adjustment see the stroke adjustment section above.

Enabling or disabling PWM mode

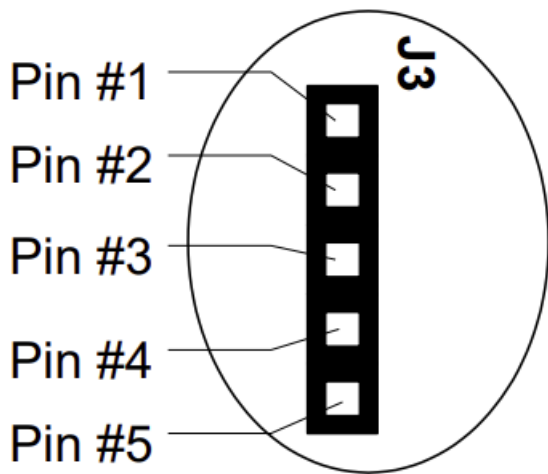
1. Remove power supply to actuator
2. Install jumper between pin 3 & 4 of J3
3. Select the desired action using the dipswitches (DS1):

DS1-1	DS1-2	Action
OFF	ON	Enable PWM Mode
ON	OFF	Disable PWM Mode

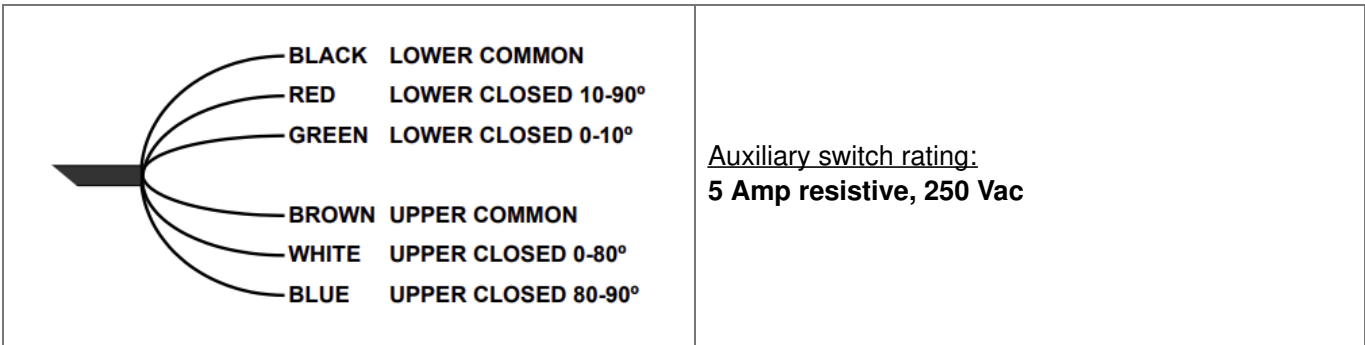
4. Re-apply power supply to actuator
5. Wait 5 seconds
6. Remove power supply to actuator
7. Remove jumper between pin 3 & 4 of J3, re-install it between pin 4 & 5.
8. Re-apply power supply to actuator

PWM is factory preset at 5 sec. pulse, refer to programming section above to change pulse setting.

When not used for programming, jumper is placed between pin 4 & 5



Wiring Diagrams for auxiliary switches (on model 220 & 280)



n e p t r o n i c[®]

Documents / Resources

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 TM200FN, TM220FN, TM260FN, TM280FN, RM200FN, RM220FN, RM260FN, RM280FN, TM
 220FN Non Spring Return Damper Actuator, Non Spring Return Damper Actuator, Return Dam
 per Actuator, Damper Actuator, Actuator