



# Milesight EM320-TILT LoRaWAN Tilt Sensor User Guide

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**Milesight EM320-TILT LoRaWAN Tilt Sensor**



## Product Information

The EM320-TILT is a tilt sensor that is used to measure the angle of an object with respect to gravity. The device is designed to provide accurate and reliable readings, and it comes with a number of safety precautions that must be followed to ensure proper usage.

## Safety Precautions

- Do not disassemble or remodel the device in any way.
- Change the device password when first configuring it to protect its security. The default password is 123456.
- Do not place the device close to objects with naked flames.
- Do not place the device where the temperature is below/above the operating range.
- The device is not intended to be used as a reference sensor, and damage may result from inaccurate readings.
- Remove the battery from the device if it is not to be used for an extended period to prevent battery leakage and damage to the device.
- Make sure all batteries are new when installing, or battery life will be reduced.
- The device must never be subjected to shocks or impacts.

## Declaration of Conformity

The EM320-TILT is in conformity with the essential requirements and other relevant provisions of the CE, FCC, and RoHS.

## Contact Information

- Email: [iot.support@milesight.com](mailto:iot.support@milesight.com)

- **Support portal:** support.milesight-iot.com
- **Tel:** 86-592-5085280
- **Fax:** 86-592-5023065
- **Address:** Building C09, Software Park III, Xiamen 361024, China

## Product Usage Instructions

### Installation

Before installing the EM320-TILT, ensure that all the items in the packing list are present and undamaged. If any item is missing or damaged, contact your sales representative. Follow these steps to install the device:

1. Choose a suitable location for the device.
2. Mount the device on a stable surface using the provided mounting hardware.
3. Connect the device to a power source using the provided cable.

### Device Payload

The EM320-TILT provides basic information, sensor data, and downlink commands. Follow these steps to access the device payload:

1. Connect to the device using a compatible device or software.
2. Select the desired payload type.
3. View the payload data.

**Note:** Consult the user manual or contact technical support for more detailed instructions on accessing the device payload.

### Safety Precautions

Milesight will not shoulder responsibility for any loss or damage resulting from not following the instructions of this operating guide.

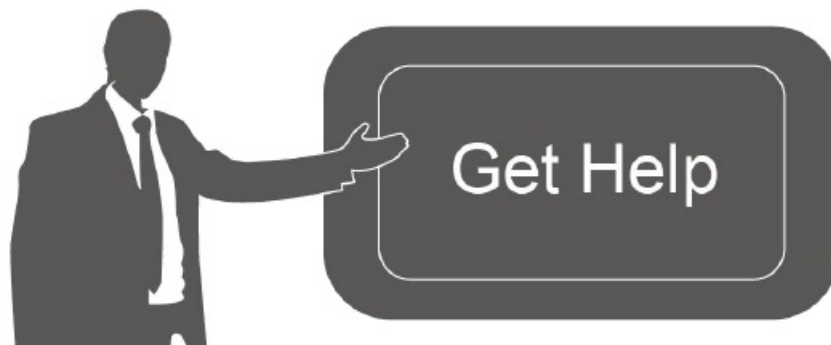
- The device must not be disassembled or remodeled in any way.
- In order to protect the security of the device, please change device password when first configuration. The default password is 123456.
- Do not place the device close to objects with naked flames.
- Do not place the device where the temperature is below/above the operating range.
- The device is not intended to be used as a reference sensor, and Milesight will not should responsibility for any damage which may result from inaccurate readings.
- The battery should be removed from the device if it is not to be used for an extended period. Otherwise, the battery might leak and damage the device. Never leave a discharged battery in the battery compartment.
- Make sure all batteries are newest when install, or battery life will be reduced.
- The device must never be subjected to shocks or impacts.

### Declaration of Conformity

EM320-TILT is in conformity with the essential requirements and other relevant provisions of the CE, FCC, and RoHS.

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**For assistance, please contact Milesight technical support:**

**Email:** [iot.support@milesight.com](mailto:iot.support@milesight.com)

**Support portal:** [support.milesight-iot.com](https://support.milesight-iot.com)

**Tel:** 86-592-5085280

**Fax:** 86-592-5023065

**Address:** Building C09, Software Park III,

## Revision History

Date	Doc Version	Description
Feb.14, 2023	V 1.0	Initial version

## Product Introduction

### Overview

EM320-TILT is an LoRaWAN® tilt sensor mainly for angle measurement and asset movement detection. With a compact size and 3-axis accelerometer, EM320-TILT can be installed to the objects easily to measure its X,Y,Z tilt angles. In addition, EM320-TILT supports customizing initial position to detect movement based on angle changes and send threshold alarms. Compliant with Milesight LoRaWAN® gateway and Milesight IoT Cloud solution, users can know the angles and tilt threshold alarms in real-time via browser or mobile app remotely. EM320-TILT can be widely used in tree monitoring, pole lean detection, landslide monitoring, etc.

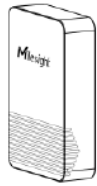
### Features

- Built-in MEMS accelerometer sensor to measure the 3-axis angles of any objects
- Flexible threshold condition settings, suitable for different kinds of applications
- Easy to install, suitable for various types of objects as trees, poles, grounds, etc.
- IP67 waterproof enclosure for outdoor applications
- Anti-theft design on back cover to secure firm and sturdy installation
- Ultra-wide-distance wireless transmission up to line of sight of 15km
- Equipped with NFC for one touch configuration

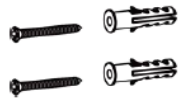
- Function well with standard LoRaWAN® gateways and network servers
- Compliant with Milesight IoT Cloud

## Hardware Introduction

### Packing List



1 × EM320-TILT  
Sensor



2 × Wall  
Mounting Kits



1 × Fixing Screw



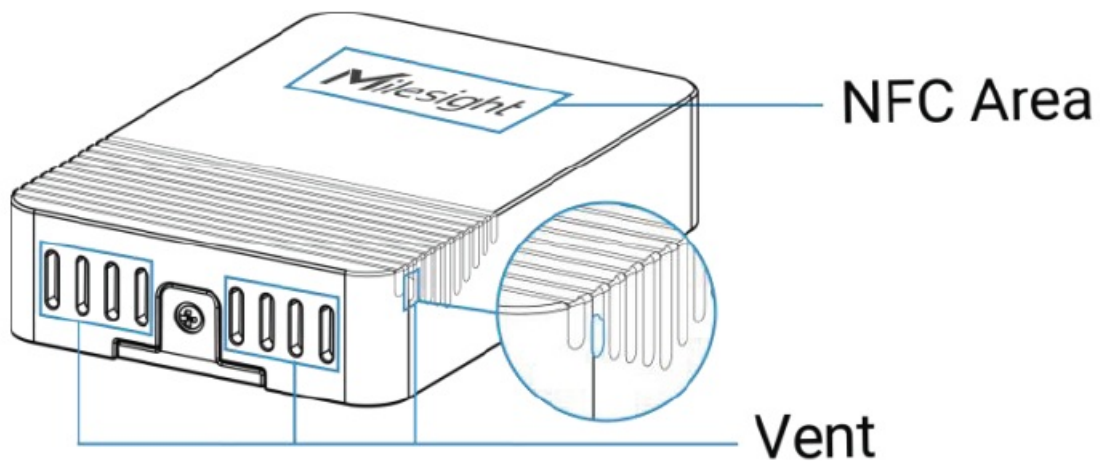
1 × Quick Start  
Guide



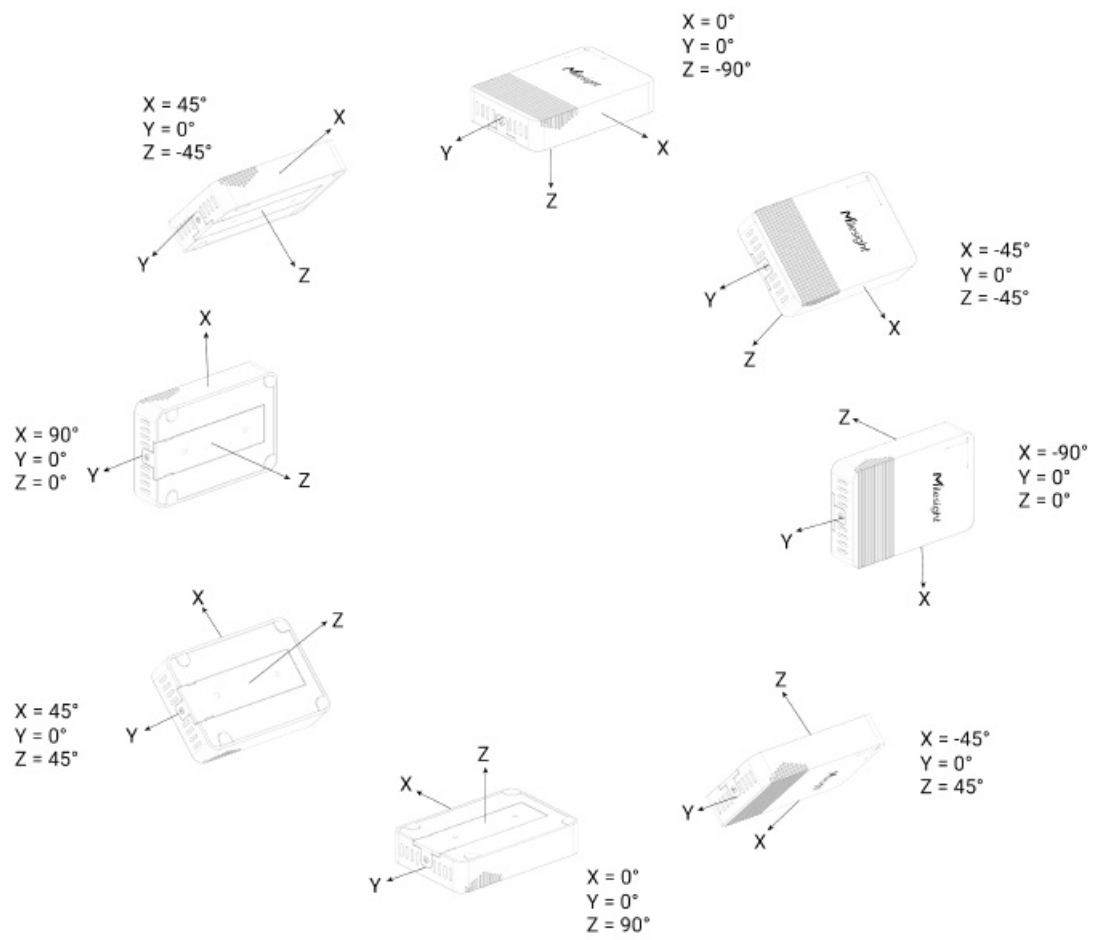
1 × Warranty  
Card

If any of the above items is missing or damaged, please contact your sales Representative.

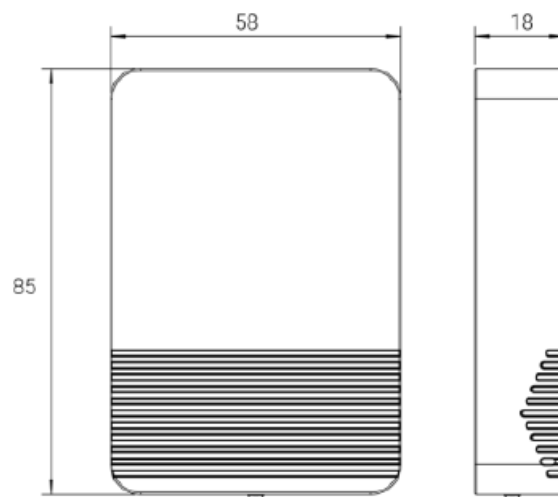
### Hardware Overview



When you install EM320-TILT on site, below is the angle number you can expect with corresponding device gesture.



## Dimensions(mm)



## Power Button

The LED indicator and power button are inside the device. Switch on/off and reset can also be configured via NFC.

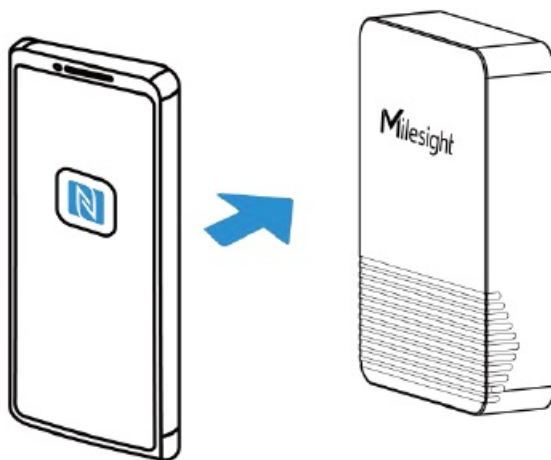
Function	Action	LED Indication
Turn On	Press and hold the button for more than 3 seconds.	Off → On
Turn Off	Press and hold the button for more than 3 seconds.	On → Off
Reset	Press and hold the button for more than 10 seconds.	Blink 3 times.
Check	Quickly press the power button.	Light On: Device is on.
On/Off Status		Light Off: Device is off.

## Operation Guide

### NFC Configuration

EM320-TILT sensor can be monitored and configured via NFC. Please refer the following steps to complete the configuration.

1. Download and install “Milesight ToolBox” App from Google Play or Apple App Store.
2. Enable NFC on the smartphone and launch Milesight ToolBox.
3. Attach the smartphone with NFC area to the device to read device information. Basic information and settings of the device will be shown on ToolBox App if it's recognized successfully. You can read and configure the device by tapping the Read/Write device on the App. In order to protect the security of the device, please change the password when first configuring. The default password is 123456.



### Note:

1. Ensure the location of smartphone NFC area and it's recommended to take off phone case.
2. If the smartphone fails to read/write configurations via NFC, keep the phone away and back to try again.
3. EM320-TILT sensor can also be configured by dedicated NFC reader, which can be purchased from Milesight IoT.

### LoRaWAN Settings

LoRaWAN settings is used for configuring the transmission parameters in LoRaWAN® network.

#### Basic LoRaWAN Settings:

Go to Device > Settings > LoRaWAN Settings of ToolBox App to configure join type, App EUI, App Key and other

information. You can also keep all settings by default.

Device EUI

24E124785C381440

\* APP EUI

24e124c0002a0001

\* Application Port - 85 +

Join Type

OTAA

\* Application Key

\*\*\*\*\*

LoRaWAN Version

V1.0.3

Work Mode

Class A

Confirmed Mode ⓘ ☒

Rejoin Mode ☒

Set the number of detection signals sent ⓘ

32

ADR Mode ⓘ ☒

Spreading Factor ⓘ

SF10-DR2

TXPower

TXPower0-16 dBm

Parameters	Description
Device EUI	Unique ID of the device which can also be found on the label.



App EUI	Default App EUI is 24E124C0002A0001.
Application Port	The port is used for sending and receiving data, default port is 85.
Join Type	OTAA and ABP mode are available.
Application Key	Appkey for OTAA mode, default is 5572404C696E6B4C6F52613230313823.
Device Address	DevAddr for ABP mode, default is the 5th to 12th digits of SN.
Network Session Key	Nwkskey for ABP mode, default is 5572404C696E6B4C6F52613230313823.
Application Session Key	Appskey for ABP mode, default is 5572404C696E6B4C6F52613230313823.
LoRaWAN Version	V1.0.2, V1.0.3 are available.
Work Mode	It's fixed as Class A.
RX2 Data Rate	RX2 data rate to receive downlinks.
RX2 Frequency	RX2 frequency to receive downlinks. Unit: Hz
Spread Factor	If ADR is disabled, the device will send data via this spread factor.
Confirmed Mode	If the device does not receive ACK packet from network server, it will resend data once.
Rejoin Mode	Reporting interval $\leq$ 30 mins: the device will send a specific number of LinkCheckReq M AC packets to the network server every 30 mins to validate connectivity; If there is no response, the device will re-join the network.  Reporting interval $>$ 30 mins: the device will send a specific number of LinkCheckReq M AC packets to the network server every reporting interval to validate connectivity; If there is no response, the device will re-join the network.
Set the number of packets sent	When rejoin mode is enabled, set the number of LinkCheckReq packets sent.
ADR Mode	Allow network server to adjust data rate of the device.
Tx Power	Transmit power of the device.

**Note:**

1. Please contact sales for device EUI list if there are many units.
2. Please contact sales if you need random App keys before purchase.
3. Select OTAA mode if you use Milesight IoT cloud to manage devices.
4. Only OTAA mode supports rejoin mode.

### LoRaWAN Frequency Settings:

Go to Settings > LoRaWAN Settings to select supported frequency and select channels to send uplinks. Make sure the channels match the LoRaWAN® gateway.

\* Support Frequency

EU868

<input checked="" type="checkbox"/>	-	868.1	+
<input checked="" type="checkbox"/>	-	868.3	+
<input checked="" type="checkbox"/>	-	868.5	+
<input type="checkbox"/>	-	863	+

If frequency is one of CN470/AU915/US915, you can enter the index of the channel that you want to enable in the input box, making them separated by commas.

### Examples:

- 1, 40: Enabling Channel 1 and Channel 40
- 1-40: Enabling Channel 1 to Channel 40
- 1-40, 60: Enabling Channel 1 to Channel 40 and Channel 60

**All:** Enabling all channels

**Null:** Indicates that all channels are disabled

### \* Support Frequency

AU915

### Enable Channel Index <sup>①</sup>

8-15

Index

Frequency/MHz



0 - 15

915.2 - 918.2

16 - 31

918.4 - 921.4

32 - 47

921.6 - 924.6

48 - 63

924.8 - 927.8

64 - 71

915.9 - 927.1

## Basic Settings

Go to Device > Settings > General Settings to change the reporting interval, etc.

Reporting Interval



1080



min

Change Password



Parameters	Description
Reporting Interval	Reporting interval of transmitting current sensor values to network server. Default: 1080 mins, Range: 1-1080 mins
Change Password	Change the password for ToolBox App or software to read/write this device.

## Threshold Settings

Go to Device > Settings > Threshold Settings to enable the threshold settings and input the angle threshold. You can set a relative initial surface to measure the deviance from an initial one and if the device detects the angle of a certain axis reaches the threshold based on the initial position, it will upload the current data instantly.

## Deflection Angle



Relative Initial Surface ⓘ

Setting

Clear

The triaxial angle relative to the initial face is  
(0.00°, 0.00°, -90.00°)

X-axis



Over / °

Below / °

Y-axis



Z-axis



Alarm Condition ⓘ

Alarm Reporting Interval  1  min

Alarm Reporting Times  2

Parameters	Description
Initial Position	<p>Click Setting to set current position of device as initial position to measure the deflection angle.</p> <p>Click Clear to change the initial position back to (0.00°, 0.00°, -90.00°).</p> <p>Note: after writing Setting or Clear configuration, click Read to read the device to check if the initial position changes successfully.</p>
Over / °	The maximum/upper limit of angle threshold.
Below / °	The minimum/lower limit of angle threshold.
Alarm Condition	<p>Acceptable elements are “X”, “Y”, “Z”, “and”, “or” “only”, it takes 2 or 3 axes to complete an expression and the device will only read from left to right. If left blank, it will consider the condition as “or”.</p> <p>Example:</p> <p>1) XandYorZ means (X and Y) or Z, that is XandY meets the threshold or Z meets the threshold.</p> <p>2) XorYandZ means (X or Y) and Z, that is XandZ meets the threshold or YorZ meets the threshold.</p>
Alarm Reporting Interval	After the threshold is triggered, the device will detect if the threshold is triggered again according to this reporting interval.
Alarm Reporting Times	After the threshold is triggered, the device will detect according to Alarm Reporting Interval and if still triggered, the device will send the certain number of alarms to NS.

#### Example:

When X axis is detected to 0° ( $0^\circ - 1.91^\circ = -1.91^\circ < -1^\circ$ ), it will trigger the threshold and upload an alarm package right away. If it changes back to normal, the device will also upload a data package immediately; if not, it will send alarm package after 1 minute. This process will repeat 2 times.

**Deflection Angle**
☒

Relative Initial Surface ⓘ

Settin  
g
Clear

The triaxial angle relative to the initial face is  
(1.91°, -2.03°, -87.21°)

**X-axis**
☒

Over / °

60.00

Below / °

-1.00

**Y-axis**
☐

**Z-axis**
☐

Alarm Condition ⓘ

Alarm Reporting Interval

-

1

+

min

Alarm Reporting Times

-

2

+

## Maintenance

### Upgrade

1. Download firmware from [www.milesight-iot.com](http://www.milesight-iot.com) to your smartphone.
2. Open ToolBox App and click Browse to import firmware and upgrade the device.

### Note:

1. Operation on ToolBox is not supported during the upgrade.
2. Only Android version ToolBox supports the upgrade feature.

SN	6785C38144050018
Model	EM320-TILT-868M
Firmware Version	V1.1-a2
Hardware Version	V1.1
Manual Upgrade	

Browse

### Backup

EM320-TILT sensor supports configuration backup for easy and quick device configuration in bulk. Backup is allowed only for devices with the same model and LoRaWAN® frequency band.

1. Go to Template page on the App and save current settings as a template. You can also edit the template file.
2. Select one template file that saved in the smartphone and click Write, then attach it to another device to write the configuration.

**Note:** Slide the template item to the left to edit or delete it. Click the template to edit the configurations.

Template

empty template

New Template






Please enter template name

EM320-TILT-868M

CancelOK

### Reset to Factory Default

Please select one of following methods to reset device:

Template		
<input type="text"/>		
	EM500-UDL-868M_20201124	
	Last Modified Time: 2020-11-24 17:06:26	
	EM300-TH-915M_20210112	
	Last Modified Time: 2021-01-12 14:35:12	
	UC512-DI-868M_20210128	
	Last Modified Time: 2021-01-28 16:57:20	
	UC501-470M_20210201	
	Last Modified Time: 2021-02-01 11:29:43	
	UC501-470M_20210208	
	Last Modified Time: 2021-02-08 16:44:37	
	<a href="#">Edit</a>	<a href="#">Delete</a>

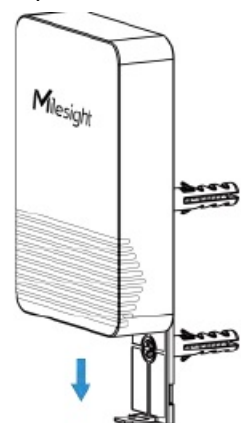
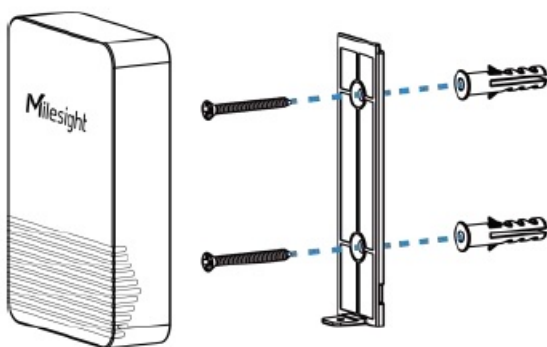
- **Via Hardware:** Hold on reset button inside the device more than 10s.
- **Via ToolBox App:** Go to Device > Maintenance > Reset to click Reset, then attach the smartphone with NFC area to the device to complete reset.



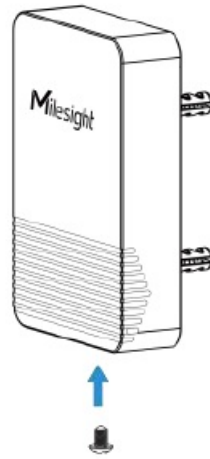
Status	Setting	Maintenance
SN	6785C38144050018	
Model	EM320-TILT-868M	
Firmware Version	V1.1-a2	
Hardware Version	V1.1	
Manual Upgrade		
<button>Browse</button>		
Restore Factory Default		
<button>Reset</button>		

## Installation

- Remove the backplate on the back of the device, screw the wall plugs into the wall and fix the backplate with screws on it, then install back the device. Note that the vent of device should not face upwards when installing.

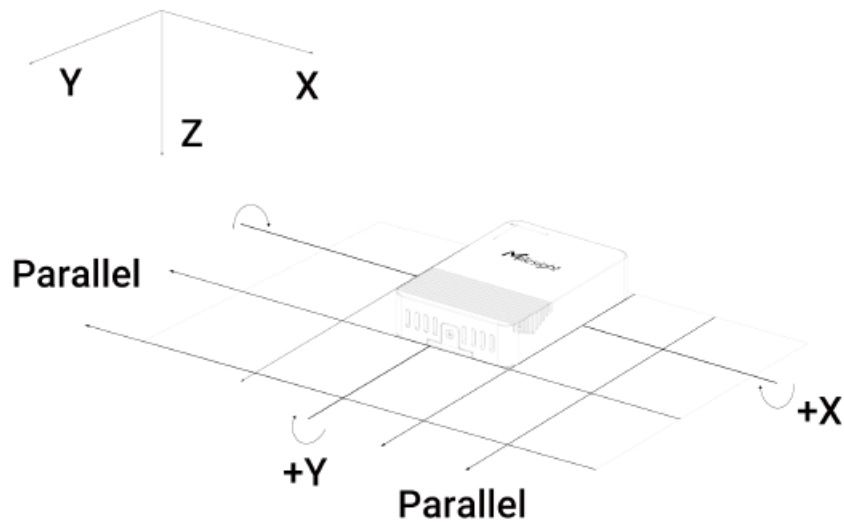


- Fix the bottom of the device to the cover with a fixing screw.



### Installation Location:

- Ensure the location of device is within the communication range of LoRaWAN® gateway and keep it away from metal objects.
- Ensure that the device is tightly attached without any gap to the surface to be measured of a certain object, and one of the 3 axes should be paralleled with the measuring axis of the object, otherwise, the result may not be correct.



### Device Payload

All data are based on following format (HEX), the Data field should follow little-endian:

Channel1	Type1	Data1	Channel2	Type2	Data2	Channel 3	...
1 Byte	1 Byte	N Bytes	1 Byte	1 Byte	M Bytes	1 Byte	...

For decoder examples please find files on <https://github.com/Milesight-IoT/SensorDecoders>.

### Basic Information

EM320-TILT sensors report basic information of sensor whenever joining the network.

Channel	Type	Description
ff	01(Protocol Version)	01=>V1
	09 (Hardware Version)	01 40 => V1.4
	0a (Software Version)	01 14 => V1.14

	0b (Power On)	Device is on
	0f (Device Type)	00: Class A, 01: Class B, 02: Class C
	16 (Device SN)	16 digits

### Example:

ff0bff ff0101 ff166785c38144050018 ff090110 ff0a0101 ff0f00					
Channel	Type	Value	Channel	Type	Value
ff	0b (Power On)	ff (Reserved)	ff	01 (Protocol Version)	01 (V1.0)
Channel	Type	Value	Channel	Type	Value
ff	16 (Device SN)	6785c381440 50018	ff	09 (Hardware version)	0110 (V1.1)
Channel	Type	Value	Channel	Type	Value
ff	0a (Software version)	0101 (V1.1)	ff	0f (Device Type)	00 (Class A)

### Sensor Data

EM320-TILT sensors report sensor data according to reporting interval (1080mins by default).

Item	Channel	Type	Description
Battery Level	01	75	UINT8, Unit: %
Angle	03	d4	6 Bytes, INT16 angle_x (2B) + angle_y(2B) + angle_z(2B), Unit:°, Resolution: 0.01° angle_x bit0: 0-normal; 1-trigger angle_y bit0: 0-normal; 1-trigger angle-z bit0: 0-normal; 1-trigger

**Example:**

017564 03d498fd 44ff 6b22					
Channel	Type	Value	Channel	Type	Value
					X: 98 fd => fd 98
					= (-616-0)/2 * 0.01
01	75 (Battery Level)	64=>100%	03	d4 (Angle)	= -3.08° Y: 44 ff => ff 44
					= (-188-0)/2 * 0.01
					= -0.94°
					Z: 6b 22 => 22 6b = (8811-1)/2 * 0.01 = 44.05° X=fd 98 => 1111 1101 1001 1000 X_bit0: 0 => normal Y_bit0: 0 => normal Z_bit0: 1 => trigger

**Downlink Commands**

EM320-TILT sensors support downlink commands to configure the device. The application port is 85 by default.

Channel	Type	Description
ff	03 (Set Reporting Interval)	2 Bytes, unit: s
	06 (Set Threshold)	9 Bytes: Threshold Type(1B) + Min Threshold (2B) + Max Threshold (2B) + Alarm Reporting Interval (2B) + Alarm Reporting Time (2B)  Threshold Type: Bit0~Bit2: 00-     disable 01-     below (minimum threshold) 010-over (maximum threshold) 011-within 100-below or above Bit3: X-axis angle Bit4: Y-axis angle Bit5: Z-axis angle Bit6~Bit7: Reserved
	10 (Reboot)	ff (Reserved)
	62 (Set Initial Position)	ff: set current position as initial position fe: set the initial position to (0.00°, 0.00°, -90.00°)
	63 (Set Alarm Condition)	8 Bytes, hex string of ASCII expression; if ASCII expression takes less than 8 bytes, add 0 in the

		end to meet the size.  Note: before setting the condition, ensure the corresponding axis threshold is enabled, or this condition will not work
--	--	--

### Example:

1. Set reporting interval as 20 minutes.

ff03b004		
Channel	Type	Value
ff	03 (Set Reporting Interval)	b0 04=>04 b0=1200s =20 minutes

2. Set X-axis threshold between 10° and 20°, it will detect the threshold every 1 minute, send alarm 3 times at

most.

ff060ce803d0073c000300		
Channel	Type	Value
ff	06 (Set Threshold)	0c => 00 001 100 = when X axis angle is below or above,  e803 => 1000 = 10.00°  d007 => 2000 = 20.00°  3c00 => 60 s = 1 min 0300 => 00 03 = 3 times

3. Reboot the device.

ff10ff		
Channel	Type	Value
ff	10 (Reboot)	ff (Reserved)

4. Set the alarm condition to be X and Y or Z, before setting ensure X, Y and Z thresholds are enabled.


ff635826597c5a0000		
Channel	Type	Value
ff	63 (Set Alarm Condition)	5826597c5a0000 = X&Y Z

5. Set current position as initial position.





ff62ff		
Channel	Type	Value
ff	62 (Set Initial Position)	ff = set current position as initial position

[www.milesight-iot.com](http://www.milesight-iot.com)

## Documents / Resources

	<p><b>Milesight EM320-TILT LoRaWAN Tilt Sensor</b> [pdf] User Guide EM320-TILT LoRaWAN Tilt Sensor, EM320-TILT, LoRaWAN Tilt Sensor, Tilt Sensor, Sensor</p>
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## References

-  [Support : IoT Support](#)
-  [Milesight IoT - LoRaWAN, 5G & AIoT](#)
-  [GitHub - Milesight-IoT/SensorDecoders](#)
-  [Milesight IoT - LoRaWAN, 5G & AIoT](#)

Manuals+.