



# MICROCHIP MIC2776 Micropower Low Voltage Supervisor Owner's Manual

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## MICROCHIP MIC2776 Micropower Low Voltage Supervisor



### Product Information

The MIC2776 is a micropower low voltage supervisor. It is available in different package types, including the 5-Lead SOT-23 (M5) package. The product features include undervoltage detection, input current monitoring, reset outputs, manual reset inputs, and internal pull-up current.

### Features

- User-Adjustable Input Can Monitor Supplies as Low as 0.3V
- $\pm 1.5\%$  Threshold Accuracy
- Separate VDD Input
- Generates Power-On Reset Pulse (140 ms min.)
- Manual Reset Input
- Choice of Active-High, Active-Low or Open-Drain Active-Low Reset Output
- Inputs Can be Pulled Above VDD (7V abs. max.)
- Open-Drain Output Can be Pulled Above VDD (7V abs.max.)
- Ultra-Low Supply Current, 3.0  $\mu$ A Typical
- Rejects Brief Input Transients
- Available in 5-Lead SOT-23 Package

### Applications

The MIC2776 can be used in various applications that require low voltage supervision and monitoring, such as microprocessors and other electronic devices.

- Monitoring Processor, ASIC, or FPGA Core Voltage
- Computer Systems
- PDAs/Handheld PCs

- Embedded Controllers
- Telecommunications Systems
- Power Supplies
- Wireless/Cellular Systems
- Networking Hardware

## Package Types

- MIC2776 5-Lead SOT-23 (M5) (Top View, H Version)
- MIC2776 5-Lead SOT-23 (M5) (Top View, L and N Versions)



## Product Usage Instructions

**Before using the MIC2776, please ensure that you follow these instructions:**

1. Handle the device with care as it is ESD sensitive. Use recommended handling precautions to prevent damage.
2. The operating voltage range for VDD is 1.5V to 5.5V. Ensure that the voltage supplied is within this range for proper functioning.
3. Connect the appropriate inputs and outputs according to your application requirements.
4. If using the manual reset feature, ensure that the input voltage (V/MR) is below the specified input low voltage (VIL) to trigger a reset.
5. Refer to the timing diagram in Figure 1-1 for understanding the propagation delays and voltage levels.

For detailed electrical characteristics and temperature specifications, please refer to the product manual provided by Microchip Technology Inc. and its subsidiaries.

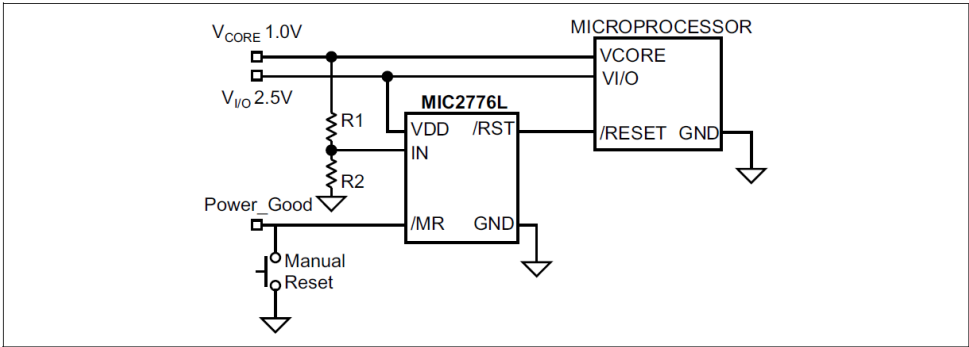
## General Description

The MIC2776 is a power supply supervisor that provides undervoltage monitoring and power-on reset generation in a compact 5-lead SOT-23 package. Features include an adjustable undervoltage detector, a delay generator, a manual reset input, and a choice of active-high, active-low, or open-drain active-low reset output. The user-adjustable monitoring input is compared against a 300 mV reference. This low reference voltage allows monitoring voltages lower than those supported by previous supervisor ICs.

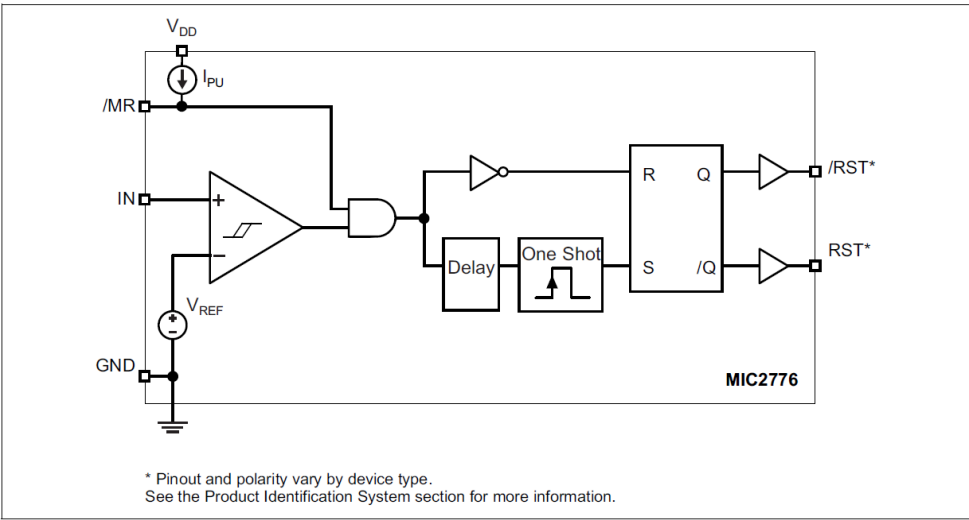
The reset output is asserted for no less than 140 ms at power-on and any time the input voltage drops below the reference voltage. It remains asserted for the timeout period after the input voltage subsequently rises back above the threshold boundary. A reset can be generated at any time by asserting the manual reset input, /MR. The reset output will remain active at least 140 ms after the release of /MR. The /MR input can also be used to daisy-chain

the MIC2776 onto existing power monitoring circuitry or other supervisors. Hysteresis is included to prevent chattering due to noise. Typical supply current is a low 3.0  $\mu$ A.

Typical Application Circuit



Functional Block Diagram



ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings †

- Supply Voltage (VDD)  
..... -0.3V to +7V
- Input Voltages (VIN, V/MR)  
..... -0.3V to +7V
- RST, /RST Current  
.....20 mA
- ESD Rating (Note 1)  
..... 1.5 kV

Operating Ratings ‡

- Supply Voltage (VDD)

..... +1.5V to  
+5.5V

- Input Voltages (VIN, V/MR)

..... –0.3V to +6.0V

## Output Voltages

- V/RST (N Version)

..... –0.3V to  
+6.0V

- V/RST, VRST (H and L Versions)

.....–0.3V to VDD + 0.3V

† **Notice:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational sections of this specification is not intended. Exposure to maximum rating conditions for extended periods may affect device reliability.

‡ **Notice:** The device is not guaranteed to function outside its operating ratings.

**Note 1:** Devices are ESD sensitive. Handling precautions recommended. Human body model, 1.5 kΩ in series with 100 pF.

## ELECTRICAL CHARACTERISTICS

**Electrical Characteristics:** VDD = 3.3V; TA = +25°C, bold values valid for –40°C ≤ TA ≤ +85°C, unless noted.

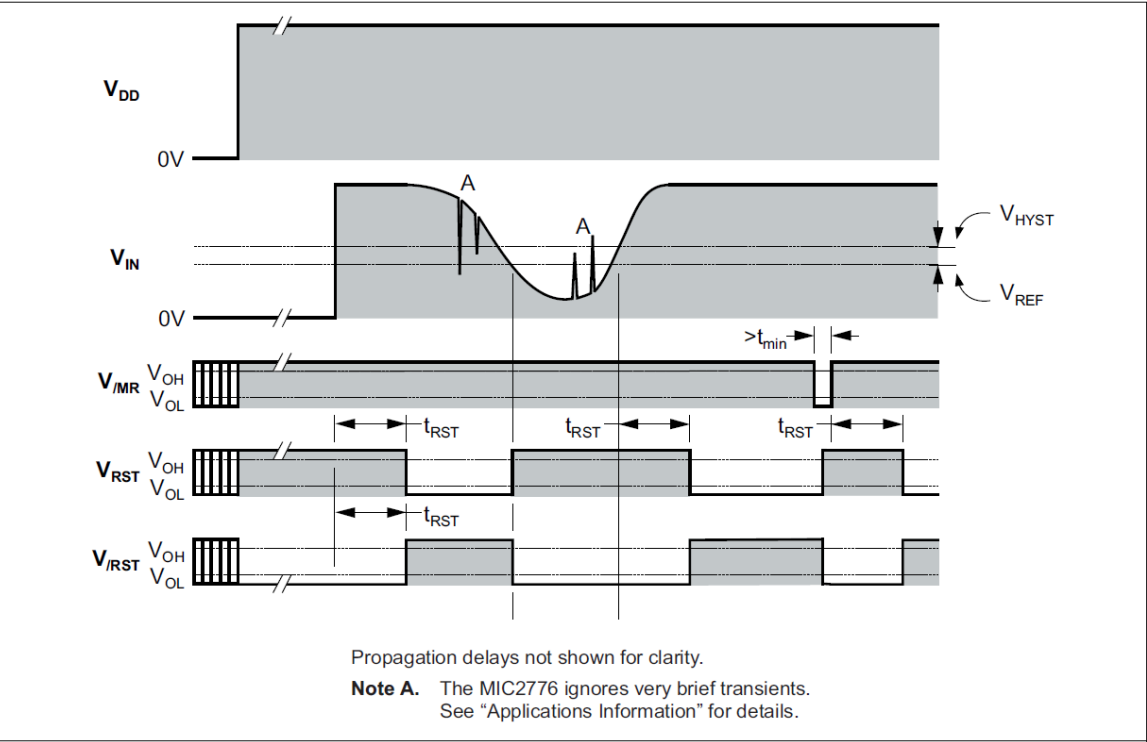
Note 1

Parameter	Symbol	Min.	Typ.	Max.	Units	Conditions
Supply Current	I <sub>DD</sub>	—	3.0	—	μA	V <sub>DD</sub> = V <sub>IN</sub> = 3.3V; /MR, RST, /RST open
IN, Undervoltage Detector Input						
Undervoltage Threshold	V <sub>REF</sub>	295	300	305	mV	T <sub>A</sub> = +25°C
Hysteresis Voltage	V <sub>HYST</sub>	—	3	—	mV	—
Input Current	I <sub>IN</sub>	—	5	—	pA	—
		—	—	10	nA	T <sub>MIN</sub> ≤ T <sub>A</sub> ≤ T <sub>MAX</sub>
Reset Outputs (/RST, RST)						
Propagation Delay	t <sub>PROP</sub>	—	20	—	μs	V <sub>IN</sub> = (V <sub>REF(MAX)</sub> + 100 mV) to V <sub>IN</sub> = (V <sub>REF(MIN)</sub> – 100 mV)
Reset Pulse Width	t <sub>RST</sub>	140	—	280	ms	—
RST or /RST Output Voltage Low	V <sub>OL</sub>	—	—	0.3	V	I <sub>SINK</sub> = 1.6 mA; V <sub>DD</sub> ≥ 1.6V
		—	—	0.3		I <sub>SINK</sub> = 100 μA; V <sub>DD</sub> ≥ 1.2V, <a href="#">Note 1</a>
RST or /RST Output Voltage High (H & L Versions Only)	V <sub>OH</sub>	0.8V <sub>DD</sub>	—	—	V	I <sub>SOURCE</sub> = 500 μA; V <sub>DD</sub> ≥ 1.5V
		0.8V <sub>DD</sub>	—	—		I <sub>SOURCE</sub> = 10 μA; V <sub>DD</sub> ≥ 1.2V, <a href="#">Note 1</a>
Manual Reset Inputs (/MR)						
Input High Voltage	V <sub>IH</sub>	0.7V <sub>DD</sub>	—	—	V	1.5V ≤ V <sub>DD</sub> ≤ 5.5V
Input Low Voltage	V <sub>IL</sub>	—	—	0.3V <sub>DD</sub>	V	1.5V ≤ V <sub>DD</sub> ≤ 5.5V
Propagation Delay	t <sub>PROP</sub>	—	5	—	μs	V <sub>/MR</sub> < V <sub>IL</sub>
Minimum Input Pulse Width	t <sub>MIN</sub>	—	33	—	ns	Reset occurs, V <sub>/MR</sub> < V <sub>IL</sub>
Internal Pull-Up Current	I <sub>PU</sub>	—	100	—	nA	—
Input Current, /MR	I <sub>IN</sub>	—	100	—	nA	V <sub>/MR</sub> < V <sub>IL</sub>

**Note 1:** VDD operating range is 1.5V to 5.5V. Output is ensured to be asserted down to VDD = 1.2V.

TEMPERATURE SPECIFICATIONS

Parameters	Sym.	Min.	Typ.	Max.	Units	Conditions
<b>Temperature Ranges</b>						
Storage Temperature Range	T <sub>S</sub>	−65	—	+150	°C	—
Ambient Temperature Range	T <sub>A</sub>	−40	—	+85	°C	—
<b>Package Thermal Resistances</b>						
Thermal Resistance, SOT-23 5-Ld	θ <sub>JA</sub>	—	256	—	°C/W	—



PIN DESCRIPTIONS

The descriptions of the pins are listed in Table 2-1.

TABLE 2-1: PIN FUNCTION TABLE

Pin Number MIC2776H	Pin Number MIC2776L MIC2776N	Pin Name	Description
1	—	RST	Digital (Output): Asserted high whenever $V_{IN}$ falls below the reference voltage. It will remain asserted for no less than 140 ms after $V_{IN}$ returns above the threshold limit.
—	1	/RST	Digital (Output): Asserted low whenever $V_{IN}$ falls below the reference voltage. It will remain asserted for no less than 140 ms after $V_{IN}$ returns above the threshold limit. (Open-drain for “N” version.)
2	2	GND	Ground.
3	3	/MR	Digital (Input): Driving this pin low initiates an immediate and unconditional reset. Assuming IN is above the threshold when /MR is released (returns high), the reset output will be de-asserted no less than 140 ms later. /MR may be driven by a logic signal or a mechanical switch. /MR has an internal pull-up to $V_{DD}$ and may be left open if unused.
4	4	IN	Analog (Input): The voltage on this pin is compared to the internal 300 mV reference. An undervoltage condition will trigger a reset sequence.
5	5	VDD	Analog (Input): Independent supply input for internal circuitry.

FUNCTIONAL DESCRIPTION

IN, Undervoltage Detector Input

The voltage present at the IN pin is compared to the internal 300 mV reference voltage. A reset is triggered if and when VIN falls below VREF. Typically, a resistor divider is used to scale the input voltage to be monitored such that VIN will fall below VREF as the voltage being monitored falls below the desired trip-point. Hysteresis is employed to prevent chattering due to noise.

### **RST, /RST Reset Output**

Typically, the MIC2776 is used to monitor the power supply of intelligent circuits such as microcontrollers and microprocessors. By connecting the reset output of a MIC2776 to the reset input of a microcontrollers or microprocessor, the processor will be properly reset at power-on and during power-down and during brown-out conditions. In addition, asserting /MR, the manual reset input, will activate the reset function. The reset outputs are asserted any time /MR is asserted or if VIN drops below the threshold voltage. The reset outputs remain asserted for tRST(MIN) after VIN subsequently returns above the threshold boundary and /MR is released. A reset pulse is also generated at power-on.

### **/MR, Manual Reset Input**

The ability to initiate a reset via external logic or a manual switch is provided in addition to the MIC2776's automatic supervisory functions. Driving the /MR input to a logic low causes an immediate and unconditional reset to occur. Assuming VIN is within tolerance when /MR is released (returns high), the reset output will be de-asserted no less than tRST later. /MR may be driven by a logic signal, or mechanical switch. Typically, a momentary push-button switch is connected such that /MR is shorted to ground when the switch contacts close. The switch may be connected directly between /MR and GND. /MR has an internal 100 nA pull-up current to VDD and may be left open if unused.

## **APPLICATION INFORMATION**

### **Programming the Threshold Voltage**

Referring to the Typical Application Circuit, the voltage threshold is calculated as follows:

#### **EQUATION 4-1:**

$$V_{TH} = V_{REF} \times \frac{R1 + R2}{R2}$$

Where:

$$V_{REF} = 0.300V$$

In order to provide the additional criteria needed to solve for the resistor values, the resistors can be selected such that the two resistors have a given total value, that is,  $R1 + R2 = R_{TOTAL}$ . Imposing this condition on the resistor values provides two equations that can be solved for the two unknown resistor values. A value such as 1 MΩ for RTOTAL is a reasonable choice because it keeps quiescent current to a generally acceptable level while not causing any measurable errors due to input bias currents. The larger the resistors, the larger the potential errors due to input bias current (IIN). The maximum recommended value of RTOTAL is 3 MΩ.

Applying this criteria and rearranging the VTH expression to solve for the resistor values gives:

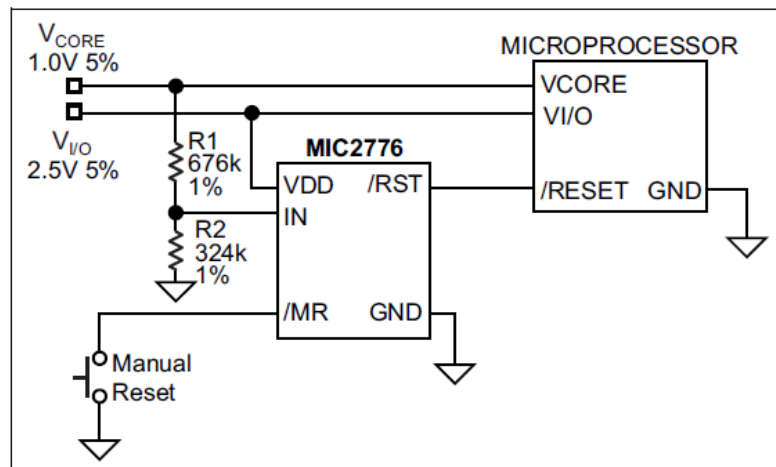
#### **EQUATION 4-2:**

$$R2 = \frac{R_{TOTAL} \times V_{REF}}{V_{TH}}$$

$$R1 = R_{TOTAL} - R2$$

## Application Example

Figure 4-1 illustrates a hypothetical MIC2776 application in which the MIC2776 is used to monitor the core supply of a high-performance CPU or DSP. The core supply, V<sub>CORE</sub>, in this example is 1.0V ±5%. The main power rail and I/O voltage, V<sub>I/O</sub>, is 2.5V ±5%. As shown in Figure 4-1, the MIC2776 is powered by V<sub>I/O</sub>. The minimum value of V<sub>I/O</sub> is 2.5V – 5% = 2.375V; the maximum is 2.5V + 5% = 2.625V. This is well within the MIC2776's power supply range of 1.5V to 5.5V.



**FIGURE 4-1:** Example Design.

Resistors R1 and R2 must be selected to correspond to the V<sub>CORE</sub> supply of 1.0V. The goal is to ensure that the core supply voltage is adequate to ensure proper operation, i.e., V<sub>CORE</sub> ≥ (1.0V – 5%) = 0.950V. Because there is always a small degree of uncertainty due to the accuracy of the resistors, variations in the devices' voltage reference, etc., the threshold will be set slightly below this value. The potential variation in the MIC2776's voltage reference is specified as ±1.5%. The resistors chosen will have their own tolerance specifications. This example will assume the use of 1% accurate resistors. The potential worst-case error contribution due to input bias current can be calculated once the resistor values are chosen. If the guidelines above regarding the maximum total value of R1 + R2 are followed, this error contribution will be very small thanks to the MIC2776's very low input bias current.

**To summarize, the various potential error sources are:**

- Variation in V<sub>REF</sub>: Specified at ±1.5%
- Resistor tolerance: Chosen by designer (typically ≤ ±1%)
- Input bias current, I<sub>IN</sub>: Calculated once resistor values are known, typically very small

Taking the various potential error sources into account, the threshold voltage will be set slightly below the minimum V<sub>CORE</sub> specification of 0.950V so that when the actual threshold voltage is at its maximum, it will not intrude into the normal operating range of V<sub>CORE</sub>. The target threshold voltage will be set as follows: Given that the total tolerance on V<sub>TH</sub> is

### EQUATION 4-3:

$$[\text{VREF tolerance}] + [\text{resistor tolerance}] = \\ \pm 1.5\% + \pm 1\% = \pm 2.5\%$$

$$\text{and} \quad V_{TH(MAX)} = V_{CORE(MIN)}$$

$$\text{then} \quad V_{CORE(MIN)} = V_{TH} + 2.5\% V_{TH} = 1.025 V_{TH}$$



Therefore, solving for  $V_{TH}$  results in:

$$V_{TH} = \frac{V_{CORE(MIN)}}{1.025} = \frac{0.950}{1.025} = 0.9268 V$$

**EQUATION 4-4:**

Solving for  $R_1$  and  $R_2$  using this value for  $V_{TH}$  and the equations above yields:

- $R_1 = 676.3 \text{ k}\Omega \approx 673 \text{ k}\Omega$
- $R_2 = 323.7 \text{ k}\Omega \approx 324 \text{ k}\Omega$
- The resulting circuit is shown in Figure 4-1.

#### Input Bias Current Effects

Now that the resistor values are known, it is possible to calculate the maximum potential error due to input bias current,  $I_{IN}$ . As shown in the Electrical Characteristics table, the maximum value of  $I_{IN}$  is 10 nA. Note that the typical value is a much smaller 5 pA. The magnitude of the offset caused by  $I_{IN}$  is given by:

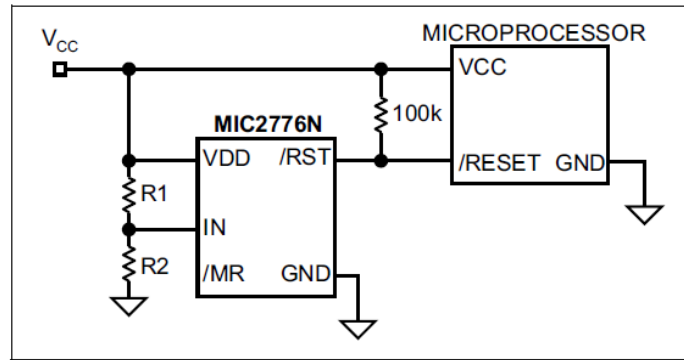
**EQUATION 4-5:**

$$\begin{aligned} V_{ERROR} &= I_{IN(MAX)} \times (R_1 \parallel R_2) \\ V_{ERROR} &= \pm 1 \times 10^{-8} \text{ A} \times 2.189 \times 10^5 \Omega \\ V_{ERROR} &= \pm 2.189 \times 10^{-3} \text{ V} \\ V_{ERROR} &= \pm 2.189 \text{ mV} \end{aligned}$$

The typical error is about three orders of magnitude lower than this—close to 1  $\mu\text{V}$ . Generally, the error due to input bias can be discounted. If it is to be taken into account, simply adjust the target threshold voltage downward by this amount and recalculate  $R_1$  and  $R_2$ . The resulting value will be very close to optimal. If accuracy is more important than the quiescent current in the resistors, simply reduce the value of  $R_{TOTAL}$  to minimize offset errors.

#### Interfacing to Processors with Bidirectional Reset Pins

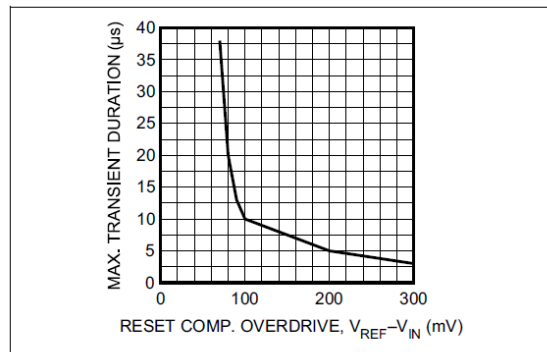
Some microprocessors have reset signal pins that are bidirectional, rather than input only. The Motorola 68HC11 family is one example. Because the MIC2776N's output is open-drain, it can be connected directly to the processor's reset pin using only the pull-up resistor normally required. See Figure 4-2.



**FIGURE 4-2:** *Interfacing to Bidirectional Reset Pin.*

### Transient Response

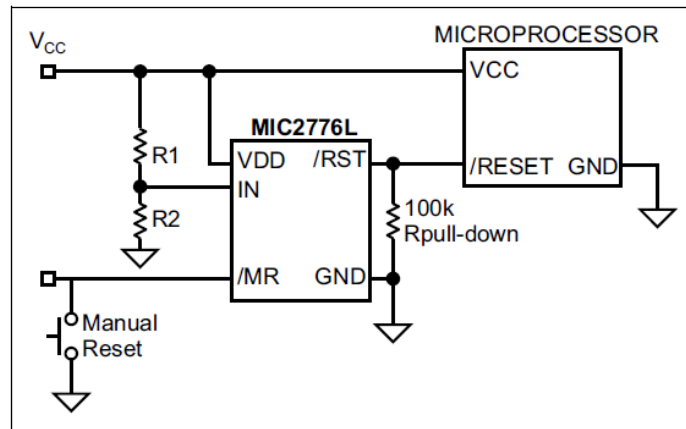
The MIC2776 is inherently immune to very short negative going glitches. Very brief transients may exceed the voltage threshold without tripping the output. As shown in Figure 4-3, the narrower the transient, the deeper the threshold overdrive that will be ignored by the MIC2776. The graph represents the typical allowable transient duration for a given amount of threshold overdrive that will not generate a reset.



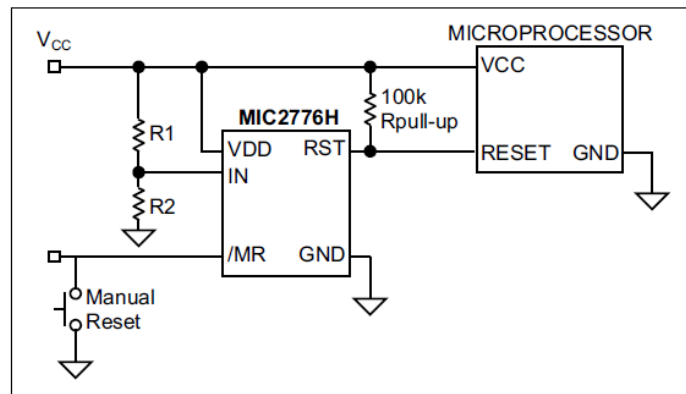
**FIGURE 4-3:** *Typical Input Transient Response.*

### Ensuring Proper Operation at Low Supply

At levels of VDD below 1.2V, the MIC2776L's /RST output driver cannot turn on sufficiently to produce a valid logic low on the /RST output. In this situation, other circuits driven by /RST could be allowed to float, causing undesired operation. In most cases, however, it is expected that the circuits driven by the MIC2776L will be similarly inoperative at  $VDD \leq 1.2V$ . If a given application requires that /RST be valid below  $VDD = 1.2V$ , this can be accomplished by adding a pull-down resistor to the /RST output. A value of 100 kΩ is recommended as this is usually an acceptable compromise of leakage current and pull-down current. The resistor's value is not critical, however. See Figure 4-4. The statements above also apply to the MIC2776H's RST output. That is, to ensure valid RST signal levels at  $VDD < 1.2V$ , a pull-up resistor (as opposed to a pull-down) should be added to the RST output. A value of 100 kΩ is typical for this application as well. See Figure 4-5.



**FIGURE 4-4:** MIC2776L Valid /RST Below 1.2V.



**FIGURE 4-5:** MIC2776H Valid RST Below 1.2V.

## PACKAGING INFORMATION

### Package Marking Information

5-Lead SOT-23\*  
(Front)

XXXX

Example

ULAA

5-Lead SOT-23\*  
(Back)

NNN

Example

DW4

**Note:** The Marking Code for the H version is ULAA; the marking code for the L version is UMAA; the marking code for the N version is UKAA.

Legend: XX...X: Product code or customer-specific information

Y: Year code (last digit of calendar year)

YY: Year code (last 2 digits of calendar year)

WW: Week code (week of January 1 is week '01')

NNN: Alphanumeric traceability code

( e 3 ): Pb-free JEDEC® designator for Matte Tin (Sn) \* This package is Pb-free. The Pb-free JEDEC designator ( e 3 ) can be found on the outer packaging for this package.

, ▲, ▼ Pin one index is identified by a dot, delta up, or delta down (triangle mark).

**Note:** In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information. Package may or may not include the corporate logo.

Underbar ( ) symbol may not be to scale.

**Note:** If the full seven-character YYWWNNN code cannot fit on the package, the following truncated codes are

used based on the available marking space:

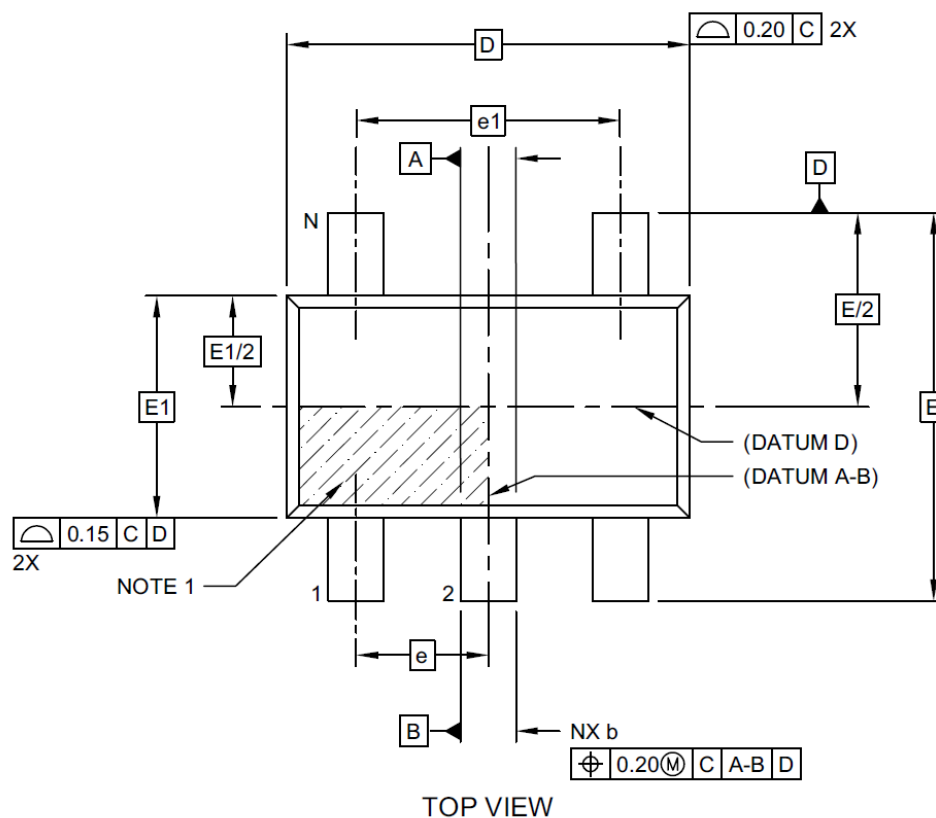
- 6 Characters = YWWNNN;
- 5 Characters = WWNNN;
- 4 Characters = WNNN;
- 3 Characters = NNN;
- 2 Characters = NN;
- 1 Character = N

## 5-Lead SOT-23 Package Outline and Recommended Land Pattern

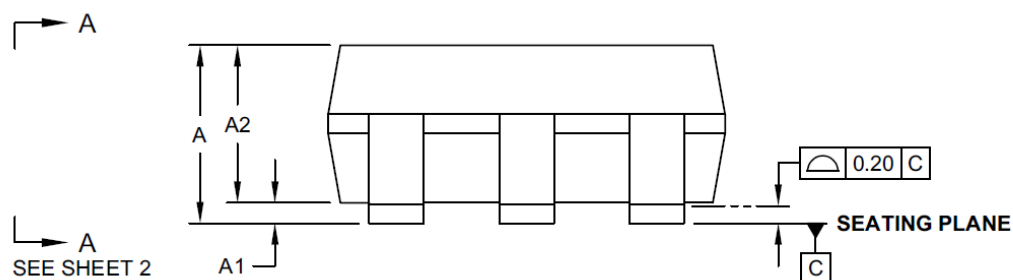
### Note:

For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>

### TOP VIEW

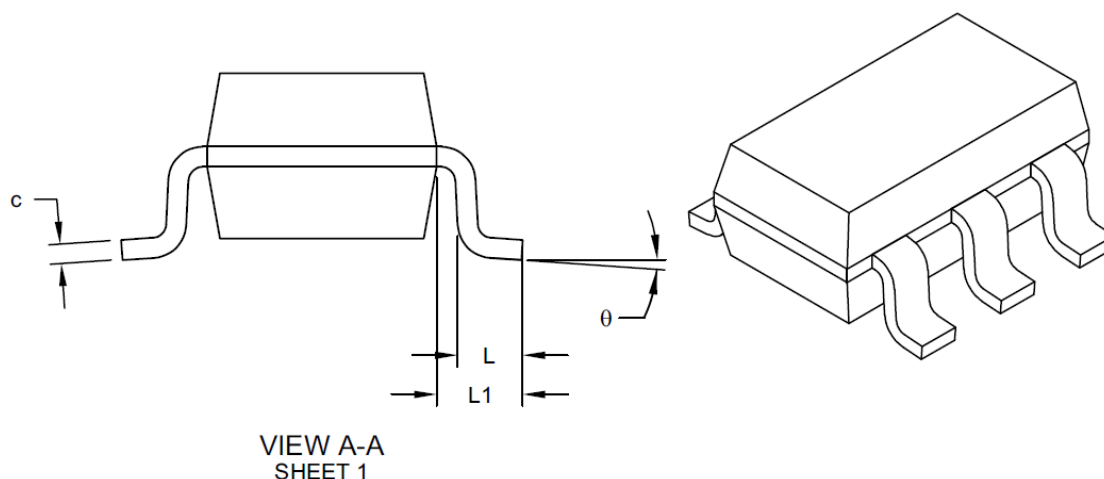


### SIDE VIEW



## 5-Lead Plastic Small Outline Transistor (6BX) [SOT231

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packageing>

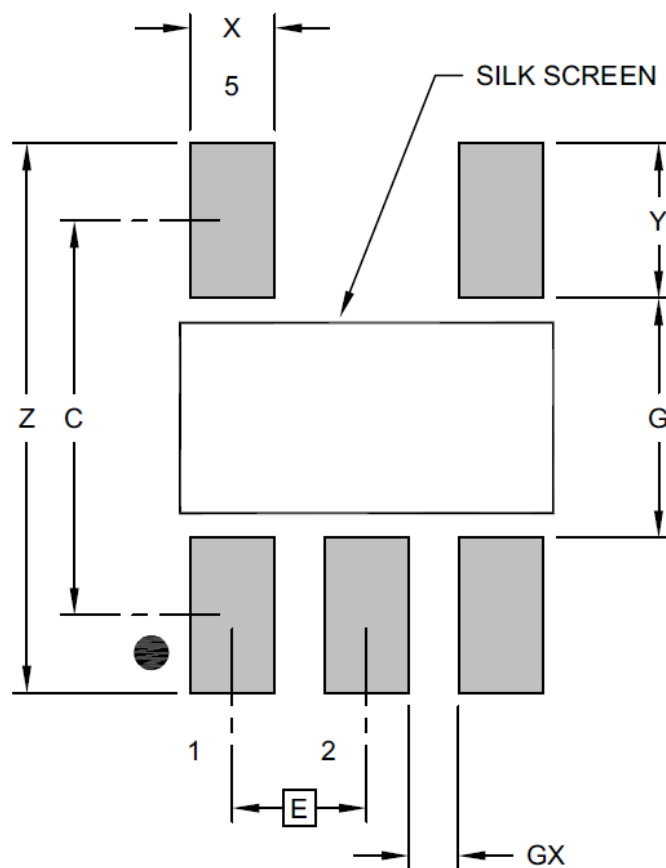


Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Pins	N	5		
Pitch	e	0.95 BSC		
Outside lead pitch	e1	1.90 BSC		
Overall Height	A	0.90	-	1.45
Molded Package Thickness	A2	0.89	-	1.30
Standoff	A1	-	-	0.15
Overall Width	E	2.80 BSC		
Molded Package Width	E1	1.60 BSC		
Overall Length	D	2.90 BSC		
Foot Length	L	0.30	-	0.60
Footprint	L1	0.60 REF		
Foot Angle	φ	0°	-	10°
Lead Thickness	c	0.08	-	0.26
Lead Width	b	0.20	-	0.51

**Notes:**

- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25mm per side.
- Dimensioning and tolerancing per ASME Y14.5M
  - BSC:** Basic Dimension. Theoretically exact value shown without tolerances.
  - REF:** Reference Dimension, usually without tolerance, for information purposes only.

**5-Lead Plastic Small Outline Transistor (6BX) [SOT23]**



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	0.95 BSC		
Contact Pad Spacing	C		2.80	
Contact Pad Width (X5)	X			0.60
Contact Pad Length (X5)	Y			1.10
Distance Between Pads	G	1.70		
Distance Between Pads	GX	0.35		
Overall Width	Z			3.90

#### Notes:

1. Dimensioning and tolerancing per ASME Y14.5M
  - **BSC:** Basic Dimension. Theoretically, the exact value is shown without tolerances.

## APPENDIX A: REVISION HISTORY

### Revision A (August 2022)

- Converted Micrel document MIC2776 to Micro-chip data sheet DS20006705A.
- Minor text changes throughout.

## PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, contact your local Microchip representative or sales office.

Part Number	X	-X	XX	-XX	Examples:
Device	Reset Output	Temp. Range	Package	Media Type	
<b>Device:</b> MIC2776: Micropower Low Voltage Supervisor  <b>Reset Output:</b> N = Open-Drain, Active-Low /RST H = Active-High, Complementary RST L = Active-Low, Complementary /RST  <b>Temperature Range:</b> Y = -40°C to +85°C  <b>Package:</b> M5 = 5-Lead SOT-23  <b>Media Type:</b> TR = 3,000/Reel TX = 3,000/Reel Reversed					a) MIC2776N-YM5-TR: MIC2776, Open-Drain, Active-Low /RST, -40°C to +85°C Temp. Range, 5-Lead SOT-23, 3,000/Reel  b) MIC2776H-YM5-TR: MIC2776, Active-High, Complementary RST, -40°C to +85°C Temp. Range, 5-Lead SOT-23, 3,000/Reel  c) MIC2776L-YM5-TR: MIC2776, Active-Low, Complementary /RST, -40°C to +85°C Temp. Range, 5-Lead SOT-23, 3,000/Reel  d) MIC2776N-YM5-TX: MIC2776, Open-Drain, Active-Low /RST, -40°C to +85°C Temp. Range, 5-Lead SOT-23, 3,000/Reel Reversed  e) MIC2776L-YM5-TX: MIC2776, Active-Low, Complementary /RST, -40°C to +85°C Temp. Range, 5-Lead SOT-23, 3,000/Reel Reversed  <b>Note 1:</b> Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.

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- Microchip products meet the specifications contained in their particular Microchip Data Sheet.
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## Documents / Resources



	<p><b><a href="#">MICROCHIP MIC2776 Micropower Low Voltage Supervisor</a></b> [pdf] Owner's Manual  MIC2776L-YM5-TR, MIC2776, MIC2776 Micropower Low Voltage Supervisor, Micropower Low Voltage Supervisor, Low Voltage Supervisor, Voltage Supervisor, Supervisor</p>
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