





# Agenda

# Overview

Application Model (CAPL)

Technical References



### This document is for ...

- ► Help you Implement logic of SOME/IP application via CAPL Programming
- ► Help to understand for the Initial Setup
  - ► SOME/IP concept in CANoe
  - ► Import Data Sources
  - ► Import Application Models
  - Write Data Source as a vCDL
  - ► Simulation with CANoe GUI features
  - ► Analysis of SOME/IP data
  - Simulation with CAPL programming

covered in Part1, Part2, Part3

- ► CANoe sample configuration is prepared for your understanding
  - ▶ https://portal.vector.com/shared/068f1303-77de-4eab-8bd0-ca37938c6885
- Quick start guide for work of basic SOME/IP simulation, analysis
  - ➤ You can extend your knowledge and know-how through CANoe Help Manual!
  - ▶ It covers More detailed technical information.



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## Basic CAPL Applications

- Value Access
  - Use \$ sign for accessing communication values
    - > 'Write Value' can trigger Event and Field Notification

```
$CommunicationObjects::Calculator.providerSide[Provider].State.AddCount = gAddCount;
$CommunicationObjects::Calculator.providerSide[Provider].State.SubtractCount = gMultiplyCount;
$CommunicationObjects::Calculator.providerSide[Provider].State.MultiplyCount = gMultiplyCount;
$CommunicationObjects::Calculator.providerSide[Provider].State.DivideCount = gDivideCount;
```

'Read Value'

- Request Call
  - ▶ Use CallAsync(params...) function for calling Method and Field Getter/Setter
    - 'Method Call'

```
// Call method 'Add' of service 'Calculator' when key 'c' is pressed
CommunicationObjects::Calculator.Add.CallAsync(3,6);
```

> 'Field Getter/Setter'

```
// Call Field Getter 'CalcResult' of service 'Calculator' when key 'g' is pressed
CommunicationObjects::Calculator.CalcResult.Get.CallAsync();

//Set CalcResult to '0'
CommunicationObjects::Calculator.CalcResult.Set.CallAsync(0);
```

 The number and data type of input parameters follow the prototype defined by the Data Source(vCDL)



## Basic CAPL Applications

- Event Handler
  - on fct\_called / on fct\_returned is called when Method and Field Getter/Setter are processed
    - > Provider side on fct\_called is called when receive the request from consumer

```
// Implementation for method 'Add'

on fct_called CommunicationObjects::Calculator.Add
{
   this.result = this.operand1 + this.operand2; // Calculate result
   gAddCount++; // Update counter
   this.ReturnCall(); // Return result
}
```

> Consumer side – on fct\_returned is called when receive the response from provider

```
// This handler is called when the return value of method 'Add' of service 'Calculator' is received

on fct_returned CommunicationObjects::Calculator.Add

{
    // Print result in the Write Window of CANoe
    write("Result of Add method: %f", this.result);
}
```

on value\_change is called when value of Event / Field Notification changed

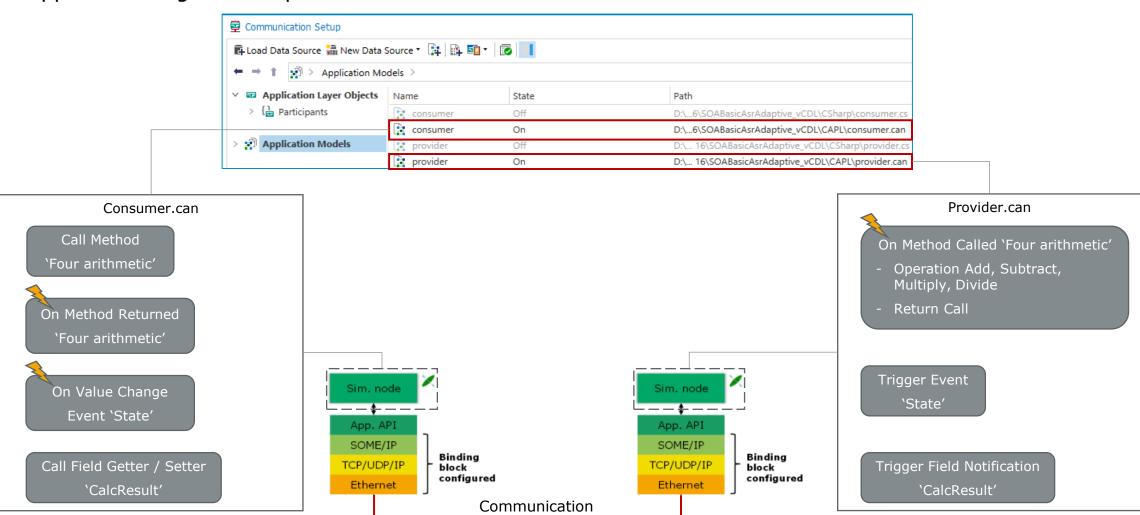
```
// This handler is called when the value of the event 'State' changed

Eon value_change CommunicationObjects::Calculator.consumerSide[Consumer,Provider].State
{
   write("State event received. AddCount: %d, SubtractCount: %d, MultiplyCount: %d, DivideCount: %d",
```

on value\_update is called when value of Event / Field Notification updated

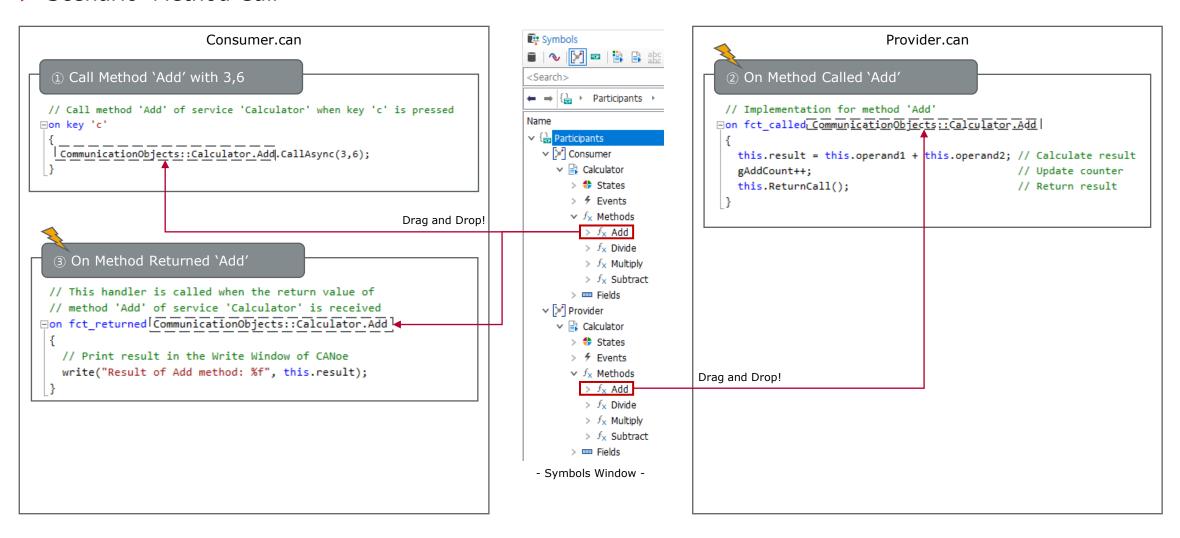


► Application Logics Example



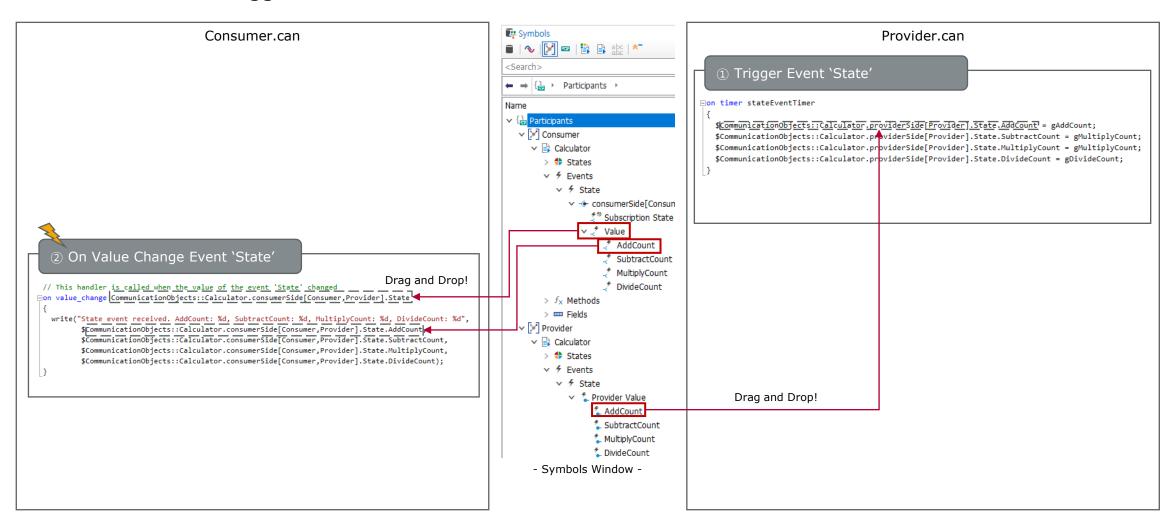


#### Scenario 'Method Call'



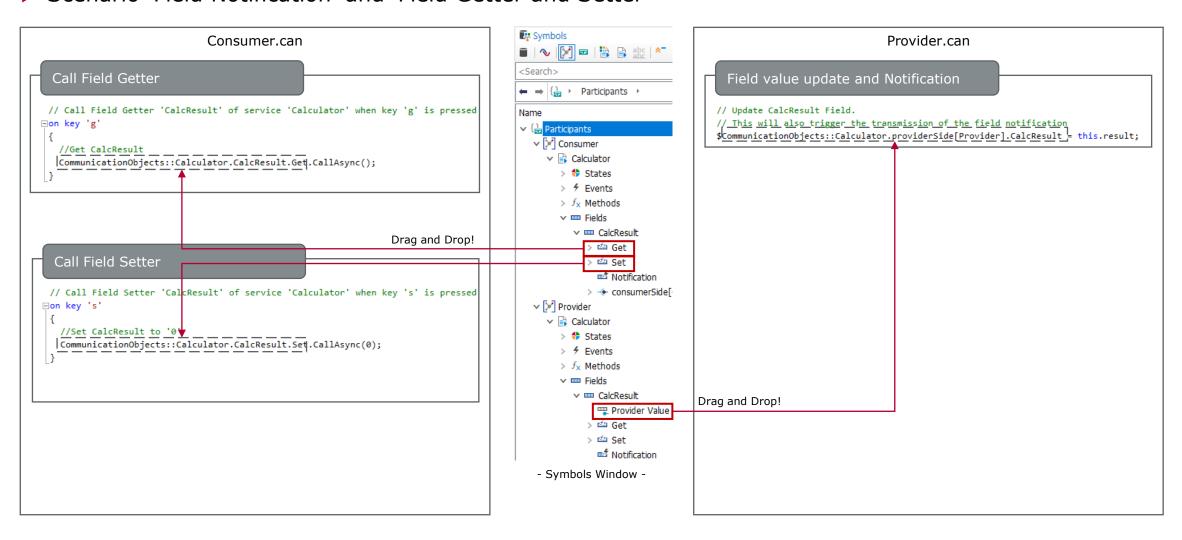


Scenario 'Event' Trigger





Scenario 'Field Notification' and 'Field Getter and Setter'





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**▶** Technical References



# Video Recording

- ▶ Introduction to Automotive Ethernet
  - ► <a href="https://www.vector.com/kr/ko/events/global-de-en/webinar-recordings/2023/introduction-to-automotive-ethernet/">https://www.vector.com/kr/ko/events/global-de-en/webinar-recordings/2023/introduction-to-automotive-ethernet/</a>
    - ▶ Introduction to Ethernet- and IP-based communication
    - ▶ Physical layers: IEEE 10BASE-T1S, 100BASE-T1, 1000BASE-T1, 100BASE-TX and Multi-Gig
    - ▶ Overview of used communication protocols: IP, TCP, and UDP
    - ▶ DoIP: Diagnostics over IP
    - ▶ SOME/IP: Scalable service-Oriented MiddlewarE over IP

Playback

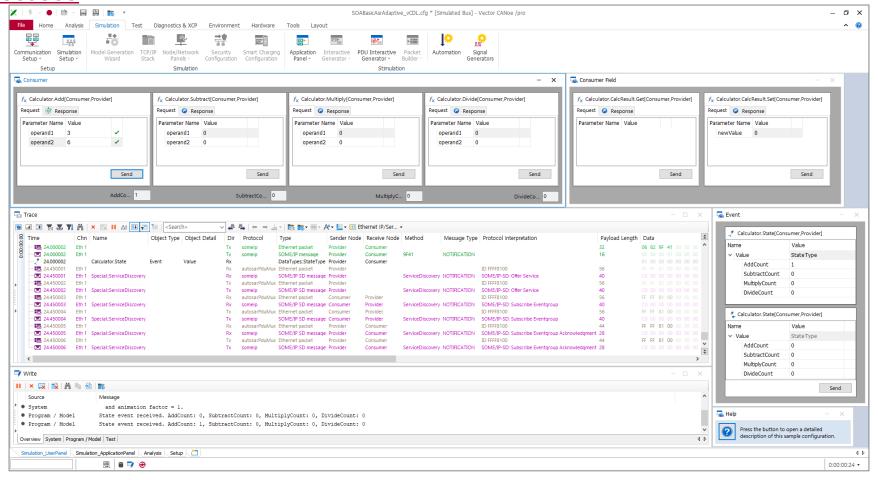
- ► CANoe for Service-Oriented Architectures(SOA) Part1. SOA Fundamental
  - ► <a href="https://youtu.be/M\_SXOgci1p4">https://youtu.be/M\_SXOgci1p4</a>





# Calculator Example

- ▶ CANoe configuration, vCDL, Analysis Features, Simulation Features, CAPL Codes
  - ► Download Sample Configuration: <a href="https://portal.vector.com/shared/068f1303-77de-4eab-8bd0-ca37938c6885">https://portal.vector.com/shared/068f1303-77de-4eab-8bd0-ca37938c6885</a>



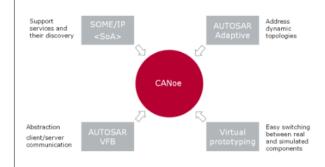


# **CANoe Help Manual**

### ► CANoe Communication Concept Overview

✓ CANoe » Communication Concept

#### Communication Concept



CANoe as simulation and test environment provides an uniform and cross-network communication concept. This communication concept enables application-related modeling of classic and new communication patterns. The communication concept provides consistent decoupling of logical communication on the application level from protocols of the network level.

This means that CANoe provides a network-independent interface for application models and test scripts. Separately from this, the actual access or transmission is configured via a specific network.

▶ Comparison: How was it before - how is it now?

#### Concept

- ▶ Basics of the Communication Concept
- ▶ Service-Oriented Communication
- Binding

#### **Application Layer Objects**

- ▶ Communication Objects
- Distributed Objects
- ▶ Display and Stimulate Application Layer Objects

#### Configuration

- Communication Setup
  - ▶ Load Data Source
  - ▶ AUTOSAR Preprocessor
  - ▶ CANoe AUTOSAR Converter

#### Binding

#### Communication Objects

- Abstract Binding
- ▶ SOME/IP Binding

#### Distributed Objects

- Abstract Binding
- ▶ MOTT Binding
- ▶ HTTP Binding
- ▶ DDS Binding
- ▶ IoT Enabler
- ▶ Mapping
- ► <u>CAPL</u>
- ▶ C#
- ▶ FDX

#### Serialization

- ▶ JSON
- ▶ Google Protocol Buffers

#### **Programming**

- ▶ Programming C#, Python and CAPL
- Description how you can use the objects and the APIs of the communication concept in C#, Python or in CAPL to create, for example application models or to test functionality.
- Vector Communication Description Language (vCDL)
- vCDL allows the CANoe communication concept to be extended by a tool for the simple and text-based configuration of communication objects.



# **CANoe Help Manual**

### ► CAPL Programming Overview

✓ CANoe » Communication Concept » Programming with the Communication Concept (C#, Python and CAPL)

### Programming with the Communication Concept (C#, Python and CAPL)

The following pages describe how you can use the objects and the APIs of the communication concept in C# or in CAPL to create, for example application models or to test functionality.

Chapter	Contents
Introductory Examples	Introductory examples in C# and CAPL
Access to Values	How can you access the values of <u>distributed objects</u> / <u>communication objects</u> ?
Function Calls	How can you call and implement functions?
Communication Objects (COs)	
CO Types	Description of the APIs for different types of <u>communication objects</u>
Endpoint Selection	What if the communication object has several endpoints?
CAPL/C# Data Types	Reuse of code by means of variables and parameters
Service Discovery	APIs and models for using Service Discovery
CAPL Functions for COs	Overview and description of available CAPL functions
Distributed Objects (DOs)	
DO Types	Data types for <u>distributed objects</u> (CAPL, Python and C#)
<u>Dynamic Objects and References</u>	Creating dynamic objects, using them with references and destroying them
Programming with DO Interfaces	Using interfaces of distributed objects for generic programming
Attributes	Tabular overview of the available attributes
Member and Methods	Members and method call for distributed objects
CAPL Functions for DOs	Overview and description of available CAPL functions



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