

# Vector Addition

## Equipment Needed

Super Pulley Force Table (ME-9447B)  
 Super Pulley Table Clamp (ME-9448B)  
 Mass and Hanger Set (ME-8979)  
 Mass Balance (SE-8723)

## Equipment Needed

String (spool of thread)  
 Protractor  
 Metric Ruler  
 Sheet of paper (2)

## Purpose

The purpose of this experiment is to use the force table to experimentally determine the force that balances two other forces. This result is checked by adding the two forces using their horizontal and vertical vector components, and by graphically adding the force vectors.

## Theory

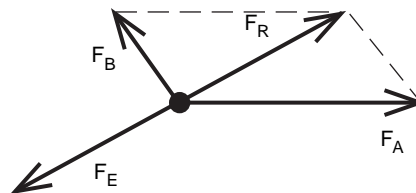
This experiment finds the resultant of adding two vectors by three methods: experimentally, by adding components, and graphically

NOTE: In all cases, the force caused by the mass hanging over the pulley is found by multiplying the mass by the acceleration due to gravity,  $9.8 \text{ m/s}^2$ .

## Experimental Method

Two forces are applied on the force table by hanging masses over pulleys position at certain angles. Next, the angle and amount of mass hanging over the third pulley are adjusted until the force from this pulley balances the forces from the other two pulleys. The third force is called the equilibrant ( $F_E$ ) because it is the force that establishes equilibrium. The equilibrant is not the same as the resultant ( $F_R$ ). The resultant is the addition of the two forces. The equilibrant has the same magnitude as the resultant, but it is in the opposite direction of the resultant because it must balance the resultant. The equilibrant is the 'negative' of the resultant.

$$-\vec{F}_E = \vec{F}_R = \vec{F}_A + \vec{F}_B$$



## Setup

1. Assemble the force table as shown in the Assembly section. Use three super pulley clamps (two for the forces that will be added and one for the force that balances the sum of the other two forces).
2. Arrange the strings from the String Tie over the pulleys.

3. Hang the following masses over two of the super pulleys and clamp the pulleys at the given angles.

Table 1.1:

Force	Mass	Angle
$F_A$	50 g (0.050 kg)	0°
$F_B$	100 g (0.100 kg)	120°
$F_E$		

## Procedure (Experimental Method)

By trial and error, find the angle for the third super pulley clamp and the mass that must be suspended over the pulley so that its weight will balance the forces exerted on the strings by the other two masses. This third force is called the equilibrant ( $F_E$ ) because it establishes equilibrium. The equilibrant is the negative of the resultant.

Record the mass and angle for the third pulley to put the system into equilibrium into Table 1.1.

To test whether the system is in equilibrium, use the following criteria.

### Method of Finding Equilibrium

The clear disk will be centered in the String Tie when the system is in equilibrium. Pull the clear disk slightly to one side and let it go. Check to see that the disk returns to the center. If not, adjust the mass and/or the angle of the super pulley clamp until the disk always returns to the center when pulled slightly to one side.

## Analysis

To theoretically determine what mass should be suspended over the third pulley, and at what angle, calculate the magnitude and direction of the resultant by the component method and the graphical method. The equilibrant ( $F_E$ ) will have the same magnitude, but it will be opposite in direction. In other words, the direction will be 180° from the direction of the resultant.

### Component Method

On a separate sheet of paper, add the vector components of Force A and Force B to determine the magnitude of the equilibrant. Record the components  $R_x$  and  $R_y$  in Table 1.2. Use trigonometry to find the direction of the equilibrant (remember, the equilibrant is exactly opposite in direction to the resultant.) Record the results in Table 1.2.

### Graphical Method

On a separate sheet of paper, construct a tail-to-head diagram of the vectors of Force A and Force B. Use a metric ruler and protractor to measure the magnitude and direction of the resultant. Record the results in Table 1.2. Remember to record the direction of the equilibrant as opposite in direction to the resultant..

Table 1.2:

Method	Equilibrant ( $F_E$ )	
	Magnitude	Direction
Experimental		
Component		
Graphical		

$$R_x = \underline{\hspace{2cm}} \quad R_y = \underline{\hspace{2cm}}$$

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## Question

How do the theoretical values for the magnitude and direction of the equilibrant compare to the actual magnitude and direction?