

MERCURY

YANMAR

YAMAHA

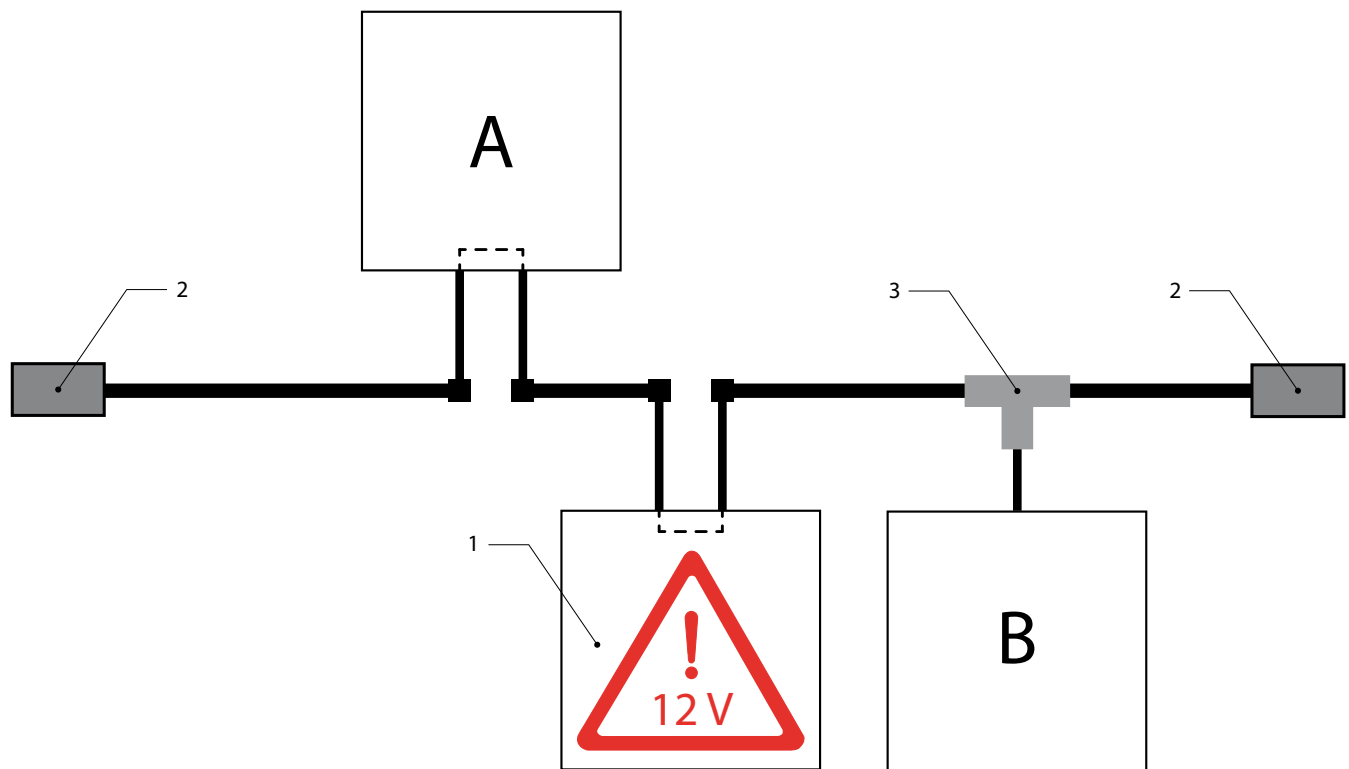
HONDA



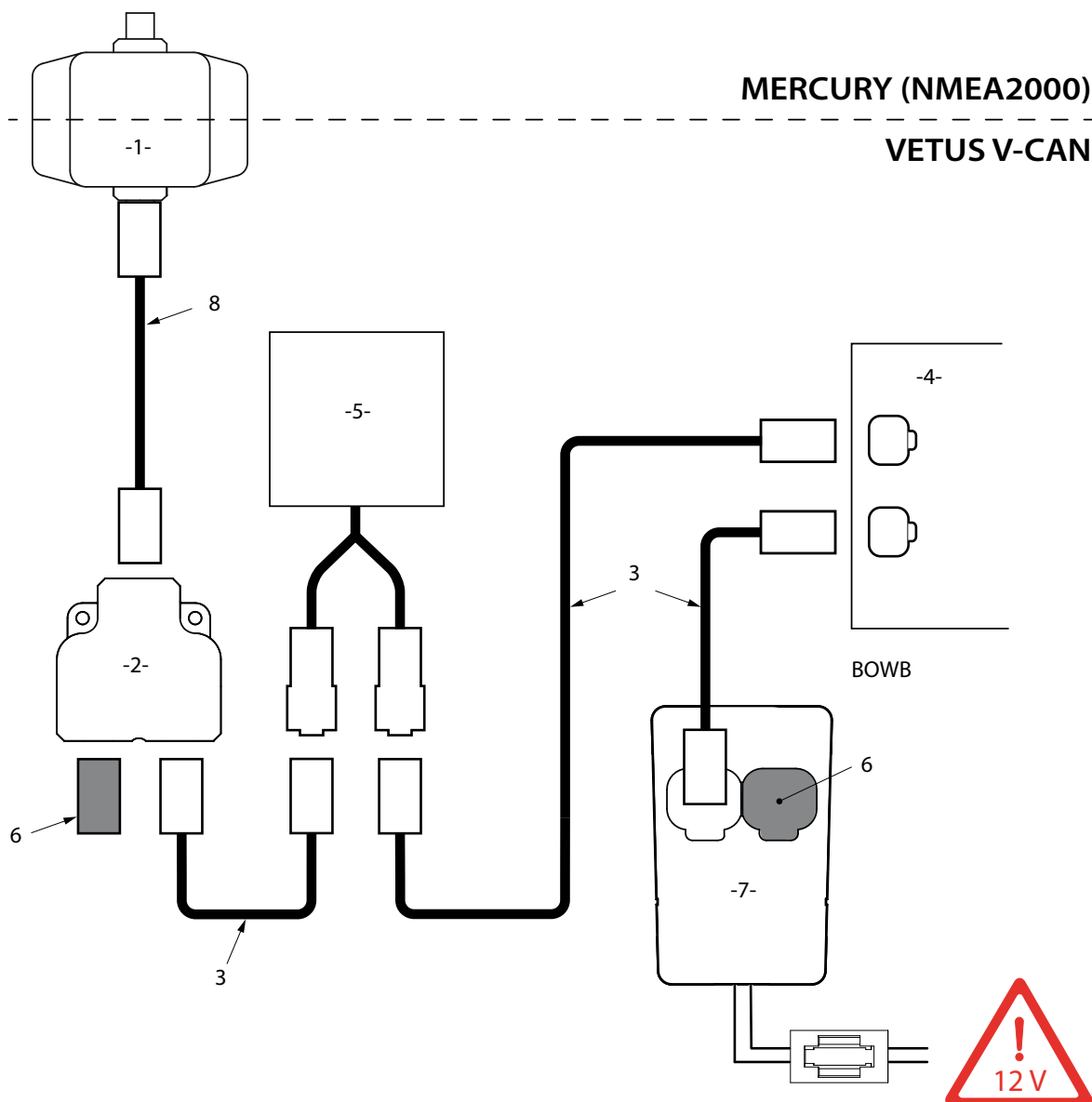
Installation manual

CAN-bus diagrams thruster integration

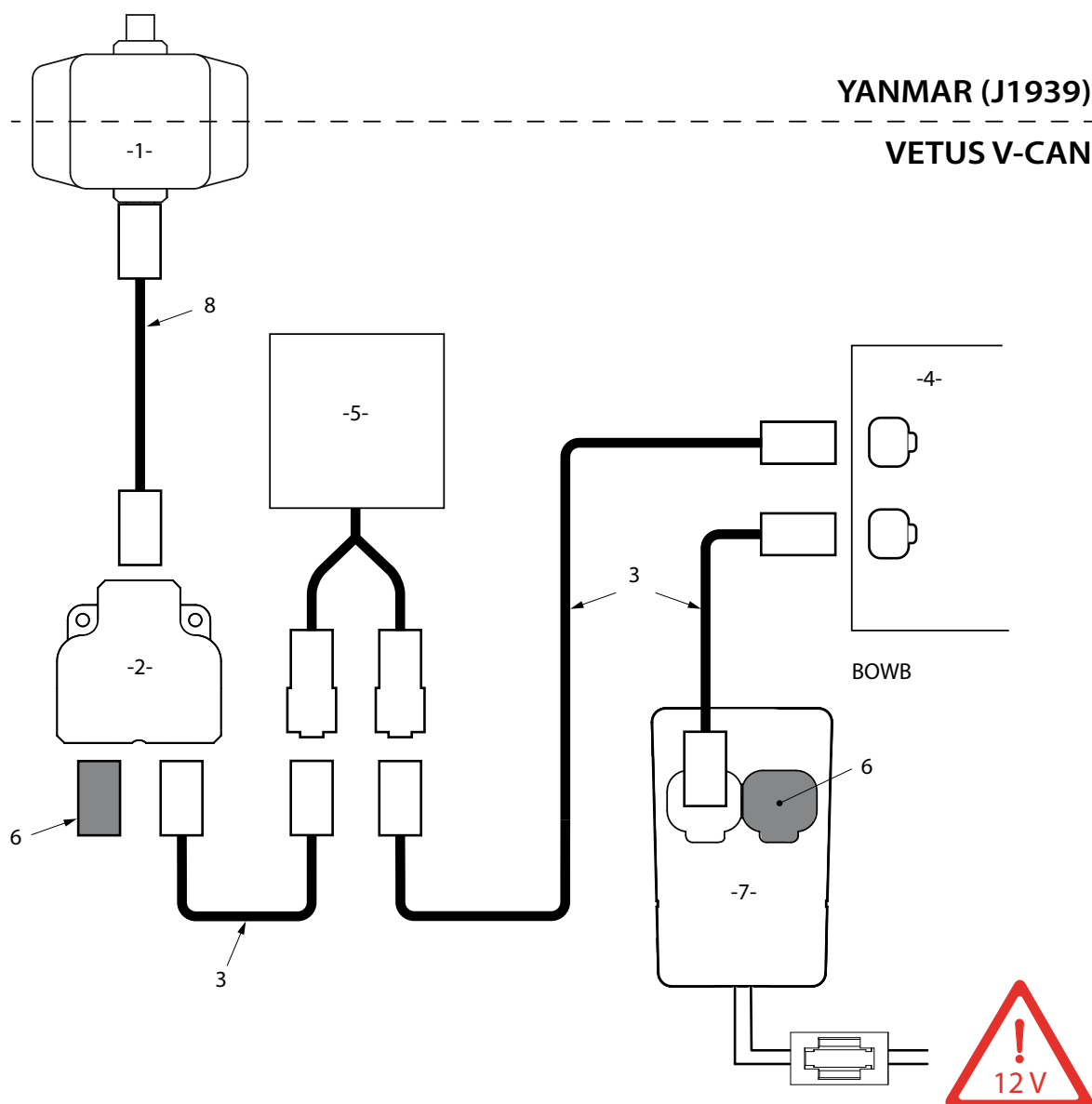
V-CAN principle diagram


 NOTE

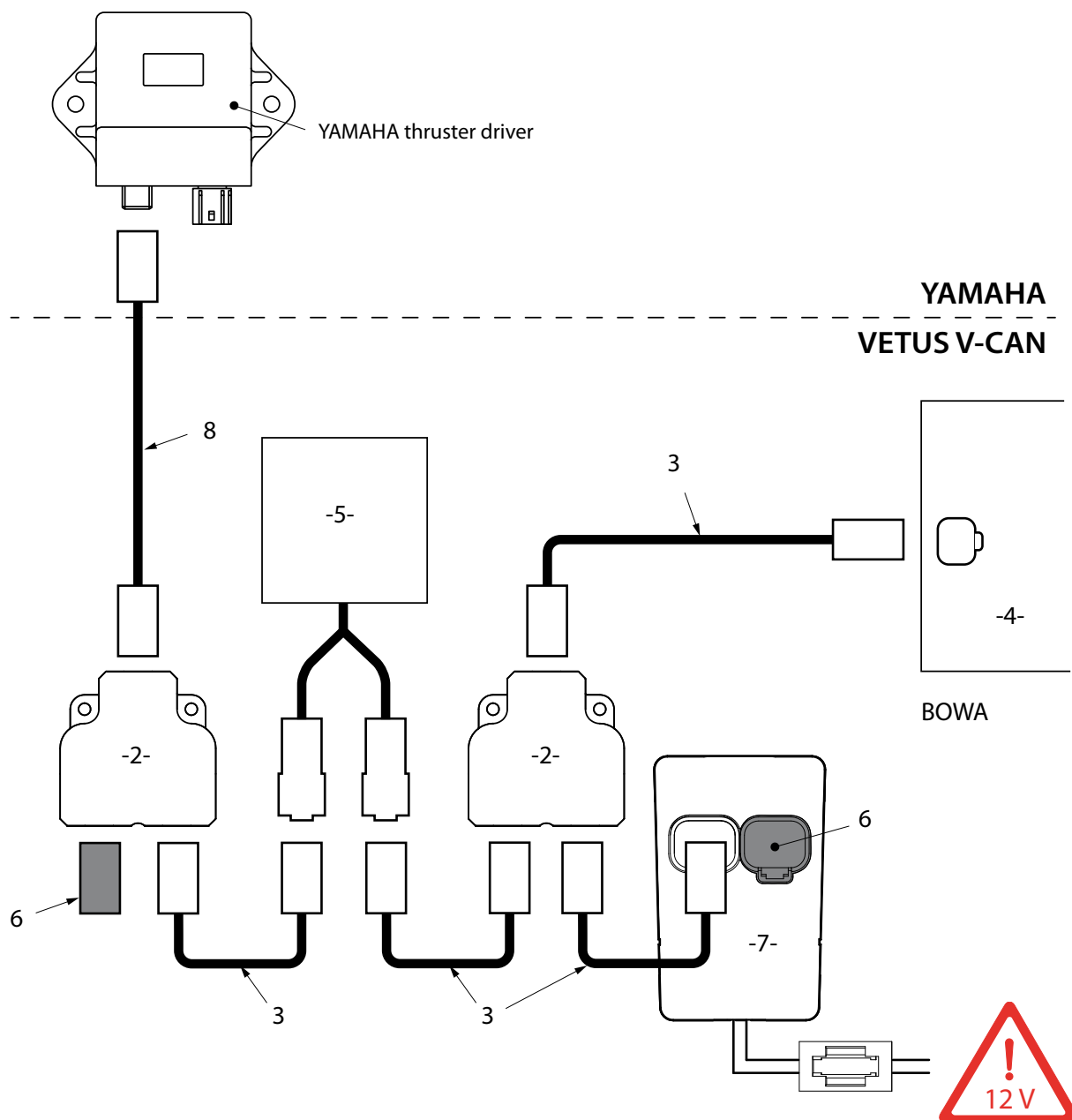
The V-CAN network system allows components to communicate with each other over a single data line. Components with one connection (B) must be connected to the network using a hub (3). Components with two connections (A) can be simply interconnected. Preferably place the 12 Volt CAN bus power supply (1) in the middle of the system. **Both ends of the network should always be equipped with a terminating resistor (2).**



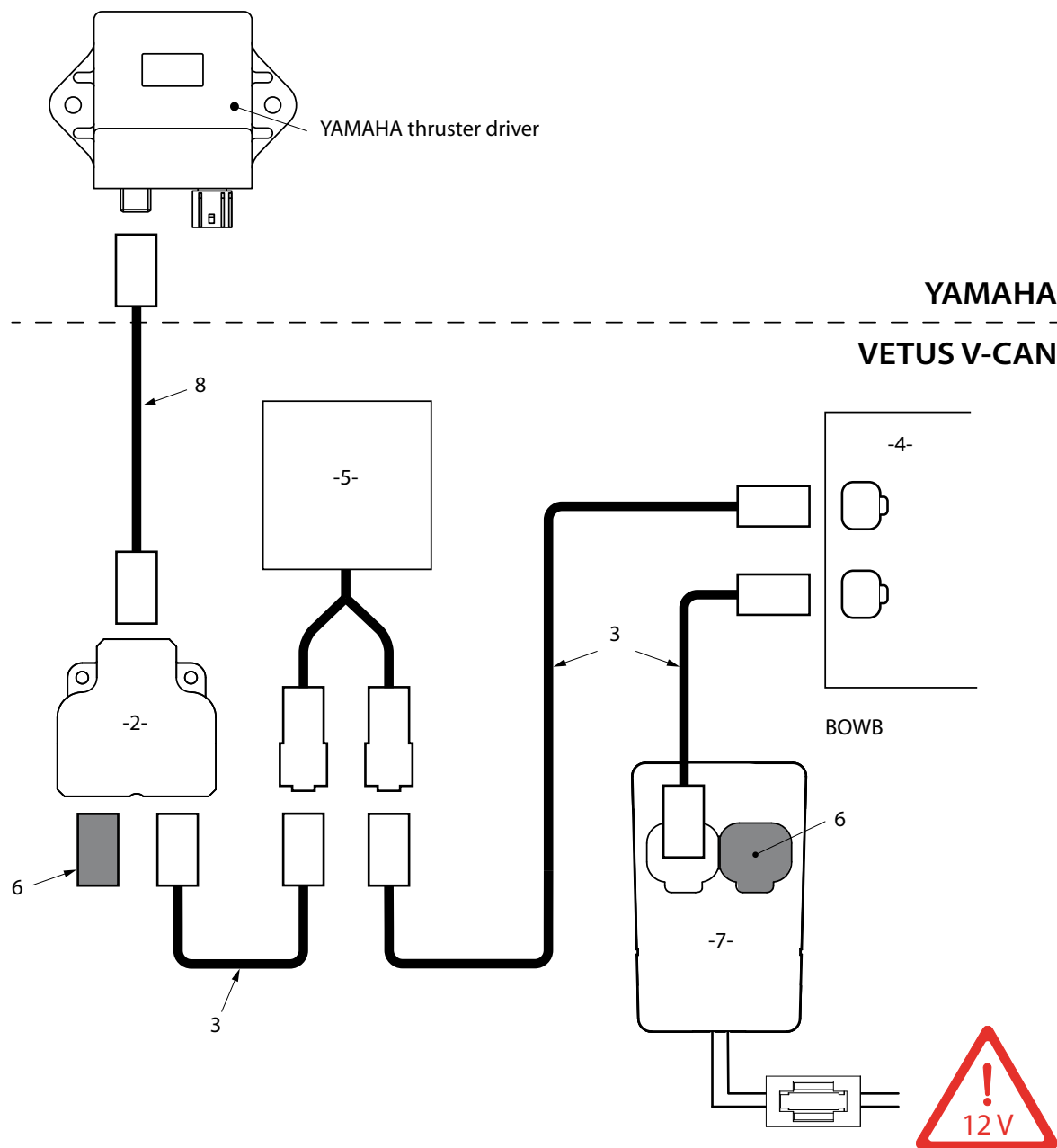
1	VETUS CANverter CANV2N2
2	CANVHUB
3	BPCABxxHF
4	BOWBxx
5	BPPA / BPPJA
6	CANVT
7	CANVPS
8	CANVM12A Included with CANverter



- | | |
|---|----------------------------------|
| 1 | VETUS CANverter CANV2Y2 |
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- | | |
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1 ---

2 CANVHUB

3 BPCABxxHF

4 BOWBxx

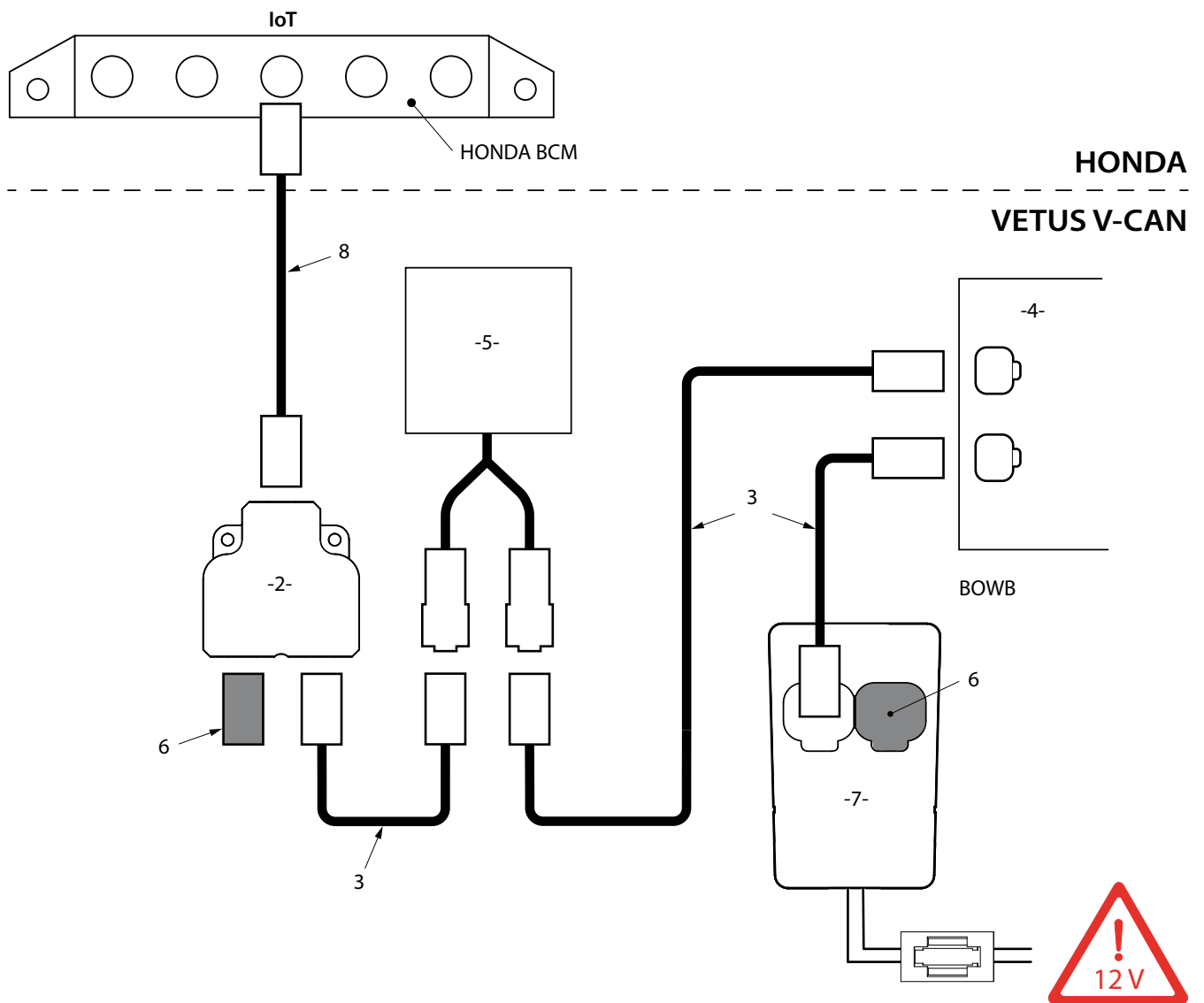
5 BPPPA / BPPJA

6 CANVT

7 CANVPS

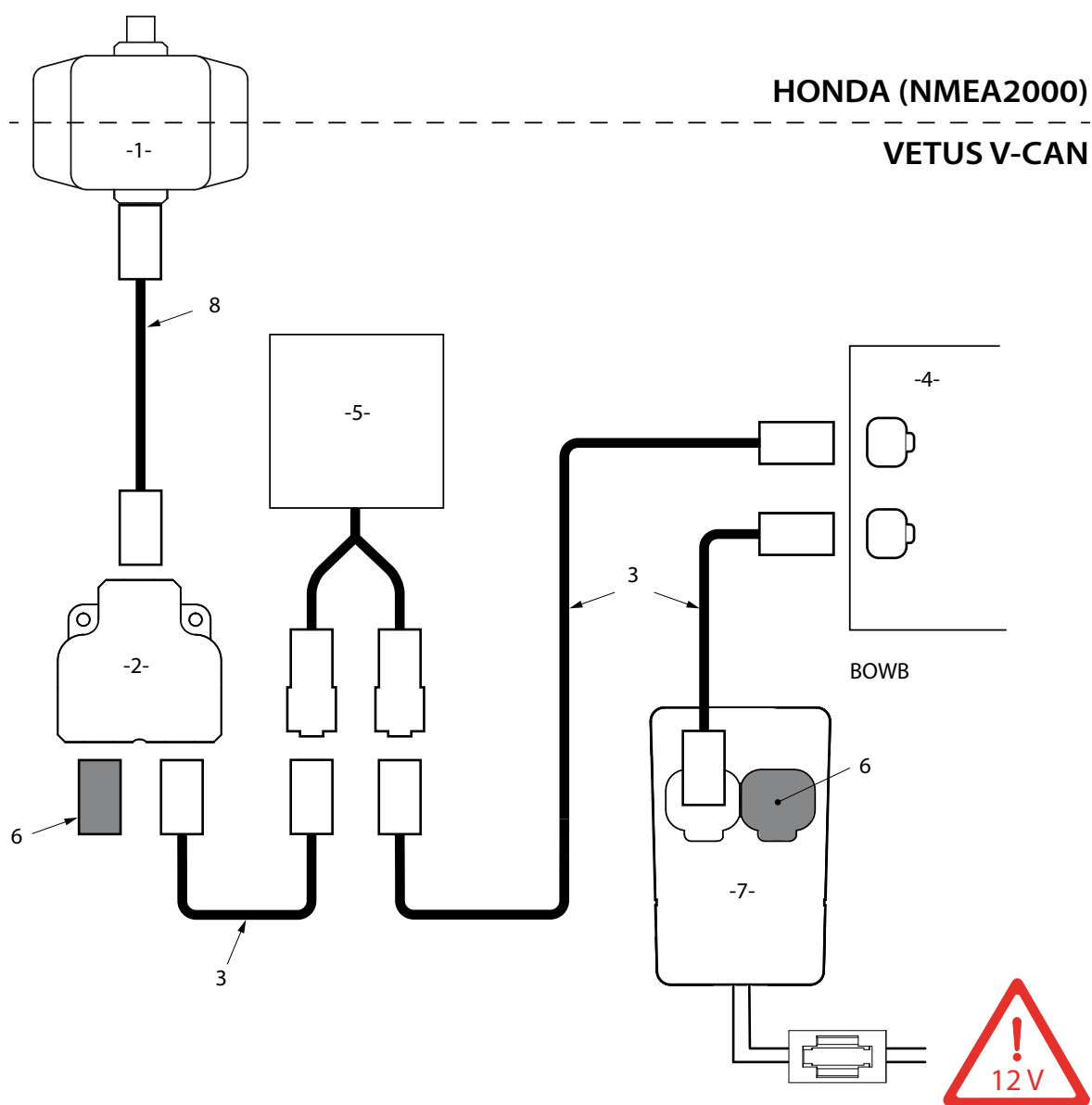
8 CANVM12A

Preferred connection diagram (use IoT port)



1	---
2	CANVHUB
3	BPCABxxHF
4	BOWBxx
5	BPPPA / BPPJA
6	CANVT
7	CANVPS
8	CANVM12A

Alternative connection diagram (when IoT port is in use)



- | | |
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