

# USER MANUAL

## Z-10-D-IN

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# Seneca Z-10-D-IN

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## 1. Introduction

The Z-10-D-IN module acquires 10 single-ended digital signals, then converts them to a digital format (IN 1-10 state).

The supported communication protocol is Modbus RTU.

The following counters are available:

8 counters at 16 bits

2 counters at 32 bits.

### 1.1. Features

- Acquisition of digital signals from sensor: Reed, NPN, PNP, Proximity, contact, etc...
- Counters are saved to a non volatile memory (NVM)
- Input signals IN1-IN8 can be filtered
- Pulse counters for digital signals, with max frequency equal to: 100 Hz for 16bit-registers (the signal is acquired from IN1-8); 10kHz, 32bit-registers (the signal is acquired from IN9-IN10)
- Advanced pulse management for digital signals IN9-IN10 (see table 1)
- Up to 10 sensors power by internal supply voltage (Vaux=16V)
- Node address and baud-rate configurable from Dip-Switches
- RS485 serial communication with MODBUS-RTU protocol, maximum 32 nodes.

## 2. Features

INPUT	
Number	10
Input filter	Cut-off frequency: 100Hz (for IN1-8); 10kHz (for IN9-10)
Filter	Configurable between: 1[ms] and 254[ms]
Protection	This module provides inputs and power supply (Vaux) protection against the overvoltage surge transient by transient suppressor TVS (600W/ms); max current supplied from Vaux is 100mA (limited by internal series PTC)
Pulse min duration (ton)	4ms (for IN1-IN8); 50µs (for IN9-IN10)
Sensor=closed	The sensor is detected «closed» if: acquired signal voltage >12 Vdc and acquired signal current > 3 mA
Sensor=open	The sensor is detected «open» if: acquired signal voltage <10 Vdc and acquired signal current < 2 mA

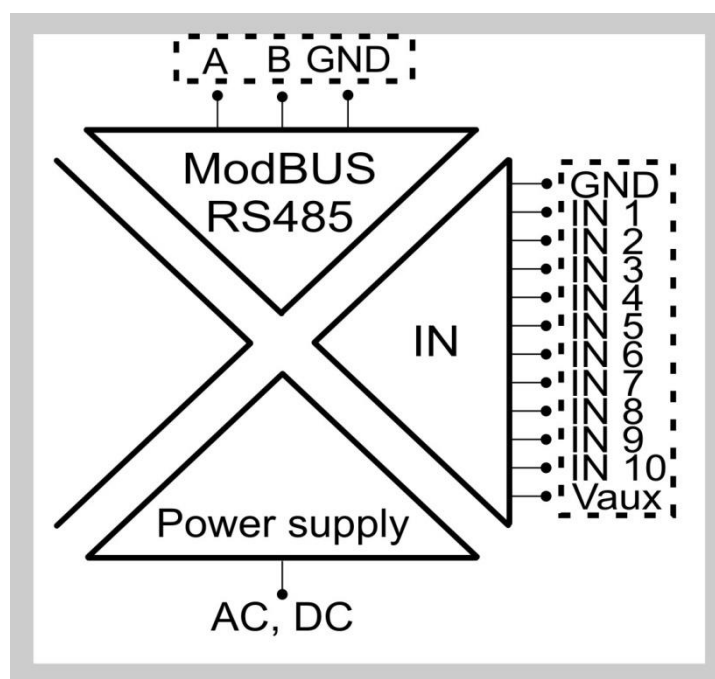
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<b>Internal supply Vaux</b>	The screw terminal 12 (Vaux) supplies 16 V with reference to the screw terminal 1 (GND)
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Measure error for frequency: 2% of fmax (for IN1-IN8:  $\pm 2\text{Hz}$ ; for IN9-IN10:  $\pm 200\text{Hz}$ )

Measure error for period, ton, toff: 1ms

CONNECTIONS	
<b>RS485 interface</b>	IDC10 connector for DIN 46277 rail (back-side panel)
1500 Vac ISOLATIONS	
	Between: power supply, ModBUS RS485, digital inputs

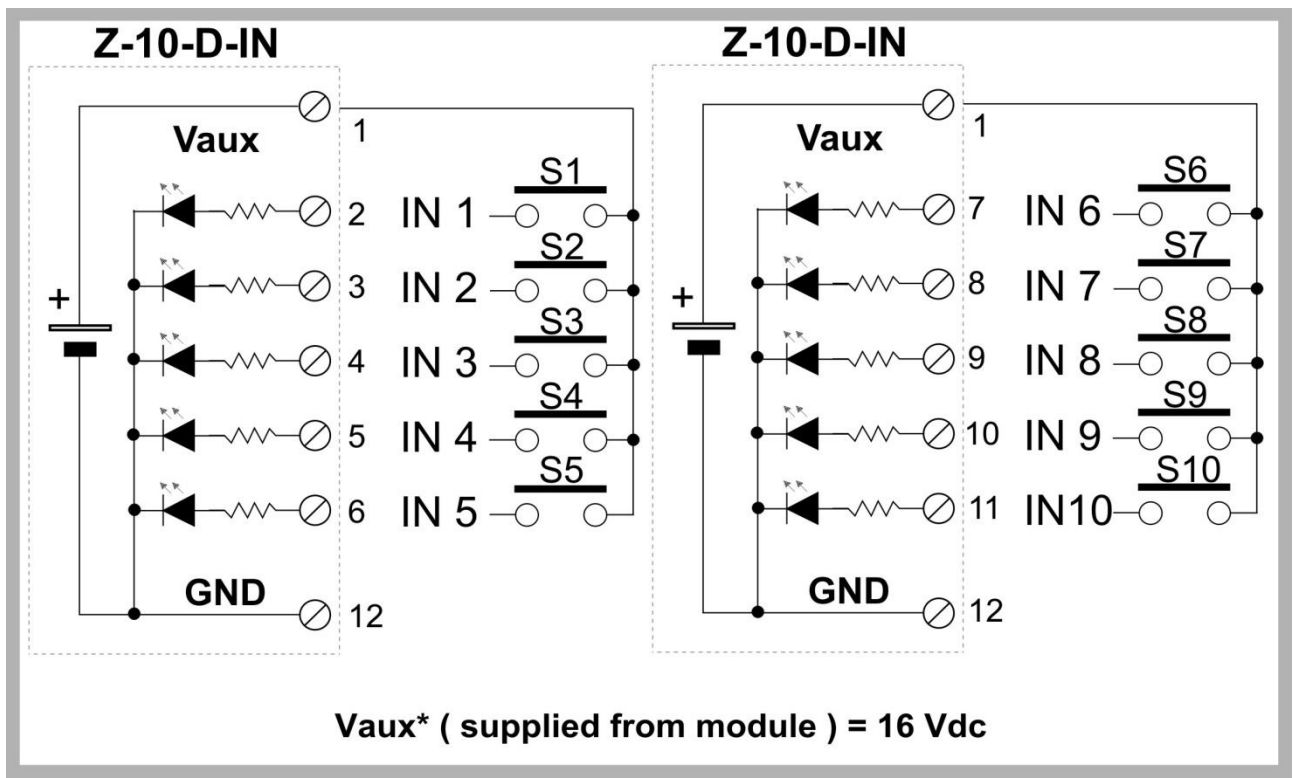


POWER SUPPLY	
<b>Supply voltage</b>	10 – 40 Vdc or 19 – 28 Vac ( 50Hz - 60Hz)
<b>Power consumption</b>	Min: 0.5W; Max: 2.5W

*The power supply transformer necessary to supply the module must comply with EN60742 (Isolated transformers and safety transformers requirements). To protect the power supply, is recommended to install a fuse.*

### 3. Input connections

Power on the module with < 40 Vdc or < 28 Vac voltage supply. These upper limits must not be exceeded to avoid serious damage to the module.



## 4. Dip-switches table

Power off the module before configuring it by Dip-Switches to avoid serious damage due to electrostatic discharges.



In the following tables: box without circle means Dip-Switch=0 (OFF state); box with circle means Dip-Switch=1 (ON state).

BAUD-RATE (Dip-Switches: DIP-SWITCH STATUS)						
1	2	Meaning				
		Baud-rate=9600 Baud				
	●	Baud-rate=19200 Baud				
●		Baud-rate=38400 Baud				
●	●	Baud-rate=57600 Baud				
ADDRESS (Dip-Switches: DIP-SWITCH STATUS)						
3	4	5	6	7	8	Meaning
						Address and Baud-Rate are acquired from memory(EEPROM)
					●	Address=1
				●		Address=2
				●	●	Address=3
			●			Address=4
X	X	X	X	X	X	.....
●	●	●	●	●	●	Address=63
RS485 TERMINATOR (Dip-Switches: DIP-SWITCH STATUS)						
9	10	Meaning				
		RS485 terminator disabled				
	●	RS485 terminator enabled				



## 5. Modbus RTU protocol

All registers are “Holding register” (Read Modbus function 3) with the convention that the first register is the 40001 address.

The following Modbus functions are supported:

*Read Modbus Register (function 3)*

*Write Single Modbus Register (function 6)*

*Write Multiple Modbus Registers (function 16)*

All values in 32bits are stored into 2 consecutive registers

For more info refers to:

<http://www.modbus.org/specs.php>

### 5.1. Abbreviation used

In the following table this abbreviations are used:

“MS” = Most significant
“LS” = Less significant
“MSB” = Most significant Bit
“LSB” = Less significant Bit
“MSW” = Most significant Word (16 bits)
“LSW” = Less significant Word (16 bits)
“R” = Read only register
“RW” = Read and write register

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"Unsigned 16 bits" = Unsigned 16 bits register
"Signed 16 bits" = 16 bits register with sign
"Float 32 bits" = Floating point single precision 32 bits (IEEE 754) register
"0x" = Hexadecimal Value (example 0x1234 = 4660 decimal)
"0b" = Binary Value (example 0b1110 = 14 decimal)

***Default communication parameters are 38400 baud, 8bit , parity None, 1 stop bit.***

## 5.2. Modbus Register Addresses

Register Name	Comment	Register Type	R/W	Default value or Start Value	Modbus Address	Modbus Offset Address
<b>MachineID</b>	Module ID code	Unsigned 16 bits	R	0x0A00	40001	0
<b>Inputs</b>	<p>Digital inputs 1..10 status value</p> <p>Bit 0 (LSB) = IN1 status            Bit 1 = IN2 status            Bit 2 = IN3 status            Bit 3 = IN4 status            Bit 4 = IN5 status            Bit 5 = IN6 status            Bit 6 = IN7 status            Bit 7 = IN8 status            Bit 8 = IN9 status            Bit 9 = IN10 status            Bit 10..14 = not used            Bit 15 (MSB) = not used</p> <p>For example if the register value is:            813 decimal =</p> <p>(MSB)0000 0011 0010 1101(LSB)            binary</p> <p>IN1 = 1            IN2 = 0            IN3 = 1            IN4 = 1</p> <p>IN5 = 0            IN6 = 1            IN7 = 0            IN8 = 0</p> <p>IN9 = 1            IN10 = 1</p>	Unsigned 16 bits	R	0	40002	1
<b>Counter 1</b>	<p>16 bit counter (from 0 to 65535)            The value is stored into a non volatile RAM (FeRAM).            The Counter 1 value can be written (for example writing 0 for setting the counter)</p>	Unsigned 16 bits	R/W	-	40003	2

<b>Counter 2</b>	16 bit counter (from 0 to 65535) The value is stored into a non volatile RAM (FeRAM). The Counter 2 value can be written (for example writing 0 for setting the counter)	Unsigned 16 bits	R/W	-	40004	3
<b>Counter 3</b>	16 bit counter (from 0 to 65535) The value is stored into a non volatile RAM (FeRAM). The Counter 3 value can be written (for example writing 0 for setting the counter)	Unsigned 16 bits	R/W	-	40005	4
<b>Counter 4</b>	16 bit counter (from 0 to 65535) The value is stored into a non volatile RAM (FeRAM). The Counter 4 value can be written (for example writing 0 for setting the counter)	Unsigned 16 bits	R/W	-	40006	5
<b>Counter 5</b>	16 bit counter (from 0 to 65535) The value is stored into a non volatile RAM (FeRAM). The Counter 5 value can be written (for example writing 0 for setting the counter)	Unsigned 16 bits	R/W	-	40007	6
<b>Counter 6</b>	16 bit counter (from 0 to 65535) The value is stored into a non volatile RAM (FeRAM). The Counter 6 value can be written (for example writing 0 for setting the counter)	Unsigned 16 bits	R/W	-	40008	7
<b>Counter 7</b>	16 bit counter (from 0 to 65535) The value is stored into a non volatile RAM (FeRAM). The Counter 7 value can be written (for example writing 0 for setting the counter)	Unsigned 16 bits	R/W	-	40009	8
<b>Counter 8</b>	16 bit counter (from 0 to 65535) The value is stored into a non volatile RAM (FeRAM). The Counter 8 value can be written (for example writing 0 for setting the counter)	Unsigned 16 bits	R/W	-	40010	9
<b>Counter 9</b>	32 bit counter (from 0 to 4294967295) The value is stored into a non volatile RAM (FeRAM). The Counter 9 value can be written (for example writing 0 for setting the counter)	Unsigned 32 bits	R/W	-	40011 (LSW) 40012 (MSW)	10-11
<b>Counter 10</b>	16 bit counter (from 0 to 4294967295) The value is stored into a non volatile RAM (FeRAM).	Unsigned 32 bits	R/W	-	40013 (LSW) 40014 (MSW)	12-13

	The Counter 10 value can be written (for example writing 0 for setting the counter)					
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<b>Counters Overflow Flags</b>	<p>The flag is “1” if the counter has performed an overflow</p> <p>Bit 0 (LSB)= Overflow Counter 1            Bit 1 = Overflow Counter 2            Bit 2 = Overflow Counter 3            Bit 3 = Overflow Counter 4            Bit 4 = Overflow Counter 5            Bit 5 = Overflow Counter 6            Bit 6 = Overflow Counter 7            Bit 7 = Overflow Counter 8            Bit 8 = Overflow Counter 9            Bit 9 = Overflow Counter 10            Bit 10..14 = not used            Bit 15 (MSB) = not used</p>	Unsigned 16 bits	R/W	0	40015	14
<b>Measure B</b>	Input B measure value	Unsigned 16 bits	R	0	40016	15
<b>Measure A</b>	Input A measure value	Unsigned 16 bits	R	0	40017	16
<b>Measure A/B Type</b>	<p>Bit [15..12] = 0b0000 Measure A frequency            Bit[15..12] = 0b0001 Measure A period            Bit[15..12] = 0b0010 Measure A Ton            Bit[15..12] = 0b0011 Measure A Toff</p> <p>Bit[11..8] = 0b0001 Measure A from input 1            Bit[11..8] = 0b0010 Measure A from input 2            Bit[11..8] = 0b0011 Measure A from input 3            Bit[11..8] = 0b0100 Measure A from input 4            Bit[11..8] = 0b0101 Measure A from input 5            Bit[11..8] = 0b0110 Measure A from input 6            Bit[11..8] = 0b0111 Measure A from input 7            Bit[11..8] = 0b1000 Measure A from input 8            Bit[11..8] = 0b1001 Measure A from input 9 (only frequency)</p>	Unsigned 16 bits	R/W*	0	40018	17

	<p>Bit[11..8] = 0b1010 Measure A from input 10 (only frequency)</p> <p>Bit [7..4] = 0b0000 Measure B frequency          Bit[7..4] = 0b0001 Measure B period          Bit[7..4] = 0b0010 Measure B Ton          Bit[7..4] = 0b0011 Measure B Toff</p> <p>Bit[3..0] = 0b0001 Measure B from input 1          Bit[3..0] = 0b0010 Measure B from input 2          Bit[3..0] = 0b0011 Measure B from input 3          Bit[3..0] = 0b0100 Measure B from input 4          Bit[3..0] = 0b0101 Measure B from input 5          Bit[3..0] = 0b0110 Measure B from input 6          Bit[3..0] = 0b0111 Measure B from input 7          Bit[3..0] = 0b1000 Measure B from input 8          Bit[3..0] = 0b1001 Measure B from input 9 (only frequency)          Bit[3..0] = 0b1010 Measure B from input 10 (only frequency)</p>					
<b>IN1..IN8 FILTER</b>	<p>Filter value from 1 ms to 255 ms.</p> <p>For example with filter = 1 ms will attenuate pulse with frequency &gt; 1/1ms = 1000 Hz</p> <p>With filter = 10 ms will attenuate pulse with frequency &gt; 1/10ms=100 Hz</p>	Unsigned 16 bits	R/W*	3 ms	40019	18
<b>IN9..IN10 COUNT MODE / RS485 PARITY</b>	<p>Bit [12:8] = 0b00000 IN9 Upcounter IN10 Upcounter</p> <p>Bit [12:8] = 0b00001 IN9 Downcounter IN10 Upcounter</p> <p>Bit [12:8] = 0b00010 IN9 Upcounter IN10 Downcounter</p> <p>Bit [12:8] = 0b00100 IN9 Downcounter IN10 Downcounter</p>	Unsigned 16 bits	R/W*	0	40020	19

	<p>Bit [12:8] = 0b01000 Count+1 from IN9 and Count-1 from IN10. Only Count 9 is active</p> <p>Bit [12:8] = 0b10000 if IN10=1 Count9 Upcounter, if IN10=0 Counter9 Downcounter</p> <p>Bit[4] = 0 Port RS485 Parity Even Bit[4] = 1 Port RS485 Parity Odd</p> <p>Bit[3] = 0 Port RS485 Parity Not Active Bit[3] = 1 Port RS485 Parity Active</p> <p>Bit[2] = 0 Delay Between Rs485 Port TX and RX disabled Bit[2] = 1 Delay Between Rs485 Port TX and RX enabled</p> <p>Bit[1] = 0 IN1..IN8 Upcounter Bit[1] = 1 IN1..IN8 Downcounter</p> <p>Bit[0] = 0 IN1..IN10 Normal Logic Bit[0] = 1 IN1..IN10 Reverse Logic</p>					
<b>ADDRESS BAUDRATE</b>	<p>Bit[15..8] = 0b00000000 RS485 use 4800baud Bit[15..8] = 0b00000001 RS485 use 9600baud Bit[15..8] = 0b00000010 RS485 use 19200baud Bit[15..8] = 0b00000011 RS485 use 38400baud Bit[15..8] = 0b00000100 RS485 use 57600baud Bit[15..8] = 0b00000101 RS485 use 115200baud Bit[15..8] = 0b00000110 RS485 use 1200baud Bit[15..8] = 0b00000111 RS485 use 2400baud</p> <p>Bit[7:0] = Station Node Address (if all dip switched are set to OFF)</p>	Unsigned 16 bits	R/W*	0b000001000000 0001 (38400 baud, station address 1)	40021	20
<b>COMMAND</b>	If set to 2: Copy the actual contents of registers R/W* into EEPROM.	Unsigned 16 bits	R/W	0	40022	21

	If set to 1: Perform a Reset					
<b>FW REVISION</b>	Fw revision	Unsigned 16 bits	R	-	40024	23

## 6. EASY SETUP

To configure the Z-10-D-IN download the Easy Setup PC software from the Seneca Website:

<http://www.seneca.it/en/linee-di-prodotto/software/easy/easy-setup/>

