

Quick Start Guide

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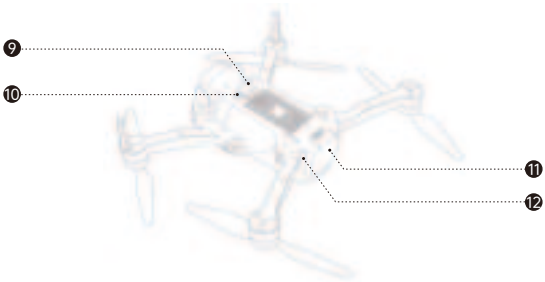
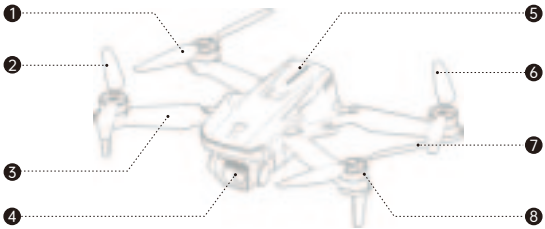


Download the
CHUBORY FUN App

watch the
tutorial video

view the
instruction for use

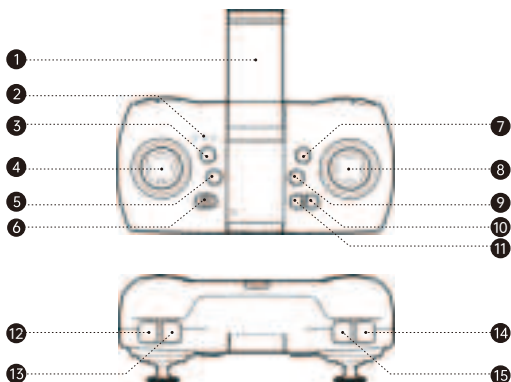
DIAGRAM OF THE DRONE



- ① Propeller A
- ② Propeller B
- ③ Arm
- ④ Wifi Camera
- ⑤ Upper Casing
- ⑥ Propeller B

- ⑦ Propeller A
- ⑧ Brushless Motor
- ⑨ Optical Flow Lens
- ⑩ Power Switch
- ⑪ Drone Battery
- ⑫ Indicator Light

DIAGRAM OF THE TRANSMITTER



① Mobile phone clip

② Indicator

③ One-key ascend

④ Left joystick

⑤ One-key landing

⑥ Power switch

⑦ Camera upward

⑧ Right joystick

⑨ Camera downward

⑩ Fine-tuning key

⑪ Press 3 seconds to stop

⑫ High/Low speed

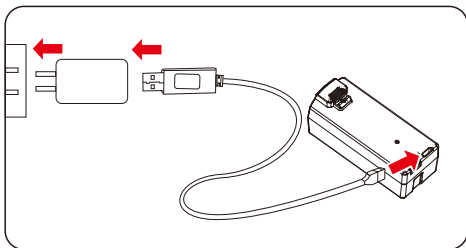
⑬ Headless mode

⑭ One-key flips&rolls

⑮ Calibration


1

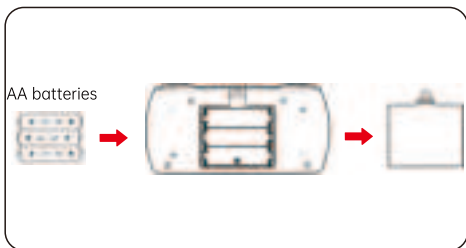
CHARGING



● Charging

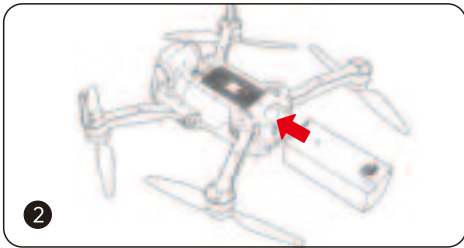
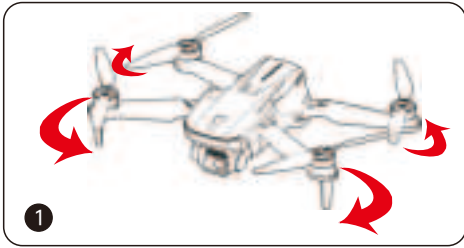
● Fully charged(off)

 To charge each battery with a 5V=2A charger, it takes approximately 4-6 hours.



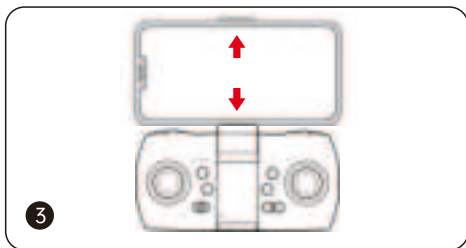
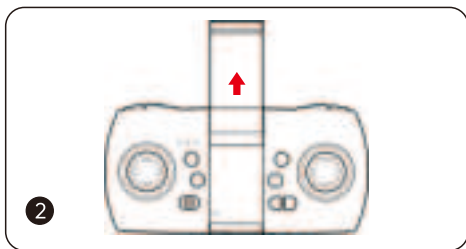
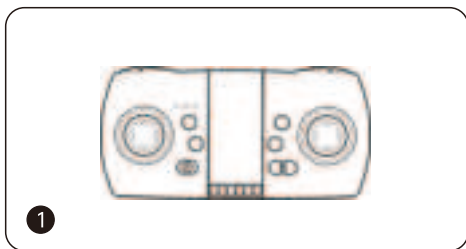
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GET THE DRONE READY



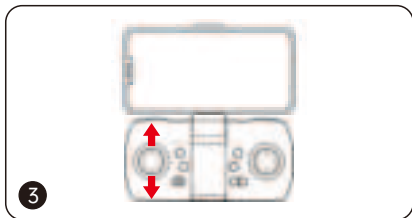
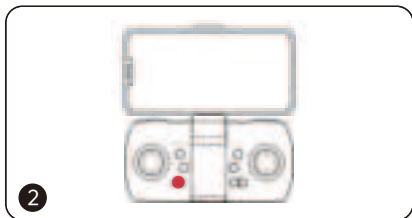
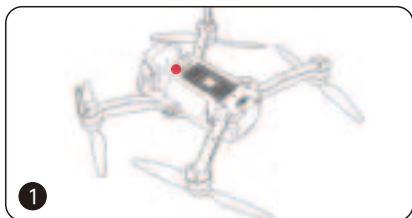
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GET THE TRANSMITTER READY



4

PAIRING



 Place the drone on a level ground and turn on the power, and then turn on the power of the remote control. Push the throttle joystick to the highest point then push back to lowest point, the light changes from flashing to steady, indicating the signal connection is completed.

5

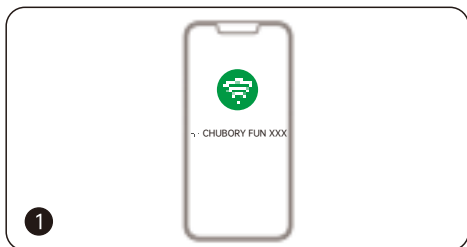
CALIBRATE THE GYRO

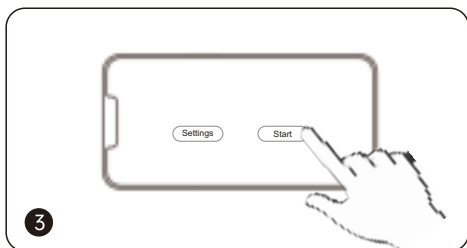
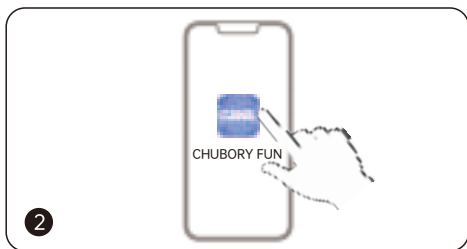


Press the "One button calibration" button When the lights of drone are on and then start flashing and keep on again, the calibration is complete. the drone must be placed on a horizontal surface in a steady state when the calibration is conducted.

6


CONNECT TO WIFI

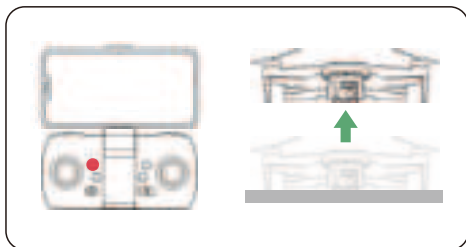




7

TAKE-OFF

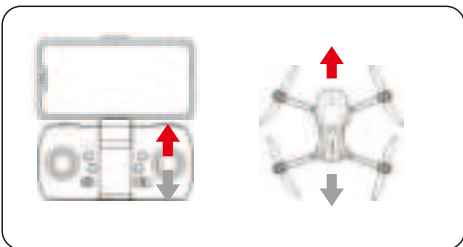
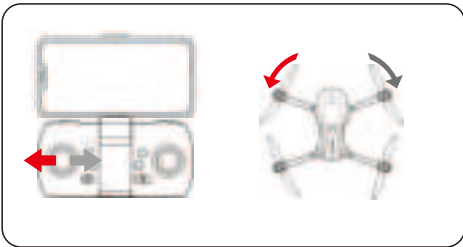
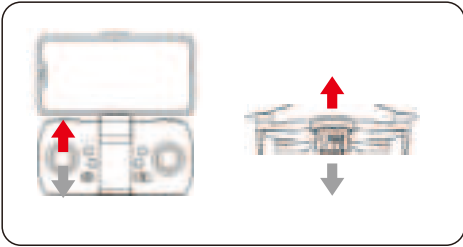
 Please fly the drone in an open outdoor area free of surrounding obstructions.

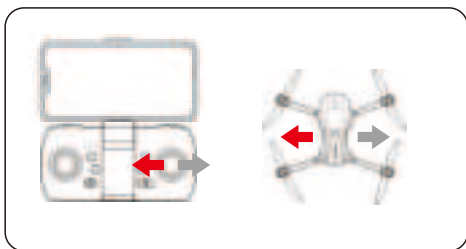


8

FLIGHT DIRECTION CONTROL

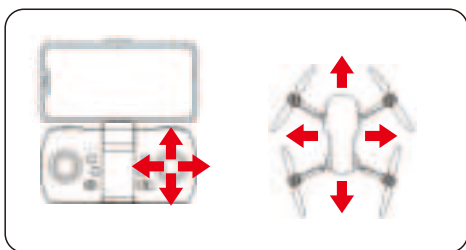
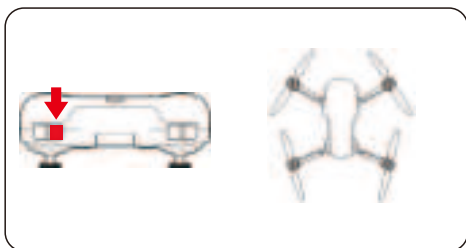
🧩 The left joystick controls the drone's altitude and orientation during flight, while the right joystick manages its forward, backward, and lateral movements.





9

HEADLESS MODE

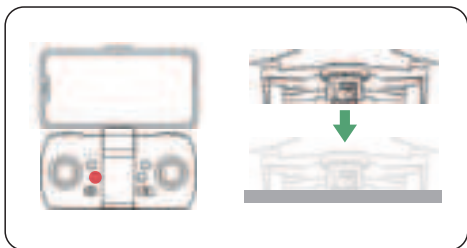


🔑 In the headless state, operator doesn't need to identify the direction of nose, but control the drone according to the operating lever of remote control.

When the drone flies far away and it's difficult to determine its orientation, it is advisable to activate headless mode to bring the drone back.

10

LANDING



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