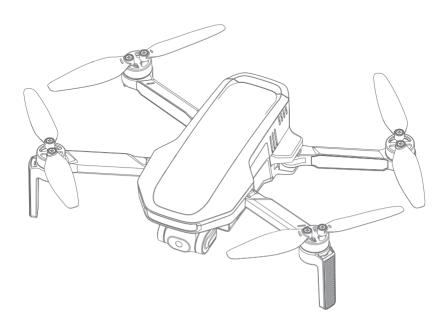
# **Potensic** ATOM





# **User Manual**

V04, 24, 06

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## 1 Disclaimer & Precautions

#### >> 1 1 Disclaimer

Drones are products with potential dangers and relatively complex operations. Prior to usage, it is crucial to thoroughly read the complete User Manual to grasp basic knowledge and become familiar with the drone's functions. For the initial use of ATOM, it is recommended to operate it in GPS mode in a spacious outdoor area to acquaint yourself with its functions.

Strictly adhere to the Manual's operational instructions and precautions to ensure safe and correct usage. Users below the age of 16 should be supervised by an adult, and the product should be kept out of reach of children.

The Company disclaims responsibility and does not provide warranty services for any direct or indirect losses (including property loss and personal injury) resulting from the user's failure to follow the Manual's safety quidelines.

Avoid dismantling any part of the product except for propellers or modifying it without official guidance; users will be accountable for any consequences arising from such violations.

For assistance with usage, operation, and maintenance issues, feel free to contact our local dealer or the Company.

Potensic reserves the final interpretation rights of this document and related product documents, and the information is subject to change without notice. For the latest updates, please visit https://www.potensic.com.

#### >> 1.2 Safety & Precautions

#### Keep away from obstacles and crowds

To ensure the safety of both the user and those around, please keep the product away from crowded areas, high-rise buildings, and high-voltage cables. Additionally, refrain from using it in severe weather conditions such as strong winds, heavy rain, and thunderstorms. This precaution is necessary as the product may exhibit unpredictable flight speeds, status fluctuations, and potential hazards.

#### Keep off moisture

To prevent anomalies or damage caused by humidity affecting precise electronic components and mechanical parts inside the product, please ensure it is kept away from moisture.

#### Safe operation

When operating the drone, the likelihood of unforeseen risks rises when users are fatigued, in poor mental condition, or lack experience. To ensure safety, it is essential to refit or repair the product using original parts. Operate the product strictly within specified limits, and be sure to adhere to local safety regulations.

#### Keep away from high-speed revolving parts

While the product's propellers are spinning at a high speed, keep it away from crowds and animals to prevent scratches or disturbances. Avoid touching the spinning propellers with your hands.

#### Keep away from heat source

To prevent anomalies, deformation, and potential damage, keep the product away from heat and high-temperature exposure. This precaution is especially crucial as the product comprises metal, fiber, plastic, and electronic elements.

## 3 1.3 Warning & Prompts

- 01. Keep the package and manual in a secure place as they contain important information.
- 02. Users are responsible for ensuring that the use of this drone does not cause harm to the person or property of others.
- 03. Our company and dealers are not liable for losses and personal injuries resulting from improper use or operation.
- 04. Users must strictly follow the steps outlined in the user manual to install and test the drone. During flight, maintain a minimum distance of 1 to 2 meters from users or other individuals to prevent the drone from colliding with human bodies, causing injury.
- 05. The product should be assembled by an adult. Users aged below 16 should not handle the product alone. The battery should be charged under the supervision of an adult and should be kept away from flammable materials during the charging process.
- 06. The product contains small parts. Please place them out of reach of children to prevent accidental ingestion.
- 07. Do not operate the product over roads or standing water to avoid accidents.

- OR It is forbidden to dismantle or refit the product, except for the propellers, as doing so may lead to malfunctions
- 09. Please recharge the intelligent battery with a USB charger that conforms to FCC/CE standards.
- 10. The remote controller has a built-in 3.7V lithium battery which needs no replacement
- 11 Do not short-circuit or squeeze the battery to avoid explosion
- 12. Do not place the battery in hot place (in fire or near electric heater).
- 13. Keep a safe distance from the high-speed revolving propellers; avoid using the product in crowds to prevent scratches or injuries
- 14. Do not use the product in places with strong magnetic field, such as pear high-voltage cable, buildings that contain metals, automobiles and trains; otherwise, the connection stability can be compromised.
- 15. Please make sure to thoroughly understand local laws and regulations to avoid any unauthorized use of the
- 16. To comply with the requirements of the aeronautical radio magnetic environment, during the period of radio control orders issued by the relevant national authorities within the specified regions, the use of remote controller should be suspended as instructed
- 17. Please refrain from flying at low altitudes over water surfaces.
- 18. Please stay away from airports, flight paths, and other restricted areas.

## 2. Reading Tips

## >> 2.1 Legend





-Ö- Operation & use prompts



Technical Terms and reference information

## >> 2.2 Suggestions of Use

- 1. It is advisable to watch the tutorial video and Quick Start Guide before referring to the Manual.
- 2. Be sure to read the Disclaimer & Precautions section first when consulting the Manual.

## 2.3 Tutorial Video / Download App

Scan the QR code on the right and you can:

- 1. Download PotensicPro App (hereinafter referred to as "the App").
- 2 Watch the tutorial videos
- 3. Access the latest User Manual.
- Learn about the frequently asked questions(FAQ).

## 2.4 Registration & Help

It's required to set up an account when using the App for the first time to have better user experience.

#### Registration Procedures

- 1. Enter your email;
- 2. Set your password;
- 3. Check and agree with the Protocols;
- 4. Register.

You can log into the App after registration.

Note: An Internet connection is required during the registration.

#### Help

Thanks for purchasing Potensic Atom. Before using the drone for the first time, we recommend that you read the user manual carefully.

Please contact our support team at support@potensic.com if you encounter any problem or issue with the drone. Make sure to submit your order ID and the details of the issue.

## ≫ 2.5 Technical Terms ■

IMU	IMU (inertial measurement unit), the most important core sensor of the drone.
TOF (Time of Flight)	TOF (time of flight), the period from transmission and receiving of detection infrared signal, in order to determine the target distance.
Downward Vision System	The sensor system, which lies at the bottom of the drone and consists of camera and TOF module.
Vision Positioning	High-accuracy positioning, which is realized through Downward Vision System.
Compass	Geomagnetic sensor, which enables the drone to identify the direction.
Barometer	Atmospheric pressure sensor, which enables the drone to determine the altitude through atmospheric pressure.
Lock/unlock	Refers to the transition of the drone's motors from a stationary state to idle rotation.
ldling	Once unlocked, the motor will start spinning at a fixed speed, but it can't provide sufficient lifting force for the drone to take off.
Auto return	The drone will return to HOME point automatically based on GPS positioning.
Drone head	Position of the drone camera.
Throttle control stick	Ascend or descend the drone.
Pitch control stick	Fly the drone forward or backward.
Roll control stick	Fly the drone leftward or rightward.
Yaw control stick	Enables the drone to rotate clockwise or anticlockwise.

## 3. Overview

This chapter introduces the functional characteristics of ATOM, as well as the diagrams of the drone and the remote controller.

#### >> 3.1 Introduction

Atom features foldable arms for convenient portability, with a lightweight body weighing less than 250g. The drone possesses a Vision Positioning System, which allows for precise hovering in low-altitude indoor and outdoor environments. Equipped with a GPS sensor, the drone enables positioning and automatic return. The camera utilizes a 1/3-inch Sony CMOS image sensor, capable of capturing high-definition 4K/30FPS video and 12 million pixels photos. The camera is mounted on a 3-axis gimbal, which allows the camera to acquire stable footages while operating the drone.

ATOM's remote controller utilizes the PixSync™ 3.0 2.4G digital transmission technology, achieving a maximum communication distance of up to 6km and 720P video transmission in ideal conditions. The controller features a retractable and foldable design, providing a placement for your mobile device when unfolded. When connected to the controller via a USB cable, you can operate and configure your drone through the App, as well as view high-definition video transmission. The built-in lithium battery in the remote controller has a maximum working time of approximately 2.3 hours.

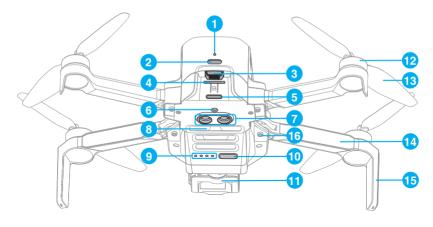
ATOM utilizes proprietary SurgeFly™ flight control technology, achieving a maximum flight speed of 16m/s (52ft/s) and a maximum flight time of approximately 32 minutes, with resistance against wind up to Level 5.

- ⚠
- Test conditions of the max. flight time: Fly at an even speed of 5m/s at 25°C and in breezeless condition.
  - Test conditions of the max. transmission distance: Measured at an open and no-interference environment, with a flight height of 120m, and without considering the return of the drone.
  - Power consumption will increase considerably when the drone is returning against the wind. If you
    receive a prompt of encountering strong wind from the App, please make sure to lower the flight
    altitude and return in time to ensure safety of the drone.

#### Pre-Flight Checklist:

- 1. Pay attention to the local weather forecast and make sure it is suitable for flying the drone.
- 2. Make sure the battery is fully charged.
- 3. Make sure the firmware is updated to the latest version.
- 4. Make sure the flight environment is open and free of interference.
- Before takeoff, make sure the battery is secured and the buckle pops out correctly, and no deformed propellers and loose screws.
- Power on the drone on open and level ground, wait for the drone to enter GPS Mode before takeoff, and pay attention to the HOME point.

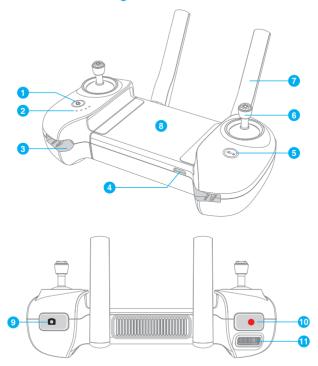
## >> 3.2 Drone Diagram



- 1. Charging indicator
- 2. TYPE-C charging port
- 3. Battery buckle
- 4. SD card slot
- 5. Tail indicator
- 6. Monocular visual module
- 7. TOF module
- 8. Bottom cooling hole

- 9. Power indicator
- 10. Power/frequency pairing button
- 11. 3-axis gimbal and camera
- 12. Brushless motor
- 13. Propeller
- 14. Arm
- 15. Antenna tripod
- 16. Arm shaft

## >> 3.3 Remote Controller Diagram



#### 1. Power button

Long press for 2s to power on/off.

#### 2. Power indicator

Indicate the power level or other status of the remote controller.

#### 3. Control stick slot

One slot respectively at the left and right side, which are used to store the sticks.

#### 4. TYPE-C interface

To charge the remote controller/connect mobile device.

#### 5. RTH / Pause button

Long press for 1s to return to HOME point automatically.

Short press to pause auto flight.

#### 6. Control stick

#### 7. Foldable dual antennas

## 8. Placement for mobile device To place mobile device.

#### 9. Shoot button

Short press it to shoot one picture.

#### 10. Record button

Short press to start/stop recording.

#### 11. Gimbal dial

Use the gimbal dial to control the tilt of the camera.

## >> 3.4 Preparing the Drone

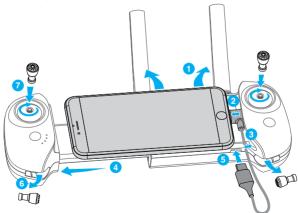
The product is delivered under folded status. Please unfold it as follows:

- 1 Remove the gimbal protector
- 2. Unfold the front arm before the rear arm.
- 3. Unfold the propeller blades.

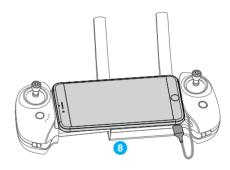


## >> 3.5 Preparing the Remote Controller

Installation of mobile phone and control stick

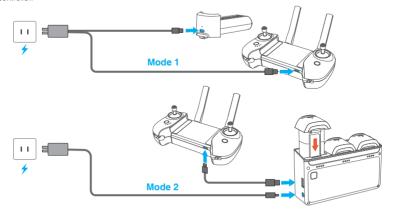


- 1. Unfold the antenna.
- 2. Connect your mobile phone to the USB cable.
- 3. Insert the part of your mobile phone with the USB cable into the slot of the remote controller.
- 4. Pull and open the remote controller with both hands and fix your mobile phone stably.
- 5. Connect the other end of the USB cable to the remote controller.
- 6. Take out the sticks.
- 7. Screw in both control sticks clockwise.
- 8. Installation completed.



## >> 3.6 Charging / Startup and Shutdown

Before the first flight, it is essential to wake up the battery; otherwise the drone wouldn't start. Connect the TYPE-C charging port of battery and a USB charger to the AC power supply to finish single charging (USB charger is not included in the package. User can use a charger that conforms to FCC/CE specification to charge the battery). The red indicator will stay on during charging, and turn off automatically after charging is done. User can charge the battery with the Parallel Charging HUB if Fly More Combo is purchased. For more details, please refer to Fly More Combo of Parallel Charging HUB. The Parallel Charging HUB can also charge the remote controller.



- The shortest charging period is approx. 1h 25min through the TYPE-C charging port. Make sure your charger supports 5V/3A output in order to achieve this charging speed.
  - User is suggested to charge the battery through the Parallel Charging HUB, in order to charge 3 batteries quickly at the same time.
- It is suggested to remove the battery from the drone to charge for safety reasons; otherwise, the drone won't power on if the battery is being charged in the drone.
  - If the charging cable is connected while the drone is on, it will power off automatically and the charging will continue.
  - The battery may become too hot after use; do not charge it until it cools down; otherwise, charging can be rejected by the smart battery.
  - . Charge the battery every three months to sustain the cell's activity.
  - Please connect the original cable or any cable that supports over 3A current to the TYPE-C port;
     otherwise, it may cause charging failure or battery damage.

#### Startup

**Drone:** Make sure the battery is inserted in battery bin, short press and then long press the power button until all indicators are on, and then release the button to start up.

Remote controller: Long press the power button until all indicators are on, and then release the button to finish startup.

#### Shutdown

**Drone:** Short press and then long press the power button of the drone until all indicators are off, and then release the button to shut down.

Remote controller: Long press the power button until all indicators are off, and then release the button to shut down.

#### 4. Drone

ATOM consists of a flight control system, a communication system, a positioning system, a power system and a smart flight battery. This chapter sets down the functions of all parts of the drone

## >> 4.1 Positioning

ATOM adopts Potensic's new SurgeFly™ flight control technology, which supports the following two positioning modes:

GPS positioning: Provide precise positioning and navigation to the drone: support precise hovering, smart flight and auto return.

Vision positioning: It can realize high-precision positioning at a low altitude based on the Downward Vision System. The vision positioning can be realized without GPS signal, so that the product can be used indoors.

How to switch: The flight control system will switch automatically according to the environment of the drone. If both GPS and Downward Vision System fail, the flight control will be switched to attitude mode, under which, the drone fails to realize stable hovering and user needs to correct the flight gesture manually through the control

The difficulty of drone handling will be increased greatly in Attitude Mode: make sure to master the behaviors and operation of the drone in this mode prior to use; avoid flying the drone over a long distance to avoid risks due to failed judgment of drone behaviors.

- ♠ In Vision Positioning (OPTI Mode), the Intelligent Flight Modes are not available, and the flight mode will be limited to Video Mode.
  - . When the GPS signal is weak or there is no GPS signal, you will not be able to return the drone and activate certain functions such as Waypoint Flight or QuickShots.
- The difficulty of controlling the drone will increase dramatically in ATTI Mode so make sure to master the operation of the drone in this mode. Always keep the drone within sight in order to avoid risks in case of failed judgment of the drone's attitude and direction.

## 3 4.2 Downward Vision System

The ATOM is equipped with a downward vision system, it is located beneath the drone. The Downward Vision System consists of a monocular camera and a TOF module. The TOF module includes a transmitter tube and a receiver tub, it can precisely calculate the fly height above the ground by calculating the infrared signals transmission and receiving time. In combination with the monocular camera, the system can help achieve high-precision positioning at low altitudes



Monocular Camera

#### **Detection Fileds**

The Downward Vision System works best when the drone is at an altitude of 0.3 to 5 m, and its operating range is 0.3 to 10 m

When GPS is unavailable, the Downward Vision System will be activated if the drone is flying over discernible surfaces with sufficient light. The Downward Vision System works best when the drone is at an altitude of 0.3 to 5 m. When the altitude exceeds 5 m, the drone will enter ATTI Mode. Please fly with caution.

#### How to use

The Downward Vision System will be activated automatically if the positioning conditions are satisfied. The drone tail indicator blinks cyan twice, which indicates the Downward Vision System is working.

Speed limit: To ensure positioning accuracy and flight safety during vision positioning flight, the drone will actively limit its flight speed.

- ♠ In OPTI Mode, the maximum flight altitude is 5 m.
  - Vision positioning is only an auxiliary flight function, please always pay attention to the changes in the flight environment and positioning mode, and do not rely too much on the automatic judgment of the aircraft. Users need to control the remote controller at all times and be prepared to operate the drone manually at any time.
  - The Visual System cannot work properly when flying over the following surfaces:
    - 1 Pure-color surface
    - 2. Surface with strong reflection, such as smooth metal surface.
    - 3. Transparent object surface, such as water surface and glass.
    - 4. The moving texture, such as running pets and moving vehicles.
    - 5. Scenarios with drastic change of light: For example, the drone flies to outdoor space with strong light from indoor space.
    - 6. Places with weak or strong light.
  - 7. The surface with highly repetitive texture, such as floor tile with the same texture and small size, and highly consistent strip pattern.
  - For the sake of safety, please check the camera and TOF transceiver tube before the flight, and clean it with a soft cloth if there is any dirt, dust, or water on it: Contact Potensic Support if there is any damage to the Vision System.

## >> 4.3 Drone Status Indicator

Start-up/ Shut-down	Startup / Shutdown in progress: Green indicator is solid on					
Flight	GPS positioning	Vision positioning	Attitude mode	Return		
status	Indicator flashes slowly in green	Indicator flashes slowly in cyan	Indicator flashes slowly in blue	Indicator flashes slowly in red		
Warning &	Remote controller has no connection with the drone (disconnected)	Low battery	Sensor error	Emergency stop of propeller		
Error	Indicator is in solid blue	Indicator flashes quickly in red	Indicator is in solid red	The indicator repeatedly briefly lights up in red and then remains off for an extended period.		
Upgrade &	Compass calibration (horizontal)	Compass calibration (vertical)	Frequency pairing mode	Upgrade mode		
calibration	Indicator alternately flashes between red and green	Indicator alternately flashes between blue and green	Indicator flashes quickly in green	Indicator flashes quickly in blue		

## >> 4.4 Smart Battery

#### 4.4.1 Function

Atom's smart battery is equipped with high-energy cells and utilizes an advanced battery management system. Detailed information is as follows:

Basic Parameters						
	Model: DSBT02B					
Cell Qty.	Cell Qty. 2 series Battery Capacity 2230mAh					
Rated Voltage	Rated Voltage 7.7V Charge Completion Voltage 8.8V					
Charging Mode	Charging Mode TYPE-C/ Parallel Charging HUB  Max. Charge Current TYPE-C: 5V/3A Parallel Charging HUB: 8V/2.0A x 3					

Function	Description
Balance protection	During charging, the voltages of the battey cells are automatically balanced.
Auto-discharging protection	After being fully charged, the battery will start to auto-discharge to 50%-70% of the battery level when it's left idle for 5 days to protect the cells.
Overcharge protection	The battery stops charging automatically once fully charged.
Temperature protection	Charging will stop automatically if the temperature of the battery is below 0°C or above 40°C to prevent damage.
Auto-limit of charging current	The battery will restrict the charging current automatically if an excess current is detected to protect the cells.
Overdischarge protection	Discharging stops automatically to prevent excess discharge when the battery is not in flight use. The battery will enter Hibernation mode and it's recommended to charge the battery.
Short-circuit protection	The power supply will be automatically cut if a short-circuit is detected to protect the drone and the battery.
Battery health monitoring	The BMS will monitor the battery health, and prompt warnings if a damaged battery cell is detected so you can replace the battery in time.
Communication function	Information about charge cycles and remaining battery level is transmitted to the drone and you can view it in the App.

<sup>↑ •</sup> If the battery is not used for a long time, it needs to be charged every three months to ensure its health.

<sup>•</sup> Please store the battery in a cool and dry place where children cannot reach.

#### 4.4.2 Battery Installation & Removal

#### Installation:

Insert the battery in the battery compartment and secure the buckle. You will hear a clicking sound when the battery is fully engaged.

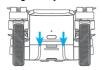


#### Removal:

Press the battery buckle and detach the battery from the battery compartment to remove it



## • After inserting the battery, please ensure that the battery buckle snaps back into place. This is crucial for flight safety.



Make sure to power off the product before removing the battery.



Buckle is in position, safe



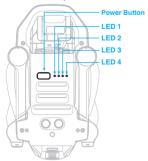
Buckle is not in position. which may result in the battery falling during flight.

#### 4.4.3 Charging

See 3.6 for charging method

#### 4.4.4 View Power Level

Once the battery is inserted in the drone, short press the power button to view the power level of smart battery. as shown in the picture below:



LED 1	LED 2	LED 3	LED 4	Current power level	
:Ö:	0	0	0	0%~25%	
٥	0	0	0	25%~30%	
⇔	Ø	0	0	30%~50%	
	≎	0	0	50%~55%	
⇔		♦	0	55%~75%	
Ö		۵	0	75%~80%	
Ö	≎	≎	۵	80%~97%	
٥		Ö	٥	97%~100%	
: Indicat	tor is on				

## 4.4.5 Operation Instructions of Smart Battery at High/Low Temperature

When the battery temperature is <5°C, the App will prompt a low temperature warning of the battery, and the battery needs to be preheated before flying.

When the battery temperature is >70°C, the App will prompt a high temperature warning of the battery, and the drone will not be able to fly.



- ↑ The discharge capacity will be weakened greatly and flight duration will reduce at a low temperature, which is normal.
  - · Avoid long-term running at a low temperature, otherwise, the battery life can be shortened.

## >> 4.5 Propellers

There are two types of ATOM propellers, which are designed to spin in different directions. Marks are used to indicate which propellers should be attached to which motors, the two blades attached to one motor are the same

	Propeller	Installation Instructions	Schematic Diagram of Installation
Marked propeller	<b>Q</b> 1	Install the marked propeller blades on marked arm	
Unmarked propeller		Install the unmarked propeller blades on unmarked arm	



- ்- Use the the screwdriver from the package to mount the propellers.
  - . When replacing the propeller blades, it is easier to handle by gripping the motor with your hand.





- ♠ Make sure you attach the marked propellers to the motors of the arm with marks and the unmarked propellers to the motors of the arm without marks. Otherwise the drone will be unable to fly.
  - If a propeller is broken, remove the two propellers and screws on the corresponding motor and discard. them. Use two propellers from the same package, DO NOT mix with propellers in other packages.
  - Propeller blades are sharp. Handle with care. DO NOT squeeze or bend the propellers during transportation or storage.
  - · Purchase the propellers separately if necessary.
  - Stay away from the rotating propellers and motors to avoid injuries.
  - . Please check the propeller blades immediately if there are any jitters or speed loss in flight, and timely replace the propellers if it's damaged or deformed.
  - Make sure the motors are mounted securely and rotating smoothly. Land the drone immediately if a motor is stuck and unable to rotate freely. Stop flying the drone and contact support if there is any abnormal sound with the motor.
  - Make sure that the propellers are installed securely before each flight. Check to make sure the screws on the propellers are tightened.



• When mount or remove the propellers, do not put the screwdriver or other foreign materials inside the motors, otherwise the motor may be damaged.



## >> 4.6 Flight Data

ATOM will record automatically the flight data and you can access it in the App.

Flight record displays the basic data for each flight.

Flight log records the detailed data of each flight. If you encounter any issue during the flight, you can report it in the App and upload the flight log if necessary to seek for assistance.



♠ • All flight data is stored on your mobile device, and the company will not obtain any of your flight data unless you voluntarily upload it to the cloud seeking for assistance.

#### > 4.7 Gimbal and Camera

#### 471 Three-Axis Gimbal

ATOM is equipped with a 3-axis gimbal, allowing you to capture clear and stable images and videos. The control nitch range is from +20° to -90° the control roll and vaw range is from +10° to -10°

The pitch angle of the gimbal can be adjusted by dialing the gimbal dial on the remote controller

In Video Mode, the control pitch range of the gimbal is +20° to -90°. Otherwise, the control pitch range is 0° to -90°





- Make sure to remove the gimbal protector before powering on the drone.
  - After each startup the default tilt angle of the gimbal is 0°(namely the horizontal view)



- Make sure that there are no objects on or around the gimbal and the lens is not dirty before taking off.
- The gimbal is connected to the drone through elastic and shock absorption support to eliminate camera vibration. Do not pull the gimbal by force. For any damage of shock absorption support, please contact the after-sales team for renairing



 DO NOT modify the gimbal or stick objects on it, otherwise this will cause the gimbal to shake or lead to permanent gimbal motor damage.

#### 472 Camera

Basic Parameters					
Sensor brand: SONY	Sensor size: 1/3" CMOS				
Effective pixel: 12MP	Aperture: F2.2				
FOV: 78°	Focus range: 3m ~ ∞				
ISO range: 100~6400	Shutter range: 1/24~1/25,000s				
Memory: Micro SD card	Picture format: JPG/JPG+RAW(DNG)				
Picture size: 12MP (4,608*2,592) Codec: H.264					
Video format: MP4					
Video Resolution: 4K@30/25/24fps; 2.7K@30/25/24fps; 1080P@60/50/30/25/24fps					



- ↑ The gimbal may shake when flying in Sport Mode or strong wind. It is recommended to fly the drone in Video Mode to acquire optimal gimbal stabilization.
  - Do not touch the lens after recording for a long period of time to avoid scald.
  - Do not record video when the drone is not flying: otherwise the drone will trigger overheat protection.
  - . The sensor will crop out the edges at 1080P@60/50fps, it's simply capturing a central section of what the full-frame sensor would capture, and FOV is about 36°.

#### 4.7.3 Image Storage

Videos and pictures recorded by ATOM will be stored on the SD card instead of the App or your phone gallery. Make sure to insert the SD card prior to flight. Otherwise, it's unable for ATOM to record videos or capture pictures. (SD card is not included in the pack list.)

User can preview and download the videos and pictures (the drone and the remote controller should be connected) in App.

#### SD Card Requirements

File format: FAT32, exFAT

Capacity: 4G-256G

Speed requirements: It is suggested to use SD card above U1 (UHS Speed Class 1) or C10 (Class 10)



்் • The video downloaded from App is just 720P image used in video transmission. Please read SD card with computer or other device in order to acquire videos of higher definition.



- ↑ The recording can be terminated due to slow write-in when using the U1/C10 SD cards of certain brands.
  - . If important data is stored on your SD card, please backup them properly.
  - . Do not insert or unplug the SD card when the product is powered on. It may lead to data damage or loss, or even SD card damage when inserting or unplugging SD card during video recording.
  - · Potensic does not bear responsibility for any loss due to user's misoperation of SD card.

## 5. Remote Controller

#### >> 5 1 Overview

Potensic ATOM is equipped with the DSRC02A remote controller, which boasts Potensic long-range PixSvnc™ 3.0 video transmission technology, offering a maximum transmission range of 6km/19.685ft and 720p when displaying video from the drone to PotensicPro App on your mobile device. Easily control the drone and camera using the onboard buttons. The detachable control sticks make the remote controller easier to store. Thanks to the 2.4Ghz dual band antenna, in a wide-open area with no electromagnetic interference. PixSvnc™ 3.0 smoothly transmits video feed at up to 720p at a max altitude of 120m.

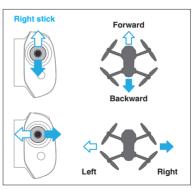
The built-in battery has a capacity of 3000mAh and a maximum run time of 2.3 hours. There is a Type-C port for device connection. The remote controller charges the mobile device with a charging ability of 500mA/5V

- ∴ When used with different drone hardware configurations, the remote controller will automatically select the corresponding firmware version for updating and support the following transmission technologies enabled by the hardware performance of the connected drone models:
  - a. ATOM SE: PixSvnc™ 2.0 b. ATOM: PixSvnc™ 3.0

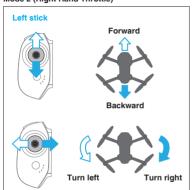
### >> 5.2 Control Stick Mode

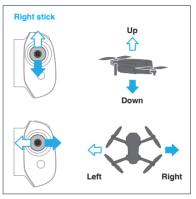
#### Mode 1 (Left Hand Throttle)





#### Mode 2 (Right Hand Throttle)





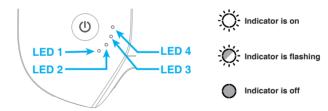
## ≫ 5.3 Function

## 5.3.1 Function List

Charge	Connect the USB Charger to the Type-C charging port.     The battery is being charged when the LED indicators start flashing.     Charging is completed when 4 LED indicators are solid on and data cable can be removed.
Charge mobile phone	When a mobile device is connected, the remote controller automatically charges the device with a charging ability of 500mA/5V.
Indicator function	See 5.3.2
Flight control	See 5.2
Low battery prompt	When power level of the remote controller is lower than 10%, the remote controller will emit a beep sound every other second.
Auto shutdown	The remote controller will shut down automatically if it has no connection or operation for 20 mins.
One-key return	See 7.8
Pause	If the drone is performing an Intelligent Flight like Circle Flight or auto landing, press once to make the drone brake and hover in place. Press again to resume the drone flight.
Emergency stop	For any emergency situations during the flight, press "Shoot" and "Record" button for 2s at the same time till the remote controller beeps, the drone will stop running and fall down.
Shoot	Short press it to shoot one photo When the camera is in video mode, short press it to switch to photo mode
Record video	Short press it to start/stop video recording When the camera is in photo mode, shot press it to switch to video mode
Gimbal Dial	Dial it to the right to increase the pitch angle (head up) Dial it to the left to decrease the pitch angle (head down)
Remote controller frequency pairing	See 5.3.3

#### 5.3.2 Indicator

As shown in the picture below, the remote controller is fitted with 4 white LED indicators to indicate the power level and other status



## Charging indication

LED 1	LED 2	LED 3	LED 4	Current power level of battery
Ö	0	0	0	0%~25%
Ö	Ö	0	0	25%~50%
Ö	Ö	Ø	0	50%~75%
Ö	Ö	Ö	Ö	75%~99%
Ö	Ö	Ö	Ö	99%~100%

## Power indication (in use)

LED 1	LED 2	LED 3	LED 4	Current power level of battery
Ö	0	0	0	0%~10%
Ö	0	0	0	10%~25%
Ö	Ö	0	0	25%~50%
Ö	Ö	Ö	0	50%~75%
Ö	Ö	Ö	Ö	75%~100%

#### Status indication

	LED 1	LED 2	LED 3	LED 4		
Frequency pairing	<b>\tilde{\</b>		Ö	Ö		
rrequericy pairing	Flashing slowly at the s		at the same time			
	Ö000 ÖÖ00 ÖÖÖ0					
Upgrade mode		Turning on	sequentially			
Otant and hunding						
Start calibration	Flashing slowly at the same time					

#### 5.3.3 Remote Controller Function

ATOM drone and the remote controller can be used immediately after startup since they have been paired before delivery. Frequency pairing is only required when using a new drone or remote controller for the first time.

Proceed frequency pairing between the drone and the remote controller by tapping "Drone Re-pairing" under Calibration in Ann Settings. See 8.5 Remote Controller Calibration for the detailed procedures.

## >> 5.4 Antenna Angle

Adjust the antenna angle along with the changes of drone altitude and distance, to ensure the best communica-

Wider communication angle is ensured at a close distance in this mode.



Keep both antennas pointing directly towards the drone to acquire a longer transmission distance.



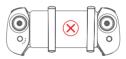
When the drone is directly above the remote controller, the transmission signal is significantly weakened due to the poor antenna angle. To address this, please lower the flight altitude or fly the drone horizontally for some distance, ensuring that the antenna points towards the drone as much as possible, as shown in the picture.



Do not cross the antenna in any case.

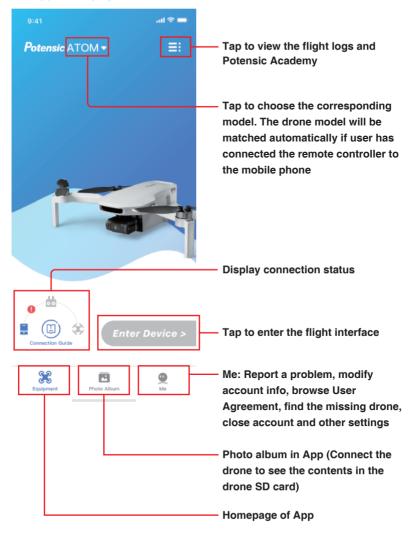


Do not press the antenna on your mobile device in any case.

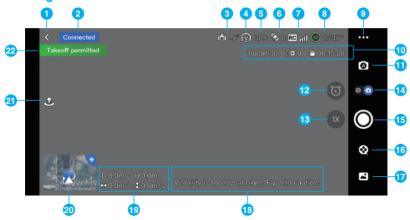


## 6. PotensicPro App

## >> 6.1 App Homepage



#### >> 6.2 Flight Interface



1. Return button:

Tap to return to the homepage

#### 2. Navigation prompt bar:

Display drone status and flight mode

3. Gimbal angle: 🚮

Display current gimbal pitch angle

#### 4. Flight mode:

- Wideo
- M Normal
- Sport

5. Positioning mode:

GPS GPS positioning

OPTI Vision positioning

Atti Attitude mode, no positioning

#### 6. GPS status:

Display GPS signal status and quantity of satellites connected

7. Signal quality of video transmission: RC 11

Display the strength of video transmission connection signal between the drone and the remote controller

8. Power level of the smart battery: 16'47" Estimated Remaining Flight Time

#### 9. Settings

## Tap to view information about Safety, Calibration, Control, Camera and About.

#### Safety

Switch on/off Beginner Mode: If switched on, the drone will be confined to fly in a cylindrical space with a radius of 30 m and a height of 30 m and restricted to fly only in Video Mode.

Set measurement system (Metric or Imperial) and speed (Video/Normal/Sport)

Set drone behavior when signal lost: Return/Land/Hover

Return — the drone will automatically ascend to 120 m and return to the HOME point.

Land — the drone will land on the spot where it loses the signal.

Hover —— the drone will hover in place where it loses the signal.

Enable the Silent Return Mode: after enabling, the remote controller will no longer beep when the drone enters RTH mode in the future (To stop the current beeping, simply short press the power button on the remote controller).

Enable/disable Flight Safety Tips

Battery information: check the temperature, current, voltage and others of the smart battery.

This sector includes compass calibration, gimbal calibration, gimbal fine-tunning, remote controller calibration and drone re-pairing.

#### Control

Remote Controller Settings: Tap to switch control stick mode (Mode 1: Left Hand Throttle; Mode 2: Right Hand Throttle)

Gimbal Settings: Tap to set gimbal maximum pitch speed, gimbal angle (0°/-90°), and to switch between Gimbal Stable Mode or FPV Mode.

#### Camera

General Settings: Tap to set white balance, gridlines, segmental recording, etc. Tap to check microSD card capacity and format.

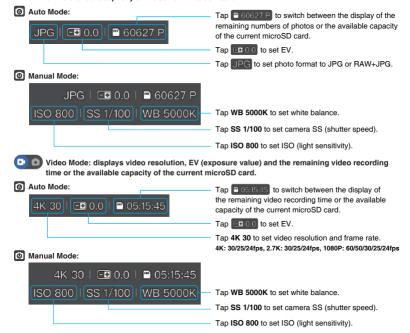
Other Settings: Enable/disable Telemetry Data, and add GPS coordinates in photos.

#### About

View device information, firmware information, Applyersion, etc.

#### 10. Shooting Information Display/Settings

Photo Mode: displays photo format, EV (exposure value) and the remaining numbers of photos or the available capacity of the current microSD card.



#### 11. Camera Manual/Auto Mode

- Auto Mode
- Manual Mode: Tap to manually adjust ISO, shutter time, white balance, and set the parameters by observing the exposure value(EV)

#### 12. Interval Timer Shooting Mode:

In Interval Timer Shooting Mode, the camera will take photos at a selected time interval continuously. Conditions to activate the Interval Timer Shooting Mode: camera set to Photo Mode and the image format to JPG.

Long press the icon to start the timer dial. Choose the time interval then tap 🔘 or click the photo button on the remote controller to start taking photos. Tap 💿 to cease shooting, and tap again 📵 to exit Interval Timer Shooting Mode.

#### 

The icon displays the current zooming setting. Tan to quickly switch between 1x, 2x or 3x to zoom in or out. For a more precise zoom, touch and hold the zoom icon then drag the dial up and down. You can also pinch in or out on the screen with two fingers to zoom in and out.

The camera supports 2x digital zoom in Photo Mode and up to 3x in Video Mode (2x digital zoom in 4K, 3x in 1080P and 2 7K, but no digital zoom in 1080P at 50/60fps)

#### 14 Shoot/Record switch button:

to switch from shooting to video recording

to switch from video recording to shooting.

#### 15 Shoot/Record button:

- Video recording mode, tap to start video recording Video recording in progress, tap to cancel
- Shooting mode, tap to shoot picture

#### 16. Intelligent Flight Modes:

- QuickShots shooting modes: Pull-Away, Rocket, Circle, Spiral and Boomerang. The drone records the target according to the selected shooting mode and automatically generates a short video which will be saved in MicroSD card.
- S Visual Tracking: The drone tracks automatically the targeted subject to record and generates a short video which will be saved in MicroSD card.

Please watch the tutorial videos for detailed instructions!

#### 17. Album: Preview or download shot videos or pictures in SD card.

#### 18. Flight Safety Tips:

Users can turn on/off Flight Safety Tips in App Settings -> Safety, After turning it on, flight-related tips or suggestions will be displayed on the lower right side of the flight interface.

#### 19. Display flight speed and distance:

- In Horizontal distance from the drone to HOME point
- Relative height from the drone to HOME point

Flight speed of the drone

Ascent/descent speed of the drone

#### 20. Attitude Indicator/Thumbnail map:

Tap the upper right corner to switch to Attitude Indicator Mode Tap thumbnail map to switch to full-screen map



The attitude indicator displays information of drone direction, tilt angle, remote controller direction, HOME point

The attitude indicator can show the angle and direction of the drone in real time as follows:

Legend	( B)	No Contract of the Contract of	b B	b a
Tilting direction of the drone	Tilt forward: the horizon line tilts towards the upper half of the attitude indicator	Tilt backward: the horizon line tilts towards the lower half of the attitude indicator	Tilt to the right: the horizon line tilts towards the right side	Tilt to the left: the horizon line tilts towards the left side

#### Different colors of the attitude indicator:

Legend	Description
b A B	Green indicates that the drone is flying at a relatively small tilt angle, high precision control over the gimbal and optimal video quality can be achieved.
b n	Yellow indicates that the drone is flying at a relatively large tilt angle, the control precision of the gimbal may be affected, and the video quality may be reduced.
O No.	Red indicates that the drone is flying at a very large tilt angle. If the attitude indicator frequently turns red during flight, the drone may be encountering strong winds and the video quality can be compromised. Please fly the drone back and land it as soon as possible.



- . When the icons of the drone and the remote controller both turn green, it indicates that the remote controller is facing the drone which guarantees the optimal communication signal.
- . After the drone is powered on and enters GPS mode, the current GPS coordinates will be updated as the HOME point. Pay attention to the update prompt of the HOME point.



↑ • When the drone takes off in OPTI mode and then enters GPS mode, the HOME point might not be the take-off point. Pay attention to the return safety.

#### 21. One-key takeoff, landing/return

The App will display different buttons based on drone status. Tap to initiate one-key takeoff, landing or return.

- Tap to unlock, take off and hover at a height of 1.2m
- Tap to land or auto return.

#### 22. Display important information or status of drone

- ♠ Make sure to fully charge the mobile device prior to flight, because the power of the mobile device will be consumed even if it is charged by the remote controller.
  - . Mobile cellular data is required when using the PotensicPro App. Please contact your wireless carrier for data charges.
  - . While using the App, make sure to read and master the pop-up prompts and warning information of App to know the current status of the drone.
  - It is recommended to replace any outdated mobile device which may have a negative impact on user experience of App and lead to potential dangers. For any poor user experience and safety problems due to the use of an outdated mobile device, Potensic does not bear any liability.

## 7. Flight

This chapter introduces safe flight practices and requirements.

## >> 7.1 Requirements of Flight Environment

- 1. Do not use the product in severe weather, such as gale, rain, show and for
- 2. Only fly in open areas. Tall structures and large metal structures may affect the accuracy of the onboard compass and GPS system and result in positioning failure. It is recommended to keep the drone at least 5m away from structures
- 3. Control the product within your sight and keep away from the obstacles and crowds
- 4. Do not use the product in places with high-voltage power lines, telecommunication base station or launching tower to avoid interference of the remote controller
- 5. Please use the product with caution when altitude is over 3,000m for the flight performance can be affected when the performance of drone battery and power system is weakened due to environment factor.

## >> 7.2 Precautions of Flight

- 1. Check if the remote controller, intelligent flight battery and mobile device are fully charged.
- 2. Check if the drone is intact and propellers are installed correctly.
- 3. Check if the camera is working normally after power-on.
- 4. Check if App is running normally.
- 5. Check if SD card is inserted and make sure camera is clean.
- 6. Make sure the drone takes off on flat and hard surface, instead of sandstone or bush; the drone may fail to be unlocked if it has major vibration.
- 7. Please be careful when the done takes off on surface of moving objects, such as running vehicle and ship.
- 8. GPS positioning and waypoint flight will be disabled in the south and north polar.
- 9. Do not use the product in extremely cold or hot place to avoid hazards.

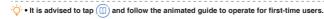
#### >> 7.3 Connection

Please follow the steps below:

- 1. Please finish the steps in "3.5 Preparing the Remote Controller" and turn on the remote controller.
- 2. Please finish the steps in "3.4 Preparing the drone" and turn on the drone.
- 3. Launch App to view the connection status. Connection is finished when it shows (A).



4. Tap finter Device > to enter the flight interface.



## >> 7.4 Flight Mode

ATOM has three flight modes-Video/Normal/Sport, which can be switched via the App.

#### Video Mode

Ascent speed: 2m/s, descent speed: 2m/s, flight speed: 6m/s

The drone enters Beginner Mode by default when being used for the first time. The flight speed will be limited to the same as in Video Mode to allow you to familiarize yourself with the controls of the drone.

#### Normal Mode

Ascent speed: 4m/s, descent speed: 3m/s, flight speed: 10m/s

You can exit Beginner Mode after you have mastered adequate flight skills, and the drone will switch to Normal Mode by default.

#### Sport Mode

Ascent speed: 5m/s, descent speed: 4m/s, flight speed: 16m/s

Video mode is recommended for aerial photography. Sport mode is recommended if you would like to get a speedy flight experience.

Please fly with caution in Sport Mode as the responsiveness of the drone significantly increases, which means a small control stick movement on the remote controller translates into the drone moving a large distance.

- ↑ To ensure flight safety, the Sport Mode is only available when the battery level is greater than 30% and the flight altitude greater than 8m. During the flight in Sport Mode, if the battery level drops below 30% or the flight altitude is lower than 4m, the drone will exit Sport Mode automatically
  - Be vigilant and maintain adequate maneuvering space during flight, as the responsiveness of the drone significantly increases in Sport mode.
  - The maximum speed and braking distance of the drone significantly increase in Sport Mode. A minimum braking distance of 30 m (100 ft) is required in windless conditions to ensure safety.
  - When flying in Sport Mode or strong wind, the gimbal may shake, which is normal.

## >> 7.5 Beginner Mode

The drone is automatically set to Beginner Mode for first-time use. In Beginner Mode:

- 1. The flight distance and height will be restricted at 0~30m.
- 2. The speed level will be restricted to the same as in Video mode
- 3. Users operating the drone for the first time are suggested to learn and master the drone in Beginner Mode

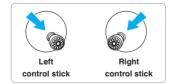
## >> 7.6 Takeoff/Landing/Hovering

#### 7.6.1 Manual Takeoff/Landing

#### Takeoff

#### Step 1: Start the motors

Use a combination stick command to start the motors. Push both sticks to the bottom inner or outer corner depending on your control stick mode to start the motors. Release both sticks simultaneously once the motors are spinning.





control stick control stick

#### Step 2: Push throttle control stick to take off

Push the throttle control stick upwards gently as shown in the picture, release the control stick when the drone leaves ground and it will keep hovering.



#### Landing

Pull the throttle control stick until the drone lands on ground. Release the throttle control stick when the motors are no longer spinning.

Take off from stable and level plane, do not take off from or land on the palm or by hand.



. When the drone in the non-static state, Push both sticks to the bottom inner or outer corners for 2s to force unlocking it. Please stay away from the drone for more than 5m before operation for your own

## 7.6.2 One-key Takeoff / Landing

#### One-key takeoff

Tap one-key takeoff button in App, then swipe right in the pop-up window to start the drone automatically then ascend to the height of 1.2m and maintain hovering.



#### One-key landing

Tap one-key landing button (2) in App, then swipe left in the pop-up window to land the drone, or swipe right to start returning.



## >> 7.7 Intelligent Flight Modes

#### 7.7.1 QuickShots

Introduction	QuickShots shooting modes include Pull-Away, Rocket, Circle, Spiral and Boomerang. The drone records the target according to the selected shooting mode and automatically generates a short video which will be saved in MicroSD card.				
How to Start	1. Tap  in the App to start QuickShots. 2. Choose a shooting mode and set the parameters on the right. 3. Tap  or drag-select your target subject(It is recommended to choose a human as a target subject rather than a building), then tap  to begin recording.				
How to Exit	Tap (3) in the App or move a control stick to finish recording. The drone will hover in place.     Tap (6) on the right to exit QuickShots.				
	Mode	Description	Adjustable Parameter		
	Pull-Away	The drone flies backward and ascends with the camera locked on the subject.	Return to the starting point after finishing recording?	Distance	
	Rocket	The drone ascends vertically with the camera pointing downward at the subject.	Yes No	Relative altitude	
Explanation	Circle	The drone circles around the subject starting from current position.	Flight direction(clockwise/ counterclockwise) Number		
	Spiral	The drone ascends and spirals around the subject.			
	Boomerang	The drone flies around the subject in an oval path, ascending as it flies away from its starting point to the farthest distance and descending as it flies backward.	Clockwise Counterclockwise	laps(choose from 1-3)	

## -்்੍- • Conditions to activate QuickShots:

- 1. The drone is airborne with strong GPS signal;
- 2. MicroSD card is inserted with available storage;
- 3. Sufficient battery level;
- 4. The drone is not in auto-flight state (auto return or landing).
- 5. The drone must be at least 2 m above the ground.
- 6. When locking the target in QuickShots, the gimbal pitch angle needs to be between -75° ~ -15°.

- ♠ Use QuickShots at locations that are clear of buildings and other obstacles. Make sure there are no humans, animals, or other obstacles on the flight path.
  - Refore getting familiar with the flight nath of QuickShots, please try a smaller flight distance first.
  - Be ready to take over control of the drone by moving any control stick at any time in emergency and the drone will exit QuickShots and hover in place.
  - Pay attention to objects around the drone and use the remote controller to avoid collision with the drone or when the drone is being blocked
  - DO NOT use QuickShots in places that are close to buildings or where the GPS signal is weak. Otherwise, the flight path will be unstable.
  - Make sure to follow local privacy laws and regulations when using QuickShots.
  - QuickShots is not available in the following situations:
    - 1. The drone is on the ground.
    - 2. GPS signal is weak.
  - 3. MicroSD card is not inserted or no storage available.
  - 4. The battery level is low.
  - 5. The current altitude of the drone is insufficient.
  - 6. The drone reaches the virtual fence
  - 7. The gimbal is horizontal or tilted upwards.
  - DO NOT use QuickShots in any of the following situations where the Downward Vision System may not work properly:
    - 1. When the subject is blocked or outside the line of sight for an extended period.
  - 2. When the subject is more than 50 m away from the drone.
  - 3. When the subject is similar in color or pattern with the surroundings.
  - 4. When the subject is in the air.
  - 5. When the subject is moving fast.
  - 6. When the ambient lighting is extremely low or high.
  - QuickShots does not support video recording in 1080P@60/50fps.
  - After the subject is locked in QuickShots, the gimbal pitch angle can't be adjusted.

#### 7.7.2 Visual Tracking

Description	The drone tracks automatically the tracked subject to record and generates a short video which will be saved in MicroSD card.
How to Start	<ol> <li>Tap (a) in App the tap (a) on the right to start Visual Tracking.</li> <li>Tap (b) or drag-select your subject, and choose the recording period(1, 3, 5min or infinite∞).</li> <li>Tap (c) to start Visual Tracking.</li> </ol>
How to Exit	Tap  on the right or move a control stick during recording to stop and exit Visual Tracking and the drone will hover in place.      Tap  on the right to exit Visual Tracking.



- Visual Tracking is unavailable when the drone is on the ground.
  - . During Visual Tracking, the gimbal dial will remain unresponsive.
  - . Once the tracked subject is lost, the drone will hover in place.
  - When the tracked subject is approaching the drone, it will hover in place and not move backwards.
  - When locking the target in Visual Tracking, the gimbal pitch angle needs to be between -75° ~ -25°.
  - The drone must be at least 4 m above the ground to activate Visual Tracking.
  - The maximum speed supported by Visual Tracking is 8 m/s.
  - When using Visual Tracking, it is recommended to accelerate or decelerate as gently as possible when the target being followed moves, and the average speed should not exceed 4 m/s to ensure the stability of tracking.

- ↑ Use Visual Tracking at locations that are clear of buildings and other obstacles. Make sure there are no humans, animals, or other obstacles on the flight path.
  - DO NOT use Visual Tracking in places that are close to buildings or where the GPS signal is weak. Otherwise, the flight path will be unstable.
  - Be ready to take over control of the drone by moving a control stick at any time in emergency and the drone will exit Visual Tracking and hover in place.
  - Visual Tracking is not available when the drone is flying near distance and altitude limits.
  - Make sure to follow local privacy laws and regulations when using Visual Tracking.
  - Be extra vigilant when using Visual Tracking in any of the following situations:
    - 1. The tracked subject is not moving on a level plane.
    - 2. The tracked subject changes shape drastically while moving.
    - 3. The tracked subject is blocked or out of sight for an extended period.
    - 4. The tracked subject is moving at a fast speed.
    - 5. The tracked subject has a similar color or pattern to its surrounding environment.
  - 6. When the ambient lighting is extremely low or high.
  - It's recommended to maintain a distance of 5-10 m and an altitude of 4-10 m when tracking people. It's recommended to maintain a distance of 20-50 m and an altitude of 10-50 m when tracking vehicles or boats. Operate the drone outside of the recommended range and it may not detect well the intended subject.

## 7.7.3 Waypoint Flight

# When Waypoint Flight is enabled, you can pin 2 or more waypoint coordinates in App map. Description and the drone will fly over the corresponding waypoints sequentially When the GPS signal is strong, tap the map in the lower left corner of the App to switch to map, then tap 🔊 on the right to enter Waypoint Flight mode, tap on the map to pin multiple waypoints, after that tap a to start Waypoint Flight. Ann G Q Wars & com How to Start You can preset 2 to 30 waypoints on the map and the figure in the icon indicates the flight sequence. Meanwhile, you can delete certain waypoint, save the current Waypoint Flight task, or choose from the saved Waypoint Flight tasks. 1. Tap (2) on the right or move a control stick (except throttle control stick) to stop and exit the current Waypoint Flight task and the drone will hover in place. How to Exit 2. Tap on the right to exit Waypoint Flight.

- During Waypoint Flight, you can adjust the flight altitude via the throttle control stick and the gimbal tilt via gimbal dial.
- During Waypoint Flight, the drone will exit the current flight task and hover in place if it reaches the virtual fence.

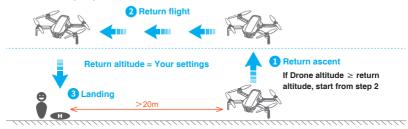
## >> 7.8 Return(RTH)

#### 7.8.1 Regular Return

The regular return consists of three steps, as follows:

- Ascent: The drone ascends to the preset return altitude (this step is skipped if the drone's altitude is already higher than the return altitude).
- 2. Level flight: The drone maintains a straight flight at the set altitude towards the HOME point.
- 3. Landing: Once it reaches the HOME point, the drone will automatically land and stop its motors.

Return to Home (RTH) The drone must be in GPS mode



#### How to Start RTH

One key RTH: Press and hold the RTH button on the remote controller for 1s or tap 🛃 in the App to pop up the menu, then swipe right to start the return.

**Auto RTH:** When either the drone battery level is low, the signal between the drone and the remote controller is lost or the drone is experiencing other abnormalities, Auto RTH will be triggered.

• If there are obstacles in the surrounding environment and it's not suitable to return, it is recommended to keep the drone hovering or land the drone after losing signal in Settings to avoid colliding with the obstacles during RTH.

#### How to exit RTH

Method 1: Tap ( on the left of App to exit RTH.

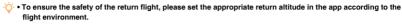
Method 2: Briefly press the return button on the remote controller to exit RTH.

#### **RTH Requirements**

The drone must take off in GPS mode and successfully record the HOME point.

If the drone takes off in OPTI mode and switches to GPS mode mid-flight, it will not be able to return to the takeoff point.

Please pay attention to the location of the HOME point on the map and the prompts in PotensicPro App.



- . During the return course, users can still adjust the flight altitude by toggling the throttle control stick.
- When the drone is within 20 m of the HOME point and RTH is initiated, a pop-up window will appear in the App for the user to select between landing and return. If return is selected, the minimum return altitude is 5 m. The drone will land automatically if no action is taken after a countdown of 10 seconds. Please pay attention to flight safety.
- Tall buildings or obstacles can block the transmission signal and cause signal loss. Do not fly behind buildings beyond the return altitude, otherwise the drone will collide with obstacles and crash during the return. If the drone enters ATTI mode due to GPS failure or GPS signal interference, it will not be able to return. During the return process, strong headwinds may be encountered. Lowering the flight altitude Appropriately can help reduce power consumption. If the power is insufficient, the drone will perform a forced landing in place. Please pay attention to the prompts in PotensicPro App. Do not initiate the return when there are obstacles overhead, such as tall trees, otherwise the drone may crash during the climb.

- Please pay attention to return safety, because the drone does not support obstacle avoidance and may crash when colliding with obstacles during the return course.
  - For any GPS signal anomaly in communication loss return, the drone will maintain hovering at ATTI mode, until GPS signal is strong enough and the return will resume.

## 7.8.2 Descending Return

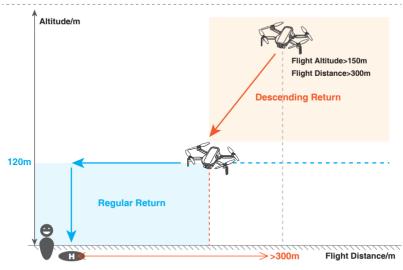
#### How to Activate

After 10 seconds into the RTH course, if the flight altitude is greater than 150m and the flight distance greater than 300m, the App will prompt a message for you to confirm whether to initiate the descending return. Once confirmed, the drone will start the descending return (the drone will descend its altitude while appropriate HOME point). When its altitude descends to 120m, the drone will switch to the regular return maintaining its current altitude till it reaches the HOME point and lands automatically.

#### How to Exit

Tap a on the left of the App interface or keep pushing the throttle control stick up for 2 seconds to exit the descending return. The drone will switch to the regular return maintaining the current altitude.

- 🔆 1. When encountering strong winds, the descending return can save power consumption and guarantee a more successful return.
  - 2. If the drone is disconnected from the remote controller during the descending return, it will switch to the regular return.
- ↑ This product does not have an obstacle avoidance function. Please pay attention to flight safety during the return process.
  - This feature is only available for countries or regions where drones are legally allowed to fly over 120 m.



## >> 7.9 Emergency Stop

See 5.3.1 Emergency stop for the detailed operation method.

♠ • Emerency stop function is designed for preventing injuring pedestrians or damaging the valuables by propeller blades in case of drone failure. Please use it with caution, because stopping the motors mid-flight will cause the drone to crash.

## 8. Calibration

This chapter mainly introduces the calibration-related functions in Settings, including compass calibration, gimbal calibration, gimbal fine-tuning, remote controller calibration, and drone re-pairing.

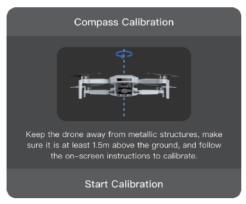
## >> 8.1 Compass Calibration

## 8.1.1 When to perform compass calibration

- 1. Compass calibration is required for first-time use.
- 2. Flying the drone at a location more than 50 km (31 miles) away from its last flight.
- Do not calibrate the compass in locations where magnetic interference may occur, such as close to
  magnetic deposits or large metallic structures such as parking structures, steel reinforced basements,
  bridges, cars, or scaffolding.
  - DO not carry objects that contain ferromagnetic materials such as mobile phones near the aircraft during calibration
  - Make sure the drone is at least 1.5m (4.92ft) above the ground when calibrating.
  - It's not necessary to calibrate the compass when flying indoors.

#### 8.1.2 Calibration Procedure

- When calibration is required, the App will pop up the calibration interface automatically, tap "Start Calibration", and the drone status indicator will alternatively flash red and green.
- Hold the drone horizontally and rotate it 360° till the App shows vertical calibration, and the drone status indicator will alternatively flash blue and green.
- 3. Hold the drone vertically and rotate it 360° around a vertical axis till the App prompts the calibration completed.
  You can also trigger compass calibration manually in the App: Settings-Calibration-Compass Calibration.







- When you get the prompt "Calibration failed" in the App repeatedly, change the location and try the calibration procedure again.
- Do not calibrate compass while arms are folded.

#### >> 8.2 Gimbal Calibration

#### 8.2.1 When to perform gimbal calibration

- 1. When the gimbal is not working or obviously unlevel after powering on and before take-off, please calibrate the gimbal
- 2. When the gimbal is unstable or unable to stay level in flight, please land the drone and calibrate the gimbal.

#### 8.2.2 Calibration Procedure

- 1. Tap Settings in the App, select "Gimbal Calibration", then place the drone on a level table with the bottom facing up
- 2. Tap "Start Calibration", then calibrate, the live transmission view will appear on the calibration interface.
- When the progress bar is fully loaded and the App prompts "Calibration Succeeded", the calibration is completed.



↑ • Do not move the drone significantly during the calibration process, otherwise the calibration may fail.

## >> 8.3 Gimbal Fine-tuning

The gimbal fine-tuning is for manually calibrating the gimbal, and adjusting the roll and yaw offset angle of the gimbal. You can tune the angle with reference to the status of the live transmission view on the App interface.

#### 8.3.1 When to perform gimbal fine-tuning

When the gimbal is unable to stay level or slightly tilting on level ground.

## 8.3.2 How to use the Gimbal Fine-Tuning

- Tap Settings in the App, select "Gimbal Fine-Tuning", then tune the roll and yaw angles of the gimbal with a range of ±10°, you can tap "+/-" to adjust the gimbal angles or set the angle value directly, tap once means "+0.1°/-0.1°".
- 2. Gimbal Roll Adjustment: Tap "+" to roll to the right, and tap "-" to roll to the left. Gimbal Yaw Adjustment: Tap "+" to yaw to the right, and tap "-" to yaw to the left.
- 3. Tap "Default Value" to restore the default angles (  $0^{\circ}$  )



#### >> 8.4 Remote Controller Calibration

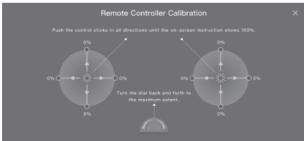
#### 8.4.1 When to perform remote controller calibration

- 1. When the drone drifts automatically in one direction without any toggling of the control sticks.
- 2. When the drone auto-rotating sideway continuously.
- 3. When the control sticks are over-sensitive or lack sensitivity.

#### 8.4.2 Calibration Procedure

- Turn on the remote controller, and connect the mobile device, tap Settings in the App, select "Remote Controller Calibration".
- 2. Make sure the control sticks are in the middle position and do not operate it before tapping to start the calibration
- 3. Tap "Start Calibration", then follow the on-screen instructions and toggle the sticks in all directions until the App displays 100%, and rotate the dial back and forth to its maximum extent.
- 4. When App prompts "Calibration Succeeded", the remote controller calibration is completed.





## >> 8.5 Drone Re-paring

### 8.5.1 When to perform drone re-paring

Drone re-pairing is required if you replace the drone or remote controller.

#### 8.5.2 Drone Re-paring Procedure

- 1. Turn on the remote controller, and connect the mobile device, tap Settings in the App, select "Calibration", tap "Re-paring the drone" to re-pair.
- Power on the drone and long press the power button till the drone status indicators flash green, the drone is ready to pairing.
- Wait for about 7s, the paring succeeds when the controller beeps "Di", then you can view the live transmission on the App interface.

- ♠ Make sure the distance between the remote controller and the drone is within 1m (3.3ft) and away from other 2.4G frequency interference during the frequency pairing process.
  - If the nairing has failed inlease check if there is any interference from the current location, if any other drones are under pairing, or if the distance is too far between the remote controller and the drone or any blocks between them. If none of the above, please try the pairing procedures again.
  - Do not move or operate the drone and controller during the frequency pairing process.



## 9. Appendix

## >> 9.1 Specification & Parameters

#### Drone

Model: DSDR04C

Takeoff Weight: < 249g (the takeoff weight includes battery and propeller blades)

Folded Size: 88x143x58mm

Unfolded Size (propeller blades included): 300x242x58mm Unfolded Size (propeller blades excluded): 210x152x58mm

Diagonal Distance: 219mm

Max Speed (Sport Mode): Ascent speed: 5m/s: Descent speed: 4m/s: Flight speed: 16m/s

Max Wind Speed Resistance: 38km/h (Level 5)

Maximum Flight Altitude: 120m/393.7ft GNSS: GPS+GLONASS+Galileo+BeiDou Operating Temperature: 0°C~40°C Operating Frequency: 2,400~2,4835GHz Transmission Power: 2.4GHz: < 20dBm

Hovering Accuracy Range: Vertical: ±0.1m (with Vision Positioning), ±0.5m (with GPS Positioning)

Horizontal Flight: ±0.3m (with Vision Positioning), ±1.5m (with GPS Positioning)

Extra Pavload: Not supported

Max Flight Time: 32min (measured at breezeless condition and even speed of 5m/s)

Max Hover Time: 29min (measured in indoor hovering)

## **Downward Vision System**

Hovering range: 0.3~5m(ideal environment); Available at 0.3~10m.

Unavailable scenarios of vision positioning:

- 1 Pure-color surface
- 2. Surface with strong reflection, such as smooth metal surface
- 3. Transparent object surface, such as water surface and glass
- 4. Moving texture, such as running pets

- Scenarios with drastic change of light; for example, the drone flies to outdoor space with strong light from indoor space
- 6. The places with weak or strong light
- 7. The surface with repeating identical patterns or textures, such as floor tile with the same texture and size
- 8. The surface with highly consistent strip pattern

#### Camera

Lens Tilt Bange: +20°~-90°

CMOS: 1/3"

Effective Pixel: 12MP ISO Range: 100~6400

Electronic Shutter Speed: 1/24s~1/25000s

FOV: 78°
Aperture: F2 2

Photo Resolution: 4608\*2592

Image Format: JPG/JPG+RAW(DNG)

Video Resolution: 4K@30/25/24fps; 2.7K@30/25/24fps; 1080P@60/50/30/25/24fps

Video Format: MP4 (H.264)

Max Video Bitrate: 50Mbps

Supported File System: FAT 32, exFAT

Type Of Supported Storage Card: MicroSD card; 4~256GB SD card transmission speed ≥ class10 or U1

standard

#### Remote Controller

Model: DSRC02A

Operation Frequency: 2.402~2.483GHz

Max Transmission Distance (unobstructed, free of interference): 6km

Operating Temperature: 0°C~40°C Battery: 3000mAh, lithium battery, 1S

Transmitter Power (EIRP): 2.4GHz: ≤20dBm

Charging Interface: TYPE-C Charging Specification: 5V/1A

Video Transmission System: PixSync™ 3.0

Video Transmission Quality: 720P

Latency (depending on environment and mobile device): 200ms

Supported Mobile Device Size: Length: 170mm, Width: 100mm, Thickness: 6.5mm~8.5mm

## Smart Flight Battery

Model: DSBT02B Capacity: 2230mAh Voltage: 7.7V

Battery Type: Li-Po 2S Energy: 17.18Wh Battery Weight: 84g

Working Temperature: 0°C~40°C

## >> 9.2 Post-Flight Checklist

- Make sure to perform a visual inspection so that the drone, remote controller, gimbal camera, flight batteries, and propellers are in good condition. Contact Potensic support if any damage is noticed.
- Make sure that the camera lens and vision system sensors are clean.
- Make sure to store the drone correctly before transporting it.

#### >> 9.3 Maintenance Instructions

To avoid serious injury to children and animals, observe the following rule:

- 1. Small parts, such as cables and straps, are dangerous if swallowed. Keep all parts out of reach of children and animals
- 2. Store the Smart Flight Battery and remote controller in a cool, dry place away from direct sunlight to ensure the built-in LiPo battery does NOT overheat. Recommended storage temperature: between 22°C and 28°C (71°F and 82°F) for storage periods of more than three months. Never store in environments outside the temperature range of -10°C to 45°C (14°F to 113°F)
- 3. DO NOT allow the camera to come into contact with or become immersed in water or other liquids. If it gets wet, wipe dry with a soft, absorbent cloth. Turning on a drone that has fallen in water may cause permanent component damage. DO NOT use substances containing alcohol, benzene, thinners, or other flammable substances to clean or maintain the camera. DO NOT store the camera in humid or dusty areas.
- Check every drone part after any crash or serious impact. If there are any problems or questions, contact Potensic support.
- Regularly check the Battery Level Indicators to see the current battery level and overall battery life. The battery is rated for 250 cycles. It is not recommended to continue use afterward.
- 6. Make sure to transport the drone with the arms folded when powered off.
- 7. Make sure to transport the remote controller with antennas folded when powered off.
- The battery will enter sleep mode after long-term storage. Charge the battery to exit from sleep mode.
- 9. Store the drone, remote controller, battery, and charger in a dry environment.
- 10. Remove the battery before servicing the drone (e.g., cleaning or attaching and detaching the propellers). Make sure that the drone and the propellers are clean by removing any dirt or dust with a soft cloth. Do not clean the drone with a wet cloth or use a cleanser that contains alcohol. Liquids can penetrate the drone housing, which can cause a short circuit and destroy the electronics.
- 11. Make sure to turn off the battery to replace or to check the propellers.

## > 9.4 Troubleshooting Procedures

- Why can the battery not be used before the first flight?
   The battery must be activated by charging before using it for the first time.
- No function Check if the Smart Flight battery and the remote controller are activated by charging. If the problem persists, contact Potensic support.
- Power-on and start-up problemsCheck if the battery has power. If yes, contact Potensic support if it cannot be started normally.

4. SW update issues

Follow the instructions in the user manual to update the firmware. If the firmware update fails, restart all the devices and try again. If the problem persists, contact Potensic support.

- 5. Shutdown and power-off problems
  - Contact Potensic support.
- How to detect careless handling or storage in unsafe conditions
   Contact Potensic support.

## ≫ 9.5 Risk and Warnings

When the drone detects a risk after powering on, there will be a warning prompt on PotensicPro. Pay attention to the list of situations below.

- 1. If the drone status is not suitable for takeoff.
- 2. If the compass experiences interference and needs to be calibrated.
- 3. Follow the on-screen instructions when prompted.

## >> 9.6 Disposal



Observe the local regulations related to electronic devices when disposing of the drone and remote controller

### **Battery Disposal**

Dispose of the batteries in specific recycling containers only after a complete discharge. DO NOT dispose of the batteries in regular trash containers. Strictly follow the local regulations regarding the disposal and recycling of batteries.

Dispose of a battery immediately if it cannot be powered on after over-discharging.

If the Smart Flight Battery cannot be fully discharged, contact a professional battery disposal/recycling agency for further assistance.

#### >> 9.7 C0 Certification

ATOM(DSDR04C) is compliant with C0 certification requirements.

Model:	DSDR04C
UAS Class:	C0
Maximum Take-Off Mass (MTOM):	242g
Maximum Propeller speed:	18000RPM

#### **MTOM Statement**

The MTOM of ATOM (Model DSDR04C), including the Smart Flight Battery, Propellers, and a microSD card, is 242 g to comply with C0 requirements.

Users must follow the instructions below to comply with the MTOM requirements for each model:

- DO NOT add any payload to the drone except the items listed in the List of Items including qualified accessories section.
- 2. DO NOT use any non-qualified replacement parts, such as intelligent fight batteries or propellers, etc.
- 3 DO NOT retrofit the drone

## List of Items, including qualified accessories

#### For C0

Item	Model Number	Dimensions	Weight
Propellers	DSDR04C-PPS	119.4×63.8mm (Diameter × Thread Pitch)	0.65g (each piece)
Smart Flight Battery	DSBT02B	83.6×42.5×34.6mm	Approx. 84g
microSD Card*	N/A	15×11×1.0mm	Approx. 0.3g

## List of Spare and Replacement Parts For C0

- 1. ATOM Propellers
- 2. ATOM Smart Flight Battery

#### **Remote Controller Warnings**

Model: DSRC02A

If the remote controller is disconnected from the drone, the PotensicPro App will prompt an on-screen note, and the drone will perform the preset behavior when the remote controller signal is lost. The remote controller will shut down automatically after 20 minutes of no operation.

- Avoid interference between the remote controller and other wireless equipment. Make sure to turn off the Wi-Fi on nearby mobile devices. Land the drone as soon as possible if there is interference
- DO NOT operate the drone if lighting conditions are too bright or dark when using a mobile
  phone to monitor the flight. Users are responsible for correctly adjusting the display brightness
  when using the monitor in direct sunlight during flight operation.
- Release the control sticks or press the flight pause button if an unexpected operation occurs.

#### **EASA Notice**

Make sure to read the Drone Information Notices document included in the package before use. Visit the link below for more EASA notice information on traceability.

https://www.easa.europa.eu/en/document-library/general-publications/drones-information-notices

## **Original instructions**

This manual is provided by Shenzhen Potensic Intelligent Co., Ltd and the content is subject to change.

Address: Room 1901, Jingizhigu Building, Tangling Road, Nanshan District, Shenzhen, China.





Warning: The product should only be used by adults and children over 16 years. Adult supervision is required for children under 16 vears

Hinweis: Dieses Produkt ist für die Frwachsene und die Kinder ah 16 Jahren. Die Kinder unter 16 Jahren müssen von Erwachsenen beaufsichtigt werden

Avertissement: Ce produit est destiné aux adultes et aux enfants de plus de 16 ans. Les enfants de moins de 16 ans. doivent être surveillés par des adultes

Avvertimento: Questo prodotto è destinato all'uso per i adulti e bambini di età superiore ai 16 anni. I bambini di età inferiore ai 16 anni devono essere sorvegliati da un adulto

Advertencia: Este producto es para adultos y niños mayores de 16 años. Los niños menores de 16 años deben ser supervisados por adultos.

警告:この製品は、大人と16歳以上の子供には使用対象です。16歳未満の子供は大人の監視が必要です。



صنعت وفقا للمو اصفات والمعاب العالمية Tested according to international standards

NOT SUITABLE FOR CHILDREN LINDER 3 YEARS DUE TO SMALL PARTS هشدار ا درای کود کان زیر ۳ سال حب نیست ، دارای قطعات کو چک است

شحدٌ بر ب غير ملائم للإطفال شعت ثلاثة (ح) ستولت ي فلطعاة الصبغيرة COUNTRY OF ORIGIN: CHINA ملدالمنشاة: الصين



CHOKING HAZARD-Small narts. Not for children under 3 years.

#### Drone ECC ID: 24YUQ-DSDR04B

Remote controller FCC ID: 2AYUO-DSRC02A

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) This device must accept any interference received, including interference that may cause undesired operation.

Note: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses, and can radiate radio frequency energy, and if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

This equipment complies with FCC radiation exposure limits set forth for an uncontrolled environment. This equipment should be installed and operated with a minimum distance of 20cm between the radiator & your body. This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

Manufacturer: Shenzhen Potensic Intelligent Co., Ltd

Address: Room 1901, Jingizhigu Building, Tangling Road, Nanshan District, Shenzhen, China

EC REP

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