ProCon® — DO3000-C Series Dissolved Oxygen Controller



Quick Start Manual





Read the user's manual carefully before starting to use the unit. Producer reserves the right to implement changes without prior notice.

Dissolved Oxygen Controller



Safety Information

De-pressurize and vent system prior to installation or removal

Confirm chemical compatibility before use

DO NOT exceed maximum temperature or pressure specifications

ALWAYS wear safety goggles or face-shield during installation and/or service

DO NOT alter product construction



Warning | Caution | Danger

Indicates a potential hazard. Failure to follow all warnings may lead to equipment damage, or failure, injury, or death.



Intended Use

When receiving the instrument, please open the package carefully, check whether the instrument and accessories are damaged by transportation and whether the accessories are complete. If any abnormalities are found, please contact our after-sales service department or regional customer service center, and keep the package for return processing.

The technical data listed in the current data sheet are engaging and must be complied with. If the data sheet is not available, please order or download it from our homepage (www.iconprocon.com).

Personnel for Installation, Commissioning, and Operation

This instrument is an analytical measurement and control instrument with highly precision. Only skilled, trained or authorized person should carry out installation, setup and operation of the instrument. Ensure that the power cable is physically separated from the power supply when connection or repair. Once the safety problem occurs, make sure that the power to the instrument is off and disconnected.

For example, it may insecurity when the following situations occur:

- Apparent damage to the analyzer
- 2. The analyzer does not work properly or provides specified measurements.
- 3. The analyzer has been stored for a long time in an environment where the temperature exceeds 70 °C.

The analyzer must be installed by professionals in accordance with relevant local specifications, and instructions are included in the operation manual.

Comply with the technical specifications and input requirements of the analyzer.

Product Description

The DO3000 Dissolved Oxygen sensor uses fluorescence quenching technology to convert optical signals into electrical signals. It delivers stable oxygen concentration readings with a self-developed 3D algorithm.

The Dissolved Oxygen Controller is a microprocessor-based water quality online monitoring control instrument. It is widely used in drinking water treatment plants, drinking water distribution networks, swimming pools, water treatment projects, sewage treatment, water disinfection and other industrial processes.

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Dissolved Oxygen Controller



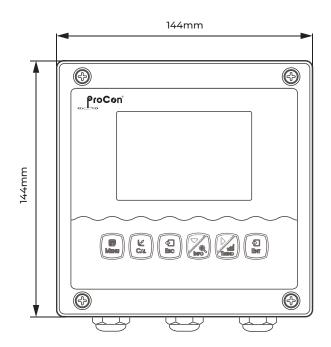
Technical Specifications

Measurement Range	0.005~20.00mg/L 0.005~20.00ppm
Measurement Unit	Fluorescence
Resolution	0.001mg/L 0.001ppm
Basic Error	±1% F.S
Temperature	14 ~ 302°F -10 ~ 150.0°C (Depends on the Sensor)
Temperature Resolution	0.1°C
Temperature Basic Error	±0.3°C
Stability	pH: ≤0.01pH/24h ; ORP: ≤1mV/24h
Current Output	2 groups: 4-20mA
Communication Output	RS485 MODBUS RTU
Other Functions	Data Record & Curve Display
Three Relay Control Contacts	5A 250VAC, 5A 30VDC
Power Supply	9~36VDC 85~265VAC Power Consumption ≤ 3W
Working Conditions	No strong magnetic field interference around except the geomagnetic field
Working Temperature	14 ~ 140°F -10~60°C
Relative Humidity	≤90%
Waterproof Rating	IP65
Weight	0.8kg
Dimensions	144 x 114 x 118mm
Installation Opening Size	138 x 138mm
Installation Methods	Panel Wall Mount Pipeline

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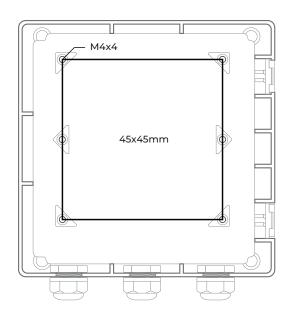


Dimensions

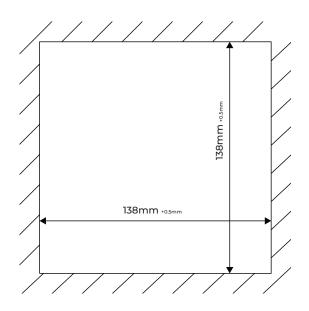


118mm 26mm

Instrument Dimensions



Back Fixed Hole Size

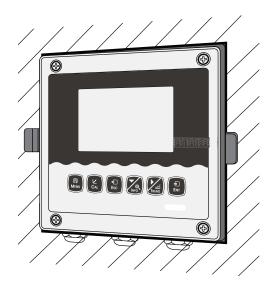


Embedded Mounting Cut-out Size

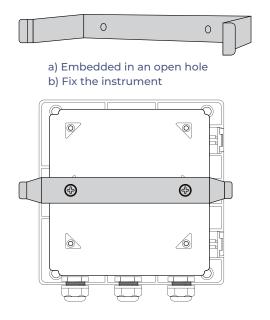
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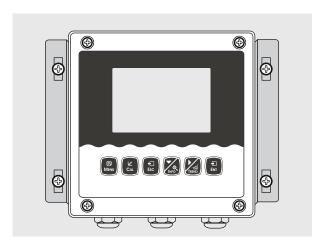
Embedded Installation



Schematic of Completion of Installation



Wall Mount Installation

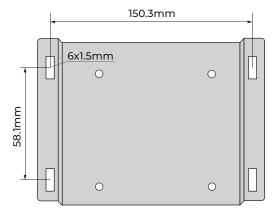


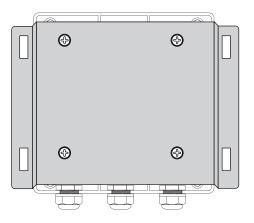
Schematic of Completion of Installation

- a) Install a mounting bracket for the instrument
- b) Wall screw fixation



Top view of mounting bracket
Pay attention of installation direction

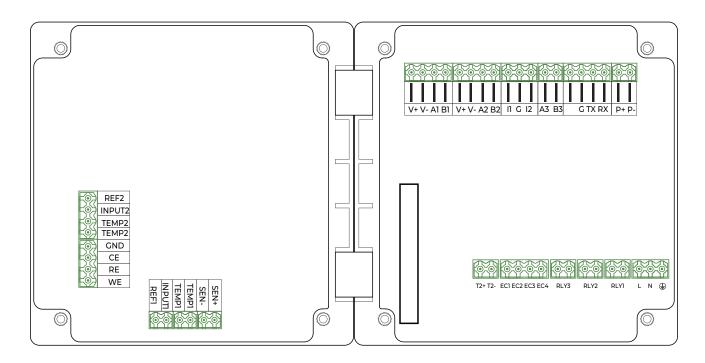




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Wiring



Terminal	Description
V+, V-, A1, B1	Digital Input Channel 1
V+, V-, A2, B2	Digital Input Channel 2
11, G, 12	Output Current
A3, B3	RS485 Communication Output
G, TX, RX	RS232 Communication Output
P+, P-	DC Power Supply
T2+, T2-	Temp Wire Connection
EC1,EC2,EC3,EC4	EC/RES Wire Connection
RLY3,RLY2,RLY1	Group 3 Relays
L,N, ⊕	L- Live Wire N- Neutral Ground

Terminal	Description		
REF1	pH/lon Reference 1		
INPUT 1	pH/Ion Measurement 1		
TEMP 1	Temp 2		
SEN-, SEN+	Membrane DO/FCL		
REF2	pH Reference 2		
INPUT 2	pH Measurement 2		
TEMP 2	Temp 2		
GND	Ground (for test)		
CE,RE,WE	Constant Voltage for FCL/CLO2/O3		

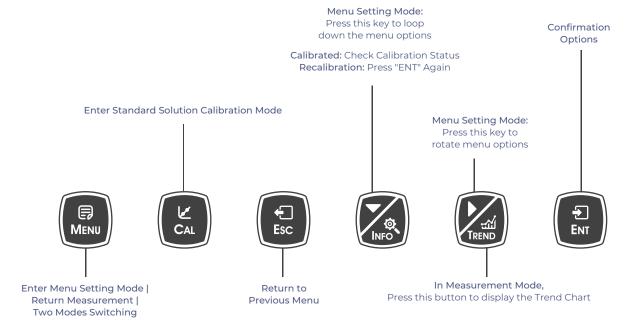
The connection between the instrument and the sensor: the power supply, output signal, relay alarm contact and the connection between the sensor and the instrument are all inside the instrument, and the wiring is as shown above. The length of the cable lead fixed by the electrode is usually 5-10 Meters, insert the line with corresponding label or color wire on the sensor into the corresponding terminal inside the instrument and tighten it.

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Keypad Description

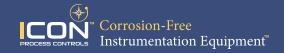




Short Press: Short Press means to release the key immediately after pressing. (Default to short presses if not included below)

Long Press: Long Press is to press the button for 3 seconds and then release it.

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Display Descriptions

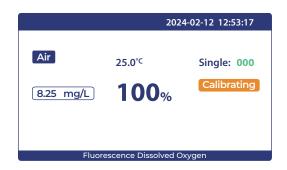
All pipe connections and electrical connections should be checked before use. After the power is switched on, the meter will display as follows.



Measurement Mode



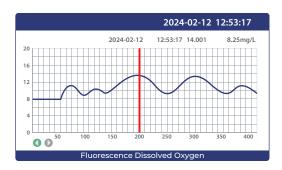
Calibration Mode



Setting Mode



Trend Chart Display



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Menu Structure

The following is the menu structure of this instrument

			mg/L	
		Unit	%	
		Pressure Compensation	101.3	
	Sensor	Salinity Compensation	0	
	3611301	Zero Oxygen Voltage Compensation	100mV	
		Saturation Oxygen Voltage Compensation	400mV	
Configure		Saturation Oxygen Compensation	8.25	
			NTC2.252 kΩ	
	Temperature	Tomporatura Concor	ΝΤC10 kΩ	
		Temperature Sensor	Pt 100	
			Pt 1000	
		Temperature Offset	0.0000	
		Temperature Input	Automatic	
		remperature input	Manual	
		Temperature Unit	°C	
		remperature offic	°F	
	Standard Calibration	Zero Calibration		
	Staridard Campidation	Air Calibration		
			Offset Correction 1	
		Correction	Slope Correction 2	
Calibration		Correction	Offset Correction 1	
	Field Calibration		Slope Correction 2	
		Field Calibration		
		Offset Adjustment		
		Slope Adjustment		

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		On-Off State	ON		
		OII-OII State	OFF		
			High Alarm		
		Specify the Type	Low Alarm		
	Relay 1		Clean		
		Limit Setting (Open Time - Cleaning State)	Continuous Opening Time		
		Lag (Off Time - In Cleaning State)	The interval between the last opening and closing and the next opening		
			ON		
		On-Off State	OFF		
			High Alarm		
		Specify the Type	Low Alarm		
Alarm	Relay 2		Clean		
		Lincit Catting			
		Limit Setting (Open Time - Cleaning State)	Continuous Opening Time		
		Lag (Off Time - In Cleaning State)	The interval between the last opening and closing and the next opening		
	Relay 3	On-Off State	ON		
			OFF		
		Specify the Type	High Alarm		
			Low Alarm		
			Clean		
		Limit Setting (Open Time - Cleaning State)	Continuous Opening Time		
		Lag (Off Time - In Cleaning State)	The interval between the last opening and closing and the next opening		
		Charan	Main		
		Channel	Temperature		
			4-20mA		
	Current 1	Output Option	0-20mA		
			20-4mA		
		Upper Limit			
Output		Lower Limit			
		Channel	Main		
			Temperature		
	Current 2		4-20mA		
		Output Option	0-20mA		
		Uppor Limit	20-4mA		
		Upper Limit Lower Limit			

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			4800BPS
		Baud Rate	9600BPS
			19200BPS
			None
Output	RS485	Parity Check	Odd
			Even
		Chara Dit	1 Bit
		Stop Bit	2 Bit
		Network Node	001 +
		Interval/Point	
	Graphic Trend	1h/Point	Display according to interval settings 480 points
	(Trend Chart)	12h/Point	screen
		24h/Point	
	Data Query	Year Month Day	
Data Log		7.5s	
	Record Interval	90s	
		180s	
	Memory Information	176932 Point	
	Data Output		
		English	
	Language	Chinese	
		Year-Month-Day	
	Date Time	Hour-Minute-Second	
			Low
			Standard
		Display Speed	Medium
System	Display		High
			Saving
		Back light	Bright
		Software Version	1.9-1.0
	Software Version	Password Settings	0000
		Serial number	
		No	
	Factory Default	Yes	

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	Terminal Current Tuning Relay Test	Current 1 – 4mA	The positive and negative ends of the ammeter are			
		Current 1 – 20mA	connected to the current 1 or current 2 output			
System		Current 2 – 4mA	terminals of the instrument respectively, press [▼] key to adjust the current to 4 mA or 20mA , press			
		Current 2 – 20mA	[ENT] key to confirm.			
		Relay 1				
		Relay 2	Select three groups of relays and hear the sound of two switches, the relay is normal.			
		Relay 3	two smeeties, and relay is merman			

Calibration

Press [MENU] to enter the setting mode and select the calibration

Calibration	Standard Calibration	Anaerobic Calibration
		Air Calibration
		Field Calibration
	Field Calibration	Offset Adjustment
		Slope Adjustment

Standard Solution Calibration

Press [ENT] key to confirm and enter the standard solution calibration mode. If the instrument has been calibrated, the screen will display the calibration status. Press the [ENT] key again to enter re-calibration if needed.

If the monitor prompts you to enter the calibration safety password, press $[\P]$ or $[\P]$ key to set the calibration safety password, then press [ENT] to confirm the calibration safety password.

Anaerobic Calibration

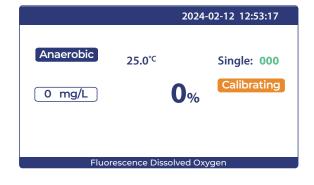
After entering the calibration mode, the instrument displays as shown in the figure. DO electrode is put into anaerobic water without shading cap.

The corresponding "signal" value will be displayed in the upper left corner of the screen. When the "signal" value is stable, press **[ENT]** to confirm.

During the calibration process, the right side of the screen will display the calibration status.

- Done = calibration was successful.
- Calibrating = calibration is in progress.
- Err = calibration failed.

After calibration is complete, press the **[MENU]** key to return to the superior menu.



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Air Calibration

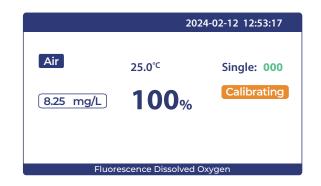
After entering the calibration mode, the instrument displays as shown in the figure. Put the DO electrode in the air with the shading cap.

The corresponding "signal" value will be displayed in the upper left corner of the screen. When the "signal" value is stable, press [ENT] to confirm

During the calibration process, the right side of the screen will display the calibration status.

- **Done** = calibration was successful.
- Calibrating = calibration is in progress.
- Err = calibration failed.

After calibration is complete, press the **[MENU]** key to return to the superior menu.

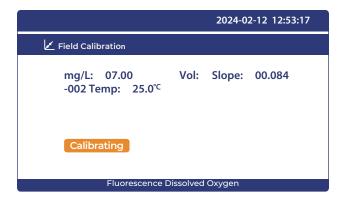


Field Calibration

Select on-site calibration methods: [Linear calibration], [Offset adjustment], [Linear adjustment].

Field Calibration

When the data from laboratory or portable instrument are input into this item, the instrument will automatically correct the data.



Calibration Results

Confirm: When the "ENT" icon is Green, press [ENT] to confirm.

Cancel: Press the [▼] key to shift the Green icon to ESC, and press [ENT] to confirm.

Offset Adjustment

Compare the data from portable instrument with the data measured by instrument. If there is any error, the error data can be modified by this function.

Linear adjustment

Linear values after "field calibration" will be saved in this term and the factory data is 1.00.

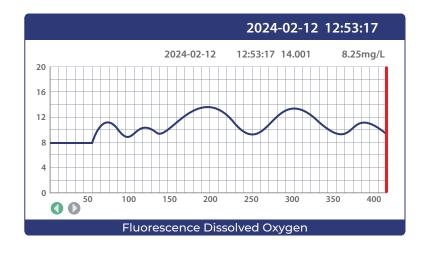
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Graphic Trend (Trend Chart)

	Curve Query (Trend Chart)	Interval/Point	400 points per screen, displays the most recent data trend graph according to interval settings	
		1h/point	400 points per screen, display trend chart of the last 16 days of data	
		12h/point	400 points per screen, display trend chart of the last 200 days of data	
Data Log		24h/point	400 points per screen, display trend chart of the last 400 days of data	
	Data Query	Year/Month/Day	Year/Month/day Time: Minute: Second Value Unit	
		7.5s	Store Data Every 7.5 Seconds	
	Interval	90s	Store Data Every 90 Seconds	
		180s	Store Data Every 180 Seconds	

Press the [MENU] button returns to the measurement screen. Press the [▶/TREND] button in the measurement mode to view the trend chart of the saved data directly. There are 480 sets of data record per screen, and the interval time of each record can be selected [7.5s, 90s, 180s), corresponding to the data displayed in [1h, 12h, 24h] per screen.



In the current mode, press the [ENT] key to move the data display line to the left and right (green) and display the data in left and right circles. Long pressing of the [ENT] key can accelerates displacement. (When the bottom Icons is green. [ENT] key is displacement direction, press [> /TREND] key to switch the direction of displacement)

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MODBUS RTU

The hardware version number of this document is V2.0; the software version number is V5.9 and above. This document describes the MODBUS RTU interface in details and the target object is a software programmer.

MODBUS Command Structure

Data format description in this document;

Binary display, suffix B, for example: 10001B - decimal display, without any prefix or suffix, for example: 256 Hexadecimal display, prefix 0x, for example: 0x2A

ASCII character or ASCII string display, for example: "YL0114010022"

Command Structure

The MODBUS application protocol defines the Simple Protocol Data Unit (PDU), which is independent of the underlying communication layer.

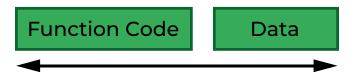


Fig.1: MODBUS Protocol Data Unit

MODBUS protocol mapping on a specific bus or network introduces additional fields of protocol data units. The client that initiates the MODBUS exchange creates the MODBUS PDU, and then adds the domain to establish the correct communication PDU.

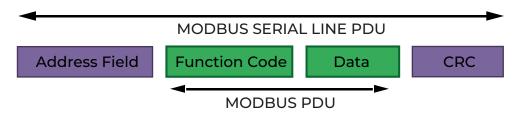


Fig.2: MODBUS Architecture for Serial Communication

On the MODBUS serial line, the address domain contains only the slave instrument address. Tips: The device address range is 1...247

Set the device address of the slave in the address field of the request frame sent by the host. When the slave instrument responds, it places its instrument address in the address area of the response frame so that the master station knows which slave is responding.

Function codes indicate the type of operation performed by the server.

CRC domain is the result of the "redundancy check" calculation, which is executed according to the information content.

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MODBUS RTU Transmission Mode

When the instrument uses RTU (Remote Terminal Unit) mode for MODBUS serial communication, each 8-bit byte of information contains two 4-bit hexadecimal characters. The main advantages of this mode are greater character density and better data throughput than the ASCII mode with the same baud rate. Each message must be transmitted as a continuous string.

The format of each byte in RTU mode (11 bits):

Coding system: 8-bit binary

Each 8-bit byte in a message contains two 4-bit hexadecimal characters (0-9, A-F)

Bits in each byte: 1 starting bit

8 data bits, the first minimum valid bits without parity check bits

2 stop bits

Baud rate: 9600 BPS

How characters are transmitted serially:

Each character or byte is sent in this order (from left to right) the least significant bit (LSB)... Maximum Significant Bit (MSB)

Start bit	1	2	3	4	5	6	7	8	Stop bit	Stop bit
ocal c bic		_	_		_	_			OCOP DIC	Otop Dit

Fig.3: RTU Pattern Bit Sequence

Check Domain Structure: Cyclic Redundancy Check (CRC16)

Structure description:

Slave Instrument	Function Code	Data	CRC
A .l. d	7 1	0. 252 h	2 byte
Address	1 byte	0252 byte	CRC Low byte CRC High byte

Fig.4: RTU Information Structure

The maximum frame size of MODBUS is 256 bytes

MODBUS RTU Information Frame

In RTU mode, message frames are distinguished by idle intervals of at least 3.5 character times, which are called t3.5 in subsequent sections.

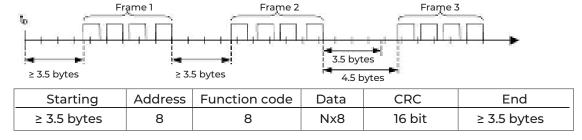


Fig.5: RTU Message Frame

The entire message frame must be sent in a continuous character stream. When the pause time interval between two characters exceeds 1.5 characters, the information frame is considered incomplete and the receiver does not receive the information frame.

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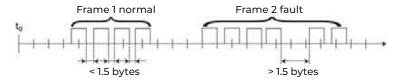


Fig.6: MODBUS RTU CRC Check

The RTU mode contains an error-detection domain based on a cyclic redundancy check (CRC) algorithm that performs on all message contents. The CRC domain checks the contents of the entire message and performs this check regardless of whether the message has a random parity check. The CRC domain contains a 16-bit value consisting of two 8-bit bytes. CRC16 check is adopted. Low bytes precede, high bytes precede.

Implementation of MODBUS RTU in Instrument

According to the official MODBUS definition, the command starts with a 3.5 character interval triggering command, and the end of the command is also represented by a 3.5 character interval. The device address and MODBUS function code have 8 bits. The data string contains n*8 bits, and the data string contains the starting address of the register and the number of read/write registers. CRC check is 16 bits.

Value	Start	Device Address	Function	Data	Summary Check		End
	No Signal bytes during 3.5 Characters	1-247 1	Function Codes Confirming to MODBUS Specification	Data Confirming to MODBUS Specification	CRCL	CRCL	No Signal bytes during 3.5 characters
Byte	3.5		1	N	1	1	3.5

Fig.7: MODBUS definition of Data Transmission

Instrument MODBUS RTU Function Code

The instrument only uses two MODBUS function codes:

0x03: Read-and-hold register 0x10: Write multiple registers

MODBUS Function Code 0x03: Read-and-hold Register

This function code is used to read the continuous block content of the holding register of the remote device. Request the PDU to specify the start register address and the number of registers. Address registers from zero. Therefore, the addressing register 1-16 is 0-15. The register data in the response information is packaged in two bytes per register. For each register, the first byte contains high bits and the second byte contains low bits.

Request:

Function Code	1 byte	0x03
Start Address	2 byte	0x00000xffffff
Read Register Number	2 byte	1125

Fig.8: Read and hold register request frame

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Response:

Function Code	1 byte	0x03	
Number of bytes	2 bytes	0x00000xffffff	
Read Register Number	2 bytes	1125	

N = Register Number

Figure 9: Read and hold register response frame

The following illustrates the request frame and response frame with the read and hold register 108-110 as an example. (The contents of register 108 are read-only, with two byte values of 0X022B, and the contents of register 109-110 are 0X0000 and 0X0064)

Request Frame		Response Frame	
Number Systems	(Hexadecimal)	Number Systems (Hexadecima	
Function Code	0x03	Function Code	0x03
Start Address (High byte)	0x00	Byte Count	0x06
Start Address (Low byte)	0x6B	Register Value (High Bytes) (108)	0x02
Number of Read Registers (High Bytes)	0x00	Register Value (Low Bytes) (108)	0x2B
Number of Read Registers (Low Bytes)	0x03	Register Value (High Bytes) (109)	0x00
		Register Value (Low Bytes) (109)	0x00
		Register Value (High Bytes) (110)	0x00
		Register Value (Low Bytes) (110)	0x64

Figure 10: Examples of read and hold register request and response frames

MODBUS Function Code 0x10: Write Multiple Registers

This function code is used to write continuous registers to remote devices (1... 123 registers) block that specifies the value of the registers written in the request data frame. Data is packaged in two bytes per register. Response frame return function code, start address and number of registers written.

Request:

Function Code	1 byte	0x10
Start Address	2 byte	2 byte
Number of input registers	2 byte	2 byte
Number of bytes	1 byte	1 byte
Register Values	N x 2 bytes	N x 2 bytes

Fig.11: Write Multiple Register Request Frames

*N = Register Number

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Response:

Function Code	1 byte	0x10
Start Address	2 byte	0x00000xffff
Register Number	2 byte	1123(0x7B)

N = Register Number

Figure 12: Write Multiple Register Response Frames

The request frame and response frame are illustrated below in two registers that write the values 0x000A and 0x0102 to the start address of 2.

Request Frame	(Hexadecimal)	Response Frame	(Hexadecimal)
Number Systems	0x10	Number Systems	0x10
Function Code	0x00	Function Code	0x00
Start Address (High byte)	0x01	Start Address (High byte)	0x01
Start Address (Low byte)	0x00	Start Address (Low byte)	0x00
Input Register Number (High bytes)	0x02	Input Register Number (High bytes)	0x02
Input Register Number (Low bytes)	0x04	Input Register Number (Low bytes)	
Number of bytes	0x00		
Register Value (High byte)	0x0A		
Register Value (Low byte)	0x01		
Register Value (High byte)	0x02		
Register Value (Low byte)			

Figure 13: Examples of writing multiple register request and response frames

Data Format in Instrument

Floating Point

Definition: Floating point, conforming to IEEE 754 (single precision)

Description	Symbol	Index	Mantissa	SUM
Bit	31	3023	220	220
Index Deviation	127			

Figure 14: Floating Point Single Precision Definition (4 bytes, 2 MODBUS Registers)

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Example: Compile decimal 17.625 to binary

Step 1:

Converting 17.625 in decimal form to a floating-point number in binary form, first finding the binary representation of the integer part

17decimal= $16 + 1 = 1 \times 2^4 + 0 \times 2^3 + 0 \times 2^2 + 0 \times 2^1 + 1 \times 2^0$

The binary representation of integer part 17 is 10001B

Then the binary representation of decimal part is obtained

 $0.625 = 0.5 + 0.125 = 1 \times 2^{-1} + 0 \times 2^{-2} + 1 \times 2^{-3}$

The binary representation of decimal part 0.625 is 0.101B.

So the binary floating point number of 17.625 in decimal form is 10001.101B

Step 2:

Shift to find the exponent.

Move 10001.101B to the left until there is only one decimal point, resulting in 1.0001101B, and

10001.101B = 1.0001101 B× 24. So the exponential part is 4, plus 127, it becomes 131, and its binary representation is 10000011B.

Step 3:

Calculate the tail number

After removing 1 before the decimal point of 1.0001101B, the final number is 0001101B (because before the decimal point must be 1, so IEEE stipulates that only the decimal point behind can be recorded). For the important explanation of 23-bit mantissa, the first (i.e. hidden bit) is not compiled. Hidden bits are bits on the left side of the separator, which are usually set to 1 and suppressed.

Step 4:

Symbol bit definition

The sign bit of positive number is 0, and the sign bit of negative number is 1, so the sign bit of 17.625 is 0.

Step 5:

Convert to floating point number

1 bit symbol + 8 bit index + 23-bit mantissa

0 10000011 0001101000000000000000000 (the hexadecimal system is shown as 0 x418d0000)

Reference code:

1. If the compiler used by the user has a library function that implements this function, the library function can be called directly, for example, using C language, then you can directly call the C library function memcpy to obtain an integer representation of the floating-point storage format in memory.

For example: float floatdata; // converted floating point number void* outdata; memcpy (outdata, & floatdata, 4);

Suppose floatdata = 17.625

If it is a small-end storage mode, after executing the above statement, the data stored in the address unit outdata is 0x00.

Outdata + 1 stores data as 0x00

address unit (outdata + 2) stores data as 0x8D

address unit (outdata + 3) stores data as 0x41

If it is large-end storage mode, after executing the above statement, the data stored in outdata of address unit is 0x41

address unit (outdata + 1) stores data as 0x8D

address unit (outdata + 2) stores data as 0x00

address unit (outdata + 3) stores data as 0x00

2. If the compiler used by the user does not implement the library function of this function, the following functions can be used to achieve this function:

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```
void memcpy(void *dest,void *src,int n)
char *pd = (char *)dest; char *ps = (char *)src;
for(int i=0;i< n;i++)*pd++=*ps++;
And then make a call to the above memcpy(outdata,&floatdata,4);
Example: Compile binary floating-point number 0100 0010 0111 1011 0110 0110 10B to decimal number
Step 1: Divide the binary floating-point number 0100 0010 0111 1011 0110 0110 0110B into symbol bit, exponential bit and mantis-
sa bit.
      10000100
                      11110110110011001100110B
1-bit sign + 8-bit index + 23-bit tail sign bit S: 0 denotes positive number
Index position E: 10000100B = 1 \times 2^7 + 0 \times 2^6 + 0 \times 2^5 + 0 \times 2^4 + 0 \times 2^3 + 1 \times 2^2 + 0 \times 2^1 + 0 \times 2^0
=128+0+0+0+0+4+0+0=132
Mantissa bits M: 11110110110011001100110B =8087142
Step 2: Calculate the decimal number
D = (-1) \times (1.0 + M/223) \times 2E - 127
= (-1)0 \times (1.0 + 8087142/223) \times 2132 - 127
= 1×1.964062452316284×32
= 62.85
Reference Code:
float floatTOdecimal(long int byte0, long int byte1, long int byte2, long int byte3)
long int realbyte0,realbyte1,realbyte2,realbyte3; char S;
long int E,M;
float D; realbyte0 = byte3; realbyte1 = byte2; realbyte2 = byte1; realbyte3 = byte0;
if((realbyte0\&0x80)==0)
S = 0;//positive number
else
S = 1;//negative number
E = ((realbyte0 << 1))((realbyte1 &0 x 80) >> 7) -127;
M = ((realbyte1\&0x7f) << 16) | (realbyte2 << 8)| realbyte3;
D = pow(-1,S)*(1.0 + M/pow(2,23))*pow(2,E);
return D;
```

Function description: parameters byte0, byte1, byte2, byte3 represent 4 bytes of binary floating point number.

The decimal number converted from the return value.

For example, the user sends the command to get the temperature value and dissolved oxygen value to the probe. The 4 bytes representing the temperature value in the received response frame are 0x00, 0x00, 0x8d and 0x41. Then the user can get the decimal number of the corresponding temperature value through the following call statement.

That is temperature = 17.625.

Float temperature = floatTOdecimal(0x00, 0x00, 0x8d, 0x41)

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Read Instruction Mode

The communication protocol adopts MODBUS (RTU) protocol. The content and address of the communication can be changed according to the needs of customers. The default configuration is network address 01, baud rate 9600, even check, one stop bit, users can set their own changes;

Function code 0x04: This function enables the host to obtain real-time measurements from slaves, which are specified as single-precision floating-point type (i.e. occupying two consecutive register addresses), and to mark the corresponding parameters with different register addresses. Communication address is as follows:

0000-0001: Temperature value | 0002-0003: Main Measured Value | 0004-0005: Temperature and Voltage Value |

0006-0007: Main Voltage Value

Communication examples:

Examples of function code 04 instructions:

Communication address = 1, temperature = 20.0, ion value = 10.0, temperature voltage = 100.0, ion voltage = 200.0

Host Send: 01 04 00 00 08 F1 CC | Slave Response: 01 04 10 00 41 A0 00 41 20 00 42 C8 00 43 48 81 E8

Note:

[01] Represents the instrument communication address;

[04] Represents function code 04;

[10] represents 10H (16) byte data;

 $[00\ 00\ 00\ 4]\ A0] = 20.0; / temperature value$

[00 00 4120]= 10.0; // Main Measured Value

[00 00 42 C8] = 100.0; // Temperature and Voltage Value

[00 00 43 48] = 200.0; // Main measured voltage value

[81 E8] represents CRC16 check code;

Oxygen Saturation Table Under Different Temperatures

°F °C	mg/L	°F °C	mg/L	°F °C	mg/L
32 0	14.64	57 14	10.30	82 28	7.82
34 1	14.22	59 15	10.08	84 29	7.69
34 2	13.82	61 16	9.86	86 30	7.56
37 3	13.44	62 17	9.64	88 31	7.46
39 4	13.09	64 18	9.46	89 32	7.30
41 5	12.74	66 19	9.27	91 33	7.18
43 6	12.42	68 20	9.08	93 34	7.07
44 7	12.11	70 21	8.90	95 35	6.95
46 8	11.81	71 22	8.73	97 36	6.84
48 9	11.53	73 23	8.57	98 37	6.73
50 10	11.26	75 24	8.41	100 38	6.63
52 11	11.01	77 25	8.25	102 39	6.53
53 12	10.77	79 26	8.11		
55 13	10.53	80 27	7.96		

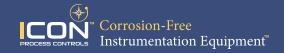
Note: this table is from appendix C of JJG291 - 1999.

The dissolved oxygen content can be calculated at different atmospheric pressures as follows.

$$A_3 = \frac{P}{A \cdot 101.325}$$

In formula In formula: As-- Solubility of atmospheric pressure at P(Pa); A-- Solubility at atmospheric pressure of 101.325(Pa); P-- pressure, Pa.

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Maintenance

According to the requirements of use, the installation position and working condition of the instrument are relatively complex. In order to ensure that the instrument is working normally, maintenance personnel should carry out regular maintenance on the instrument. Please pay attention to the following matters during maintenance:

Check the working environment of the instrument. If the temperature exceeds the rated range of the instrument, please take appropriate measures; otherwise, the instrument may be damaged or its service life may be reduced;

When cleaning the plastic shell of the instrument, please use a soft cloth and a soft cleaner to clean the shell.

Check whether the wiring on the terminal of the instrument is firm. Pay attention to disconnect the AC or DC power before removing the wiring cover.

Package Set

Product Description	Quantity
1) T6046 Fluorescence Online Dissolved Oxygen Meter	1
2) Instrument Installation Accessories	1
3) Operating Manual	1
4) Qualification Certificate	1

Note: Please check the complete set of instruments before use.

The company's other series of analytical instruments, please login to our website for inquiries.

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Warranty, Returns and Limitations

Warranty

Icon Process Controls Ltd warrants to the original purchaser of its products that such products will be free from defects in material and workmanship under normal use and service in accordance with instructions furnished by Icon Process Controls Ltd for a period of one year from the date of sale of such products. Icon Process Controls Ltd obligation under this warranty is solely and exclusively limited to the repair or replacement, at Icon Process Controls Ltd option, of the products or components, which Icon Process Controls Ltd examination determines to its satisfaction to be defective in material or workmanship within the warranty period. Icon Process Controls Ltd must be notified pursuant to the instructions below of any claim under this warranty within thirty (30) days of any claimed lack of conformity of the product. Any product repaired under this warranty will be warranted only for the remainder of the original warranty period. Any product provided as a replacement under this warranty will be warranted for the one year from the date of replacement.

Returns

Products cannot be returned to Icon Process Controls Ltd without prior authorization. To return a product that is thought to be defective, go to www.iconprocon.com, and submit a customer return (MRA) request form and follow the instructions therein. All warranty and non-warranty product returns to Icon Process Controls Ltd must be shipped prepaid and insured. Icon Process Controls Ltd will not be responsible for any products lost or damaged in shipment.

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This warranty does not apply to products which:

- 1. are beyond the warranty period or are products for which the original purchaser does not follow the warranty procedures outlined above;
- 2. have been subjected to electrical, mechanical or chemical damage due to improper, accidental or negligent use;
- 3. have been modified or altered;
- 4. anyone other than service personnel authorized by Icon Process Controls Ltd have attempted to repair;
- 5. have been involved in accidents or natural disasters; or
- 6. are damaged during return shipment to Icon Process Controls Ltd

Icon Process Controls Ltd reserves the right to unilaterally waive this warranty and dispose of any product returned to Icon Process Controls Ltd where:

- there is evidence of a potentially hazardous material present with the product;
- 2. or the product has remained unclaimed at Icon Process Controls Ltd for more than 30 days after Icon Process Controls Ltd has dutifully requested disposition.

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If any portion of this warranty is held to be invalid or unenforceable for any reason, such finding will not invalidate any other provision of this warranty.

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www.iconprocon.com | e-mail: sales@iconprocon.com or support@iconprocon.com | Ph: 905.469.9283

