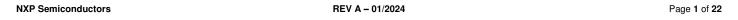
S32M27xEVB-L064

Evaluation Board for S32M27x LIN MCUs Hardware User Manual



S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers





1. Table of contents

| 1. | Table of contents | 2 |
|-----|--|----|
| 2. | Definitions, Acronyms, and Abbreviations | 3 |
| 3. | S32M27xEVB-L064 – Block Diagram | 4 |
| 4. | S32M27xEVB-L064 - Features | 5 |
| 5. | S32M27xEVB-L064 – Default Configuration | 6 |
| 6. | S32M27xEVB-L064 – Default Jumpers | 6 |
| 7. | Power Supplies Options – Overview | 7 |
| 7.1 | 1 S32M27xEVB-L064 – Main Power Supply | 7 |
| | 7.2 S32M27xEVB-L064 – VPRE | 9 |
| 7.3 | 3 S32M27XEVB-L064 VDD_HV_A | 9 |
| 8. | Motor Control Interface | 10 |
| 9. | S32M27xEVB-L064 – Programming and Debug Interface | 12 |
| 9.1 | 1 S32M27xEVB-L064 - RESET switch and led indicator | 12 |
| 9.2 | 2 S32M27xEVB-L064 – On-board Debugger | 13 |
| 10. | S32M27xEVB-L064 – CAN PHY | 14 |
| 11. | S32M27xEVB-L064 – LIN PHY | 15 |
| 12. | S32M27xEVB-L064 – User Peripherals | 17 |
| 12 | 2.1 S32M27xEVB-L064 – User Led | 17 |
| 12 | 2.2 S32M27xEVB-L064 – User Push buttons | 18 |
| 12 | 2.3 S32M27xEVB-L064 – ADC Rotary Potentiometer | 20 |
| 13. | S32M27xEVB-L064 – Revision history | 21 |
| 14. | Legal Information | 22 |
| 14 | 4.1 Definitions | 22 |
| 14 | 1.2 Disclaimers | 22 |
| 14 | 1.3 Trademarks | 22 |

2. Definitions, Acronyms, and Abbreviations

The following list defines the abbreviations used in this document.

BST Boost

CCM Counter with CBC MAC (Cipher block chaining message authentication code)

CMOS Complementary Metal Oxide Semiconductor.

CP Charge Pump

CPU Central Processing Unit.

CSPI Configurable Serial Peripheral Interface.

DDR Double Data Rate.
DIP Dual In-line Package.

DPGA Differential Programmable Gain Amplifier

EEPROM Electrically Erasable Programmable Read Only Memory.

EPROM Erasable Programmable Read Only Memory.

FET Field-Effect Transistor

GCTL Gate Control GDU Gate Driver Unit

GPIO General Purpose Input/output.
GPO General Purpose Output.

HG High-side Gate
HS High-side Source
HW Hardware.

HVI High Voltage Input
HVM High Voltage Module
I2C Inter-Integrated Circuit.

I/O Input/output.

JTAG Joint Test Access Group.
LED Light Emitting Diode.
LG Low-side Gate
LPM Low-Power Mode
LS Low-side Source
MB Megabyte.

MCU Microcontroller Unit.

MOSFET Metal-Oxide-Semiconductor Field-Effect Transistor

MS Memory Stick.

NVRAM Non-volatile Random-Access Memory.

PCB Printed Circuit Board. PHY Physical interface.

PMC Power Management Controller

POR Power-on Reset.

PSRAM Pseudo Random Access Memory.

PWR Power.

PWM Pulse Width Modulation.
RAM Random Access Memory.

SDRAM Synchronous Dynamic Random-Access Memory.

TFT Thin Film Transistor.

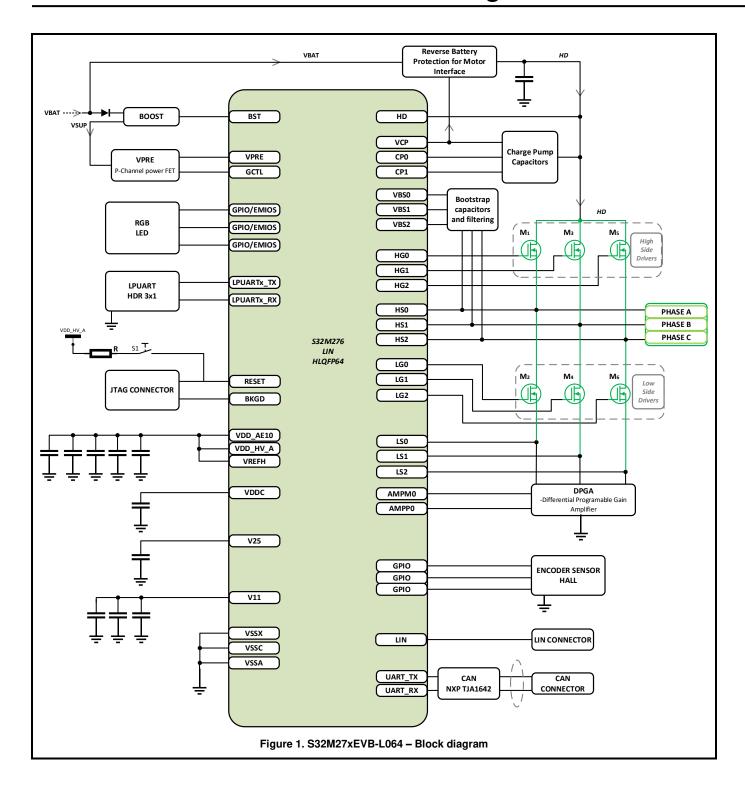
UART Universal Asynchronous Receiver/Transmitter.

USB Universal Serial Bus.

S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers

3. S32M27xEVB-L064 – Block Diagram



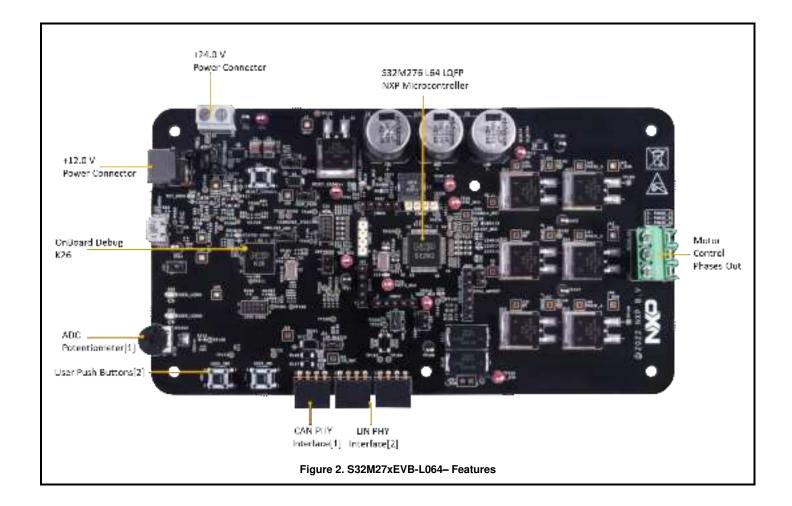
S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers

4. S32M27xEVB-L064 - Features

IMPORTANT

- Verify and download the last version of this document in http://www.nxp.com
- Before the S32M27xEVB-L064 Evaluation board is used or power is applied, please fully read this user
 manual. An incorrect configuration in the board may cause a irreparable damage on the component, MCU or
 EVB. Power must be removed from the EVB prior to:
 - Removing or placing some component or measurement
 - Re-configuring the board jumpers

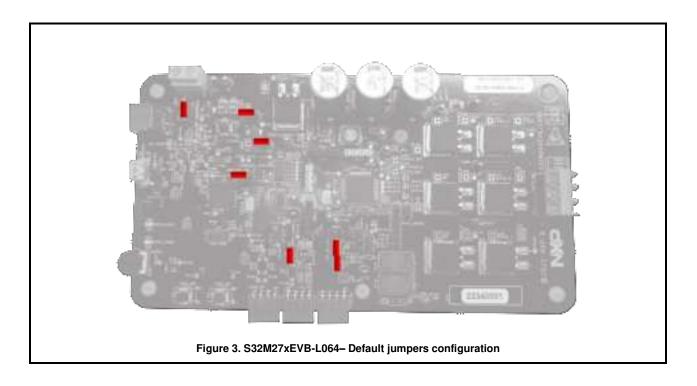


5.S32M27xEVB-L064 – Default Configuration

Table 1. S32M27xEVB-L064 - Default Configuration

| Interface | Reference / Signal | Default Configuration | Description/Comment | |
|-----------------------|-----------------------|--------------------------|---|--|
| S32M276 MCU | U13 | N/A | S32M276L_64LQFP | |
| OnBoard | U9 | PTC2 | PTC2/LPUART0_RX is routed to NTS0102GD terminal B1 for serial interface to MK26FN2M0VMI18 | |
| Debugger | | PTC3 | PTC3/LPUART0_TX is routed to NTS0102GD terminal B2 for serial interface to MK26FN2M0VMI18 | |
| LIN Interface | Internal LIN | LIN | LIN out is routed to J53 and J54 terminal 2 | |
| | | CAN0_RX_MCU | PTE15/LPUART3_RX is routed to TJA1462 RX | |
| CAN | | CAN0_TX_MCU | PTE16/LPUART3_TX is routed to TJA1462 TX | |
| Interface | U11 | CAN0_STB_MCU | PTB5 is routed to TJA1462 STB | |
| | | CANH | CANH is routed to J50 terminal 2 | |
| | | CANL | CANL is routed to J50 terminal 2 | |
| User Push | SW2 | PTA15 | Active Low, | |
| Buttons | SW3 | PTD0 | Active Low, | |
| User LEDs | D20 | PTE15 | User Led 1 | |
| | D21 | PTE16 | User Led 2 | |
| ADC Potentiometers | ADCPOT | PTE6 | ADCPOT0 is routed to PTE6 – USER_ADC | |

6. S32M27xEVB-L064 – Default Jumpers



S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers

Table 2. S32M27xEVB-L064 - Default jumpers position.

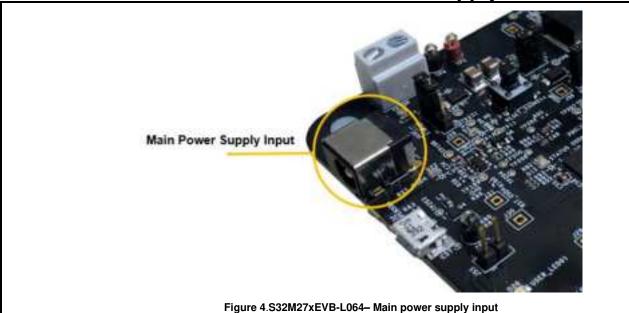
| Interface | Reference | Position | Description / Comments |
|---|-----------|----------|---|
| | J2 | 1-2 | VBAT is routed to VSUP |
| Power | J61 | 1-2 | VSUP is routed to VSUP_PERH |
| Supply | J1 | 1-2 | VSUP_MCU is routed to VSUP input of MCU |
| | J7 | 1-2 | Power LEDs to ground connection |
| Peripherals J23 | | 1-2 | VDD_MCU is connected to the VDD_MCU_PERH to supply SW peripherals (leds, buttons, user_adc) and CAN interface |
| LINPHY J51 1-2 VSUP_PERH connected to give robustness to the LIN in | | 1-2 | VSUP_PERH connected to give robustness to the LIN interface signal |

7. Power Supplies Options – Overview

The EVB requires an external power supply voltage of +12V/≥2A that can be connected in the connector J4 or J5. This allows the EVB to be easily used in a vehicle if required. The 12V input on the EVB is used to supply the microcontroller directly (VSUP) and the microcontroller generate an internally supply voltage (VDD_AE10, VDD_HV_A) with the input voltage from VPRE.

In this EVB the VSUP pin of the S32M2 is supplied a from VBAT (+12 V) after the protection and filtering phase of the board. VPRE voltage can be generated from VSUP internally or it can be either generated with an external power FET (gate controlled via GCTL pin), this last option was chosen in this EVB in order to reduce the power consumption and reduce the heat on the MCU.





S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers

Table 3. S32M27xEVB-L064 - Main power supply connector

| Connector | Description |
|--------------------------|--|
| Ground V+ (+12 Volts) | 2.1mm Barrel Connector – J4 This connector should be used to connect the supplied wall-plug main adapter. Note if a replacement or alternative adapter is used, care must be taken to ensure the 2.1mm plug uses the correct polarization as shown. |
| Ground V+ (12Volts). | 2-Way Screw Type Connector – J5 This can be used to connect a bare wire lead to the EVB, typically from a laboratory power supply. Care must be taken to ensure correct connection. For more details consult the schematic |

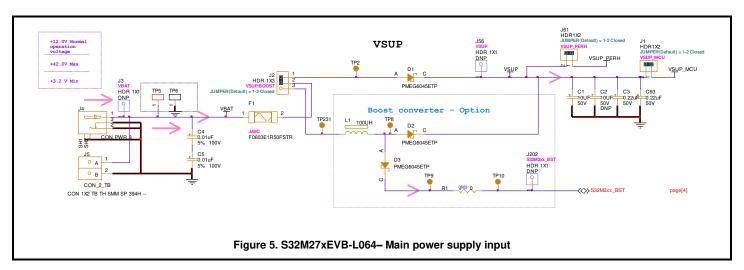


Table 4. S32M27xEVB-L064 – VSUP jumpers description.

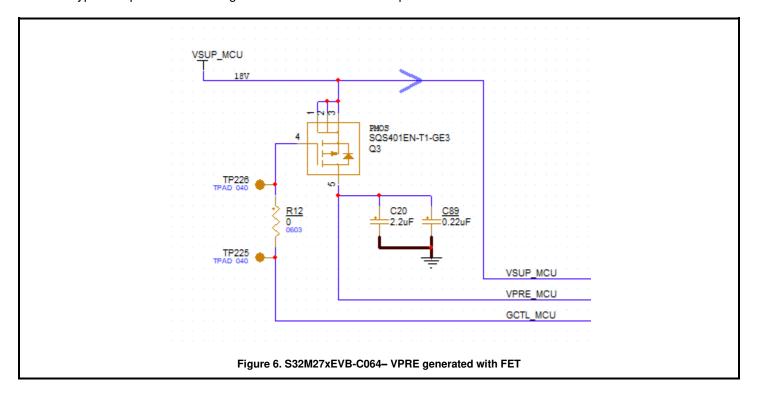
| Interface | Reference | Position | Description / Comments |
|-----------|-----------|----------------------------|--|
| | J2 | 1-2 (Default) | (Option A) This jumper configuration routes the output from the fuse (VBAT) to a protection diode and then the supply for peripherals and MCU after bulk and decoupling capacitors for the voltage input . |
| VSUP | J2 | 2-3 | (Option B) This jumper configuration routes the output from the fuse (VBAT) to a power boost converter circuit. For more details related to the boost converter circuit consult the S32M2 Hardware Design Guidelines |
| | J61 | 1-2 (Default closed) | This header is used to supply the peripherals like RESET LED, LINPHY and USER LEDS. |
| | J1 | 1-2 | This header is used to supply the VSUP input from the MCU. |

S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers

7.2 S32M27xEVB-L064 - VPRE

VPRE_MCU is typical 6V and generated from the VSUP_MCU. It can be either generated with an external power FET (gate controlled via GCTL pin) or generated by a PMC internal regulator. VPRE is always powered (FPM and LPM). An external bypass capacitor in the range from 2.2uF to 4.7uF is required.



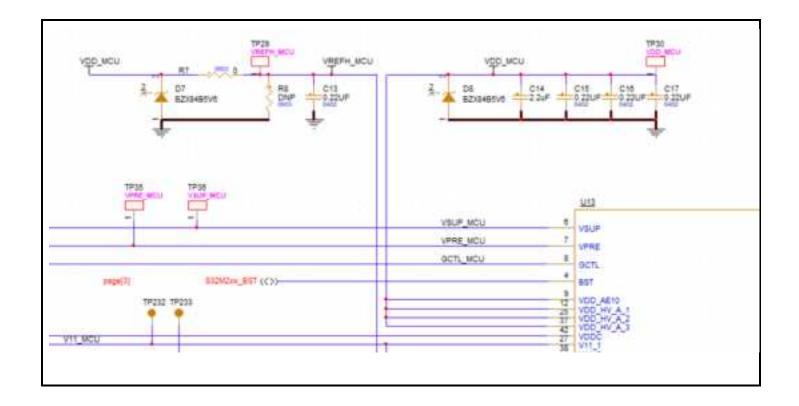
7.3 S32M27XEVB-L064 VDD HV A

As previously mentioned, the S32M276 is capable of internally regulating the voltage output of the VDD_HV_A_x pins, however it is mandatory to add an external bulk capacitor and one decoupling capacitor for each supply pin, for more details consult the S32M2XX Hardware Design Guidelines. In addition, the VDD_AE10 must be connected with VDD_HV_A pins to a common reference plane on PCB. The values of the decoupling and bulk capacitors are descripted in the

Table 5Error! Reference source not found.

Table 5. Decoupling and bulk capacitors value for VDD_HV_A pins

| Capacitor | Characteristic | Value |
|----------------------|-------------------|---------------|
| Decoupling Capacitor | X7R / X8R Ceramic | 100nf - 220nF |
| Bulk Capacitor | X7R / X8R Ceramic | 4.7uF - 2.2uF |



8. Motor Control Interface

The S32M27 integrates automotive qualified and application-focused capabilities like MOSFET Gate pre-drivers for motor control with 6 external power MOSFETs for BLDC or PMSM motor drive applications. The above due the S32M2XX MCU integrates a GDU which provides pre-drivers to control three-phase DC motor via external FETs. In order to support this control, it includes a charge pump and boost converter. The above replace a bootstrap circuit for gate driving.

The GDU contains three gate driver instances. Each instance drives 1 high-side FET (HG) and 1 low-side FET (LG). These high-side and low-side drivers support driving the three phases of a brushless DC motor. The primary function of a driver is to switch a MOSFET from off-state to on-state and vice versa. The pre-driver amplifies the control signals to the required levels to drive the power MOSFET. To guarantee reliable operation, the low-side drivers are supplied by the VLS regulator, while the high-side drivers are supplied directly by the bootstrap circuit over the VBS pins internally.

The outputs from the MOSFETs to the motor are connected to J47.

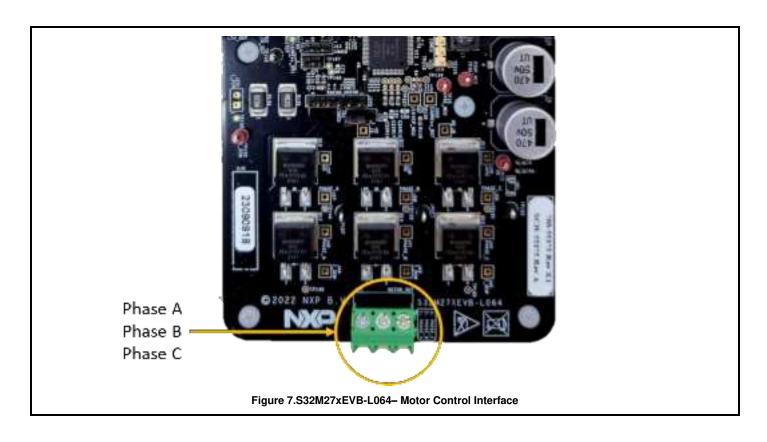
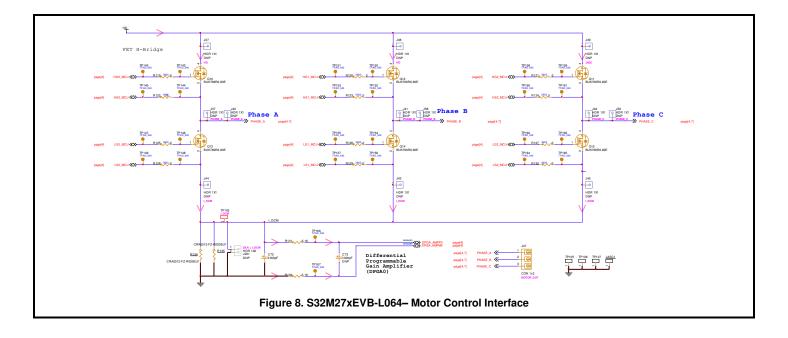


Table 6.- S32M27xEVB-C064 Motor control out

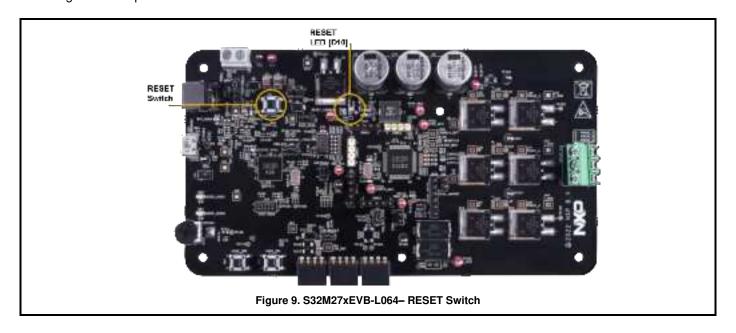
| Connector | Reference | Pin Number | Signal/Connection |
|-----------|-----------|---------------|-------------------|
| | J47 | 1 | PHASE A |
| | | 2 | PHASE B |
| A A A | | 3 | PHASE C |



9. S32M27xEVB-L064 – Programming and Debug Interface

9.1 S32M27xEVB-L064 - RESET switch and led indicator

The RESET switch [SW1] provides an input signal for manual application RESET. The S32M2 MCU will drive the RESET signal to the reset pins in the EVB [PTA5 and RESET]. The RESET LED indicator [D10] will be ON for the duration of the RESET signal. This operation indicates the S32M27 MCU is in the RESET state.

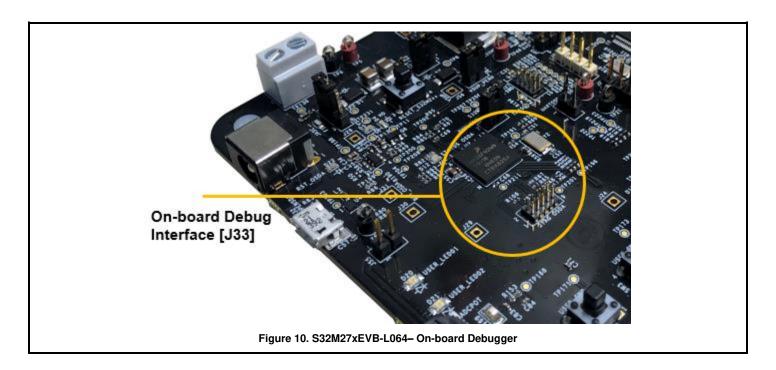


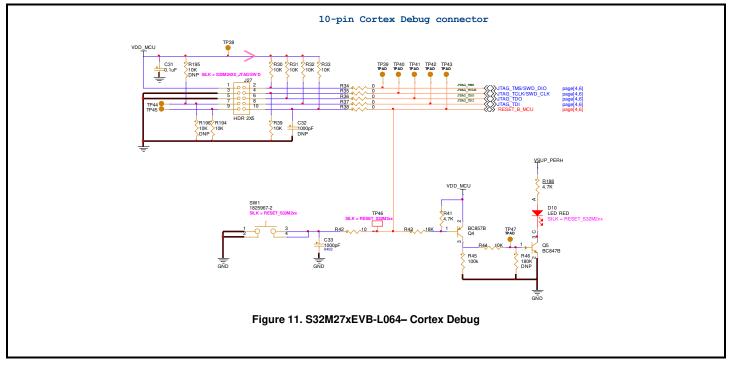
S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers

9.2 S32M27xEVB-L064 - On-board Debugger

The EVB incorporates an On-Board Debugger as well as embedded JTAG connectors. It bridges serial and debug communications between an USB host and an embedded target processor.





S32M27X-EVB-L064 HWUM

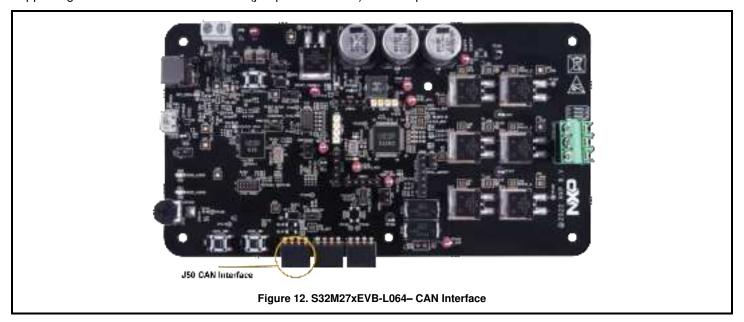
All Information provided in this document is subject to legal disclaimers

Table 7.- S32M27xEVB-C064 Cortex connector

| Connector | Reference | Pin Number | Signal/Connection | | | | | | | | | | | | | | | | | | | | | | | | |
|-----------|-----------|---------------|-------------------|--|--|--|--|--|--|--|--|--|---|----------|--|--|--|--|--|--|--|--|--|--|--|---|-----|
| | | 1 | VDD_MCU | | | | | | | | | | | | | | | | | | | | | | | | |
| | | 2 | JTAG_TMS/SWD_DIO | | | | | | | | | | | | | | | | | | | | | | | | |
| | | 3 | GND | | | | | | | | | | | | | | | | | | | | | | | | |
| 484 | J27 | 4 | JTAG_TCLK/SWD_CLK | | | | | | | | | | | | | | | | | | | | | | | | |
| LUMA | | 5 | GND | | | | | | | | | | | | | | | | | | | | | | | | |
| - | | 6 | JTAG_TDO | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | | | | | | | | | | | 7 | DNP |
| | | | | | | | | | | | | | 8 | JTAG_TDI | | | | | | | | | | | | | |
| | | 9 | GND | | | | | | | | | | | | | | | | | | | | | | | | |
| | | 10 | RESET_B_MCU | | | | | | | | | | | | | | | | | | | | | | | | |

10. S32M27xEVB-L064 - CAN PHY

The EVB incorporates a CAN interface connected to the S32M27 MCU. Using an NXP can transceiver the TJA1462, supporting both master and slave mode (jumper selectable). The output from the CAN transceiver is connected to J50.



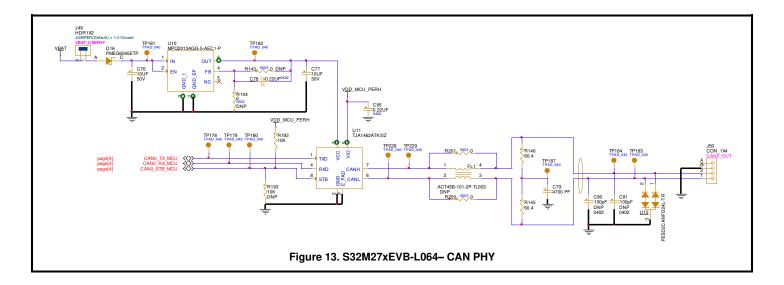
S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers

The pinout of these headers is shown below and is also displayed on the PCB silkscreen.

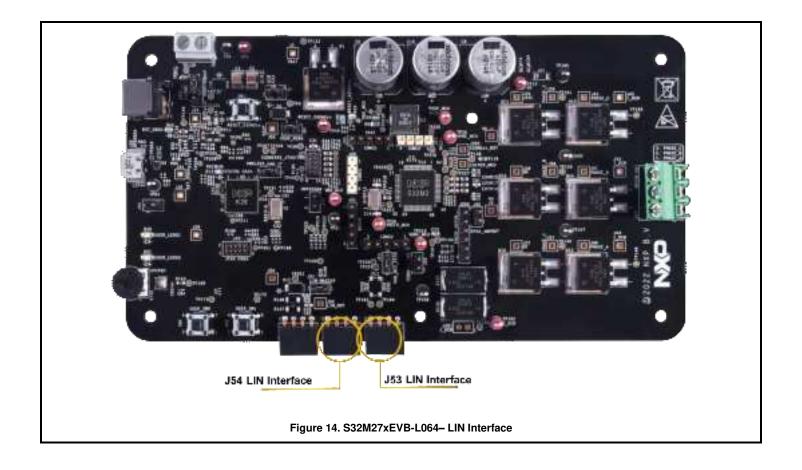
Table 8.- S32M27xEVB-L064 CAN Connector

| Connector | Reference | Pin Number | Signal/Connection |
|-----------|-----------|---------------|-------------------|
| | | 1 | CANL |
| | 150 | 2 | CANH |
| 1 2 1 | J50 | 3 | GND |
| | | 4 | NC |



11. S32M27xEVB-L064 – LIN PHY

The S32M27xEVB-L064 incorporates internally a LIN interface but is necessary connect the required circuitry to configure it as MASTER or SLAVE, the output signal is connected to J50 and J54.



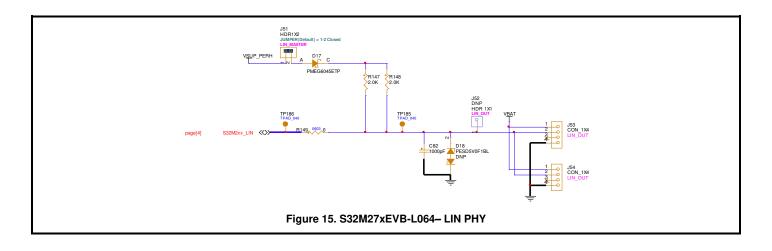
The pinout of these headers is shown below and is also displayed on the PCB silkscreen.

Table 9.- S32M27xEVB-L064 LIN Connector

| Connector | Reference | Pin Number | Signal/Connection |
|-----------|-----------|---------------|-------------------|
| | | 1 | VBAT |
| | J50 | 2 | LIN |
| 1 2 | J50 | 3 | NC |
| | | 4 | GND |
| | | 1 | VBAT |
| | J54 | 2 | LIN |
| 1 | | 3 | NC |
| | | 4 | GND |

S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers



12. S32M27xEVB-L064 – User Peripherals

12.1 S32M27xEVB-L064 - User Led

The EVB incorporates two red led connected through NPN transistors to the MCU ports. These are connected as follows:

Table 10.- S32M27xEVB-L064 LED connections

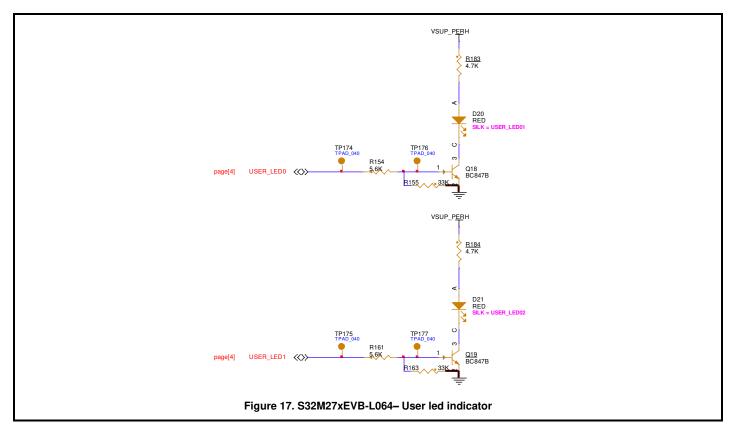
| Reference | Signal Name | MCU Port Default | Color |
|-----------|-------------|---------------------|-------|
| D20 | USER_LED0 | PTD15 | Red |
| D21 | USER_LED1 | PTD16 | Red |



Figure 16. S32M27xEVB-L064- User led indicator

S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers



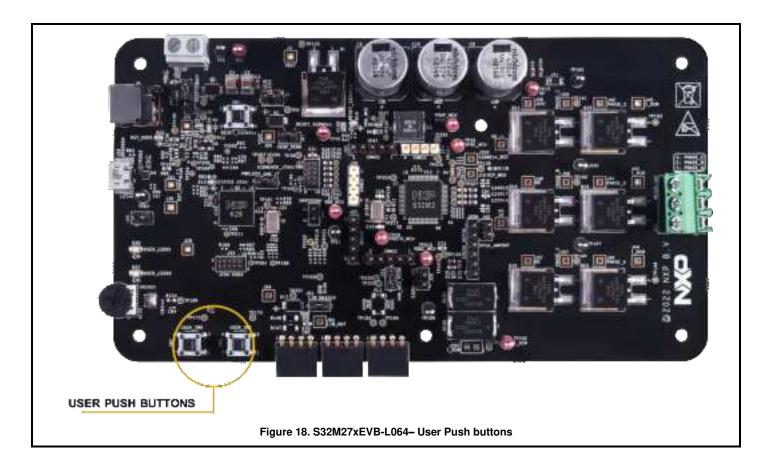
12.2 S32M27xEVB-L064 - User Push buttons

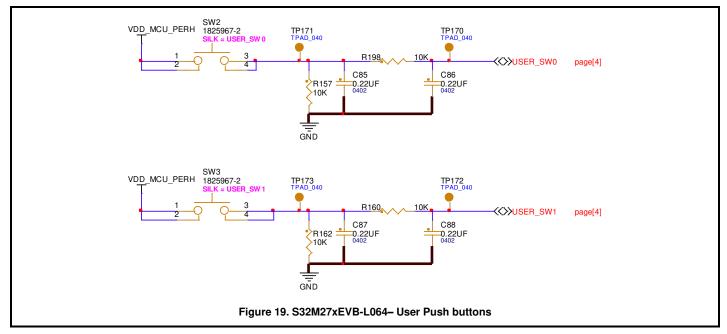
There are 2 push-buttons active high (pulled low, driven to VDD_MCU_PERH), the push button switches (SW2 and SW3) connected to MCU ports. The switches are connected as follows:

Table 11. User Pushbuttons

| Reference | Function | MCU Port | Comments |
|-----------|----------|-------------|----------|
| SW2 | USER_SW0 | PTA15 | Enabled |
| SW3 | USER_SW1 | PTD0 | Enabled |

^{1.} There are zero-ohm resistors (R181,R182) on the direct connections between each **USER_SWx** and the MCU pins. These can be removed if required to isolate or change the User Switch from the default MCU pin.



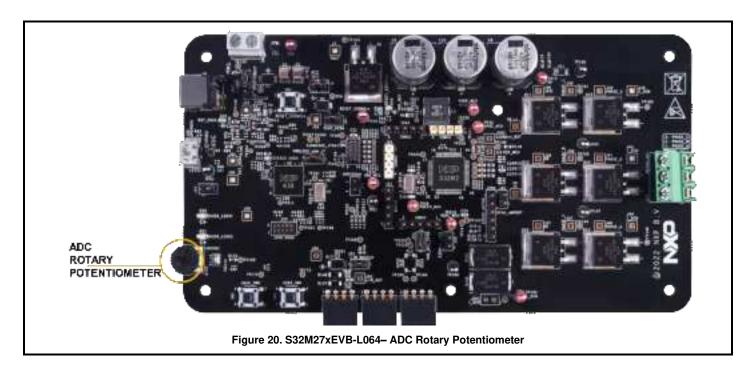


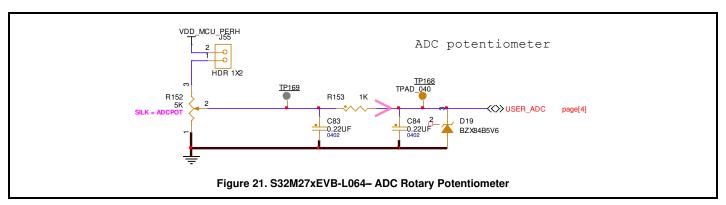
12.3 S32M27xEVB-L064 - ADC Rotary Potentiometer

The EVB incorporates an ADC Rotary Potentiometer (which routes a voltage between 0v to VDD_MCU_PERH) directly connected to ADC Input Channel of the S32M27 Microcontroller, specifically ADC1_P611.

Table 12. User ADC Potentiometer

| Reference | Function | MCU Port | Comments |
|-----------|----------|----------|----------|
| R152 | ADCPOT | PTE6 | Enabled |





S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers

13. S32M27xEVB-L064 – Revision history

Table 13. Revision history

| Document Revision | Date | Schematic/ Board Number | Schematic/ Board Revision | Changes | Author |
|----------------------|---------|----------------------------|---------------------------------|------------------|-----------|
| А | 01/2024 | 55375 | A | Internal version | Luis Rico |

14. Legal Information

14.1 Definitions

Draft — A draft status on a document indicates that the content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included in a draft version of a document and shall have no liability for the consequences of use of such information.

14.2 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors. In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory. Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Applications — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification. Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third-party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products. NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third-party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third-party customer(s). NXP does not accept any liability in this respect.

Suitability for use in automotive applications — This NXP Semiconductors product has been qualified for use in automotive applications. Unless otherwise agreed in writing, the product is not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

Export control — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Translations — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

Security — While NXP Semiconductors has implemented advanced security features, all products may be subject to unidentified vulnerabilities. Customers are responsible for the design and operation of their applications and products to reduce the effect of these vulnerabilities on customer's applications and products, and NXP Semiconductors accepts no liability for any vulnerability that is discovered. Customers should implement appropriate design and operating safeguards to minimize the risks associated with their applications and products.

14.3 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

NXP — wordmark and logo are trademarks of NXP B.V.

S32M27X-EVB-L064 HWUM

All Information provided in this document is subject to legal disclaimers