



High Availability SSO Deployment Guide for Cisco Catalyst 9800 Series Wireless Controllers, Cisco IOS XE Amsterdam 17.2

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Table of Contents

Introduction.....	4
Overview	4
Feature Description and Functional Behavior	4
Platforms Supported.....	5
SSO Pre-requisites.....	5
SSO on Cisco Catalyst C9800-40-K9 and C9800-80-K9 Wireless Controllers	5
Physical Connectivity for C9800-L, C9800-40 and C9800-80 Wireless Controller HA SSO.....	6
Connecting C9800-L Wireless Controllers using RJ-45 RP Port for SSO	6
Connecting C9800-40 and 9800-80 Wireless Controllers using RJ-45 RP Port for SSO	7
Connecting C9800-40 and 9800-80 Wireless Controllers using SFP Gigabit RP Port for SSO	7
Connecting a C9800 wireless controller HA pair to upstream switches.....	7
Option 1: Single VSS switch (or stack/VSL pair/modular switch) with RP back-to-back ...	8
Option 2: Single VSS switch (or stack/VSL pair/modular switch) with RP via upstream ...	8
Option 3: Dual Distributed switches with HSRP	9
Connecting a C9800 wireless controller HA pair to upstream switches with Release 17.1 and above.....	9
SSO on Cisco Catalyst C9800-CL running on ESXi, KVM, Hyper-V.....	10
Configuring High Availability SSO using GUI.....	10
Mobility MAC configuration.....	11
Configuring High Availability SSO using CLI.....	12
Active and Standby Election Process	12
State Transition for HA SSO Pair formation	13
Monitoring the HA Pair.....	15
Monitoring HA Pair from CLI.....	17
Verifying Redundancy States	18
Accessing standby wireless controller console.....	20
Switchover Functionality.....	21
Process Failure Switchover	21
Power-fail Switchover	21
Manual Switchover	21
Failover Process	22

Active wireless controller	22
Standby wireless controller	22
Verifying AP and Client SSO State Sync	23
SSO Failover Time Metrics.....	23
Redundancy Management Interface	23
Redundancy Management Interface Configuration using WebUI	24
Redundancy Management Interface Configuration using CLI	24
Verifying RMI and RP configuration	25
RMI and RP pairing combinations	26
Upgrade and HA Pairing with no previous HA config	26
Upgrade already Paired controllers.....	26
Downgrade	26
Default Gateway Check.....	27
Default Gateway Check WebUI Configuration	28
Default Gateway Check CLI Configuration.....	29
System and Network Fault Handling	29
HA Unpairing Behavior	34
LACP, PAGP support in SSO Pair	35
Supported LACP, PAGP topologies.....	35
Multi-chassis Link Aggregation group	36
<i>Starting with Release 17.2.1, Multi-chassis Link Aggregation Group is supported on a standalone as well as HA Pair of controllers. Multi-chassis LAG provides the capability to connect multiple uplinks from controller to separate uplink switches.</i>	36
Supported Multi-chassis LAG topologies.....	37
Supported Platforms:	37
Supported LAG Port Grouping	37
N+1 with SSO Hybrid deployment	38

Introduction

High availability has been a requirement on wireless controllers to minimize downtime in live networks. This document provides information on the theory of operation and configuration for the Catalyst 9800 Wireless Controller as it pertains to supporting stateful switchover of access points and clients (AP and Client SSO). Catalyst 9800 Wireless Controller is the next generation wireless controller that can run on multiple platforms with different scalability goals from low to high scale. AP and Client SSO is supported on the physical appliances and the virtual cloud platforms of the Catalyst 9800 Wireless Controller, namely C9800-L, C9800-40, C9800-80 and C9800-CL. The underlying SSO functionality is the same on all platforms with some differences in the setup process.

Overview

The High availability SSO capability on wireless controller allows the access point to establish a CAPWAP tunnel with the Active wireless controller and the Standby wireless controller to share a mirror copy of the AP and client database with the Standby wireless controller. The APs do not go into the Discovery state and clients do not disconnect when the Active wireless controller fails and the Standby wireless controller takes over the network as the Active wireless controller. There is only one CAPWAP tunnel maintained at a time between the APs and the wireless controller that is in an Active state.

Release 16.10 supports full access point and Client Stateful Switch Over. Client SSO is supported for clients which have already completed the authentication and DHCP phase and have started passing traffic. With Client SSO, a client's information is synced to the Standby wireless controller when the client associates to the wireless controller or the client's parameters change. Fully authenticated clients, i.e. the ones in Run state, are synced to the Standby and thus, client re-association is avoided on switchover making the failover seamless for the APs as well as for the clients, resulting in zero client service downtime and zero SSID outage. The overall goal for the addition of AP and client SSO support to the Catalyst 9800 Wireless controller is to reduce major downtime in wireless networks due to failure conditions that may occur due to box failover, network failover or power outage on the primary site.

Feature Description and Functional Behavior

All the control plane activities are centralized and synchronized between the active and standby units. The Active Controller centrally manages all the control and management communication. The network control data traffic is transparently switched from the standby unit to the active unit for centralized processing.

Bulk and Incremental configuration is synced between the two controllers at run-time and both controllers share the same IP address on the management interface. The CAPWAP state of the Access Points that are in Run State is also synced from the active wireless controller to the Hot-Standby wireless controller allowing the Access Points to be state-fully switched over when the Active wireless controller fails. The APs do not go to the Discovery state when Active wireless controller fails, and Standby wireless controller takes over as the Active wireless controller to serve the network.

The two units form a peer connection through a dedicated RP port (this can be a physical copper or fiber port) or a virtual interface for the VM. The Active/Standby election happens at boot time and it's either based on the highest priority (priority range is <1-2>) or the lowest MAC if the priority is the same. By default the C9800 has a priority of 1. Once the HA pair is formed, all the configuration and AP and client databases are synced between Active and standby. Any configuration is done on the Active is automatically synch to the Standby. The standby is continuously monitoring the Active via keepalives over the RP link. If the Active becomes unavailable, the standby assumes the role of Active. It does that by sending a Gratuitous ARP message advertising to the network that it now owns that wireless management IP address. All the configurations and databases are already in synch, so the standby can take over without service disruption

Platforms Supported

There is no pre-empt functionality with SSO meaning that when the previous Active wireless controller resumes operation, it will not take back the role as an Active wireless controller but will negotiate its state with the current Active wireless controller and transition to Hot-Standby state.

Platforms Supported

- Cisco Catalyst C9800-40 Wireless Controller
- Cisco Catalyst C9800-80 Wireless Controller
- Cisco Catalyst C9800-CL Wireless Controller
- Cisco Catalyst C9800-L Wireless Controller

SSO Pre-requisites

- HA Pair can only be form between two wireless controllers of the same form factor
- Both controllers must be running the same software version in order to form the HA Pair
- Maximum RP link latency = 80 ms RTT, minimum bandwidth = 60 Mbps and minimum MTU = 1500

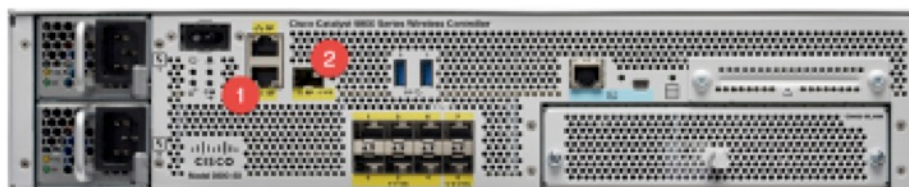
SSO on Cisco Catalyst C9800-40-K9 and C9800-80-K9 Wireless Controllers

The Cisco C9800-40-K9 wireless controller is an extensible and high performing wireless controller, which can scale up to 2000 access points and 32000 clients. The controller has four 10G data ports and a throughput of 40G.



1	RP– RJ-45 1G redundancy Ethernet port.	2	Gigabit SFP RP port
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The Cisco C9800-80-K9 Wireless Controller is a 100G wireless controller that occupies two rack unit space and supports a pluggable Module slot, and eight built-in 10GE/1GE interfaces.



1	RP– RJ-45 1G redundancy Ethernet port.	2	Gigabit SFP RP port
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Both C9800-40-K9 and C9800-80-K9 Wireless controllers have two RP Ports as shown in the figures above:

- RJ-45 Ethernet Redundancy port
- SFP Gigabit Redundancy Port

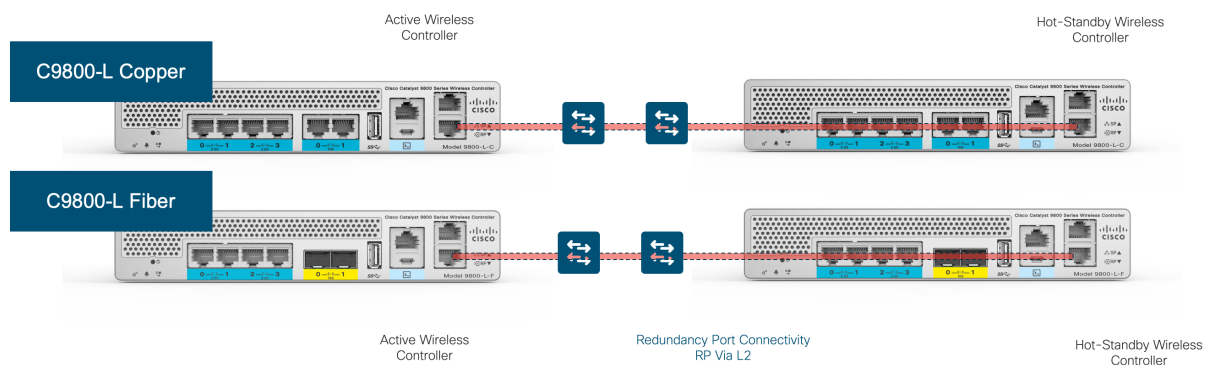
If both the Redundancy Ports are connected:

- SFP Gigabit Ethernet port takes precedence if they are connected at same time.
- HA between RJ-45 and SFP Gigabit RP ports is not supported.
- Only Cisco supported SFPs (GLC-LH-SMD and GLC-SX-MMD) are supported for RP port
- 10G SFP-10G-SR is not supported on the RP port.
- When HA link is up via RJ-45, SFPs on HA port should not be inserted even if there is no link between them. As it is a physical level detection, this would cause the HA to go down as precedence is given to SFP

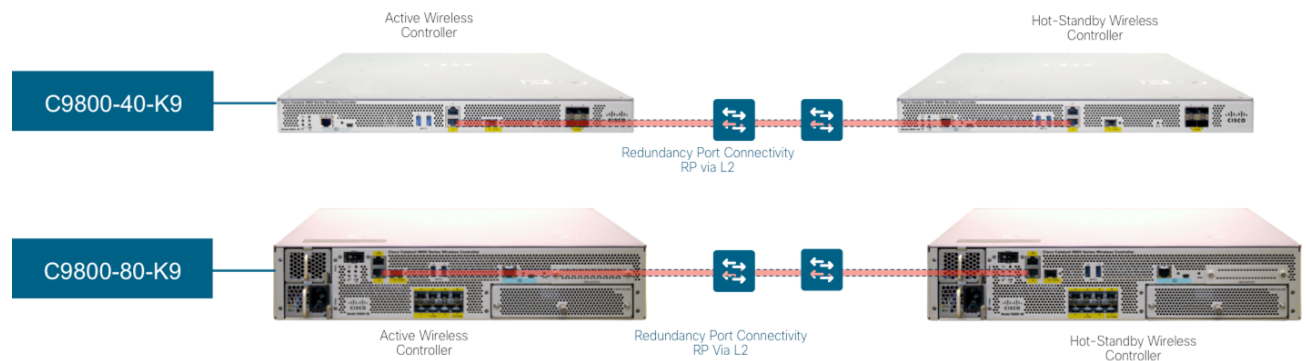
Physical Connectivity for C9800-L, C9800-40 and C9800-80 Wireless Controller HA SSO

The HA Pair always has one active controller and one standby controller. If the active controller becomes unavailable, the standby assumes the role of the active. The Active wireless controller creates and updates all the wireless information and constantly synchronizes that information with the standby controller. If the active wireless controller fails, the standby wireless controller assumes the role of the active wireless controller and continues to keep the HA Pair operational. Access Points and clients continue to remain connected during an active-to-standby switchover.

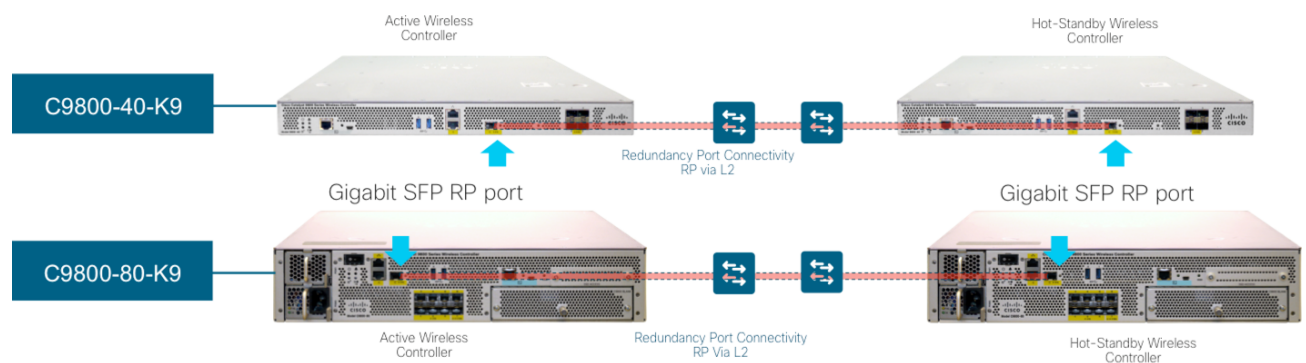
Connecting C9800-L Wireless Controllers using RJ-45 RP Port for SSO



Connecting C9800-40 and 9800-80 Wireless Controllers using RJ-45 RP Port for SSO



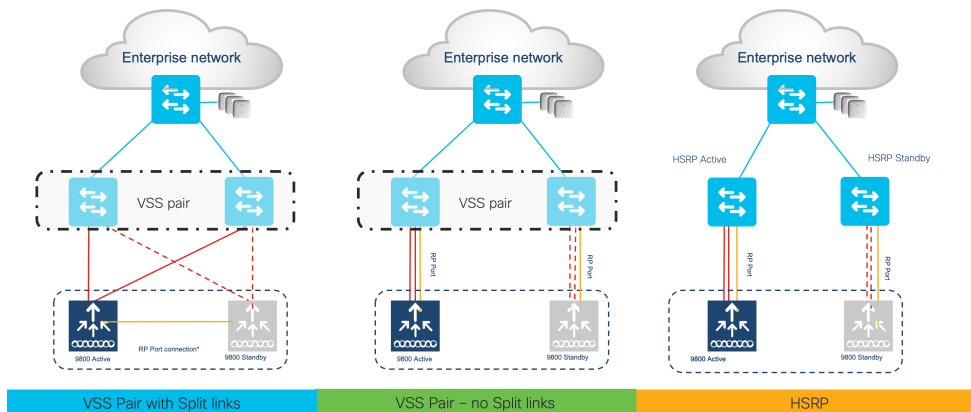
Connecting C9800-40 and 9800-80 Wireless Controllers using SFP Gigabit RP Port for SSO



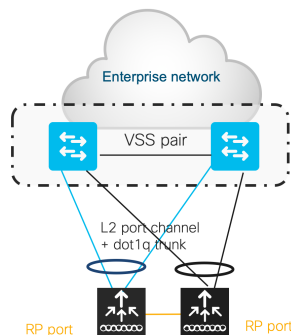
Connecting a C9800 wireless controller HA pair to upstream switches

Prior to 17.1 following topologies were supported in terms of upstream connectivity to the network:

1. SSO pair connected to upstream VSS pair with split links and RP connected back to back.
2. SSO pair connected to upstream VSS pair with RP connected via the upstream set of switches in order to detect gateway down scenario.
3. SSO pair connected to upstream HSRP active and standby and RP connected via upstream set of switches in order to detect gateway down scenario.



Option 1: Single VSS switch (or stack/VSL pair/modular switch) with RP back-to-back

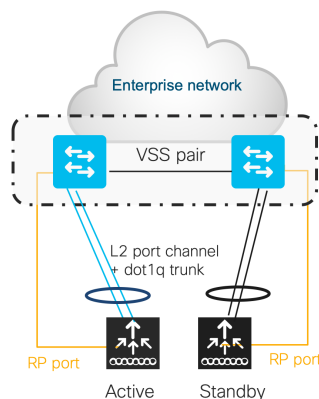


Single L2 port-channel on each box and enable dot1q to carry multiple VLANs. Spread the uplinks of the HA pair across the VSS pair and connect the RP back to back (no L2 network in between). Make sure that switch can scale in terms of ARP and MAC table entries.

This is a recommended topology.

Note: In HA SSO topology only LAG with mode ON is supported.

Option 2: Single VSS switch (or stack/VSL pair/modular switch) with RP via upstream



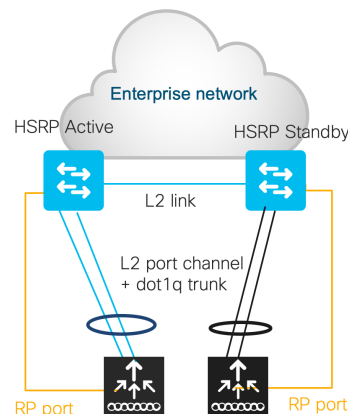
Connecting a C9800 wireless controller HA pair to upstream switches with Release 17.1 and above

With this topology a single L2 port-channel is created on each box. Enable dot1q to carry multiple VLANs and connect the standby in the same manner. Make sure that switch can scale in terms of ARP and MAC table entries

IMPORTANT: In this topology the links are not spread across the VSS stack. Connect RP port to the same VSS/stack member as the uplinks and not back to back

Note: In HA SSO topology only LAG with mode ON is supported.

Option 3: Dual Distributed switches with HSRP



With this topology a single L2 port-channel is created on each box. Enable dot1q to carry multiple VLANs and connect the standby in the same manner. Make sure that switch can scale in terms of ARP and MAC table entries.

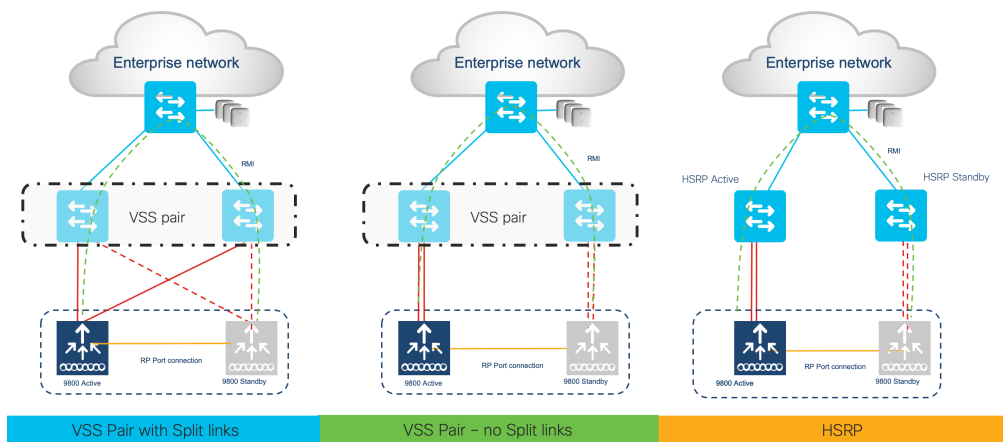
IMPORTANT: Connect RP port to the same distribution switch as the uplinks and not back to back

Note: In HA SSO topology only LAG with mode ON is supported prior to release 17.1. With 17.1, we additionally support LACP and PAGP. See the [LACP](#), [PAGP support in SSO Pair](#) section for more details

Connecting a C9800 wireless controller HA pair to upstream switches with Release 17.1 and above

With the option of RMI and default gateway check feature available in release 17.1, the following topologies are now supported and recommended:

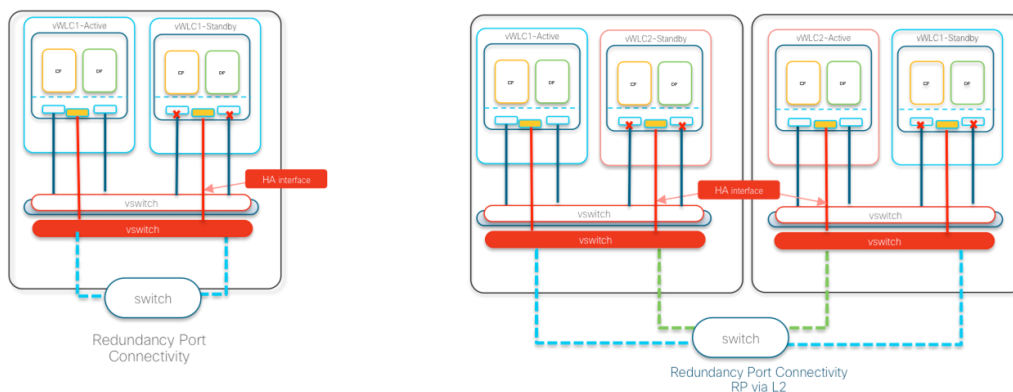
1. SSO pair connected to upstream VSS pair with split links and RP connected back to back.
2. SSO pair connected to upstream VSS pair and RP connected back to back.
3. SSO pair connected to upstream HSRP active and standby and RP connected back to back.



Note: It is recommended to configure portfast trunk in uplink switches for faster convergence using CLI "spanning-tree port type edge trunk" or "spanning-tree portfast trunk"

SSO on Cisco Catalyst C9800-CL running on ESXi, KVM, Hyper-V

The Virtual Catalyst 9800 Wireless controller can be deployed as an HA Pair in a single or dual server setup.



The figure on the left shows Redundant port connected on the same server.

The figure on the right shows Redundant port L2 connected to a separate server.

Configuring High Availability SSO using GUI

Device redundancy can be configured from **the Administration > Device > Redundancy** page

On the Active controller, the priority is set to a higher value than the standby controller. The wireless controller with the higher priority value is selected as the active during the active-standby election process. The Remote IP is the IP address of the standby controller's redundancy port IP.

Mobility MAC configuration

Search Menu Items

Dashboard

Monitoring

Configuration

Administration

Troubleshooting

Device

General

FTP/TFTP

Wireless

Redundancy

Clear Redundancy Config

Local IP*

Netmask*

Remote IP*

Peer Timeout State*

Timer value (milliseconds)*

Active Chassis Priority*

Apply to Device

Note: This page has changed starting release 17.1 to include an option to configure the HA pair using RMI. Please refer to the Redundancy Management Interface section to see the updated screens for configuration.

On the standby controller, the remote IP is set to the Active controller's redundancy port IP

Search Menu Items

Dashboard

Monitoring

Configuration

Administration

Troubleshooting

Device

General

FTP/TFTP

Wireless

Redundancy

Clear Redundancy Config

Local IP*

Netmask*

Remote IP*

Peer Timeout State*

Timer value (milliseconds)*

Active Chassis Priority*

Apply to Device

- 1) Both IP address for the Local and Remote IP must be in the same subnet.
- 2) It is suggested to use the 169.254.X.X/16 subnet. The last two octets can be derived from last two octets of the management interface.
- 3) Avoid using 10.10.10.x/24 subnet for the RP port due to defect in 9800 WLC.

Clear Redundancy config clears the SSO configuration and returns the controller to standalone mode.

Note: It is recommended to configure HA using the Redundancy Management Interface (RMI) starting Release 17.1. To see configuration using RMI please see the Redundancy Management Interface section.

Mobility MAC configuration

Ensure that you configure the mobility MAC address using the wireless mobility mac-address command for High-Availability to work.

Configuring High Availability SSO using CLI

```
WLC (config)#wireless mobility mac-address ?  
H.H.H Enter Mac Address for the mobility messages
```

Configuring High Availability SSO using CLI

- **On Virtual Catalyst 9800 Wireless controller**, enable High Availability SSO using the following command on each of the two virtual Catalyst 9800 Wireless controller instances

```
chassis redundancy ha-interface <RP interface> local-ip <local IP> <local IP subnet>  
remote-ip <remote IP>
```

e.g.

On Virtual Catalyst 9800 Wireless controller instance-1:

```
chassis redundancy ha-interface Gig 3 local-ip 172.23.174.85 /24 remote-  
ip 172.23.174.86
```

On Virtual Catalyst 9800 Wireless controller instance-2:

```
chassis redundancy ha-interface Gig 3 local-ip 172.23.174.86 /24 remote-  
ip 172.23.174.85
```

- **On C9800-40 and C9800-80 wireless controller**, enable High Availability SSO using the following command on each of the two wireless controller units

```
chassis redundancy ha-interface local-ip <local IP> <local IP subnet> remote-  
ip <remote IP>
```

Reload both wireless controllers by executing the command reload from the CLI

Note: It is recommended to configure HA using the Redundancy Management Interface (RMI) starting Release 17.1. To see configuration using RMI please see the Redundancy Management Interface section.

Active and Standby Election Process

An active C9800 wireless controller retains its role as an Active Controller unless one of the following events occur:

- The wireless controller HA pair is reset.
- The active wireless controller is removed from the HA pair.
- The active wireless controller is reset or powered off.
- The active wireless controller fails.

The active wireless controller is elected or re-elected based on one of these factors and in the order listed below:

1. The wireless controller that is currently the active wireless controller.
2. The wireless controller with the highest priority value.

Note: We recommend assigning the highest priority value to the wireless controller C9800 you prefer to be the active controller. A value of 2 would be the highest value and would be placed on the controller that you want to be the primary (since we only allow 1 or 2).

Setting the Switch Priority Value

```
chassis chassis -number priority new-priority-number
```

Chassis-number Specifies the chassis number and the new priority for the chassis. The chassis number range is 1 to 2.

The priority value range is <1-2>

Example

```
wireless controller#chassis 1 priority 2
```

You can display the current priority value by using the **show chassis** user EXEC command. The new priority value takes effect immediately but does not affect the current Active Controller. The new priority value helps determine which controller is elected as the new Active Controller when the current active wireless controller or HA redundant pair reloads.

3. The wireless controller with the shortest start-up time.
4. The wireless controller with the lowest MAC Address.

The HA LED on the chassis can be used to identify the current Active Controller.

State Transition for HA SSO Pair formation

1. Active wireless controller in Non Redundant mode

```
TLV(0): T=9, L=29, V=KEY_TLV_PACKAGE_COMPATIBILITY
FRU Key detected
TLV(1): T=9, L=11, V=FRU_RP_TYPE
found package fru type FRU_RP_TYPE
TLV(2): T=9, L=24, V=KEY_TLV_PACKAGE_BOOTARCH
ARCH Key detected
TLV(3): T=9, L=14, V=ARCH_i686_TYPE
found package arch type ARCH_i686_TYPE
TLV(4): T=9, L=20, V=KEY_TLV_BOARD_COMPAT
TLV(5): T=9, L=15, V=BOARD_qwlc_TYPE
TLV(6): T=9, L=24, V=KEY_TLV_CRYPTO_KEYSTRING
TLV(7): T=9, L=4, V=none
TLV(8): T=9, L=11, V=CW_BEGIN=$$
TLV(9): T=9, L=16, V=CW_FAMILY=$qwlc$
TLV(10): T=9, L=78, V=CW_IMAGE=$qwlc-universalk9_wlc.BLD_POLARIS_DEV_LATEST_20180310_120257.SSA.bin$
TLV(11): T=9, L=19, V=CW_VERSION=$16.9.1$
TLV(12): T=9, L=52, V=CW_DESCRIPTION=$Cisco IOS Software, IOS-XE Software$
TLV(13): T=9, L=9, V=CW_END=$$
found DIGISIGN TLV type 12 length = 388

RSA Signed DEVELOPMENT Image Signature Verification Successful.
Validating subpackage signatures: addr=0x6e13e3f8, size=01c789ed

initramfs_size: 0x1c78dcd - 0x4b0a38 - 0x3e0 = 0x17c7fb5
Image validated
Booting image with bootparam="root=/dev/ram rw console=tty1 max_loop=64 pciehp.pciehp.force pcie_ports=native SR_BOOT=tftp://172.25.140.118/auto/
tftpboot/maahmed/qwlc-universalk9_wlc.BLD_POLARIS_DEV_LATEST_20180310_120257.SSA.bin rd_start=0xaf06e000 rd_size=0x17c7fb5 pkg_start=0x33f68000
pkg_size=0x3a1d4000 bdfinfo_start=0xcd42b000 bdfinfo_size=0x35c34"
May 3 15:13:22.585: %BOOT-0-DRV_LOADFAIL: R0/0: binos: Failed to load driver modprobe ( /usr/binos/conf/driver_common.sh: line 99: indigowr:
command not found )
May 3 15:13:43.295: %PMAN-3-PROC_EMPTY_EXEC_FILE: R0/0: pvp: Empty executable used for process bt_logger
May 3 15:13:45.742: %PMAN-3-PROC_EMPTY_EXEC_FILE: R0/0: pvp: Empty executable used for process bt_logger
Waiting for remote chassis to join
```

2. Standby Insertion for HA Pairing

State Transition for HA SSO Pair formation

```
Chassis number is 1
All chassis in the stack have been discovered. Accelerating discovery
May 3 15:13:46.276: %PMAN-3-PROC_EMPTY_EXEC_FILE: R0/0: pvp: Empty executable used for process bt_logger
May 3 15:13:46.877: %PMAN-3-PROC_EMPTY_EXEC_FILE: R0/0: pvp: Empty executable used for process bt_logger
May 3 15:13:48.852: %PMAN-3-PROC_EMPTY_EXEC_FILE: R0/0: pvp: Empty executable used for process bt_logger
May 3 15:13:53.654: %PMAN-3-PROC_EMPTY_EXEC_FILE: R0/0: pvp: Empty executable used for process bt_logger
May 3 15:13:56.934: %PMAN-3-PROC_EMPTY_EXEC_FILE: R0/0: pvp: Empty executable used for process bt_logger
```

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San Jose, California 95134-1706

3. HA Sync in Progress

```
directory.
*May 3 15:13:52.681: %STACKMGR-6-STACK_LINK_CHANGE: Chassis 2 R0/0: stack_mgr: Stack port 2 on Chassis 1 is down
*May 3 15:13:52.681: %STACKMGR-6-STACK_LINK_CHANGE: Chassis 2 R0/0: stack_mgr: Stack port 1 on Chassis 1 is up
*May 3 15:13:52.681: %STACKMGR-6-STACK_LINK_CHANGE: Chassis 2 R0/0: stack_mgr: Stack port 2 on Chassis 1 is up
*May 3 15:13:52.682: %STACKMGR-6-CHASSIS_ADDED: Chassis 2 R0/0: stack_mgr: Chassis 2 has been added to the stack.
*May 3 15:13:52.682: %STACKMGR-6-CHASSIS_ADDED: Chassis 2 R0/0: stack_mgr: Chassis 2 has been added to the stack.
*May 3 15:13:52.682: %STACKMGR-6-ACTIVE_ELECTED: Chassis 2 R0/0: stack_mgr: Chassis 2 has been elected ACTIVE.
*May 3 15:13:52.682: %CMP-3-PFU_MISSING: Chassis 2 R0/0: cmd: The platform does not detect a power supply in slot 1
*May 3 15:14:41.704: %SYS-4-FREEMEMWARNING: SIP0/0: Free Memory has dropped below warning threshold.
*May 3 15:14:46.405: %SYS-6-BOOTTIME: Time taken to reboot after reload = 1073 seconds
*May 3 15:14:46.761: %PNP-6-PNP_DISCOVERY_STOPPED: PnP Discovery stopped (Startup Config Present)
*May 3 15:14:46.789: %SPA_OIR-6-ONLINECARD: SPA (BUILT-IN-4X10G/1G) online in subslot 0/0
*May 3 15:14:46.883: %IOSXE_SPA-6-UPDOWN: Interface TenGigabitEthernet0/0/0, link down due to local fault
*May 3 15:14:46.937: %IOSXE_SPA-6-UPDOWN: Interface TenGigabitEthernet0/0/1, link down due to local fault
*May 3 15:14:46.977: %IOSXE_SPA-6-UPDOWN: Interface TenGigabitEthernet0/0/2, link down due to local fault
*May 3 15:14:47.040: %IOSXE_SPA-6-UPDOWN: Interface TenGigabitEthernet0/0/3, link down due to local fault
*May 3 15:14:48.780: %LINK-3-UPDOWN: Interface TenGigabitEthernet0/0/1, changed state to down
*May 3 15:14:48.783: %LINK-3-UPDOWN: Interface TenGigabitEthernet0/0/2, changed state to down
*May 3 15:14:48.784: %LINK-3-UPDOWN: Interface TenGigabitEthernet0/0/3, changed state to down
*May 3 15:14:49.217: %IOSXE_SPA-6-UPDOWN: Interface TenGigabitEthernet0/0/0, link down due to remote fault
*May 3 15:14:49.032: %LINK-3-UPDOWN: SIP0/0: Interface TenGigabitEthernet0/0/0, changed state to down
*May 3 15:14:49.652: %LINK-3-UPDOWN: Interface TenGigabitEthernet0/0/0, changed state to down
*May 3 15:14:50.043: %LINK-3-UPDOWN: Interface GigabitEthernet0, changed state to up
*May 3 15:14:51.043: %LINEPROTO-5-UPDOWN: Line protocol on Interface GigabitEthernet0, changed state to up
*May 3 15:14:54.229: %PKI-2-NON_AUTHORITATIVE_CLOCK: PKI functions can not be initialized until an authoritative time source, like NTP, can be obtained.
*May 3 15:14:55.456: %LINK-3-UPDOWN: Interface TenGigabitEthernet0/0/0, changed state to up
*May 3 15:14:55.458: %LINK-3-UPDOWN: Interface Vlan1, changed state to down
*May 3 15:14:55.456: %LINK-3-UPDOWN: SIP0/0: Interface TenGigabitEthernet0/0/0, changed state to up
*May 3 15:14:57.892: %LINEPROTO-5-UPDOWN: Line protocol on Interface TenGigabitEthernet0/0/0, changed state to up
*May 3 15:14:58.891: %LINK-3-UPDOWN: Interface Vlan1, changed state to up
*May 3 15:14:58.892: %LINEPROTO-5-UPDOWN: Line protocol on Interface Vlan1, changed state to up
*May 3 15:15:09.367: %IOSXE_REDUNDANCY-6-PEER: Active detected chassis 2 as standby.
*May 3 15:15:09.365: %STACKMGR-6-STANDBY_ELECTED: Chassis 1 R0/0: stack_mgr: Chassis 2 has been elected STANDBY.
*May 3 15:15:09.652: %PMAN-3-PROC_EMPTY_EXEC_FILE: Chassis 2 R0/0: pvp: Empty executable used for process bt_logger
*May 3 15:15:10.140: %PMAN-3-PROC_EMPTY_EXEC_FILE: Chassis 2 R0/0: pvp: Empty executable used for process ngiolt
*May 3 15:15:14.751: %IOSXE_PEM-6-INSPEM_FM: PEM/FM slot P0 inserted
*May 3 15:15:14.754: %IOSXE_PEM-6-PEMOK: The PEM in slot P0 is functioning properly
*May 3 15:15:14.754: %IOSXE_PEM-6-INSPEM_FM: PEM/FM slot P2 inserted
*May 3 15:15:14.758: %IOSXE_PEM-6-PEMOK: The PEM in slot P2 is functioning properly
WLC>

WLC#
*May 3 15:15:39.434: %REDUNDANCY-5-PEER_MONITOR_EVENT: Active detected a standby insertion (raw-event=PEER_FOUND(4))

*May 3 15:15:39.434: %REDUNDANCY-5-PEER_MONITOR_EVENT: Active detected a standby insertion (raw-event=PEER_REDUNDANCY_STATE_CHANGE(5))

*May 3 15:15:41.404: % Redundancy mode change to SSO

*May 3 15:15:41.404: %VOICE_HA-7-STATUS: NONE-->SSO; SSO mode will not take effect until after a platform reload.
*May 3 15:15:44.413: Syncing vlan database
*May 3 15:15:44.436: Vlan Database sync done from bootflash:vlan.dat to stby-bootflash:vlan.dat (1464 bytes)
WLC#
WLC#
WLC#
WLC#
WLC#
WLC#
WLC#show chas
WLC#show chassis
Chassis/Stack Mac Address : 00a3.8e23.8769 - Local Mac Address
Mac persistency wait time: Indefinite
Local Redundancy Port Type: Twisted Pair

Chassis# Role Mac Address Priority H/W Current State IP
-----
*1 Active 00a3.8e23.8769 1 V02 Ready 172.20.226.134
2 Standby 00a3.8e23.8909 1 V02 HA sync in progress 172.20.226.133
```

4. Terminal State for SSO

Monitoring the HA Pair

```
*May 3 15:18:46.564: %HA_CONFIG_SYNC-6-BULK_CFGSYNC_SUCCEEDED: Bulk Sync succee
*May 3 15:18:46.565: %VOICE_HA-7-STATUS: VOICE HA bulk sync done.
*May 3 15:18:47.565: %RF-5-RF_TERMINAL_STATE: Terminal state reached for (SSO)
```

WLC#show chassis

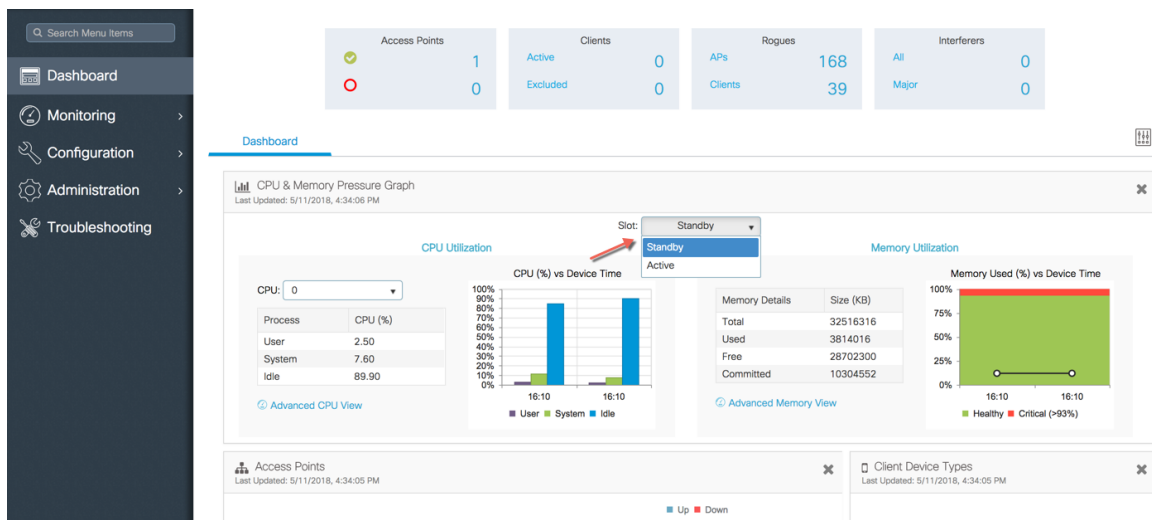
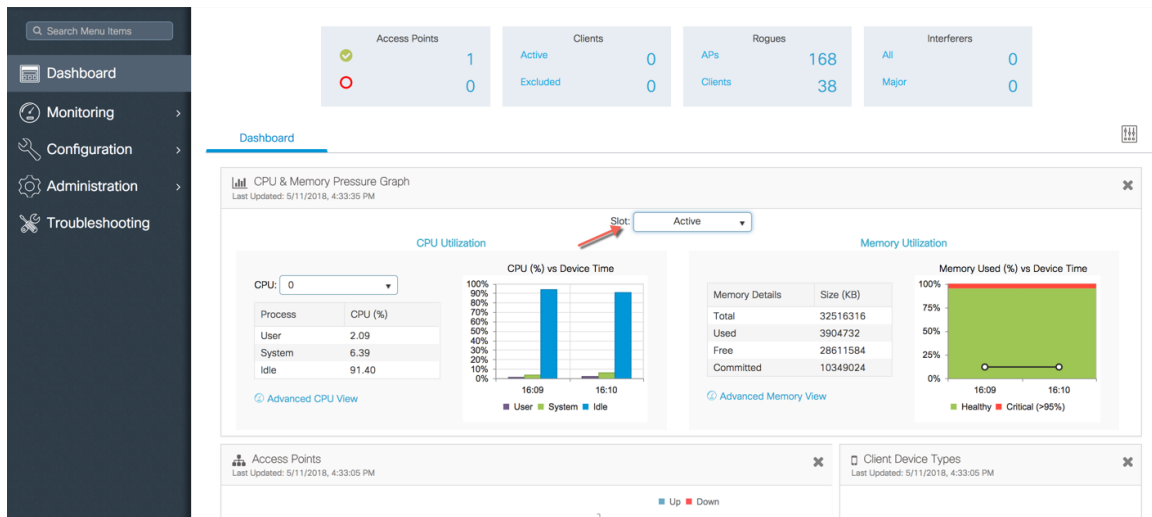
Chassis/Stack Mac Address : 00a3.8e23.8769 - Local Mac Address
Mac persistency wait time: Indefinite
Local Redundancy Port Type: Twisted Pair

Chassis#	Role	Mac Address	Priority	Version	H/W	Current State	IP
*1	Active		1	V02		Ready	
2	Standby		1	V02		Ready	

Note: Breaking the HA Pair : The HA configuration can be disabled by using the chassis clear command followed by a reload

Monitoring the HA Pair

Both Active and Standby System can be monitored from the Management UI of the Active wireless controller. This includes information about CPU and memory utilization as well and advanced CPU and memory views.



Navigate to Monitoring > System > Redundancy on the controller Web UI. The Redundancy States page is

displayed:

The screenshot displays the 'System' configuration page for a Cisco Catalyst 9800, specifically the 'Redundancy' tab. The left sidebar contains navigation links: Dashboard, Monitoring, Configuration, Administration, and Troubleshooting. The main content area shows various system parameters. A red box highlights the 'My State' (13 -ACTIVE) and 'Peer State' (8 -STANDBY HOT) fields. Below this, a table shows the redundancy history. The table has columns: Index, Previous Active, Current Active, Switch Over Time, and Switch Over Reason. The table contains one row with index 1, previous active 1, current active 2, switch over time 18:16:37 UTC Thu May 10 2018, and switch over reason user forced.

Index	Previous Active	Current Active	Switch Over Time	Switch Over Reason
1	1	2	18:16:37 UTC Thu May 10 2018	user forced

Parameter	Description
My State	Shows the state of the active CPU controller module. Values are as follows: Active Standby HOT Disable
Peer State	Displays the state of the peer (or standby) CPU controller module. Values are as follows: Standby HOT Disable
Mode	Displays the current state of the redundancy peer. Values are as follows: Simplex– Single CPU controller module. Duplex– Two CPU controller modules.
Unit ID	Displays the unit ID of the CPU controller module.

Redundancy Mode (Operational)	Displays the current operational redundancy mode supported on the unit.
Redundancy Mode (Configured)	Displays the current configured redundancy mode supported on the unit.
Redundancy State	Displays the current functioning redundancy state of the unit. Values are as follows: SSO Not Redundant
Manual Swact	Displays whether manual switchovers have been enabled.
Communications	Displays whether communications are up or down between the two controllers.

The same page displays Switchover history. The description for the following parameters are displayed in the table below:

Parameter	Description
Index	Displays the index number of the redundant unit.
Previous Active	Displays the controller that was active prior to switchover.
Current Active	Displays the controller that is currently active.
Switch Over Time	Displays the system time when the switchover occurred.
Switch Over Reason	Displays the cause of the switchover.

Monitoring HA Pair from CLI

The command `show chassis` displays summary information about the HA Pair, including the MAC address, role, switch priority, and current state of each wireless controller in the redundant HA pair. By default, the Local MAC Address of the HA Pair is the MAC address of the first elected Active Controller.

```
WLC#show chassis
Chassis/Stack Mac Address : 00a3.8e23.8760 - Local Mac Address
Mac persistency wait time: Indefinite
Local Redundancy Port Type: Twisted Pair
```

Chassis#	Role	Mac Address	Priority	H/W Version	Current State	IP
1	Standby	00a3.8e23.8760	1	V02	Ready	172.20.226.133
*2	Active	00a3.8e23.8900	1	V02	Ready	172.20.226.134

The `show chassis` command points to the current C9800 wireless controller on the console using the (*) symbol against the chassis number as shown above.

Verifying Redundancy States

- The command `show redundancy` can be used to monitor the state of the two units

```
wireless controller#show redundancy ?
application      box 2 box application information
clients          Redundancy Facility (RF) client list
config-sync      Show Redundancy Config Sync status
counters         Redundancy Facility (RF) operational counters
domain           Specify the RF domain
history          Redundancy Facility (RF) history
idb-sync-history Redundancy Facility (RF) IDB sync history
linecard-group   Line card redundancy group information
rii              Display the redundancy interface identifier for Box to Box
states           Redundancy Facility (RF) states
switchover       Redundancy Facility (RF) switchover
trace            Redundancy Facility (RF) trace
|               Output modifiers
<cr>            <cr>
```

- The command `show redundancy` displays the redundant system and the current processor information. The redundant system information includes the system uptime, standby failures, switchover reason, hardware mode, and configured and operating redundancy mode. The current processor information displayed includes the image version, active location, software state, BOOT variable, configuration register value, and uptime in the current state, and so on. The Peer Processor information is only available from the Active Controller.

Verifying Redundancy States

```
[WLC#show redundancy
Redundant System Information :
-----
    Available system uptime = 22 hours, 9 minutes
    Switchovers system experienced = 1
        Standby failures = 0
    Last switchover reason = user forced

    Hardware Mode = Duplex
    Configured Redundancy Mode = sso
    Operating Redundancy Mode = sso
    Maintenance Mode = Disabled
    Communications = Up

Current Processor Information :
-----
    Active Location = slot 2
    Current Software state = ACTIVE
    Uptime in current state = 21 hours, 43 minutes
    Image Version = Cisco IOS Software [Fuji], WLC9000 Software (X86_64_LINUX_IO
SD-UNIVERSALK9_WLC-M), Experimental Version 16.10.20180509:065558 [polaris_dev-/nobackup/mcpr
e/BLD-BLD_POLARIS_DEV_LATEST_20180509_073715 183]
    Copyright (c) 1986-2018 by Cisco Systems, Inc.
    Compiled Wed 09-May-18 06:35 by mcpre
    BOOT = bootflash:qwlc-universalk9_wlc.BLD_POLARIS_DEV_LATEST_201805
09_073715.SSA.bin,1;
    CONFIG_FILE =
    Configuration register = 0x2102

Peer Processor Information :
-----
    Standby Location = slot 1
    Current Software state = STANDBY HOT
    Uptime in current state = 21 hours, 35 minutes
    Image Version = Cisco IOS Software [Fuji], WLC9000 Software (X86_64_LINUX_IO
SD-UNIVERSALK9_WLC-M), Experimental Version 16.10.20180509:065558 [polaris_dev-/nobackup/mcpr
e/BLD-BLD_POLARIS_DEV_LATEST_20180509_073715 183]
    Copyright (c) 1986-2018 by Cisco Systems, Inc.
    Compiled Wed 09-May-18 06:35 by mcpre
    BOOT = bootflash:qwlc-universalk9_wlc.BLD_POLARIS_DEV_LATEST_201805
09_073715.SSA.bin,1;
    CONFIG_FILE =
    Configuration register = 0x2102
```

- The command show redundancy states displays all the redundancy states of the active and standby controllers.

```
[WLC#show redundancy states ?
domain Specify the RF domain
|      Output modifiers
<cr>  <cr>

[WLC#show redundancy states
my state = 13 -ACTIVE
peer state = 8 -STANDBY HOT
Mode = Duplex
Unit = Primary
Unit ID = 2

Redundancy Mode (Operational) = sso
Redundancy Mode (Configured) = sso
Redundancy State = sso
Maintenance Mode = Disabled
Manual Swact = enabled
Communications = Up

client count = 136
client_notification_TMR = 30000 milliseconds
RF debug mask = 0x0
```

- Manual Switchover Action (Manual Swact) i.e. the command redundancy force-switchover cannot be executed on the Standby wireless controller and is enabled only on the Active Controller.

- Switchover History can be viewed using the following command

```
WLC#show redundancy switchover history
```

Index	Previous active	Current active	Switchover reason	Switchover time
1	1	2	user forced	18:16:37 UTC Thu May 10 2018

Accessing standby wireless controller console

The active controller can be accessed through a console connection, Telnet, an SSH, or a Web Browser by using the Management IP address. To use the console on the standby wireless controller, execute the following commands from the active Catalyst 9800 Wireless controller

```
conf t
redundancy
main-cpu
standby console enable
```

The prompt on the Standby console is appended with “-stby” to reflect the Standby wireless controller console as shown below.

```
WLC-stby#show chassis
```

Chassis/Stack Mac Address : 00a3.8e23.8760 - Local Mac Address
Mac persistency wait time: Indefinite
Local Redundancy Port Type: Twisted Pair

Chassis#	Role	Mac Address	Priority	H/W Version	Current State	IP
*1	Standby	00a3.8e23.8760	1	V02	Ready	0.0.0.0
2	Active	00a3.8e23.8900	1	V02	Ready	0.0.0.0

Note: The `show chassis` command points to the current C9800 wireless controller on the console using the (*) symbol against the chassis number as shown above. In this case it is the console of the standby Unit.

Switchover Functionality

```
WLC-stby>en
WLC-stby#show red
WLC-stby#show redun
WLC-stby#show redundancy
Redundant System Information :
-----
      Available system uptime = 22 hours, 2 minutes
Switchovers system experienced = 1

      Hardware Mode = Duplex
Configured Redundancy Mode = sso
Operating Redundancy Mode = sso
Maintenance Mode = Disabled
Communications = Up

Current Processor Information :
-----
      Standby Location = slot 1
      Current Software state = STANDBY HOT
      Uptime in current state = 21 hours, 29 minutes
      Image Version = Cisco IOS Software [Fuji], WLC9000 Software (X86_64_LINUX_IO
SD-UNIVERSALK9_WLC-M), Experimental Version 16.10.20180509:065558 [polaris_dev-/nobackup/mcpr
e/BLD-BLD_POLARIS_DEV_LATEST_20180509_073715 183]
      Copyright (c) 1986-2018 by Cisco Systems, Inc.
      Compiled Wed 09-May-18 06:35 by mcpre
      BOOT = bootflash:qwlc-universalk9_wlc.BLD_POLARIS_DEV_LATEST_201805
09_073715.SSA.bin,1;
      CONFIG_FILE =
      Configuration register = 0x2102

Peer (slot: 2, state: ACTIVE) information is not available because this is the standby proces
sor
```

Switchover Functionality

Process Failure Switchover

This type of switch over occurs when any of the key processes running on the Active unit fails or crashes. Upon such a failure, the Active unit reloads and the hot Standby takes over and becomes the new Active unit. When the failed system boots up, it will transition to Hot-Standby state. If the Standby unit is not yet in Hot Standby State, both units are reloaded and there will be no SSO. A process failure on the standby (hot or not) will cause it to reload.

Power-fail Switchover

This switchover from the Active to Standby unit is caused due to power failure of the current Active unit. The current Standby unit becomes the new Active unit and when the failed system boots up, it will transition to Hot-Standby state.

Manual Switchover

This is a user initiated forced switchover between the Active and Standby unit. The current Standby unit becomes the new Active unit and when the failed system boots up, it will transition to Hot-Standby state. To perform a manual switchover, execute the redundancy force-switchover command. This command initiates a graceful switchover from the active to the standby controller. The active controller reloads and the standby takes over as the New Active controller.

Failover Process

Active wireless controller

```
WLC#show ap summary
Number of APs: 1
```

AP Name State	Slots	AP Model	Ethernet MAC	Radio MAC	Location	Country	IP Address
AP005D.735C.B544 Registered	3	3802I	005d.735c.b544	b4de.31d0.5800	default location	US	172.20.226.186

```
WLC#show wireless client sum
Number of Local Clients: 1
```

MAC Address	AP Name	WLAN	State	Protocol	Method	Role
e8b2.ac94.757e	AP005D.735C.B544	1	Run	11ac	None	Local

```
Number of Excluded Clients: 0

WLC#redundancy force-switchover

System configuration has been modified. Save? [yes/no]: yes
Building configuration...
[OK] Proceed with switchover to standby RP? [confirm]
Manual Swact = enabled

Chassis 1 reloading, reason - Non participant detected
```

Standby wireless controller

An Access Point and client Stateful Switch Over (SSO) implies that all the Access Point and client sessions are switched over state-fully and continue to operate in a network with no loss of sessions, providing improved network availability and reducing service downtime.

Once a redundancy pair is formed, HA is enabled, which means that Access Points and clients continue to remain connected during an active-to-standby switchover.

```
WLC-stby#
May 10 18:16:37.123: %PLATFORM-6-HASTATUS: RP switchover, received chassis event to become active
May 10 18:16:37.169: %REDUNDANCY-3-SWITCHOVER: RP switchover (PEER_NOT_PRESENT)
May 10 18:16:37.169: %REDUNDANCY-3-REDUNDANCY_ALARMS: Unable to assert REDUNDANCY alarm
May 10 18:16:37.169: %REDUNDANCY-3-REDUNDANCY_ALARMS: Unable to assert REDUNDANCY alarm
May 10 18:16:37.169: %REDUNDANCY-3-SWITCHOVER: RP switchover (PEER_DOWN)
May 10 18:16:37.169: %REDUNDANCY-3-SWITCHOVER: RP switchover (PEER_REDUNDANCY_STATE_CHANGE)
May 10 18:16:37.175: %PLATFORM-6-HASTATUS: RP switchover, sent message became active. IOS is ready to switch to primary after chassis confirmation
May 10 18:16:37.180: %PLATFORM-6-HASTATUS: RP switchover, received chassis event became active
May 10 18:16:37.789: %VOICE_HA-2-SWITCHOVER_IND: SWITCHOVER, from STANDBY_HOT to ACTIVE state.
May 10 18:16:37.797: %LINK-3-UPDOWN: Interface Lsmpl0, changed state to up
May 10 18:16:37.798: %LINK-3-UPDOWN: Interface E0BC0, changed state to up
May 10 18:16:37.798: %LINK-3-UPDOWN: Interface LIIN0, changed state to up
May 10 18:16:38.798: %LINEPROTO-5-UPDOWN: Line protocol on Interface Lsmpl0, changed state to up
May 10 18:16:38.798: %LINEPROTO-5-UPDOWN: Line protocol on Interface E0BC0, changed state to up
May 10 18:16:38.798: %LINEPROTO-5-UPDOWN: Line protocol on Interface LIIN0, changed state to up
May 10 18:16:39.786: %LINK-3-UPDOWN: Interface Null0, changed state to up
May 10 18:16:39.786: %LINK-3-UPDOWN: Interface TenGigabitEthernet0/0/0, changed state to up
May 10 18:16:39.787: %LINK-3-UPDOWN: Interface Vlan1, changed state to up
May 10 18:16:39.788: %LINK-3-UPDOWN: Interface Vlan112, changed state to up
May 10 18:16:40.787: %LINEPROTO-5-UPDOWN: Line protocol on Interface Null0, changed state to up
May 10 18:16:40.787: %LINEPROTO-5-UPDOWN: Line protocol on Interface TenGigabitEthernet0/0/0, changed state to up
May 10 18:16:40.787: %LINEPROTO-5-UPDOWN: Line protocol on Interface Vlan1, changed state to up
May 10 18:16:40.787: %LINEPROTO-5-UPDOWN: Line protocol on Interface Vlan112, changed state to up
WLC#
May 10 18:16:49.798: %LINK-3-UPDOWN: Interface GigabitEthernet0, changed state to up
May 10 18:16:50.799: %LINEPROTO-5-UPDOWN: Line protocol on Interface GigabitEthernet0, changed state to up
WLC#show ap sum
WLC#show ap summary
Number of APs: 1
```

AP Name State	Slots	AP Model	Ethernet MAC	Radio MAC	Location	Country	IP Address
AP005D.735C.B544 Registered	3	3802I	005d.735c.b544	b4de.31d0.5800	default location	US	172.20.226.186

```
WLC#show wireless client summary
Number of Local Clients: 1
```

MAC Address	AP Name	WLAN	State	Protocol	Method	Role
e8b2.ac94.757e	AP005D.735C.B544	1	Run	11ac	None	Local

```
Number of Excluded Clients: 0
```

Verifying AP and Client SSO State Sync

On successful switchover of the standby wireless controller as active, all access points and clients connected to the previously active wireless controller must remain connected to the new Active controller.

This can be verified by executing the commands:

- **show ap uptime** : Verifies that the uptime of the access point after the switchover is not reset.
- **show wireless client summary**: Displays the clients connected to the new Active controller.

```
WLC#show ap uptime
Number of APs: 1

AP Name                Ethernet MAC    Radio MAC    AP Up Time                Association Up Time
-----
AP005D.735C.B544      005d.735c.b544 b4de.31d0.5800 1 day 0 hour 47 minutes 22 seconds 1 day 0 hour 45 minutes 33 s
econds

WLC#

WLC#show wireless client summary
Number of Local Clients: 1

MAC Address    AP Name                WLAN  State    Protocol Method    Role
-----
e8b2.ac94.757e AP005D.735C.B544      1     Run      11ac      None      Local

Number of Excluded Clients: 0
```

SSO Failover Time Metrics

Metrics	Time
Failure Detection	In the order of 50 ms. - TBD
Reconciliation Time (Standby becoming Active)	In the order of 1020 ms. - TBD

Redundancy Management Interface

With a single RP link between the SSO pair, if the heartbeat on RP fails, there is no way find out if the failure is limited to the link or if the other controller has failed. Redundancy Port (RP link) that handles state sync traffic between the active and the standby is a single point of failure.

Release 17.1 introduces the Redundancy Management Interface (RMI) as a secondary link between the active and the standby controllers. This release also introduces the support for default gateway check which is done using the redundancy management interface.

Redundancy Management Interface Configuration using WebUI

- RMI IP for chassis 1 and 2 is same across both active and standby controllers
- RP IP configuration for chassis 1 and 2 auto-generated as 169.254.x.x where x.x. is from the RMI IP
- The netmask for RMI is picked up from the netmask configured on the Wireless Management VLAN.

For backward compatibility, RP based SSO configuration will also be supported, but keep in mind that this will not support default gateway check and hence is not preferred.

Redundancy Management Interface Configuration using CLI

Until 17.1, only RP-based SSO configuration was supported, i.e., chassis redundancy ha-interface <RP interface> local-ip <local IP> <local IP subnet> remote-ip <remote IP>.

17.1 and beyond, the user can use either RMI+RP or RP-based configuration. Once an HA pair is formed using RMI+RP configuration, the exec CLI for RP-based method of clearing and forming the HA pair shall

not be allowed.

Note: Chassis re-number needs to be configured while bringing up HA with RMI from scratch using RMI in 17.x release.

By default, chassis number is 1. IP addresses of RP ports are derived from RMI. If the chassis number is the same on both controllers, local RP port IP derivation will be same and discovery will fail. This will result in Active-Active case.

To avoid this scenario, execute the following CLI:

```
WLC#chassis 1 renumber ?
<1-2> Renumber local chassis id assignment

WLC(config)# redun-management interface <VLAN> chassis 1 address <RMI IP of chassis 1>
chassis 2 address <RMI IP of chassis 2>
```

Configuration example:

On WLC 1:

```
WLC(config)# redun-management interface Vlan112 chassis 1 address 172.20.226.148 chassis 2
address 172.20.226.149
```

On WLC 2: (Same CLI)

```
WLC(config)# redun-management interface Vlan112 chassis 1 address 172.20.226.148 chassis 2
address 172.20.226.149
```

Chassis numbers identify the individual controllers and must be configured before configuring the RMI IPs. It is mandatory to execute the same CLI on both controllers before forming the pair. The RMI IP configuration triggers HA pairing and forms the SSO pair. There is no IPv6 Support on RMI or Gateway IP.

Verifying RMI and RP configuration

```
WLC-9800#show chassis rmi
Sep 20 21:26:13.024: %SYS-5-CONFIG_I: Configured from console by console
Chassis/Stack Mac Address : 00a3.8e23.8760 - Local Mac Address
Mac persistency wait time: Indefinite
Local Redundancy Port Type: Twisted Pair
```

Chassis#	Role	Mac Address	Priority	H/W Version	Current State	IP	RMI-IP
1	Standby	00a3.8e23.8760	2	V02	Ready	169.254.226.149	172.20.226.149
*2	Active	00a3.8e23.8900	1	V02	Ready	169.254.226.148	172.20.226.148

```
WLC-9800#show romvar
ROMMON variables:
  SWITCH_NUMBER = 1
  LICENSE_BOOT_LEVEL =
...
  RANDOM_NUM = 842430634
  SWITCH_PRIORITY = 1
  RMI_INTERFACE_NAME = Vlan112
  RMI_CHASSIS_LOCAL_IP = 172.20.226.148
  RMI_CHASSIS_REMOTE_IP = 172.20.226.149
  CHASSIS_HA_LOCAL_IP = 169.254.226.148
  CHASSIS_HA_REMOTE_IP = 169.254.226.149
  CHASSIS_HA_LOCAL_MASK = 255.255.255.0
```

RMI and RP pairing combinations

Upgrade and HA Pairing with no previous HA config

The user shall be presented with an option to choose the existing mechanism (exec RP-based CLIs) or the RMI IP based mechanism.

If the user chooses the exec CLI based method, the RP IPs shall be configured as it happens till 16.12.

When the RMI configuration is done, it shall:

Generate the RP IPs with IPs derived from the RMI IPs and will also be used for setting RMI IPs and pair the Controllers (while pairing only standby reloads in hardware platforms. Both active and standby reload in case of 9800-CL VM). Exec RP-based CLIs are blocked in this case.

Option 1: RMI Based Configuration (Preferred)

1. Upgrade to 17.1 and connect the RPs
2. Configure RMI+RP
3. RP IPs are derived from the RMI IPs
4. RP-based exec commands are blocked
5. ROMMON RP and RMI variables are set

Option 2: RP Based Configuration

1. Upgrade to 17.1 and connect RPs
2. Configure RP via GUI/CLI
3. RP-based configuration sets the local and remote IP
4. ROMMON RP Variables are set to the local and remote IP

Upgrade already Paired controllers

If the controllers are already in an HA pair, the existing exec RP CLIs can be continued to be used.

Those who would like to migrate to the RMI based HA pairing (preferred) can enable RMI.

This will overwrite the RP IPs with RMI derived IPs. The HA pair will not be immediately disturbed, but the controllers will pick up the new IP when they reload next.

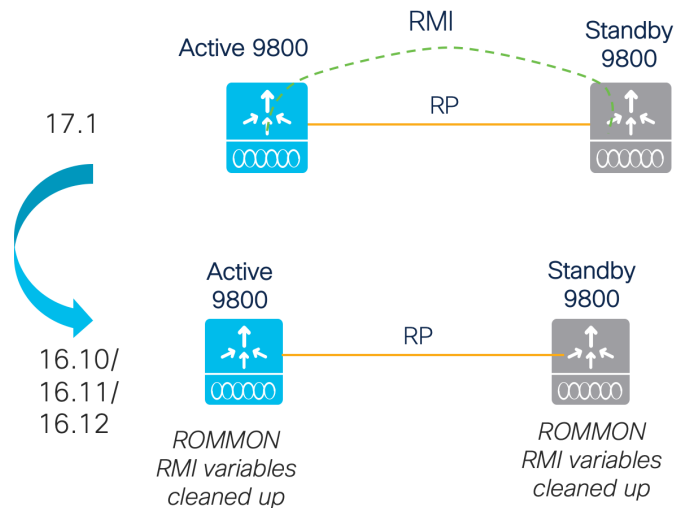
RMI feature mandates a reload for the feature to take effect.

When the controllers reload, they would come up as a pair with the new RMI-derived-RP-IPs. Exec RP-based CLIs will be blocked

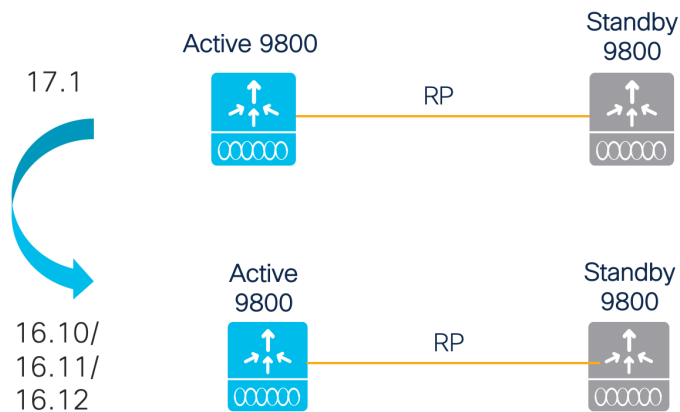
Downgrade

If RMI based configuration was used, after downgrade the system will fall back to the RP-based configuration

Default Gateway Check



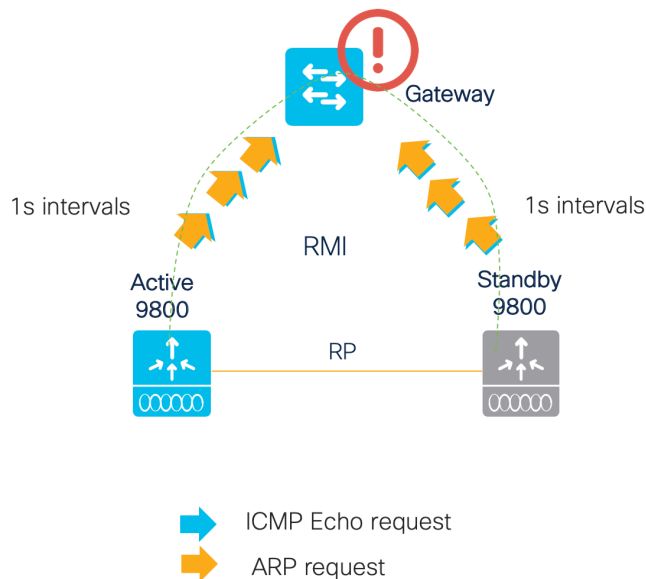
If RP based configuration was used, after downgrade the system will continue to use RP-based configuration



Default Gateway Check

Default Gateway check is done by periodically sending Internet Control Message Protocol (ICMP) ping to the gateway. Both the active and the standby controllers use the RMI IP as the source IP. These messages are sent at 1 second interval. If there are 8 consecutive failures in reaching the gateway, the controller will declare the gateway as non-reachable.

After 4 ICMP Echo requests fail to get ICMP Echo responses, ARP requests are attempted. If there is no response for 8 seconds (4 ICMP Echo Requests followed by 4 ARP Requests), the gateway is assumed to be non-reachable. Currently, this feature supports IPv4 only.



The Catalyst 9800 Wireless controller has two recovery states to prevent an active-active scenario.

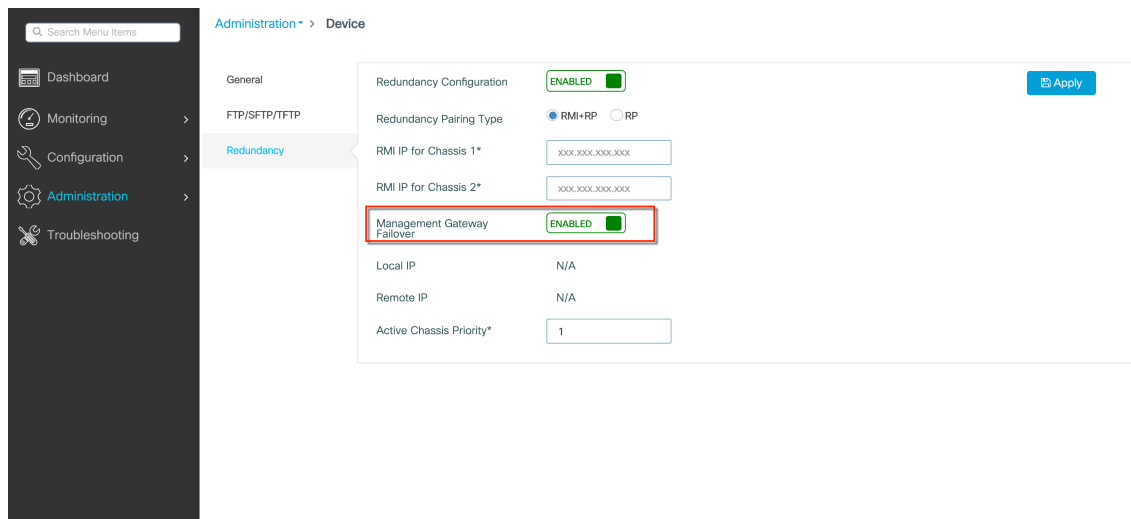
Recovery mode logically means a state where the controller does not have all “resources” available to provide the service. Currently, RP, RMI and Gateway are the resources. Ports will be in admin down in recovery mode, so no traffic goes through.

- Standby-Recovery: If Gateway goes down, standby goes to standby-recovery mode. Standby means, its state is up to date with the active. But since it does not have the other resource (Gateway) it goes to Standby-Recovery. The standby shall not be in a position to take over the active functionality when it is in standby-recovery mode. Standby-Recovery will go back to Standby without a reload, once it detects that the Gateway reachability is restored.
- Active-Recovery is when the RP goes down. Active-Recovery does not have its internal state in sync with the Active. Active-Recovery will reload when the RP link comes up so that it can come up as Standby with bulk sync.

Switchover history will show switchover reason as Gateway down in the event of a switchover triggered as a result of the gateway going down.

Default Gateway Check WebUI Configuration

The default gateway check option can be configured under Administration > Device > Redundancy > Management Gateway Failover



Default Gateway Check CLI Configuration

The following CLIs need to be configured for the gateway check functionality to be enabled and to specify the default gateway IP used by this feature

```
WLC-9800(config)#management gateway-failover enable
WLC-9800#ip default-gateway <IP>
```

To verify if gateway check is enabled, use the CLI show redundancy state

```
WLC-9800#show redundancy states
my state = 13 -ACTIVE
peer state = 8 -STANDBY HOT
Mode = Duplex
Unit = Primary
Unit ID = 2
Redundancy Mode (Operational) = sso
Redundancy Mode (Configured) = sso
Redundancy State = sso
...
Gateway Monitoring = Enabled
```

With 17.2, usage of “ip default-gateway <IP>” shall be removed . Gateway IP will be picked up from the static IP routes configured. The HA infrastructure will choose the static route IP that matches the RMI network. If there are multiple static routes configured, the route configured for the broadest network scope shall be selected. It is possible to configure multiple gateways for the same network scope. If there are multiple gateways for the same network, broadest mask and least gateway IP is chosen. The gateway IP shall be reevaluated, if necessary, when config update to static routes happens.

Note:

- Physical port down scenario takes 8 seconds to be detected as it is detected via GW check mechanism
- Physical port status is synced from the active to standby controller in release 17.1. This has been fixed in release 17.2 and the active and standby controllers maintain their own port status.

System and Network Fault Handling

If the standby controller crashes, it shall reboot and come up as standby. Bulk sync will follow and the standby will become hot. If the active controller crashes, the standby becomes active. The new active shall assume the role of master and try to detect a dual active.

These matrices provide a clear picture of what condition the WLC Switchover will trigger:

System Issues				
Trigger	RP Link Status	Peer Reachability through RMI	Switchover	Result
Critical Process crash	Up	Reachable	Yes	Switchover happens
Forced switchover	Up	Reachable	Yes	Switchover happens
Critical Process crash	Up	Unreachable	Yes	Switchover happens
Forced switchover	Up	Unreachable	Yes	Switchover happens
Critical Process crash	Down	Reachable	No	No action, one controller will be in recovery mode already.
Forced switchover	Down	Reachable	N/A	No action, one controller will be in recovery mode already.
Critical Process crash	Down	Unreachable	No	Double fault – as mentioned in Network Error handling
Forced switchover	Down	Unreachable	N/A	Double fault – as mentioned in Network Error handling

RP Link	Peer reachability through RMI	Gateway From Active	Gateway from Standby	Switchover	Result
Up	Up	Reachable	Reachable	No	No action
Up	Up	Reachable	Unreachable	No	No Action. Standby is not ready for SSO in this state as it does not have gateway reachability. The

					standby shall be shown to be in standby-recovery mode. If the RP goes down, standby (in recovery mode) shall become active.
Up	Up	Unreachable	Reachable	Yes	Gateway reachability message is exchanged over the RMI + RP links. Active shall reboot so that standby becomes active.
Up	Up	Unreachable	Unreachable	No	With this, when the active SVI goes down, so will the standby SVI. A switchover is then triggered. If the new active discovers its gateway to be reachable, the system shall stabilize in Active - Standby Recovery. Otherwise, switchovers will happen in a ping-pong fashion.
Up	Down	Reachable	Reachable	No	No Action

Up	Down	Reachable	Unreachable	No	Standby is not ready for SSO in this state as it does not have gateway reachability. Standby will go to recovery mode as LMP messages are exchanged over the RP link also.
Up	Down	Unreachable	Reachable	Yes	Gateway reachability message is exchanged over RP link also. Active shall reboot so that standby becomes active.
Up	Down	Unreachable	Unreachable	No	With this, when the active SVI goes down, so will the standby SVI. A switchover is then triggered. If the new active discovers its gateway to be reachable, the system shall stabilise in Active - Standby Recovery. Otherwise, switchovers will happen in a ping-pong fashion.
Down	Up	Reachable	Reachable	Yes	Standby will become active with (old) active going to active-recovery. Config mode is disabled in active-

					recovery mode. All interfaces will be ADMIN DOWN with the wireless management interface having RMI IP. The controller in Active Recovery will reload to become standby when the RP link comes UP.
Down	Up	Reachable	Unreachable	Yes	Same as above
Down	Up	Unreachable	Reachable	Yes	Same as above
Down	Up	Unreachable	Unreachable	Yes	Same as above
Down	Down	Reachable	Reachable	Yes	Double fault – this may result in a network conflict as there will be 2 active controllers. Standby becomes active. Old active also exists. Role negotiation has to happen once the connectivity is restored and keep the active that came up last

Down	Down	Reachable	Unreachable	Yes	Same as above
Down	Down	Unreachable	Reachable	Yes	Same as Above
Down	Down	Unreachable	Unreachable	Yes	Same as Above

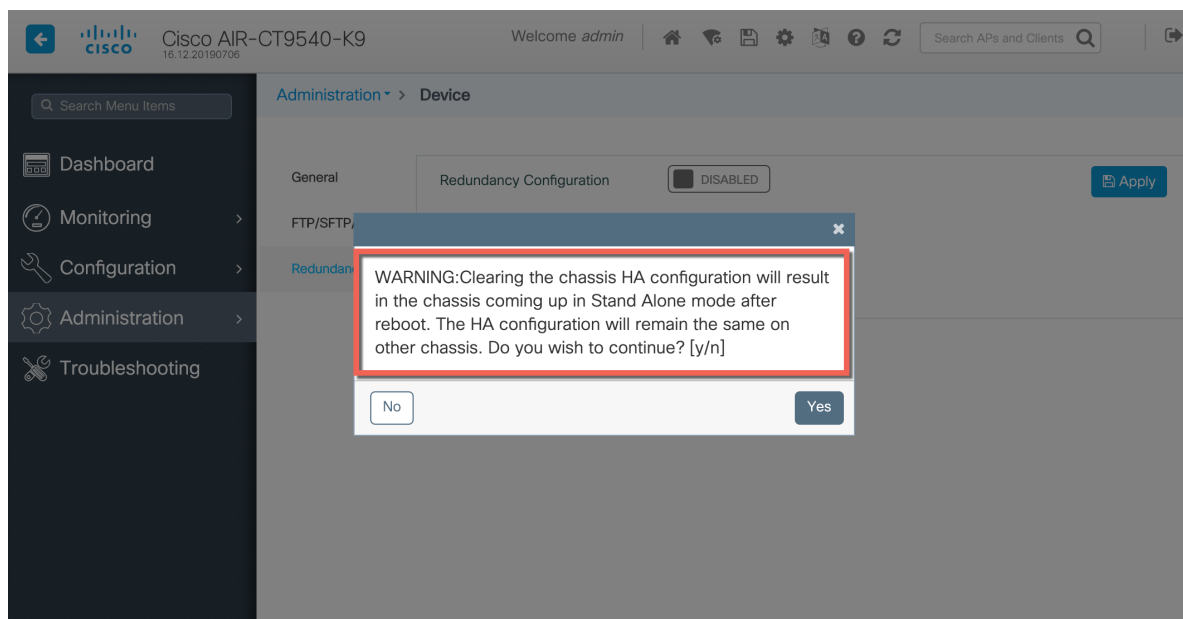
HA Unpairing Behavior

In release 16.10 and 16.11, when disjoining an HA pair by issuing the command 'clear chassis redundancy', the standby controller reboots and comes up with exactly the same configuration as the active controller, causing duplicate IP address error leading to the following messages:

```
WLC#sh log | i DUP
Mar 21 21:53:46.307 CET: %IP-4-DUPADDR: Duplicate address 120.0.0.1 on Vlan120, sourced by
d4c9.3ccc.f98b
Mar 21 21:54:16.947 CET: %IP-4-DUPADDR: Duplicate address 172.18.50.60 on
GigabitEthernet0, sourced by d4c9.3ccc.f981
```

The solution implemented in 16.12 and 17.1 is that after HA unpairing, the standby controller startup config and HA config will be cleared and standby will go to Day 0.

Before the command is executed, the user is prompted with the following warning on the active controller:



LACP, PAGP support in SSO Pair

The same is seen on the CLI as well.

```
WLC#clear chassis redundancy
WARNING: Clearing the chassis HA configuration will result in both the chassis move into Stand Alone mode. This involves reloading the standby chassis after clearing its HA configuration and startup configuration which results in standby chassis coming up as a totally clean after reboot. Do you wish to continue? [y/n]? [yes]:
*Apr 3 23:42:22.985: received clear chassis.. ha_supported:lyes
WLC#
*Apr 3 23:42:25.042: clearing peer startup config
*Apr 3 23:42:25.042: chkpt send: sent msg type 2 to peer..
*Apr 3 23:42:25.043: chkpt send: sent msg type 1 to peer..
*Apr 3 23:42:25.043: Clearing HA configurations
*Apr 3 23:42:26.183: Successfully sent Set chassis mode msg for chassis 1.chasfs file updated
*Apr 3 23:42:26.359: %IOSXE_REDUNDANCY-6-PEER_LOST: Active detected chassis 2 is no longer standby
```

On the standby controller, the following messages indicate that the configuration is being cleared:

```
WLC-stby#
*Apr 3 23:40:40.537: mcprp_handle_spa_oir_tsm_event: subslot 0/0 event=2
*Apr 3 23:40:40.537: spa_oir_tsm subslot 0/0 TSM: during state ready, got event 3(ready)
*Apr 3 23:40:40.537: @@@ spa_oir_tsm subslot 0/0 TSM: ready -> ready
*Apr 3 23:42:25.041: Removing the startup config file on standby
*Apr 3 23:42:26.466: Calling HA configs clear on standby
*Apr 3 23:42:26.466: Clearing HA configurations
*Apr 3 23:42:27.499: Successfully sent Set chassis mode msg for chassis 2.chasfs file updated
```

Note: To unpair the SSO pair when using RMI based config, use the “no” version of the RMI configuration followed command by reload:

```
WLC(config)# no redun-management interface <VLAN> chassis 1 address <RMI IP of chassis 1>
chassis 2 address <RMI IP of chassis 2>
```

LACP, PAGP support in SSO Pair

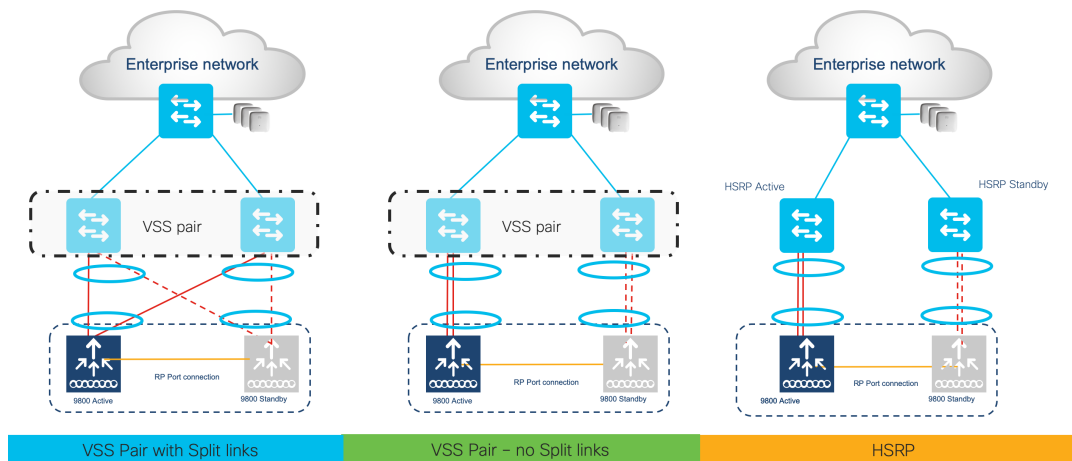
LACP protocol (IEEE 802.3ad) aggregates physical Ethernet interfaces by exchanging the Link Aggregation Control Protocol Data Units (LACPDUs) between two devices.

LACP, PAGP support is needed on SSO pair in order to have the ability to detect and monitor the link/connectivity failures on the standby controller and to have seamless transfer of client data traffic upon switchover (SSO). Prior to 17.1 only LAG mode ON was supported in SSO mode. With 17.1 both LACP (active and passive) and PAGP will be supported in SSO mode.

This feature is supported on Cisco Catalyst 9800-L, Cisco Catalyst 9800-40and Cisco Catalyst 9800-80 (including module ports).

Supported LACP, PAGP topologies

The following topologies are supported with SSO and LACP/PAGP



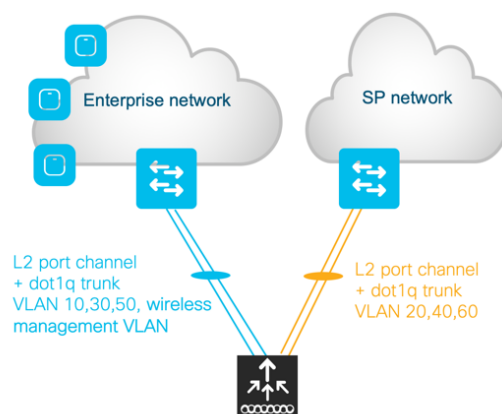
The following are not supported with LACP, PAGP topologies:

- Auto-LAG is not supported.
- C9800-CL and EWC on AP is not supported.
- L3 port-channel is not supported.

Multi-chassis Link Aggregation group

Starting with Release 17.2.1, Multi-chassis Link Aggregation Group is supported on a standalone as well as HA Pair of controllers. Multi-chassis LAG provides the capability to connect multiple uplinks from controller to separate uplink switches.

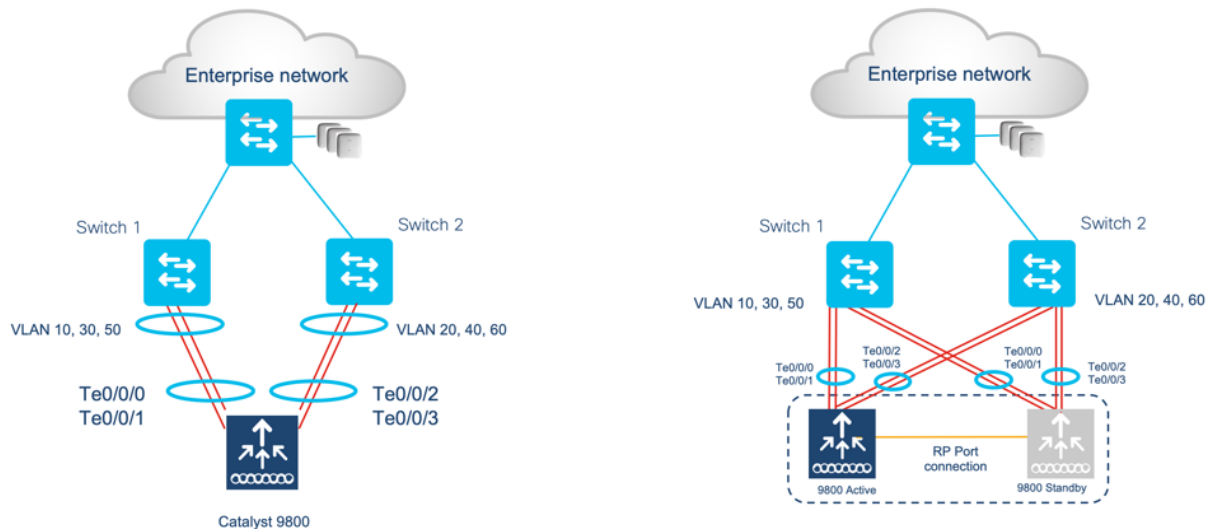
This enables flexibility in connecting controller(s) to switch infrastructure and VLAN-based traffic splitting when connected to a multi-switch topology, for e.g., to isolate Guest traffic on completely different switch/network from Enterprise traffic. Each LAG must be connected to a single switch and different VLANs must be assigned to different LAGs.



Note: It is the user's configuration responsibility not to create a loop.

Supported Multi-chassis LAG topologies

- Multi-chassis LAG is supported with LAG mode ON and dynamic LAG (LACP and PAGP)
- Multi-chassis LAG is supported with a standalone controller as well as an HA pair as depicted below.



Note: Controller with multiple LAGs can be connected to a single switch, However, different VLANs must be connected to different LAGs

Supported Platforms:

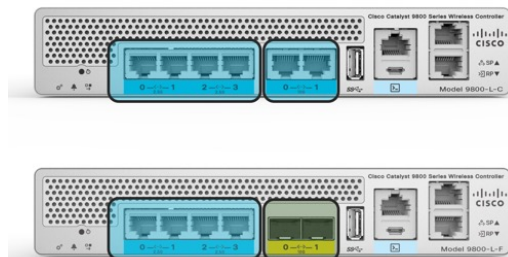
Multi-chassis LAG is supported on the following platforms:

- Catalyst 9800-L Wireless Controllers
- Catalyst 9800-40 Wireless Controllers
- Catalyst 9800-80 Wireless Controllers

Supported LAG Port Grouping

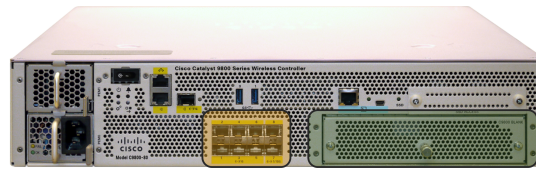
Best practice is to have ports of same type and speed in the port channel

- 9800-L-C with 2.5G/1G and 10G/mGig ports in different port channels
- 9800-L-F with 2.5G/1G and 10G/1G Fiber ports in different port channels



Replacing a controller in an HA setup

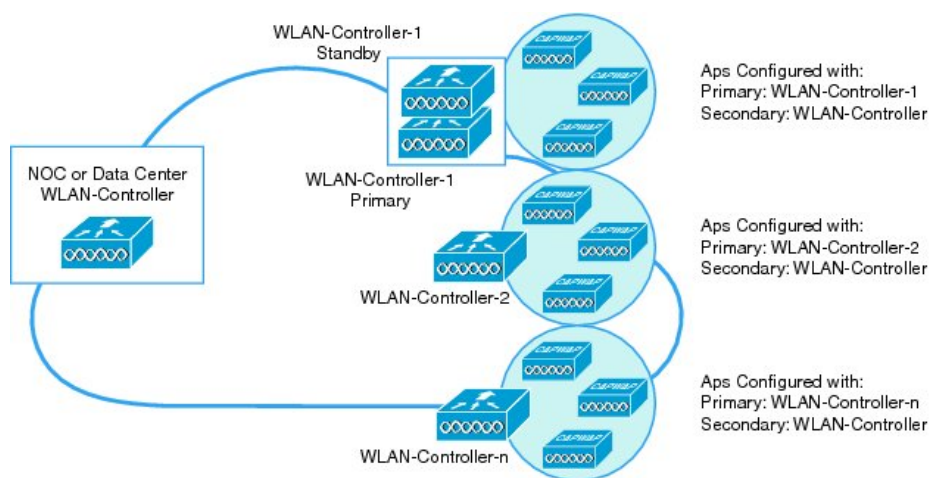
On the 9800-80 ports on Bay 0 and Bay 1 (modular slots) cannot be combined into the same port channel group. Best practice is to have ports of same slot in the port channel.



Replacing a controller in an HA setup

- Remove the active controller from the HA pair without breaking the pair. As a result of active controller going away, the standby controller will take over the role of Active.
- Prepare the new 9800 controller with the same configuration as the previous active controller. This means the same software version, licensing level, IP addresses WMI, RMI and mobility MAC.
- Configure a higher priority on the current Active controller to make sure that the current active remains the active even in the unlikely event of the active controller rebooting before the new controller is paired in SSO.
- Physically connect the new 9800 controller using the redundancy ports (RP)
- Enable SSO configuration on the new 9800 controller
- The new 9800 controller will reboot and come up as Standby paired with the current Active controller.

N+1 with SSO Hybrid deployment



A hybrid topology of SSO redundant pair and N+1 primary, secondary and tertiary model is supported as shown above. The secondary controller at the DR site can be a Catalyst C9800-L, C9800-40 C9800-80 or C9800-CL Wireless controller. Access points failing back from Catalyst 9800 Wireless controller to CUWN

controllers will re-download the code before joining the CUWN wireless controller and vice versa.

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