

# VX1000 DaVinci Integration

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**Abstract** Using DaVinci to configure the VX1000 AppDriver

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## 1 Overview VX1000 DaVinci Integration

The VX1000 provides powerful measurement and calibration access to the microcontroller via debug interfaces. For maximum flexibility and optimal measurement results, the VX1000 Application Driver must be integrated into the ECU software. The VX1000 Application Driver is a Complex Device Driver in the AUTOSAR stack. AUTOSAR modules are typically configured using dedicated AUTOSAR configuration tools such as DaVinci Configurator. This application note shall provide the essential information for integrating the VX1000 Application Driver into the ECU Software with the help of DaVinci.

The VX1000 Application Driver configuration with the DaVinci Configurator is optional and allows an easy-to-use configuration of the Application Driver in an AUTOSAR project. If DaVinci is not used within the project, the C4VX1000 Application Driver can easily be configured by directly modifying its \_cfg.h files. For the latter, please see the Getting Started Application Notes that are delivered with the VX1000 Application Driver.



## 2 Installation of the VX1000 Application Driver

### 2.1 Getting the VX1000 Application Driver

The VX1000 Application Driver can be downloaded via <a href="https://www.vector.com/VX1000If-VX1000AppDriver">https://www.vector.com/VX1000If-VX1000AppDriver</a>.

Please note the Product-Specific Special Terms for VX1000If and the VX1000 AppDriver, clearly highlighted on the website or within the driver package.

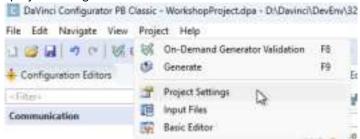
## 3 Installation in the Software Integration Package

After installation, the installation folder contains two folders

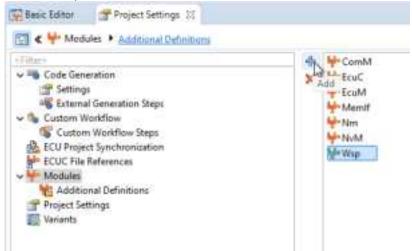


The folder "MSR\_Components" is structured to allow seamless copying into the Software Integration Package (SIP) without requiring modifications.

- Ensure that your Davinci-Software is closed
- Copy \$Install-Directory/MSR\_Components/VX1000 to \$SIPLocation/Components/VX1000
- Open DaVinci
- · Open the project settings

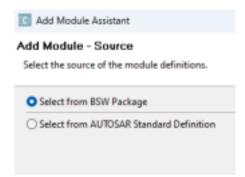


• Select "Modules" and press Add

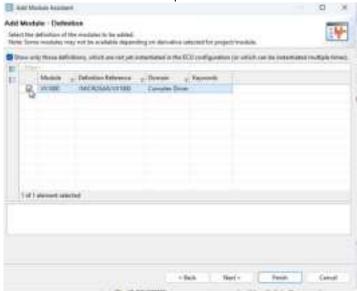


Use "Select from BSW package"

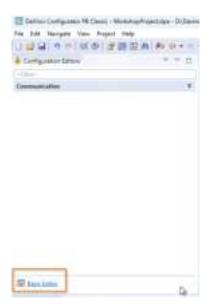




• Select the VX1000 Module and press "Finish"

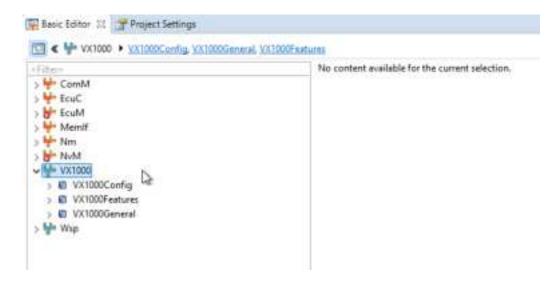


Switch to the Basic-Editor.



• Now, the VX1000 Module can be configured like other AUTOSAR modules





## 4 Modifications of the build process

must be modified. Add these lines at the end of the file

To add the VX1000 Application Driver to the build process the file \$(Project)\Appl\Makefile.project.part.defines

```
# additional includes for VX1000 driver
ADDITIONAL_INCLUDES += $(ROOT)\Components\VX1000\Implementation
ADDITIONAL_INCLUDES += $(ROOT)\Components\VX1000If\Implementation
# vx1000 driver source files
APP_SOURCE_LST += $(ROOT)\Components\VX1000\Implementation\VX1000.c
APP SOURCE_LST += $(ROOT)\Components\VX1000If\Implementation\VX1000If.c
```

## 5 VX1000 Application Driver configuration

The module configuration contains several configuration options. A functional description is provided for each parameter.

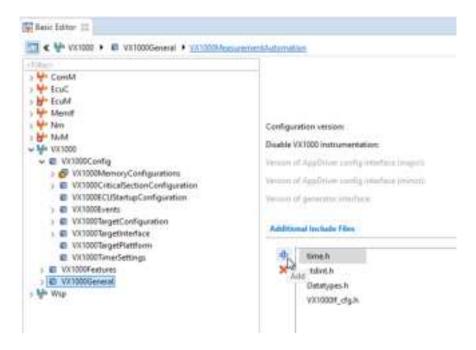


The most important steps are described in the later sections of this Application Note. For advanced features, please refer to the corresponding Application Notes or Getting Started Manuals.

#### 5.1 Additional Include Files.

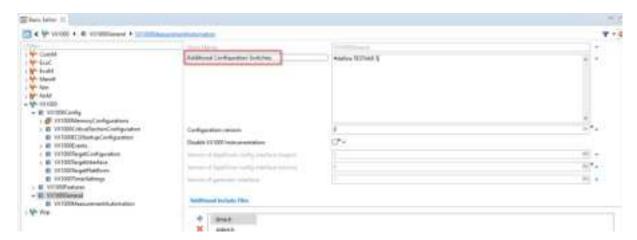
If you require additional header files for your implementation, you can add these easily.





#### 5.2 Additional Code includes

If some additional code blocks are required for the configuration, these can be added within "Additional Configuration Switches". This block will be copied without modification to the generated file.



## 5.3 Target controller configuration

The VX1000 supports many different target controller families and architectures. The correct target can be configured through

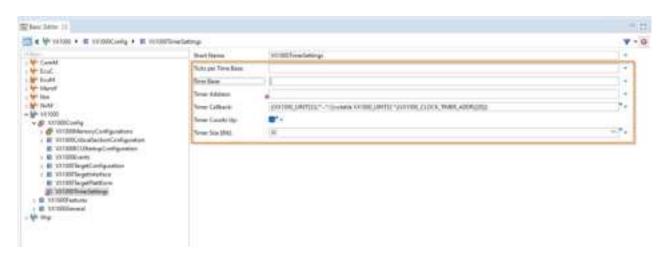
VX1000/VX1000Config/VX1000TargetConfiguration[VX1000\_TARGET]





## 5.4 Timer configuration

Each time a measurement event is triggered, the VX1000 Application Driver captures a timestamp. The timestamp source must be explicitly configured:



#### Time Base + Ticks per Time Base

For the tool to correctly interpret the timestamps, the timestamp resolution must be declared. For this, the characteristics of the timer counter must be specified as a time base in decades of nanoseconds and the ticks per time base. The latter is the counter increment within the time base period.

#### Example:

Time Base: 1000

Ticks per Time Base: 21

Specifies a counter incrementing at a rate of 21 MHz (21 ticks per 1000 ns)

### **Timer Address:**

The address of the counter register of the used timer.

#### **Timer Callback:**

This callback is executed whenever the VX1000 AppDriver needs to capture a timestamp. In most cases, the default configuration is sufficient and does not require modification.

### **Timer Counts Up:**

Specifies whether the counter is an up-counter or a down-counter. In most cases, up-counters are used.

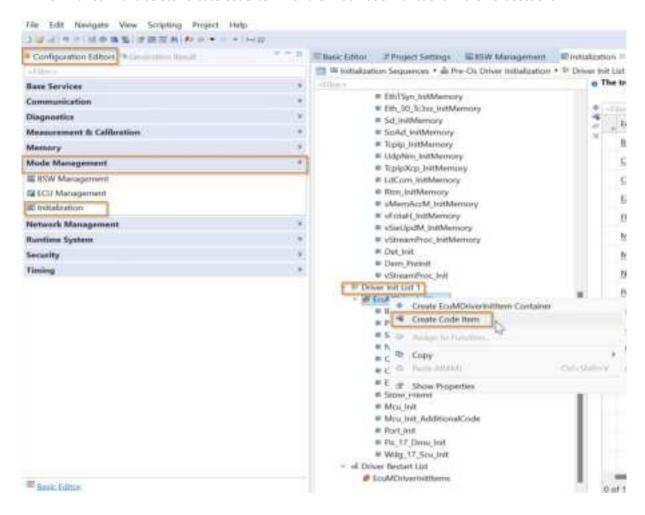
#### Timer Size [Bit]:

Size in bytes of the timer counter which is used for timestamping. Supported timer counter widths are 16 bit, 24 bit or 32 bit. In most cases, 32 bit counters are used.



## 5.5 Startup configuration

For the correct startup configuration, the Mode Management Initialization must be modified. Right click on "Driver Init List 1" and select "Create Code Item" for the initialization functions in the next sections.



### 5.5.1 Startup configuration VX1000lf\_InitAsyncStart

/Initialization Sequences/Pre-Os Driver Initialization/Driver Init List 1/EcuMDriverInitItems /VX1000If\_InitAsyncStart

Select "Create Code Item" for the function VX1000If\_InitAsyncStart()



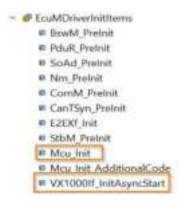
Name: VX1000If\_InitAsyncStart

Header: VX1000If.h



Code: VX1000If\_InitAsyncStart();

Move the code after the Mcu\_Init init steps



## 5.5.2 Startup configuration VX1000lf\_InitAsyncEnd

/Initialization Sequences/Pre-Os Driver Initialization/Driver Init List 1/EcuMDriverInitItems /VX1000If\_InitAsyncEnd

Select "Create Code Item" for the function VX1000If\_InitAsyncEnd()



Name: VX1000If InitAsyncEnd

Header: VX1000If.h

Code: VX1000If\_InitAsyncEnd();

Ensure that this function is called as late as possible, but definitely before the first measurement event is triggered.





### 5.6 Memory allocation

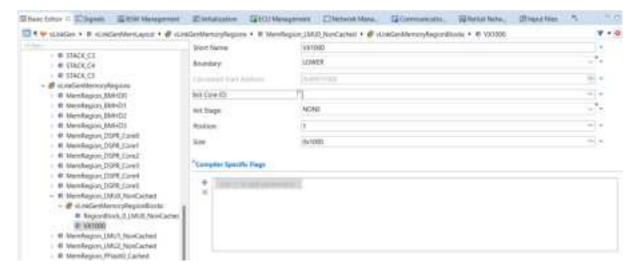
The VX1000 communicates with the VX1000 Application Driver via a shared memory structure. Adjusting the address of this communication structure in the VX1000 configuration is error-prone when switching between different ECU Software Versions. By pinning the structure to a fixed address, the workflow becomes both simpler and faster. To do so, the vLinkGen module can be used to put the variable into a linker section at a fixed address.

### 5.6.1 Configuration of vLinkGen

#### 5.6.1.1 vLinkGenMemoryRegion

Create a VX1000 container in the appropriate vLinkGenMemoryRegions like the LMU0 memory. The memory must be uncached. Its required size depends on the expected extent of the DAQ configurations. The parameter /VX1000/VX1000Config/VX1000MemoryConfiguration/VX1000OldaMemory/VX1000\_OLDA\_MEMORY\_SIZE should be taken into consideration.

Treepath: /vLinkGen/vLinkGenMemLayout/vLinkGenMemoryRegions

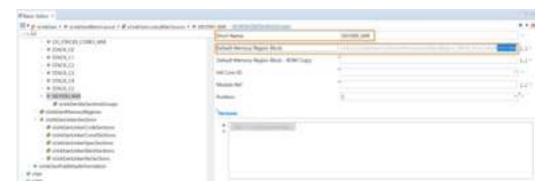




#### 5.6.1.2 Create vLinkGenLogicalVarGroups Container VX1000 VAR

Create a VX1000\_VAR container in vLinkGenLogicalVarGroups container with reference "Default Memory Region Block" to the container from step 1.

Treepath /vLinkGen/vLinkGenMemLayout/vLinkGenLogicalVarGroups/VX1000\_VAR

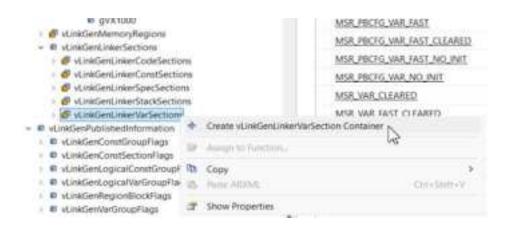


### 5.6.1.3 Create vLinkGenLinkerVarSection

For assigning the VX1000 Variables to a memory section, vLinkGenLinkerVarSections must be created:

/vLinkGen/vLinkGenMemLayout/vLinkGenLinkerSections/vLinkGenLinkerVarSections

Right click on vLinkGenLinkerVarSections and press "Create vLinkGenLinkerVarSection Container" for each for the following Linker Sections

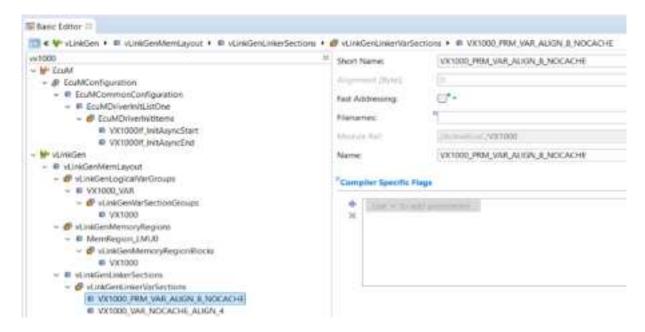


### 5.6.1.3.1 Create vLinkGenLinkerVarSection VX1000\_PRM\_VAR\_ALIGN\_8\_NOCACHE

Create a new vLinkGenLinkerVarSection with name VX1000\_PRM\_VAR\_ALIGN\_8\_NOCACHE. Select VX1000\_PRM\_VAR\_ALIGN\_8\_NOCACHE as Name and Short Name

 $/v Link Gen/v Link GenMem Layout/v Link GenLinker Sections/v Link GenLinker Var Sections/VX1000\_PRM\_VAR\_ALIGN\_8\_NOCA CHE$ 



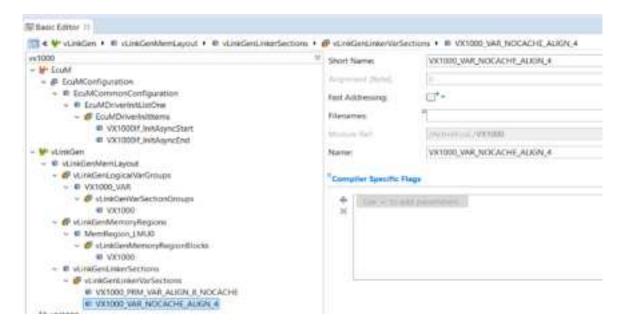


#### 5.6.1.3.2 Create vLinkGenLinkerVarSection VX1000\_VAR\_NOCACHE\_ALIGN\_4

Create a vLinkGenLinkerVarSection VX1000\_VAR\_NOCACHE\_ALIGN\_4.

/vLinkGen/vLinkGenMemLayout/vLinkGenLinkerSections/vLinkGenLinkerVarSections/ VX1000\_VAR\_NOCACHE\_ALIGN\_4

Create a new vLinkGenLinkerVarSection with name VX1000\_VAR\_NOCACHE\_ALIGN\_4. Select VX1000\_VAR\_NOCACHE\_ALIGN\_4 as name and Short Name.

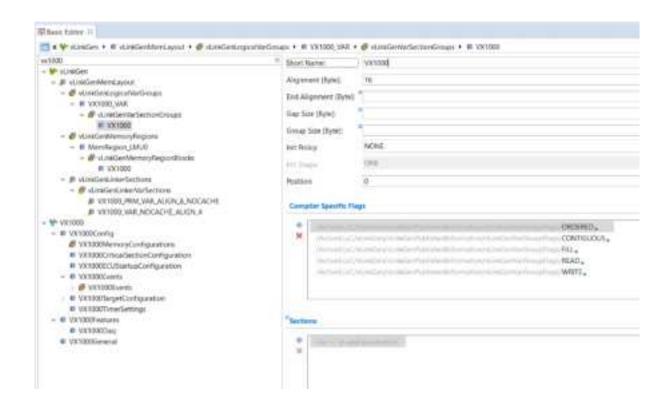


#### 5.6.1.4 Create vLinkGenVarSectionGroup Container VX1000

Create a vLinkGenVarSectionGroup Container

 $/v Link Gen/v Link Gen Mem Layout/v Link Gen Logical Var Groups/VX1000\_VAR/v Link Gen Var Section Groups/VX1000$ 

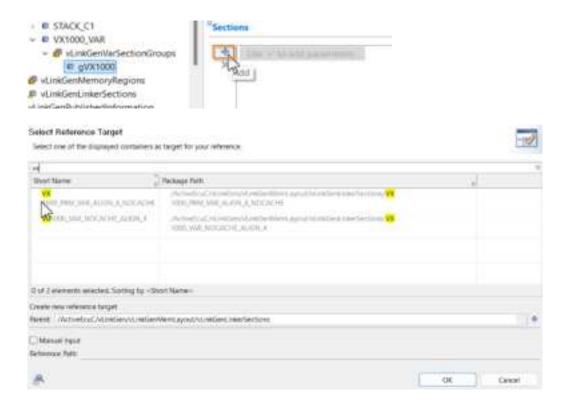




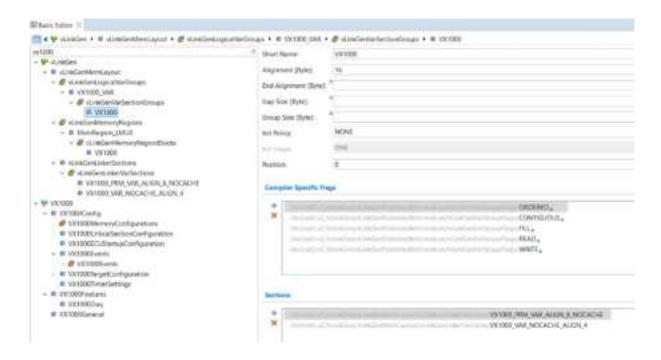
#### Add the Linker Section Groups

VX1000\_PRM\_VAR\_ALIGN\_8\_NOCACHE,

VX1000 VAR NOCACHE ALIGN 4,







After you have generated your project ...



the compiler/link should look like this (.\Appl\Source\ vLinkGen Template.lsl)

```
group VK1000 VAR GROUP (ordered, contiguous, fill, run addr = mem:mpe:VK1000)
287
            group VX1000 (ordered, contiguous, fill, align = 16)
290
               section "VX1000_SEC" (blocksize = 2, attributes = rw)
291
              - (
                  select *[.]bss.VX1000 PRM VAR ALIGH # NOCACHE";
                  select "[.]bus.VX1000 VAR NOCACHE ALIGN 4";
2003
291
295
            "_VX1000_START" = "_lc_gb_VX1000";
"_VX1000_END" = ("_lc_ge_VX1000" == 0) 7 0 : "_lc_ge_VX1000" - 1;
"_VX1000_LIHIT" = "_lc_ge_VX1000";
297
290
193
            " VX1000 VAR ALL START" - " VX1000 START";
            " VX1000 VAR ALL END" - " VX1000 END";
" VX1000 VAR ALL LIMIT" = " VX1000 END";
```

After compiling the application with b.bat in the .\Appl directory, the gVX1000 structure should be put in the memory region defined in 5.6.1.1 Overview VX1000 DaVinci Integration. You can double check this in the map file.



```
10103 | 0xb0041000 | 1c gb VX1000 VAR GROUP
10104 | 0xb0041000 | gVX1000
10101 | 0xb004150c | vx1000 DetectStartTime
```

### 5.7 DAQ Event configuration

The VX1000 provides the possibility to configure DAQ events and to set various attributes of these events. A detailed configuration is only needed for special features like Multibuffer OLDA or In-Place OLDA. For plain OLDA or Data Trace-based measurement, nothing must be configured and this chapter can be skipped.



#### Configuration of VX1000 DAQ Events:

This is the measurement type and how the event is instrumented within the ECU software.

For In-Place OLDA Events, besides triggering the event, the VX1000If\_EventProcessingBarrier must be called in a defined sequence. To indicate this special type of code instrumentation, such events need to be configured as VX1000 EVENT ALSO USES BARRIER.

Events that have a very short cycle time < 1ms should be marked as VX1000\_EVENT\_MBUF\_ONLY\_TRIGGER.

This annotation given by the ECU software is just a hint for the VX1000. In the VX1000 there are also configuration options to override these settings.

#### **Event Channel Number:**

This is the XCP DAQ event channel number that must be used by the measurement tool for this event channel. For <auto>, the numbers are calculated on demand and can be accessed via VX1000\_EVTCH\_\$(Eventname) (with Eventname in uppercase letters).

## **Event Channel Priority:**

The EVENT\_CHANNEL\_PRIORITY defines the processing order of this event channel by the VX1000 when multiple channels are triggered at the same time.

#### **Event Channel Time Cycle [us]:**

The EVENT\_CHANNEL\_TIME\_CYCLE indicates the period for cyclic events, specifying how frequently this event channel is triggered. This is useful information for the VX1000 and for the measurement tool. A non-cyclic task is indicated by 0.

#### **Event Channel Type:**

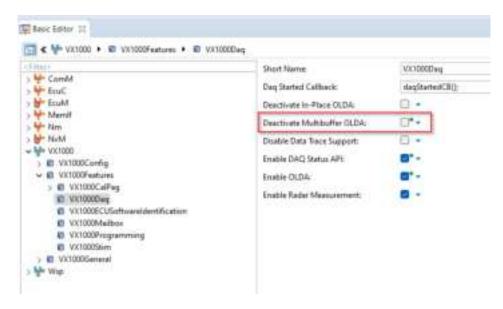
Describes the type of the event channel. DAQ is for Synchronous Data Acquisition and is used for measuring ECU data. STIM is for Synchronous Data Stimulation and is used for sending data to the ECU like for functional bypassing use cases. DAQ\_STIM events can be used for either DAQ or STIM.



### 5.8 Feature configuration

### 5.8.1 Short cycle times

Projects that must acquire data at very short cycle times of <1ms should ensure that Multibuffer OLDA is activated. Also ensure that the fast event channels are correctly configured (see 5.7 DAQ Event configuration).



### 5.8.2 Minimum system

If running on a device with very limited hardware resources, the VX1000 Application Driver can be configured to have a minimal RAM and runtime footprint. Start with an empty configuration, then ...

- Check: Deactivate In-Place OLDA
- Check: Deactivate Multibuffer OLDA
- Check: Disable Data Trace Support
- Uncheck: Enable DAQ Status API
- Check: Enable OLDA
- Uncheck: Enable Radar Measurement

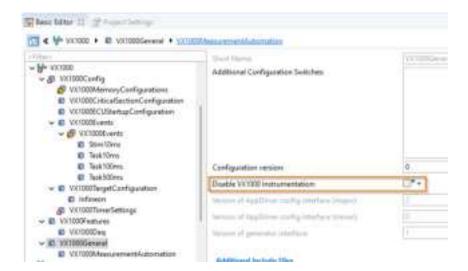


### 5.8.3 Disable VX1000 Application Driver

The VX1000 Application Driver provides configuration switches to remove nearly the complete driver from code. Afterwards, the VX1000 measurement features are not available anymore. The driver can be easily reactivated later with all settings preserved.

Parameter: /ActiveEcuC/VX1000/VX1000General[VX1000 DISABLE INSTRUMENTATION]





# 6 VX1000lf generation

Please make sure to carefully read the VX1000If Technical Documentation and ensure that VX1000If\_IsVX1000DriverAccessEnabled is correctly defined.



## 7 Additional Resources

 $Technical Reference\_VX1000.pdf: Technical\ Reference\ for\ the\ VX1000\ Application\ Driver$ 

TechnicalReference\_VX1000If.pdf: Technical Reference for the VX1000 Interface

## 8 Contacts

For a full list with all Vector locations and addresses worldwide, please visit <a href="http://vector.com/contact/">http://vector.com/contact/</a>.