

# Tilt Sensor

## Featuring LoRaWAN®

### EM320-TILT

User Guide



## Safety Precautions

Milesight will not shoulder responsibility for any loss or damage resulting from not following the instructions of this operating guide.

- ❖ The device must not be disassembled or remodeled in any way.
- ❖ In order to protect the security of the device, please change device password when first configuration. The default password is 123456.
- ❖ Do not place the device close to objects with naked flames.
- ❖ Do not place the device where the temperature is below/above the operating range.
- ❖ The device is not intended to be used as a reference sensor, and Milesight will not should responsibility for any damage which may result from inaccurate readings.
- ❖ The battery should be removed from the device if it is not to be used for an extended period. Otherwise, the battery might leak and damage the device. Never leave a discharged battery in the battery compartment.
- ❖ Make sure all batteries are newest when install, or battery life will be reduced.
- ❖ The device must never be subjected to shocks or impacts.

## Declaration of Conformity

EM320-TILT is in conformity with the essential requirements and other relevant provisions of the CE, FCC, and RoHS.



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**Revision History**

Date	Doc Version	Description
Feb.14, 2023	V 1.0	Initial version
Aug. 15, 2023	V 1.1	Add pole mounting plate and installation

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## 1. Product Introduction

### 1.1 Overview

EM320-TILT is an LoRaWAN® tilt sensor mainly for angle measurement and asset movement detection. With a compact size and 3-axis accelerometer, EM320-TILT can be installed to the objects easily to measure its X,Y,Z tilt angles. In addition, EM320-TILT supports customizing initial position to detect movement based on angle changes and send threshold alarms. Compliant with Milesight LoRaWAN® gateway and Milesight IoT Cloud solution, users can know the angles and tilt threshold alarms in real-time via browser or mobile app remotely. EM320-TILT can be widely used in tree monitoring, pole lean detection, landslide monitoring, etc.

### 1.2 Features

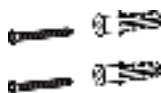
- Built-in MEMS accelerometer sensor to measure the 3-axis angles of any objects
- Flexible threshold condition settings, suitable for different kinds of applications
- Easy to install, suitable for various types of objects as trees, poles, grounds, etc.
- IP67 waterproof enclosure for outdoor applications
- Anti-theft design on back cover to secure firm and sturdy installation
- Ultra-wide-distance wireless transmission up to line of sight of 15km
- Equipped with NFC for one touch configuration
- Function well with standard LoRaWAN® gateways and network servers
- Compliant with Milesight IoT Cloud

## 2. Hardware Introduction

### 2.1 Packing List



1 × EM320-TILT  
Sensor



2 × Wall  
Mounting Kits



1 × Fixing Screw



1 × Pole Mounting  
Plate



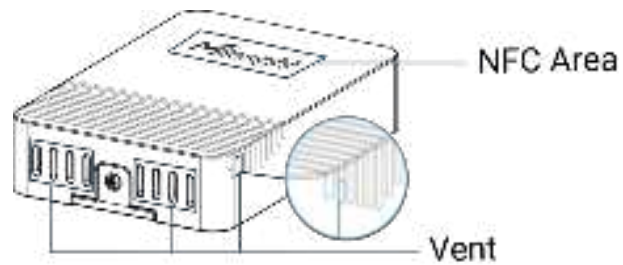
1 x Quick Start  
Guide

1 x Warranty  
Card

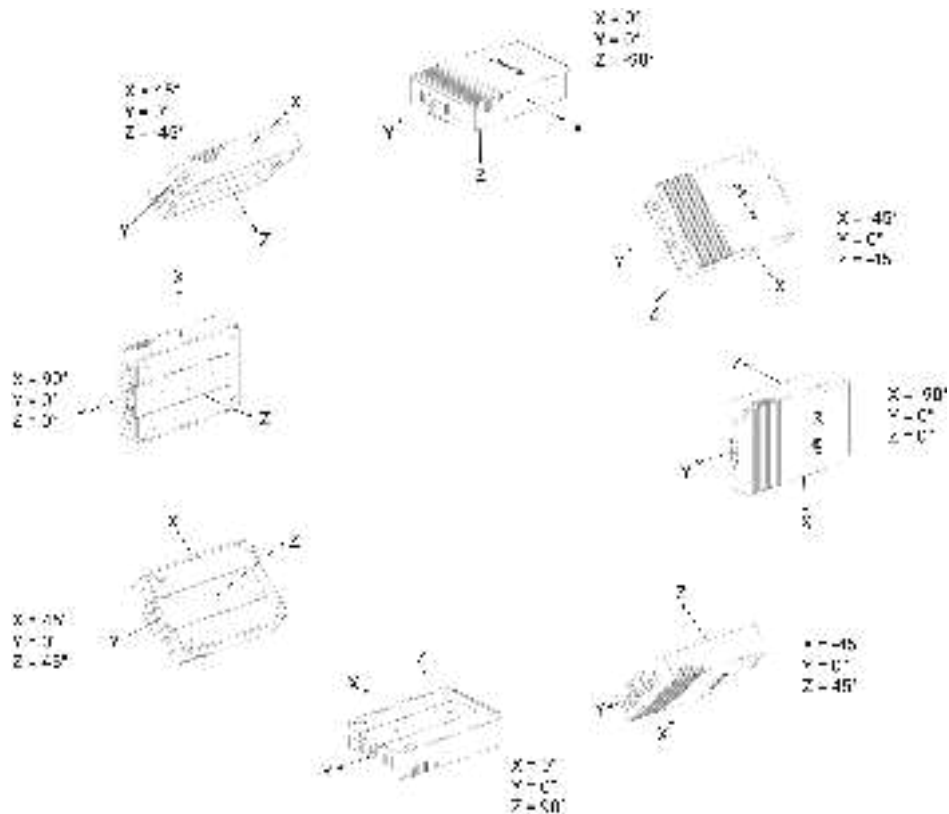


**If any of the above items is missing or damaged, please contact your sales Representative.**

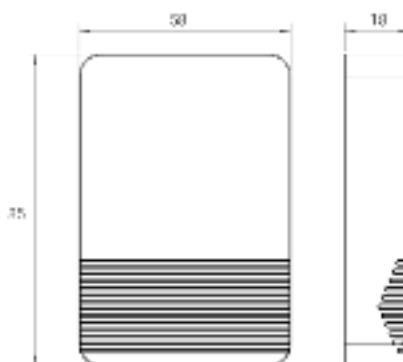
## 2.2 Hardware Overview



When you install EM320-TILT on site, below is the angle number you can expect with corresponding device gesture.



## 2.3 Dimensions(mm)



## 2.4 Power Button

The LED indicator and power button are inside the device. Switch on/off and reset can also be configured via NFC.

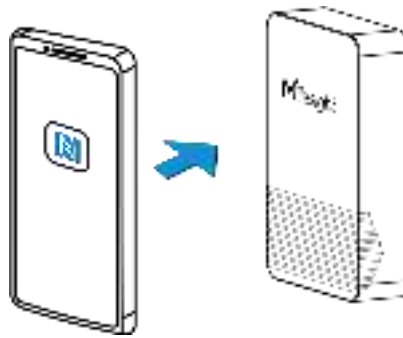
Function	Action	LED Indication
Turn On	Press and hold the button for more than 3 seconds.	Off → On
Turn Off	Press and hold the button for more than 3 seconds.	On → Off
Reset	Press and hold the button for more than 10 seconds.	Blink 3 times.
Check On/Off Status	Quickly press the power button.	Light On: Device is on.
		Light Off: Device is off.

## 3. Operation Guide

### 3.1 NFC Configuration

EM320-TILT sensor can be monitored and configured via NFC. Please refer the following steps to complete configuration.

1. Download and install “Milesight ToolBox” App from Google Play or Apple App Store.
2. Enable NFC on the smartphone and launch Milesight ToolBox.
3. Attach the smartphone with NFC area to the device to read device information. Basic information and settings of the device will be shown on ToolBox App if it's recognized successfully. You can read and configure the device by tapping the Read/Write device on the App. In order to protect the security of the device, please change password when first configuration. The default password is **123456**.

**Note:**

- 1) Ensure the location of smartphone NFC area and it's recommended to take off phone case.
- 2) If the smartphone fails to read/write configurations via NFC, keep the phone away and back to try again.
- 3) EM320-TILT sensor can also be configured by dedicated NFC reader, which can be purchased from Milesight IoT.

## 3.2 LoRaWAN Settings

LoRaWAN settings is used for configuring the transmission parameters in LoRaWAN® network.

**Basic LoRaWAN Settings:**

Go to **Device > Settings > LoRaWAN Settings** of ToolBox App to configure join type, App EUI, App Key and other information. You can also keep all settings by default.

Device EUI

24E124785C381440

\* APP EUI

24e124c0002a0001

\* Application Port

- 85 +

Join Type

OTAA

\* Application Key

\*\*\*\*\*

LoRaWAN Version

V1.0.3

Work Mode

Class A



Confirmed Mode ? ☒

Rejoin Mode ☒

Set the number of detection signals sent ?

32

ADR Mode ? ☒

Spreading Factor ?

SF10-DR2

TXPower

TXPower0-16 dBm

Parameters	Description
Device EUI	Unique ID of the device which can also be found on the label.
App EUI	Default App EUI is 24E124C0002A0001.
Application Port	The port is used for sending and receiving data, default port is 85.
Join Type	OTAA and ABP mode are available.
Application Key	Appkey for OTAA mode, default is 5572404C696E6B4C6F52613230313823.
Device Address	DevAddr for ABP mode, default is the 5 <sup>th</sup> to 12 <sup>th</sup> digits of SN.
Network Session Key	Nwkskey for ABP mode, default is 5572404C696E6B4C6F52613230313823.
Application Session Key	Appskey for ABP mode, default is 5572404C696E6B4C6F52613230313823.
LoRaWAN Version	V1.0.2, V1.0.3 are available.
Work Mode	It's fixed as Class A.
RX2 Data Rate	RX2 data rate to receive downlinks.
RX2 Frequency	RX2 frequency to receive downlinks. Unit: Hz
Spread Factor	If ADR is disabled, the device will send data via this spread factor.
Confirmed Mode	If the device does not receive ACK packet from network server, it will resend data once.
Rejoin Mode	Reporting interval $\leq$ 35 mins: the device will send a specific number of LinkCheckReq MAC packets to the network server every reporting interval or 2*reporting interval to validate connectivity; If there is no response, the device will re-join the network. Reporting interval $>$ 35 mins: the device will send a specific number of

	LinkCheckReq MAC packets to the network server every reporting interval to validate connectivity; If there is no response, the device will re-join the network.
Set the number of packets sent	When rejoin mode is enabled, set the number of LinkCheckReq packets sent. <b>Note:</b> the actual sending number is <b>Set the number of packet sent + 1</b> .
ADR Mode	Allow network server to adjust data rate of the device.
Tx Power	Transmit power of the device.

**Note:**

- 1) Please contact sales for device EUI list if there are many units.
- 2) Please contact sales if you need random App keys before purchase.
- 3) Select OTAA mode if you use Milesight IoT cloud to manage devices.
- 4) Only OTAA mode supports rejoin mode.

**LoRaWAN Frequency Settings:**

Go to **Settings > LoRaWAN Settings** to select supported frequency and select channels to send uplinks. Make sure the channels match the LoRaWAN® gateway.



If frequency is one of CN470/AU915/US915, you can enter the index of the channel that you want to enable in the input box, making them separated by commas.

**Examples:**

- 1, 40: Enabling Channel 1 and Channel 40
- 1-40: Enabling Channel 1 to Channel 40
- 1-40, 60: Enabling Channel 1 to Channel 40 and Channel 60
- All: Enabling all channels
- Null: Indicates that all channels are disabled

\* Support Frequency

AU915

Enable Channel Index ⓘ

8-15

Index	Frequency/MHz ⓘ
0 - 15	915.2 - 918.2
16 - 31	918.4 - 921.4
32 - 47	921.6 - 924.6
48 - 63	924.8 - 927.8
64 - 71	915.9 - 927.1

### 3.3 Basic Settings

Go to **Device > Settings > General Settings** to change the reporting interval, etc.

Reporting Interval - 1080 min

Change Password ☐

Parameters	Description
Reporting Interval	Reporting interval of transmitting current sensor values to network server. Default: 1080 mins, Range: 1-1080 mins
Change Password	Change the password for ToolBox App or software to read/write this device.

### 3.4 Threshold Settings

Go to **Device > Settings > Threshold Settings** to enable the threshold settings and input the angle threshold. You can set a relative initial surface to measure the deviance from an initial one and if the device detects the angle of a certain axis reaches the threshold based on the initial position, it will upload the current data instantly.

The screenshot shows the 'Deflection Angle' configuration screen. At the top, there is a toggle switch for 'Deflection Angle' which is turned on. Below it, the 'Relative Initial Surface' section includes a help icon, 'Setting' and 'Clear' buttons, and a text box showing the current triaxial angle: '(0.00°, 0.00°, -90.00°)'. The 'X-axis' section has a toggle switch turned on and two input fields for 'Over / °' and 'Below / °'. The 'Y-axis' and 'Z-axis' sections each have a toggle switch turned off. The 'Alarm Condition' section has a help icon and a large text input field. At the bottom, there are two sections: 'Alarm Reporting Interval' with a minus button, a value of '1', and a plus button followed by 'min'; and 'Alarm Reporting Times' with a minus button, a value of '2', and a plus button.

Parameters	Description
<u>Relative Initial Surface</u>	<p>Click <b>Setting</b> to set current position of device as initial position to measure the deflection angle.</p> <p>Click <b>Clear</b> to change the initial position back to (0.00°, 0.00°, -90.00°).</p> <p><b>Note:</b> after writing <b>Setting</b> or <b>Clear</b> configuration, click <b>Read</b> to read the device to check if the initial position changes successfully.</p>
Over / °	The maximum/upper limit of angle threshold.
Below / °	The minimum/lower limit of angle threshold.
Alarm Condition	<p>Acceptable elements are "X", "Y", "Z", "and", "or" "only", it takes 2 or 3 axes to complete an expression and the device will only read from left to right. If left blank, it will consider the condition as "or".</p> <p><b>Example:</b></p> <p>1) XandYorZ means (X and Y) or Z, that is XandY meets the threshold or Z meets the threshold.</p> <p>2) XorYandZ means (X or Y) and Z, that is XandZ meets the threshold or YorZ meets the threshold.</p>

Alarm Reporting Interval	After the threshold is triggered, the device will detect if the threshold is triggered again according to this reporting interval.
Alarm Reporting Times	After the threshold is triggered, the device will detect according to Alarm Reporting Interval and if still triggered, the device will send the certain number of alarms to NS.

**Example:**

When X axis is detected to  $0^\circ$  ( $0^\circ - 1.91^\circ = -1.91^\circ < -1^\circ$ ), it will trigger the threshold and upload a alarm package right away. If it changes back to normal, the device will also upload a data package immediately; if not, it will send alarm package after 1 minute. This process will repeat 2 times.

The screenshot shows the 'Deflection Angle' configuration screen. At the top, there is a toggle switch for 'Deflection Angle' which is turned on. Below it, the 'Relative Initial Surface' section includes a 'Set Initial' button and a 'Clear' button. A text box displays 'The triaxial angle relative to the initial face is (1.91°, -2.03°, -87.21°)'. The 'X-axis' section has a toggle switch turned on, with input fields for 'Over / °' set to 60.00 and 'Below / °' set to -1.00. The 'Y-axis' and 'Z-axis' sections have their respective toggle switches turned off. The 'Alarm Condition' section has an empty input field. At the bottom, the 'Alarm Reporting Interval' is set to 1 minute, and the 'Alarm Reporting Times' is set to 2.

## 3.5 Maintenance

### 3.5.1 Upgrade

1. Download firmware from Milesight website to your smartphone.
2. Open ToolBox App and click **Browse** to import firmware and upgrade the device.

**Note:**

- 1) Operation on ToolBox is not supported during the upgrade.
- 2) Only Android version ToolBox supports the upgrade feature.

SN	6785C38144050018
Model	EM320-TILT-868M
Firmware Version	V1.1-a2
Hardware Version	V1.1
Manual Upgrade	

Browse

### 3.5.2 Backup

EM320-TILT sensor supports configuration backup for easy and quick device configuration in bulk. Backup is allowed only for devices with the same model and LoRaWAN® frequency band.

1. Go to **Template** page on the App and save current settings as a template. You can also edit the template file.
2. Select one template file that saved in the smartphone and click **Write**, then attach it to another device to write configuration.

Template

empty template

New Template

Please enter template name

EM320-TILT-868M

Cancel OK

**Note:** Slide the template item to the left to edit or delete it. Click the template to edit the configurations.



### 3.5.3 Reset to Factory Default

Please select one of following methods to reset device:

**Via Hardware:** Hold on reset button inside the device more than 10s.

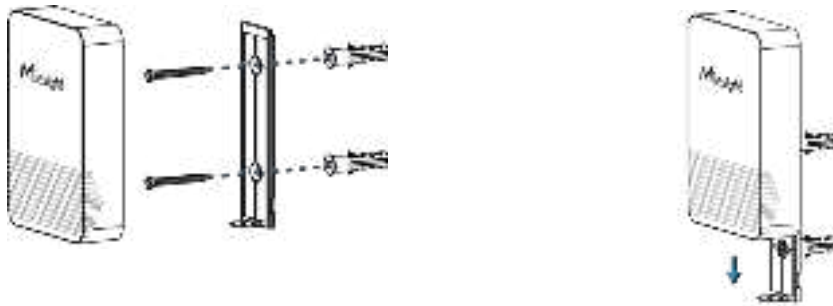
**Via ToolBox App:** Go to **Device > Maintenance > Reset** to click **Reset**, then attach smart phone with NFC area to device to complete reset.



## 4. Installation

### Wall Mounting:

1. Remove the backplate on the back of the device, screw the wall plugs into the wall and fix the backplate with screws on it, then install back the device. Note that the vent of device should not face upwards when installing.

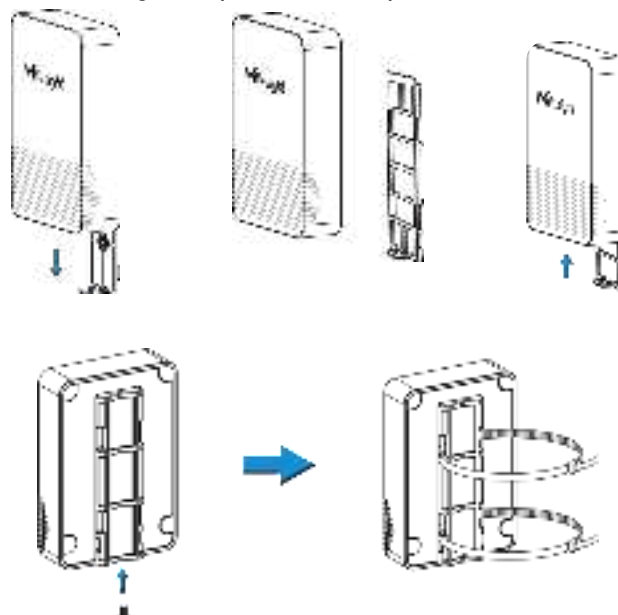


2. Fix the bottom of the device to the cover with a fixing screw.



### Pole Mounting:

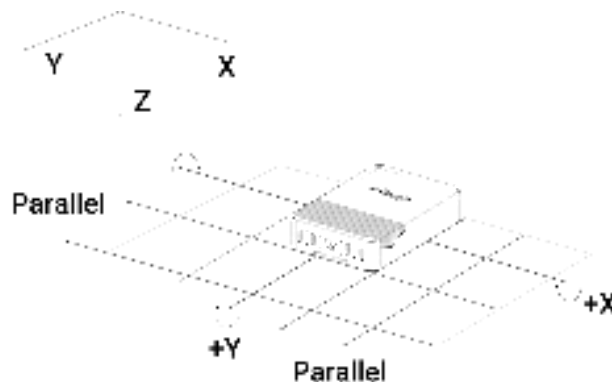
Switch the backplate on the back of the device to the pole mounting plate and fix the plate with a screw, then pass a cable tie through the plate and wrap it with device to the pole.





**Installation Location:**

- Ensure the location of device is within the communication range of LoRaWAN® gateway and keep it away from metal objects.
- Ensure that the device is tightly attached without any gap to the surface to be measured of a certain object, and one of the 3 axes should be paralleled with the measuring axis of the object, otherwise, the result may not be correct.



## 5. Device Payload

All data are based on following format (HEX), the Data field should follow little-endian:

Channel1	Type1	Data1	Channel2	Type2	Data2	Channel 3	...
1 Byte	1 Byte	N Bytes	1 Byte	1 Byte	M Bytes	1 Byte	...

For decoder examples please find files on <https://github.com/Milesight-IoT/SensorDecoders>.

### 5.1 Basic Information

EM320-TILT sensors report basic information of sensor whenever joining the network.

Channel	Type	Description
ff	01 (Protocol Version)	01=>V1
	09 (Hardware Version)	01 40 => V1.4
	0a (Software Version)	01 14 => V1.14
	0b (Power On)	Device is on
	0f (Device Type)	00: Class A, 01: Class B, 02: Class C
	16 (Device SN)	16 digits

**Example:**

ff0bff ff0101 ff166785c38144050018 ff090110 ff0a0101 ff0f00					
Channel	Type	Value	Channel	Type	Value
ff	0b (Power On)	ff (Reserved)	ff	01 (Protocol Version)	01 (V1.0)
Channel	Type	Value	Channel	Type	Value
ff	16	6785c381440	ff	09	0110

	(Device SN)	50018		(Hardware version)	(V1.1)
Channel	Type	Value	Channel	Type	Value
ff	0a (Software version)	0101 (V1.1)	ff	0f (Device Type)	00 (Class A)

## 5.2 Sensor Data

EM320-TILT sensors report sensor data according to reporting interval (1080mins by default).

Item	Channel	Type	Description
Battery Level	01	75	UINT8, Unit: %
Angle	03	d4	6 Bytes, INT16 angle_x (2B) + angle_y(2B) + angle_z(2B), Unit:°, Resolution: 0.01° angle_x bit0: 0-normal; 1-trigger angle_y bit0: 0-normal; 1-trigger angle-z bit0: 0-normal; 1-trigger <b>Note:</b> the angles are based on <a href="#">relative initial surface</a> .

### Example:

017564 03d498fd 44ff 6b22					
Channel	Type	Value	Channel	Type	Value
01	75 (Battery Level)	64=>100%	03	d4 (Angle)	X: 98 fd => fd 98 = $(-616-0)/2 * 0.01$ = -3.08° Y: 44 ff => ff 44 = $(-188-0)/2 * 0.01$ = -0.94° Z: 6b 22 => 22 6b = $(8811-1)/2 * 0.01$ = 44.05° X=fd 98 => 1111 1101 1001 1000 X_bit0: 0 => normal Y_bit0: 0 => normal Z_bit0: 1 => trigger

### 5.3 Downlink Commands

EM320-TILT sensors support downlink commands to configure the device. The application port is 85 by default.

Command	Channel	Type	Description
Reporting Interval	ff	03	2 Bytes, unit: s
Reboot		10	ff
Threshold Alarm		06	9 bytes: CTRL (1B) + Min (2B) + Max (2B) + Alarm Reporting Interval (2B) + Alarm Reporting Times(2B) CTRL: Bit 2~0: 000-disable 001-below (minimum threshold) 010-over (maximum threshold) 011-within 100-below or over Bit 5~3: 001: X-axis angle 010: Y-axis angle 011: Z-axis angle Bit 6~7: 00 Min./Max. Threshold: INT16/100, Unit: °
Initial Position		62	ff-set current position as initial position fe-set the initial position to (0.00°, 0.00°, -90.00°)
Alarm Condition		63	8 bytes, hex string of ASCII expression; if ASCII expression takes less than 8 bytes, add 0 in the end to meet the size. <b>Note:</b> before setting the condition, ensure the corresponding axis threshold is enabled, or this condition will not work.

#### Example:

1. Set reporting interval as 20 minutes.

ff03b004

Channel	Type	Value
ff	03 (Set Reporting Interval)	b0 04=>04 b0=1200s =20 minutes

2. Set X-axis threshold between 10° and 20°, it will detect the threshold every 1 minute, send alarm 3 times at most.

ff060ce803d0073c000300		
Channel	Type	Value
ff	06 (Set Threshold)	0c => 00 001 100 = when X axis angle is below or over, e803 => <u>03e8</u> =1000/ <u>100</u> = 10.00° d007 => <u>07d0</u> = 2000/ <u>100</u> = 20.00° 3c00 => 60 s = 1 min 0300 => 00 03 = 3 times

3. Reboot the device.

ff10ff		
Channel	Type	Value
ff	10 (Reboot)	ff (Reserved)

4. Set the alarm condition to be X and Y or Z, before setting ensure X, Y and Z thresholds are enabled.

ff635826597c5a000000		
Channel	Type	Value
ff	63 (Set Alarm Condition)	5826597c5a000000 = X&Y Z

5. Set current position as initial position.

ff62ff		
Channel	Type	Value
ff	62 (Set Initial Position)	ff = set current position as initial position

-END-