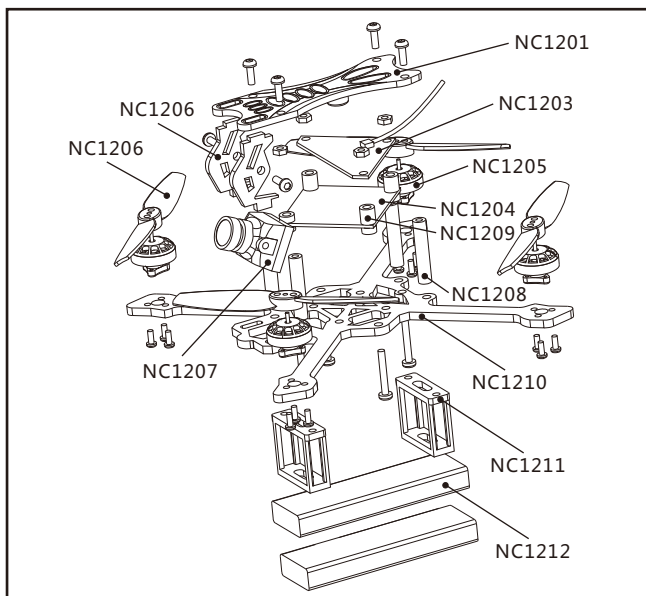




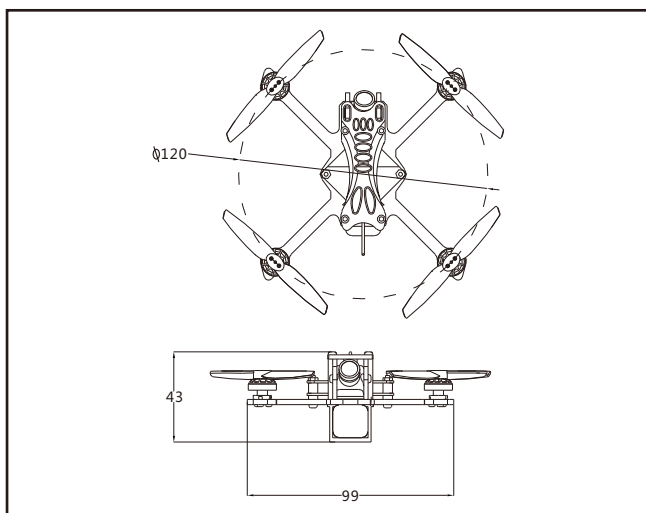
Item	Part No.	RTF	FLY More
120mm toothpick frame	NC1210	1	1
NanoX F4FS V1.0 flight controller	NC1204	1	1
Eachine NC1103 KV8500	NC1205	4	4
HQPROP T65 bi-blade propeller	NC1206	2	2
Caddx EOS2 v2 version 4:3	NC1207	1	1
VTX: 5.8g 25mw~200mw switchable Whoop VTX	NC1203	1	1
3.8v 460mah battery	NC1212	2	10
6in1 6-way LIPO/LIHV Charger		1	1
FS-I6 2.4G radio transmitter		1	1
Eachine VR009 5.8G 40CH goggles		1	1
Propeller disassemble tool		1	1
Screwdriver		1	1
LED&Buzzer PCB top board	NC1201	1	1
M2*D3.5*L20 Aluminum Alloy column	NC1208	4	4
Damping ball	NC1209	4	4
Battery mounted tray	NC1211	2	2

1. Specification

Brand Name: Eachine
Item Name: NOVICE-II 1-2S Toothpick RTF & Fly more
Wheelbase: 120mm
Size: 100mm*100mm*40mm
Weight: 50g(without battery)

2. Features

Nano X F4 pro flight controller
Powerful and smoothly
Led Strip ready
Built-in Buzzer
New design 1103 KV8500 motors
Camera Angle adjustable
VTX power switchable 25mw~200mw
Smartaudio ready , change VTX bands, powers, channels via OSD
Ready to fly
Compatible both for 1s-2s Lipo/LIHV

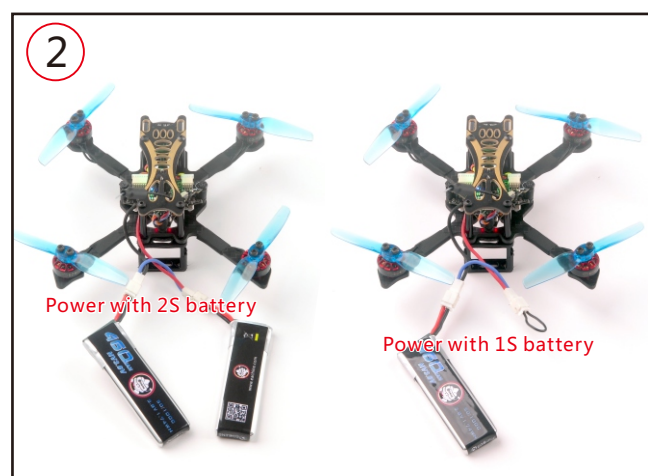


3. Start FPV Flight

Start by powering on your Radio and Goggles. NOVICE-II comes already bound to your radio and on the right video channel matched with your goggles. Power on NOVICE-II by sliding the battery into the battery tray and plugging it in. Once the battery is plugged in, set NOVICE-II on a stable surface so it can calibrate. Calibration takes a few seconds then NOVICE-II is ready to fly.



Install 4x AA 1.5v battery to the radio and push the power switch to turn on the radio. If the throttle stick was not at the bottom position the radioter will alarm.



Connect the battery for the NOVICE-II



.Turn on the Vr009 goggles and check the Video

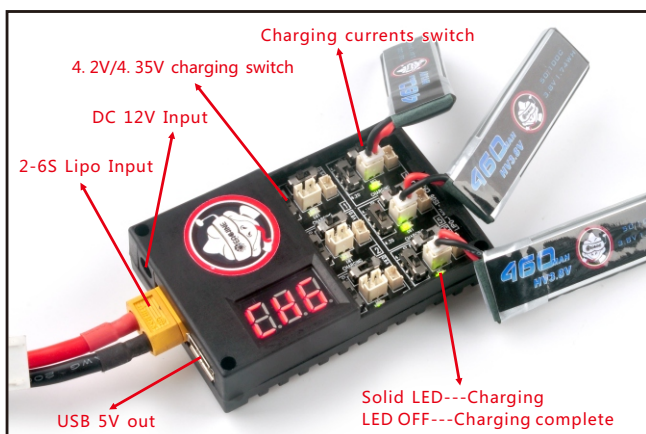


Toggle SWA(AUX1) switch to arm the NOVICE-II , you will find "ARMED" notice in the screen of the Goggles. Recommend Toggle SWC(AUX2) to choose Stable mode for the beginner. Happy flight and keep it safe.



Toggle SWC(AUX2) switch to select flight mode (Default is Acro mode)

4. Charger the Lipo Battery

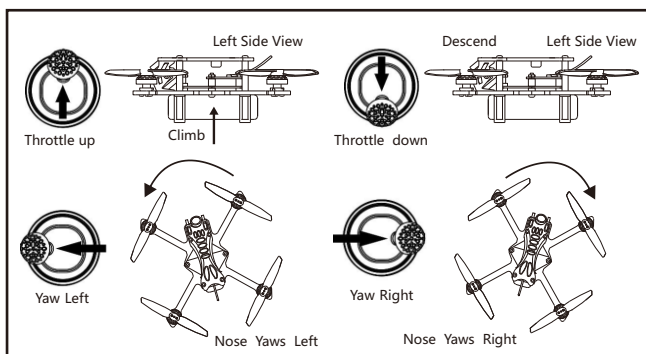


△ Ports are numbered 1-6. Do not put more than one battery on a single port. For example: do not insert one battery on the Picoblade 1.25 plug and another on the same port with the PH 2.0 plug.

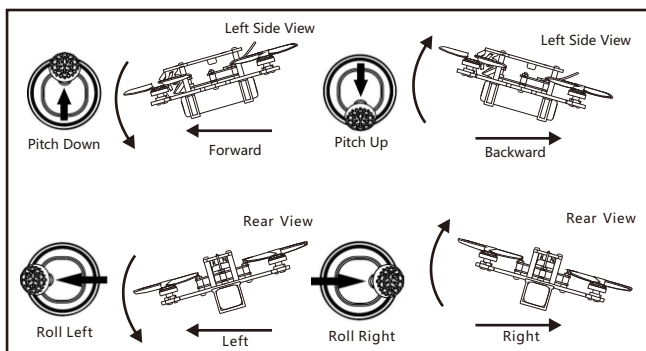
5. Flight and Radio Stick Controls

Always use caution when flying and operate in an open and controllable area. Please learn the flight controls first before powering on the aircraft to fly. The left stick controls throttle and yaw direction of NOVICE-II. The right stick controls pitch and roll of the aircraft.

Left Stick Diagram



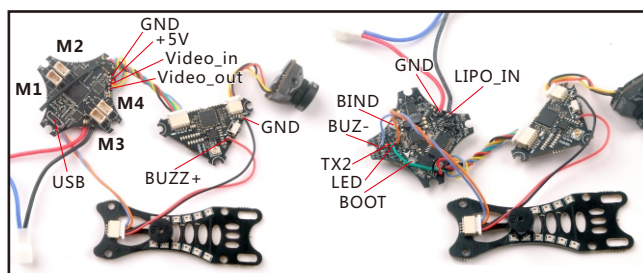
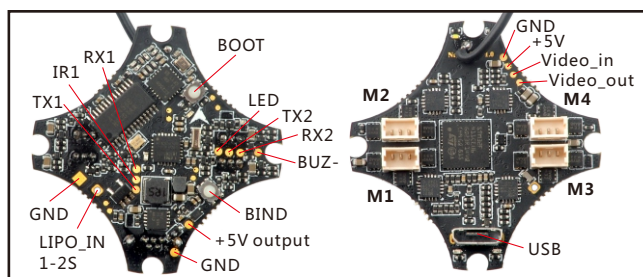
Right Stick Diagram



Important notice:

1. The belowing content are regarding the advanced tutorial. The drone comes out already finished all the settings and bound with the radio .
2. Don't mod to XT30 Plug , it will burnt the flight controller if mod to xt30 and use high discharge rating battery .

6. Flight controller connection diagram

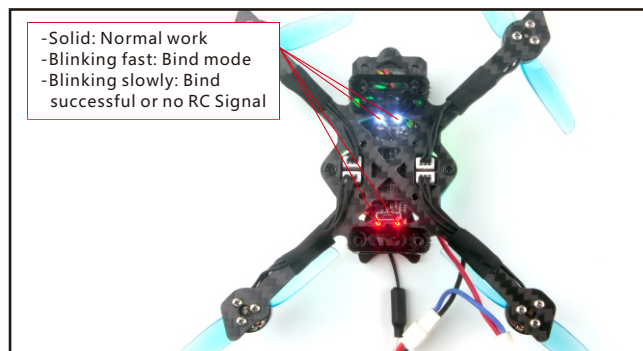


7. Binding procedure

1. Plug the usb and go to the CLI command tab in the betaflylight configurator, then type "bind_rx_spi", the receiver will getting into bind mode , and then make your Flysky radio to bind mode.

```
$M>De"000"0000000"000000000000$M> n0000000000e
Entering CLI Mode, type 'exit' to return, or 'help'
# bind_rx_spi
Binding..
```

2. Please Ensure the RX setup of your transmitter is in AFHDS 2A Mode. Then get your transmitter into binding mode : Turn on the transmitter while holding the bind button. The White and red LED on the flight controller should blinking fast first and then blinking slowly, this indicates binding successfully. Now you need to exit binding mode of the transmitter and re-connect the Novice-II to the computer, then the Red and white LED should be getting to be solid , this indicates the connection was established between the NOVICE-II and your transmitter.



8 Receiver configuration

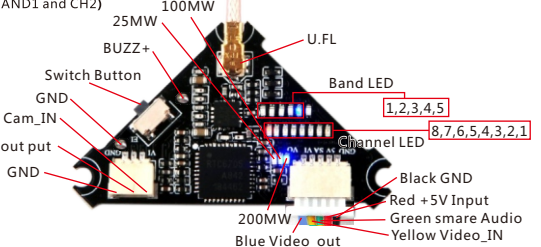
Please set Receiver mode to be SPI RX Support from the Configuration tab of the Betaflight Configurator, then select A7105_Flysky_2A Provider for AFHDS-2A Protocol Radio transmitter or Select A7105_Flysky Provider for AFHDS Protocol Radio transmitter, don't enable Serial RX since the Flight controller is integrated SPI BUS Receiver

Identifier	Configurations/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	115200	Disabled	AUTO	Disabled	AUTO
UART1	115200	Disabled	AUTO	Disabled	AUTO
UART2	115200	Disabled	AUTO	Disabled	TBS SmartAuc

Receiver	
SPI RX support	Receiver Mode
Note: The SPI RX provider will only work if the required hardware is on board or connected to an SPI bus.	
A7105_FLYSKY_2A	Flysky AFHDS-2A
Note: The SPI RX provider will only work if the required hardware is on board or connected to an SPI bus.	
SPI RX support	Receiver Mode
A7105_FLYSKY	Flysky AFHDS

9 VTX Bands and Channels setup

Blue LEDs and Red LED8 light on, indicating frequency 5917MHz (BAND5 and CH8)
 Blue LED1 and Red LED2 light on, indicating frequency 5845MHz (BAND1 and CH2)



Frequency and channel frequency table:

FR	CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
Band1		5865M	5845M	5825M	5805M	5785M	5765M	5745M	5725M
Band2		5733M	5752M	5771M	5790M	5809M	5828M	5847M	5866M
Band3		5705M	5685M	5665M	5645M	5625M	5605M	5585M	5565M
Band4		5740M	5760M	5780M	5800M	5820M	5840M	5860M	5880M
Band5		5658M	5695M	5732M	5769M	5806M	5843M	5880M	5917M

Notes:

Default vtx setting is 200mw but the VTX power LED indicate will always show 25mw when the quad was disarmed, because we have "set vtx_low_power_disarm=on" There are 3 ways to switch the vtx channels:

1. Short press to choose the VTX channel, press and holding the button to Choose the VTX Band (Can't save, it will lost the channel while power off)

2. Go to Betaflight CLI, type the command:

```
set vtx_band=3
set vtx_channel=1
set vtx_freq=5705
save
```

Notes: The vtx_freq should match the vtx_band and vtx_channel as the VTX Channel list shows.

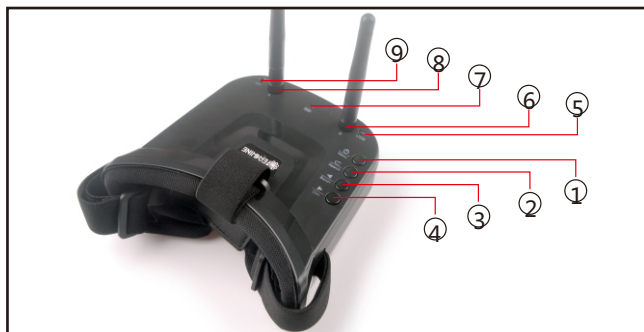
For example, if you set vtx_freq=5732, you should set vtx_band=5 and VTX_channel=3

3. Enable Smartaudio for UART2, then move the stick of the transmitter (THR MID+ YAW LEFT+ PITCH UP) to enter OSD Menu, Enter to Features, then enter to VTX SA to set VTX Band and channel

Identifier	Configurations/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	115200	Disabled	AUTO	Disabled	AUTO
UART1	115200	Disabled	AUTO	Disabled	AUTO
UART2	115200	Disabled	AUTO	Disabled	VTX (TBS Sm)



10 Goggles and VTX Receiver channel setting



Description:

- Key 1: Short press for MENU mode; Long press (More than 3 sec) for Power ON/OFF.
- Key 2: Short press for Auto-Searching (Automatic selection of the strongest channel).
- Key 3: Short press for Band+ (Change bands A-B-E-F-R circularly).
- Key 4: Short press for Channel+ (Change channels 1-2-3-4-5-6-7-8 circularly).
- Micro-USB Charging port: Supports DC5V only.
- Antenna port B: RP-SMA male.
- Charging indicator: Red light when charging light; full power, the indicator goes off.
- Antenna port A: RP-SMA male.
- AV Jack: In RF receiving mode can output AV signal; In AV mode can enter the video signal.

Menu Operation Instructions:

In normal mode, press Key 1 to enter the MENU mode.

In MENU mode:

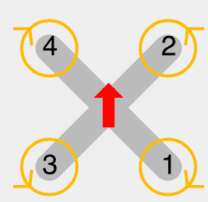
- Key 1: Select the option bar.
- Key 2: Return to normal mode.
- Key 3: Value -.
- Key 4: Value +.

Frequency (5.8GHz):

Band	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
A	5865	5845	5825	5805	5785	5765	5745	5725
B	5733	5752	5771	5790	5809	5828	5847	5866
E	5705	5685	5665	5645	5625	5605	5585	5565
F	5740	5760	5780	5800	5820	5840	5860	5880
R	5658	5695	5732	5769	5806	5843	5880	5917

11. Mixer type and ESC/motor protocol

Quad X



Props IN

Fix the CW propeller onto the M1 and M4 motor (CW motors)
 Fix the CCW propellers onto the M2 and M3 motor (CCW motors)

☐ Motor direction is reversed

ESC/Motor Features	
DSHOT600	ESC/Motor protocol
☐ MOTOR_STOP	Don't spin the motors when armed
☐ Disarm motors regardless of throttle value (When ARM is configured in Modes tab via AUX channel)	
5	Disarm motors after set delay [seconds] (Requires MOTOR_STOP feature)
4.5	Motor Idle Throttle Value [percent]

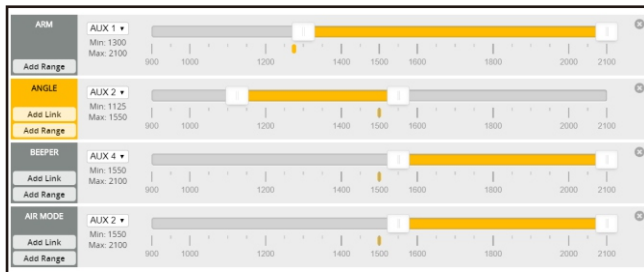
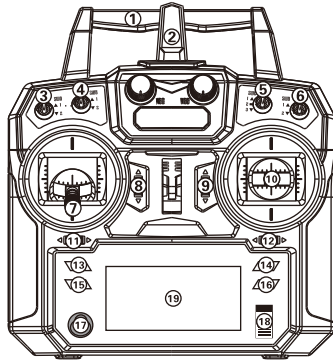
12. Default PID setting and currents setting

	Proportional	Integral	Derivative	Feedforward	RC Rate	Super Rate	Max Vel [deg/s]	RC Expo
ROLL	40	50	32	60	1.00	0.76	833	0.10
PITCH	42	50	37	60	1.00	0.76	833	0.10
YAW	65	55	0	100	1.00	0.70	667	0.10

Voltage Meter	
Battery	0 V
	110 Scale
	10 Divider Value
	1 Multiplier Value
Amperage Meter	
Battery	0.00 A
	1175 Scale [1/10th mV/A]
	0 Offset [mA]

13. Radio channels/Switch and Betaflight mode setting

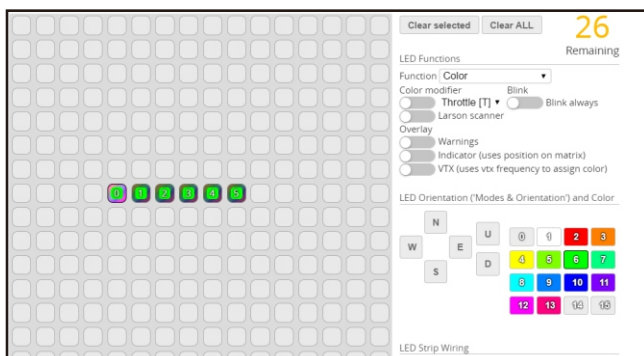
1. Handle
2. Antenna
3. Switch A (arm and disarm)
4. Switch B
5. Switch C (Mode switch)
6. Switch D
7. Left stick
8. Left trim
9. Right trim
10. Right stick
11. Left trim
12. Right trim
13. Up
14. press the Enter key
15. Down
16. Short press the Cancel key
17. Code keys
18. Switch
19. LCD Display



14. AUX Channel set up

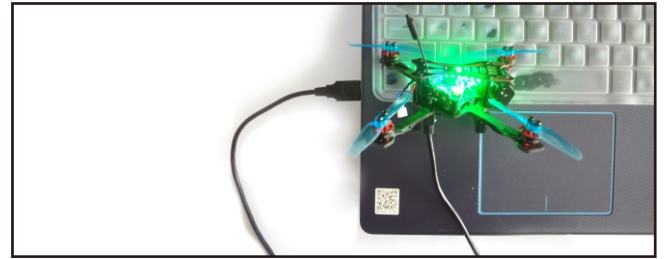


15. LED Strip Setting

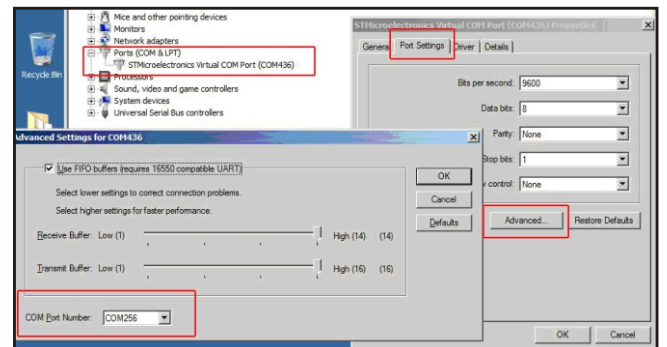


16 ESC Check and Flash firmware

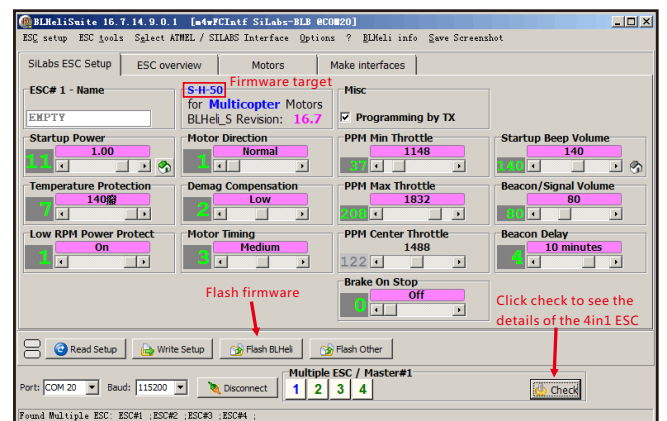
1. Download New release BLHeliSuite from:
<https://www.mediafire.com/folder/dx6kfaasyo241/BLHeliSuite>
2. Connect the NOVICE-II flight controller to computer



3. Open the Device Manager of your computer, find the Ports, please make sure the Com port Serial Number is under 255, otherwise it will can't connect to the BLHELISUITE. You can change the port serial number like the bellowing step :



4. Open the BLHELISUITE, Select SILABS BLHeli Bootloader (Cleanflight) from the third tab on the top side. Then Select the right Serial com port and Click connect. You can also Flash the new release BLHeli_s firmware via the BLHELISUITE, the firmware Target is "S-H-50"



17. Flight controller firmware update

1. Install latest STM32 Virtual COM Port Driver
<http://www.st.com/web/en/catalog/tools/PF257938>
2. Install STM BOOTLOAD Driver (STM Device in DFU MODE)
3. Open Betaflight configurator and choose firmware target "CrazybeeF4FS", then select the firmware version.
4. There are 2 ways to get in DFU Mode: 1). Press_and_hold_the_boot_button, then plug USB to computer 2). loading betaflight firmware and hit "flash", then it will getting into DFU Mode automatically.
5. Open Zadig tools to replace the drivers from STM32 Bootloader to WINUSB Driver.
6. Reconnect the flight controller to the computer after replace driver done, and open Betaflight Configurator, loading firmware and flash.

