STM32G4 Mixed Signal MCU

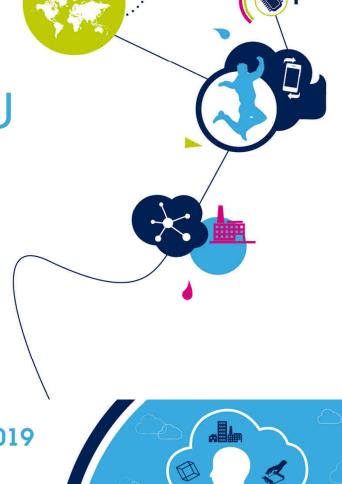
Hands-On Workshop

Karthik Chidambaranathan
Jason Stover
Bruno Montanari
The STMicroelectronics Team



Technology Tour 2019

Boston, MA | November 5



You need to have administration rights on your Laptop Computer to be able to install drivers and software and also to do the workshop.

System & Software requirements for Laptop Computer:

- Windows® 7 and later or MacBook running Windows using Parallels, VM Fusion
- Install Java™ Run Time Environment for 1.8.0 or later. If Java™ is not installed on your computer, we are providing the installer for the latest Java on the USB drive.

Minimum Recommended Hardware Requirements for Laptop Computer:

- Type A USB port
- 2+ GHz processor
- 4 GB of system memory (RAM)
- 10 GB of available disk space

Note: For laptops with only USB Type C ports, you will need a Type A (female) to Type C (male) adapter.



Overview

☐ STM32CubeMX: version 5.3.0 minimum

☐ STM32CubeG4: version 1.1.0 minimum

☐ STM32CubeProgrammer: version 2.1.0 minimum

☐ Keil MDK-ARM: version 5.28a minimum

☐ Keil MDK-ARM License: Professional Evaluation License Add On

☐ Tera Term or equivalent terminal emulator

☐ Java Runtime Environment: 1.8.0 minimum

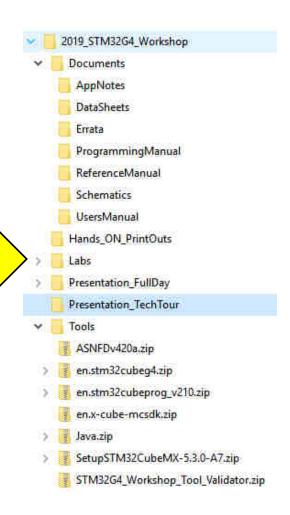


STM32G4 Workshop Installation Guide - Overview

- □ Copy the contents of your thumb drive or download to your C:\ root
- ☐ If not done automatically, name the top folder 2019 STM32G4 Workshop

This is the Labs folder. You will be here many times.

Note: We don't recommend copying to a deep path such as your Desktop or Documents because long path names can create build issues with some compilers.

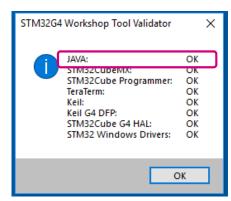




STM32G4 Workshop Installation Guide – Java JRE 1.8.0+

Java™ Run Time Environment 1.8.0 or later is required to run Cube software tools.

To check if you have the correct version of Java installed please launch the app "STM32G4_Workshop_Tool_Validator_vx.x.exe" on the USB drive.



If needed, the Java installer is located in the **Java** directory:

To install Java right Click on "**jre-8u201-windows-i586.exe**" and Run as administrator.



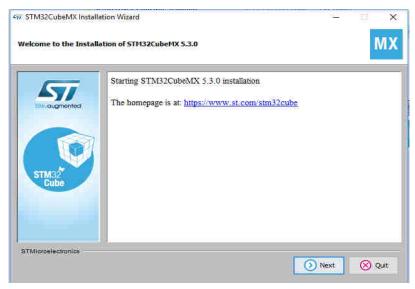


STM32G4 Workshop Installation Guide – CubeMX v5.1.0+

Unzip *en.SetupSTM32CubeMX-5.3.0.zip* and you will see this:



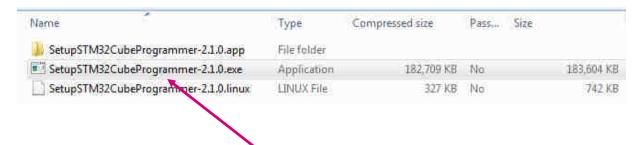
Right Click on SetupSTM32CubeMX-5.3.0.exe and Run as administrator:



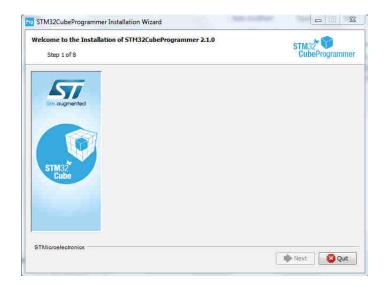


STM32G4 Workshop Installation Guide – CubeProgrammer v2.1.0

Unzip *en.stm32cubeprog_v2.1.0.zip* and you will see this:



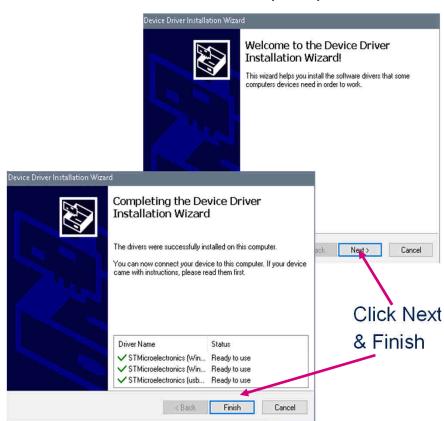
Right Click on SetupSTM32CubeProgrammer-2.1.0.exe and Run as administrator:

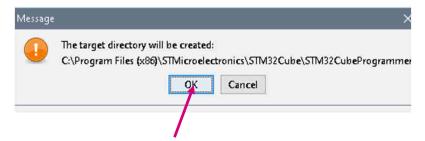




STM32CubeProgrammer v2.1.0

Install the Windows drivers if prompted



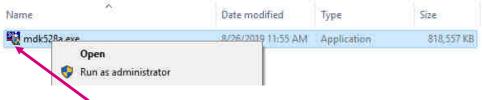


Click OK to create the Directory (if the directory does not already exist)



g

STM32G4 Workshop Installation Guide – Keil MDK-ARM v5.28a

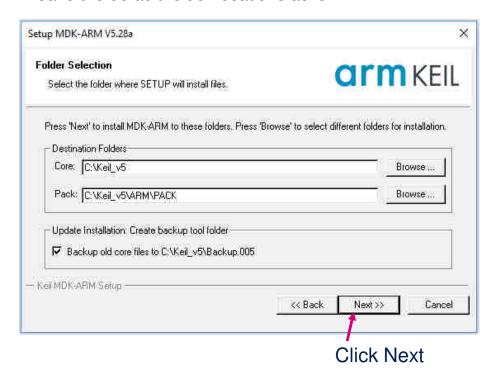


Right Click on mdk528a.exe and Run as administrator:

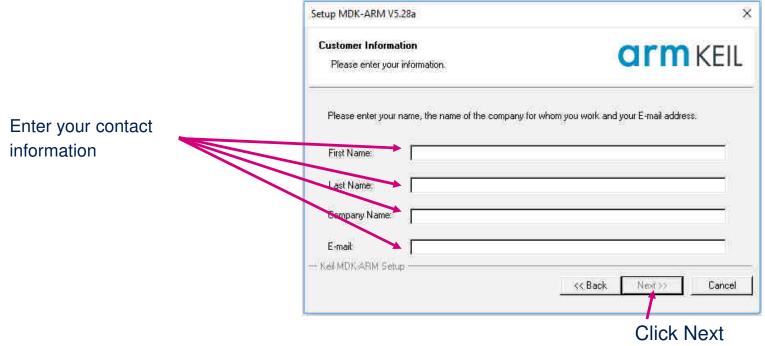




Leave the default folder locations as is

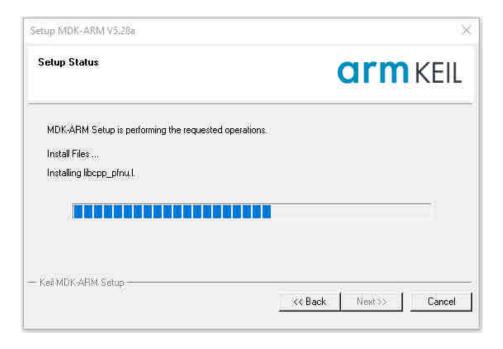


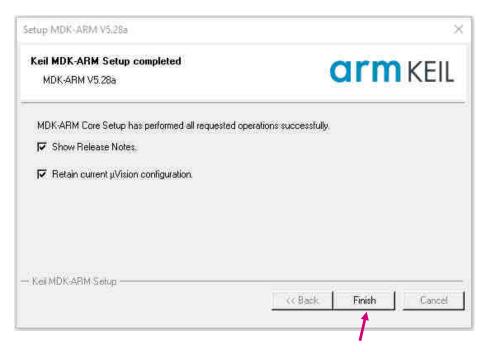






The installation should run and look like this:

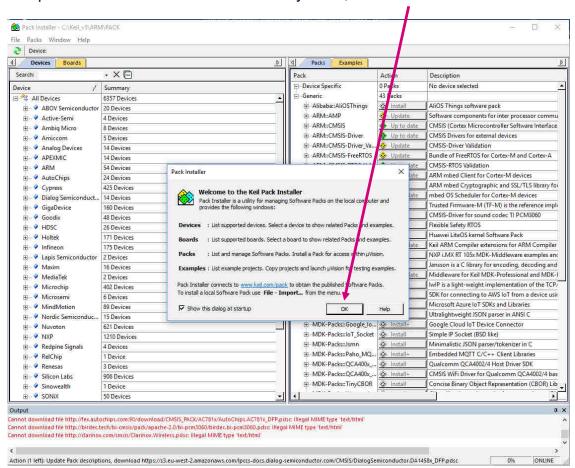




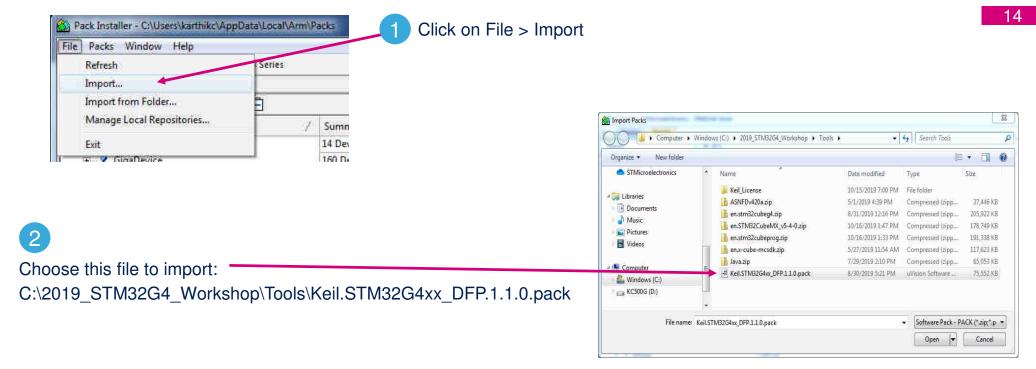
Once the installation has completed click Finish



The pack installer should automatically start, click OK to close the welcome screen



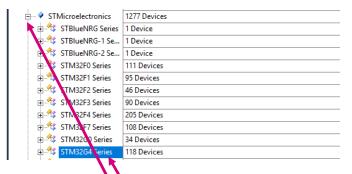




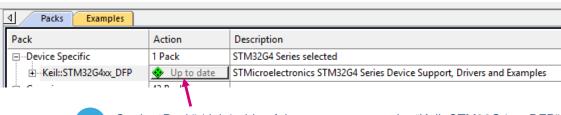
Wait until progress bar on bottom right corner is completed to 100%



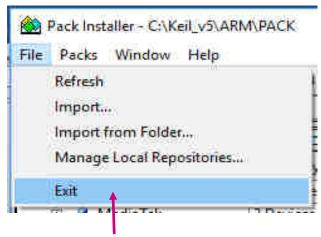




1 On the "Device" (left) side of the screen scroll down and click on the "+" to expand "STMicroelectronics" and then click on the "STM32G4 Series" to select it



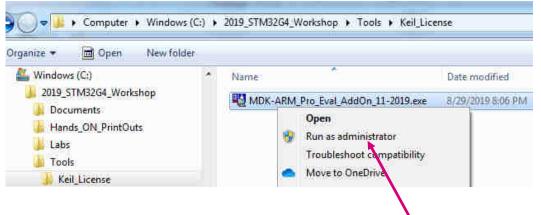
On the "Pack" (right) side of the screen, next to the "Keil: STM32G4xx_DFP", once complete it should show "Up to date"





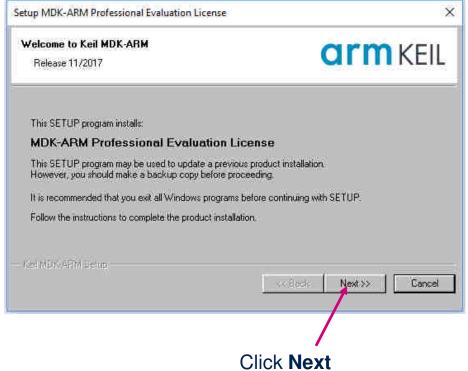
Click on "File" and then "Exit" to quick the pack installer, installation is now complete

Keil MDK-ARM License Installation



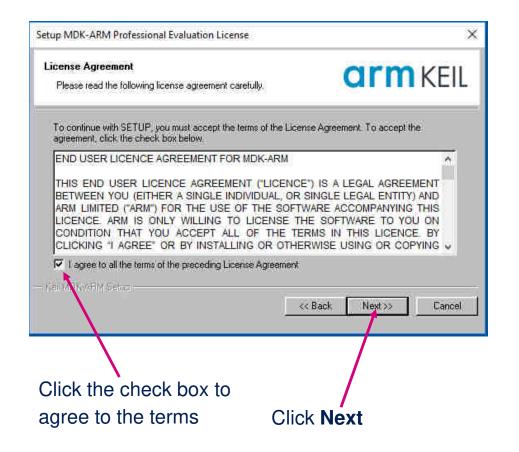
C:\2019_STM32G4_Workshop\Tools\Keil_License\ MDK-ARM_Pro_Eval_AddOn_11-2019.exe

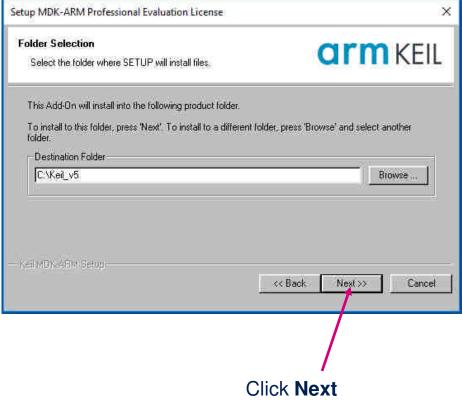
Right click and click "Run as administrator" to install the Professional Evaluation **License Add On**





Keil MDK-ARM License Installation

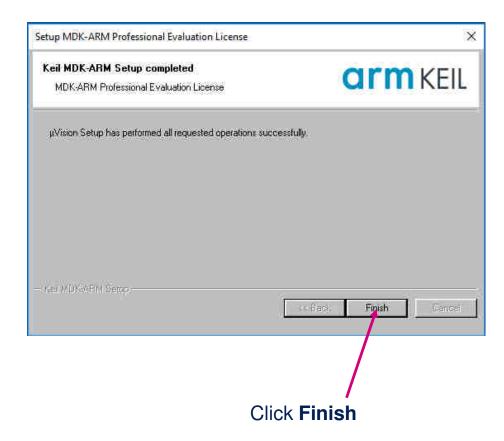






Setup MDK-ARM Professional Evaluation License **Customer Information** arm KEIL Please enter your information. Please enter your name, the name of the company for whom you work and your E-mail address. First Name: Last Name: Company Narie: E-mail: << Back Cancel Enter your contact Click Next information

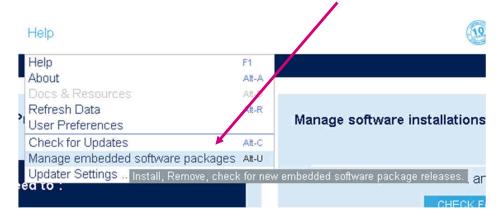
Keil MDK-ARM License Installation





STM32G4 Workshop Installation Guide – CubeG4, v1.1.0

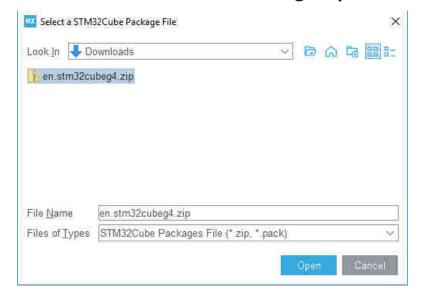
Open CubeMX and select *Manage embedded software packages*



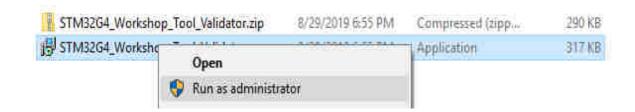




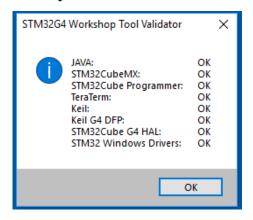
Select en.stm32cubeg4.zip



Run the STM32G4_Workshop_Tool_Validator.exe



See a workshop proctor for any installation issues

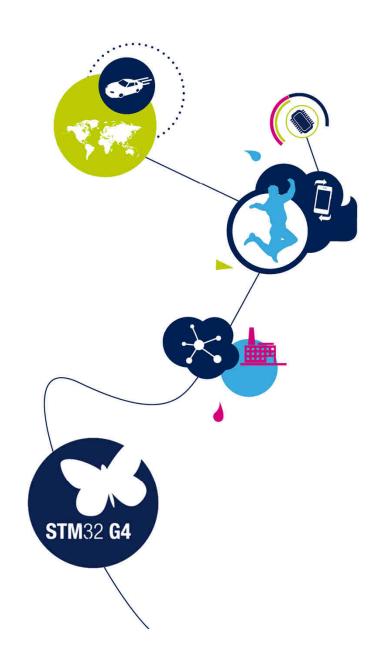




STM32G4 mixed-signal MCU workshop

Introduction to the STM32G4
Mainstream Series
Mixed Signal MCU







STM32G4 mixed-signal MCU workshop

Agenda

Software Installation

Introduction to the STM32G4 Series

Hands On: STM32G474 Discovery Kit Demo

Hands On: DAC Signal Generation

Hands On: Programmable Gain Amplifier

Break

Hands On: CORDIC Hardware Accelerator Filter Math Accelerator (FMAC) Overview

Hands On: Dual Bank Flash Live Firmware Upgrade

Wrap Up





STM32 portfolio

17 product series / More than 50 product lines





Note ●: Cortex-M0+ Radio Co-processor, ●: Cortex-M4 Co-processor

STM32 Rolling Longevity Commitment 24

Longevity commitment is renewed every year



starting January 1st 2019 → Until 2029

(launched in 2007)
(launched in 2009)
(launched in 2010)
(launched in 2011)
(launched in 2012)
(launched in 2012)
(launched in 2013)
(launched in 2014)
(launched in 2015)
(launched in 2016)
(launched in 2017)
(launched in 2018)
(launched in 2018)
(launched in 2019)





STM32G4 Series 25

Ideal for applications requiring MCU with advanced and rich analog peripherals



- Control applications (Motor Control...)
- Industrial equipment
- Instrumentation and Measurement
- Digital Power
 - Digital SMPS (switch mode power supply)
 - PFC (power factor correction)





STM32G4 Series – Key Messages



Performance

- Arm® Cortex®-M4 at 170 MHz
- 213 DMIPS and 550 CoreMark® results
- Better dynamic power consumption (163μA/MHz)
- ART Accelerator[™] (dynamic cache)
- Mathematical accelerators
- CCM-SRAM Routine Booster (static cache)



Rich Integrated Analog and Digital

- Op-Amps (Built-in gain), DACs, Comparators
- 12-bit ADCs 4Msps with hardware oversampling
- CAN-FD (flexible data rate 8Mbps bit rate)
- High resolution timer (184 ps)
- USB type-C Power Delivery3.0
- 1% RC accuracy [-5°..90°C], 2% full T° range



Safety and security focus

- Dual Bank Flash with ECC (error code correction)
- Securable Memory Area
- Hardware encryption AES-256
- SIL, Class-B
- SRAM with Parity bit

Secure Live Upgrade

Functional safety design packages



Complete portfolio

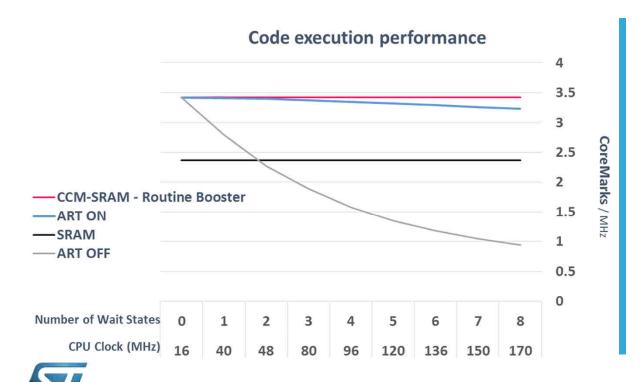
- Complements existing STM32F3 Series portfolio
- From -40°C up to 85 or 125°C devices

- From 32- up to 128-pin
- From 32KB to 512KB Flash



Greater Performance 27

Pure 170 MHz CPU performance (Arm® Cortex®-M4) with 3 accelerators



Arm Cortex-M4 with FPU **Up to 170** MHz CPU frequency Up to 213 DMIPS and 550 CoreMark® results

3 different HW accelerators:

- **ART accelerator** (~dynamic cache) → Full code acceleration (average)
- Routine Booster CCM-SRAM (~static cache) → determinism preserved
- Mathematical (CORDIC + FMAC





Mathematical Accelerators

Function acceleration and CPU offload

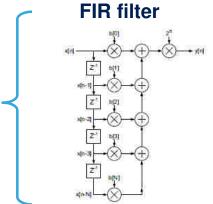
1. CORDIC (Trigo)

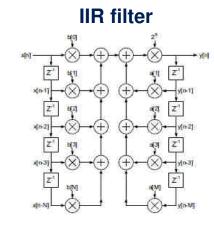
 Very helpful for Field Oriented Motor Control method (FOC)

- · Vector rotation (polar to rectangular): Sin, Cos
- Vector translation (rectangular to polar): Atan2, Modulus
- Sinh, Cosh, Exp
- Atan, Atanh
- Square root
- Ln

2. Filter Math Accelerator (FMAC)

- Can be used to create
 - 3p3z Compensator (→ Digital power)
 - Sigma Delta modulator
 - Noise Shaper



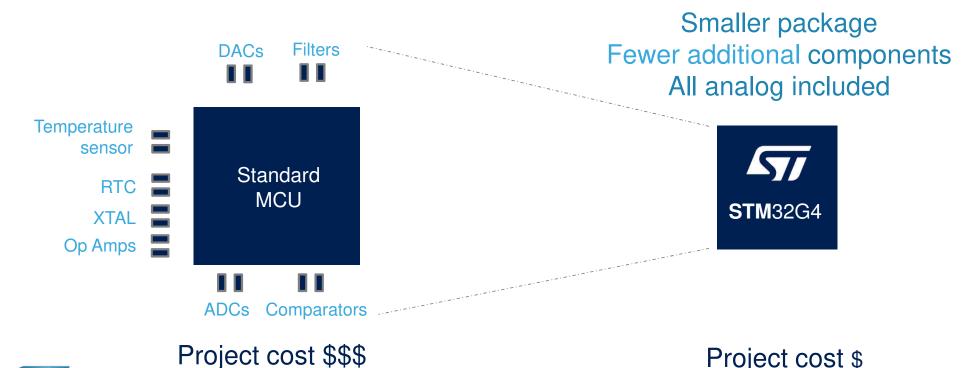






Reducing PCB Size and BOM Cost 29

System-on-Chip – All-in-one solution





Project cost \$



Rich, Advanced Analog 30

Mixed-signal SoC for wide variety of applications

ADC (up to 5)	Values
Topology	SAR 12-bit + HW oversampling → 16-bit
Sampling rate	Up to 4 Msps
Input	Single-ended and differential
Offset and Gain compensation	Auto calibration to reduce gain and offset

Op-Amp (up to 6)	Values
GBW	13 MHz
Slew rate	45 V/μs
Offset	3mV over full T° range 1.5mV @ 25°C
PGA Gain (accuracy)	2, 4, 8, 16, -1,-3,-7,-15 (1%) 32, 64, -31,-63 (2%)

DAC (up to 7)	Values
Sampling rate	15 Msps (internal) 1Msps (from buffered output)
Settling time	16ns

Comparator (up to 7)	Values
Power supply	1.62 3.6V
Propagation delay	16.7ns
Offset	-6 +2 mV
Hysteresis	8 steps:
	0, 9, 18, 27, 36, 45, 54, 63 mV







Key Features for Targeted Applications

Motor Control

Home appliances, E-bikes, Air Conditioning

- Fast CPU 170MHz
- Mathematical accelerator (Cordic)
- Advanced Motor Control timers
- Fast comparators
- 4Msps ADC-12bit + HW oversampling
- Op-Amp with built-in gain (PGA)
- DAC-12bit
- 1% RC accuracy (UART communication w/o external Xtal)



Digital Power

Rechargeable devices, drones, toys

- Low-thickness, small form-factor
- Low consumption in run mode ~ 160µA/MHz
- Embedded analog
- SAI (Sound Audio Interface)
- USB type-C Power Delivery 3.0



Industrial devices **Measurements**

Industrial equipment

- Fast CPU 170MHz
- Mathematical accelerator (Cordic)
- High temperature 125°C
- CAN FD support
- SPI, USART, I2C
- Advanced timers
- Real Time Clock with backup registers
- Dual bank flash for live upgrade
- AES & security



Servers, Telecom, EV Charging station

- Fast CPU 170 MHz
- Mathematical accelerator (Filtering)
- 12ch High Resolution timer (184ps)
- 4Msps ADC-12bit + HW oversampling
- Fast comparators (17ns)
- Embedded analog
- Dual bank flash for live upgrade
- AES & security
- FMAC for 3p3z compensation

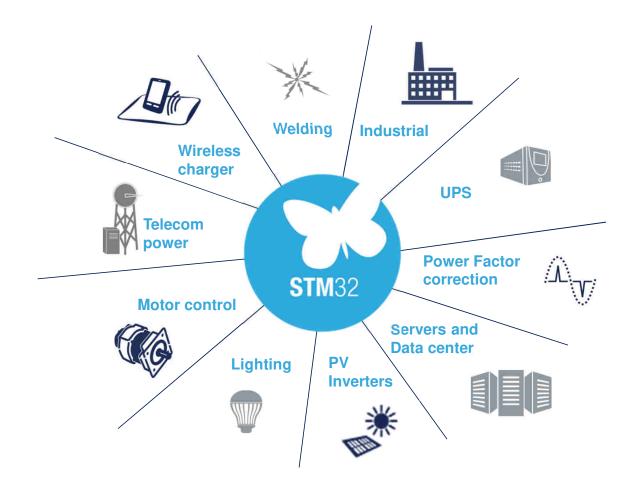






Ease Digital Power Conversion 32

Enhance your digital power solutions using the STM32G4's full features High **Resolution Timer** (HRTIM)







HRTimer – Not only High Resolution...

High resolution PWM

- 12 channels with 184ps resolution on frequency and duty cycle
- 184ps is equivalent to 5.4GHz timer clock

Flexible PWM generation

- 7x independent time base to create various shape of PWM
- 6x complementary pair PWM outputs
- Up to 32 set/reset transition per PWM period thx to the built-in crossbar
- Master/Slave configuration for multi phase converter

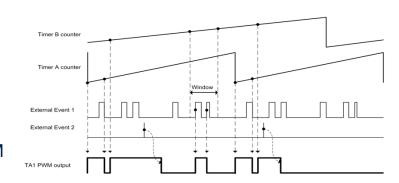
Multiple Event handler

- 6x Digital and Analog fault input
- 10x Events cycle to cycle current control or PWM restart (constant Ton/Toff)
- Blanking, windowing and digital filter

12 independent channels

 Any topology supported from 1x 12 PWM (triple interleaved LLC (servers application) up to 12x1 PWM (multiple independent buck converters (lighting)

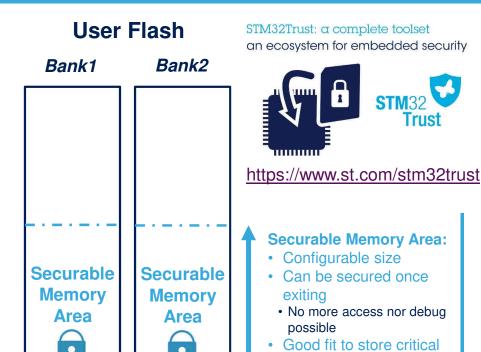






Greater Security 34

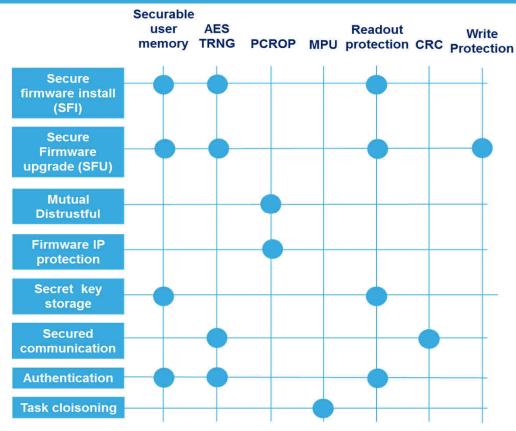
Integrated security features, ready for tomorrow's needs



data

Keys

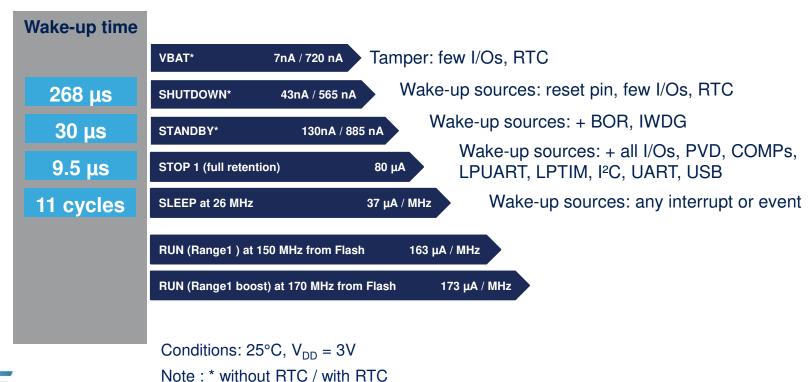
· Critical routines





Dynamic Efficiency Modes

When Mainstream MCU Series meets low-power requirements

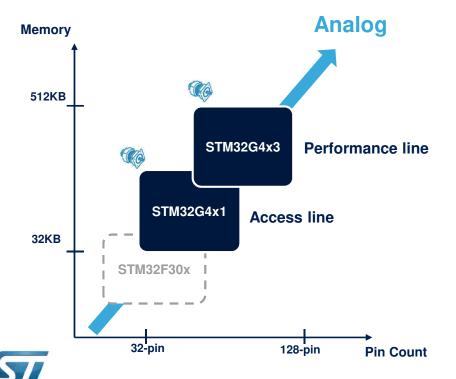




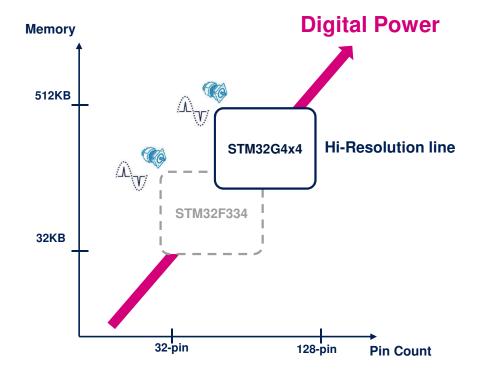


STM32G4 Products Lines 36

General Purpose



Applications Specific





Extensive & Innovative Peripheral Set 37

No compromise on what matters

Unit parameters	STM32G474 Hi-Resolution line	STM32G473 Performance line	STM32G431 Access line	
Core, frequency		ЛНz		
Flash (max)	512 Kbytes (2x2	56KB dual bank)	128 Kbytes single bank	
RAM (up to)	96 KI	oytes	22 Kbytes	
CCM -SRAM (code-SRAM)	32 KI	10 Kbytes		
12-bit ADC SAR	4x 1 4 MS	2x 12-bit 4 MSPS		
Comparator	7	4		
Op amp with 4 built-in gain values with 1% accuracy	6	3		
12-bit DAC	7	4		
Motor Control timer	3x (170	2x (170 MHz)		
CAN-FD	3	1x		
12 channel Hi-resolution Timer	1x	-	-	
Power supply	1.72 to 3.6 V			



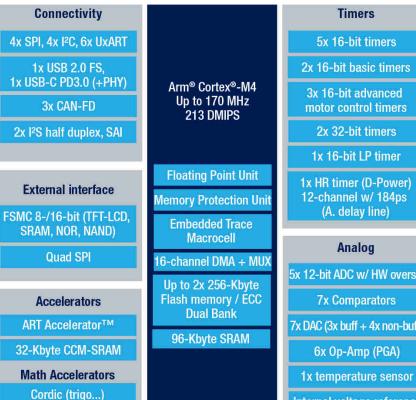


STM32G47x 38

High Resolution and Performance lines [128KB .. 512KB]

- 32-bit Arm Cortex-M4 core with FPU
- ART + CCM-SRAM + **Mathematic Accelerators**
- **Dual Bank Flash with ECC**
- **SRAM** with Parity bit
- +/- 1% internal clock
- 1.72 to 3.6V power supply
- Up to 125°C





Filtering

Timers 5x 16-bit timers 2x 16-bit basic timers 3x 16-bit advanced motor control timers 2x 32-bit timers 1x 16-bit LP timer 1x HR timer (D-Power) 12-channel w/ 184ps (A. delay line) **Analog** 5x 12-bit ADC w/ HW overspl 7x Comparators 7x DAC (3x buff + 4x non-buff) 6x Op-Amp (PGA)

Internal voltage reference

- **High resolution timer** 3x Advanced Motor Control timers **Rich Advanced Analog** 3x CAN Flexible Data rate **USB-C Power Delivery3.0 Advanced Security and Safety** features
- Robustness: highest level 5 / FTB/ESD - IEC 61000-4-4



STM32G43x 39

Access line [32KB .. 128KB] and up to 512KB in H1-2020!

- 32-bit Arm Cortex-M4 core with FPU
- ART + CCM-SRAM + **Mathematic Accelerators**
- Single Bank Flash with ECC
- **SRAM** with Parity bit
- +/- 1% internal clock
- 1.72 to 3.6V power supply
- Up to 125°C





Arm® Cortex®-M4 Up to 170 MHz **Floating Point Unit** Memory Protection Unit **Embedded Trace** Macrocell 2-channel DMA + MUX Up to 128-Kbyte Flash memory / ECC Single Bank 22-Kbyte SRAM

5x 16-bit timers 2x 16-bit basic timer 2x 16-bit advanced motor control timers 1x 32-bit timer 1x 16-bit LP timer

Timers

Analog 2x 12-bit ADC **4x Comparators** 4x DAC (2x buff + 2x non-buff) 3x Op-Amp (PGA) 1x temperature sensor

- 2x Advanced Motor Control timers
- **Rich Advanced Analog**
- **CAN Flexible Data rate**
- **USB-C Power Delivery3.0**
- **Advanced Security and Safety features**
- Robustness: highest level 5 / FTB/ESD - IEC 61000-4-4



STM32G4 Portfolio 40

Flash memory / RAM size (bytes)

Crypto AES-256

Available in H1 2020

		-	-				
		STM32G484CE	STM32G484RE	STM32G484ME	STM32G484VE	STM32G4840E	
512 K / 128 K		STM32G474CE STM32G483CE	STM32G474RE	STM32G474ME STM32G483ME	STM02G474VE	STM32G4740E	
S. C. (1)		STM32G473GE	STM32G483RE STM32G473RE	STM32G473ME	STM32G483VE STM32G473VE	STM32G483GE STM32G473GE	
		STM32G491CE	STM32G491RE	STM32G491ME	STM32G491VE		
		STM32647400	STMS2G474HC	STMS25474MC	STM326474VC	STM32G474QC	
256 K / 128 K		STMX26473CC	STM32G473RC	STM32G473MC	STM32G473VC	STM32G4730C	
		STM32G491CC	STM32G491RC	STM32G491MC	STM32G491VC		
100 V / 100 V		STM32G474C8	STM326474R8	STM32G474MB	STM32G474VB	STM3264740B	
128 K / 128 K		STM32G479E8	STM326A73RB	STM326473MB	STM32G473VB	STM32G4730B	
128 K / 32 K	STM32G441KB	STM32G441CB	STM32G441RB	STM32G441MB	STM32G441VB		
	STM32G431KB	STM32G431CB	STM32G431RB	STM326431M8	STM32G431VB		
64 K / 32 K	STM326431K8	STM32G431C8	STM32G431R8	STM32G431M8	STM32G431V8		
32 K / 32 K	STM32G431K6	5TM32G431G6	STM32G431R6	STM32G431M6	STM326431V6		2
	32-pln LQFP/QFN	48-pln LQFP/QFN	64-pin LOFP/WLCSP	80-pln LQFP/WLCSP	100-pln LOFP/BGA	128-pln LQFP	+ Pin cou





Broad Portfolio 41

Portfolio extended to support budget applications efficiently

More memory and pin counts

Flash memory (bytes)	32-pin LQFP QFN	48-pin LQFP QFN	64-pin LQFP BGA WLCSP	80-pin LQFP WLCSP	100-pin LQFP BGA	121-pin BGA	128-pin LQFP
512 K		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	✓
256 K		\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
128 K	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
64 K	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark		
32 K	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark		

More packages







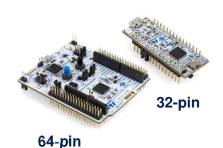


Note: new packages in STM32 portfolio



STM32G4 Hardware Solutions 42

Accelerate evaluation, prototyping and design











STM32 Nucleo

Flexible prototyping

- NUCLEO-G431RB
- NUCLEO-G474RE
- NUCLEO-G431KB

Evaluation boards

Full feature STM32G4 evaluation

- STM32G484E-EVAL
- STM32G474E-EVAL
- STM32G474E-EVAL1

Motor Control Pack

Full feature for Motor Control and Analog

P-NUCLEO-IHM03

Discovery kits

Key feature prototyping

- B-G474E-DPOW1
- B-G431B-ESC1





STM32G4 Software Tools 43

SYSTEMS

Complete support of Arm Cortex-M ecosystem











STM32CubeMX

STM32CubeMX

- · Configure and generate Code
- · Conflicts solver

IDEs Compile and Debug

Flexible Solutions

- · Partners IDE, like IAR and Keil
- · Free IDE based on Eclipse, like STM32CubeIDE*

STM32 Programming Tool

STM32CubeProgrammer

- Flash and/or system memory
- GUI or command line interface



^{*} SW examples will be available in Q4 19



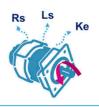
Dedicated Ecosystems

Motor Control

- Complete ecosystem (HW boards, SW Development Kit (SDK), docs and trainings)
 - X-CUBE-MCSDK (v5.4)
 - Motor Control FW library based on STM32Cube HAL and LL
 - Motor control workbench: Graphical configurator of the motor control library linked with STM32CubeMx
 - P-NUCLEO-IHM03: Motor Control Nucleo pack
 - NUCLEO-G431RB Nucleo-64
 - X-NUCLEO-IHM16M1 motor driver expansion board
 - Low Voltage motor



 Motor Profiler: Plug and spin your motor within less than one minute



Digital Power

- Complete ecosystem (HW boards, FW examples, SW tools, docs and trainings)
- Dedicated HRTIM Cook Book AN4539: How to operate the Hi-Resolution timer in different topology
- Digital Power training (PSU and PFC) based on STM32 G4 series done in collaboration with Biricha (from Q4 2019)







STM32G4 Series - Take Away

Analog-rich MCUs for mixed-signal applications



Performance

170MHz Cortex-M4 coupled with 3x accelerators



Rich and Advanced Integrated Analog ADC, DAC, Op-Amp, Comp.



Safety and security focus



Large portfolio available from NOW!

32..512KB Flash memory 32..128-pin packages



STM32G4 Mainstream Series Mixed Signal MCU

Demo Hands On

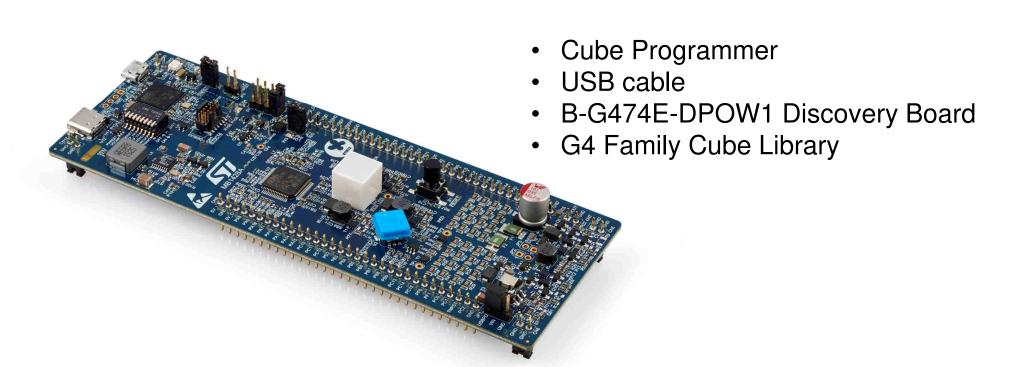








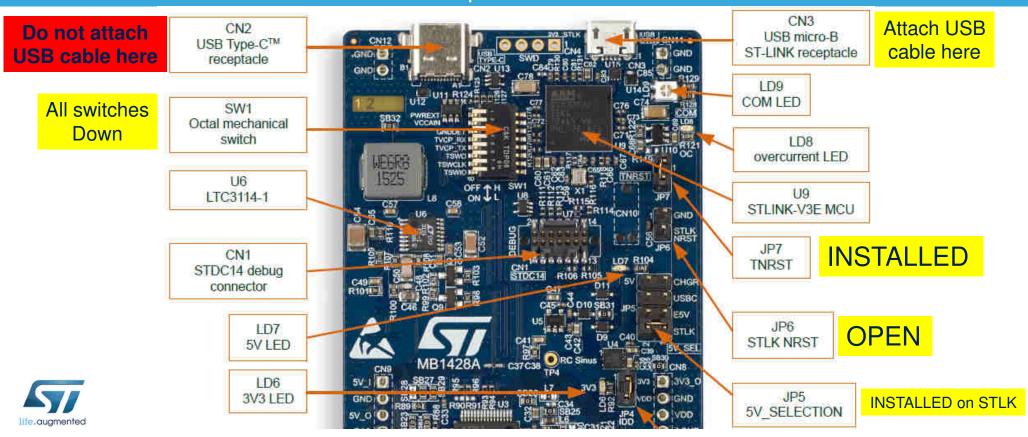
Systems Check





B-G474E-DPOW1 48

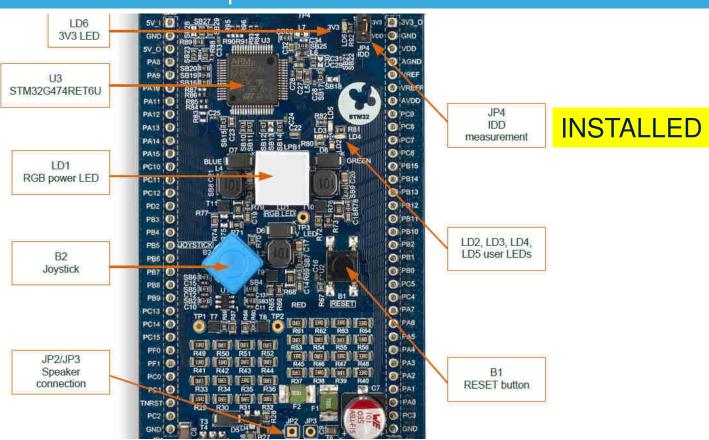
Jumpers – 1 of 2





B-G474E-DPOW1 49

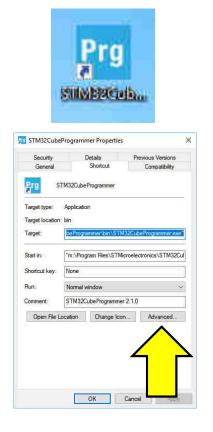
Jumpers – 2 of 2

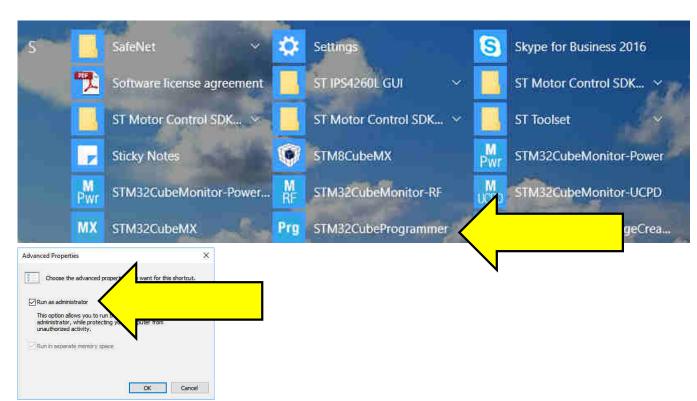






Start up

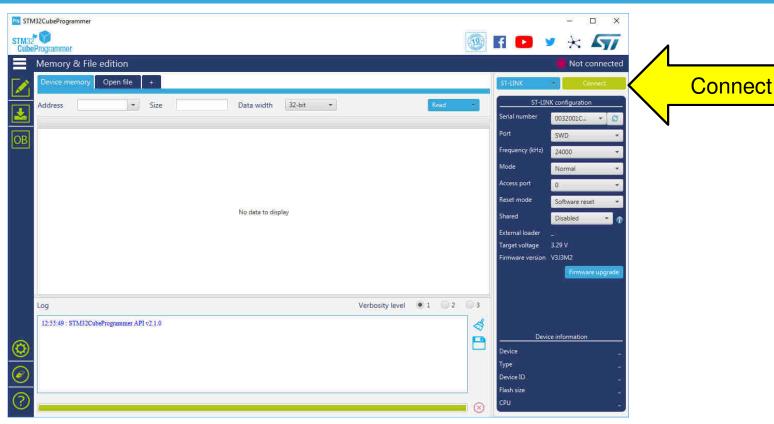








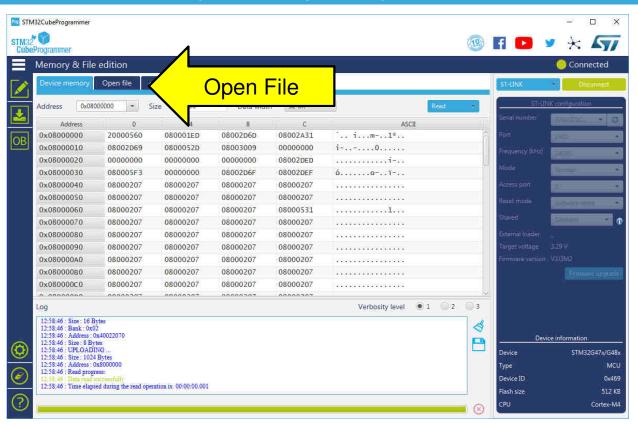
Splash Page - Connect







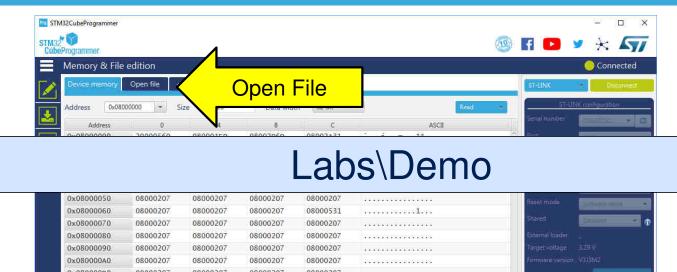
Splash Page - Open File



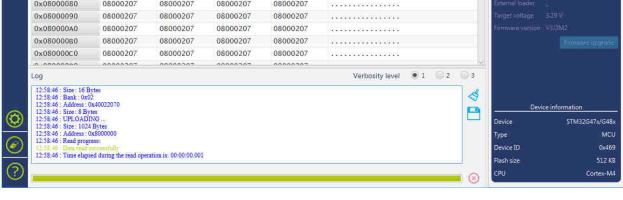




Find Demo.hex

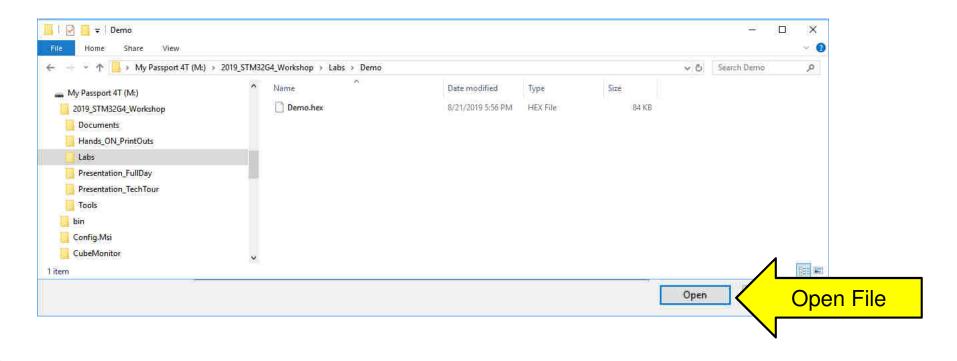








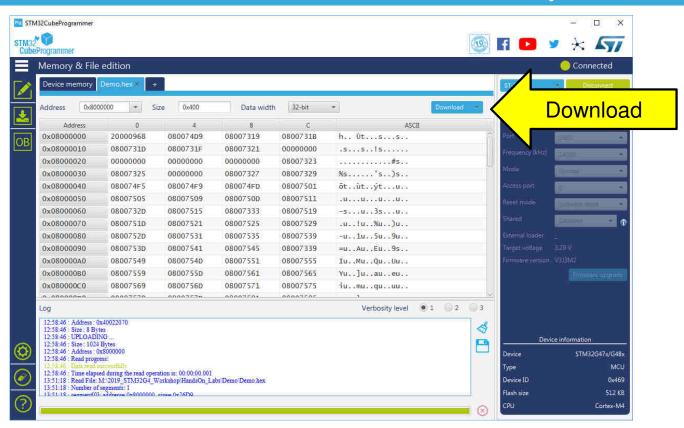
File Folder







Move Demo.hex from the PC to the Discovery board

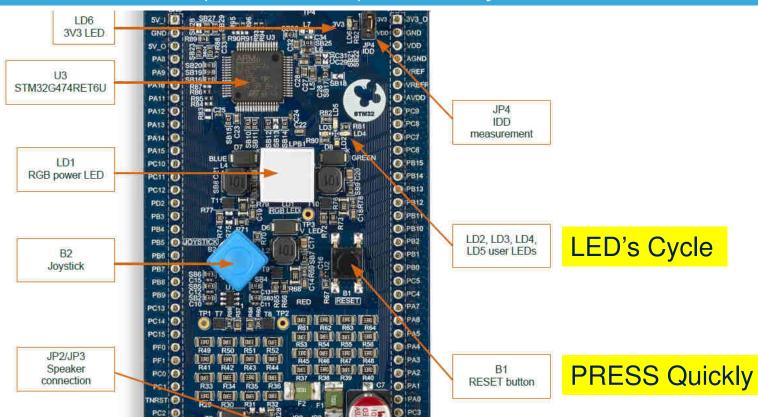






B-G474E-DPOW1

Press RESET (Black Button) - LED's cycle



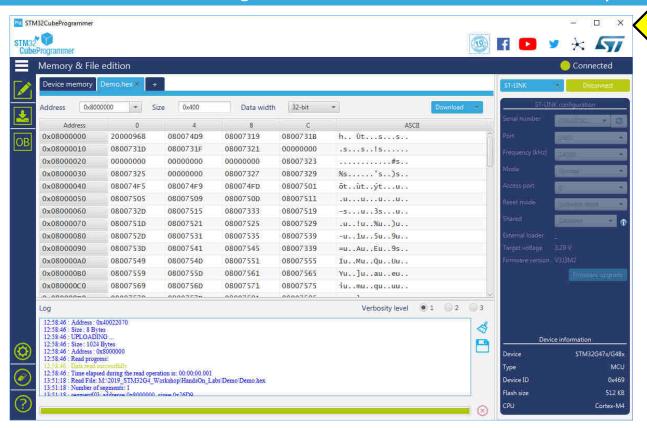


Exit



CubeProgrammer 57

Shut down the CubeProgrammer to release the VCOM port.







Getting back home – "CompletedLab"

For all of today's Hands On Labs:

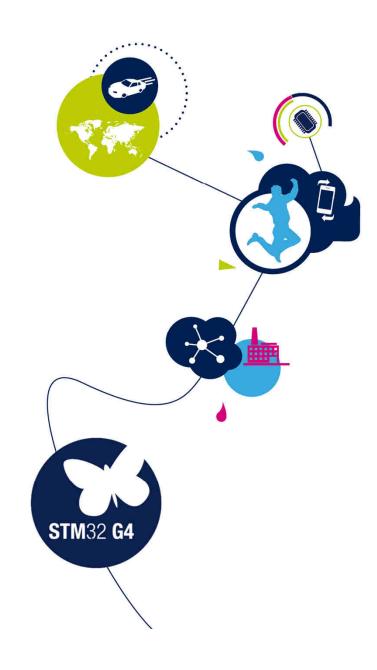
- The *.hex file is available to you as a final product of the lab if you get lost along the way and still want to see the result of the lab.
- 2. The *.uvprojx file is available to you as a final result in case you want to pull it up in KEIL MDK-ARM and just walk through the files you see there.
- 3. The final STM32CubeMx *.ioc file for each lab is made available to you if you want to see the finished product of the lab or if you want to extend the lab with your own design ideas.



STM32G4 mixed-signal MCU workshop

Hands On: DAC Signal Generation

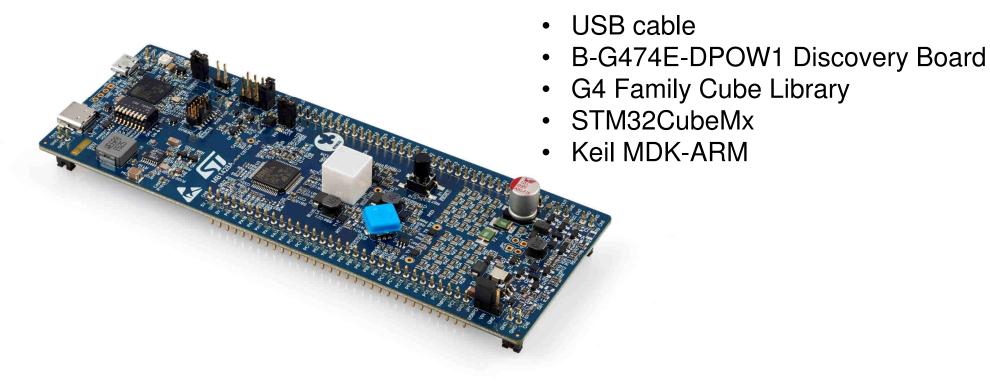






TOOS 60

Systems Check





Rich, Advanced Analog 61

Mixed-signal SoC for wide variety of applications

ADC (up to 5)	Values
Topology	SAR 12-bit + HW oversampling → 16-bit
Sampling rate	Up to 4 Msps
Input	Single-ended and differential
Offset and Gain compensation	Auto calibration to reduce gain and offset

Op-Amp (up to 6)	Values
GBW	13 MHz
Slew rate	45 V/μs
Offset	3mV over full T° range 1.5mV @ 25°C
PGA Gain (accuracy)	2, 4, 8, 16, -1,-3,-7,-15 (1%) 32, 64, -31,-63 (2%)

DAC (up to 7)	Values
Sampling rate	15 Msps (internal) 1Msps (from buffered output)
Settling time	16ns

Comparator (up to 7)	Values
Power supply	1.62 3.6V
Propagation delay	16.7ns
Offset	-6 +2 mV
Hysteresis	8 steps:
	0, 9, 18, 27, 36, 45, 54, 63 mV





Digital to Analog Converter 62

G4 DAC

- 3 external outputs:
 - DAC1-OUT1 and OUT2, 1Msps
- 4 internal outputs:
 - DAC3 and DAC4
 - OUT1 and OUT2, 15Msps
- Double data DMA
- Sample & Hold
- Left or Right data alignment
- Signed or unsigned data input format {Q1.15, Q1.11, Q1.7}

Internally connected to:

- Voltage reference
- **External Triggers**
- Comparator inputs
- Op Amp inputs
- Multiple Timers (+ HRTimer)
- DMA





Digital to Analog Converter 63

G4 DAC Sample and Hold

DAC conversion during the "sample and hold" mode has three phases:

- 1. Sampling phase: the "sample and hold" element is charged with the desired voltage.
- 2. Holding phase: the DAC output is tri-stated (High-Z) to maintain the "sample" and hold" element's stored electrical charge.
- 3. Refresh phase: due to leakage coming from several sources, a refresh phase is essential to maintain the output voltage at the desired value (+/-LSB).





Digital to Analog Converter 64

Dual Conversion from DMA

We will use the DAC dual channel mode with DMA to generate signals on both DAC channels at the same time.

DAC conversions are made with a timer trigger and data fed from DMA.

The timer is configured to trigger the DAC channels at about 1kHz.

DMA is feeding both channels at the time.

Channel 1 pattern is ~0V/~1.65V/~3.3V/~1.65V

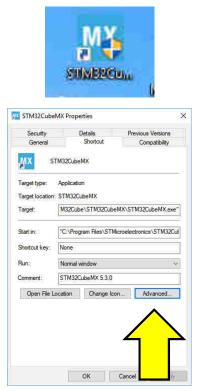
Channel 2 pattern is ~1.65V/~3.3V/~1.65V/~0V

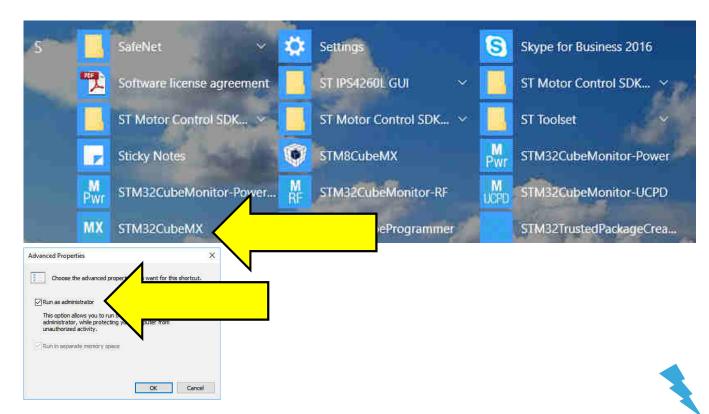
We will use the built in Logic Analyzer today instead of an o'scope on the DACs





Start up

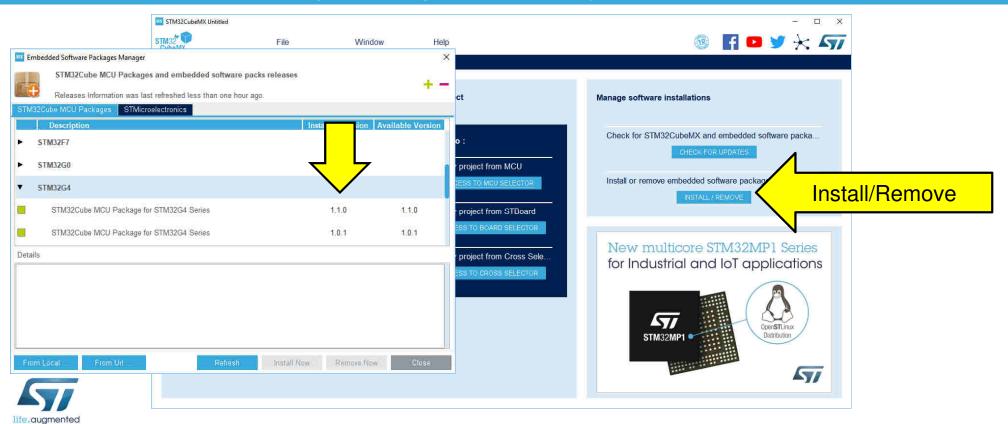






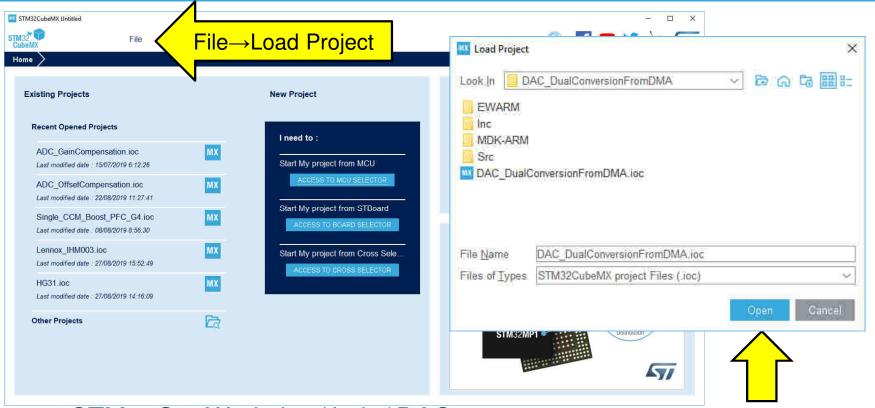


Splash Page – G4 Library Installed?







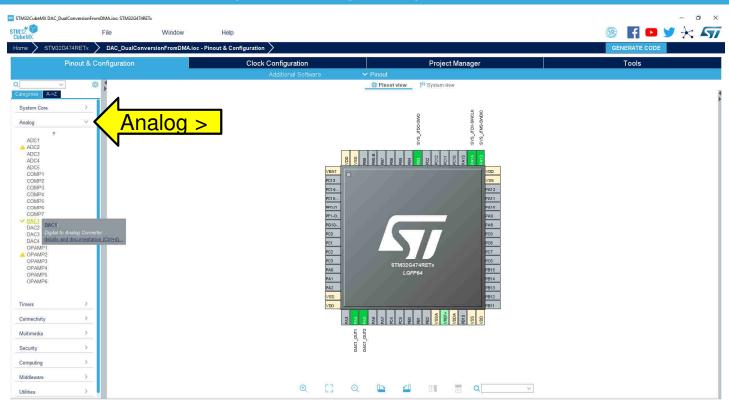




C:\2019_STM32G4_Workshop\Labs\DAC



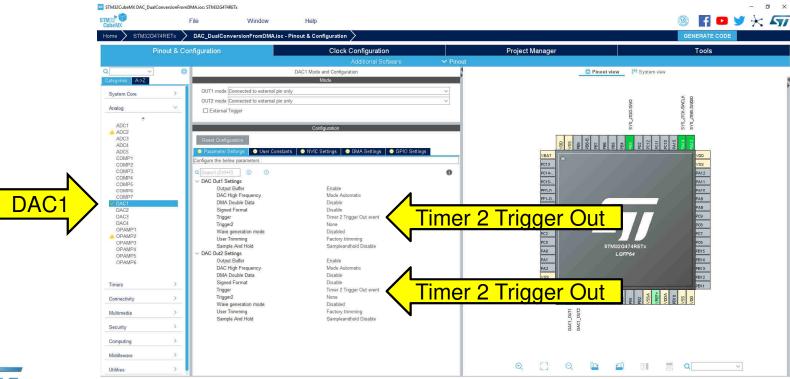
Graphic Design Representation







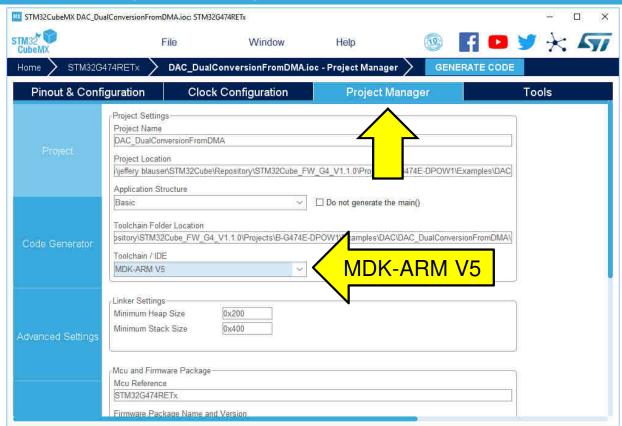
DAC1, Timer 2







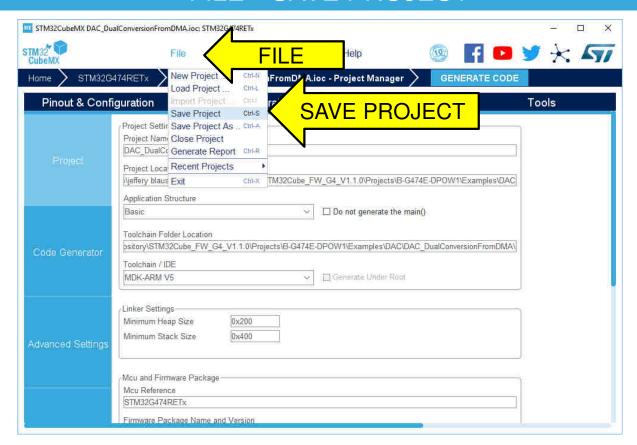
Project Manager – Keil MDK-ARM V5







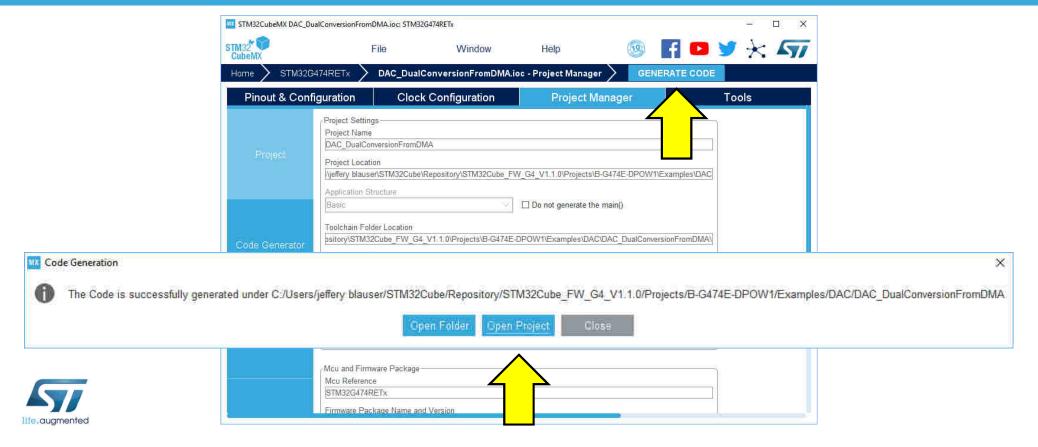
FILE→SAVE PROJECT







Generate Code





Keil Start up page

```
🖫 C.\Users\jeffery blauser\STM32Cube\Repository\STM32Cube, FW_G4_V1, L0\Projects\8-G474E-DPOW1\Examples\DAC\DAC_DualConversionFromDMA\MDK-ARM\DAC_DualConversionFr
File Edit View Project Flash Debug Peripherals Tools SVCS Window Help
□ 🚰 🛃 🐉 🐰 😘 选 9 🤭 😁 🕪 🦰 🟗 🐧 🕸 華 譯 //// //// 💆 WaitForl2C

    □ □ □ □ + □ □ □ DAC_DualConversionFro □ A □ □ □ ◆ → □

                                                      startup_stm32g474xx.s main.c readme.txt
☐ 🎁 Project: DAC_DualConversionFromDMA
                                                       128 if (HAL_DACEx_DualStart_DMA(&hdacl, DAC_CHANNEL_l, wave, sizeof(wave)
   □ DAC_DualConversionFromDMA
                                                       129
                                                                 /* DAC conversion start error */

    Application/MDK-ARM

                                                       130
                                                       131
                                                                 Error_Handler();
     Application/User
                                                       132
     ⊕ 💯 Doc
                                                       133
         readme.txt
                                                       134
                                                               BSP_LED_On(LED4);
                                                       135
     ⊕ Drivers/BSP/B-G474E-DPOW1
                                                       136

■ Drivers/STM32G4xx_HAL_Driver

                                                                 /* USER CODE END WHILE */
                                                       137

■ Drivers/CMSIS

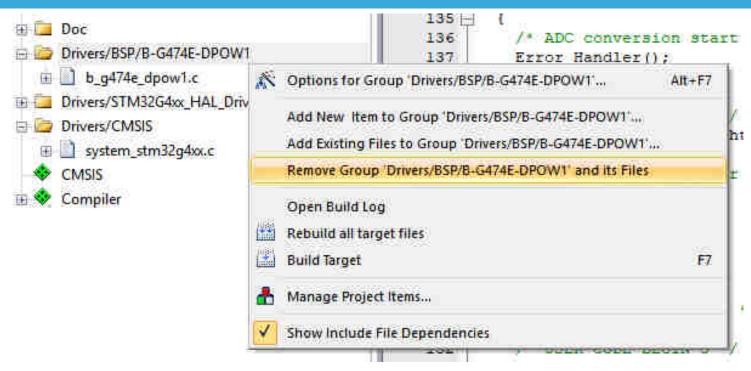
                                                       138
139
       CMSIS
                                                                /* USER CODE BEGIN 3 */
                                                       140
                                                       141
                                                               /* USER CODE END 3 */
                                                       143
                                                       144 - /**
                                                              * @brief System Clock Configuration
                                                       145
146
                                                              · @retval None
                                                       147
                                                            void SystemClock_Config(void)
                                                       150
                                                               RCC_OscInitTypeDef RCC_OscInitStruct = {0};
                                                               RCC ClkInitTypeDef RCC ClkInitStruct = {0};
                                                              /** Configure the main internal regulator output voltage
                                                       153
                                                       154
                                                              HAL PWREx ControlVoltageScaling(PWR REGULATOR VOLTAGE SCALE1);
                                                              /** Initializes the CPU, AHB and APB busses clocks
                                                              RCC_OscinitStruct.OscillatorType = RCC_OSCILLATORTYPE_HSI;
RCC_OscinitStruct.HSIState = RCC_HSI_ON;
RCC_OscinitStruct.HSICalibrationValue = RCC_HSICALIBRATION_DEFAULT;
                                                       158
                                                       159
                                                              RCC OscinitStruct.PLL.PLLState = RCC PLL ON;
RCC OscinitStruct.PLL.PLLSource = RCC PLLSOURCE HSI;
                                                       161
                                                              RCC_OscInitStruct.PLL.PLLM = RCC_PLLM_DIV4;
                                                       164
                                                               RCC_OscInitStruct.PLL.PLLN = 75;
                                                              RCC OscInitStruct.PLL.PLLP = RCC PLLP DIV2;
                                                               RCC OscInitStruct.PLL.PLLQ = RCC_PLLQ_DIV2;
                                                       166
167
                                                              RCC_OscInitStruct.PLL.PLLR = RCC PLLR DIV2;
                                                              if (HAL_RCC_OscConfig(&RCC_OscInitStruct) != HAL_OK)
                                                       168
                                                       169
                                                       171
                                                       172 | /** Initializes the CPU, AHB and APB busses clocks
Project Books | O Functions | D. Templates
```







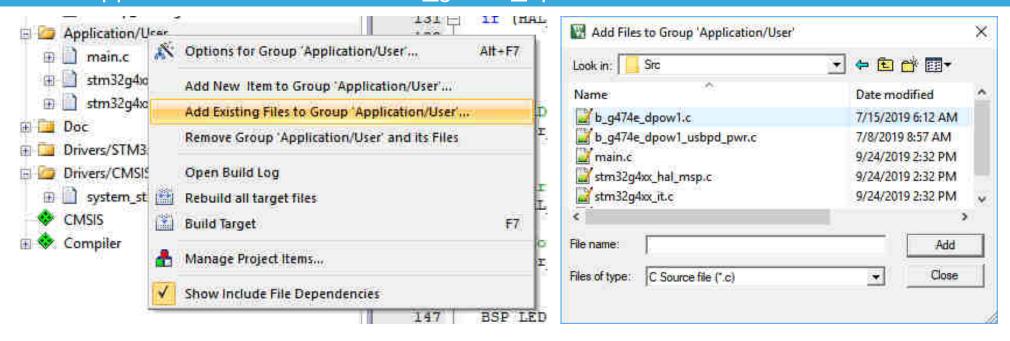
Delete Drivers Folder







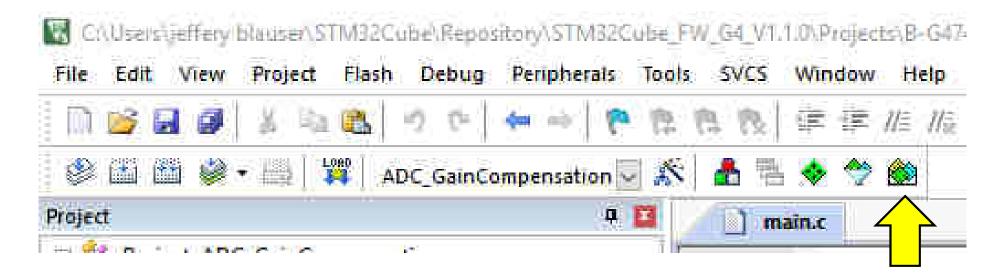
Application/User folder add b_g474e_dpow1.c from SRC folder - CLOSE





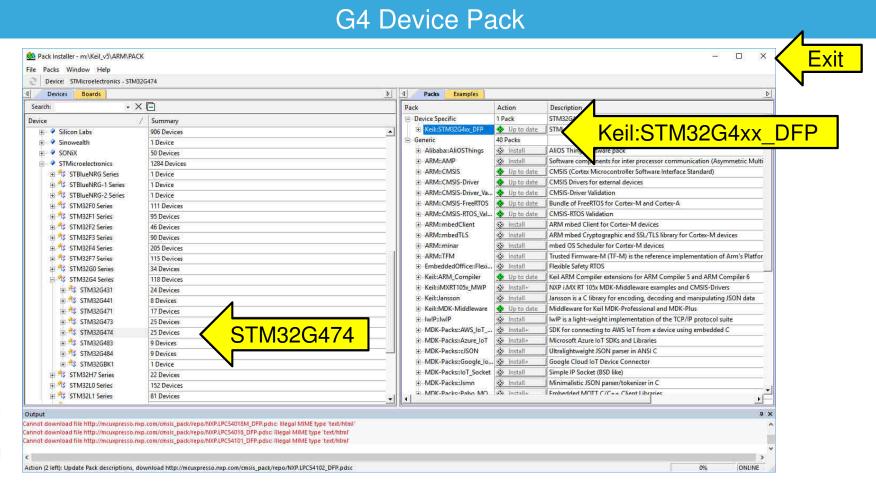


Check the Device Pack





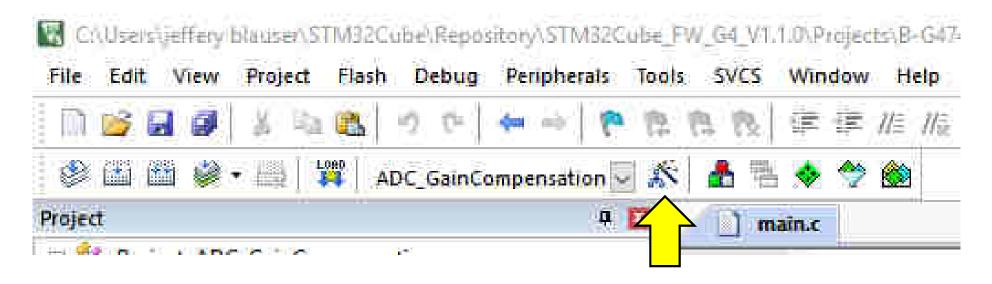






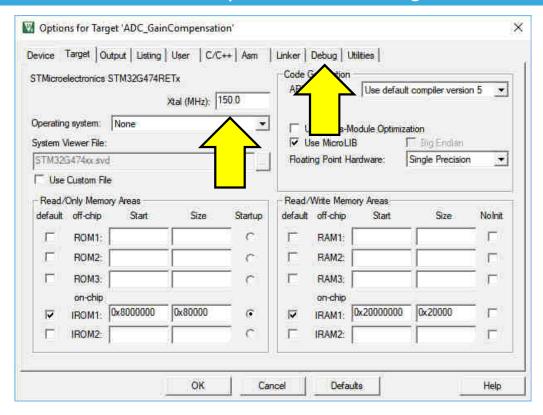


Check the Options





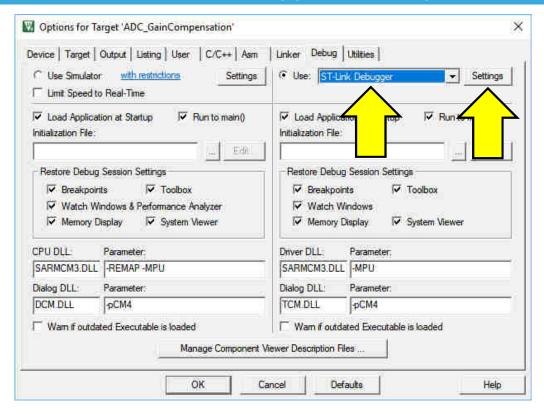
Clock speed and Debug







ST-Link Debugger - Settings

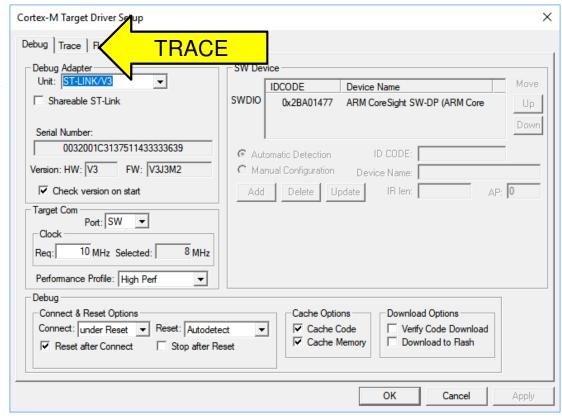






ST-Link/V3 & TRACE

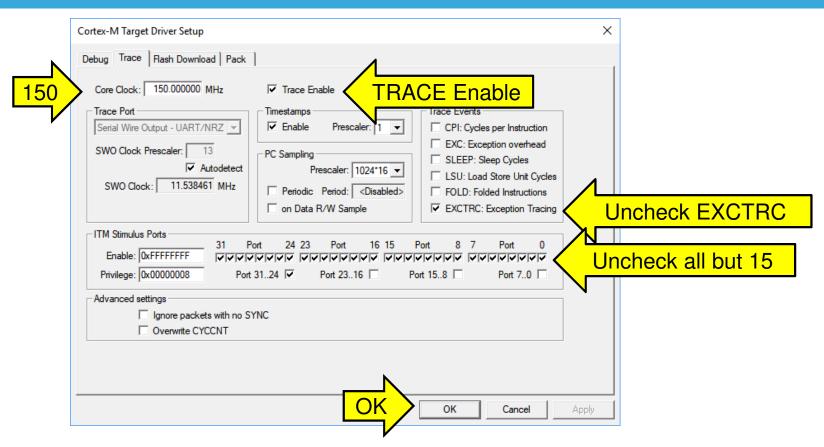








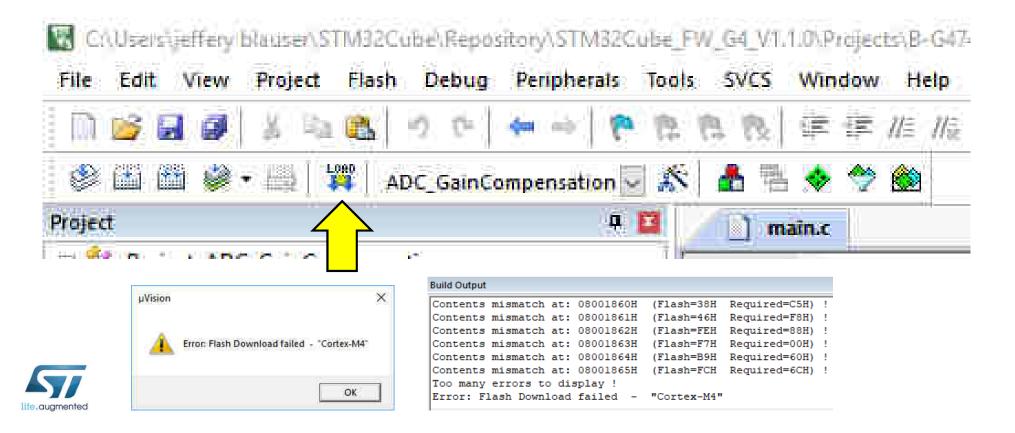
Core Clock & TRACE Enable





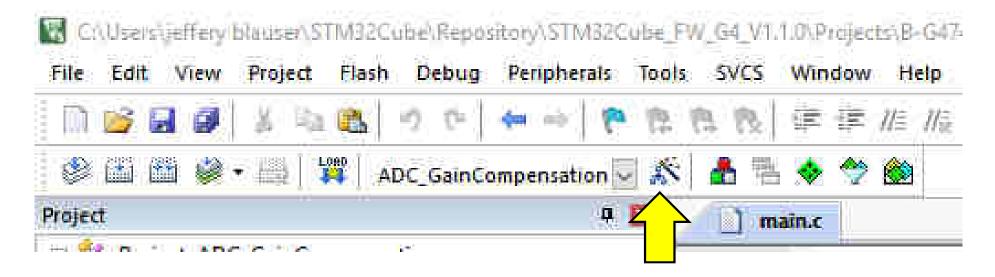


Load





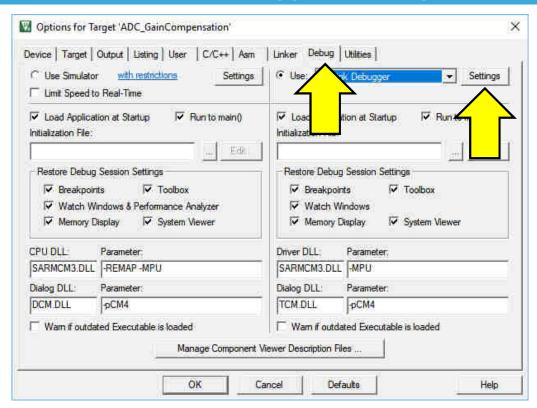
Options







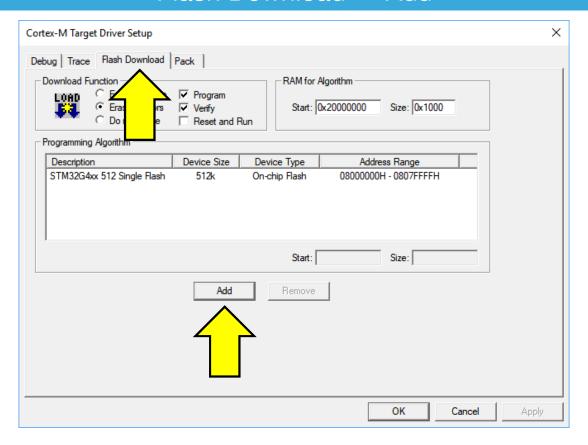
ST-Link Debugger - Settings







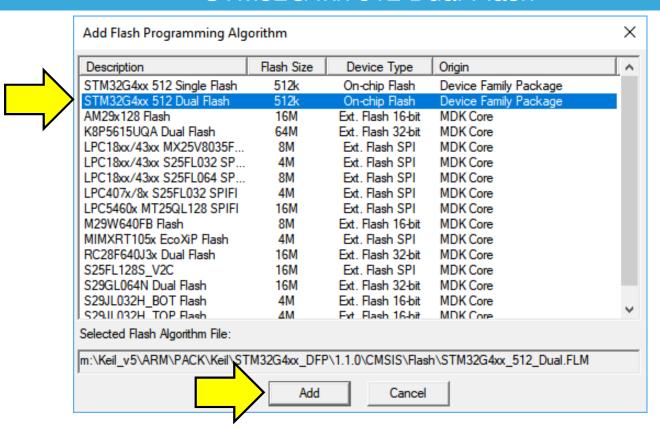
Flash Download → Add







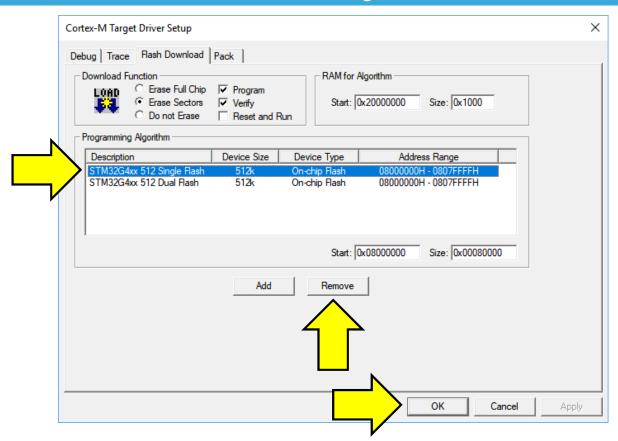
STM32G4xx 512 Dual Flash







Remove Single Flash







Place 2 new variables for the Analyzer – main.c about line 56

```
/* USER CODE BEGIN PV */
      Private variables
53
54
    uint32 t wave[4] = \{0x07FF0\}
55
5.5
    uintl6 t Display DACIDOR1;
    uintl6 t Display DACIDOR2;
57
58
59
      USER CODE END PV */
```



See c:\2019 STM32G4_Workshop\Labs\DAC For the file CodeLinesForMain_DAC.txt for cut and paste Or open the file from the Doc folder in the Editor



Execute 3 new lines for the Analyzer – main.c about line 143

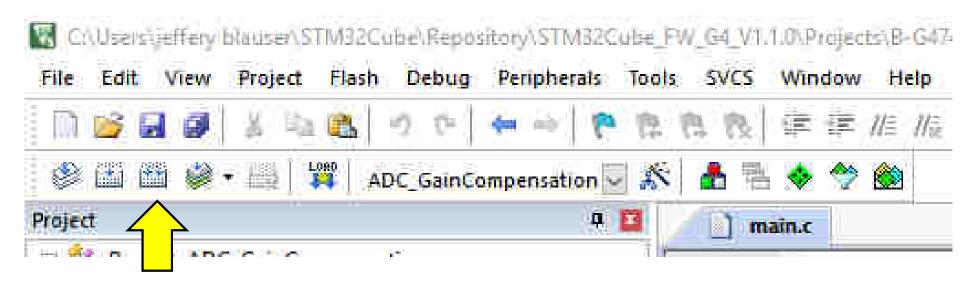
```
while (1)
138
139
         /* USER CODE END WHILE */
140
141
         /* USER CODE BEGIN 3 */
142
143
         Display DAC1DOR1 = DAC1->DOR1;
         Display DAC1DOR2 = DAC1->DOR2;
144
         HAL Delay(25);
145
146
```



See c:\2019_STM32G4_Workshop\Labs\DAC For the file CodeLinesForMain_DAC.txt for cut and paste. Or open the file from the Doc folder in the Editor



Build



Build Output

Program Size: Code=6572 RO-data=576 RW-data=92 ZI-data=1204

FromELF: creating hex file ...

DAC DualConversionFromDMA\DAC DualConversionFromDMA.hex: Warning: Q9931W: Your license for feature Keil will expire in 30 days Finished: 0 information, 1 warning and 0 error messages.

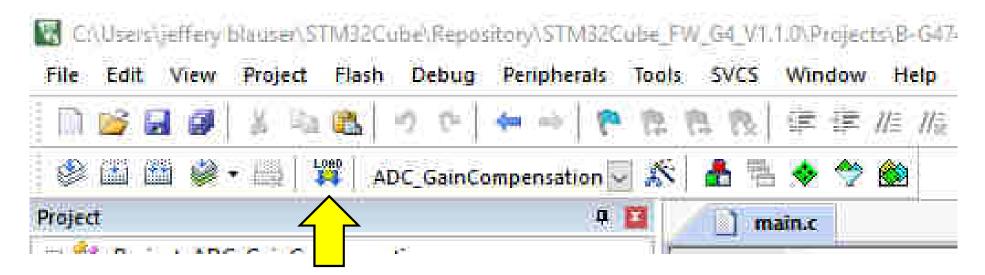
"DAC DualConversionFromDMA\DAC DualConversionFromDMA.axf" - 0 Error(s), 0 Warning(s).

Build Time Elapsed: 00:01:38





Load



Build Output

Build Time Elapsed: 00:01:38

Load "DAC DualConversionFromDMA\\DAC DualConversionFromDMA.axf"

Erase Done.

Programming Done.

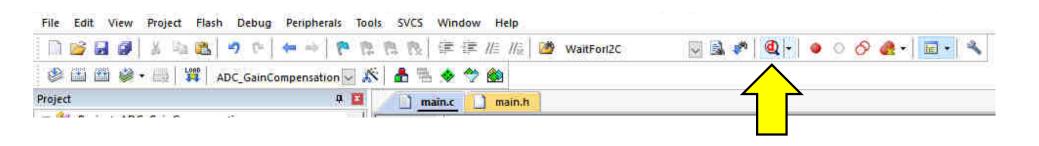
Verify OK.

Flash Load finished at 14:51:03





Debugger

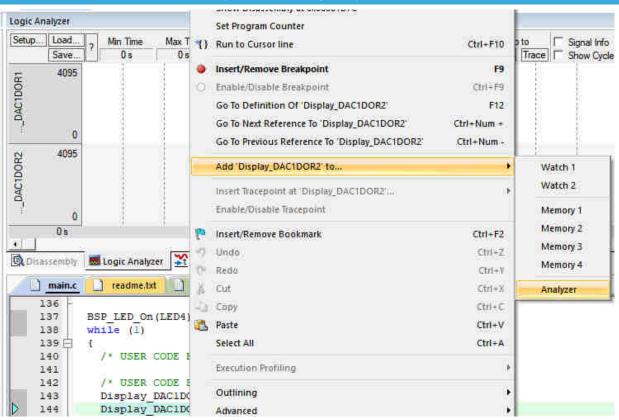








Add to Analyzer Display_DAC1DOR1 & 2



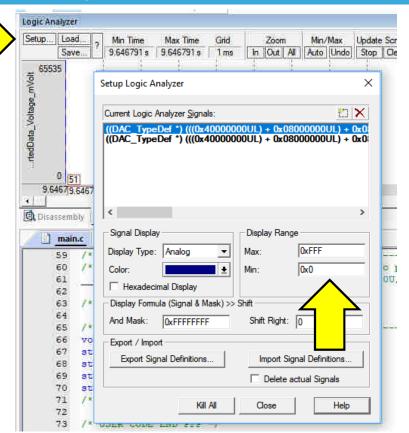


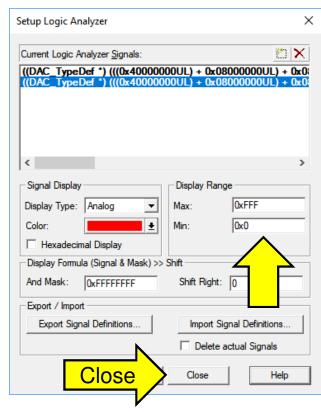


Setup

Keil MDK-ARM 95

Setup – Min=0x0, Max = 0xFFF

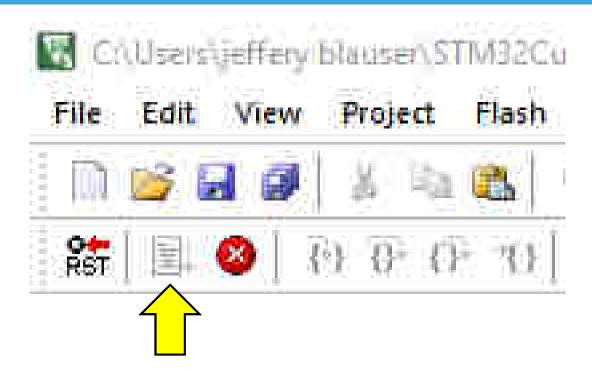








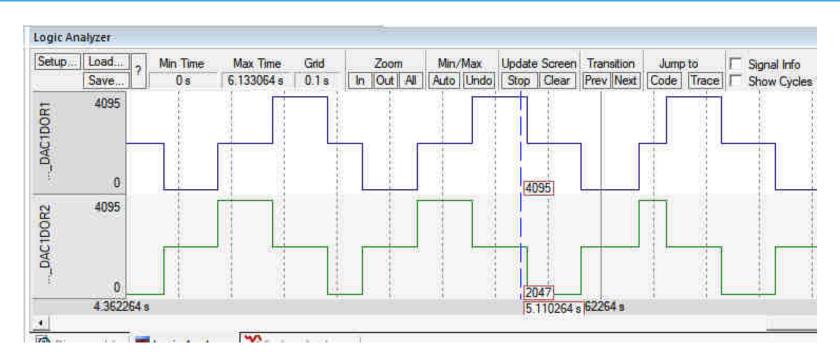
RUN







Logic Analyzer Output

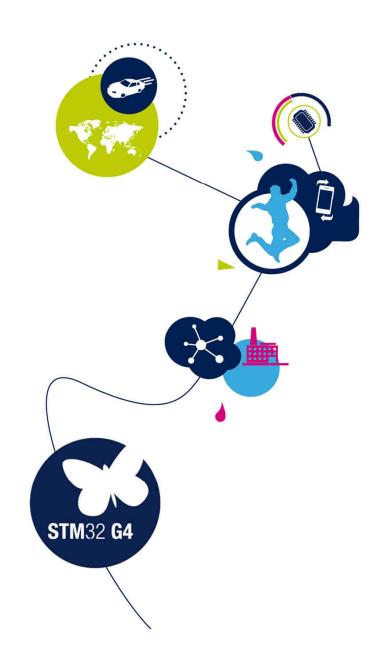




STM32G4 mixed-signal MCU workshop

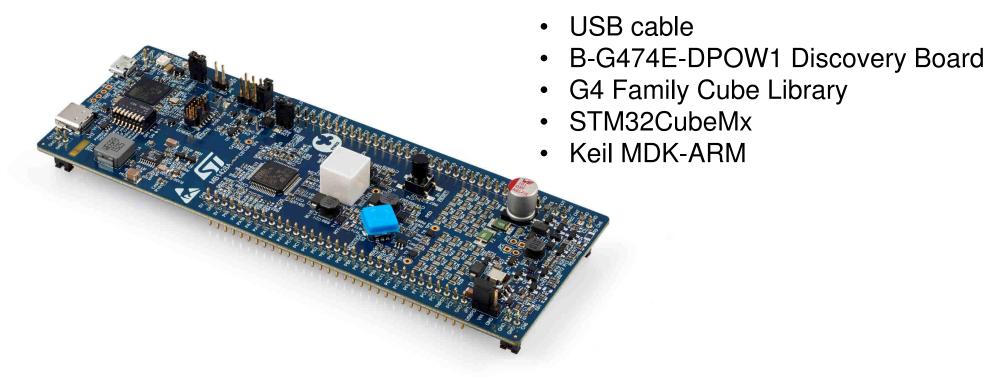
Hands On: Programmable Gain Amplifier







Systems Check





Rich, Advanced Analog 100

Mixed-signal SoC for wide variety of applications

ADC (up to 5)	Values
Topology	SAR 12-bit + HW oversampling → 16-bit
Sampling rate	Up to 4 Msps
Input	Single-ended and differential
Offset and Gain compensation	Auto calibration to reduce gain and offset

Op-Amp (up to 6)	Values
GBW	13 MHz
Slew rate	45 V/μs
Offset	3mV over full T° range 1.5mV @ 25°C
PGA Gain (accuracy)	2, 4, 8, 16, -1,-3,-7,-15 (1%) 32, 64, -31,-63 (2%)

DAC (up to 7)	Values
Sampling rate	15 Msps (internal) 1Msps (from buffered output)
Settling time	16ns

Comparator (up to 7)	Values
Power supply	1.62 3.6V
Propagation delay	16.7ns
Offset	-6 +2 mV
Hysteresis	8 steps:
	0, 9, 18, 27, 36, 45, 54, 63 mV





G4 PGA

- 6 PGA's available
- Non inverting gain 2/4/8/16/32/64
- Inverting gain -1/-3/-7/-15/-31/-63
- Rail-to-Rail input and output
- Low input bias current
- Low input offset voltage
- 15MHz GBW product
- High speed mode for better slew rate

Internally connected to:

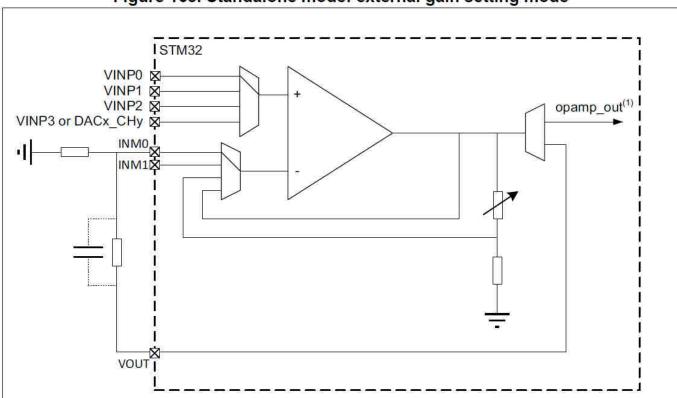
- ADC inputs
- External pins, both inputs and outputs
- Internal resistors
- DAC3 & DAC4 outputs





G4 Op Amp Stand Alone Mode

Figure 168. Standalone mode: external gain setting mode

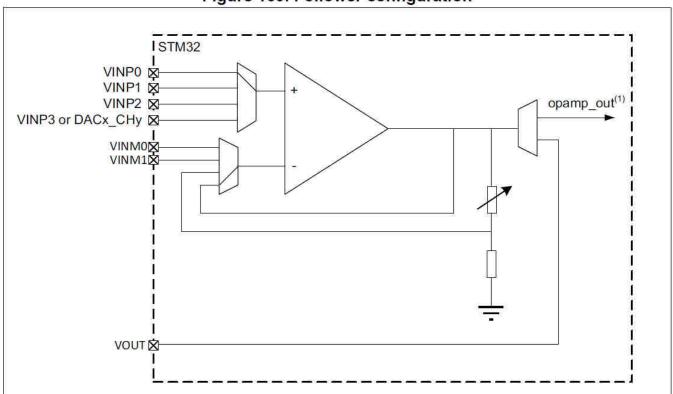






G4 Op Amp Follower Mode

Figure 169. Follower configuration

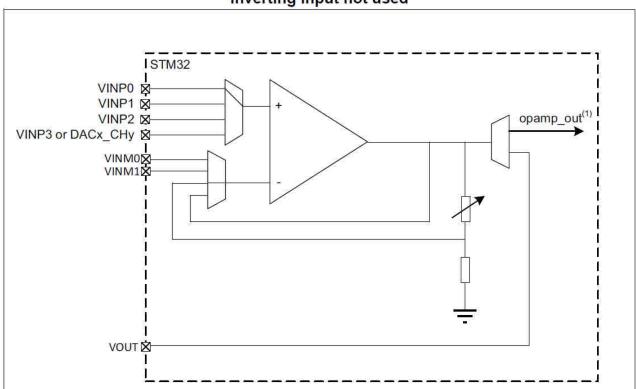






G4 Op Amp PGA Mode – This is what we will use today

Figure 170. PGA mode, internal gain setting (x2/x4/x8/x16/x32/x64), inverting input not used







PGA Hands On 105

Lab steps 1 of 2

- The DMA provides samples (sine wave) to the DAC.
- The DAC peripheral generates a sine wave signal on DAC1_OUT1(PA4) which is amplified by the OPAMP3. (Later DAC3 OUT2 as well)
 - The OPAMP3 amplified output is on PB1 with gain of either 2 or 4. The OPAMP gain is changed on the fly while the OPAMP remains enabled.
 - The test steps are:
 - Step 1:

DAC: normal power mode

OPAMP: normal power mode with gain = 2

DMA: circular mode - DMA half transfer IT handled by CPU





PGA Hands On 106

Lab steps 2 of 2

- Step 2:

DAC: normal power mode

OPAMP: normal power mode

- gain is changed from 2 to 4 or from 4 to 2

circular mode - DMA half transfer IT handled by CPU DMA:

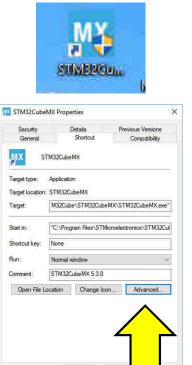
We will use the built in Logic Analyzer today instead of an o'scope on the DACs and Op Amps.



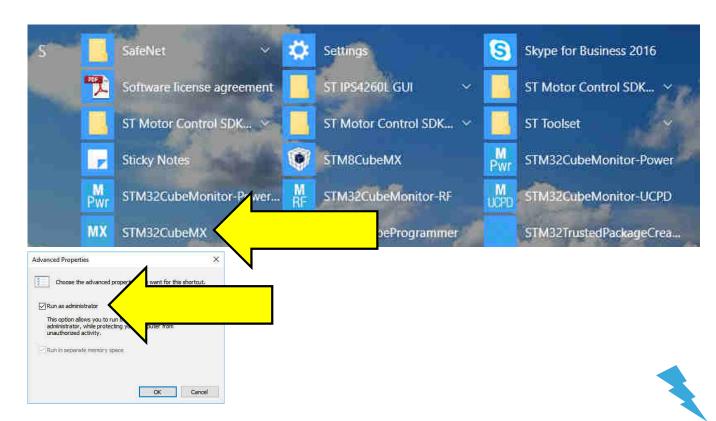


STM32CubeMx 107

Start up



OK Cancel

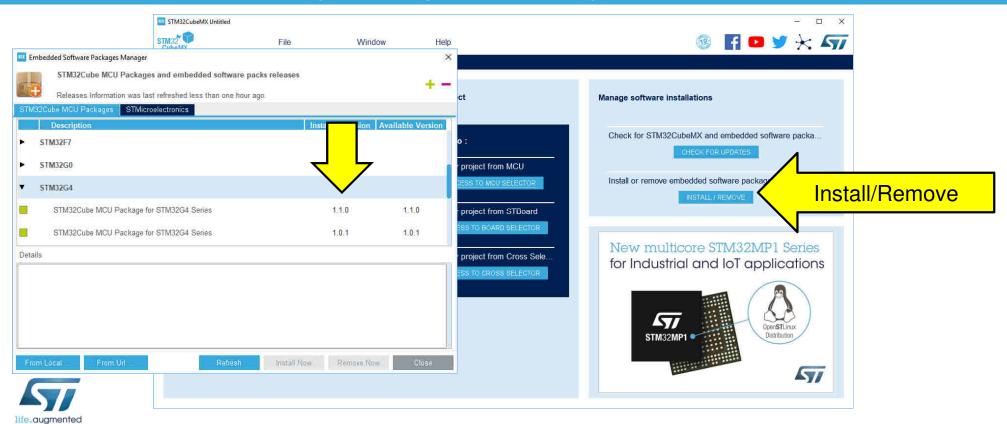






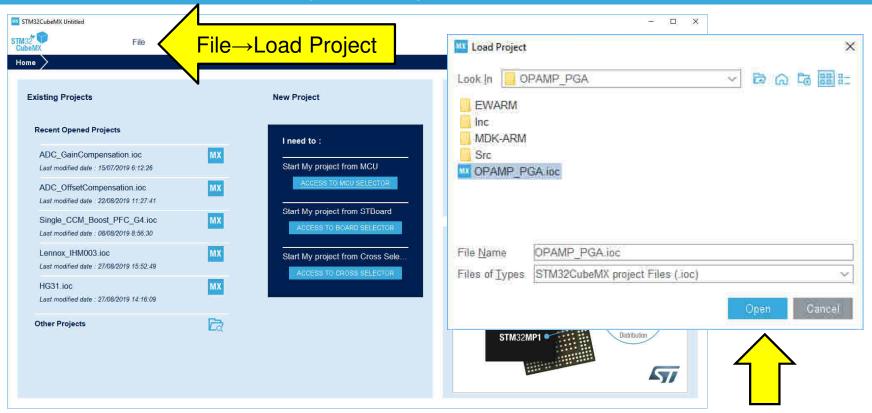
STM32CubeMx 108

Splash Page – G4 Library Installed?







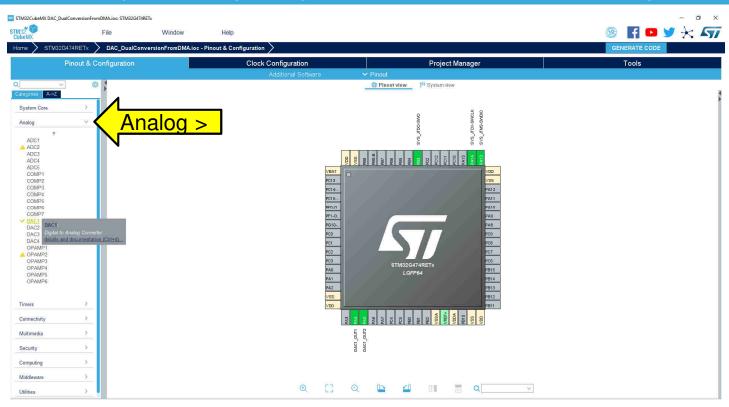




C:\2019_STM32G4_Workshop\Labs\OpAmp



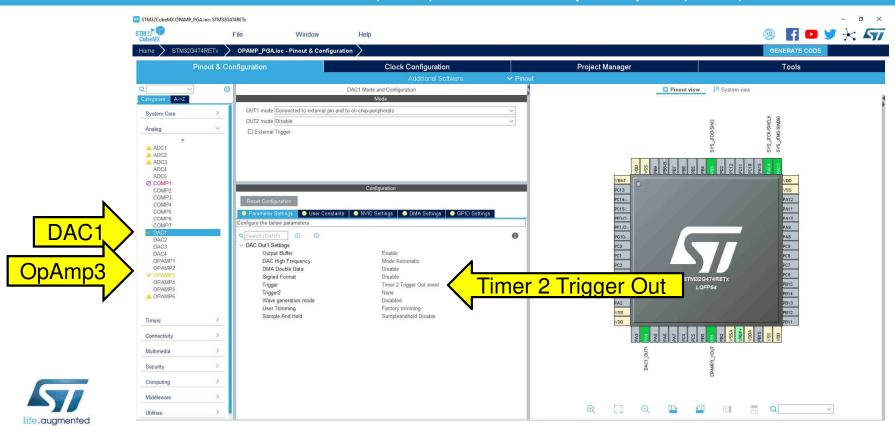
Graphic Design Representation - Click on Analog>





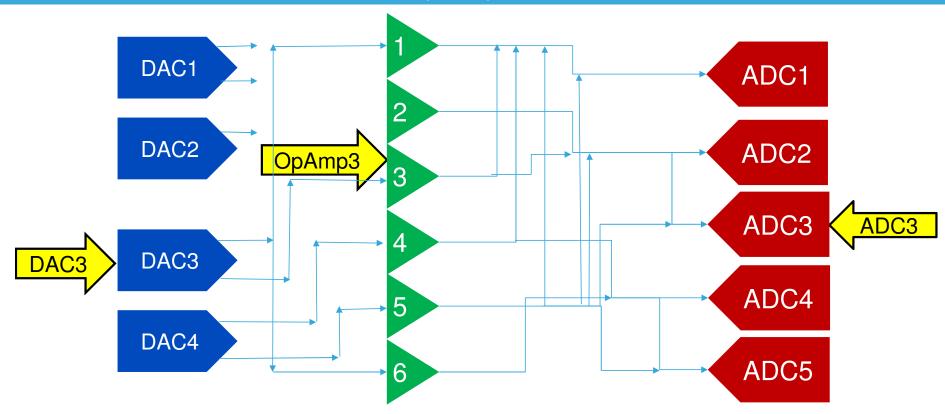


DAC1 (PA4), Timer 2, Op Amp 3 (PB1)





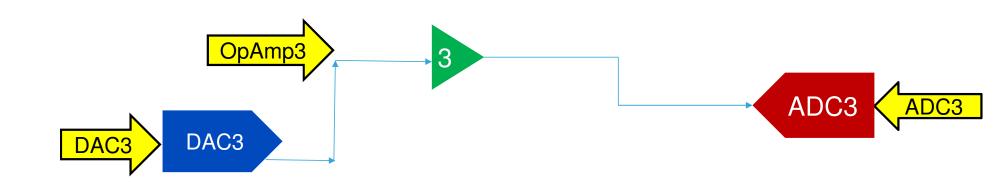
DAC3_OUT2 - Op Amp 3 - ADC3







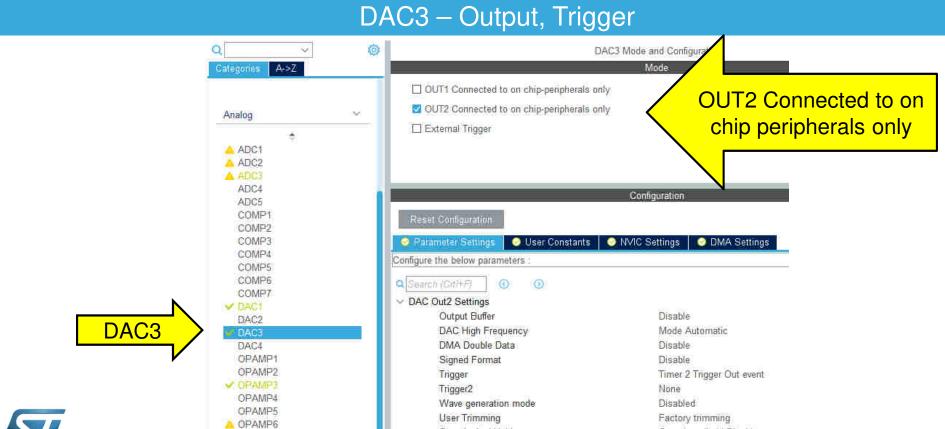
DAC3_OUT2 - Op Amp 3 - ADC3







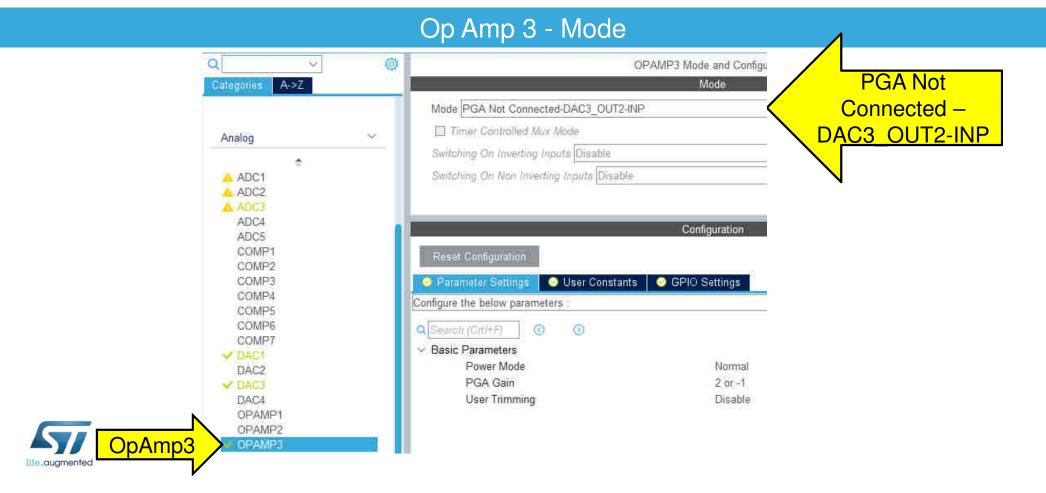
Sampleandhold Disable



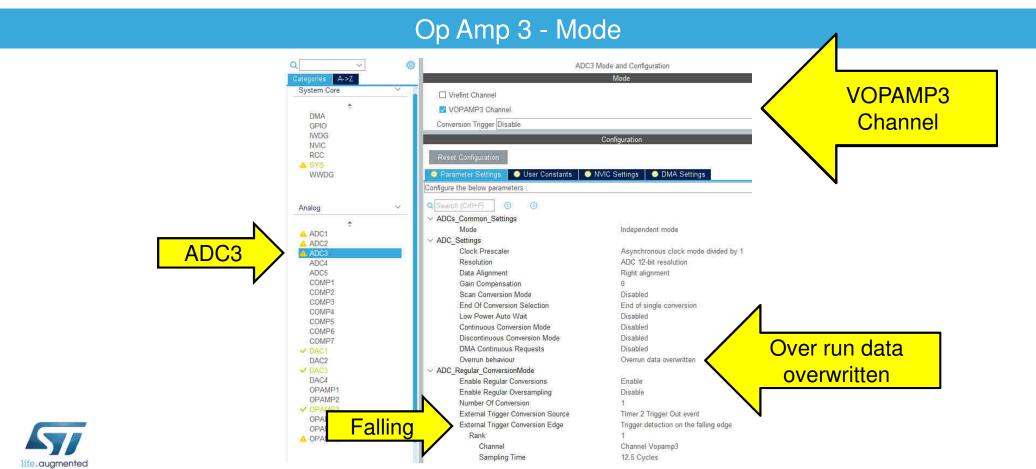
Sample And Hold





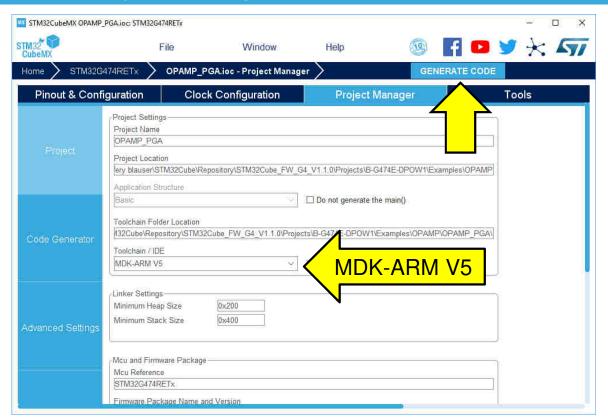








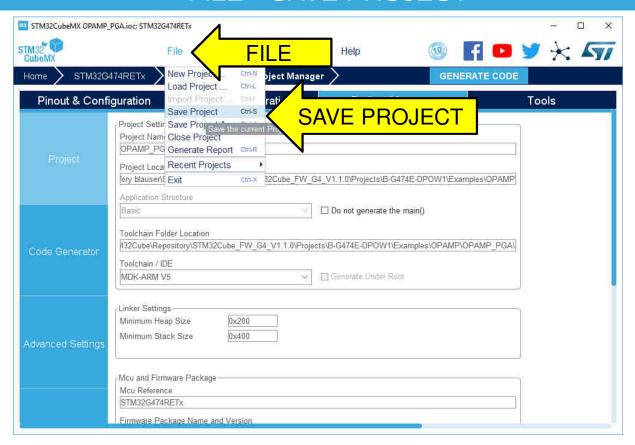
Project Manager – Keil MDK-ARM V5







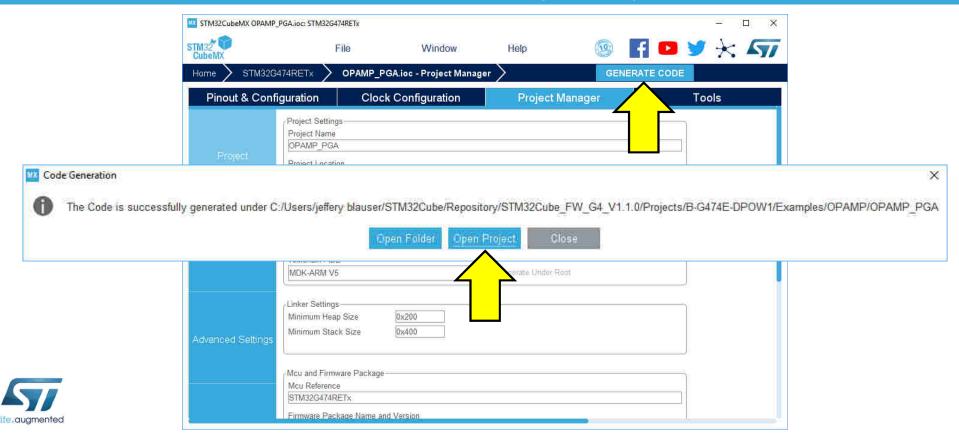
FILE→SAVE PROJECT







Generate Code→Open Project





Keil Start up page

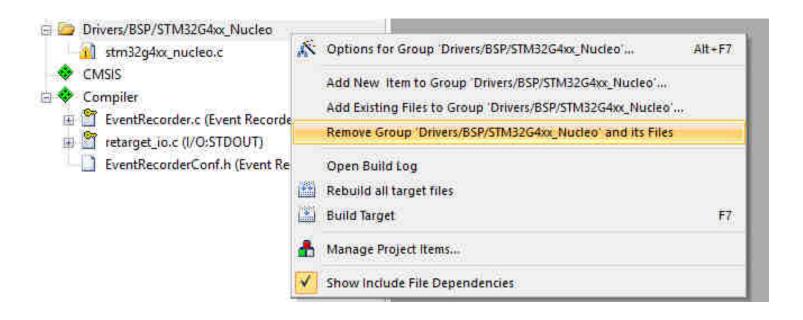
```
File Edit View Project Flash Debug Peripherals Tools SVCS Window Help
 ☑ 🗟 🏕 ◎ - | ○ ○ 🔗 🐠 - | 🗃 - 🔍
 OPAMP_PGA
                                  ■系 品品◆◆館
                             readme.txt main.c stm32g4xx_it.c
Project: OPAMP_PGA
                                       if (UserButtonStatus == 1)
  DOPAMP_PGA
                               145
                                         HAL Delay(200);
     Application/MDK-ARM
                               146
                                         UserButtonStatus = 0;
     Application/User
                               147
                                         /* Change the gain */
       main.c
                               148
                                         if (hopamp3.Init.PgaGain == OPAMP PGA GAIN 2 OR MINUS 1)
       stm32q4xx_it.c
                               149
                                          hopamp3.Init.PgaGain = OPAMP PGA GAIN 4 OR MINUS 3;
      stm32g4xx_hal_msp.c
                               151
     🗎 🛅 Doc
                               152
        readme.txt
                               153
     ⊞ 🍱 Drivers/BSP/STM32G4xx Nuc
                               154
                                          hopamp3.Init.PgaGain = OFAMP_PGA_GAIN_2_OR_MINUS_1;
                               155
     Drivers/STM32G4xx_HAL_Driv
                               156
                                         /* Update OPAMP config */
     Drivers/CMSIS
                               157
                                         /* Gain is changed on the fly */
if(HAL_OK != HAL_OPAMP_Init(&hopamp3))
       ⊞ 📗 system_stm32g4xx.c
                               158
      CMSIS
                               159
                                          Error_Handler();
                               160
                               161
                               162
                               163
                                       /* USER CODE END WHILE */
                               164
                               165
                               166
                                       /* USER CODE BEGIN 3 */
                               167
                                     /* USER CODE END 3 */
                               168
                               169
                              170 ⊟/**
                                     * @brief System Clock Configuration
                               172
                                     * @retval None
                               173
                                   void SystemClock Config(void)
                               175
                              176
177
                                     RCC_OscInitTypeDef RCC_OscInitStruct = {0};
RCC_ClkInitTypeDef RCC_ClkInitStruct = {0};
                               178
                               179
                                     /** Configure the main internal regulator output voltage
                               181
                                     HAL PWREx_ControlVoltageScaling(PWR_REGULATOR_VOLTAGE_SCALE1_BOOST);
                               182
                                     /** Initializes the CPU, AHB and AFB busses clocks
                               183
                               184
                                     RCC OscInitStruct.OscillatorType = RCC OSCILLATORTYPE HSI;
                                     RCC OscInitStruct.HSIState = RCC HSI ON;
                                     RCC OscInitStruct.HSICalibrationValue = RCC HSICALIBRATION DEFAULT;
                                     RCC_OscInitStruct.PLL.PLLState = RCC_PLL_ON;
```







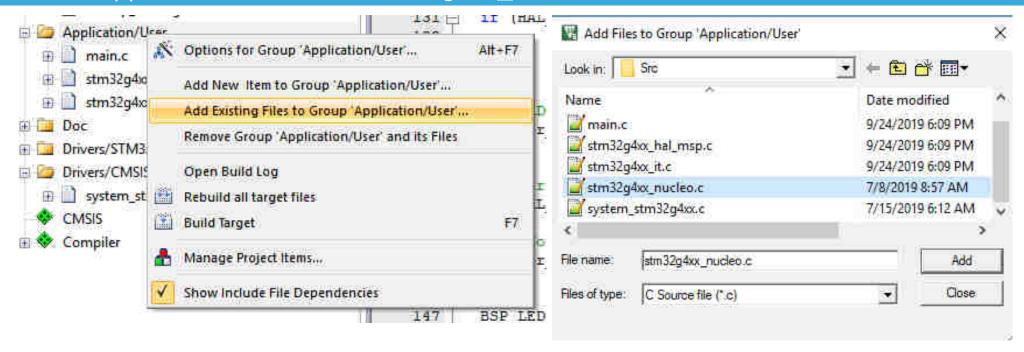
Delete Drivers Folder







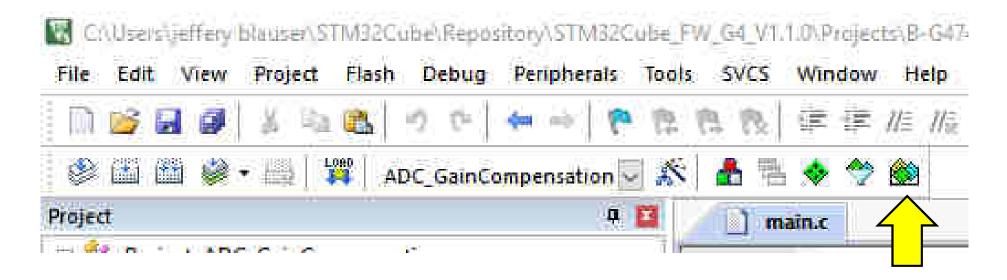
Application/User folder stm32g4xx_nucleo.c from SRC folder - CLOSE





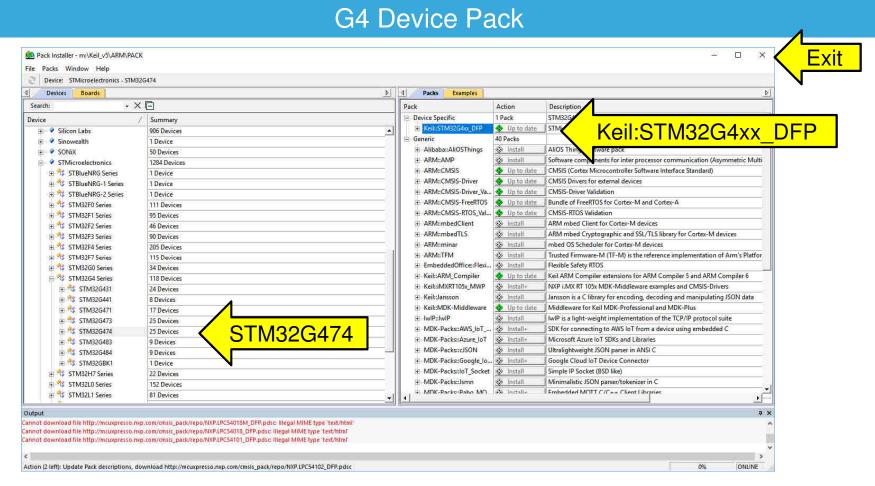


Check the Device Pack





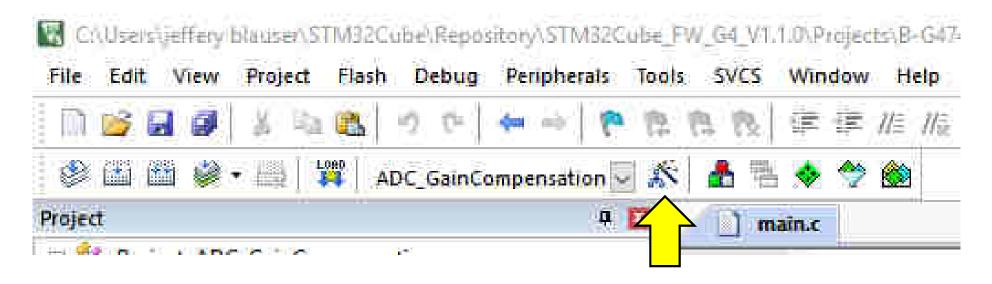








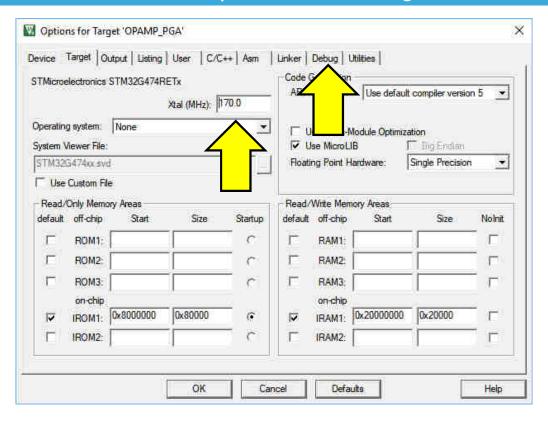
Check the Options







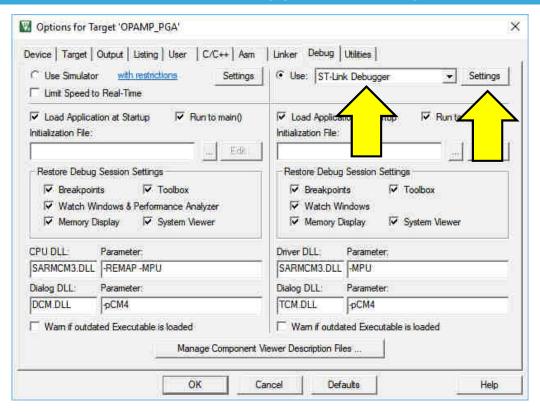
Clock speed and Debug







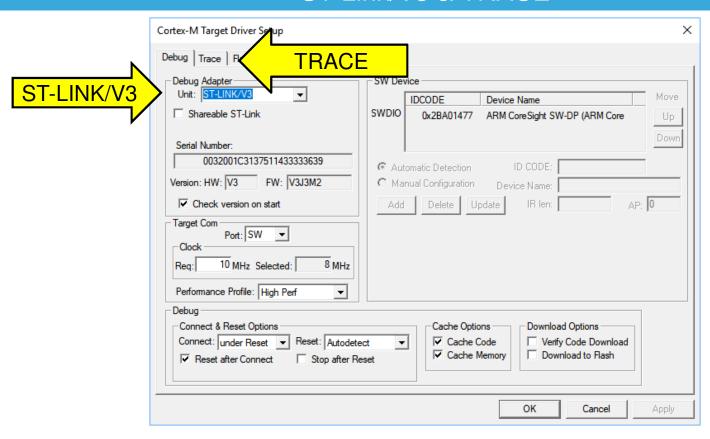
ST-Link Debugger - Settings







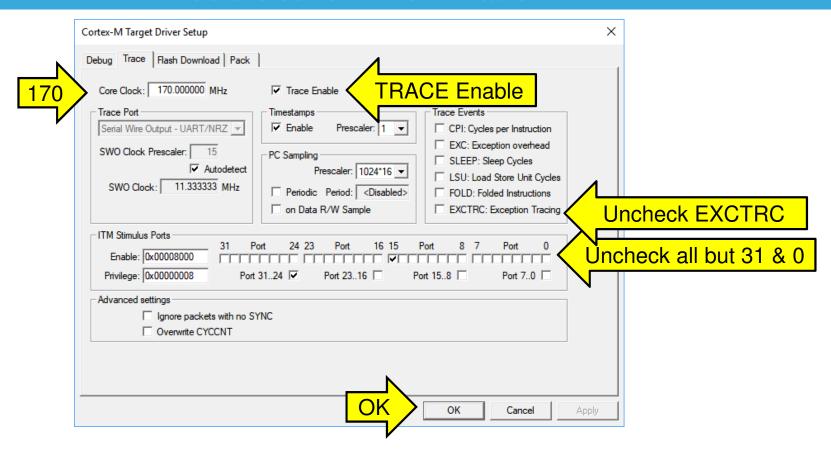
ST-Link/V3 & TRACE







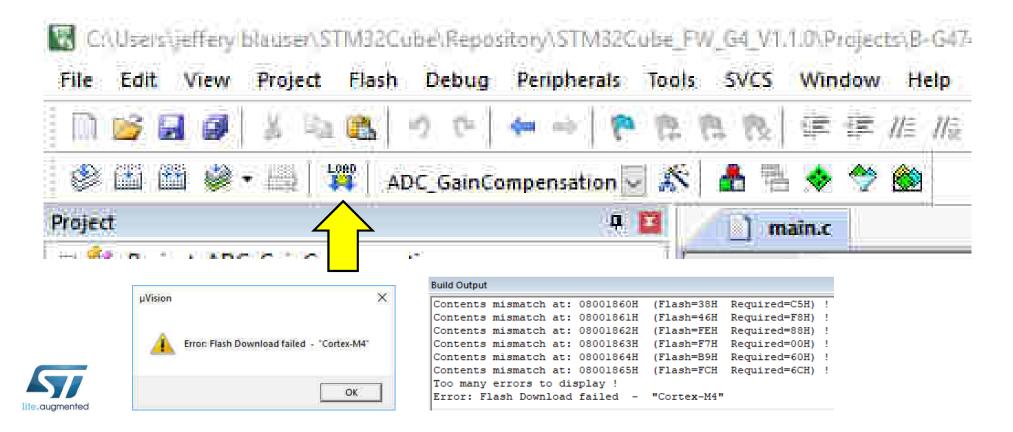
Core Clock & TRACE Enable





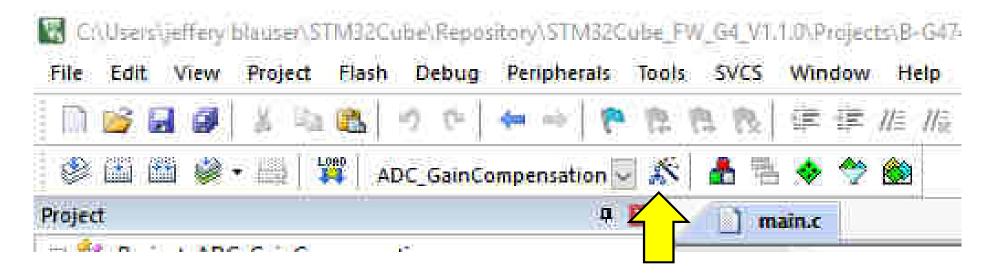


Load





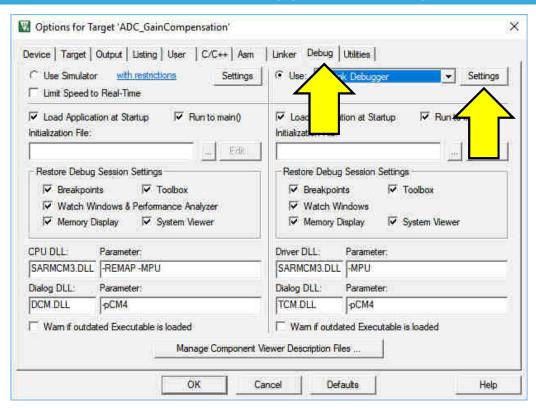
Options







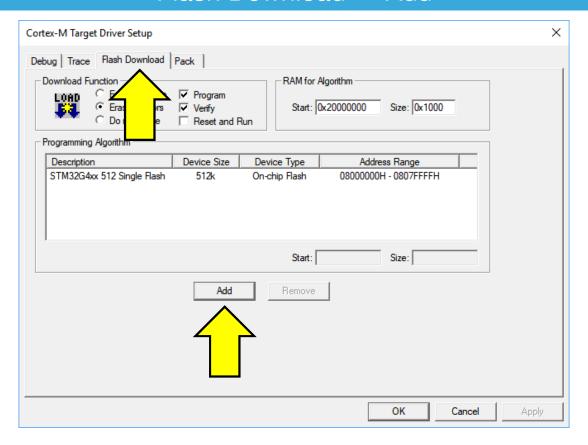
ST-Link Debugger - Settings







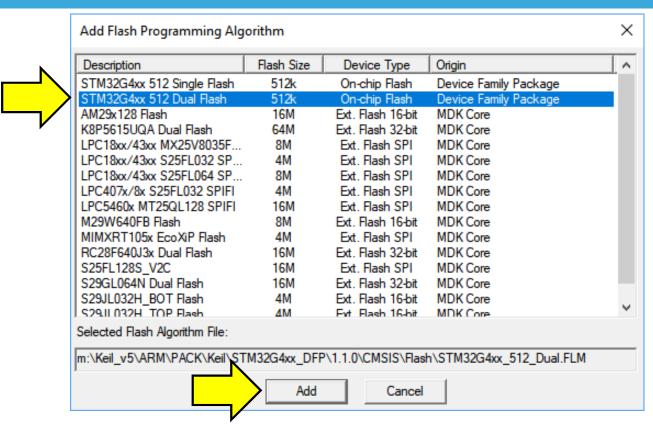
Flash Download → Add







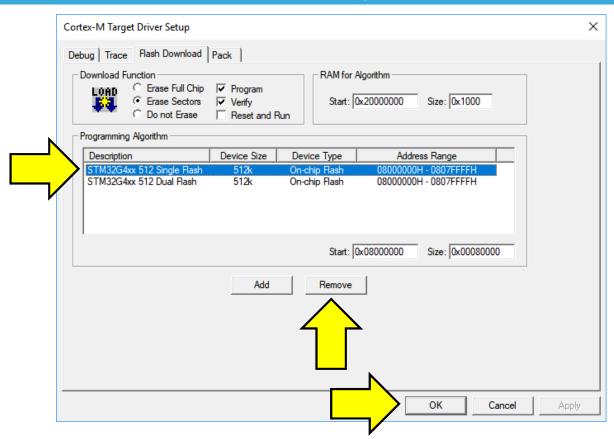
STM32G4xx 512 Dual Flash







Remove Single Flash







Place variable in the Analyzer - main.c about lines 235 & 240

```
startup_stm32g474xx.s main.c readme.txt
         /* USER CODE BEGIN DAC1 Init 2 */
 234
         / ** DAC calibration
 235
 236
         if (HAL DACEX SelfCalibrate (&hdacl, &sConfig, DAC CHANNEL 1) != HAL OK)
 237
                                                                              Split Window horizontally
 238
           Error Handler();
 239
                                                                              Insert #include file
 240
         if (HAL DACEx SelfCalibrate(&hdacl, &sConfig, DAC CHANNE
                                                                              Toggle Header/Code File
 241
 242
            Error Handler();
 243
                                                  μVision
         /* USER CODE END DAC1 Init 2 */
 244
 245
                                                                                                                       Ctrl+F10
 246
                                                   Cannot add 'DAC_CHANNEL_1' to Logic Analyzer
 247
 248 -/**
                                                                                                                        Ctrl+F9

    Øbrief TIM2 Initialization Functi

                                                                                               C_CHANNEL_1'
                                                                                                                           F12
         · @param None
                                                                                     OK
 251
         · Gretval None
                                                                                                DAC CHANNEL 1"
                                                                                                                     Ctrl+Num +
 252
                                                                              Go To Previous Reference To 'DAC_CHANNEL_1'
                                                                                                                     Ctrl+Num -
 253
       static void MX TIM2 Init (void)
254 - [
                                                                              Add DAC_CHANNEL_1' to...
                                                                                                                                   Watch 1
 255
 256
         /* USER CODE BEGIN TIM2 Init 0 */
                                                                                                                                   Watch 2
                                                                             Insert Tracepoint at 'DAC_CHANNEL_1'...
 257
                                                                              Enable/Disable Tracepoint
                                                                                                                                   Memory 1
 258
         /* USER CODE END TIM2 Init 0 */
 259
                                                                                                                                   Memory 2
                                                                          Insert/Remove Bookmark
                                                                                                                        Ctrl+F2
 260
         TIM ClockConfigTypeDef sClockSourceConfig = {0};
                                                                                                                                   Memory 3
                                                                          Undo
 261
         TIM MasterConfigTypeDef sMasterConfig = {0};
                                                                                                                        Ctrl+Z
                                                                                                                                   Memory 4
 262
                                                                          P Redo
                                                                                                                         Ctrl+Y
 263
         /* USER CODE BEGIN TIM2 Init 1 */
                                                                          A Cut
                                                                                                                        Ctrl+X
                                                                                                                                   Analyzer
 264
         /* USER CODE END TIM2 Init 1 */
 265
                                                                          - Copy
                                                                                                                        Ctrl+C
```





Debugger – Exit back to the Editor









Add 3 new variables in main.c about line 59

```
54 /* USER CODE BEGIN PV */
55 /* Private variables -----
56 /* set to 1 after User push-button interrupt */
     IO uint32 t UserButtonStatus = 0;
58
    uint16 t Display DAC1DOR1;
59
    uint16 t Display DAC3DOR2;
60
    uintl6 t Display ADC3IN1;
61
```

See C:\2019_STM32G4_Workshop\Labs\OPAMP CodeLinesForOpAmp.txt if you prefer to copy and paste Or open the file from the Doc folder in the Editor





Add new lines in main.c about line 177

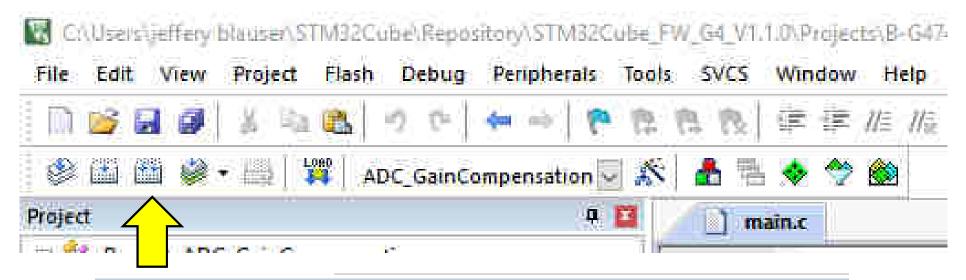
```
174
             Error Handler();
175
176
         /* Display the global variables in the Logic Analyzer */
177
         Display DAC1DOR1 = DAC1->DOR1;
178
         HAL Delay(1); //1 millisecond delay to transfer data to the PC
179
         Display DAC3DOR2 = DAC3->DOR1;
180
                       //1 millisecond delay to transfer data to the PC
181
         HAL Delay(1);
182
         Display ADC3IN1 = ADC3->DR;
         HAL Delay(1); //1 millisecond delay to transfer data to the PC
183
184
185
         /* USER CODE END WHILE */
```

See C:\2019_STM32G4_Workshop\Labs\OPAMP CodeLinesForOpAmp.txt if you prefer to copy and paste Or open the file from the Doc folder in the Editor





Build



Build Output

Program Size: Code=6516 RO-data=596 RW-data=44 ZI-data=1268

FromELF: creating hex file ...

OPAMP PGA\OPAMP PGA.hex: Warning: Q9931W: Your license for feature Keil will expire in 30 days

Finished: 0 information, 1 warning and 0 error messages.

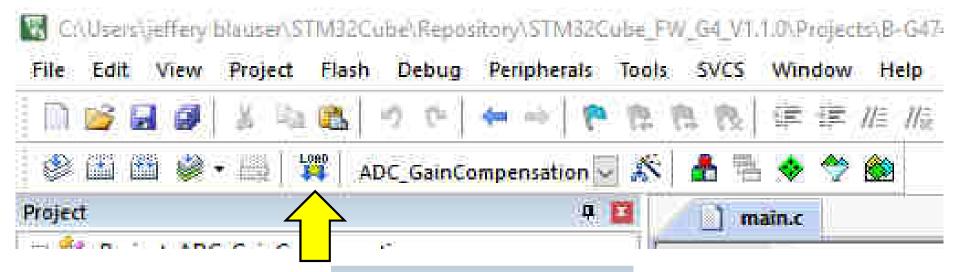
"OPAMP PGA\OPAMP PGA.axf" - 0 Error(s), 0 Warning(s).

Build Time Elapsed: 00:01:22





Load





Build Time Elapsed: 00:01:22 Load "OPAMP PGA\\OPAMP PGA.axf" Erase Done.

Programming Done.

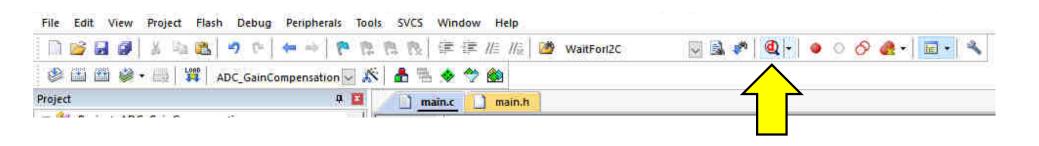
Verify OK.

Flash Load finished at 17:34:57





Debugger

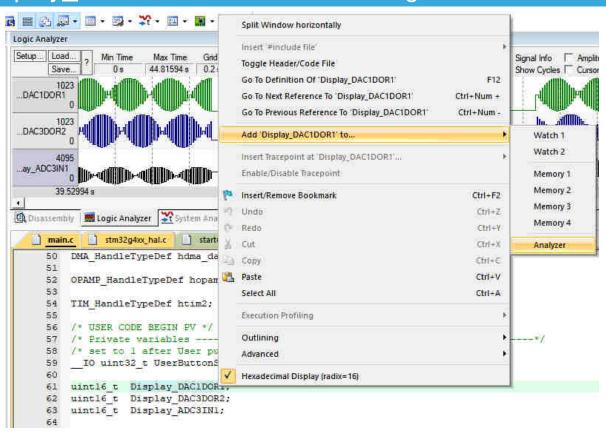








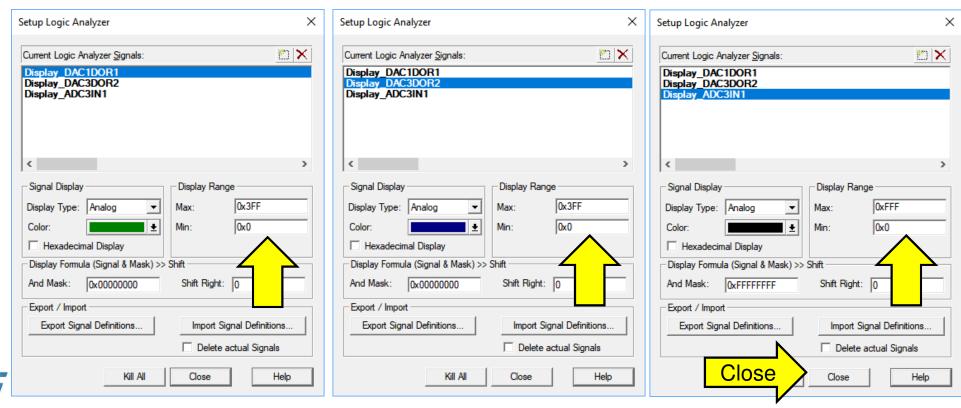
Find the 3 Display_xxx about main.c line 61 - right click on each - add to Analyzer







Setup – Min=0x0, Max = 0x3FF for DACs, then Min=0x0, Max = 0xFFF for ADC - Close

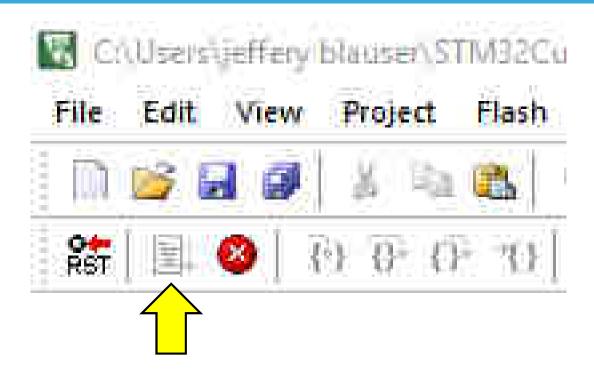






Keil MDK-ARM 145

RUN

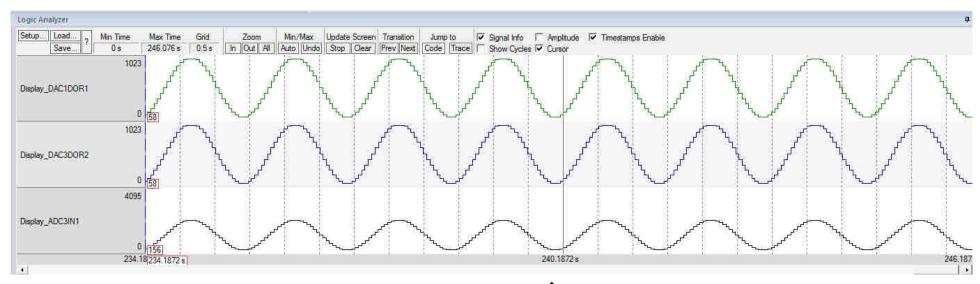






Keil MDK-ARM 146

RUN



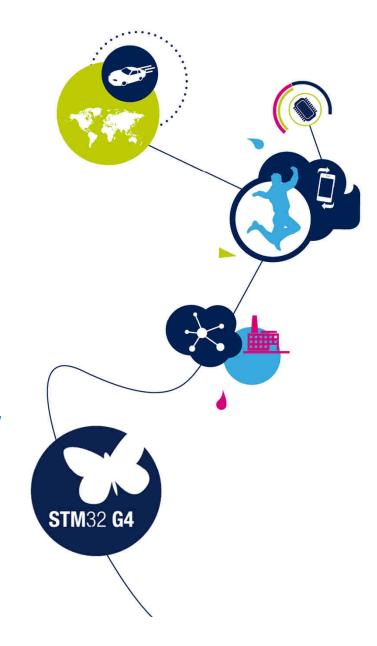




STM32G4 mixed-signal MCU workshop

Hands On: CORDIC Hardware Accelerator







CORDIC: Main features 148

- 24-bit CORDIC rotation engine
 - Trigonometric and Hyperbolic functions
- Circular and Hyperbolic modes
- Rotation and Vectoring modes
- Programmable precision
- Low latency AHB slave interface
- DMA read and write channels



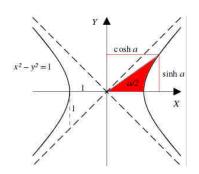


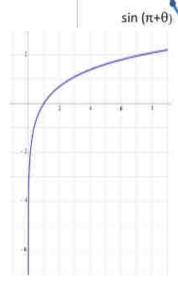
Cordic: Main features 149

- Supported functions:
 - Sine, Cosine: Vector rotation (polar to rectangular)
 - Arctangent, Modulus: Vector translation (rectangular to polar)
 - Hyperbolic cosine
 - Hyperbolic sine
 - Hyperbolic tangent
 - Natural logarithm
 - Square root



- Q1.31 or Q1.15 format
- Performance improvement relative to software
 - Sine and Cosine functions are typically 5x faster than software execution





 $\sin \theta$

 $sin(\pi-\theta)$

 $\sqrt{\sin(2\pi-\theta)}$





CORDIC - Precision 150

Precision is dependent on number of iterations

Function	Number of iteration	of	Max residual error	
	(precision)		q1.31 format	q1.15. format
Sin, Cos, Phase, Mod, Atan	4	1	2 ⁻³	2 ⁻³
	8	2	2 ⁻⁷	2 ⁻⁷
	12	3	2 ⁻¹¹	2 ⁻¹¹
	16	4	2 ⁻¹⁵	2 ⁻¹⁵
	20	5	2 ⁻¹⁸	2 ⁻¹⁶
	24	6	2 ⁻¹⁹	2 ⁻¹⁶





CORDIC - Precision 151

	Number of	Number of cycles	Max residual error	
Function	iteration (precision)		q1.31 format	q1.15. format
Sinh, Cosh, Atanh, Ln	4	1	2 ⁻²	2 ⁻²
	8	2	2 ⁻⁶	2 ⁻⁶
	12	3	2 ⁻¹⁰	2 ⁻¹⁰
	16	4	2 ⁻¹³	2 ⁻¹³
	20	5	2 ⁻¹⁷	2 ⁻¹⁵
	24	6	2 ⁻¹⁸	2 ⁻¹⁵
	4	1	2 ⁻⁷	2 ⁻⁷
Sqrt	8	2	2 ⁻¹⁴	2 ⁻¹⁴
	12	3	2 ⁻¹⁹	2 ⁻¹⁵





CORDIC accelerator 152

Objective:

- To show how to configure the CORDIC accelerator.
 - Calculate the SIN and COS of angles with 6 cycles of precision.
- Enable the Event Recorder to measure the time for the CORDIC and ARM Math Library functions.
- Display CORDIC results in the Logic Analyzer.





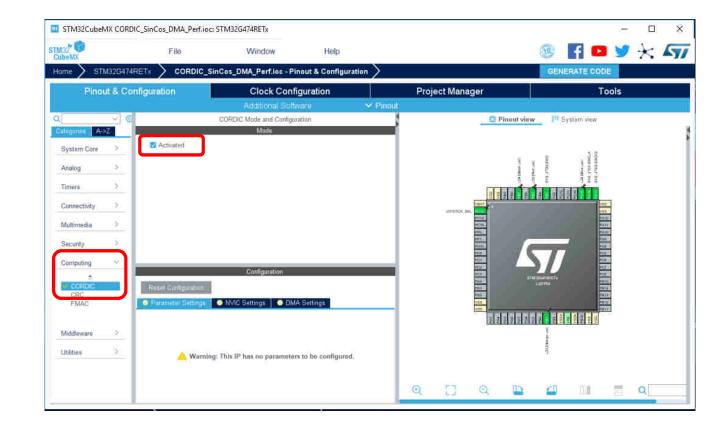
- Open CubeMX project "CORDIC_SinCos_DMA_Perf.ioc" file
 - \labs\Cordic\CORDIC_SinCos_DMA_Perf

Date modified	Туре	Size
8/28/2019 4:57 PM	File folder	
8/28/2019 8:22 PM	File folder	
8/29/2019 2:53 AM	File folder	
8/28/2019 8:22 PM	File folder	
8/28/2019 8:22 PM	MXPROJECT File	7 KB
8/29/2019 3:32 AM	IOC File	9 KB
	8/28/2019 4:57 PM 8/28/2019 8:22 PM 8/29/2019 2:53 AM 8/28/2019 8:22 PM 8/28/2019 8:22 PM	8/28/2019 4:57 PM File folder 8/28/2019 8:22 PM File folder 8/29/2019 2:53 AM File folder 8/28/2019 8:22 PM File folder 8/28/2019 8:22 PM MXPROJECT File





- Expand "Computing" Category
- Select "CORDIC"
 - CHECK "Activated"





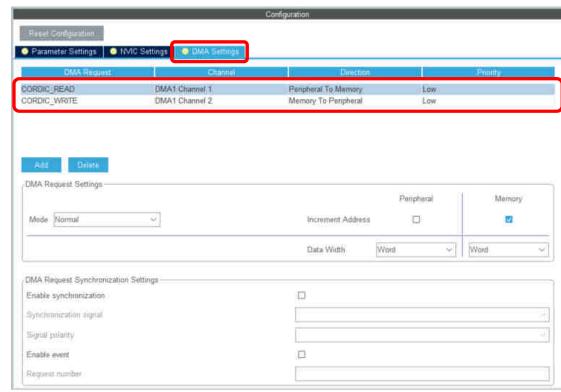


Resel Configuration DMA Request is enabled

32-bit Data Width (Word)

of CORDIC

to transfer data in and out

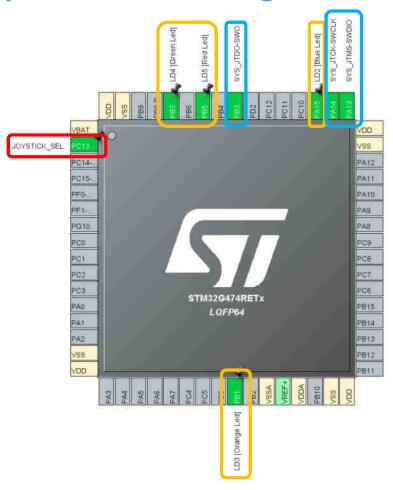






Additional Peripheral configuration 156

- JOYSTICK_SEL: EXTI13
 - PC13
- LD2-5: GPIO_Output
 - PA15, PB1, PB5 and PB7
- Serial Wire Debug with Trace (SWO):
 - PA13, PA14 and PB3





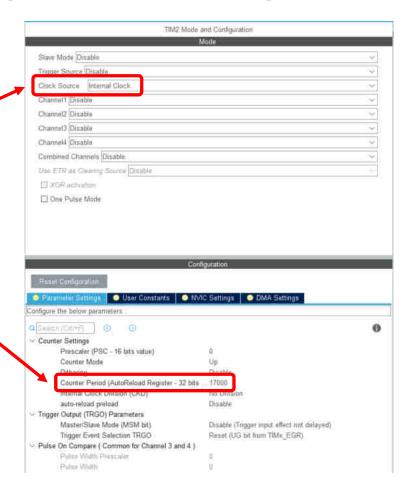


Additional Peripheral configuration

- Timer 2: Debug Logic Analyzer
- Internal Clock Source = 170 MHz
- Counter Period = 17000
 - 10 kHz timebase interrupt
- TIM2 global interrupt Enabled

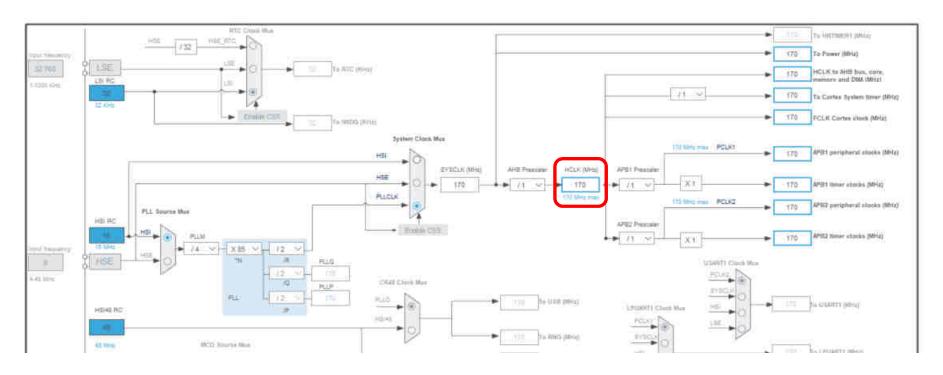








Validate "HCLK (MHz)" is set to 170







Generate Code



Open Project in MDK-ARM







aAnglesCordic - Array of angles for CORDIC Q1.31 format (Line 57)

```
56 /* Array of angles for CORDIC Q1.31 format, regularly incremented from 0 to 2*pi */
57 static int32 t aAnglesCordic[ARRAY SIZE] =
59 0x00000000, 0x04000000, 0x08000000, 0x0C000000,
```

aAnglesLib – Array of angles for ARM Math library (Line 78)

```
77 /* Array of angles for arm math library Q1.31 format, regularly incremented from 0 to 2*pi */
78 static int32 t aAnglesLib[ARRAY SIZE] =
80 0x00000000, 0x02000000, 0x04000000, 0x06000000,
```

aRefSin & aRefCos – Array of Sin & Cos result reference (Line 99 & 120)

```
119 /* Array of reference cosines in Q1.31 format */
 98 /* Array of reference sines in Q1.31 format */
                                                             120 static int32 t aRefCos[ARRAY SIZE] =
 99 static int32 t aRefSin[ARRAY SIZE] =
                                                            122 0x80000000, 0x7F62368F, 0x7D8A5F3F, 0x7A7D055B,
101 0x00000000, 0x0C8BD35E, 0x18F8B83C, 0x25280C5D,
```

aResults – Array of calculation results (Line 142)

```
140 □/* Array of calculation results in Q1.31 format.
141 Will contain alternatively Sine and Cosine of input angles */
142 static int32 t aResults[2 * ARRAY SIZE];
```





- Sine calculation function (Line 219)
- 6 cycles of precision (Line 220)
- No Scaling (Line 221)
- One input angle data (Line 222)
 - Q1.31 format for input data (Line 224)

```
217
       /* USER CODE BEGIN 2 */
218
       /*##-2- Configure the CORDIC peripheral ########
219
       sCordicConfig.Function
                                       = CORDIC FUNCTION SINE;
220
                                       = CORDIC PRECISION 6CYCLES;
       sCordicConfig.Precision
221
       sCordicConfig.Scale
                                       = CORDIC SCALE 0;
222
       sCordicConfig.NbWrite
                                       = CORDIC NBWRITE 1;
223
       sCordicConfig.NbRead
                                       = CORDIC NBREAD 2;
224
       sCordicConfig.InSize
                                       = CORDIC INSIZE 32BITS;
225
                                       = CORDIC OUTSIZE 32BITS;
       sCordicConfig.OutSize
```

- Two output data (Sine and Cosine) (Line 223)
 - Q1.31 format for input data (Line 225)





Step = 0

- Calculation made with CORDIC
- Simple call to HAL_CORDIC_Calculate_DMA

- Step = 1
 - Calculation made with ARM Math library
 - Lines 277 through 283 are called to perform same CORDIC operation

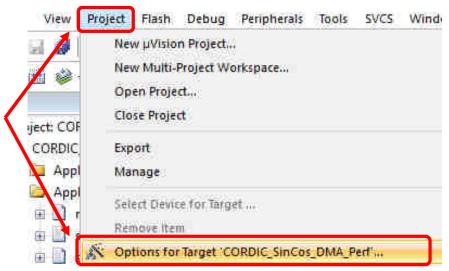
```
246
            /*###################### Calculation using CORDIC ########################
247
248
              for (uint32 t i = 0; i < LOOP NB; i++)
249
250
251
                   Start calculation of sines in DMA mode */
252
                    HAL CORDIC Calculate DMA(&hcordic, aAnglesCordic, aResults,
                                                                            != HAL OK)
253
                                           ARRAY SIZE, CORDIC DMA DIR IN OUT)
254
255
                  /* Processing Error */
256
                  Error Handler():
257
258
272
            273
274
              for (uint32 t i = 0; i < LOOP NB; i++)
275
276
277
                for (uint32 t j = 0; j < ARRAY SIZE; j++)</pre>
278 円
279
                  /* Calculate sine */
280
                  aResults[2*j] = arm sin q31(aAnglesLib[j]);
281
282
                  /* Calculate cosine */
283
                  aResults[(2*j) + 1] = arm cos q31(aAnglesLib[j])
284
285
```



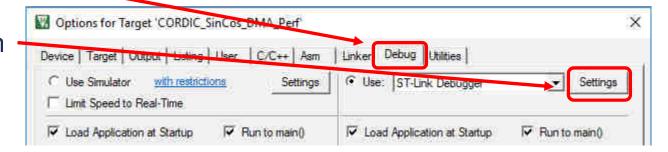


Enable Debug Trace

 Open "Options for Target 'CORDIC_SinCos_DMA_Perf' ..." window.



- Switch to "Debug" tab
- Click "Settings" button

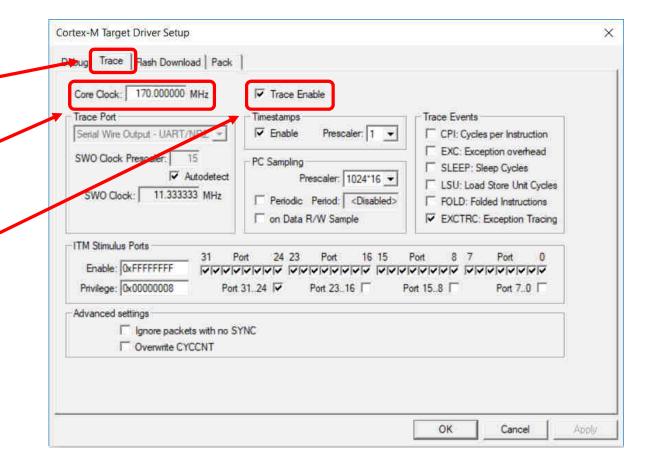






Enable Debug Trace 164

- Switch to "Trace" tab
- Set "Core Clock" = 170 MHz
- Click "Trace Enable" check box



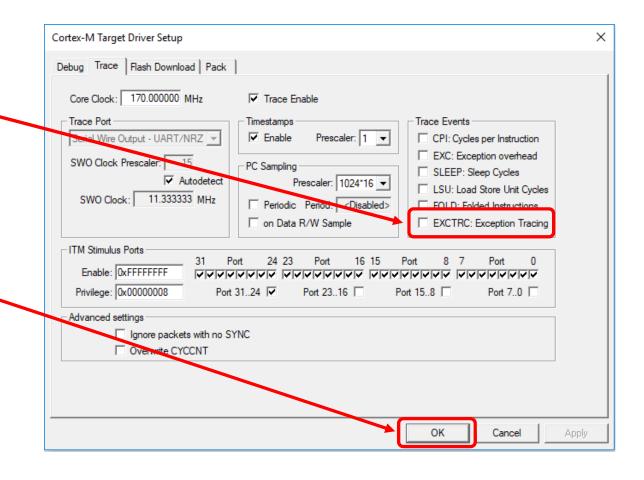




Enable Debug Trace 165

- Disable "Exeception Tracing"
 - Uncheck Box

 Click "OK" to close setup window

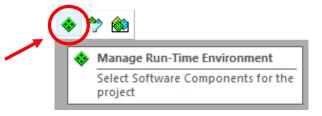




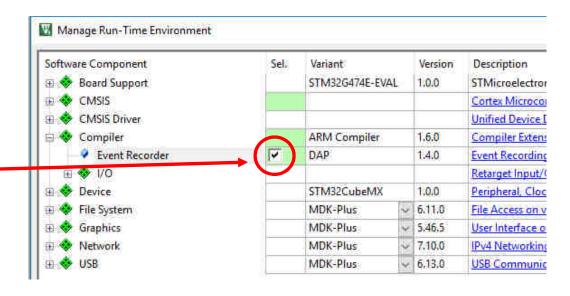


Enable Event Recorder 166

Click on Manage Run-Time Environment



- Expand "Compiler"
- Enable "Event Recorder"
 - Check Box
- Click "OK"







Enable Event Recorder 167

Open "main.c" under Application/User folder



Line 27: Add (uncomment)

#include "EventRecorder.h.

Line 191 & 192: Add (uncomment)

EventRecorderInitialize(EventRecordAll, 1); EventRecorderStart();

```
/* Private includes -----
/* USER CODE BEGIN Includes */
#include <arm math.h>
#include "EventRecorder.h"
/* USER CODE END Includes */
```

```
178 int main (void)
179 □ {
180
       /* USER CODE BEGIN 1 */
181
       /* STM32G4xx HAL library initialization:
182
            - Configure the Flash prefetch
183
            - Systick timer is configured by default as source of time base, but user
184
              can eventually implement his proper time base source (a general purpose
185
              timer for example or other time source), keeping in mind that Time base
186
              duration should be kept lms since PPP TIMEOUT VALUEs are defined and
187
              handled in milliseconds basis.
188
            - Set NVIC Group Priority to 4
189
            - Low Level Initialization
190
191
       EventRecorderInitialize(EventRecordAll, 1);
192
       EventRecorderStart();
       /* USER CODE END 1 */
193
```





Add (uncomment)

Line 250: EventRecord2(0,i,1); Line 258: EventRecord2(0,i,2);

Add (uncomment)

Line 276: EventRecord2(1,i,1); Line 285: EventRecord2(1,i,2);

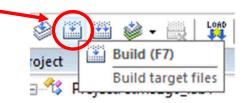


Enable Event Recorder 168

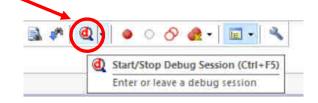
```
246
           247
248
             for (uint32 t i = 0; i < LOOP NB; i++)
249
250
              EventRecord2(0,1,1);
251
              / Start calculation of sines in DMA mode */
252
              if (HAL CORDIC Calculate DMA(&hcordic, aAnglesCordic, aResults,
253
                                      ARRAY_SIZE, CORDIC_DMA_DIR_IN_OUT) != HAL_OK)
254
255
                /* Frocessing Error */
256
                Error Handler();
257
258
              EventRecord2(0,1,2);
259
```

```
272
              /*########################### Calculation using arm math library #############*/
273
274
                for (uint32 t i = 0; i < LOOP NB; i++)
275 🖹
276
                  EventRecord2(1,i,1);
277
                  for (uint32 t j = 0; j < ARRAY SIZE; j++)
278
279
                    /* Calculate sine */
280
                    aResults[2*j] = arm sin q31(aAnglesLib[j]);
281
282
                    /* Calculate cosine */
283
                    aResults[(2*j) + 1] = arm_cos_q31(aAnglesLib[j]);
285
                  EventRecord2(1,i,2);
286
```

Click the "Build"



"Start Debug" Session



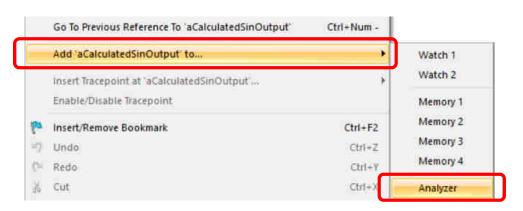


Enable Logic Analyzer

On line 152, Right mouse click on "aCalculatedSinOutput" variable

```
151  /* Logic Analyzer variables */
152  static int32_t aCalculatedSinOutput = 0;
153  static int32_t aCalculatedCosOutput = 0;
154  int32_t aResults_ptr = 0;
```

- Move mouse over "Add 'aCalculatedSinOutput' to…"
- Click on "Analyzer"





Enable Logic Analyzer

On line 153, Right mouse click on "aCalculatedCosOutput" variable

```
151  /* Logic Analyzer variables */
152  static int32 t aCalculatedSinOutput = 0;
153  static int32_t aCalculatedCosOutput = 0;
154  int32_t aResults_ptr = 0;
```

- Move mouse over "Add 'aCalculatedCosOutput' to…"
- Click on "Analyzer"



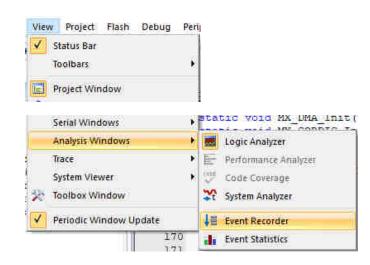


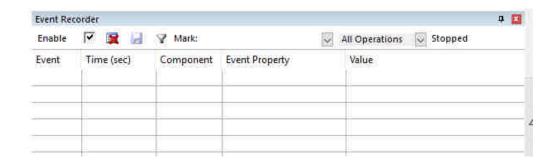
View Event Recorder

Go to "View" menu

Select "Analysis Windows"

Select "Event Recorder"



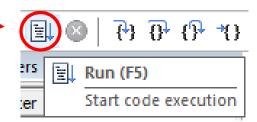




Run the Project

- "Run" the project
 - Capture trace data
 - Press "JOYSTICK_SEL" triggers "CORDIC" or "ARM Math library"
 - Green Led blinking
 - Fast blink (CORDIC used)
 - Slow blink (ARM Math Lib. Used)

"Stop" the project execution

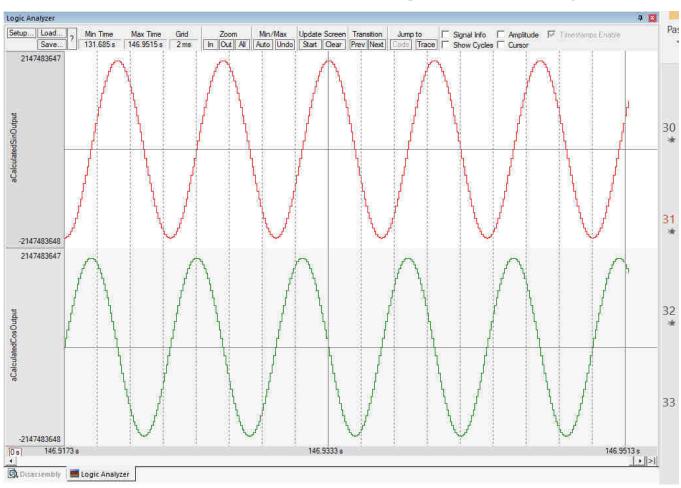






Logic Analyzer

 CORDIC results are shown in Logic Analyzer

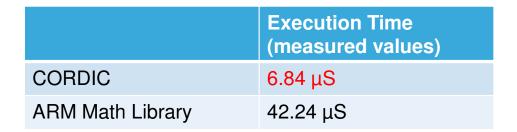




Event Recorder

- Events Captured
 - Event Number
 - Event Time Stamp
 - Event Property
 - Id = 0 (CORDIC)
 - Id = 1 (ARM Math Library)
 - Event Values
 - 1st: Loop Number
 - 2nd: Start(0x01) and End(0x02) of array calculation

Event Rec	order	en and a		₽ 🖫
Enable		▼ Mark:	Maria and an analysis of	All Operations Stopped-Missed 4523
Event	Time (sec)	Component	Event Property	Value
41819	1.44499562		id=0x0000	0x000031AF,0x00000002
41820	1:44500605		id=0x0000	0x000031B0,0x00000001
41821	1.44501337		id=0x0000	0x000031B0,0x00000002
41822	1.44502308		id=0x0000	0x000031B1,0x00000001
41823	1.44502995		id=0x0000	0x000031B1,0x00000002
41824	1.44503989		id=0x0000	0x000031B2,0x00000001
41825	1.44504672		id=0x0000	0x000031B2,0x00000002
41826	1.44505666		id=0x0000	0x000031B3,0x00000001
41827	1.44506349		id=0x0000	0x000031B3,0x00000002
41828	1.44507343		id=0x0000	0x000031B4,0x00000001
41829	1.44508026		id=0x0000	0x000031B4,0x00000002
41830	1.44509020		id=0x0000	0x000031B5,0x00000001
41831	1.44510062		id=0x0000	0x000031B5,0x00000002
41832	1.55492708		id=0x0000	0x0000057F,0x00000001
41833	1,55493392		id=0x0000	0x0000057F,0x00000002



Theoretical Calculation:

- 64 Array Size
- 2 functions output: sin and cos
- 24bit precision: 6cycles
 - Expected time: 4.52us =(1/170MHz)*64*2*6





CORDIC: Additional Notes 176

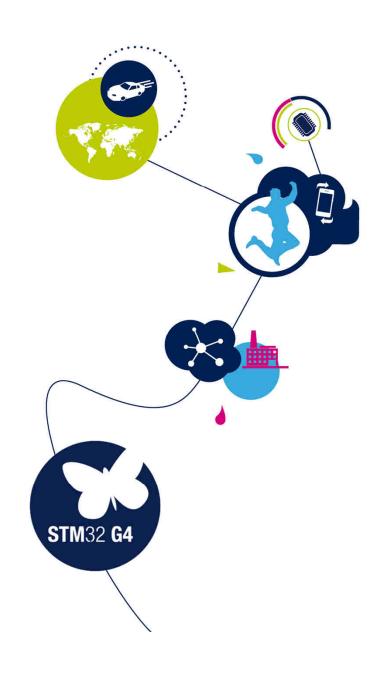
- Use Cube Low Level driver to reduce HAL overhead
- AN5325: Getting started with the CORDIC accelerator using the STM32CubeG4 MCU Package
- Keil Application Note 321: Event Recorder Debugging with STM32G Cortex-M0/M0+



STM32G4 mixed-signal MCU workshop

Filter Math Acclerator (FMAC)
Overview







Filter Math Accelerator 178

G4 FMAC

- Multiplier (16x16)
- Accumulator (24bit + 2bit)
- Address generation logic
- Input and Output Circular Buffers
- FIR & IIR filters possible
- Dot product, convolution, correlation
- Does not stall the CPU
- 256 x 16bit local memory
- Built-in sequencer
- Runs at the System Clock speed

Internally connected to:

- DMA
- AHB slave interface
- NVIC

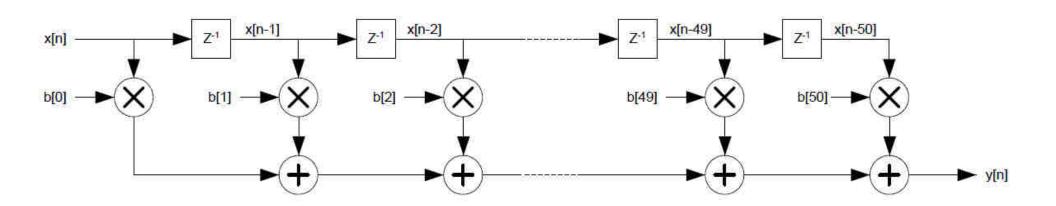




Filter Math Accelerator 179

G4 Adaptive FIR Filter

Figure 7. 51-tap FIR filter



- FIR filter is a convolution of the signal with filter coefficients
- The number of coefficients determines the minimum notch size
- Calculating N coeffcients requires N*N operations





Filter Math Accelerator 180

G4 Adaptive FIR Filter - Quantities

- Filter Coefficients will probably be in floating point format
- Coefficient conversion to 16 bit fixed point is necessary
- Fixed point format is Q1.15
 - Bits [0..14] represent fractional digits
 - Bit 15 is a sign bit
 - Range = -1.0 (0x8000) to +0.999969482421875 (0x7FFF)
- Proper design will keep the absolute value coefficients < or = 1
 - If not, all coefficients will need to be divided by the greatest coefficient
- To convert floating to fixed point, the Floating Point Unit is used
 - FPU takes 8 cycles per conversion
 - 51 coefficients take ~408 clock cycles





Lab steps 1 of 6

This Hands On Lab illustrates noise cancellation using an adaptive FIR filter.

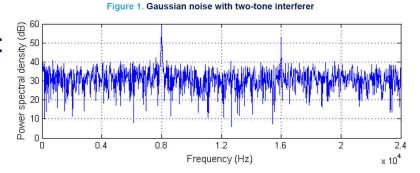
The experiment will be run on two input frames:

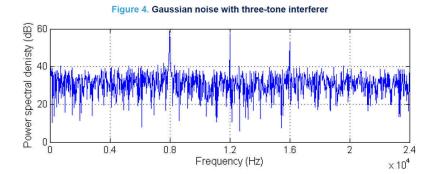
- a gaussian noise with two tone interferers.
- a gaussian noise with three tone interferers.

Create individual coefficient sets.

The result is a "whitened" noise.









Lab steps 2 of 6

- The FMAC peripheral will be configured to perform an adaptive FIR filter.
- There will be 51 feed-forward taps.
- The gain is equal to 0.
- The input and output thresholds are set to 1.
- The clipping feature can be enabled or disabled thanks to the compilation







Lab steps 3 of 6

The FMAC peripheral is making the best use of its 256 x 16-bit internal memory.

The local memory is divided into three buffers:

- 0 to 50: coefficient buffer;
- 51 to 150: input buffer;
- 151 to 250: output buffer;
- 251 to 255: unused.





Lab steps 4 of 6

- DMA mode is used to transfer input data from memory TO the FMAC peripheral.
- DMA mode is used to transfer output data FROM FMAC peripheral to memory.
- The coefficient buffer contains the vector of feed-forward taps
- This is named the B buffer
 - (size comprised in [2:127]; here, size N = 51 elements).
- This buffer is initialized during the configuration step in DMA mode.





Lab steps 5 of 6

The size of the input buffer is the sum of:

- the size of the coefficient vector B (N = 51 elements);
- the size of the additional space D1 needed for throughput improvement (minimum: 0; here, D1 = 49 elements).

The input buffer is filled during the preload step in DMA mode; new values are added in DMA mode once the preloaded ones have been consumed.

The size of the output buffer is the one of the additional space D2 needed for a better throughput (minimum: 1; here, D2 = 100 elements). The output buffer is read in DMA mode.





Lab steps 6 of 6

STM32 board LEDs are used to monitor the example status:

- LED4 is ON when correct FMAC FIR results have been calculated.
- LED5 is blinking (1 second period) if an error is detected in the FIR filter results or if there is an initialization or configuration error.

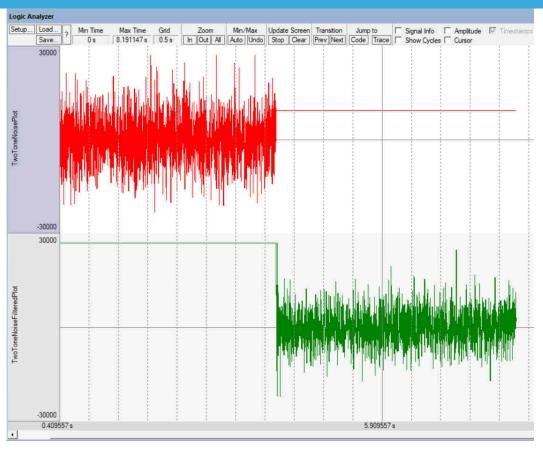
The filtered output is displayed in the Terminal I/O if the compilation switch PRINT OUTPUT is enabled in main.h.





How to view it

- Red shows 2 tone noise
- Green the filtered signal

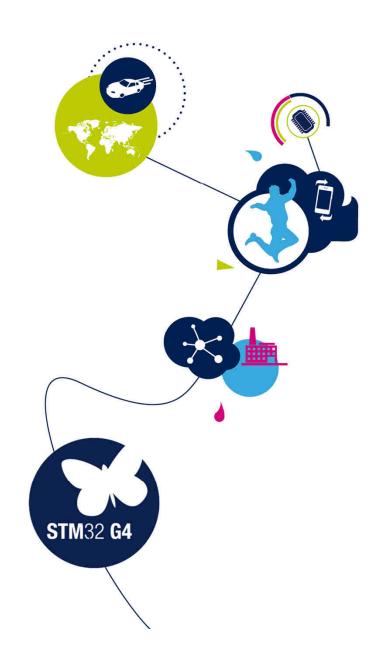




STM32G4 mixed-signal MCU workshop

Hands On: Dual Bank Flash Live Firmware Upgrade







Dual Bank flash 189

Objective:

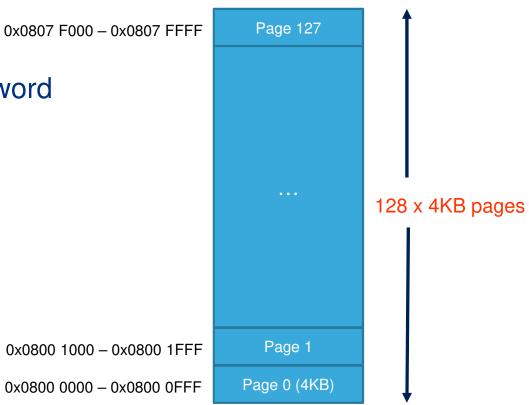
- To show the application running from one bank and writing to the second bank(Read-While-Write). Demonstrate the live upgrade possibility.
- Using a Terminal (TeraTerm) to send updated application binary file via the Virtual Comm Port.



512 KB die Flash Organization

- DBANK = 0 (Single Bank)
 - 128 bits read access
- ECC: 8 bits per 64 bit double-word
- 4 Write protection areas
- Page and Mass erase

512 KB Flash (Cat. 3)



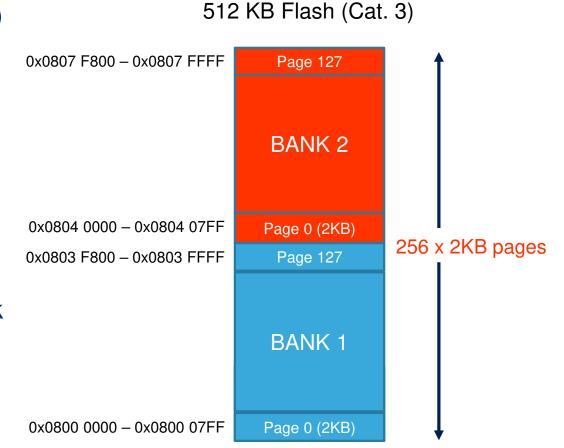
0x0800 1000 - 0x0800 1FFF

0x0800 0000 - 0x0800 0FFF



512 KB die Flash Organization

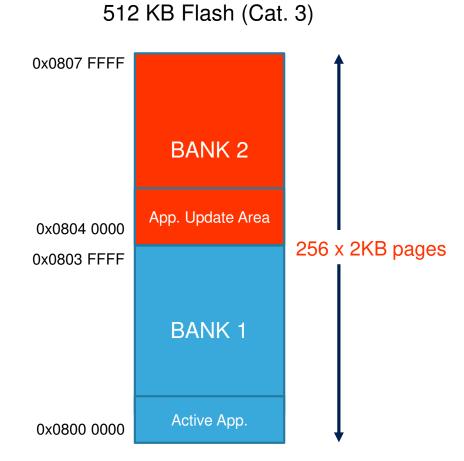
- DBANK = 1 (Dual Bank Default)
 - 64 bits read access
- Read-While-Write (RWW)
- ECC: 8 bits per 64 bit doubleword
- 2 Write protection areas per bank
- Page, Bank and Mass erase





512 KB die Flash Organization

- Active application executing from Bank 1
- Using serial port to receive update
 - Temporary storage in RAM
- Write to BANK 2 area
- Switch application execution to BANK 2

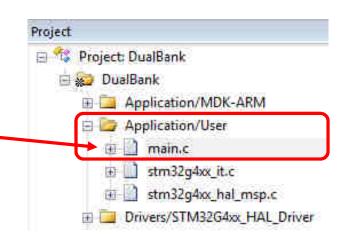






Hands-On: Dual Bank flash 193

- Open the DualBank project in Keil MDK-ARM folder
 - DualBank\MDK-ARM\DualBank.uvprojx
- Expand "Application/User" folder
- Open "main.c" file
 - Initialize the Clocks, GPIO and Peripherals
 - Main while loop (State Machine)
 - Handles BANK 2 page erase
 - Handles BANK 2 page write
 - Jump and Execute in Bank 2



DualBank.uvprojx





IRQ Callback functions 194

- Timer 2 IRQ Callback(Line 481)
 - 10 Hz period
 - LD ptr: Tracks LED to toggle
- GPIO EXTI Callback (Line 509)
 - Detects rising edge of JOYSTICK_SEL button
- UART Rx complete Callback (Line 524)
 - Signals that the USART Rx DMA has completed

```
void HAL_TIM_PeriodElapsedCallback(TIM_HandleTypeDef *htim)
482 - {
       switch ( LD ptr )
509 void HAL GPIO EXTI Callback (uintl6 t GPIO Pin)
510 - {
       if ( ( GPIO Pin == JOYSTICK SEL Pin ) && ( UpdateState == 0 ) )
511
     void HAL UART RxCpltCallback(UART HandleTypeDef *huart)
525 □ {
526
        rx complete = 1;
527
```

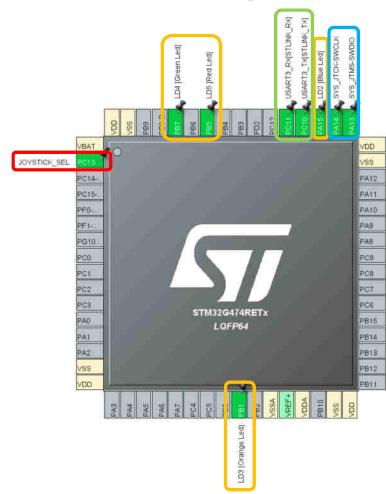




Peripheral configuration 195

- JOYSTICK_SEL: EXTI13
 - PC13
- LD2-5: GPIO_Output
 - PA15, PB1, PB5 and PB7
- ST-LINK VCP: USART3
 - PC10 and PC13
- Serial Wire Debug with Trace (SWO):
 - PA13, PA14 and PB3



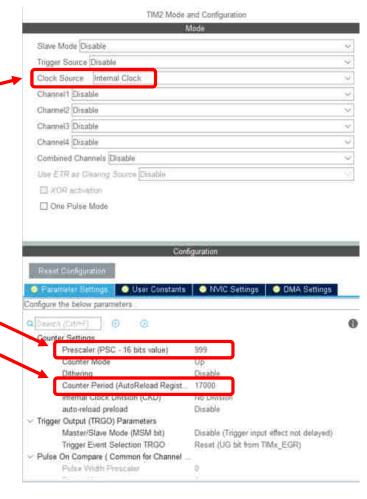




Peripheral configuration

- Timer 2: LED blink rate timer
- Internal Clock Source = 170 MHz
- Prescaler = 999
- Counter Period = 17000
 - 10 Hz timebase interrupt
- TIM2 global interrupt Enabled





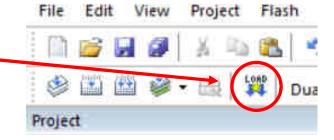


Build the Project

"Build" project



"LOAD" project to flash



- Press the "RESET" button on the Discovery
 - 4 LEDs blinking in rotating pattern.



Hands On: Dual Bank

Launch "TeraTerm"



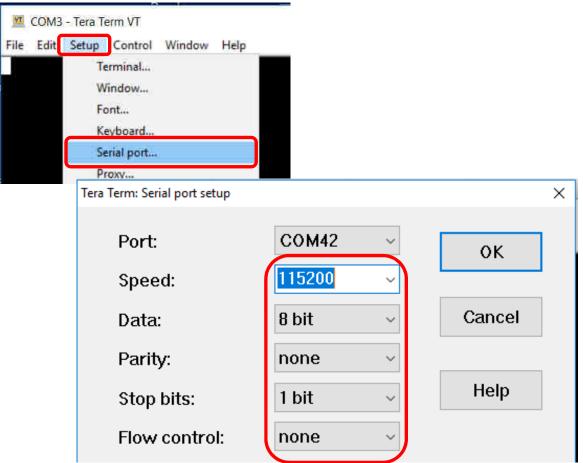
- Open "New Connection"
 - Click "Serial" button
 - Change Port to "STLink Vitual COM Port"
 - Click "OK"





Hands On: Dual Bank

- Verify "Serial port.."
 - Baud = 115200
 - Data = 8 bit
 - Parity = none
 - Stop = 1 bit
 - Flow control = none



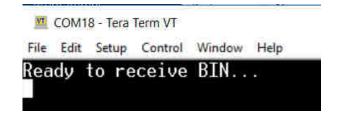


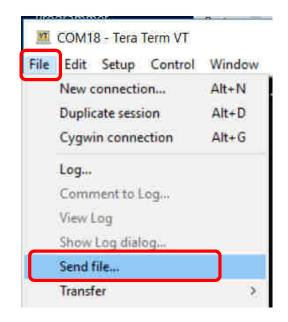
Press "JOYSTICK_SEL" on Discovery

- Send binary file in TeraTerm
 - File > Send file...



Hands On: Dual Bank



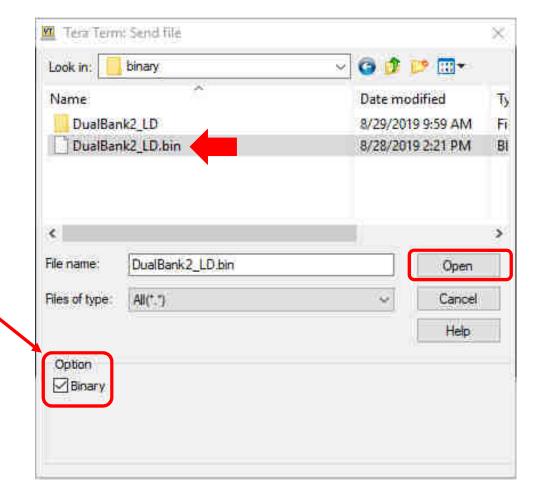


Hands On: Dual Bank

- Select "DualBank2_LD.bin" file
 - DualBank\binary folder

Check "Binary" Option

Click "Open"





Hands On: Dual Bank

TeraTerm will display programming status

```
File Edit Setup Control Window Help

Ready to receive BIN...
BIN file received!
Executing in Bank 1 - Erasing Bank 2 Pages.
Programming Bank 2.
Programming Complete.
Press User Button to launch program in Bank 2.
```

- Press "User Button" to launch program in Bank 2
 - · LEDs blink pattern has changed.





Dual Bank: Additional Notes 203

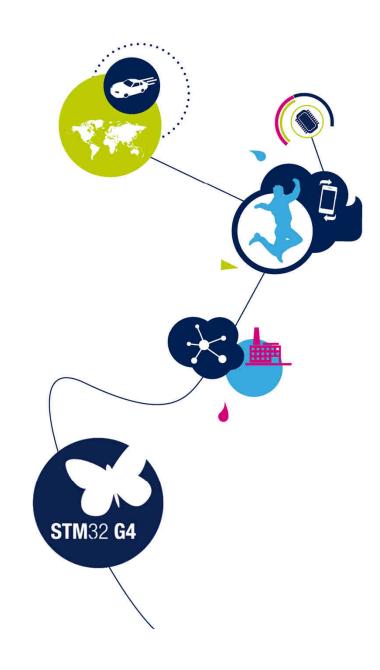
- Push board "RESET" button to switch execution back to Bank 1
 - To select boot from Bank 2, set the BFB2 bit in the user option bytes
- Reference Manual RM0440: STM32G4 Series advanced ARMbased 32-bit MCUs
 - Section 3: Embedded Flash memory for category 3 devices
- AN2606: STM32 microcontroller system memory boot mode



STM32G4 mixed-signal MCU workshop

Wrap Up





STM32G4 Workshop Related Survey

Use your phone to scan the QR code or type the link into your browser.



https://www.surveymonkey.com/r/PC5DHBM



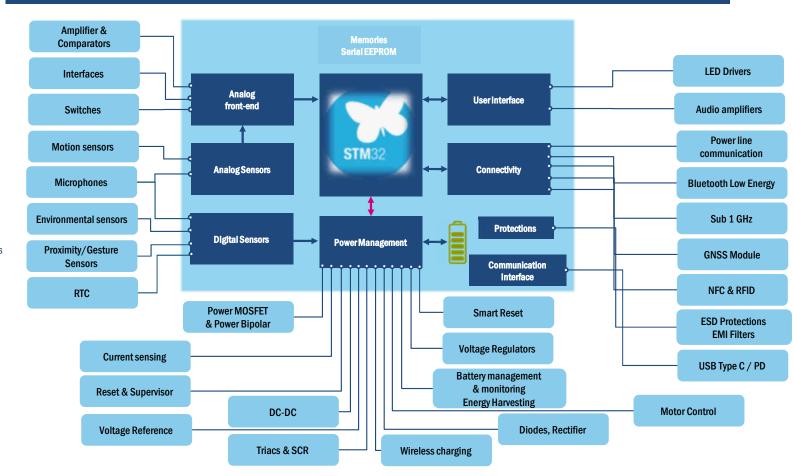
We Greatly Value Your Feedback - Thank you!

STMicroelectronics: one of the broadest Standard Product Portfolios

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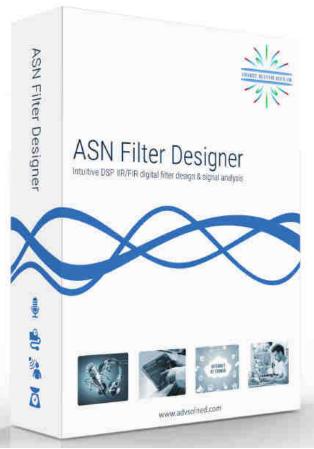


- Protection devices
- Power bipolar transistors
- Power MOSFETs
- Amplifiers and Comparators
- Linear voltage regulators
- EEPROM
- Rectifiers
- SCRs and TRIACs
- Interface ICs
- Voltage references
- Reset and supervisor ICs









ASN Filter Designer 207

Powerful DSP experimentation platform

Design and fine-tune your digital filter within minutes, and then test it in real-time with a variety of test signals (including your own datasets) via the tool's built-in signal analyser.

Real-time design feedback

No need to explicitly define technical specifications, just sketch your requirements and let the tool automatically fill in the exact specifications for you!

Live math scripting

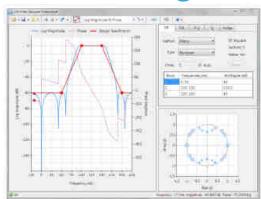
Interactively experiment with specialised transfer functions, pole-zero pairs and other mathematical functions with ASN FilterScript.

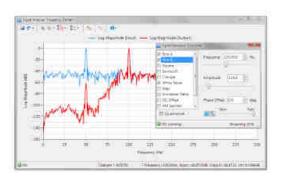
Automatic documentation

Get a detailed specification report of all designed filter blocks for official project documentation, which can be pasted directly into Microsoft Word/Powerpoint.

Deploy to Arm CMSIS-DSP, C/C++, Python, Matlab and more

Easily integrate your designed filter blocks with your other algorithms in Arm CMSIS-DSP, C/C++, Python, Matlab, Octave, Scilab or Labview using provided royalty free software development frameworks.





Download a free demo http://www.advsolned.com/asn_filter_designer/





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Workshop based on STM32F334 and STM32G474 Nucleo and its dedicated Eigitel Fower expansion board

STMicroslectronics brings industry leading ST MiCUs together with Diricha's tools and training







Appendix – Reference Documents 209

Datasheet and Reference Manual Links

Datasheets

STM32G431xx STM32G431x6 STM32G431x8 STM32G431xB

STM32G441xB STM32G441xB

STM32G473xx STM32G473xB STM32G473xC STM32G473xE

STM32G474xB STM32G474xC STM32G474xE STM32G474xx

STM32G483xE STM32G483xE

STM32G484xE STM32G484xE

Reference Manual

STM32G4 Series Reference Manual RM0440





Appendix – Reference Documents 210

Application Note Links

AN2834	How to get the best ADC accuracy
<u>AN4013</u>	STM32 Cross series timer overview
<u>AN4232</u>	Getting started with analog comparators
AN4296	Using CCM SRAM with IAR, Keil, and GNU based tool chains
<u>AN4539</u>	HRTIM Cookbook
<u>AN4899</u>	STM32 GPIO configuration for hardware settings and low power consumption
<u>AN4989</u>	STM32 debug toolbox
<u>AN5305</u>	Digital filter implementation with the FMAC
<u>AN5306</u>	Operational Amplifier usage in STM32G4
<u>AN5310</u>	Guideline for using analog features of the G4 vs. the F3
<u>AN5315</u>	STM32Cube firmware examples for STM32G4
<u>AN5325</u>	Getting started with the CORDIC accelerator
<u>AN5345</u>	High-brightness RGB LED control using the B-G474E-DPOW1 Discovery kit
<u>AN5346</u>	STM32G4 use tips and recommendations





Appendix – Reference Documents 211

User Manual Links

<u>UM1721</u>	Developing applications on STM32Cube with FatFS
<u>UM1722</u>	Developing applications on STM32Cube with RTOS
<u>UM2454</u>	STM32G4 Seris Safety Manual
<u>UM2492</u>	Getting started with STM32CubeG4 for STM32G4 Series
<u>UM2552</u>	USB Power Delivery
<u>UM2570</u>	Description of STM32G4 HAL and low-layer drivers
<u>UM2573</u>	STM32CubeG4 Nucleo demonstraion firmware
<u>UM2577</u>	Discovery kit with STM32G474RE MCU





STM32G4 Series – Take Away

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170MHz Cortex-M4 coupled with 3x accelerators



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32..512KB Flash memory 32..128-pin packages



Releasing Your Creativity 213





