

MEITRACK® MD600 User Guide




Documentation

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Documentation Update Records

| Version | Date | Modified |
|---------|------------|--|
| 1.0 | 2023-09-15 | Initial draft. |
| 1.1 | 2023-10-31 | Modify the optional model. |
| 1.2 | 2023-11-24 | Modified I/O port sequence. |
| 1.3 | 2024-08-08 | Modified usage precautions. Change the color of the I/O line. |
| 1.4 | 2024-11-20 | Added AI camera and UPS accessories. Modify the ACC color line. |
| 1.5 | 2025-05-06 | Add the number of cache storage. A 10-inch VGA display screen has been added. New AI alarm function has been added. Add the server configuration steps. Installation guidance for new equipment. New Settings for the MD600 function have been added. New upgrade steps added. New video-related setting methods have been added. Add the MS06 platform. |

Cautions

Installation Environment

1. To extend equipment life, please install the equipment in locations with little vibration.
2. To ensure normal heat dissipation, do not install the device in a poorly-ventilated area (such as a trunk), and also keep it about 15 cm away from other objects on the same level.
3. The device shall be horizontally installed and protected against water, humidity and lightning; in addition, keep the vehicle still during installation to prevent damage to the device due to falling off.
4. To ensure safe operation, keep the device, camera, cables and other accessories out of reach of passengers and driver.

Avoid electric shock and fire

1. The machine uses 11.4V-36V DC power supply, notice the polarity when wiring to avoid short circuits.
2. Before installation, disconnect the power supply of the device and wrap each unused I/O cable with adhesive tape to prevent other cables from touching the output power cable, which may cause the device to burn.
3. Please power off the device when connecting accessories with device.
4. Do not touch the power and the device with wet hands.
5. Do not spray liquid on the device to prevent internal short circuit or fire.
6. Do not put any other equipment on top of camera.
7. Do not disassemble the housing without authorization to avoid damage or electric shock.

Transport and handling

1. Please use the original package in transport to avoid damage in transport.
2. Please keep power off in moving the device or replacing components.

Contents

| | |
|---|--------|
| 1 Product Introduction | - 6 - |
| 2 Specifications | - 6 - |
| 3 Main Device and Accessories | - 8 - |
| 3.1 Main Device | - 8 - |
| 3.2 Optional Accessories | - 9 - |
| 3.2.1 MDVR Camera options | - 9 - |
| 3.2.2 Additional options | - 11 - |
| 4 Host interface | - 12 - |
| 4.1 Appearance and interface | - 12 - |
| 4.2 I/O Interface Definitions | - 14 - |
| 4.3 Power interface Definition | - 15 - |
| 4.4 RS232 interface definition | - 16 - |
| 4.5 AV-OUT Definition | - 16 - |
| 4.6 VGA interface definition | - 17 - |
| 4.7 AV-IN1 to 6 Interface Definition | - 17 - |
| 4.8 Backup interface Definition | - 18 - |
| 4.9 MIC&SPEAKER interface definition | - 18 - |
| 5 LED indicator | - 19 - |
| 6 AI alarm function | - 20 - |
| 6.1 ADAS Function | - 21 - |
| 6.1.1 Lane Left Deviation Alarm | - 21 - |
| 6.1.2 Lane Right Deviation Alarm | - 22 - |
| 6.1.3 Front impact warning | - 22 - |
| 6.1.4 Pedestrian Impact Warning | - 22 - |
| 6.1.5 Distance Detection | - 23 - |
| 6.2 DMS Function | - 23 - |
| 6.2.1 Smoking | - 23 - |
| 6.2.2 Calling | - 23 - |
| 6.2.3 Distraction Warning | - 24 - |
| 6.2.4 Fatigue Driving Alarm (Eyes Closed) | - 24 - |
| 6.2.5 Yawning | - 24 - |
| 6.2.6 Driver Absence Detected | - 25 - |
| 6.2.7 Seat Belt Detection | - 25 - |
| 6.2.8 IR block | - 25 - |
| 6.2.9 Covered | - 26 - |
| 7 AI Server Configuration Steps | - 26 - |
| 7.1 Single Server | - 26 - |
| 7.2 Dual Server | - 27 - |
| 7.3 JTT 808\JTT 1708 Server | - 27 - |
| 8 APP (MT Manager+) | - 27 - |

| | |
|--|--------|
| 8.1 APP connection to MD600 | - 28 - |
| 8.2 Configure parameters using the MT Manager + APP | - 29 - |
| 9 AI alarm settings | - 30 - |
| 9.1 Indoor testing: enable simulated speed | - 30 - |
| 9.2 Calibration of ADAS, DMS, BSD, and facial recognition via the APP. | - 30 - |
| 9.2.1 Installation and calibration of the DMS camera | - 30 - |
| 9.2.2 Installation and Calibration of the ADAS Camera | - 31 - |
| 9.2.3 BSD Camera Installation and Calibration | - 32 - |
| 9.2.4 AI Function Video Channel Configuration | - 33 - |
| 10 Installation Guide | - 33 - |
| 10.1 Installation of SD Card and SIM Card | - 33 - |
| 10.2 Hard Drive Installation | - 34 - |
| 10.3 Install External Devices | - 34 - |
| 10.4 Powering the device | - 35 - |
| 11 MD600 Function Settings, | - 37 - |
| 11.1 Set Overspeed, Harsh acceleration\Harsh Braking, and Impact Alarm | - 37 - |
| 11.2 Upload Alarm Images and Videos | - 39 - |
| 11.2.1 Configure to trigger alarm photo capture and snapshots; | - 39 - |
| 11.2.2 Configure FTP Server | - 40 - |
| 11.3 Set the resolution for stored stream video and real-time stream video | - 40 - |
| 11.3.1 Set the resolution for stored stream video. | - 40 - |
| 11.3.2 Set the resolution for real-time stream video | - 41 - |
| 11.4 MD600 Upgrade | - 42 - |
| 12 MS06 Platform | - 44 - |
| 12.1 Bind Device | - 44 - |
| 12.2 How to view live video | - 45 - |
| 12.3 How to view playback video | - 46 - |

1 Product Introduction

MD600 is the second generation of a new solution AI MDVR with high-performance AI processing chips, with a dual-system (dual communication channel), highly stable 6-channel AHD, and 1080P high-definition vehicle-mounted hard disk video recorder. It possesses high computing power and can support AI applications such as ADAS and DMS. The product is based on a dual system of Linux operating system and MCU OS, incorporating advanced technologies including high-performance H.264/H.265 video compression/decompression, 4G, GPS, WiFi, Bluetooth, power-off data protection, wide voltage, high voltage protection, and other technologies. It serves as the core product of the next-generation wireless vehicle-mounted video surveillance solution.

It is widely used in buses, long-distance coaches, taxis, logistics vehicles, special-purpose vehicles (e.g., armored cash transport vehicles), private cars, and forklifts, and other mobile video surveillance fields.

Product features:

Support 6-channel AHD720P/1080P cameras.

Embedded high-performance AI video processing chip (optional AI video algorithm: ADAS, DMS).

M.2 SSD, which is more suitable for low-temperature environments than conventional hard disks, supports up to 2TB hard disk, and comes with an SD card slot (up to 512G).

Adopt industrial grade power supply chip, support 11.4~36V wide range power input, adapt to the harsh environment.

It supports dual working modes of local recording and network transmission.

The built-in 6-axis sensor can be used for sharp turning, rapid acceleration, rapid deceleration, and other alarms.

The self-developed data writing mechanism is adopted to effectively protect the video data and prevent data loss caused by abnormal power failure of the system.

2 Specifications

| Power supply | |
|--------------------------|--|
| Rated voltage | DC: 11.4-36V. Rated at 12V/3A |
| Power consumption | The audio and video on the host is about 6W connected to 6 cameras, about 24W in the day (29W connected to the display), about 32W in the night (37W connected to the display), Connect to a single camera (normal range is 50mA~100mA during the day, 200mA~250mA at night) |
| AI | |
| AI video | ADAS、DMS、BSD、face recognition |
| Storage media | |
| SD card & SSD hard drive | 1*M2 SSD and 2*SD, Capacity: 2 TB + 2* 512 GB, supports PCIe x2 and PCIe x4 NVME protocol M.2 NGFF SSD (2280 specifications) |
| System structure | |
| System operation | Dual system operation, dual communication channels (to prevent data loss) |
| Audio and video | |

| | |
|----------------------------|--|
| Video input | 6-channels AHD camera, can support D1/720P/1080P arbitrary mixing Adaptive camera resolution and format (PAL and NTSC) Maximum support 6x1080P@15fps real-time video recording |
| Video output | 1 channel VGA video output (8Pin aviation head interface), default resolution 1024*7681 1 CVBS aviation plug (level: 1.0Vp-p, impedance: 75Ω) Resolution: PAL 704*576, NTSC 704*480 |
| Compression standard | H.264/H.265 configurable |
| Image display | Support 1, 6 screen display |
| Audio input | 6 channels for the camera Mic input, the camera should support audio 1 way of intercom handle input 1 channel 3.5MM headphone interface input (GSM call interface) |
| Audio output | 1 independent audio isolation output (and connected to AV-OUT interface, VGA aviation head interface and intercom handle interface)1 channel 3.5MM headphone interface output (GSM call interface) |
| Audio compression | G.726/G.711a/AAC |
| Video Request and Playback | It can retrieve and playback by channel, video type, bitstream type and time |
| Video Recording method | Ordinary video and alarm video, sound and video recording synchronization |

| Frequency band | |
|------------------|---|
| MD600-AU | GSM: B2/B3/B5/B8 WCDMA: B1/B2/B4/B5/B8 LTE-FDD: B1/B2/B3/B4/B5/B7/B8/B28/B66 LTE-TDD: B40 |
| MD600-A | WCDMA: B2/B4/B5 LTE-FDD: B2/4/5/12/13/14/66/71 |
| MD600-J | WCDMA: B1/B6/B8/B19 LTE-FDD: B1/B3/B8/B18/B19/B26 LTE-TDD: B41 |
| MD600-G | GSM: B2/B3/B5/B8 WCDMA: B1/B2/B4/B5/B8/B6/B19 LTE-FDD: B1/B2/B3/B4/B5/B7/B8/B12/B13/B18/B19/B20/B25/B26/B28 LTE-TDD: B38/B39/B40/B41 |
| MD600-E | GSM: B3/B8 WCDMA: B1/B5/B8 LTE-FDD: B1/B3/B5/B7/B8/B20/B28 LTE-TDD: B38/B40/B41 |
| WiFi\BLE\GNSS | |
| WiFi | IEEE 802.11b /g/n, frequency 2.4G&5.8G, supports STA and AP dual mode |
| Bluetooth | It supports master-slave dual mode, can read Bluetooth accessories, and can configure parameters through APP |
| Positioning mode | GPS/GPS_BEIDOU/GPS_GLONASS |

| | |
|----------------------|---|
| Positioning accuracy | 2.5m |
| Tracking sensitivity | -162dBm |
| GNSS antenna | Support antenna insert/pull out/short circuit detection |

| Others | |
|-----------------------|--|
| SPI memory | Built-in 64Mbit; |
| GPRS Cache | Store 100W pieces of GPRS data. |
| Operating temperature | Without battery: -20 to 70 degrees |
| Sensor | 6-axis acceleration sensor |
| I/O port | Main cable port: 8*Din(Max 8*Din) + 2*Dout(Max 8*Dout) + 2*AD(Max 6*AD) + 1*Speed_IN + 1*1-wire + 2*RS485 + 1*CAN + 1*DC_5V + 1*DC_12V Other interfaces: 2-way RS232, 1-way ACC |
| Dimensions | Dimensions: 120*154*43mm |
| Weight | 740g (excluding accessories) |

| Certification |
|------------------|
| CE certification |

| Protocol |
|---|
| Meitrack Protocol (CCE) RTMP (Audio Video Transport Protocol, also compatible with Meitrack's Audio Video Private Transport Protocol) |

3 Main Device and Accessories

3.1 Main Device



MD600



Power cord/ACC cord



CD download card



IO cables



Lock key



USB configuration cable



WIFI antenna



4G antenna



GPS antenna



Bluetooth antenna



M.2 Screw

| Standard | Quantity | Remarks |
|-------------------------|----------|--|
| Host | 1 | MD600 |
| Power cord/ACC cord | 1 | 3PIN with 20cm of wire |
| IO cables | 1 | 24PIN with 20cm thread length |
| CD download card | 1 | Neutral packaging does not come standard |
| USB configuration cable | 1 | Standard Type C connector cable For connecting PC configuration with upgrades |
| Key lock | 2 | For locking SD and SIM cards |
| 4G antenna | 1 | 4G signal gain |
| GPS antenna | 1 | GPS signal gain |
| WIFI antenna | 1 | WiFi signal gain |
| Bluetooth antenna | 1 | Bluetooth signal gain |
| M.2 Screw | 1 | Used to fix the M.2 SSD hard disk |
| Total | 12 | |

3.2 Optional Accessories

3.2.1 MDVR Camera options

AI Camera

DMS Telescopic Camera (ACP506)



DMS Side-mounted Camera (ACP505)



DMS Camera (ACP503)



ADAS Camera(ACP603)



ADAS Wide Dynamic Range Camera (ACP604)



BSD Side-mounted Camera (ACP301)



Install the left and right blind areas of the vehicle.

BSD Overhead Camera (ACP504)



Install blind spots in front and rear of the vehicle

Waterproof Standard Camera (Outdoor)

Side-mounted Waterproof Camera 720/1080P (ACA301)



Waterproof Mini Camera 1080P (ACA105)



Waterproof Square Camera 720/1080P (ACA501)



Waterproof Square Camera 1080P (ACA503)



Non-waterproof Standard Camera (Indoor)

Metal Shell Miniature Snail Camera 720/1080P (ACA303)



Camera extension cable (default: 3M or 5M)



Note: Standard camera cable length is generally 50cm, please adapt the corresponding camera extension cable.

3.2.2 Additional options

Optional Bluetooth external accessory

| Bluetooth temperature and humidity sensor (AST101) | Bluetooth beaco (AB401) | Bluetooth beaco (AB402) |
|--|---|--|
|  |  |  |

Other optional external accessories

| A53 Fuel sensor (voltage AD) | A52 digital temperature sensor | Relay | iButton |
|---|---|--|---|
|  |  |  |  |
| Ultrasonic Fuel Sensor ASUF103 (range 100cm) | Ultrasonic Fuel Sensor ASUF104 (range 250cm) | Ultrasonic Fuel Sensor ASUF105(range 400cm; AD analog) | Ultrasonic Fuel Sensor A76 (range 100cm, Without AD analogue) |
|  |  |  |  |
| Microphone (A58) + speaker (A57) + connector cable | RFID reader | High temperature batteries(400mA) | Sound and Light Alarm (AAL101) |
|  |  |  |  |

| | | | |
|---|---|--|---|
| Intercom (A95) | 7\10.1 inch VGA display | 7 inch CVBS display | UPS Power Supply(APU101) |
|  |  |  |  |
| Memory card | M.2 Hard drive | | |
|  |  | | |

4 Host interface

4.1 Appearance and interface



| No. | Interface | Signage | Description |
|-----|-----------------------------|---------|--|
| 1 | 1.4G indicator light | 4G | Green, network status indicator |
| | 2.REC indicator | REC | Green, video status indicator |
| | 3.PWR indicator | PWR | Red, power supply status indication |
| | 4.GPS indicator | GPS | Blue, GPS status indicator |
| | 5.ALM indicator | ALM | Orange, video loss status indication |
| | 6.WIFI/ Bluetooth indicator | WIFI | Green, WIFI& Bluetooth status indicator |
| 2 | Microphone/speaker port | Audio | For external microphone \ speaker +GSM two-way calls |
| 3 | Infrared interface | IR | Infrared receiver (reserved function) |
| 4 | Debug interface | debug | Connect the PC side for parameter configuration |
| 5 | SIM card | SIM | SIM card port |
| 6 | Lid detection | NA | Start work only when the lid is detected to have |




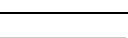
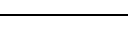






| | | | |
|---|-----------------------------|--------------------|--|
| | switch | | been installed |
| 7 | SD slot | SD | 2*SD card loading port |
| 8 | Electronic locks | Pick/lock the sign | Lock the SD\SIM card, which is also the on/off machine for the device |
| 9 | Ethernet with USB interface | ETH&USB | Used to connect Ethernet for data transfer or parameter configuration. USB is used to upgrade the device and supports USB3.0 |
















| No. | Interface | Signage | Description | |
|-----|-----------------------------|----------------------|--|---------------------------|
| 1 | Power port | PWR&ACC | Red wire power 11.4~40V, rated 12V/3A; The black wire is GND.Yellow wire is connected to ACC high level detection, 3V effective, up to 40V | |
| 2 | Serial Port 1 | RS232_1 | RS232_1: Used for external RFID, ultrasonic oil sensor and other peripherals | |
| 3 | Serial port 2 | RS232_2 | RS232_2: For extended connection peripherals such as G_MOSE | |
| 4 | 24PIN main cable | IO&AD&RS485&CAN | 8*Din(Max8*Din)+2*Dout(Max8*Dout)+2*AD(Max6*AD)+1*Speed_IN+1*1-wire +2*RS232+2*RS485+1*CAN+1*DC_5V+1*DC_12V | |
| 5 | 4G antenna port | 4G | 4G antenna access point | |
| 6 | Bluetooth antenna interface | BLE | Bluetooth antenna port | |
| 7 | WIFI antenna interface | WIFI | WIFI antenna access point | |
| 8 | GPS antenna interface | GNSS | GPS antenna access point | |
| 9 | Video output | AV-OUT | Vehicle video CVBS output: Resolution -PAL 704*576,NTSC 704*480 | |
| 10 | Video output | VGA | Vehicle video VGA output: Default output resolution 1280*720. | |
| 11 | 1.AV-IN1 | AV- IN1~6&USB Backup | Label DMS AV-IN1 on the wire | DMS 4-core aviation head |
| | 2.AV-IN2 | &SPK&MIC | Identify ADAS AV-IN2 on | ADAS 4-core aviation head |

| | | | |
|--------------------|---------------|---|----------------------|
| 3.AV-IN3 | the wire | Label AV-IN3 on the wire | 4 core aviation head |
| 4.AV-IN4 | | Label AV-IN4 on the wire | 4 core aviation head |
| 5.AV-IN5 | | Label AV-IN5 on the wire | 4 core aviation head |
| 6.AV-IN6 | | Label AV-IN6 on the wire | 4 core aviation head |
| 7.MIC & SPEAKER | MIC & SPEAKER | Intercom handle for external and monitoring platform voice intercom input/output device (A95 intercom handle) Default: 4-core aviation head | |
| 8. Backup | Backup | Disaster recovery interface or USB interface default: 5 core aviation head | |

4.2 I/O Interface Definitions

| No | Label | Color | Pin color | Function Description |
|----|------------------|--------------|---|---|
| 1 | RS485_1A+ | Purple/White |  | 485+ signal (MCU) |
| 2 | RS485_1B- | Purple |  | 485-Signal (MCU) |
| 3 | AD1 | Blue |  | 12-bit analogue input 1 with valid input voltage values of 0-30V For connection of external sensors, e.g. fuel sensor |
| 4 | SPEED_IN | White/Black |  | Connect speed signal wire |
| 5 | IN8/OUT8 | White/Purple |  | Digital input 8, default positive trigger, can be configured to negative trigger, or OUTPUT8 |
| 6 | IN7/OUT7 | White/Blue |  | Digital input 7, default positive trigger, can be configured to negative trigger, or OUTPUT7 |
| 7 | IN6/OUT6/A D6 | White/Green |  | Digital input 6, default positive trigger (Connect the right turn signals), configurable as negative trigger, or AD5 (0 to 30V) analogue input or OUTPUT6; Connect vehicle right turn signal |
| 8 | IN5/OUT5/A D5 | White/yellow |  | Digital input 5, default positive trigger (Connect the left turn signals), configurable as negative trigger, or AD5 (0 to 30V) analogue input or OUTPUT5 |
| 9 | IN4/OUT4/A D4 | White/Orange |  | Digital input 4, default positive trigger, configurable as negative trigger, or AD4 (0 to 30V) analogue input or OUTPUT4 |
| 10 | IN3/OUT3/A D3 | White/Red |  | Digital input 3, default positive trigger, configurable as negative trigger, or AD3 (0 to 30V) analogue input or OUTPUT3 |
| 11 | OUT2 | Yellow/Brown |  | Output control 2. default low level trigger (0V), open drain output (OC) when invalidOutput open-drain (invalid) voltage tolerance: 40 volts maximum, 400 mA maximum current, can be set to high level trigger and PWM trigger mode, can be connected to an external relay for remote disconnection of vehicle fuel/engine power etc. |

| | | | | |
|----|-----------|---------------|---|--|
| | | | | Output control 1. default low level trigger (0V), open drain output (OC) |
| 12 | OUT1 | Yellow/brown |  | when invalid Output open-drain (invalid) voltage tolerance: 40 volts maximum, 400mA maximum current, can be set to high level trigger and PWM trigger mode, can be connected to an external relay for remote disconnection of vehicle fuel/engine power etc. |
| 13 | DC_5V | Pink/yellow |  | 5V DC output; MAX current 750MA, software controllable shutdown |
| 14 | GND | Black |  | Ground line |
| 15 | SOS/IN1 | Grey |  | Emergency alarm input line Digital input 1, configurable for positive and negative triggering (default is SOS button, negative trigger) |
| 16 | RS485_2B- | Purple/Green |  | 485-signal (RS485 interface) |
| 17 | RS485_2A+ | Purple/Yellow |  | 485+signal (RS485 interface) |
| 18 | GND | Black |  | Ground line |
| 19 | CAN_L | Orange |  | For connection of CANBUS peripherals |
| 20 | CAN_H | Orange/White |  | For connection of CANBUS peripherals |
| 21 | GND | Black |  | Ground line |
| 22 | AD2 | Blue/Brown |  | 12 bit analog input 1, effective input voltage value 0-30V for connecting external sensors, such as oil level sensors, etc |
| 23 | 1-WIRE | green |  | For connecting temperature sensors, iButtons and other 1-Wire accessories |
| 24 | DC_12V | Pink/orange |  | MAX current @1.35A, software controlled off |

4.3 Power interface Definition

| | |
|----------------|-------------|
| 1 Power (+) | 2 GND(-) |
| 3 ACC | |

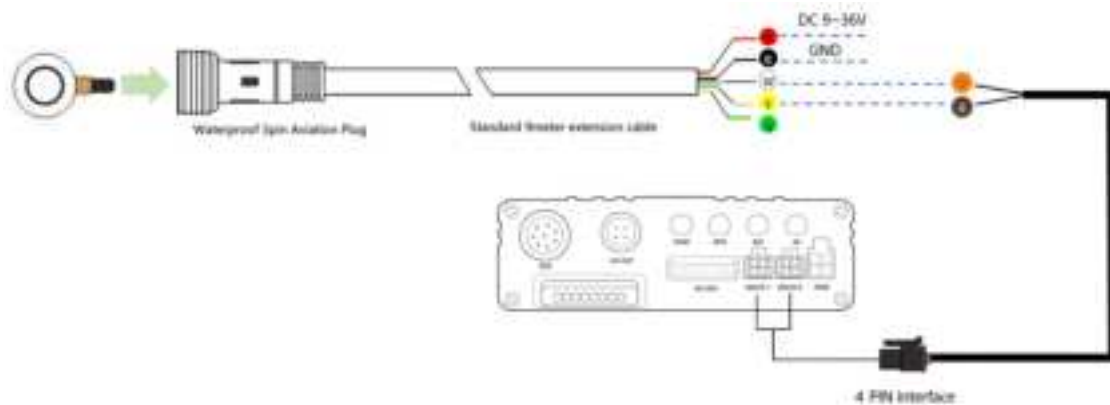
| No. | Color | Function Description |
|-----|-------|-----------------------------|
| 1 | Red | Power supply positive input |
| 2 | black | GND |
| 3 | White | ACC signal input |

4.4 RS232 interface definition

| | |
|--------|----|
| 1 | 3 |
| 5V(+) | RX |
| 2 | 4 |
| GND(-) | TX |

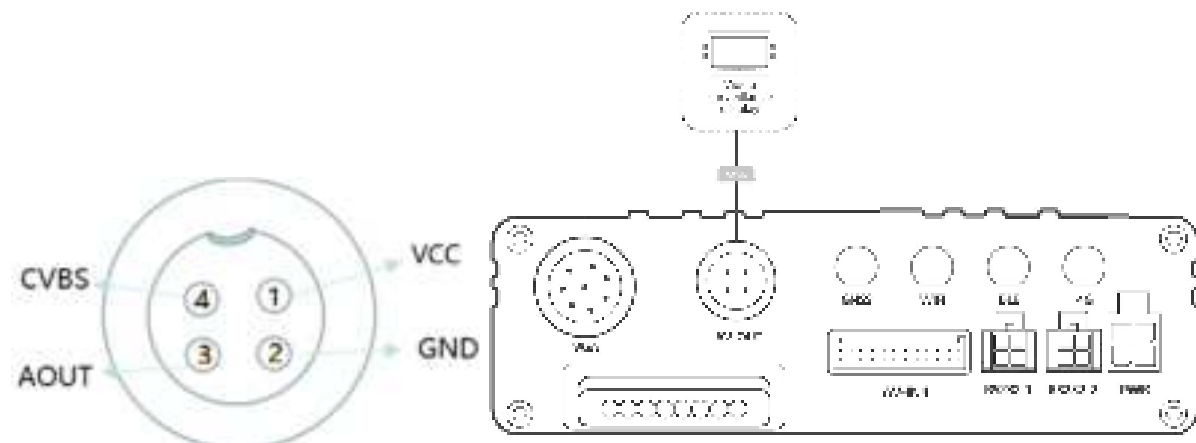


| Pin Number | Description |
|------------|------------------------|
| 1 | Power supply output 5V |
| 2 | Ground wire |
| 3 | RX |
| 4 | TX |



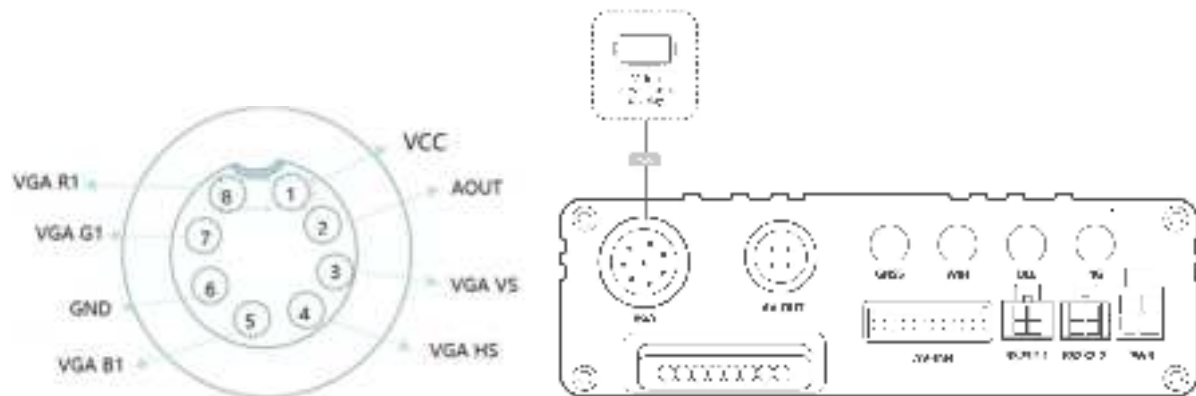
Note: RS232 is used to connect ultrasonic oil sensors, RFID and other peripherals.

4.5 AV-OUT Definition



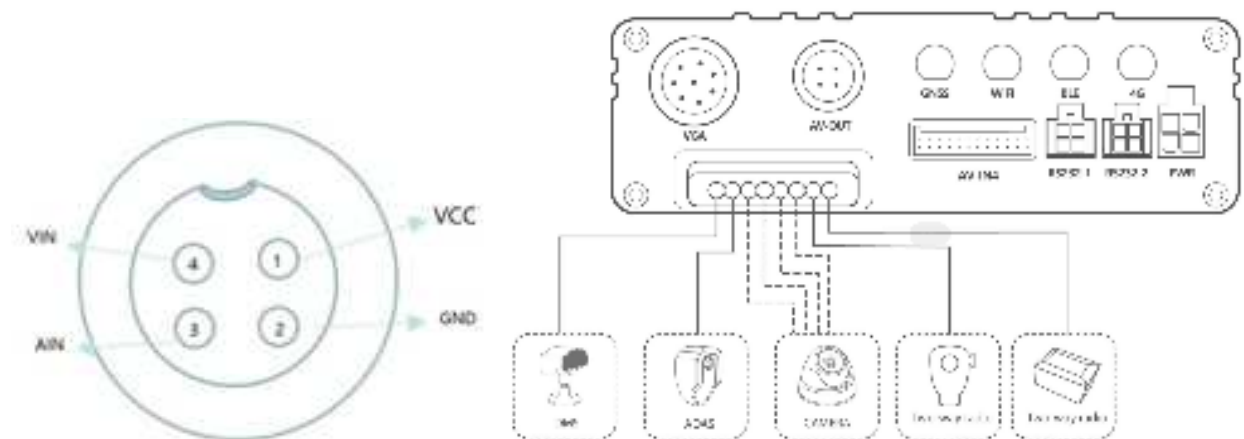
| No. | Description |
|-----|-------------|
| 1 | VCC (+12V) |
| 2 | GND |
| 3 | AOUT |
| 4 | CVBS |

4.6 VGA interface definition



| No. | Description |
|-----|-------------|
| 1 | VCC (+12V) |
| 2 | AOUT |
| 3 | VGA VS |
| 4 | VGA HS |
| 5 | VGA B1 |
| 6 | GND |
| 7 | VGA G1 |
| 8 | VGA R1 |

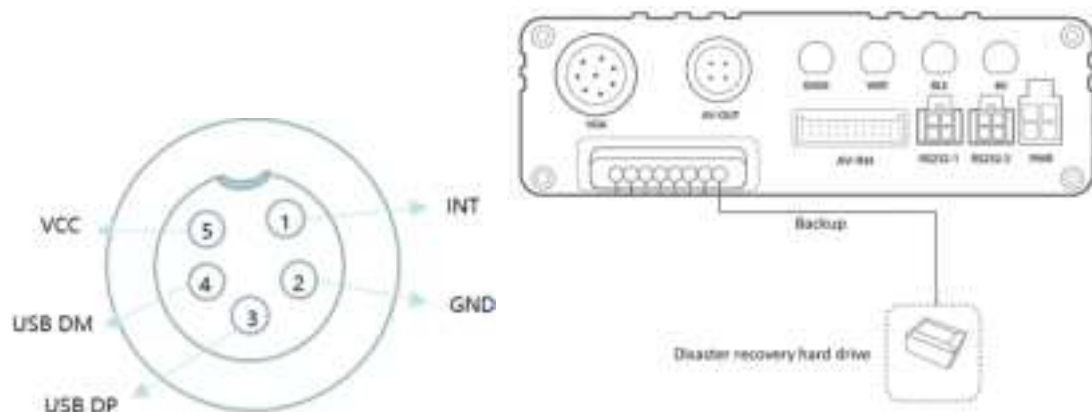
4.7 AV-IN1 to 6 Interface Definition



| No. | Description |
|-----|-----------------|
| 1 | VCC +12V |
| 2 | GND |
| 3 | AIN |
| 4 | VCC |

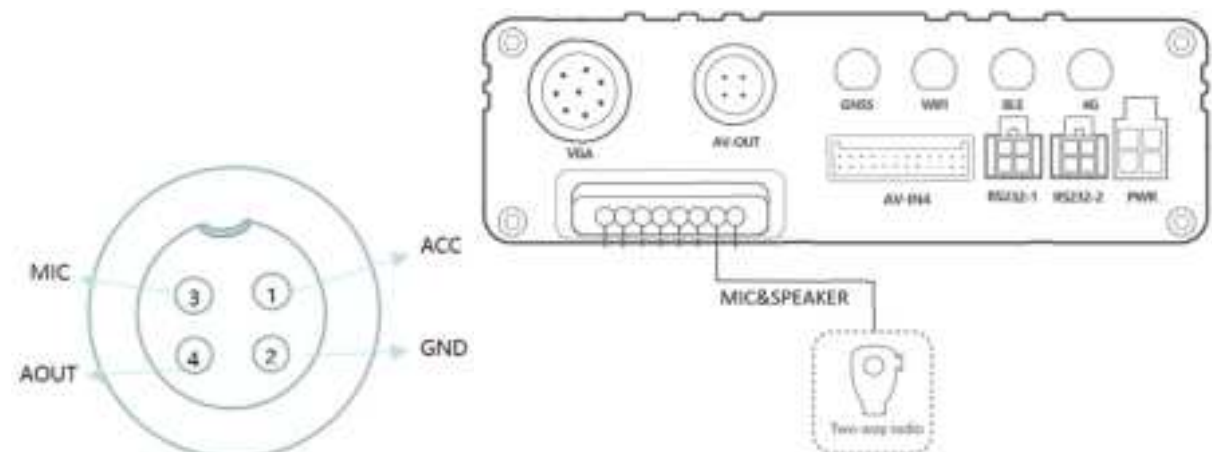
Note: The interface between ADAS and DMS can be set through the MM.

4.8 Backup interface Definition



| No. | Description |
|-----|-------------|
| 1 | INT |
| 2 | GND |
| 3 | USB DP |
| 4 | USB DM |
| 5 | VCC +5V |

4.9 MIC&SPEAKER interface definition



| No. | Description |
|-----|-------------|
| 1 | ACC |
| 2 | GND |
| 3 | AOUT |
| 4 | MIC |

5 LED indicator



| Identifier | Meaning | Color | Status | Description |
|------------|---------------------------------|--------|-----------------------------------|--|
| PWR | Power LED indicator | Red | Steady on | The ACC is on and the device is locked. |
| | | | Steady off | The ACC is off and the device is unlocked. |
| REC | SD card /M.2 Video instructions | green | Flash (frequency of writing data) | The storage disk is detected and there is written audio and video data |
| | | | once every 5 seconds | The storage disk has been detected, but no data has been written |
| | | | Steady off | No SD card is detected. |
| 4G | 4G LED indicator | Green | once every 5 Seconds | There is a 4G module, but no data is sent. |
| | | | Blink fast | 4G data is sent and received normally. |
| | | | Steady off | There is no 4G module. |
| ALM | Video loss status | orange | Steady on | All AV inputs are not connected to cameras. |
| | | | once every 5 seconds | One AV input is not connected to a camera. |
| | | | twice every 5 seconds | Two AV inputs are not connected to cameras. |
| | | | 3 times every 5 Seconds | Three AV inputs are not connected to cameras. |
| | | | 4 times every 5 Seconds | Four AV inputs are not connected to cameras. |
| | | | 5 times every 5 seconds | Five AV inputs are not connected to cameras. |
| | | | 6 times every 5 seconds | Six AV inputs are not connected to cameras. |
| | | | 7 times every 5 seconds | Seven AV inputs are not connected to |

| | | | | |
|---------|-----------------------|-------|---|---|
| | | | | cameras. |
| | | | Steady off | All AV inputs are connected to cameras. |
| WIFI/BT | WIFI/BT LED indicator | Green | once every 5 Seconds | There is a WiFi module, but no data is sent. |
| | | | Blink fast (once every 0.1 seconds) | WiFi data is sent and received normally. |
| | | | Steady off | There is no WiFi module. |
| | | | | |
| GPS | GPS LED indicator | Blue | Steady on | A button or an input is triggered. |
| | | | Blink fast (once every 0.1 seconds) | The MDVR is being initialized, or the battery power is low. |
| | | | Blink fast (0.1 seconds on and 2.9 seconds off) | A GPS signal is received. |
| | | | Blink slowly (1 second on and 2 seconds off) | No GPS signal is received. |

6 AI alarm function

The specific list of violation operations and the description of the corresponding Chinese and English voice alerts are as follows:

| Camera | Alarm type | Prompt voice in English |
|--------|--|---------------------------------|
| DMS | Phone calls | No phone call |
| | Smoking | No smoking |
| | fatigue | Attention, drowsiness detected |
| | Yawning | Please stay awake |
| | Turn your head left and right, up and down | Please face forward |
| | Face lost | Please return to the seat |
| | Block the lens | Do not block the DMS lens |
| | Wear sunglasses | Do not block the DMS IR |
| | Please wear your seat belt | Please fasten your seat belt |
| ADAS | left Lane departure | Watch out lane departure |
| | Right lane departure | Watch out lane departure |
| | Watch out for cars ahead | Watch out for the front vehicle |
| | keep a safe distance | Keep a safe distance |
| | Watch out for pedestrians | Watch out for pedestrians |

Note: If you need to use the AI camera to detect the alarm voice function, you must have the interphone handle or display screen as the AI alarm voice output.

Trigger conditions and sensitivity

| Alarm Type | Trigger speed (Default) | Sensitivity | | |
|----------------------|-------------------------|------------------|-------------------|-------------------|
| | | High | Medium | Low |
| Left lane departure | > 50 | Sensitivity: 0.3 | Sensitivity: -0.3 | Sensitivity: -0.7 |
| Right lane departure | > 50 | Sensitivity: 0.3 | Sensitivity: -0.3 | Sensitivity: -0.7 |

| | | | | |
|---------------------------|------|---------------------------------|--------------------------------|--------------------------------|
| Forward Impact Warning | > 30 | TTC = 4.6s | TTC = 3.6s | TTC = 2.7s |
| Pedestrian impact warning | > 30 | TTD = 3.0s | TTD = 2.5s | TTD = 2.0s |
| Distance Detection | > 30 | TTD = 2.0s | TTD = 1.6s | TTD = 1.2s |
| Smoking | > 10 | Alarm Trigger Duration: 2s | Alarm Trigger Duration: 3s | Alarm Trigger Duration: 4s |
| Calling | > 10 | Alarm Trigger Duration: 2s | Alarm Trigger Duration: 3s | Alarm Trigger Duration: 4s |
| Distraction Warning | > 10 | Alarm Trigger Duration: 2s | Alarm Trigger Duration: 3s | Alarm Trigger Duration: 4s |
| Drowsiness | > 10 | Alarm Trigger Duration: 2s | Alarm Trigger Duration: 3s | Alarm Trigger Duration: 4s |
| Yawning | > 10 | Alarm Trigger Duration: 1.5s | Alarm Trigger Duration: 2s | Alarm Trigger Duration: 3s |
| Driver Absence Detected | > 10 | Alarm Trigger Duration: 2s | Alarm Trigger Duration: 5s | Alarm Trigger Duration: 8s |
| Seat belt not fastened | > 10 | Alarm Trigger Duration: 2s | Alarm Trigger Duration: 5s | Alarm Trigger Duration: 8s |
| IR block | > 10 | Alarm Trigger Duration: 2s | Alarm Trigger Duration: 4s | Alarm Trigger Duration: 6s |
| DMS camera covered | > 10 | Alarm Trigger Duration: 5s | Alarm Trigger Duration: 10s | Alarm Trigger Duration: 15s |

6.1 ADAS Function

6.1.1 Lane Left Deviation Alarm

Real-time identification of lane deviation behavior during driving. If there is unintentional lane deviation behavior, the driver will be reminded to ensure driving safety.

Note: The left and right turn signal wires must be connected in the vehicle, and the turn signal must be activated before turning; otherwise, turning may trigger a false lane deviation alarm.



6.1.2 Lane Right Deviation Alarm

Real-time identification of lane deviation behavior during driving. If there is unintentional lane deviation behavior, the driver will be reminded to ensure driving safety.

Note: The left and right turn signal wires must be connected in the vehicle, and the turn signal must be activated before turning; otherwise, turning may trigger a false lane deviation alarm.



6.1.3 Front impact warning

Real-time identification of the relative speed between the vehicle and the vehicle in front during driving. The driver will be reminded when a impact is likely to occur, ensuring sufficient emergency braking time.



6.1.4 Pedestrian Impact Warning

During driving, real-time identification of pedestrians, bicycles, and motorcycles in front of the vehicle. If there is a potential impact risk, the driver will be reminded to ensure sufficient emergency braking time.



6.1.5 Distance Detection

When the vehicle is moving at low speed, it identifies the relative speed between this vehicle and the vehicle in front. When there is a potential impact risk, it alerts the driver to maintain a safe distance.



6.2 DMS Function

6.2.1 Smoking

Identifies the driver's smoking behavior during driving and issues a warning to ensure driving safety.

Note: Smoking alarms may produce false positives easily. When the driver makes movements similar to smoking, such as resting their chin on their hand or eating and drinking, false alarms may occur. You can collect false alarm videos and provide them to us to optimize the AI algorithm.



6.2.2 Calling

Identifies the driver's mobile phone call behavior while driving and issues a warning to ensure driving safety.



6.2.3 Distraction Warning

Identifies the behavior of the driver not looking at the road ahead (looking around, looking down for something, etc.) and triggers an alarm to ensure driving safety.



6.2.4 Fatigue Driving Alarm (Eyes Closed)

Identifies the driver's fatigue state (eyes closed) and issues a warning to ensure driving safety.



6.2.5 Yawning

Identifies the driver's fatigue state (yawning) and issues a warning to ensure driving safety.



6.2.6 Driver Absence Detected

Detects that the driver may be leaving and issues a voice reminder.



6.2.7 Seat Belt Detection

The device identifies the seatbelt status and issues a warning to the driver when the seatbelt is not fastened while driving to ensure driving safety.



6.2.8 IR block

The device has detected that the driver is wearing sunglasses, which prevents it from detecting whether the driver's eyes are closed.



6.2.9 Covered

The device has detected that the DMS camera is covered and will issue a voice warning to the driver.



7 Server Configuration Steps

Single Server, Dual Server, JTT 808\JTT 1708 Server

MS06: IP: **MS06.trackingmate.com** Port: **6006**

JTT 808\JTT 1708 MS06: IP: **MS06.trackingmate.com** Port: **8506**

7.1 Single Server

First, click Tracking Settings ①, then enter the MDVR platform IP ② and port ③, confirm the selection of TCP Connection ④, then click Set ⑤.



7.2 Dual Server

First, click Tracking Settings①, then enter the MDVR platform IP② and port③, confirm the selection of TCP Connection④, then enter the MS06 platform IP⑤ and port⑥, confirm the selection of TCP Connection⑦, and finally click Set⑧.



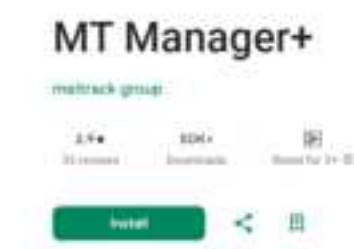
7.3 JTT 808\JTT 1708 Server

First, click Tracking Settings①, then enter the MDVR platform IP② and port③, confirm the selection of TCP Connection④, then click Set⑤.



8 APP (MT Manager+)

Search for the “MT Manager +” app in the Google Play Store or App Store on your mobile device, then download and install it.



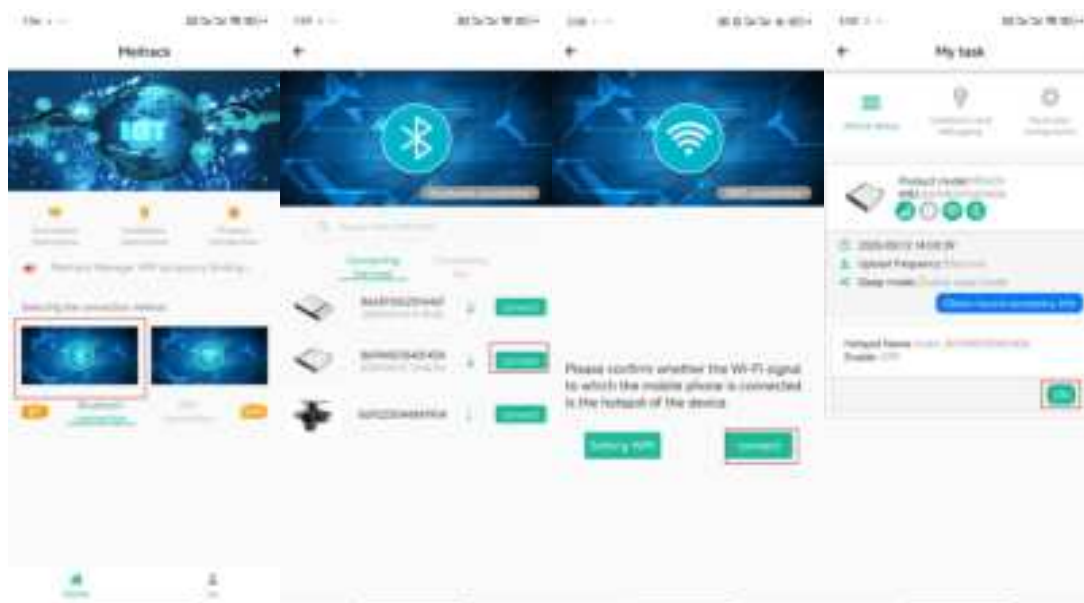
<https://apps.apple.com/cn/app/mt-manager/id1640858688>



<https://play.google.com/store/apps/details?id=com.meitrack.mm.all>

8.1 APP connection to MD600

Open MT Manager+, tap the Bluetooth icon, select the connect button corresponding to the device IMEI number, then tap the ON button to activate the device WiFi hotspot.



Tap Confirm, connect the mobile device to the MD600 WiFi hotspot, tap connect, then tap Parameter to enter the settings interface.



Note:

1. ACC must be activated when the APP connects to the MD600.
2. When the device WiFi hotspot is enabled, the device cannot upload data via WiFi.

8.2 Configure parameters using the MT Manager + APP

Tap the gear icon to switch to the parameter settings interface; Enter '**admin**' in the account field, use the default password '**0000**', then tap Confirm:



9 AI alarm settings

9.1 Indoor testing: enable simulated speed

Usage: Indoor testing of ADAS and DMS with simulated speed; set the simulated speed as shown in the figure below:



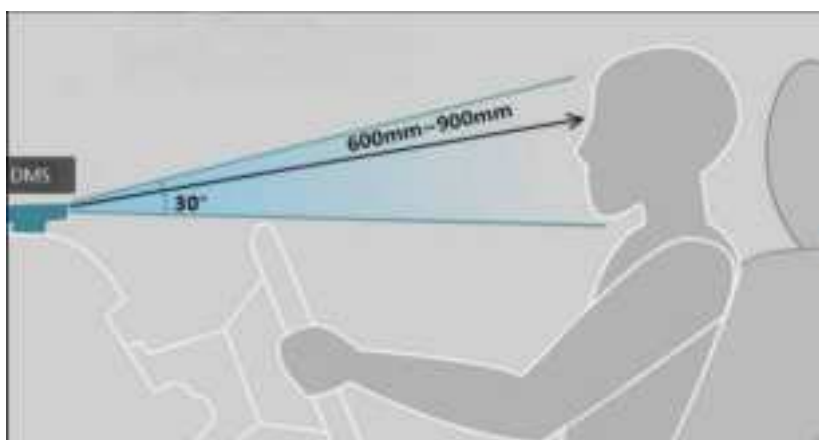
| Parameter | Description |
|----------------|--|
| Enable | Toggle option for simulated speed |
| Speed (Km/h) | The device automatically simulates the current driving speed to trigger specific conditional event feedback. |
| Duration (min) | Duration for which the simulated speed remains active to prevent forgetting to disable it, thereby avoiding false alerts during use. |

Note: The simulated speed will be disabled after the device restarts.

9.2 Calibration of ADAS, DMS, BSD, and facial recognition via the APP.

9.2.1 Installation and calibration of the DMS camera.

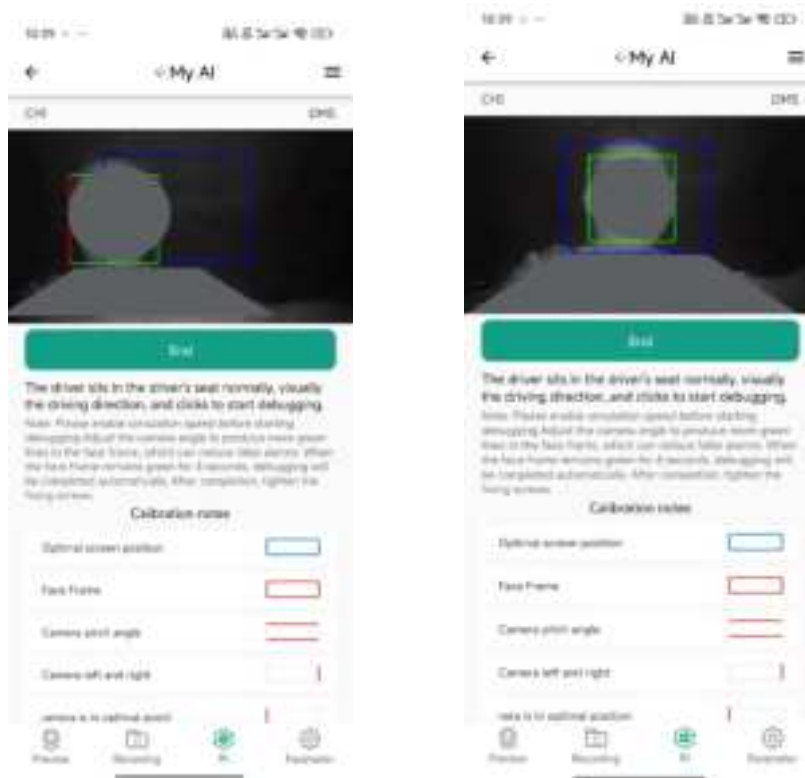
The DMS should preferably be installed directly in front of the driver at a relatively high position, with an angle not exceeding 30 degrees. The main unit should not be higher than eye level, nor lower than 30 degrees below the eye. The lens distance from the eyes should be between 60 cm and 90 cm. Additionally, the maximum horizontal angle must not exceed 30° to the left or right of the driver. An example image is shown below:



Calibration adjustments can be performed via MT Manager +, as shown in the following image:

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The blue box represents the fixed DMS detection area; the red box indicates a detected face outside the range; the green box indicates a detected face within the range and functioning properly. When the primary facial features are fully enclosed within the blue box and the face frame turns green, calibration is successful.



9.2.2 Installation and Calibration of the ADAS Camera

Install as close to the center of the windshield as possible without obstructing the driver's field of view. An example image is shown below:



Note: After installation, adjustment and calibration must be performed using MT Manager+ to enhance ADAS accuracy.

There are three methods to calibrate ADAS. Once the ADAS position is confirmed, you may proceed with calibration:

Method One: On the touchscreen, drag the red horizontal line to the position where the horizon disappears (the green lines

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indicate the range). The yellow vertical line represents the road's center line.

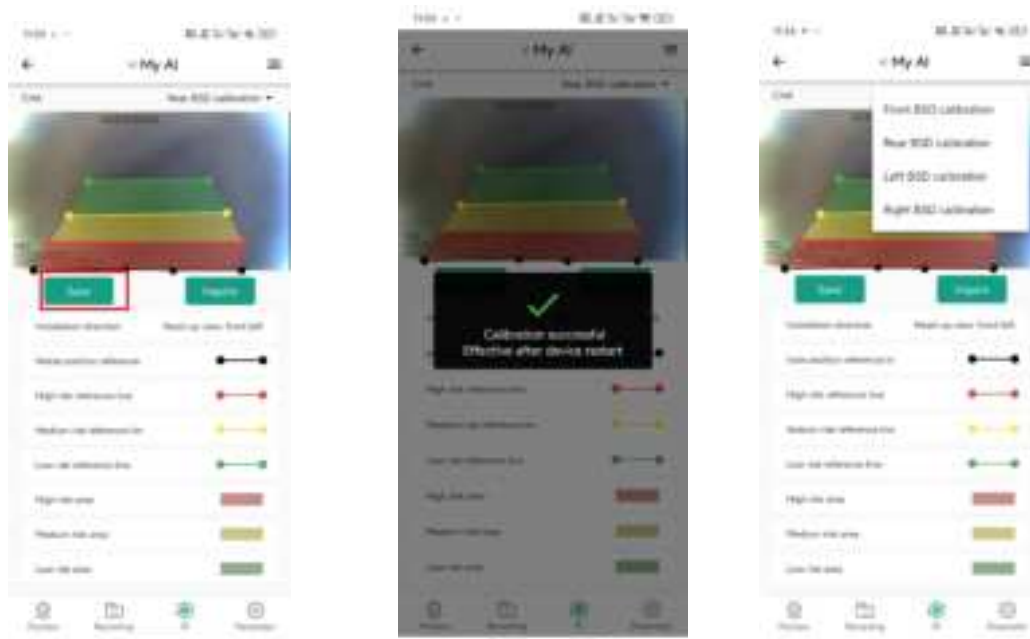
Second method: Click the button and drag the red horizontal line to the position where the sky and ground disappear (the green line indicates the range). The yellow vertical line represents the road centerline.

Third method: Configure the ADAS calibration parameters and click Save to apply.



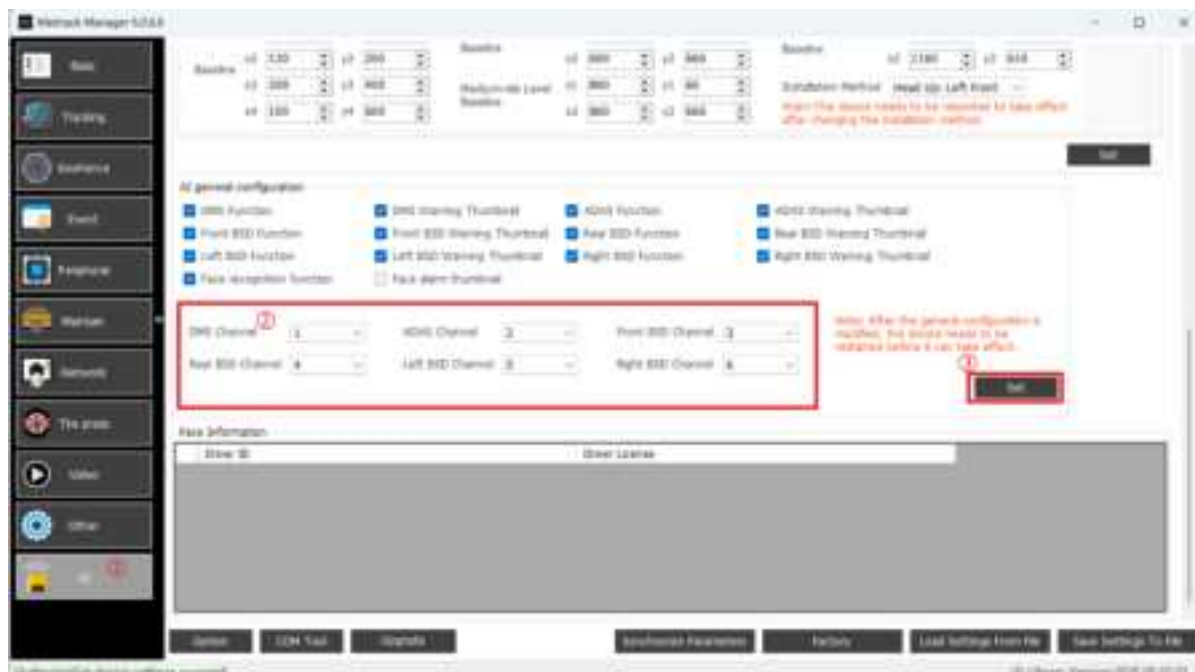
9.2.3 BSD Camera Installation and Calibration

- (1) The screen will automatically switch to the BSD camera. Use your finger to adjust the four lines on the screen to define three zones. By default, red represents a high-risk area, yellow represents a medium-risk area, and green represents a low-risk area.
- (2) Only one save is required; click Save to apply the settings.
- (3) Then click the upper right corner to switch to the other BSD camera and repeat the procedure.
- (4) Once all BSD calibrations are completed, testing may commence.



9.2.4 AI Function Video Channel Configuration

In MM, click AI Settings ①, select the desired AI function channel number ②, then click Set to apply the configuration ③.



10 Installation Guide

10.1 Installation of SD Card and SIM Card

(1) Insert the SD Card and unlock the SD Card lock using the key.



(2) Install the SIM Card and SD Card, then lock the SD Card lock (Note: After closing the card cover, use the key to lock it to ensure proper startup of the video function).

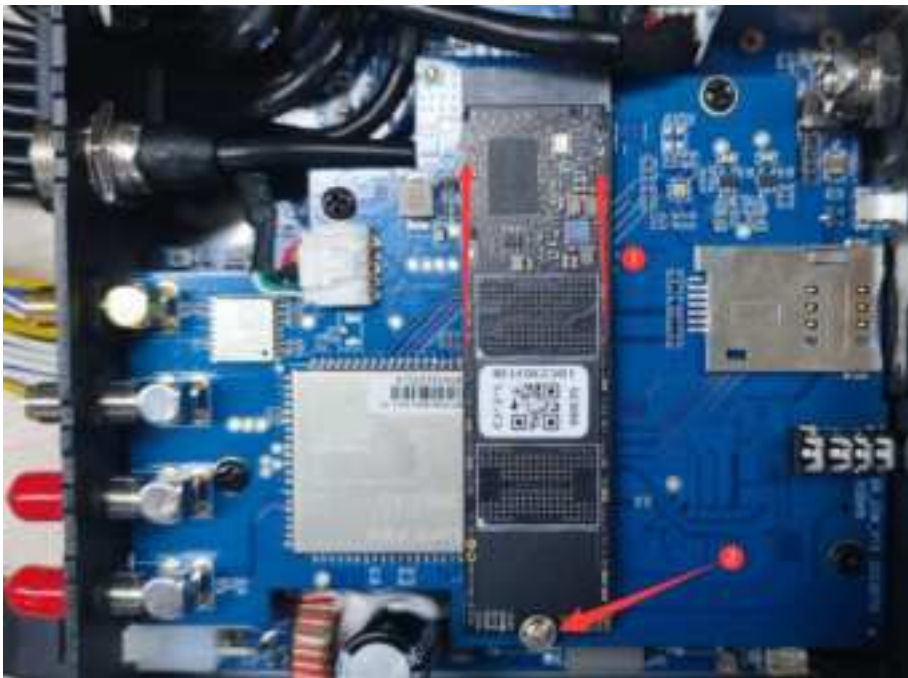


10.2 Hard Drive Installation

- (1) Unscrew the four screws on the top of the enclosure and open the cover.



- (2) Firmly insert the hard drive into the slot, secure it with screws, and then reassemble the enclosure.



10.3 Install External Devices

- (1) Connect six cameras, the display screen, GPS antenna, GSM antenna, WIFI antenna, and power cable.
- (2) Connect the power cable to PWR.
- (3) Connect cameras 1 through 6 to AV IN1 through IN6; connect the display screen to AV-OUT/VGA.
- (4) Connect the intercom handset to MIC & SPK.
- (5) Connect the WIFI antenna (otherwise WIFI will not function properly), GPS antenna, and 3G/4G antenna.



10.4 Powering the device

(Note: During testing, the recording function will only be activated when the ACC is connected to the positive power supply and the SD card cover is closed.)

Typically, the device should be connected to the vehicle's constant power line or engine line. Prior to installation, it is necessary to use a multimeter to identify the locations of these two wires within the vehicle. First, locate the constant power line and engine signal line in the vehicle's fuse box, then verify these wires using a multimeter according to their characteristics.

Connect the multimeter's black probe to ground and the red probe to the vehicle battery line. Measure the voltage with the engine off and ignition on to confirm it is approximately 12V (or around 24V for heavy vehicles). If the voltage remains stable, this can be considered the battery line.

Connect the black probe of the multimeter to ground and the red probe to the vehicle's engine signal line. Measure the voltage during vehicle ignition to verify whether it is approximately 12V (for larger vehicles, around 24V). Observe if the voltage drops to 0 when the vehicle is turned off.



After confirming the constant power and engine signal lines, you may select the appropriate wiring method for installation..

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Different wiring methods:**Method One:**

(If recording is required only during ignition and should stop after shutdown, while the device's MCU remains operational for positioning, this method can be used.)

Connect the MDVR's ACC detection line to the vehicle's engine line, and connect the MDVR's power line to the vehicle's constant power. In this configuration, the MDVR's video module will only power on and begin recording when the engine is running.



By setting the power-off delay time, the video module is allowed to continue operating for a period after the vehicle is turned off, recording video data for a short duration post shutdown.



Furthermore, if special circumstances require remotely activating the device's video module while the vehicle is off, the BCA command can be used to forcibly power on the video module for a limited time.

Method Two:

(This method can be used if the device only needs to power on after the engine starts and fully shut down after the engine is turned off.)

Connect both the MDVR's power line and ACC line to the vehicle's engine line. This ensures the device fully powers down when the engine is off, and both the MCU and video module start simultaneously when the engine is running.

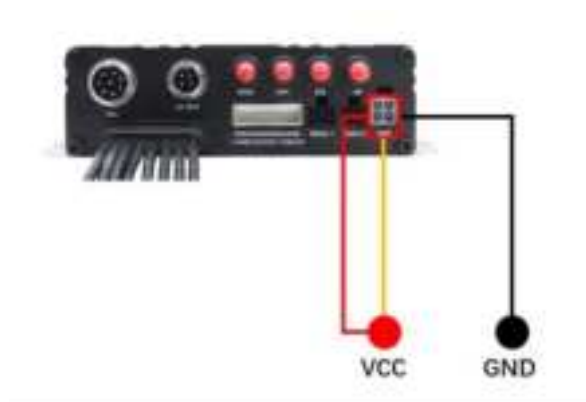


This method does not consume the vehicle battery's power; however, when the vehicle is turned off, the device will completely shut down, and the video module can only record footage prior to engine shutdown.

Method Three:

(If continuous recording is required regardless of engine status, and video recording must be uninterrupted, this method can be used.)

Connect both the MDVR's power line and ACC line to the vehicle's constant power (battery line). In this way, even when the engine is off, the device will continue to consume battery power, which carries a risk of depleting the battery. Therefore, this method is generally not recommended for customers. If the user is only conducting indoor testing, this wiring method can be used to keep the device's video module continuously operational.

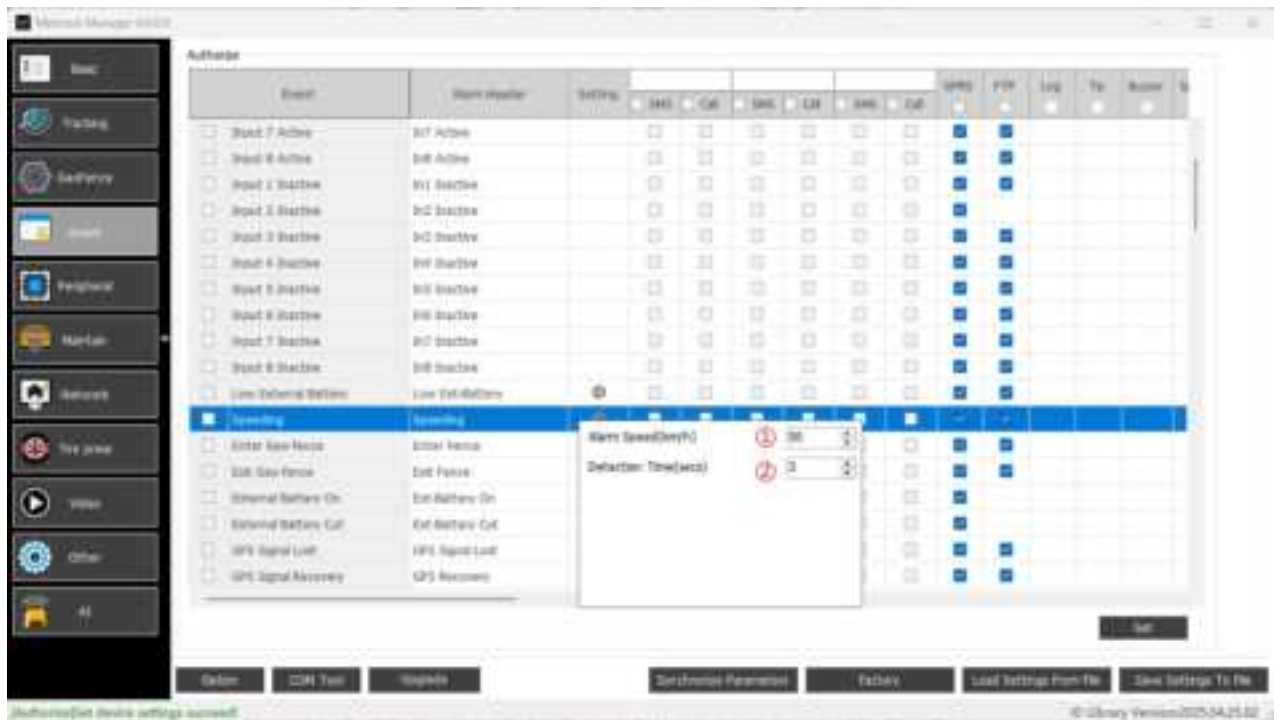


11 MD600 Function Settings,

11.1 Set Overspeed, Harsh acceleration\Harsh Braking, and Impact Alarm

(1) Overspeed: In the MM overspeed event settings, the alarm method can be configured as SMS, telephone, or GPRS.

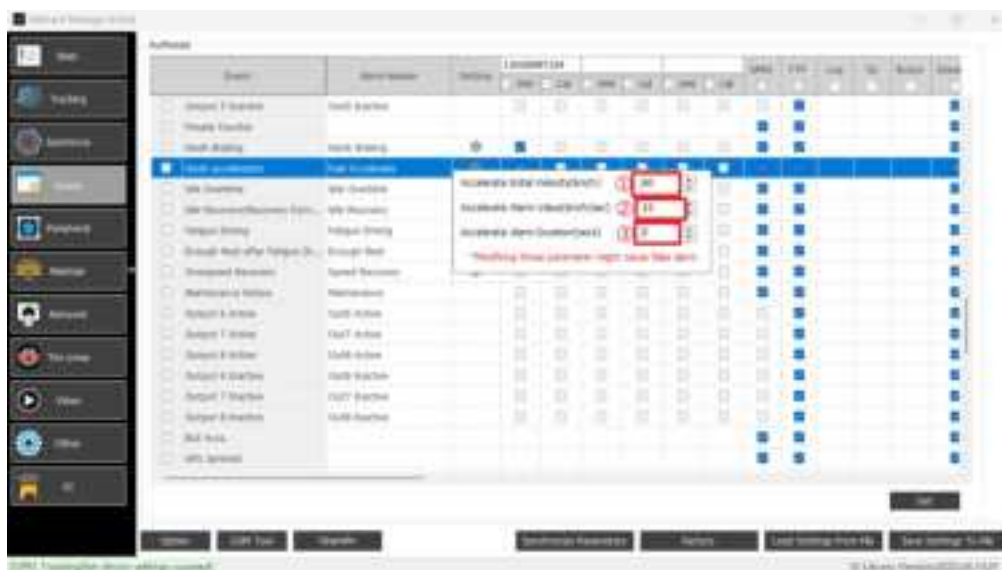
Set the overspeed threshold and alarm detection time: When the device detects that the speed exceeds the threshold and remains above it for the specified detection time, an overspeed alarm will be triggered.



(2) Harsh acceleration\Harsh Braking: In the MM Harsh acceleration and Harsh Braking event settings, the alarm method can be configured as SMS, telephone, or GPRS.

For Harsh acceleration\Harsh Braking events, you can set ① initial speed, ② acceleration\deceleration threshold, and ③ alarm duration;

- ① Initial speed: The initial speed value that triggers Harsh acceleration or Harsh Braking;
- ② Harsh acceleration/deceleration value: Sets the trigger threshold for acceleration or deceleration;
- ③ Detection time for triggering Harsh acceleration/deceleration: Within this time frame, the acceleration or deceleration value reaches the trigger threshold.

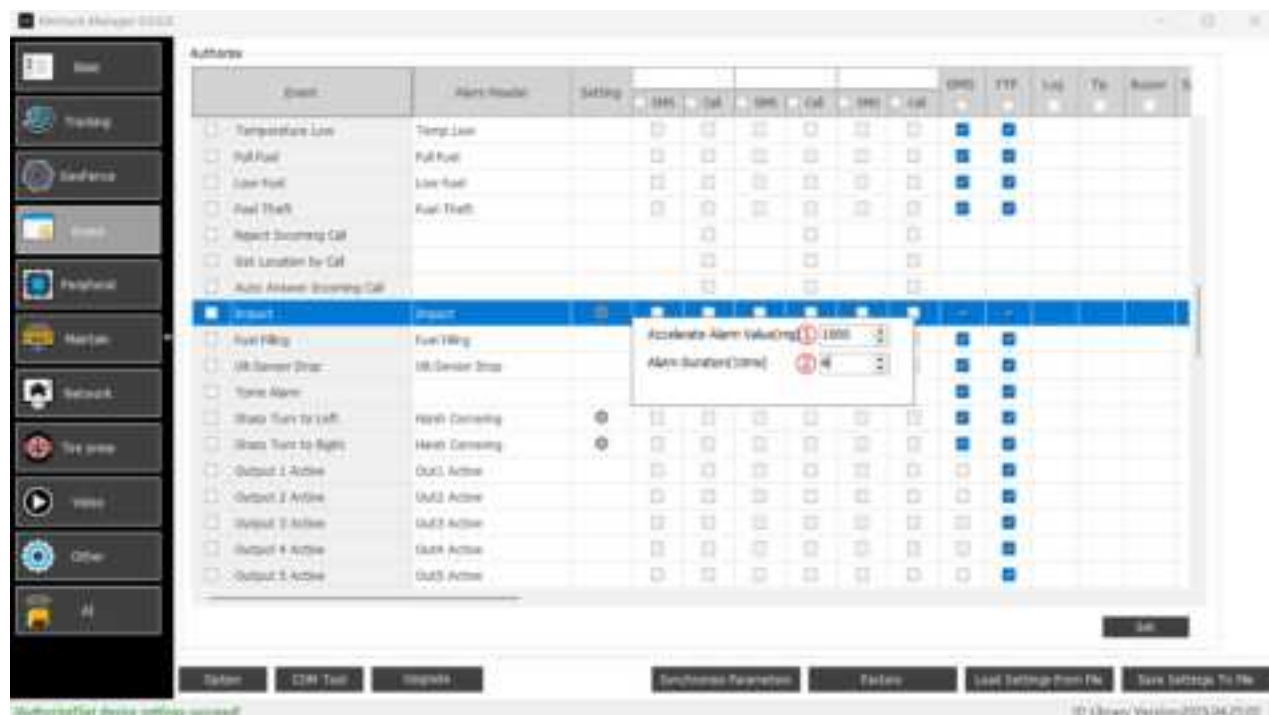


(3) Impact alarm: In the MDVR impact event settings, the alarm method can be configured as SMS, telephone, or GPRS;

① Alarm acceleration: Sets the acceleration threshold that triggers a impact event, unit mg, range 500–65535;

② Alarm duration: Sets the duration of the impact event, unit 10 ms, range 0–255;

Note: For actual vehicle installation, the device must be firmly secured to the vehicle to ensure more accurate impact alarms. (The default values are identical for both small and large vehicles. If frequent false impact alarms occur during actual use, the impact acceleration threshold can be raised.)

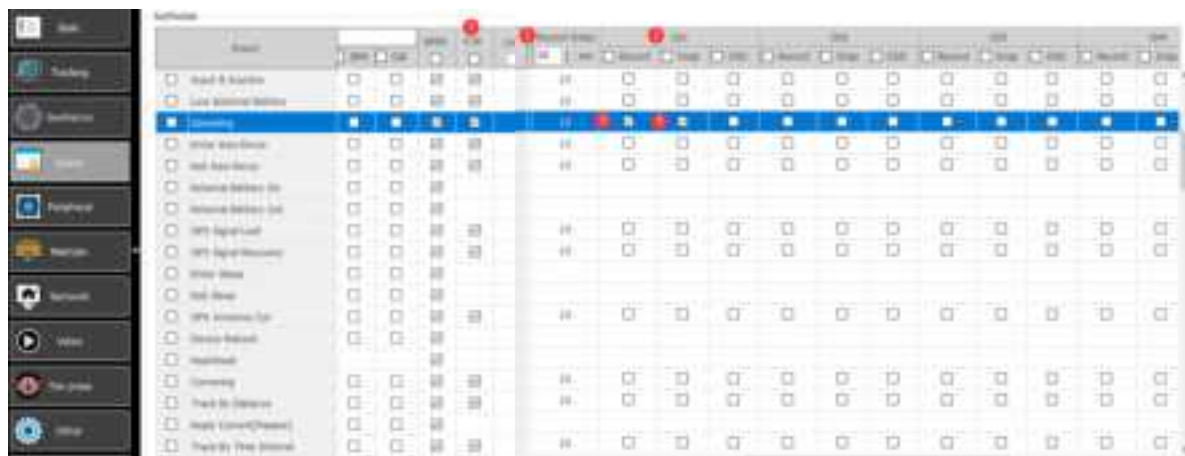


11.2 Upload Alarm Images and Videos

11.2.1 Configure to trigger alarm photo capture and snapshots;

- ① Set whether to upload to the FTP Server;
- ② After triggering the alarm, select which CH to capture photos and record videos;
- ③ “Record” refers to video recording; video recording will start after triggering the overspeed alarm;
- ④ “Snap” refers to photo capture; a photo will be taken after triggering the overspeed alarm;

⑤ “Record delay” specifies the duration of video recording after the alarm is triggered. For example, setting it to 10 seconds will record video data 5 seconds before and 5 seconds after the alarm.



11.2.2 Configure FTP Server

① In Network Settings, enable ② FTP Enable;

Enter ③ Domain Name, ④ Port, ⑤ Username, ⑥ Password, then click Set

Default FTP Server IP: **67.203.15.7**; Port: **9876**;

The username and password are the same as the MS06 platform account.

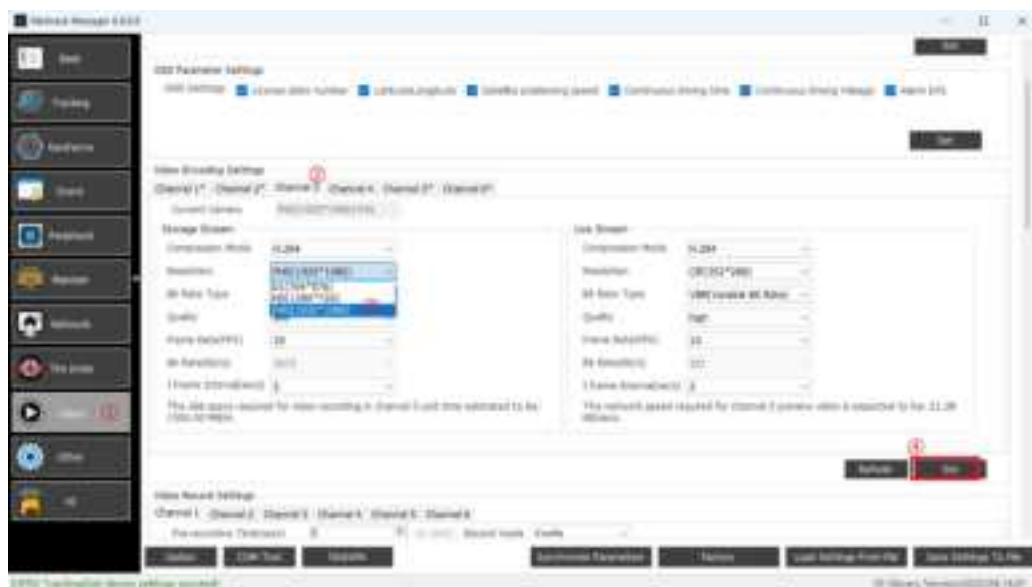


Note: Incorrect FTP Server parameter settings will cause images and videos to fail to upload properly to the FTP Server.

11.3 Set the resolution for stored stream video and real-time stream video.

11.3.1 Set the resolution for stored stream video.

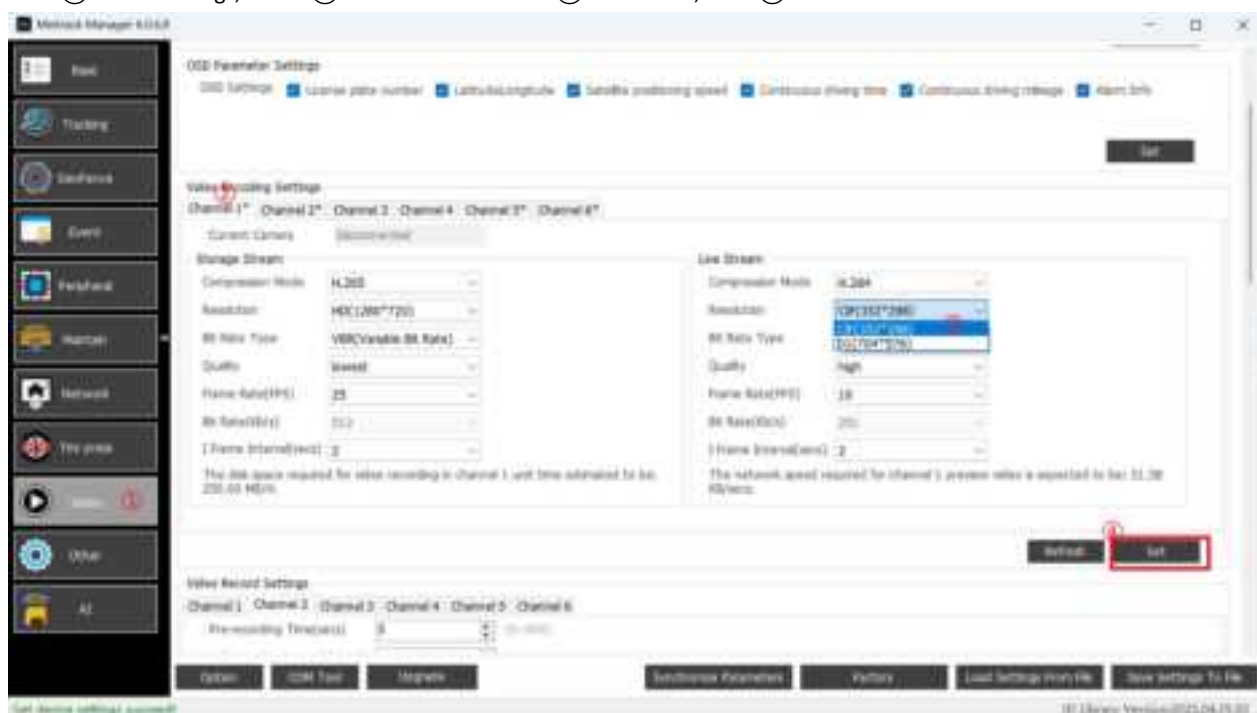
Click ① Video Settings, select ② Camera Channel and ③ Resolution, then ④ click Set.



Note: Stored stream video will not be actively uploaded to the FTP Server; it requires a command from the server to retrieve the stored stream video.

11.3.2 Set the resolution for real-time stream video.

Click ① Video Settings, select ② Camera Channel and ③ Resolution, then ④ click Set.



Note: Real-time video can be configured to actively upload video to the FTP Server. To enable this function, please follow the steps below:

- (1) Configure the FTP Server first.
- (2) Select ① Video Settings, then choose ② Camera Channel, ③ Real-time Video Storage (if unchecked, real-time video will not be uploaded), and ④ Upload Real-time Video to FTP Server;

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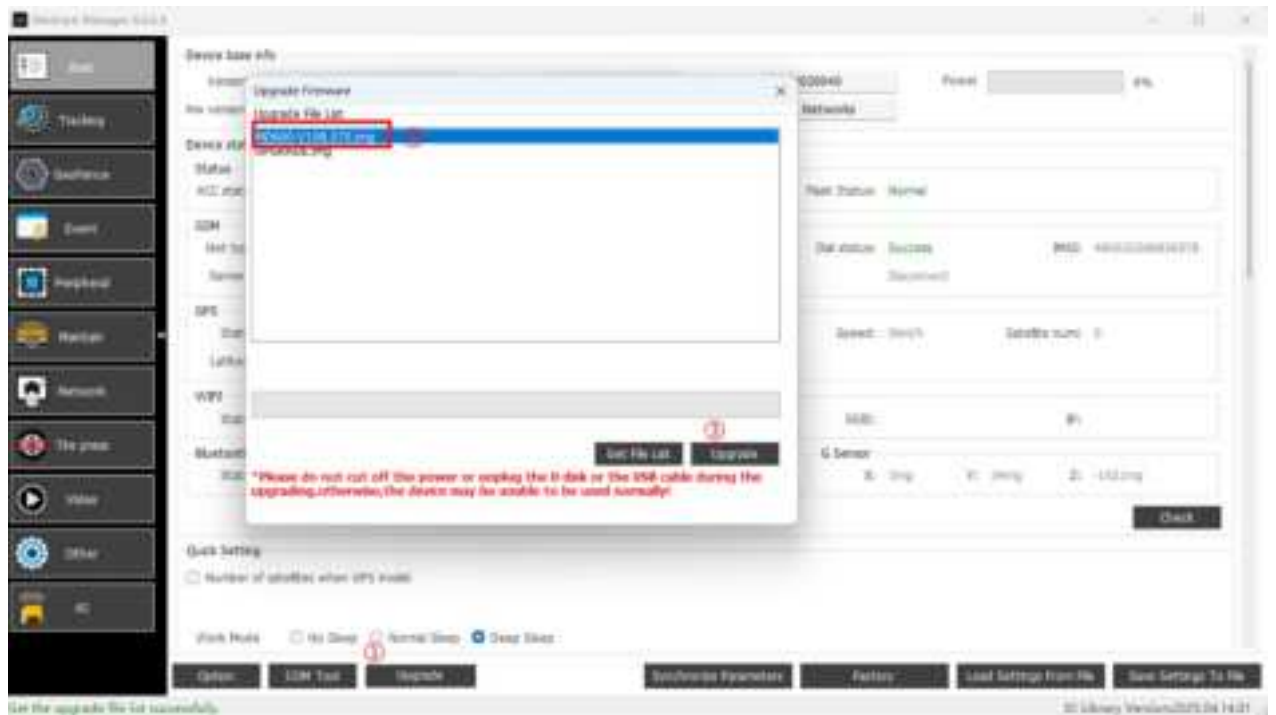
11.4 MD600 Upgrade

Ensure the USB drive contains an img file, for example, MD600-V108.070.img

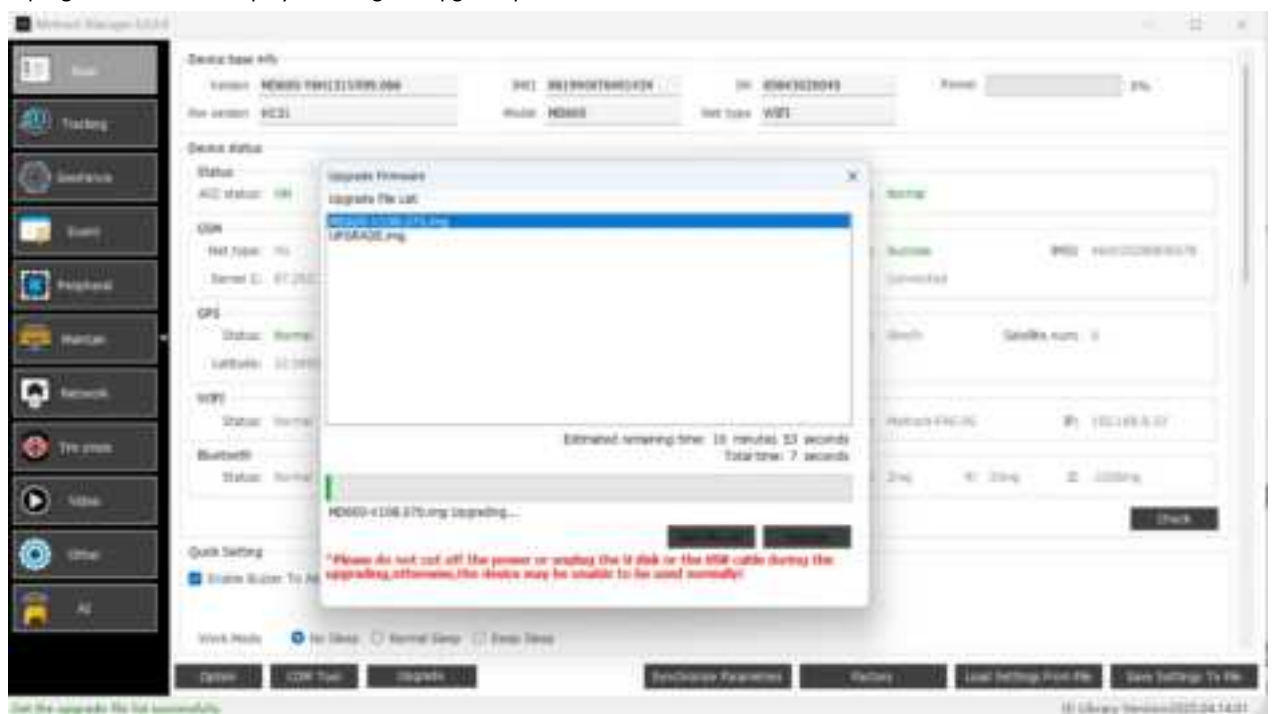
Insert the USB drive into the USB port of the MD600 device

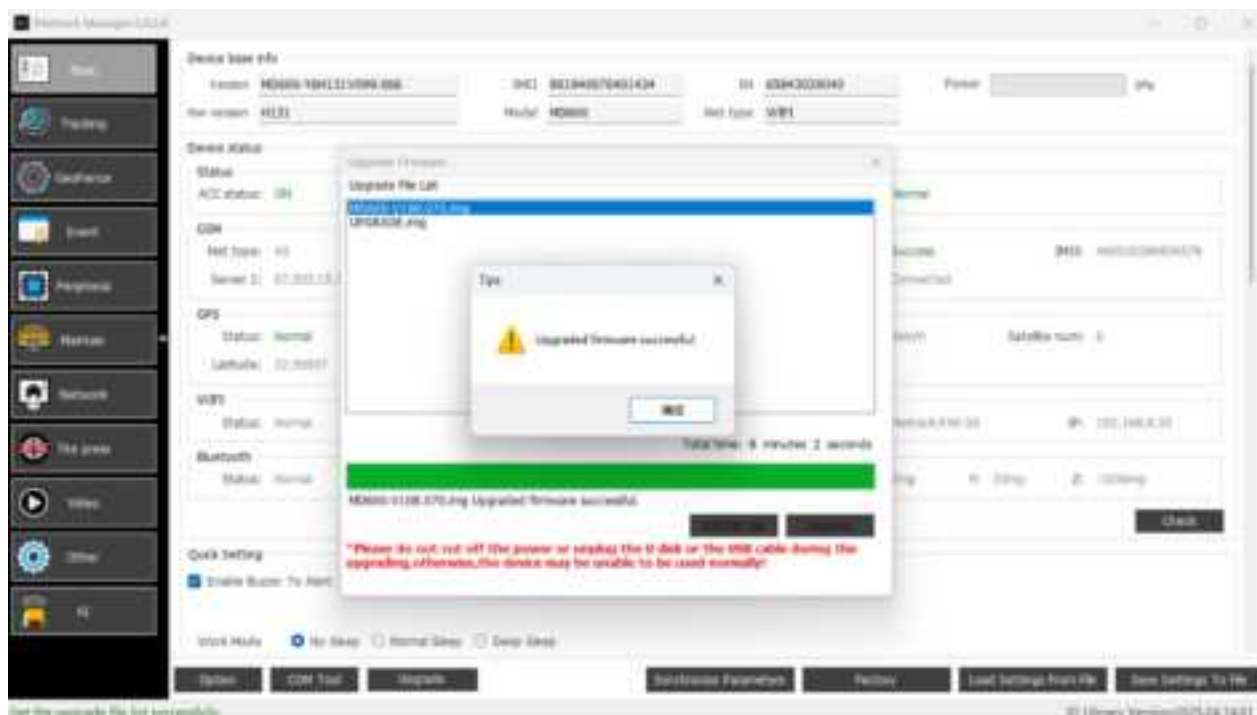


Open the MM software, then click ①, select the upgrade file ②, and click Upgrade ③



A progress bar will be displayed during the upgrade process





12 MS06 Platform

12.1 Bind Device

Enter <https://ms06.trackingmate.com/loginPage> to open the MS06 official platform website, then enter your account and password, and click Login



Click Device; select Add; fill in the required fields marked with *; then click save ;



Note: If unclear, please refer to the detailed MS06 user manual or contact Meitrack technical support for assistance;

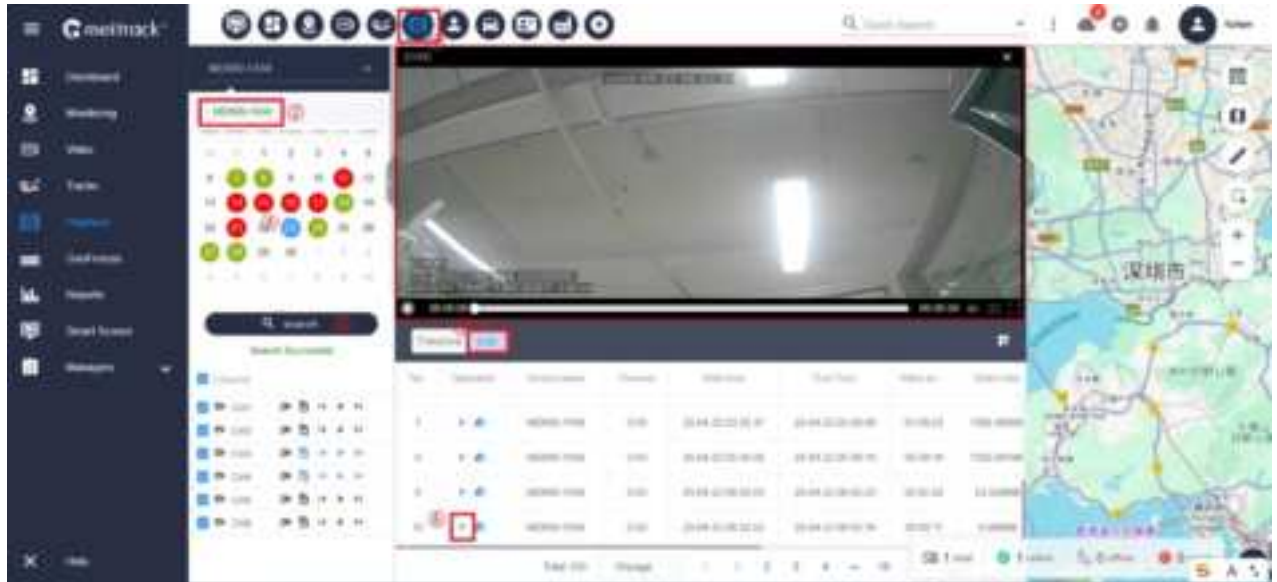
12.2 How to view live video

Click the ① icon, then double-click the desired ② video channel to view the video.



12.3 How to view playback video

Then click the icon ①, select the device name ②, click Search ③, select the date ④, choose from the list ⑤, and click Play ⑥.



Playback video viewing diagram

Note: For additional features of the M S06 platform, please refer to the M S06 platform user manual.

If you have other questions, please email us at info@meitrack.com, and we will be happy to serve you.