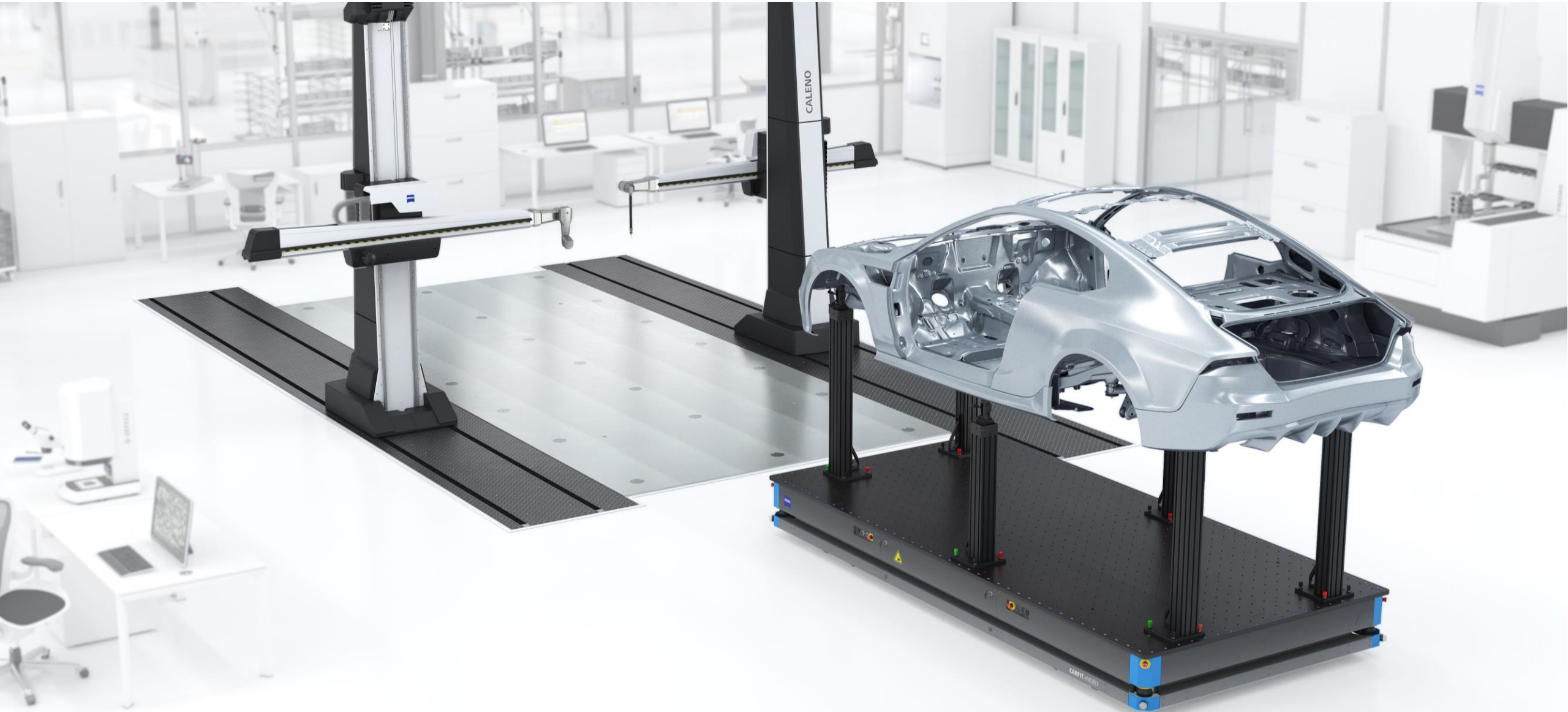


ZEISS Multi Sensor CMMs for Car Body Applications



ZEISS Multi Sensor CMMs for Car Body Applications

More than a Robot – The Hambot



More than a Robot – The Hambot

Trends in Carbody Metrology



Optical sensor for Carbody metrology

- Faster to the result.
- Surface information (CAD compare)
- Digital Twin
- Optical sensor on industrial robots

Multi Purpose CMMs

- Holistic Approach for measurement: More sensors in one automated Run.
- Increasing Flexibility: the application decides about the sensor.
- More Metrology in production environment.
- Reduction of logistics and transportation costs.

New applications due to Electric Mobility

- Short cycle times
- Tight tolerances
- Critical surfaces (machined aluminum)
- Access to the part

More than a Robot – The Hambot

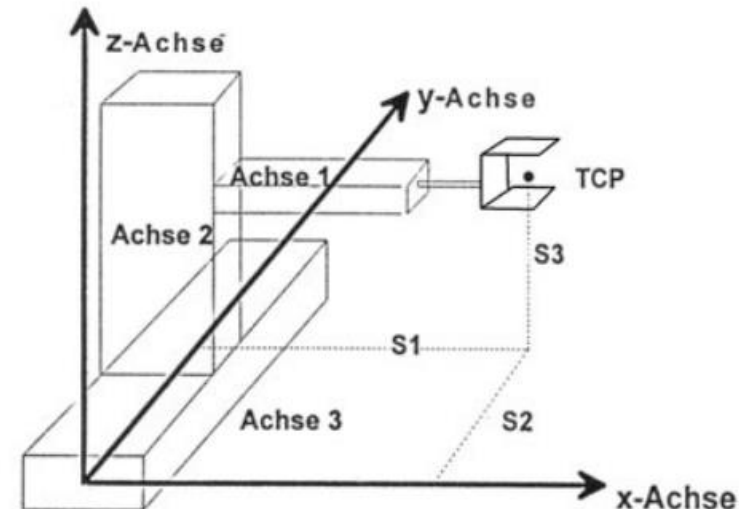
Definition Industrial Robot

Industrial robots are defined by ISO 8373:2012:

An automatically controlled, reprogrammable, multipurpose manipulator programmable in three or more axes, which can be either fixed in place or mobile for use in industrial automation applications

Classification by mechanical structure

- **Linear robots (including cartesian and gantry robots)**
- SCARA robots - Articulated robots
- Parallel robots (delta)
- Cylindrical robots
- Others

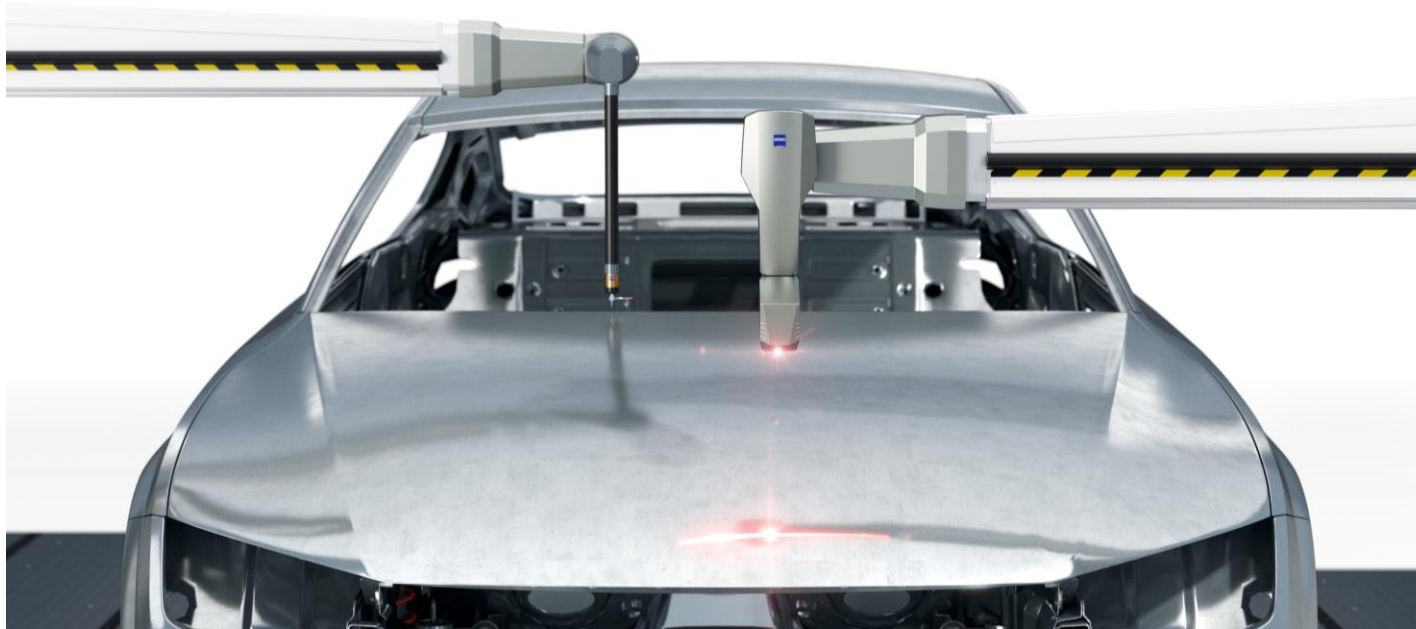


- Horizontal arm CMMs, especially combined with optical sensors are automatically controlled, programmable in more than 3 axis and are therefore robots based on ISO 8373:2012

More than a Robot. The Hambot.

More than a Robot – The Hambot

ZEISS CALENO – More than a Robot



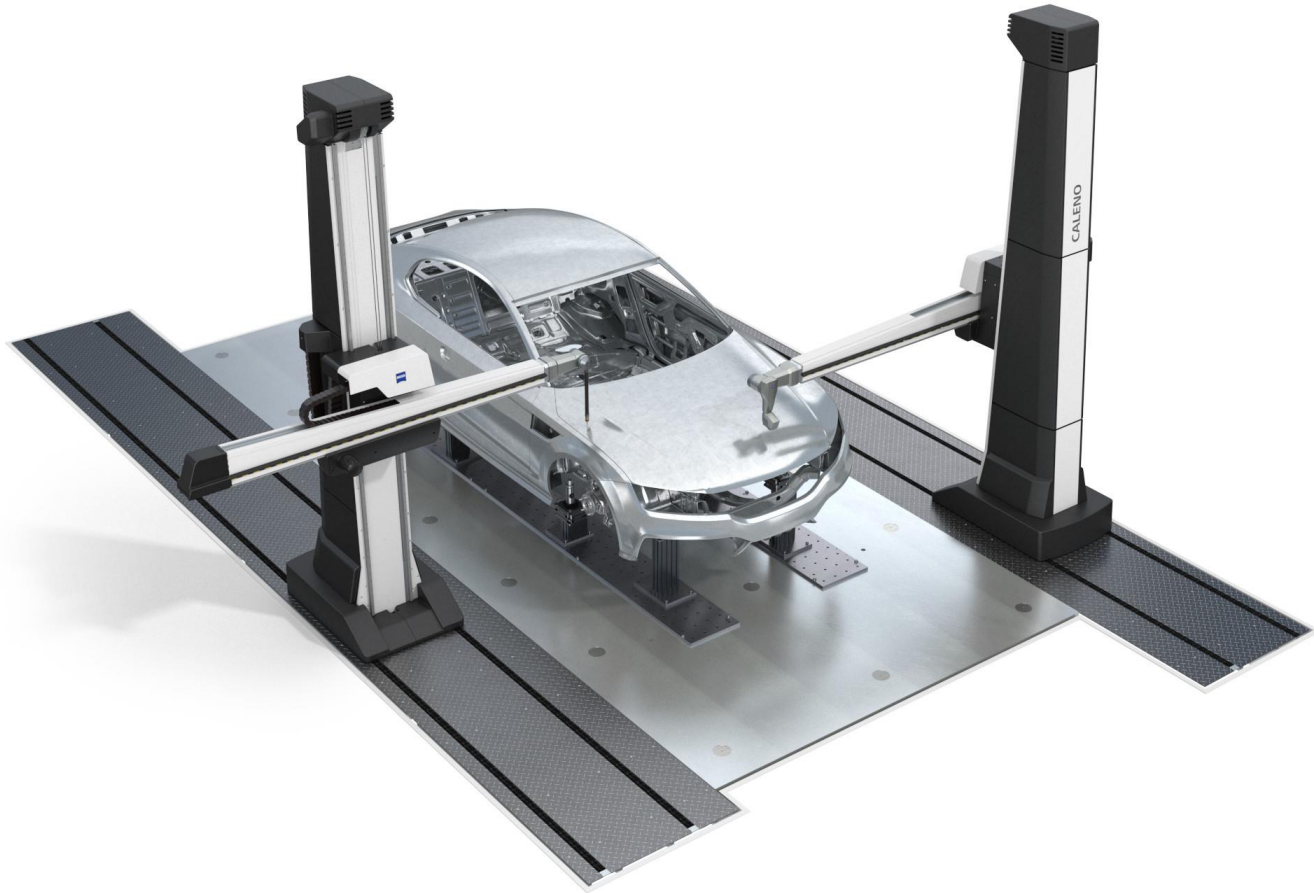
- CALENO is a cartesian 6-axis robot
- CALENO is a robot with an outstanding optical sensor system – EagleEye
- With CALENO you get proven CMM accuracy, a collaborative system and a multi sensor system with automatic sensor change.

This is not possible with an articulating robot.

Therefore, CALENO is more than a robot.

More than a Robot – The Hambot

ZEISS CALENO – The Hambot



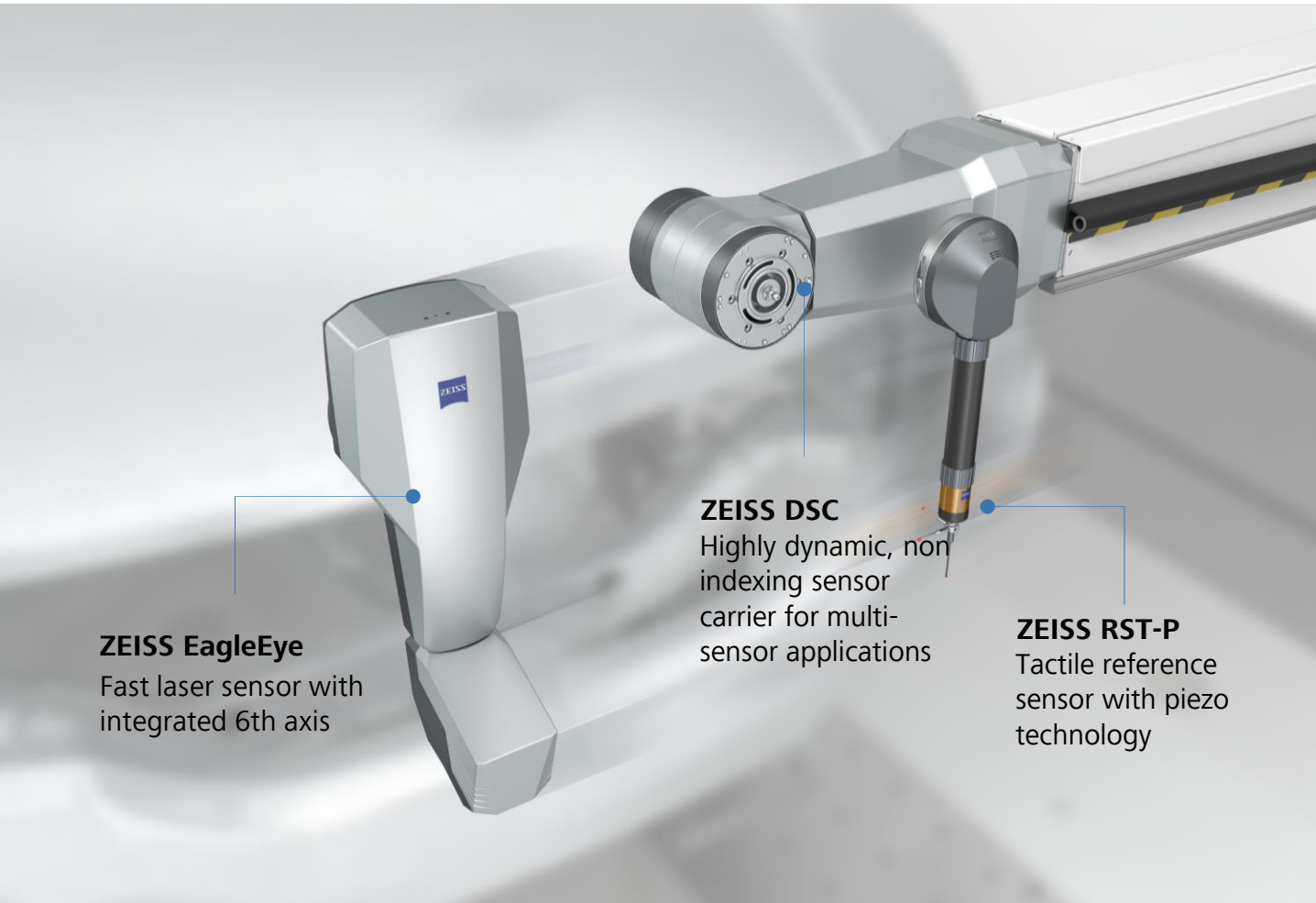
- The new wording Hambot combines two different needs in metrology
 - The experience with **HAM**, that it is ideal for sheet metal metrology and provides high and absolute accurate measurements
 - The requirement for high productivity, which is linked with the wording **robot**
- **Hambot** will be used instead of Horizontal Arm Machine to underline the new class of CMMs with optical sensors.

ZEISS Multi Sensor CMMs for Car Body Applications

The Hambot - Overview



More than a Robot – The Hambot Multi-Sensor System



ZEISS EagleEye
Fast laser sensor with
integrated 6th axis

ZEISS DSC
Highly dynamic, non
indexing sensor
carrier for multi-
sensor applications

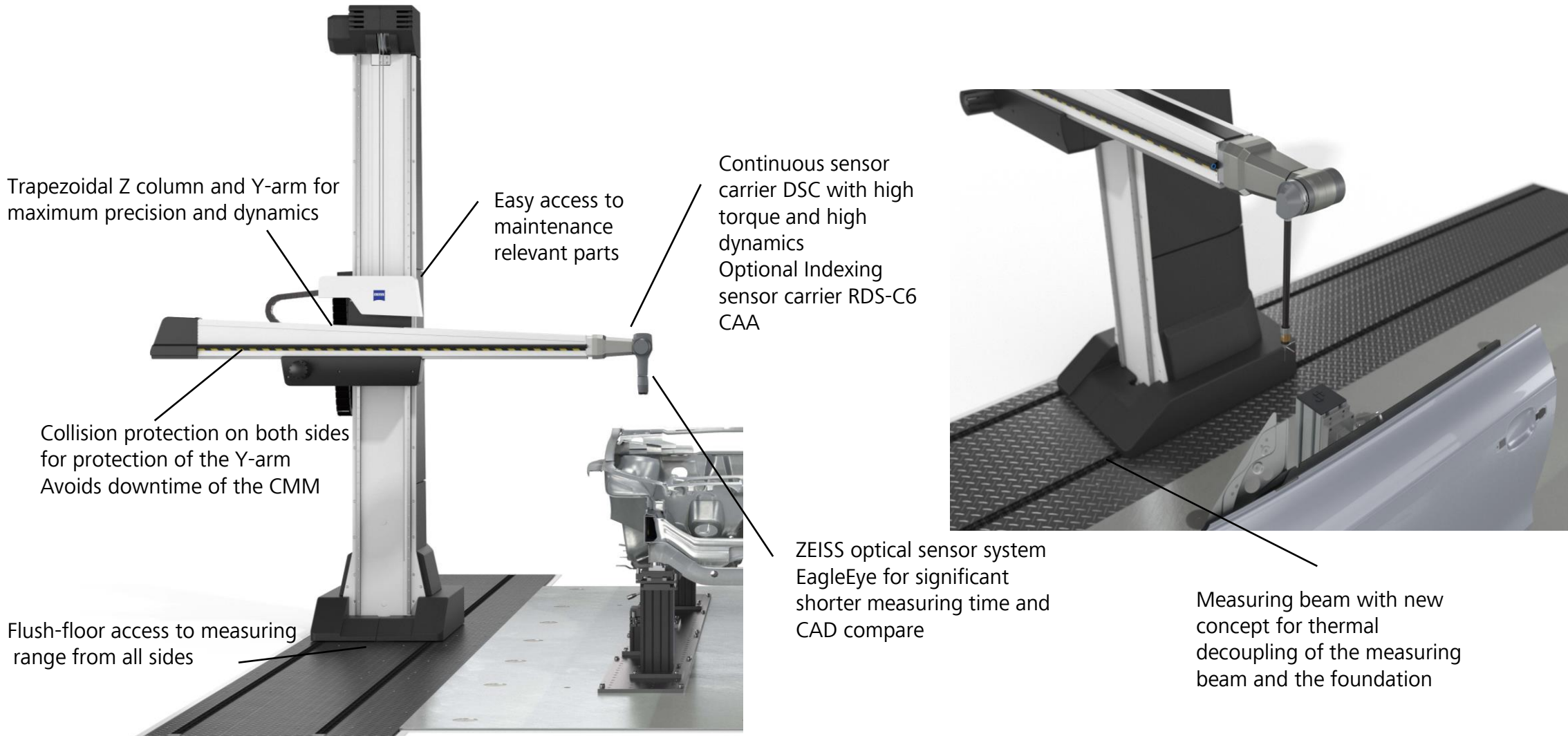
ZEISS RST-P
Tactile reference
sensor with piezo
technology

Multi Sensor System

- With ZEISS EagleEye, geometric elements can be measured and evaluated in record time
- Scanning of free-form geometries for CAD comparison and of geometry elements with the same sensor
- Automatic switch between optical and tactile sensors for features that cannot be optically measured.
- Thermofit extensions with up to 800mm.

More than a Robot – The Hambot

Exceptional Technology - CALENO



More than a Robot – The Hambot

Exceptional Technology – CALENO T



Full covers made of EPP for excellent thermal isolation

Measuring tables available with optional T-slots or bore pattern for the clamping of fixtures

Inherent stiff measuring plate allows the installation with active damping system

Continuous sensor carrier DSC with high torque and high dynamics
Optional Indexing sensor carrier RDS-C6 CAA

Easy access to maintenance relevant parts

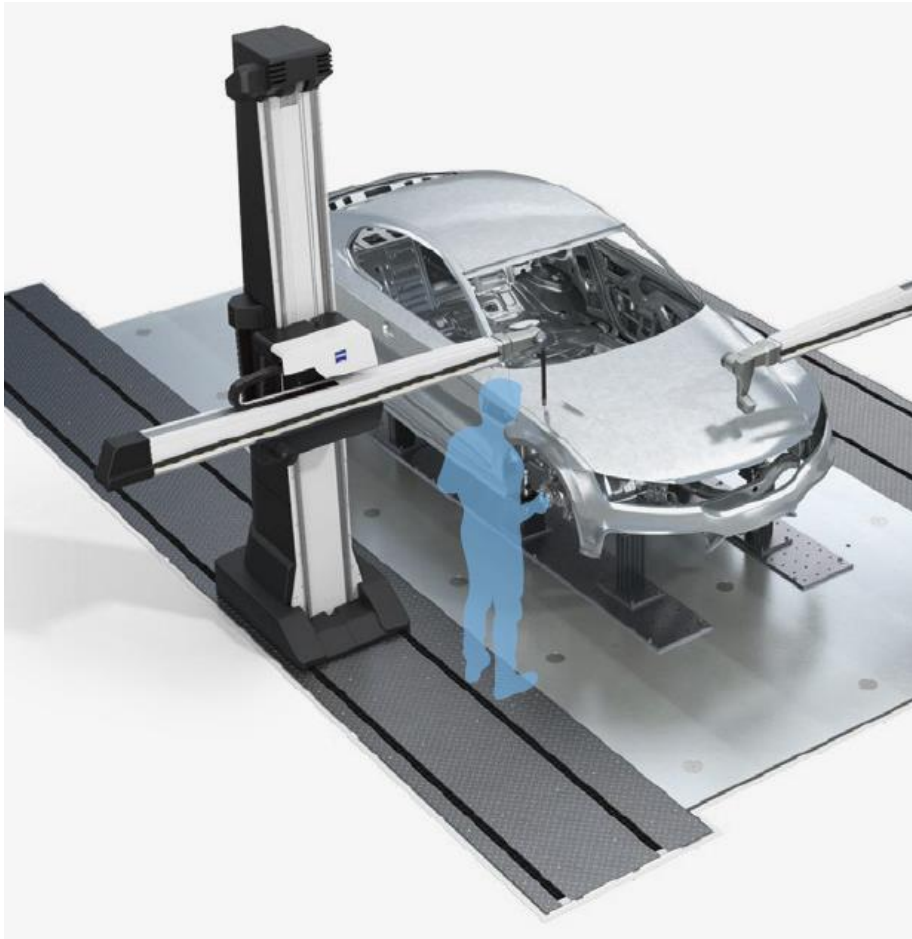
ZEISS Multi Sensor CMMs for Car Body Applications

Safety for the operator and the Hambot



More than a Robot – The Hambot

Safety for the Operator

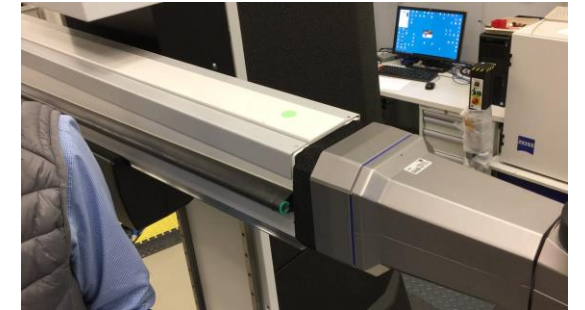


Friction drives, lag detection and over current protection

- The multi layer safety concept will stop the system, if any obstacle is in the travel path to protect the hambot and the operator.

Safety edge at the Y-arm

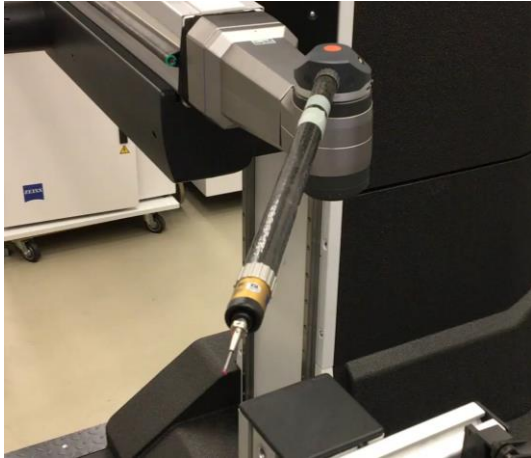
- ZEISS CALENO has standard sensor strips along the entire length of both sides of the Y-arm. If the narrow elastic tubes are deformed on contact, they will instantaneously shut down.



- Due to the safety features, the operator is allowed to work in the system, whilst measuring
- Risk of damaging is significantly reduced to reduce downtime and repair costs.
- Protects the operator from injury

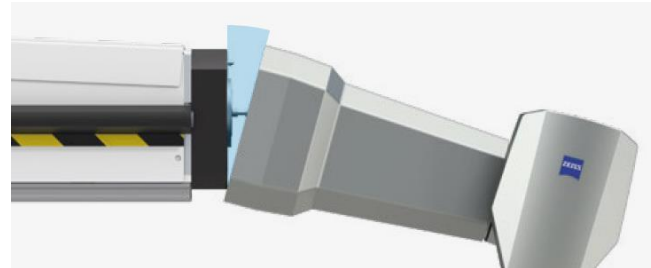
More than a Robot – The Hambot

Safety for the sensor system



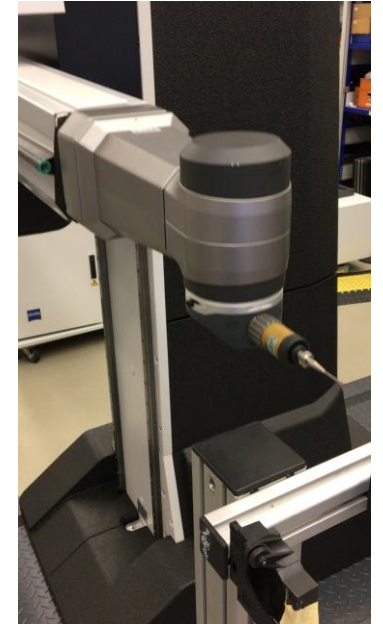
Collision protection for the sensor

- The connection point to the sensor is spring-mounted on the sensor carrier. This protects the sensor from damage in the case of a collision.



Optional collision protection for the ZEISS DSC or RDS-C6

- In addition, CALENO can optionally be delivered with an additional spring-mounted collision between the sensor carrier and the Y-arm.



Protective device on the ZEISS RST-P sensor

- Overtravel protection for ZEISS RST-P To minimize damage by collisions with the stylus. The traverse angle of the stylus on the ZEISS RST-P is an exceptionally large 26 °.

- Maximum protection of the sensor carrier and the sensor system leads to maximum availability of the system and reduced repair costs.

ZEISS Multi Sensor CMMs for Car Body Applications

CALENO/CALENO T – What is new

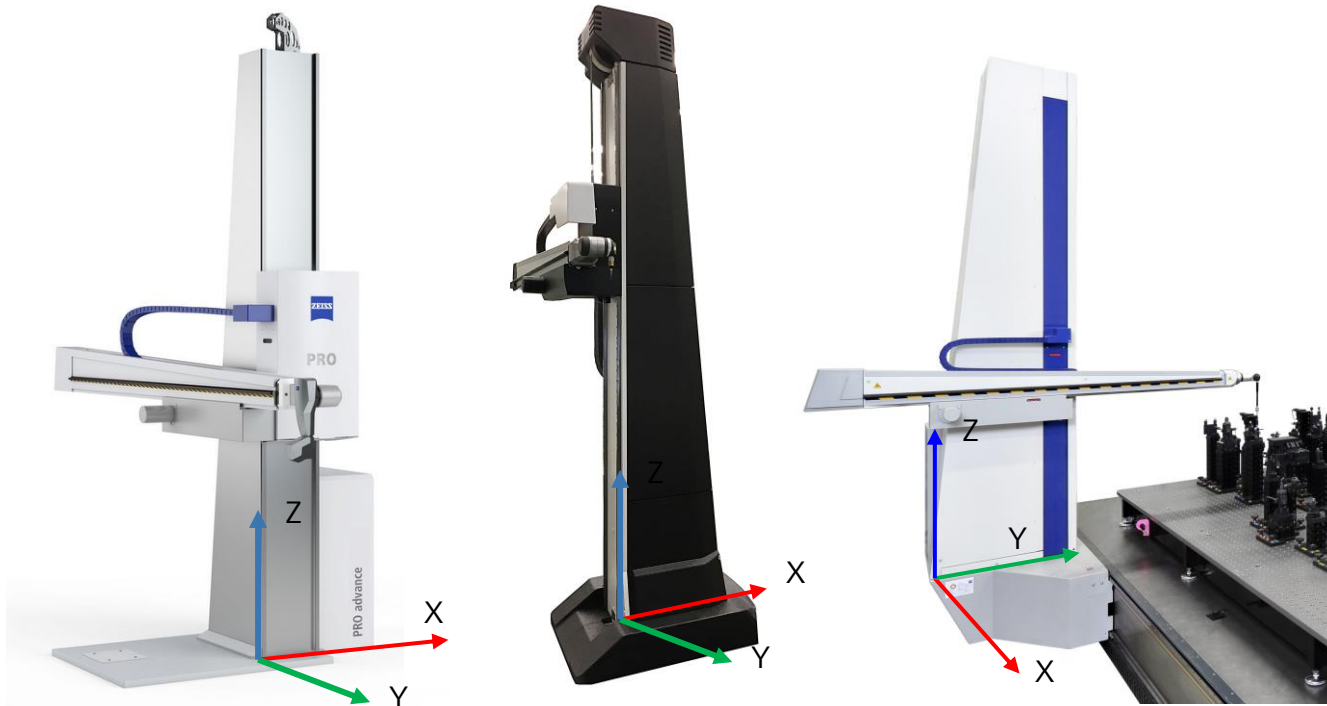


More than a Robot – The Hambot

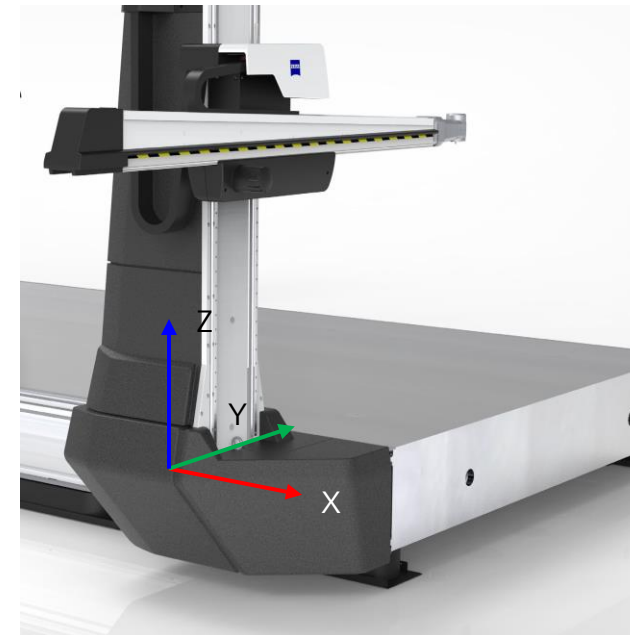
PRO/ CALENO Improvements



- Column turned by 90° for enhanced stiffness



PRO/ CALENO



PRO T/ CALENO T

More than a Robot – The Hambot

PRO/ CALENO Improvements



PRO



CALENO

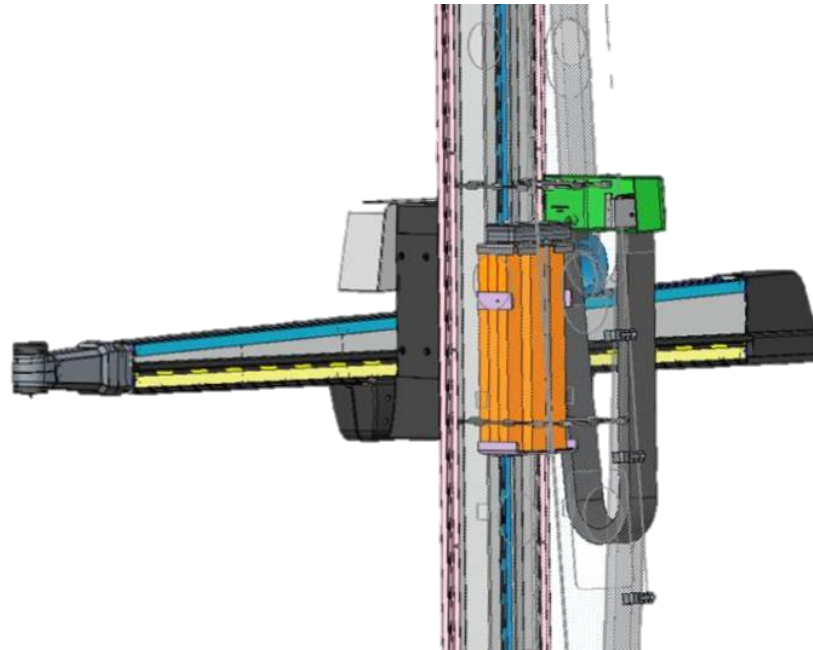
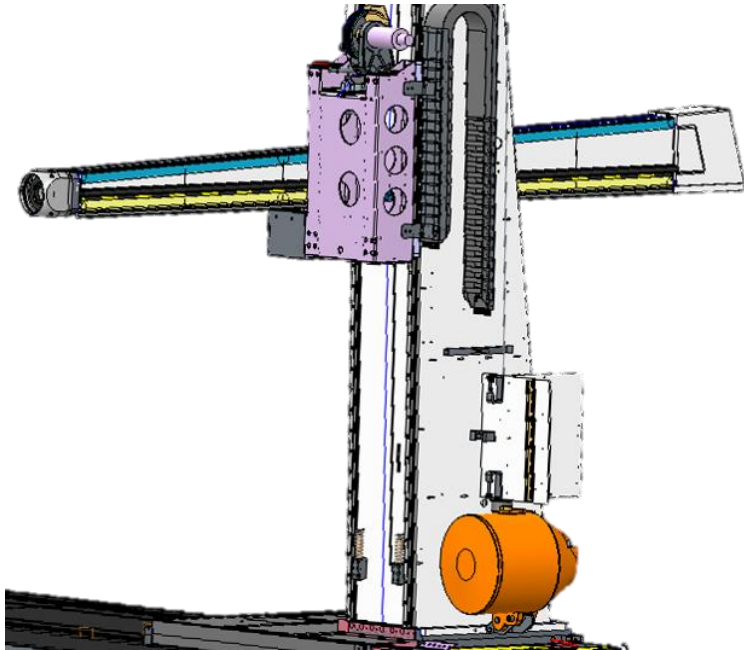
- PRO/ PRO T was available with standard, or full covers
- CALENO is always with full covers
 - Enhanced thermal stability
 - New material EPP with excellent thermal isolation

More than a Robot – The Hambot

PRO/ CALENO Improvements

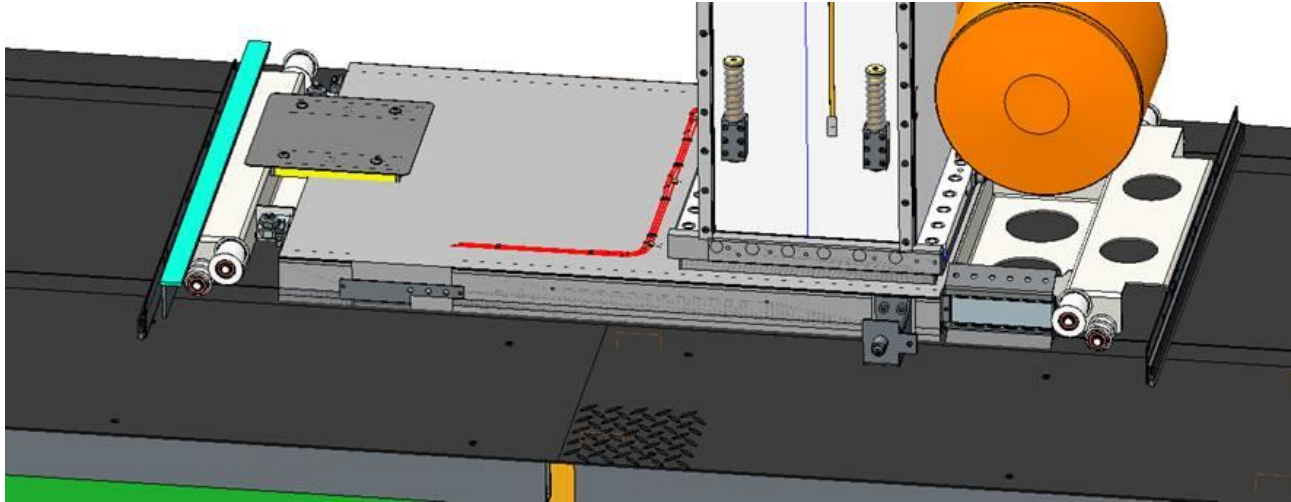


- New counter balance system
 - Counter weight instead of balancer
 - Less service costs
 - Improved MTBF

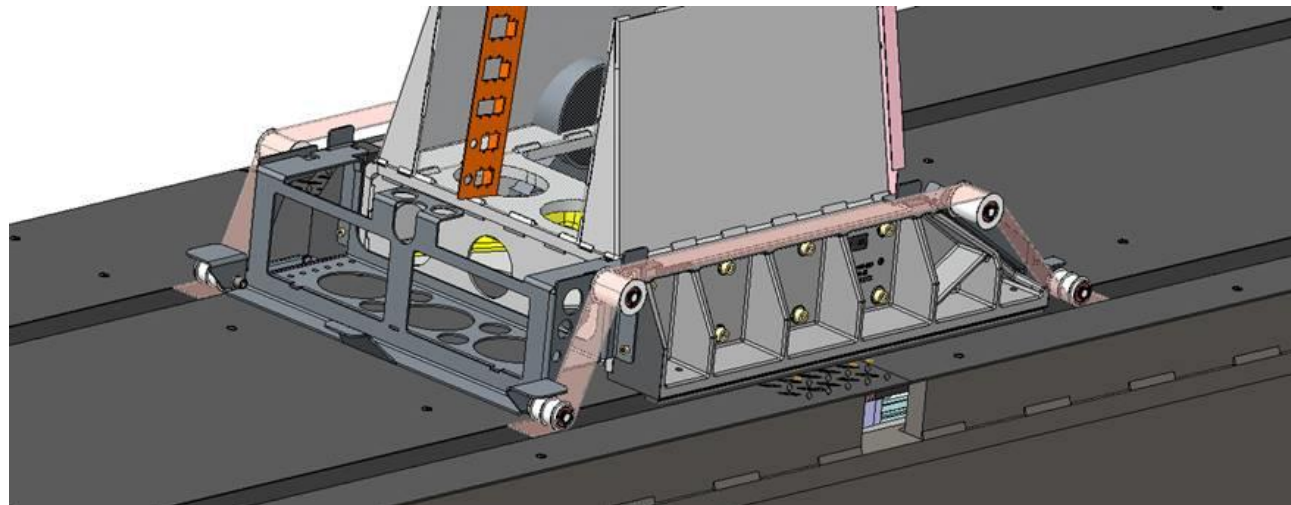


More than a Robot – The Hambot

PRO/ CALENO Improvements

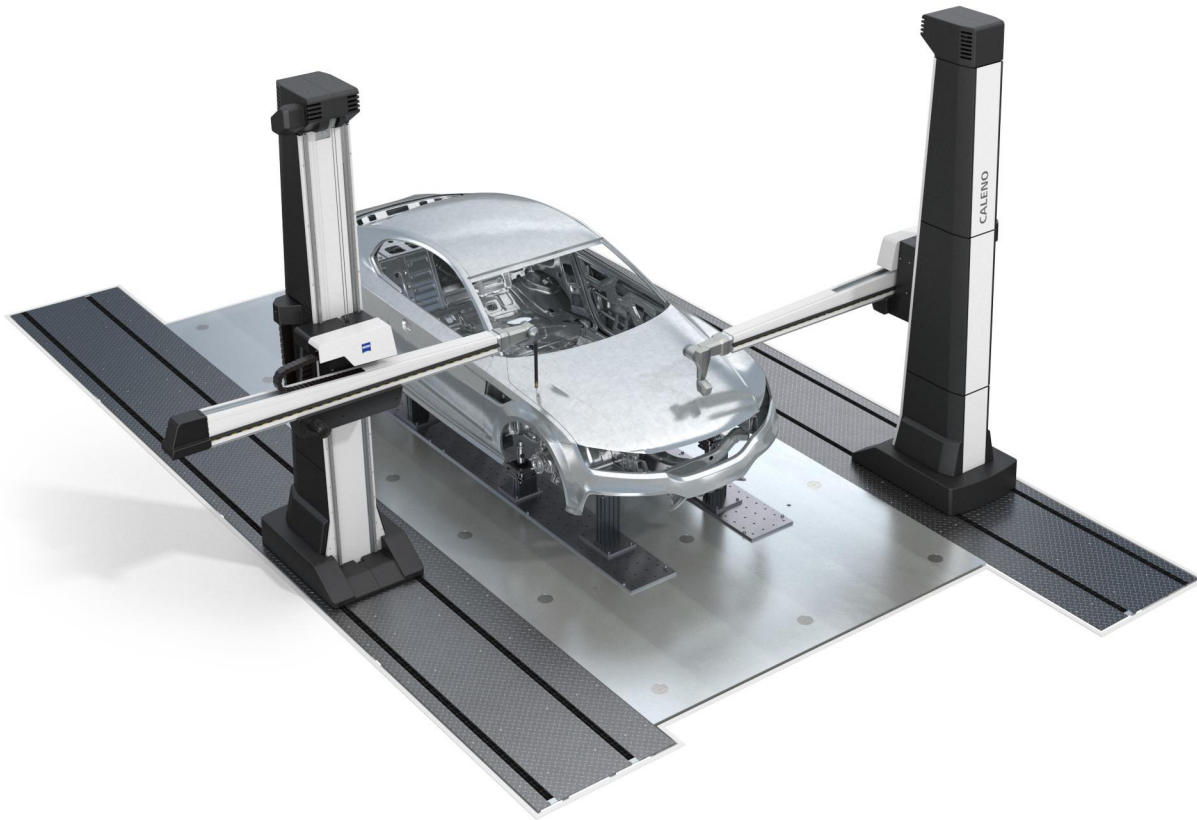


- New X-carrier
 - No welded dedicated X-carrier
 - Reduced complexity
 - Standard with gap covers



More than a Robot – The Hambot

What is new? Summary



- CALENO is a fully new developed Hambot (horizontal arm CMM)
 - New designed X-axis as a welded structure with integrated thermal decoupling
 - New Y/Z tower with trapezoid shaped axis and linear ball bearing in all axis
 - New counterbalance system for the column
 - New full covers as standard for improved thermal isolation, environmental protection and modern design
 - New non indexing sensor carrier DSC

ZEISS Multi Sensor CMMs for Car Body Applications

Articulation



More than a Robot – The Hambot

Indexing sensor carrier RDS-C6 CAA



More than a Robot – The Hambot

Indexing sensor carrier RDS-C6 CAA - Summary



Sensor carrier RDS-C6 CAA

- Indexing articulating probe holder

- CAA-calibration
 - For short calibration time
 - For maximum uptime of the CMM
- Step width of only 2,5°
- Position repeatability $\pm 1''$
- Maximum extension 400mm
 - For excellent accessibility even on complex parts
- Safety
 - Spring loaded probe plate with mechanical fall arrester
- Sensors
 - Touch trigger probes:
 - RST-P, TP6 und TP20
 - Optical sensor system FalconEye



More than a Robot – The Hambot

Non Indexing Swivel Head DSC



More than a Robot – The Hambot

Non Indexing Swivel Head DSC – Improvements CSC - DSC



Customer benefit

- Higher data rates for future optical sensor systems.
- Improved reliability.
- New, attractive design

Innovation

- New, improved bearings.
- Slip rings for A axis, n X 360°
- B axis $\pm 137,5^\circ$

Replacement for CSC and CSC-U2



More than a Robot – The Hambot

Non Indexing Swivel Head DSC – Differences CSC - DSC



DSC – non indexing probe holder

- Improved performance compared to indexing swivel head
 - XYZ movement and rotation at the same time
- Improved safety, due to additional collision protection of the probe plates
- If extensions longer than 400mm are required, e.g. truck cabins
- For the optical sensor system EagleEye with 6th axis
- Passive probe changer for reduced costs and improved reliability
 - Additional ports can be added
- Replaces the CSC



CSC probe changer with 4 ports



ZEISS Multi Sensor CMMs for Car Body Applications

Touch Trigger Probes



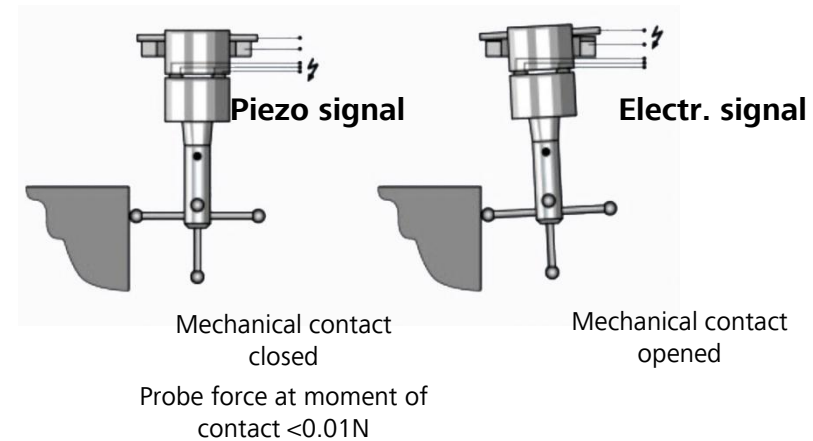
More than a Robot – The Hambot

Touch Trigger Probes Zeiss



RST-P Piezo Probe

- Dual principle of probing
 - first force-free Piezo probe impulse
 - then mechanical deflection
- Better reproducibility than Renishaw touch trigger probes
- Robust
 - Overtravel 26°
 - MTBF more than 5 million trigger
- Optimum universal probe due to
 - Stylus weight up to 10g
 - Stylus length up to 90mm
- Temperature stabilized invar body



More than a Robot – The Hambot

Touch Trigger Probes Renishaw



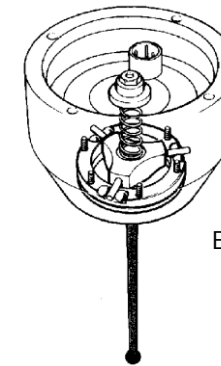
TP6

- Universal probe, if customer requests Renishaw
- More over travel than TP20
- Cheapest touch trigger probe
- Trigger force can be adjusted



TP20

- Stylus modules can be changed
- Small diameter
- Different probe modules available
- Standard delivery with one module medium force and one high force
- Due to the risk of false trigger, low force should not be used



Electromechanical switch

More than a Robot – The Hambot

Comparison Trigger Probes



	RST-P	TP6	TP20
Principle of function	Piezo	Electro mechanical switch	Electro mechanical switch
Trigger force in the moment of data capture X/Y	<0,01 N	0,11 - 0,3 N with stylus L=20mm	0,08N/ 0,25N/ 0,4N with stylus L=10mm
Trigger force in the moment of data capture Z	<0,01 N	??	0,75N/ 1,9N/ 3,2N
Max. possible stylus length	90 mm	50 mm	50 mm (high force)
Max acceptable stylus mass	10 g	5 g	5 g (high force)
Reproducibility	0,3 µm	0,35 µm	0,35 µm
Stylus length at specification	20 mm	20 mm	10 mm
Durability/ no. of trigger	> 5 Mio	> 1 Mio	> 1 Mio
Over travel X/Y	± 26°	± 22°	± 14°
Over travel Z	8 mm	5,5 mm	4 mm/ 3,7 mm/ 2,4 mm

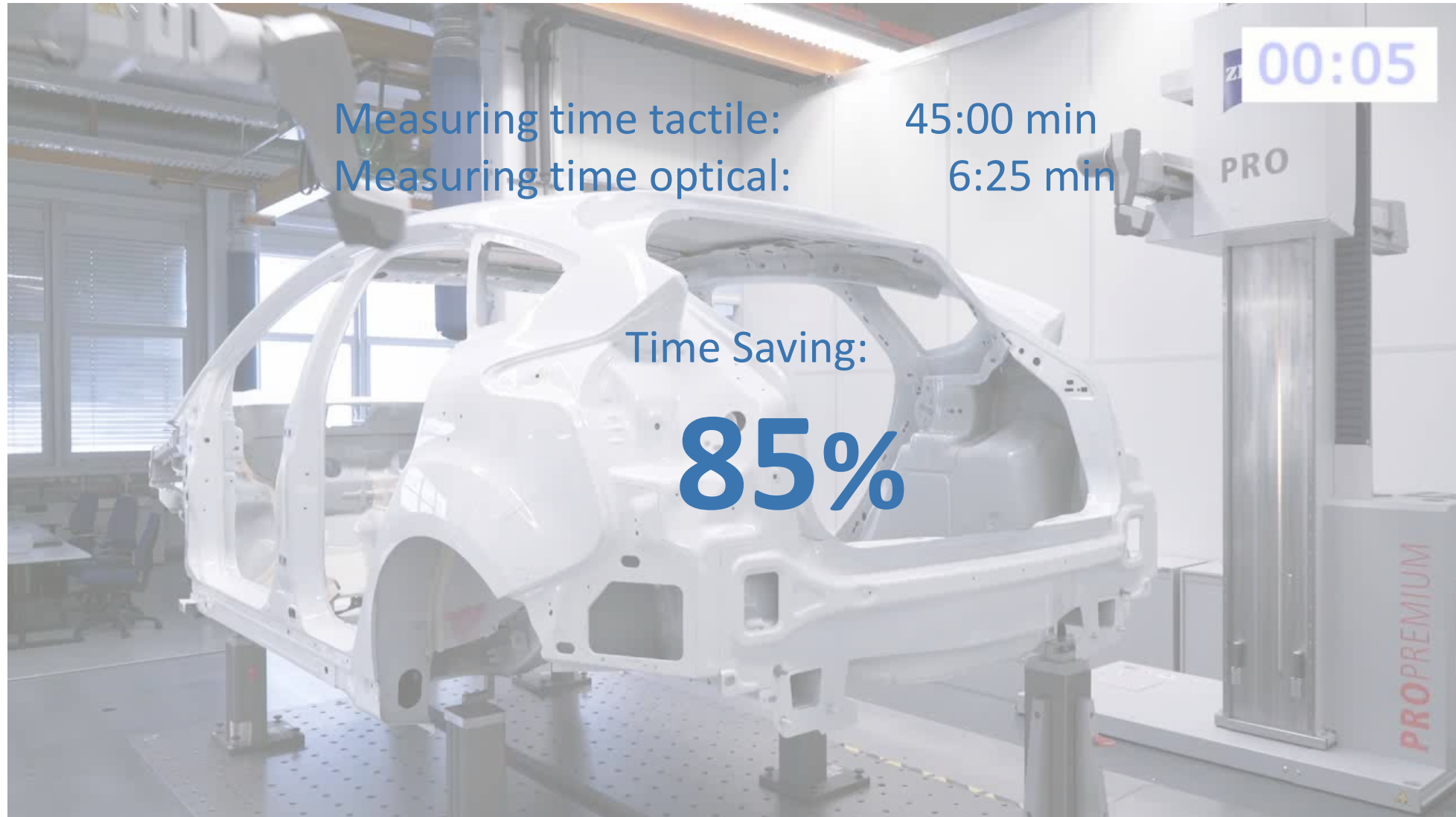
ZEISS Multi Sensor CMMs for Car Body Applications

Optical Sensor System EagleEye



More than a Robot – The Hambot

Productivity improvement with the EagleEye system

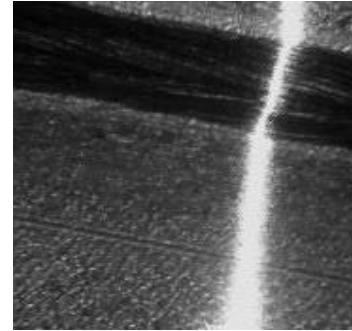


More than a Robot – The Hambot

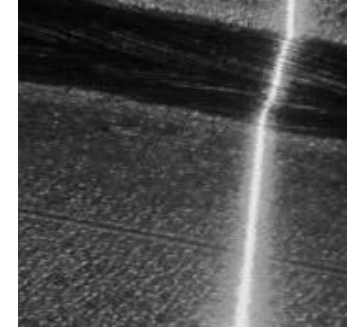
Ease of use



- Ease of use
 - by new camera technology
 - Very high dynamic range

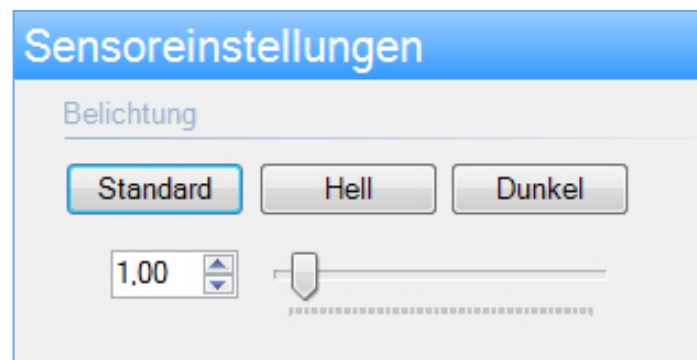


Without LinLog



With LinLog

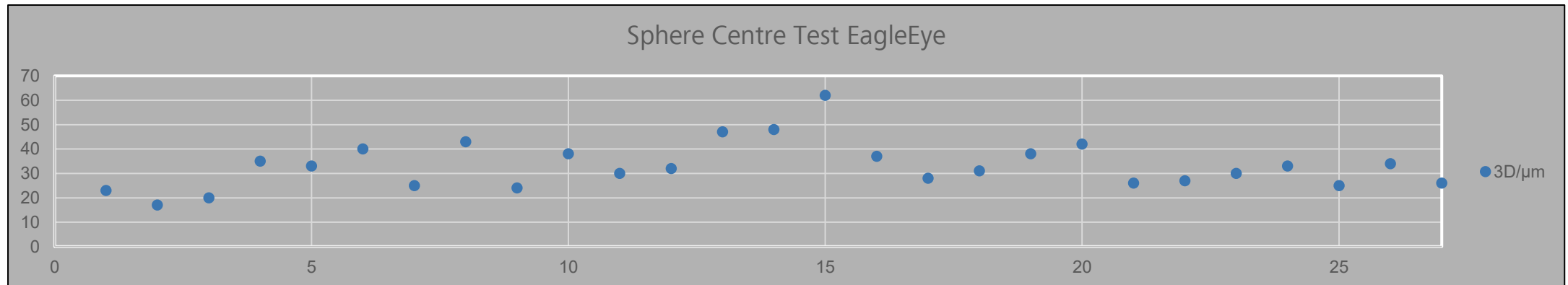
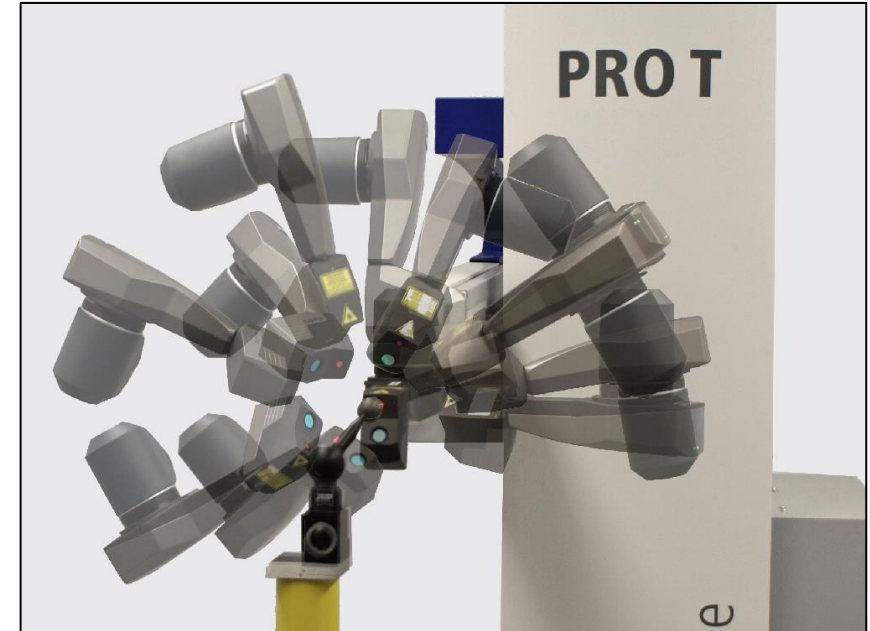
- Easy scanning of different materials



More than a Robot – The Hambot Accuracy



- Sensor accuracy: $20\mu\text{m}^1$
- System accuracy: $< 70\mu\text{m}^2$



¹ The accuracy of the sensor is defined as the maximum deviation of the X or Y center point of a sphere, measured in the measuring area of the sensor

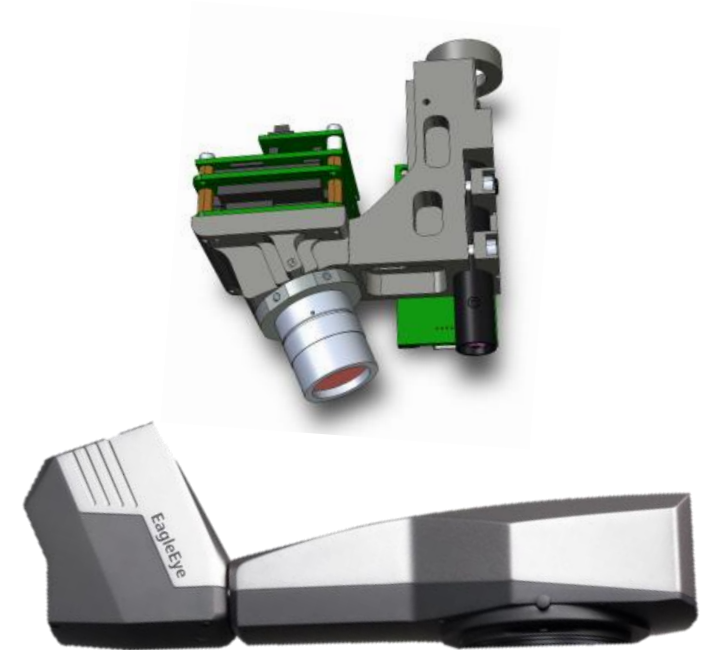
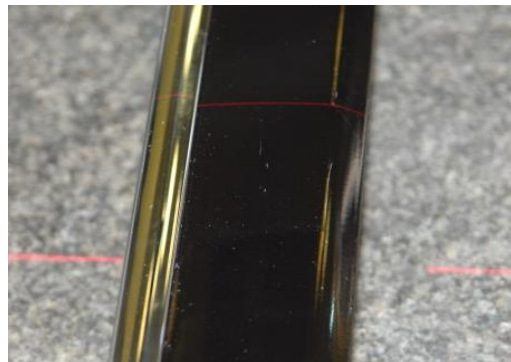
² Sphere center test on PRO premium 16/25. 29 angular positions of A-/B- and C-axis

More than a Robot – The Hambot

Robustness



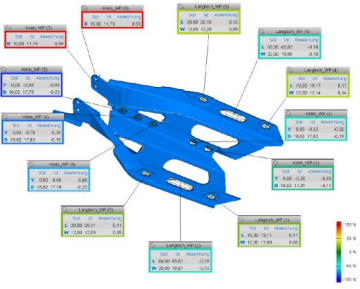
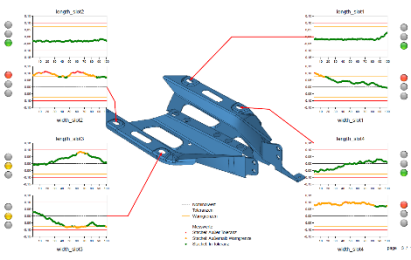
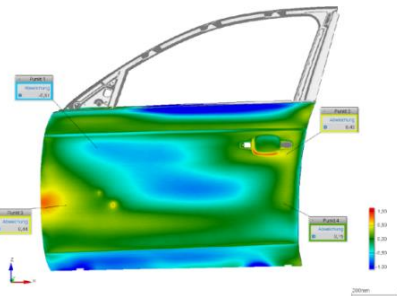
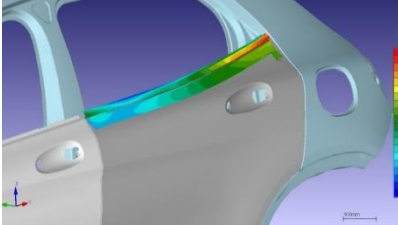
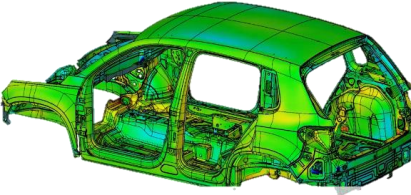
- Mechanically robust system without moving parts
- Body out of aluminum
 - Sensor
 - C-axis
- No spikes, even at critical geometries and materials
 - Due to LinLog Technology



More than a Robot – The Hambot

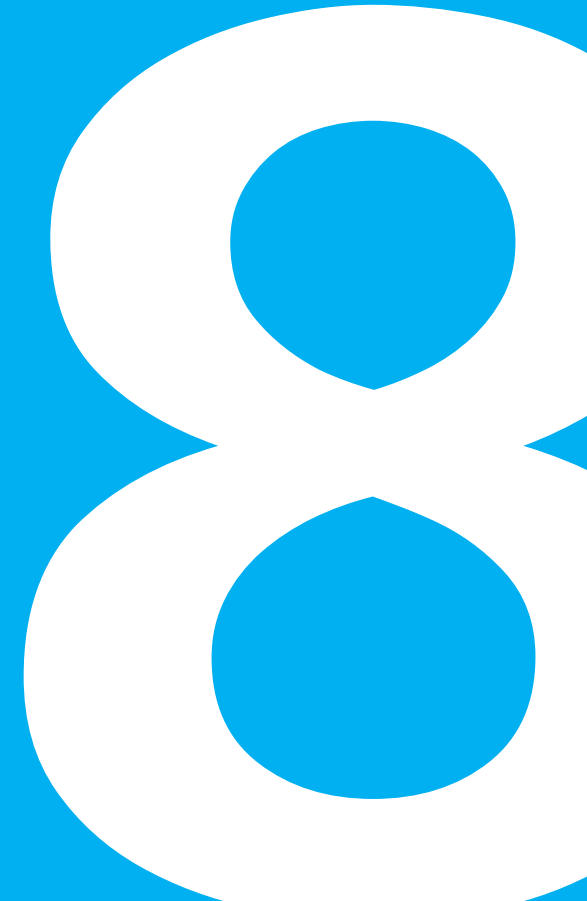
Description of the Application/ differentiation



				
Feature Analysis	Feature Serial Measurement	CAD Compare outer shell	CAD Compare problem analysis	Complete Scan for virtual Meisterbuck
<p>Individual features are measured in order to detect and correct problems. Feature measurement during product startup.</p>	<p>Process control based on test features and functional dimensions. Statistical evaluation of the results. Samples from the current series.</p>	<p>Essentially, the visible surfaces in the area of the outer skin are detected. There is no requirement to detect the inside of the components, or the structural areas.</p>	<p>A typical problem analysis with optical metrology is shown in the picture above. It is e.g. for leak tests in the area of the doors. For this purpose, only the information in this subarea is needed.</p>	<p>All components are recorded completely, ie inside and outside, in order to carry out virtual analyzes and simulations of the components to each other. For this, the deformations must be simulated by the dead weight of the components for the virtual masterbuck.</p>

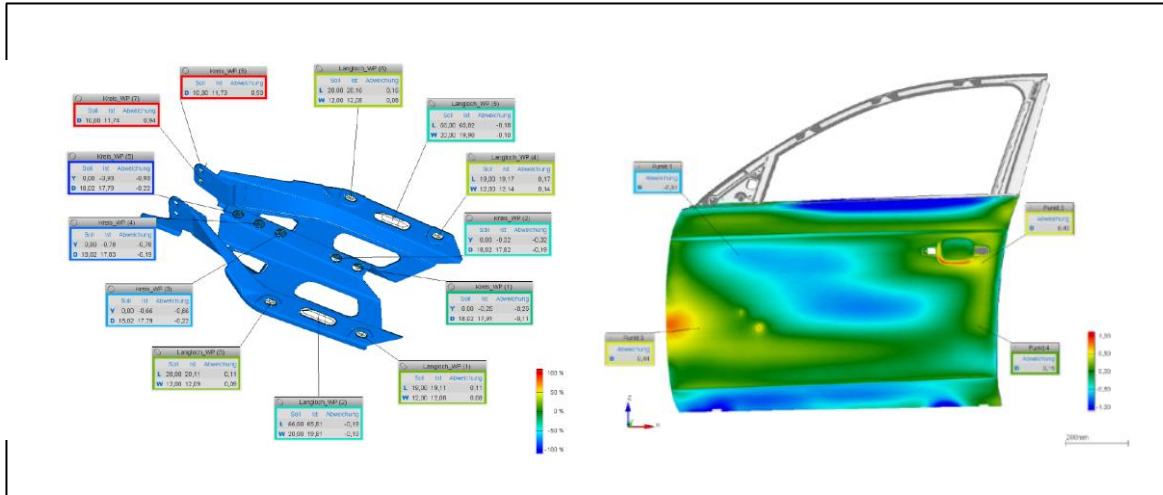
ZEISS Multi Sensor CMMs for Car Body Applications

Software



More than a Robot – The Hambot

ZEISS CALIGO - The software for freeform surfaces and features



02 Benefits // Highlights

- Easy to use software
- Path-in/Path-out
- Efficient software architecture for processing large data quantity
- Efficient change management
- Integrated simulation functions for off-line programming
- Collision protection by using automatic travel paths
- Including ZEISS PiWeb reporting (professional report creation)

01 Main application // description

- Efficient tool for testing and inspection freeform surfaces and standard geometries in car body construction
- Allow meaningful conclusions of car body reports
- Sectional view and 3D intersection curves
- Statistic analyses for processes and production means
- Management dashboards

03 Installation locations // facilities

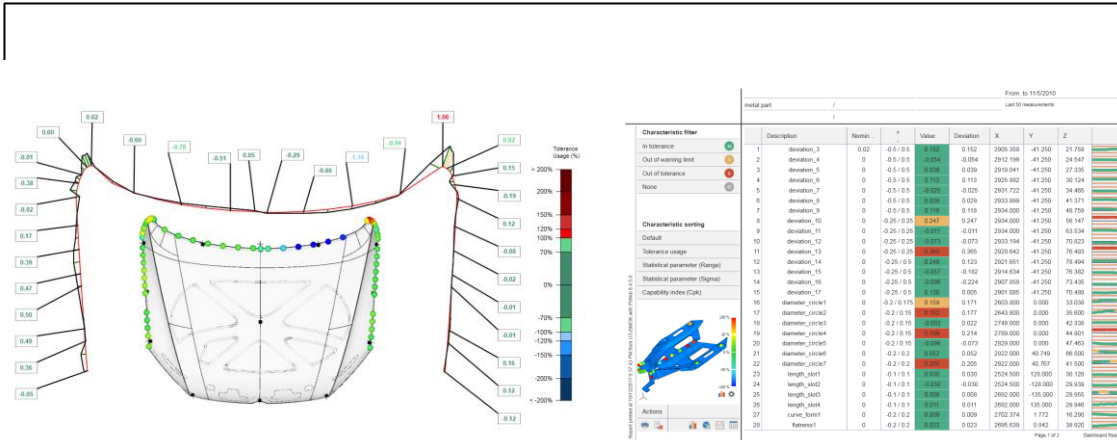
Facilities of automotive manufactures and suppliers:

- Individual parts, assembly (geometries, features, surfaces)
- Body construction (geometries, features, surfaces)
- Client/server installation is embedded in existing IT infrastructure



More than a Robot – The Hambot

ZEISS PiWeb - Quality data management



02 Benefits // Highlights

- Central data store with global data availability
- Tools for in-line data, fast creation of reports with large data
- User specific reports for QA and in-line (e.g. tool manufacturing, assembly, final assembly, management)
- Fast and intuitive handling and creation reports with drag and drop

01 Main application // description

- Interactive reports for complex data
- Allow meaningful conclusions of car body reports
- Sectional view and 3D intersection curves
- Statistic analyses for processes and production means
- Management dashboards

03 Installation locations // facilities

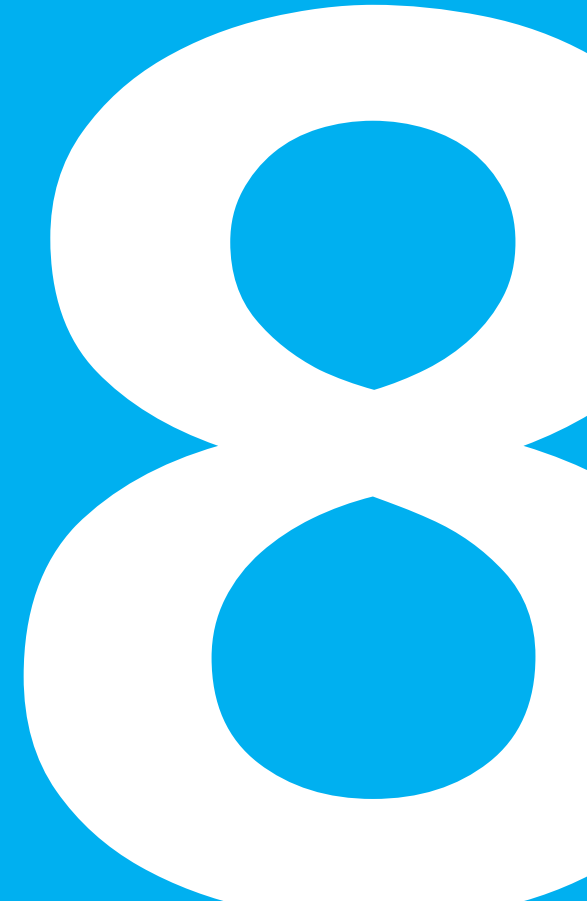
Facilities of automotive manufactures and suppliers:

- Individual parts, assembly (geometries, features, surfaces)
- Body construction (geometries, features, surfaces)
- Paint shop (gap-and-flush measurement after painting)
- Final assembly (gap-and-flush measurements for fully assembled vehicles)
- Client/server installation is embedded in existing IT infrastructure



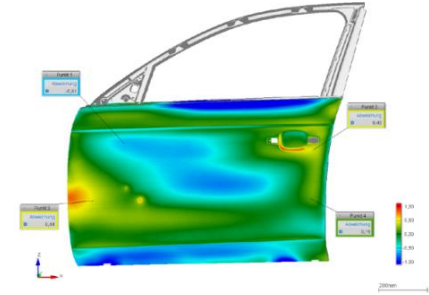
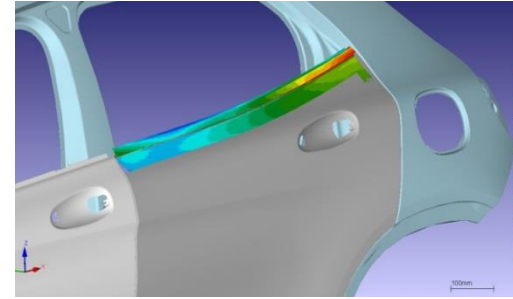
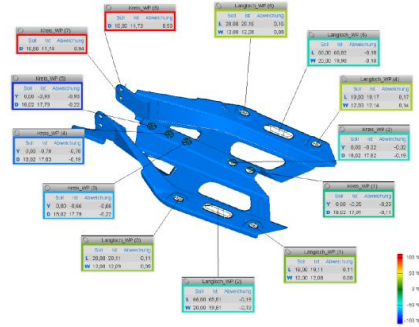
ZEISS Multi Sensor CMMs for Car Body Applications

Applications



More than a Robot – The Hambot

Analysis of press parts, assemblies and BIW



In which phase is being measured?

- Part qualification for start up phase of production
- Fast analysis in the series

What will be measured?

- Press parts, hanging parts, up to the complete body-in-white.

How will be measured?

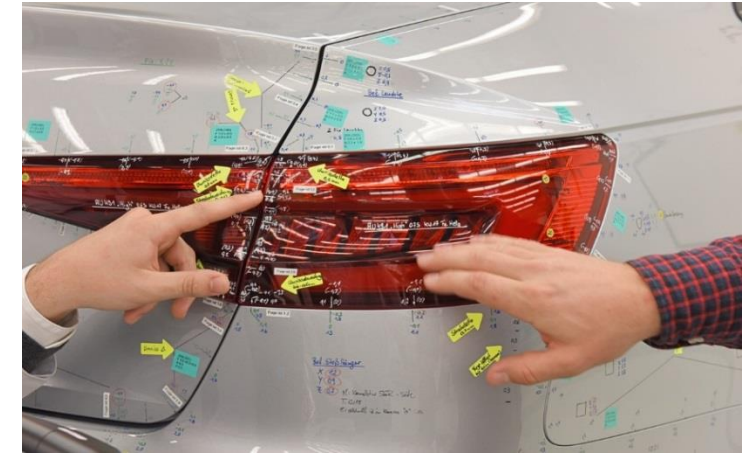
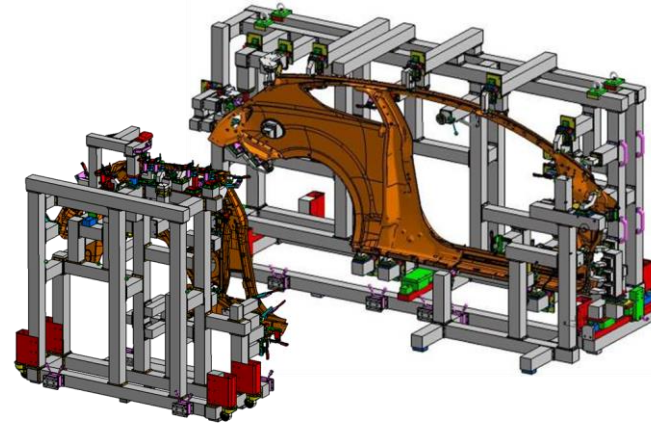
- Fast, tactile and optical feature measurement
- CAD compare for problem analysis.
- Digitization

How to create the measuring programs?

- Offline, with simulation for the start up phase
- Direct at the CMM for problem analysis

More than a Robot – The Hambot

Meisterbock analysis and finished car analysis



In which phase is being measured?

- Part qualification for start up phase of production
- Fast analysis in the series

What will be measured?

- Verification of the dimension of the individual components.
- Verification and analysis of quality, flush&gap, optics, haptics, function and assemblies capability.

How will be measured?

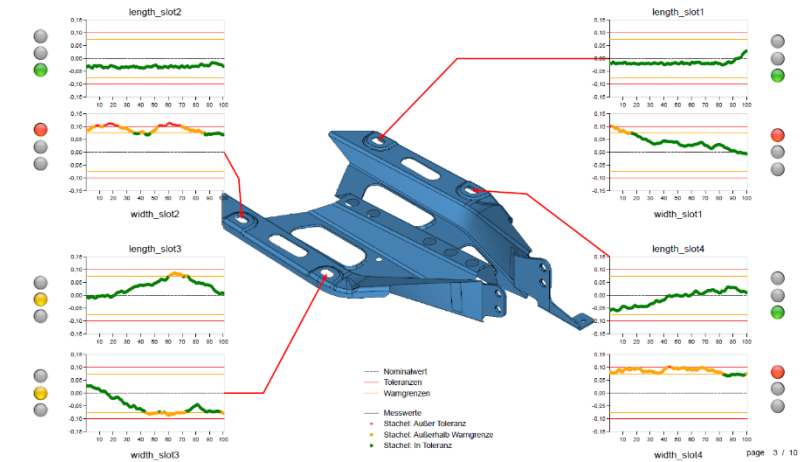
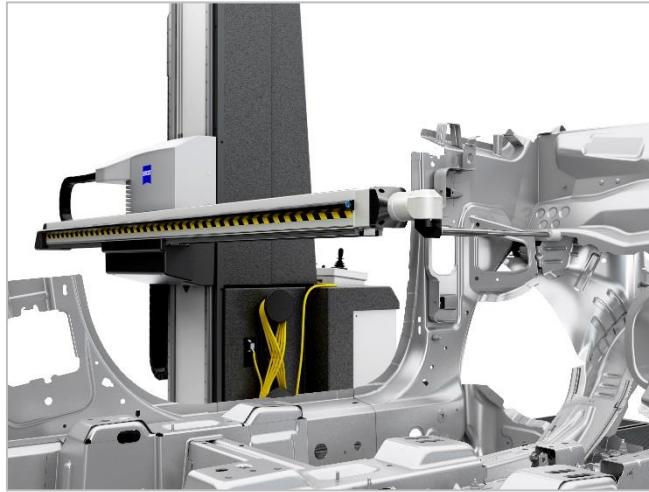
- If necessary, tolerances, construction and design issues can be discussed on the Meisterbock with parts, data and reports

How to create the measuring programs?

- Direct at the CMM for problem analysis

More than a Robot – The Hambot

Serial measurement BIW



In which phase is being measured?

- Fast process control in serial production

What will be measured?

- Body-in-white and hanging parts

How will be measured?

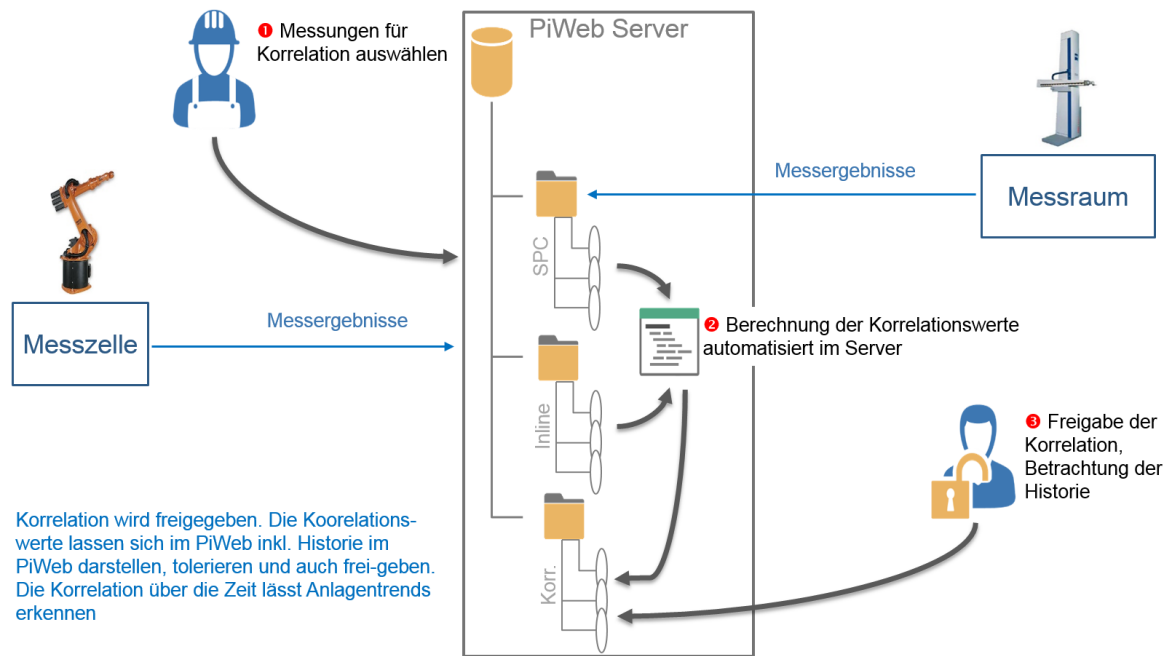
- Direct measurement of geometrical features with optical or tactile sensor.

How to create the measuring programs?

- Central creation of measuring programs, or at offline stations in the measuring room.

More than a Robot – The Hambot

Serial measurement BIW – Correlation for Inline Measurement



In which phase is being measured?

- Correlation for inline measurement

What will be measured?

- Body-in-white and hanging parts

How will be measured?

- Direct measurement of geometrical features with optical or tactile sensor .

How to create the measuring programs?

- Central creation of measuring programs, or at offline stations in the measuring room.

ZEISS Multi Sensor CMMs for Car Body Applications

Portfolio Overview



More than a Robot – The Hambot

Portfolio Overview



Performance CMMs

Premium CMMs

Flush to floor



CALENO RDS C6-CAA



CALENO DSC



CALENO DSC
with optical sensor system EagleEye,
Option HA and HP

Table version



CALENO T RDS C6-CAA

CALENO T DSC



CALENO T DSC
with optical sensor system
EagleEye,
Option HA and HP

Upgrade concept of CALENO T and CALENO up to highest specification

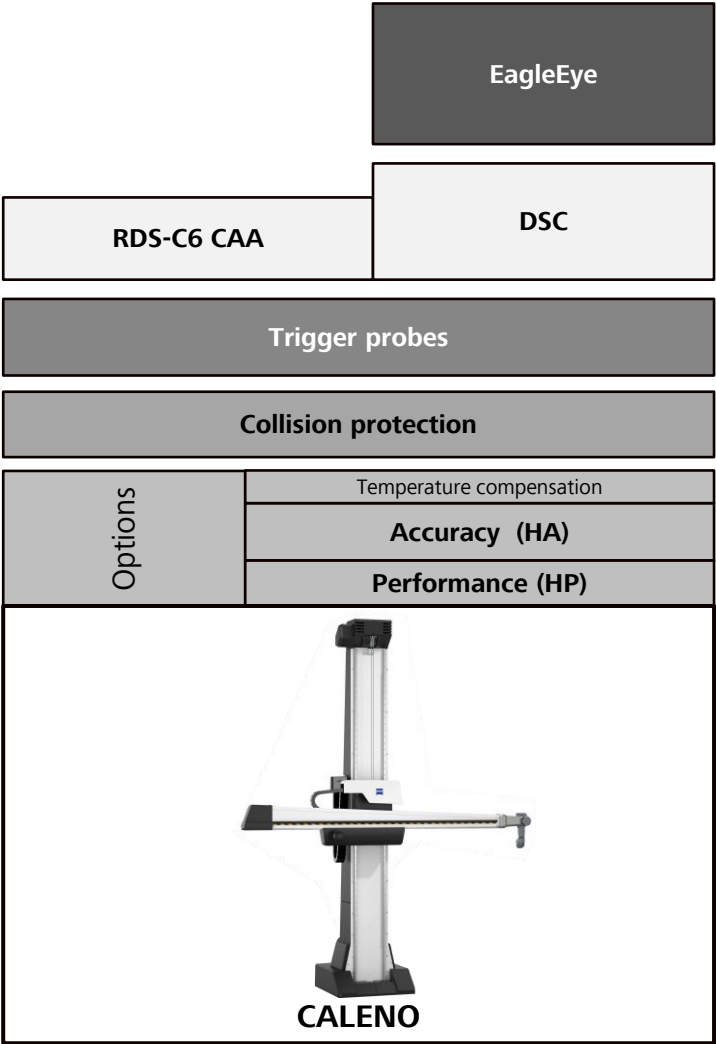
Speed, better accuracy sensor carrier, optical sensor

Application

Performance

More than a Robot – The Hambot

The platform strategy



More than a Robot – The Hambot

The platform strategy



CALENO / CALENO T	
Accuracy for 16/25	27+L/80≤70
Option High accuracy	18+L/125≤50
Measuring range X	3.000 - 25.000
Measuring range Y	1200 ¹ , 1600, 1800 ²
Measuring range Z	2100, 2500, 3000 ²
Max acceleration	1000mm/s ²
Option performance	1500mm/s ²
Max. Travel speed without light barrier	260mm/s
Max. Travel speed with light barrier	866mm/s ³
Sensor Carrier	RDS-C6, indexing 2,5°/ DSC, continuous
Max. probe extension RDS (indexing)	400mm
Max. probe extension CSC (continuous)	800mm
Tactile probes	TP6/ TP20/ RST-P
Optical sensor CSC	EagleEye
Covers	Full covers

ZEISS Multi Sensor CMMs for Car Body Applications

Summary

10

More than a Robot – The Hambot

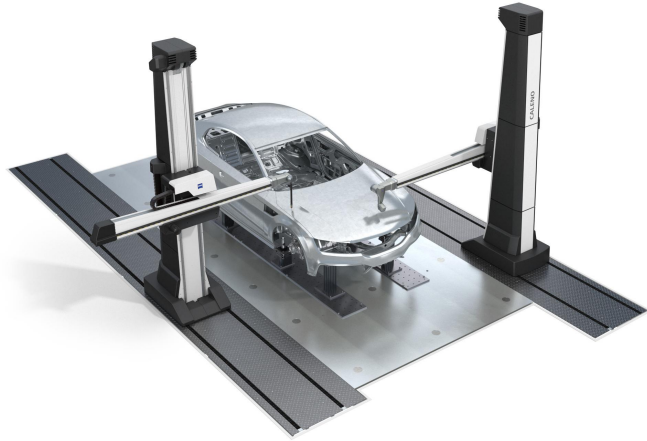
Summary



- Modular platform concept of the CALENO / CALENO For an optimized adaption of the CMM to the customer needs
 - The CMM can be upgraded with modules like high speed and high accuracy
- Flexible installation
 - Flush to floor with CALENO
 - Side mounted table version CALENO T
- Highest precision and highest productivity
- Robust and service-friendly
- RDS C6 – CAA, DSC
 - the benchmark for indexing and continuous articulating heads
- Machine and operator safety
- Maximum flexibility of the measuring range
- Technology from one source: ZEISS



More than a Robot – The Hambot Solutions



CALENO RDS-C6 CAA Duplex

Typical for OEMs with small and medium quantities or pure analysis systems

- Analysis
- Process control series and correlation – low and mid volume
- Meisterbock CMMs
- Finished car analysis



CALENO T Single/ Duplex

Typical for 1st Tier

- Analysis of press parts and hanging parts
- Serial measurement, e.g., battery trays in production environment



CALENO DSC Duplex

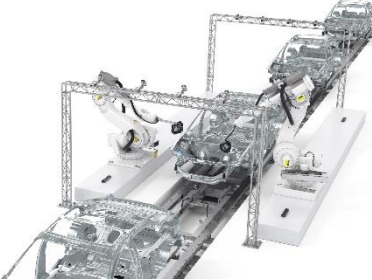





Typical for big OEMs

- Analysis
- Process control series and correlation – high volume
- Meisterbock CMMs
- Finished car analysis

More than a Robot – The Hambot

Hambot und Scanbox: Differentiation of the two measuring systems Inline/Atline/Offline



		Strength: Metrology Feature extraction	Strength: Digital Twin Full part scanning	Process control	Metrology & Digital Twin
Inline 01	Measuring of individual modules and full part digitization of assembled parts and complete bodies // e.g. 54 sec.	AICell trace 	ATOS Inline 		
Atline 02	Complete optical scans for CAD comparison e.g. of attachments // within 10 to 15 min..	Hambot – CALENO 	ATOS ScanBox 		
Offline 03	Precise analysis of any carbody part. Highly precise and optically efficient. // from a few min. to hrs.	Hambot – CALENO 	ATOS ScanBox 		



Seeing beyond