



LCLCTC SK Series Built In Speed Controller User Manual

Home » LCLCTC » LCLCTC SK Series Built In Speed Controller User Manual



Contents

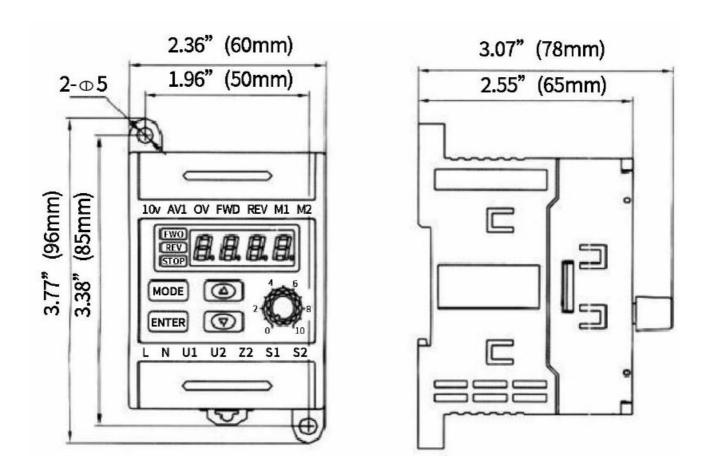
- 1 LCLCTC SK Series Built In Speed Controller
- **2 DIMENSIONS**
- 3 Instructions for Use
- 4 Features
- 5 Wiring Diagram for SK Series Built-in Speed Controller
- **6 Running Capacitor Specifications**
- 7 SK Series Built-in Variable Speed Controller Menu
- 8 Troubleshooting
- 9 Documents / Resources
 - 9.1 References

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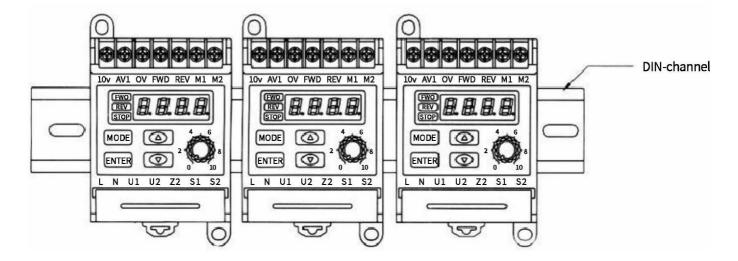
LCLCTC SK Series Built In Speed Controller



DIMENSIONS



SK Series Built-in Speed Controller Outline and Installation Diagram



Instructions for Use

- Do not use in explosive environments, flammable gas environments, corrosive environments, or places that are prone to getting wet or near combustible materials.
- Avoid continuous vibration and excessive impact.
- During normal operation, the surface temperature of the motor casing may exceed 70°C. Therefore, please affix the warning sign shown in the image on the environments where contact with the motor is possible.
- Please ensure that the grounding terminal is properly grounded.
- Installation, connection, inspection, and other operations should be carried out by professional technicians.

Thank you for purchasing and using this product. To ensure safety and proper operation, please read this user manual before installing and using the product!

Features

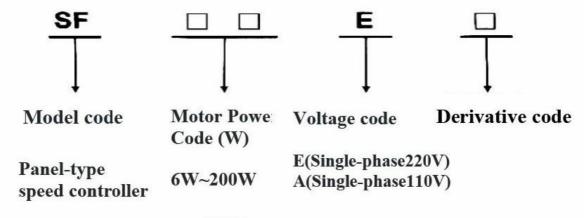
- Utilizing MCU digital control technology, this product features rich functions and outstanding performance.
- Featuring a digital display menu-driven interface, it allows for convenient and quick modification of settings.
- It can set the display magnification according to the user's display needs and automatically convert the displayed target value.
- It can achieve complex motion control such as slow acceleration, slow deceleration, quick stop, and four-speed levels.
- External switch control and 0-10V analog control are available.
- Analog control can automatically match the maximum rotational speed, making adjustment and control convenient and safe.
- A stall protection function is provided to prevent the motor and speed controller from burning out due to lockedrotor conditions.

Model Array List

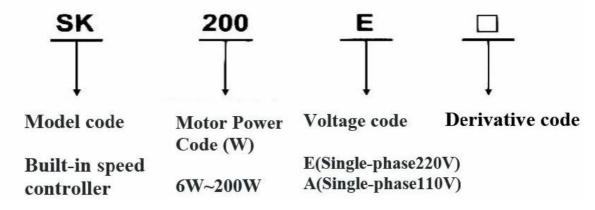
Category Category Motor Power Voltage	SF Series Panel Mounted Variable Frequency Drive		SK Series Built-in Variable Frequency Drive		
Motor Power Voltage	220V	110V	220V	110V	
6w	SF06E	SF06A			
15W	SF15E	SF15A			
25W	SF25E	SF25A			
40W	SF40E	SF40A	CIVOLOD	GWOOD A	
60W	SF60E	SF60A	SK200E	SK200A	
90W	SF90E	SF90A			
120W	SF120E	SF120A			
200W	SF200E	SF200A			

Model Naming Method





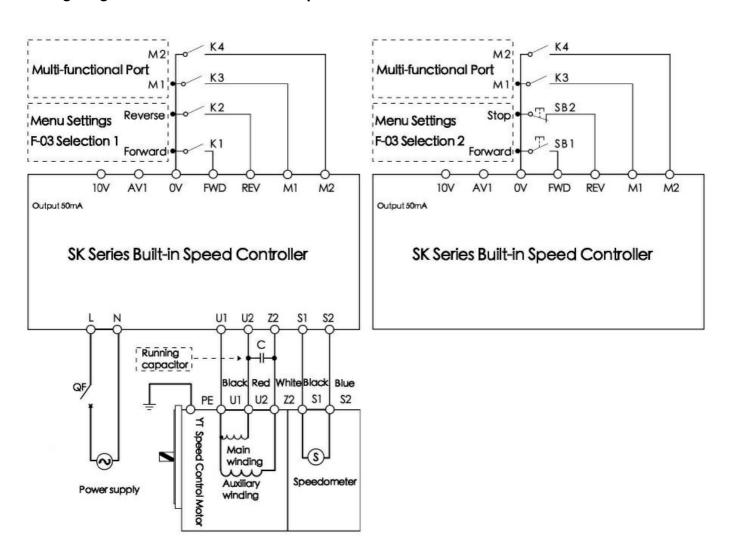
O Built-in type:



Performance parameter table

				_		
Model number	SF□□E	SF□□A	SK200E	SK200A		
Installation method	Panel-	type	Built-in type			
Power supply voltage	Single-phase 220V	Single-phase 110V	Single-phase 220V	Single-phase 110V		
Power supply frequency		50/60 Hz				
Applicable motor type	YT Series Variable Speed Motor					
Operating capacitance	Built-in (built insid	le the speed controller)	External (placed inside the packaging of the variable speed motor, requiring user connection)			
Motion control function		ration control, speed regulation, and slow deceleration	External switch operation control, speed regulation, slow acceleration, slow deceleration, quick stop, 4-speed levels			
Speed regulation method	Panel "▲"、"▼" key; Panel Knob Panel "▲"、"▼"key; Panel Knob; 0~10V Analo			Knob; 0~10V Analog Signal		
Speed control range	90~3000 r/min. (User can set based on motor pole number, power frequency, and usage requirements.)					
Operating environment	Ambient temperature: -10°C~+45°C (no freezing), ambient humidity: below 85% (no condensation).					

Wiring Diagram for SK Series Built-in Speed Controller



QF Circuit Breaker Specification Sheet

Power supply voltage	Motor power	QF current specification
220V	6~90W	1 A
220V	120~200W	2A
11 0V	6~90W	3A
11 0V	120~200W	4A

- The power supply voltage must be consistent with the voltage specification of the speed controller.
- QF is a circuit breaker that protects the speed controller and motor when a short circuit occurs.

Running Capacitor Specifications

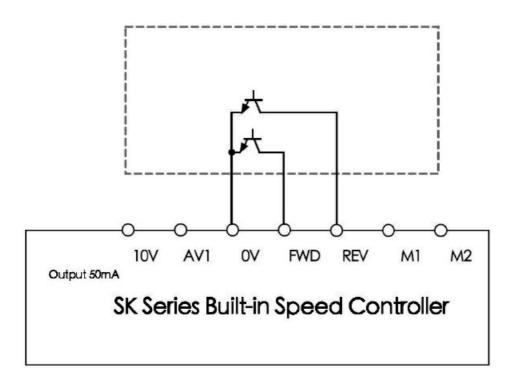
Power supply voltage Motor power	220V	220V
6W	0.7µF/450V	2.5µF/250V
15W	1µF/450V	4µF/250V
25W	1.5µF/450V	6µF/250V
40W	2.5µF/450V	10µF/250V
60W	3.5µF/450V	14µF/250V
90W	5µF/450V	20µF/250V
120W	6µF/450V	24µF/250V
200W	10µF/450V	40µF/250V

Note: The running capacitor should be selected according to the motor model and placed inside the variable speed motor package.

The maximum output current of the 10V port is 50mA.

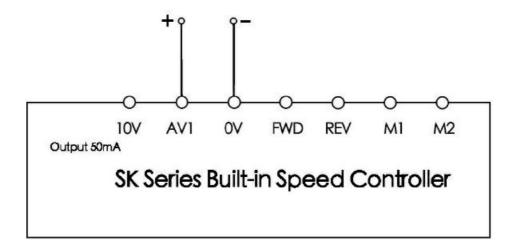
Programmable Logic Controller (PLC)

- 1. The control ports of FWD, REV, M1, and M2 are controlled by a Programmable Logic Controller (PLC)
- 2. NPN or open collector transistor output



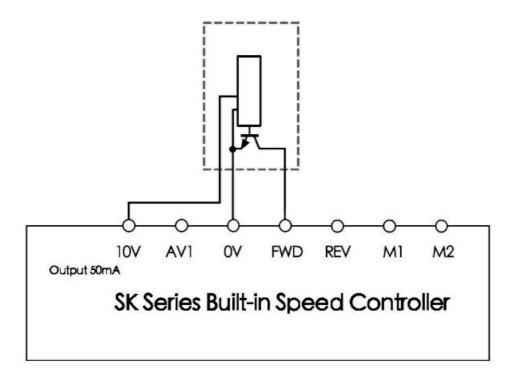
0-10V analog control

- 1. Use external 0-10V analog control to regulate motor speed.
- 2. Menu settings: Set F-06 to 3 for external 0-10V analog control.



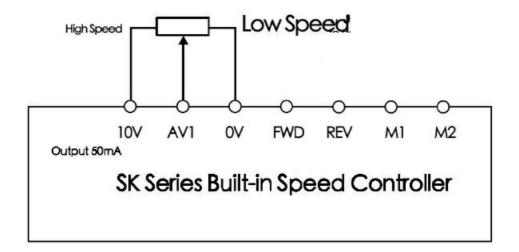
Sensor

- 1. The FWD, REV, M1, and M2 control ports are suites do shots oct riches. etc.
- 2. Switch output mode: Three-wire NPN transistor output.



5k Speed Potentiometer

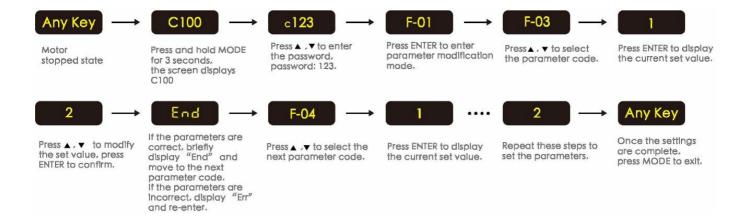
- 1. Use an external speed potentiometer To control the motor speed.
- 2. Menu settings: Set F-06 to value 3 for external 0-10V analog control.



SK Series Built-in Variable Speed Controller Menu

Menu Modification

Note: To ensure safety, parameter modifications for F-03, F-05, and F-29 must be performed when the motor is in a stopped state Otherwise, the settings cannot be applied and the screen will display "**Err**".



SK Series Built-in Speed Controller Menu List

Paramete r Code	Parameter Function	Setting Range	Function Description	Fac tor y Def aul t Va lue	Us er Set Val ue
F-01	Display Co ntent	1. Motor Speed Set Value 2.Rati o Speed Set Val ue	Ratio Speed Set Value= Motor Speed Set Value+ Rat io	1	
F-02	Ratio Settin	1.0-999.9	Set according to the display intuitiveness, displaying the target value.	1.0	
F-03	Operation Control Mo di	Forward/Reverse Foiward/Stop	electing Foiward/Reverse, the motor is controlled by s witches KI and IC.2.Selecting Foiward/Stol the motor i s controlled by buttons S81 and S82.	, 1	
F-04	Rotation M ade	1. Allow Forwar d and Reverse Rotation 2. Allow Forwar d Rotation. Disa ble Reverse Rot ation 3. Allow Revers e Rotation, Disa ble Forward Rotation	Limit motor rotation direction to prevent equipment m alfunctions or accidents. When F-03 is set to 2. F-04 is automatically set to 2 and cannot be changed. If the rotation direction needs to be changed. it can be set by F-05.	1	

F-05	Rotation Dir ection	1.No reversal 2. Reversal	No need to change motor wiring, easily change the motor rotation direction to match habits or requirements .	1	
F06	Main Speed Adjustment Method	1.Pane bu tton 2.Panel lc:: nob 3.Extern6l -10V analog input	 When any multifunction terminal MI, M2 is closed, the motor operation is segmented speed and the main speed adjustment is invalid. The panel Ic::nob and external 0-1OV analog input automatically match from O to the maximum speed. When an external speed control potentiometer is connected to the 0-10V analog input AVI. The main speed adjustment method, F-06, should be set to 3. 	1	
F-07	Maximum S peed	500-3000	Limits the maximum motor speed to prevent overspeed. damage, or accidents. For a 50Hz power supply, the maximum speed is UOO, and for a 60Hz p ower supply, the maximum speed is 1600. If the maximum speed exceeds these values, the motor may overheat and vibrate.	140	
F-0B	Minimum S peed	90-1000	Limits the minimum motor speed to prevent unstable speed. overheating, and overload caused by running at low speeds.	90	
F-09	Forward St art Acceleratio n Time	0.1-10.0s	Longer time results in a smooth and gradual motor st artup. Shorter time results in a fast and a ggressive motor startup.	1.0	
F-10	Forward St op Mode	Free deceleration sto p 2.Quiclc:: stop Slow deceler ation stop	 If free deceleration stop is selected, and the motor stops slowly. To choose quick:: stop, change the F-11 setting value to adjust the speed of quick:: stop. If free deceleration stop is selected, the motor stop s quickly. To choose slow deceleration stop, change the F-12 setting value to adjust the speed of slow deceleration stop. 	1	
F-11	Quick:: stop intensi ty during th e forward st op.	1-10	When F-10 is set to 2, the menu is effective. The larg er the value, the faster the stop.	5	
F-12	Slow decel eration time during a for ward stop.	01-10.os	When F-1O is set to 3. the menu is effective. The larg er the value. the slower the stop.	1	

	Time for ac		IA longer time results in a gentle motor start, with a lo	
F-13	celeration d uring revers e start	01~10.0S	a fast and aggressive motor start. with a shorter start up time.	1.0
F-14	Reverse st opping met hod	Free Deceler ation Stop Quick Stop Slow Deceler	 If the free deceleration stop option is selected, the motor will stop slowly, You can choose the quick stop option by changing the F-15 setting to adjust the spee d of the quick. stop. 12-the free deceleration stop option is selected, the m otor will stop quickly. You can choose the 15l0w decel eration stop option by changing the F-16 setting to adj 	1
		ation Stop	ust the speed of the slow deceleration stop.	
F-15	Quick stop i ntensity dur ing reverse stop	1~10S	When F-14 is set to 2, the menu is active. The larger the value, the quicker. er, the stop.	5
F-16	Time for slo w deceleratio n all in revers e ston	1-10s	When F-14 is set to 3, the menu is active. The larger the value, the slower the stop.	1.0
F-17	First Speed Range	Minimum soeed – Maximum soe ed	When multifunction terminal M1 is closed, the motor o perates at the first speed.	500
F-1B	Second Sp eed Range	Minimum speed – Maximum spe ed	When multifunction terminal M1 is closed, the motor o perates at the first speed.	700
F-19	Third Spee d Range	MinimLm speed Maximum spe ed	When both multifunction terminals M1 and M2 are clo sed, the motor operates at the third speed.	900
F-29	Restore Fa ctory Settin gs	Do not restor e Restore facto ry settings		1
F-30	Program Ve rsion	Code+ Version		02

Fault Alarm Er-1

- 1. Overload or blockage.
- 2. Abd the motor or tie heme, capacitor troller,

Troubleshooting

- 1. Check and eliminate the faults.
- 2. Power off and restart to clear the alarm.

Documents / Resources



<u>LCLCTC SK Series Built In Speed Controller</u> [pdf] User Manual SK Series Built In Speed Controller, SK Series, Built In Speed Controller, Controller

References

User Manual

Manuals+, Privacy Policy

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