

# GuardforceA PR1120B008F6 Al Reception Robot User Manual

Home » GuardforceA » GuardforceA PR1120B008F6 Al Reception Robot User Manual



#### Contents

- 1 GuardforceA PR1120B008F6 Al Reception **Robot**
- 2 product introduction
- **3 Function Introduction**
- 5 Documents / Resources
- **6 Related Posts**



GuardforceA PR1120B008F6 AI Reception Robot



# product introduction

Al Reception Robot is an indoor intelligent service robot used in office buildings, restaurants, hotels, hospitals, exhibition halls,shopping malls and other places. It can provide contactless temperature measurement, voice interaction, information release and other services,which can improve the the service efficiency and safety management and reduce the overall service cost for clients.

1.1ProductFunctions			
Module	Function	Introduction	
	Solicitation spare time	When the robot does not interact with each other, the solicitation once, audiofile or an imation is played for solicitation.	
Attraction	Advertising	Configureadvertisementsinvideoandpictureformatsontheplatf orm forrotation.	
	Body temperture measur ement	After recognizing the face, perform body temperature detection and broadcast the detection result.	
Temperature me asurement	Minimumtempera- turesetting	The minimum temperature can be set, the default is 36°C, and (0.1 - 0.3) will be increased a random fit is lower than 36°C.	
	Normal body temper nat ure will not be broad cast ed	This function is used for temperature measurement. It is enabled by default and cannot bed is abled. Normal tempera- true will not be broadcasted.	
Broadcasting	Abnormal tempera- true broadcast	This function is used to broad cast the ab normal bodytempera- tr ue of the users. It is enabled by default and cannot be disabled. Ab normal temperature will be broadcasted.	
Mask	Mask reminder	When no mask is detected, the visit or will be reminded of wearin g mask by the voice and interface.	
Robot wakeup	ouch screewakeup	Click Wakeup button to wake up.	

Reception	Greetings	When some one approaches the robot about 1.5meters ,the robot will lbroad cast the greetings.
Merchant introd uction	Merchant introduction	Merchant introduction.
Consultation ser vice	Consultation service	It is used to answer questions that users will consultinvarious sce nes. The user scan configure Q&A services and consulting services the GFAII CP Robot Operation&Management Platform to provide intelligent consulting and answering services for users.
Information display	Content/pro- duct/comm odity introduction	It is used to introduce the content in various scenes, such as the d ining menu, the room type of the hotel, and the exhibits in the exhibition hall, etc., by means of pictures, videos and text.

1 .2 Scene Application			
	Recommendation	It is used for cuisine and activity recommendation in the dining sc ene.	
	Menu	It is used for menu display and cuisine query in the dining scene.	
Dining module	Query	Query It is used for FAQ query in the dining scene.	
	Activity	It is used for cuisine and activity recommendations in the dining s cene.	

# **Function Introduction**

#### Power-on/off

Power-on

Note the following points before power-on:

- 1. Please ensure that 4G signal or WIFI signal of the robot is normal and stable and can access the Internet before power-on.
- 2. Please make sure the power supply of the robot is normal before power-on.

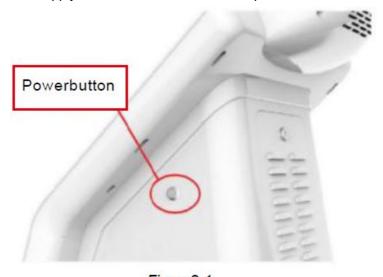


Figure2-1

Short press Power button and release it when a beep sound is made. The button light is on, the robot is powered on, and the screen displays the start up picture (left picture below), the main page of the the robot is started, and the robot enters the temperature measurement interface by default (right picture below), indicating that the soft start up is successful.



Figure2-2

#### Power-off

Hold down Power button and release it until three long beep sare made. When the button light is off and the screen isoff, the soft power-off of the robot is successful.

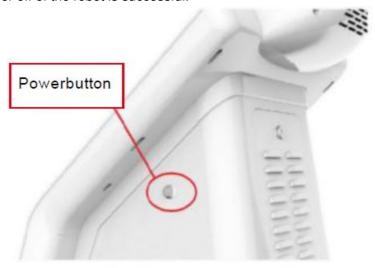


Figure 2-3

After soft power-off, some hardware inside the robot still works normally. If you want to completely power off the robot, please unplug the power cord for hard power-off after softpower-off.

Note the following points afterpower-off:

- 1. Place the robot in the designated safe position and cut off the powersupply.
- 2. Protect the robot and ensure that the robot is kept in a dry and clean environment..

#### **Network Configuration**

Enter the [main interface] of the robot, click the redbox button as shown in Figure 2-4 below, enter [Settings], enable WIFI, find the corresponding WIFI name in the WIFI list, and enter the password to connect. After the connection is successful, "Connected" is displayed under the WIFI name.

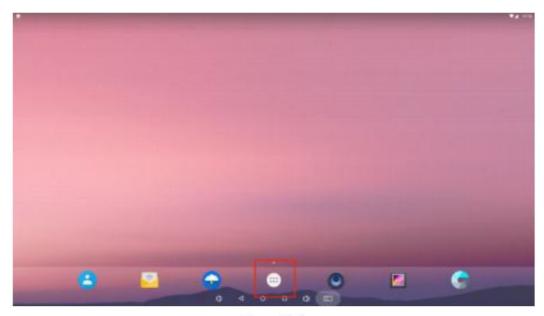


Figure2-4

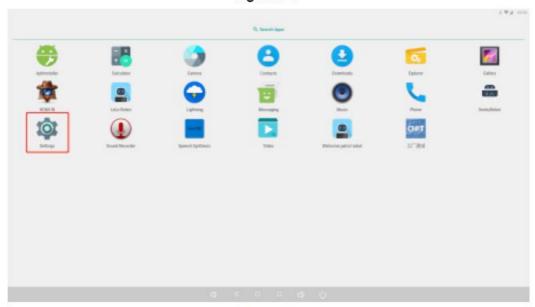


Figure2-5

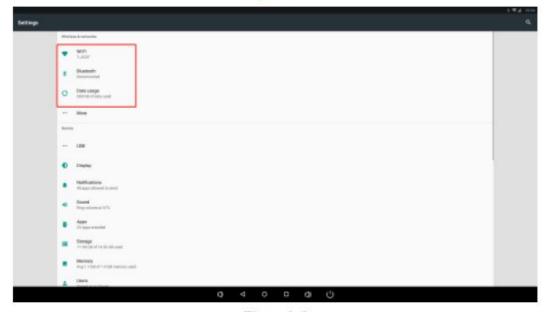


Figure 2-6

# **Product Configuration**

In order to ensure the normal use of the intelligent reception robot APP, there levant configuration shall be

completed. The configuration consists of two parts:

- 1. Configuration of Human-machine Collaboration Comprehensive Service Platform
- 2. Robot Configuration

GFAIICP Robot Operation & Management Platform Client Human-machine Collaboration Comprehensive Service Platform is mainly used to view the temperature measurement and the access data and configure here commendation, menu, activity, consulting service and other information of the robot. For the operation and configuration of the platform, please refer to Guide for Configuration of Human-machine Collaboration Service Platform (Catering).



Figure2-7

#### **Robot Configuration**

Open [Intelligent Reception Robot] APP, click [StatusBar] of [MainInterface] for 8 times consecutively, as shown in Figure 2-8, enter the password ciot 2020, and enter [Settings] interface as shown in Figure 2-9-1.

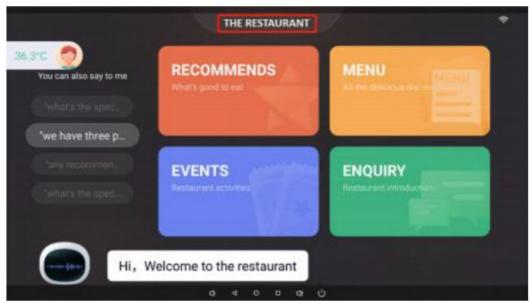


Figure2-8

#### 1. AboutDevice

**Device number:** The robot number can not be modified, otherwise the cloud service of the robot cannot be used.

**Front gateway:** Cloud server gateway address. It is the production server by default. It is not recommended to change the address, otherwise the robot cannot be connected to the server.

**Semantic server:** Semantic server address. It is the production server by default. It is not recommended to change the address, otherwise the robot cannot be connected to this mantic-server.

**Software version:** The name of the current robot application software version. It is recommended to update to the latest version in time for better application experience.

ICCID: The identification number of the their card, which is used as the unique identifier of the IoT card.

Operator: Network operator that displays the IoT card.

Trafficused: Traffic data used in this month



Figure2-9-1

#### 2. Dialogue Settings

**Dialog window lock:** The mode of entering the [Settings] interface, which is disabled by default. When it is enable ,it is necessary to enter the administrator password to enter the [Settings] interface; When it is disabled, you only need to continuously click the status bar for 8 times to enter the [Settings] interface. Whether to display virtual button navigation bar: it is used to display and hide the virtual navigation bar displayed by sliding up and down on the system. When this function is enabled, the navigation bar is displayed; when the function is disabled, the navigation bar is hidden.

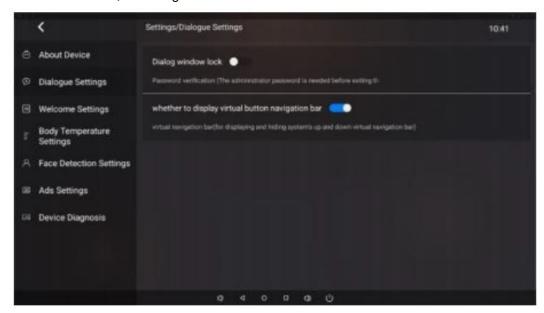


Figure2-9-2

#### 3. WelcomeSettings

Welcome Settings: it is used to set the greetings. When the robot detect saface, it can broad cast the

greetings. To broad cast the greetings according to the identity of the identified person, goto [LinkG Cloud Human-machine Collaboration Comprehensive Service Platform][Solicitation Reception] to set.

**Broadcast in spare time:** switch for controlling the broadcast of the robot in spare time. When it is enabled, the robot will broad cast in spare time; when it is disabled, the robot will not broad cast in spare time.

MediaVolume: it is used to set the system volume of the robot.

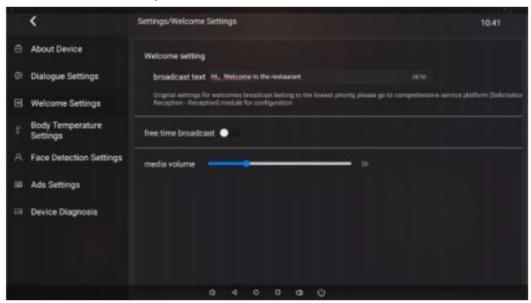


Figure 2-9-3

### 4. Body Temperature Settings

**Temperature measurement switch:** The switch is enabled by default. When the switch is enabled, the robot measure the temperature and broad cast the temperature measurement result. If the temperature is normal, ab normal temperature will be broadcasted.

**Temperature threshold**: maximum normal temperature. If the temperature exceeds this thres hold, it will be on side red ab normal. The values 37.3°C by default, which can be adjusted da according to the special application scene.

**Lower body temperature limit:** This parameter is enabled by default. The value is 36°C by default. When the temperature is lower than 36°C, the value will be increased randomly by(0.1-0.3) and can be adjusted according to the special application scene.

**Warning for not wearing a mask:** this function is disabled by default. When the function is enabled and the robot detects that some one does not wear the mask, the voice prompt Please wear a mask will be made.

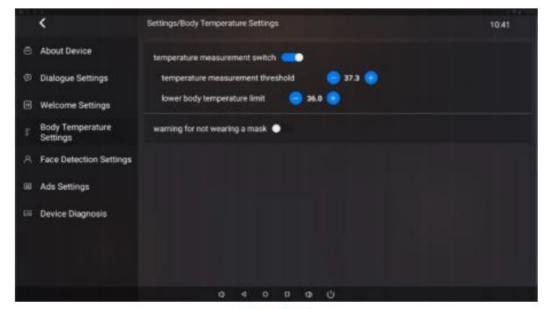


Figure2-9-4

# 5. Face Detection Settings

**Voice activation by face:** this function is enabled by default. After this function is enabled, voice inter-action will be enabled when the robot detects a face. After this function is disabled, voice interaction will not been a bled when the robot recognize saface. You need to click the voice interaction button to initiate voice dialog.



Figure2-9-5

# 6. AdsSettings

**Lower big screen:** it is used to control the volume of video ad son the lower secondary screen.



Figure 2-9-6

#### 7. Device Diagnosis

**Network module:** it is used to detect whether the network module is normal.

**Voice recognition module:** it is used to detect whether the recording module is normal and whether voice authorization is successful.

**Face recognition module:** it is used to detect the initialization status of the face recognition module and the camera.

**Infrared temperature measurement module:** it is used to monitor the initialization status of the infrared temperature measurement module.



Figure 2-9-7

#### **Catering Software Introduction**

# MainInterface

Open the [Intelligent Reception Robot] APP andenter [MainInterface] as shown in Figure 2-10.



Figure 2-10

- 1. **Business name:** THERE STAURANT by default, which can be changed in [Comprehensive Service Platform] [Business Management].
- 2. The real-time temperature measurement data is displayed by default.
- 3. **Bubble words:** take the basic question and answer data of the platform for display, play for 3 inturn, click or give voice to goto the consulting page.
- 4. Voice recognition area: click it to recognize voice, display the text result and the robot prompt in realtime. 5
- 5. Function area: click or give voice to enter the corresponding function interface.

#### **Temperature Screening**

With in 1-3 seconds after entering the temperature recognition area, the robot completes the temperature measurement independently, and then synchronizes th temperature measurement data to Human-machine Cooperation Comprehensive Service Platform. You can login to the platform to view more temperature measurement conditions. Temperature screening may appearas follows:

#### 1. Normalbodytemperature

When the body temperature is normal, the temperature value of the person will be displayed in the temperature measurement chart, and the temperature value and status will be displayed in the upper left corner of the interface. The light color of eyes and ears for the robot will remain unchanged, and the robot will broad cast by voice.

#### 2. Abnormal body temperature

When the body temperature is abnormal, the pop-up window will appear as shownin Figure 2-11. The eye light of the robot turns red and flashes, and the earlight turnsred, and "Temperature anomalies. Please stay here, and waiting for staff" will be broad casted by voice. In this case, other functions are disabled. After the temperature is normal, the abnormal temperature dialog box will disappear.

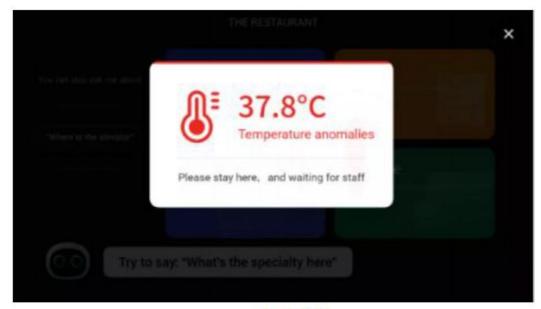


Figure2-11

#### MenuPage

Click Menu on [ Main Inter face ]or say Menu, and the interface shown in Figure 2- 12 will appear. Configuration method:

- 1. Configure Cuisine Classification in [Link G Cloud Human-machine Collaboration Comprehensive Service Platform]-[ Cuisine Management-
  - Cuisine Classification] according to the actual situation, and click save.
- 2. Configure Cuisine Information in LinkG Cloud Human-machine Collaboration Comprehensive Service Platform [Cuisine Management-
  - CuisineConfiguration] according to the actual situation, which is displayed on the front page according to the selection of different cuisines.

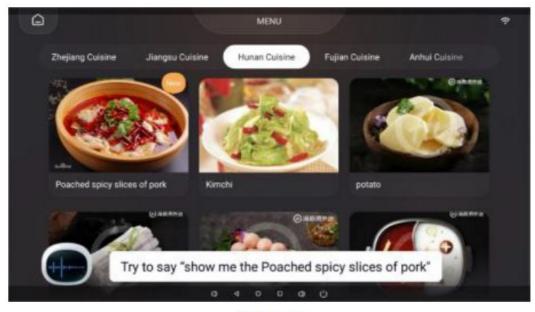


Figure 2-12

# **ActivityPage**

Click Activity on Main Interface or say Activity, and the interface shown in Figure 2- 13 will appear. Configuration method: first configure in [CloudHuman-machine Collaboration Comprehensive Service Platform]-[Catering Activity] according to the actual situation, clickAddaftertheconfiguration, and then the activity module at the robot end can be displayed.

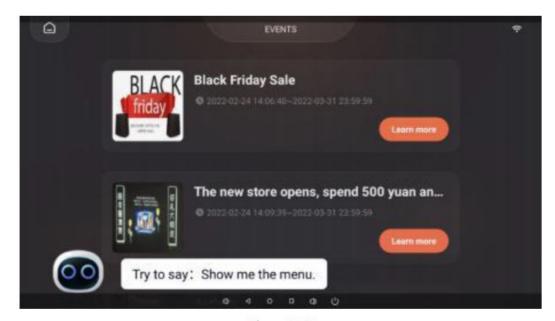


Figure2-13

# **Recommendation Page**

When no one operates, the screen will display recommended cuisines and merchant activity information in turn, a shown in Figure2-14. At this time, click the screen to enter [MainInterface]. Users can also enter this page again by clicking or saying "Recommends" in [MainInterface].

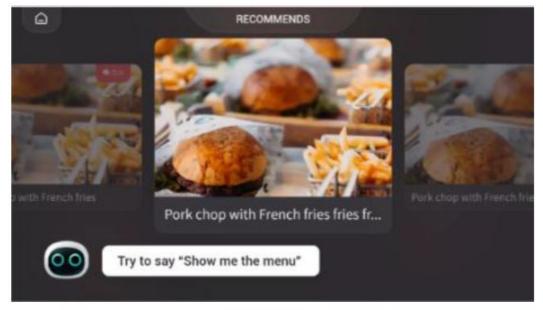


Figure 2-14

#### **Configuration method:**

- 1. **Recommended cuisines:** the merchant canconfigure in Link G Cloud Human-machine Collaboration Comprehensive Service Platform]-[Cuisine Management- Cuisine Configuration] according to the actual situation. If any of the special tyor new dishes are enabled, it can be displayed in Recommendation Page.
- 2. **Activities:** the merchantcanconfi gurein [Link G Cloud Human-machine Collaboration Comprehensive Service Platform]-

[Dining Activities] according to the actual situation, and the activities will be displayed in Recommendation Page when "Enablewhen Canvassing" is enabled.

#### **Consultation Service**

Click Consultation Service on [Main Interface]or say"View all consultation services", and the interface shown in

Figure 2-15 will appear.

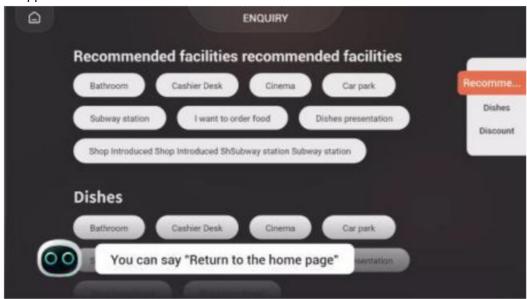


Figure 2-15

Users can customize labels to class if their consultation contents, and add high-frequency questions and answers to the corresponding categories. Users can get answers by asking questions by voice or clicking keywords to link to the question details page, as shown in Figure 2-16.

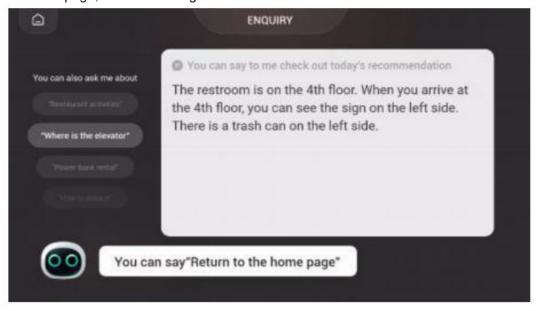


Figure2-16

**Configuration method:** Click in [Link G Cloud Human-machine Collaboration Comprehensive Service Platform]-[Information Settings-Dining Q&A] to add and configure different types of high-frequency questions and correct answers according to the actual scene and high-frequency questions, and display and broadcast tousers through the robot.

# **FCC**

#### **FCC Compliance Statement**

- 1. This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions:
- 2. this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.
- 3. Changes or modifications not expressly approved by the party responsible for compliance could void the user s

authority to operate the equipment.

#### **FCC** information

**Note:** This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receive.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

To maintain compliance with FCC's RE Exposure guidelines, This equipment should be installed and operated with minimum distance between 20cm the radiator your body: Use only the supplied antenna.

#### **Documents / Resources**



<u>GuardforceA PR1120B008F6 AI Reception Robot</u> [pdf] User Manual PR1120B008F6 AI Reception Robot, PR1120B008F6, AI Reception Robot, Reception Robot

Manuals+,