



## GEPRC GEP-M8U Stable Connection Dual Mode Reception Power Supply User Manual

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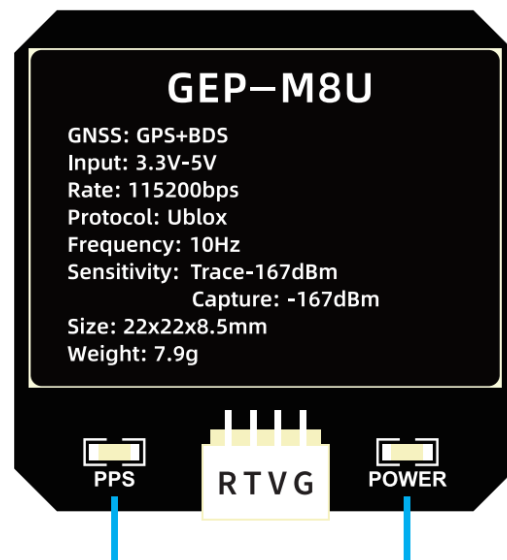
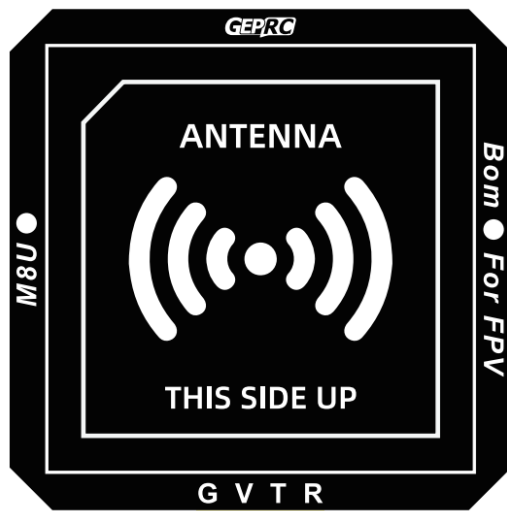


**GEP-M8U Stable Connection Dual Mode Reception  
3-3v-5v Power Supply**



### Summary:

GEP-M8U GPS module features a small size, lightweight, fast positioning, and stable connection. Suitable for FPV, model aircraft, and other products.



PPS indicator      Power indicator

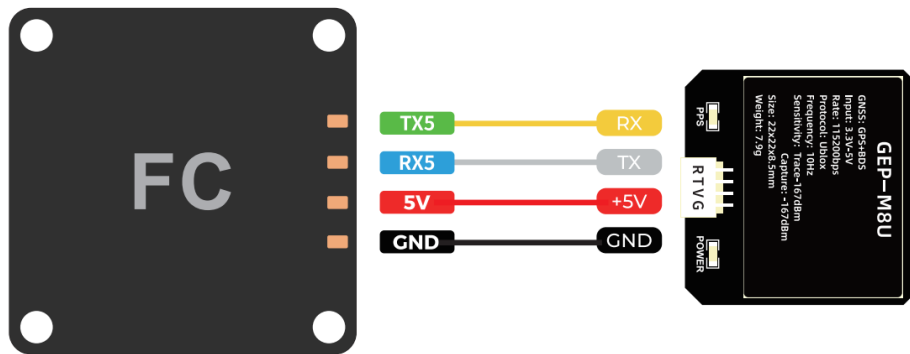
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## Specification:

Model: GEP-M8U  
Receiving Format: GPS, GLONASS, BDS (Choose GLONASS or BDS)  
Input Voltage: 3.3V-5V  
Receiving Channel: 72ch  
Compass: None  
Baud Rate: 115200bps  
Output Connector: SH1.04Pin  
Communication Protocol: UART  
Output Protocol: UBLOX  
Output Frequency: 10Hz  
Speed Accuracy: 0.05 m / s  
Receiving Sensitivity: Trace -162dBm, Capture-160dBm  
Dynamic Characteristics : Max Height:50000m Max Speed:500m/s  
Max Acceleration: 4G  
Working Temperature: -40°C-85°C  
Storage Temperature: -40°C-105°C  
Size: 22mm x 22mm x 8mm  
Weight: 7.9g

## Wiring Diagram:



## Turn on GPS Settings:

1. Turn on GPS on UART5 and set the baud rate to 115200bps.

Identifier	Sensor Input	
USB VCP	Disabled ▼	AUTO ▼
UART5	GPS ▼	115200 ▼

2. Open the configuration interface to enable GPS and select the UBLOX protocol.

GPS

☒

**GPS**

GPS for navigation and telemetry

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Note: Remember to configure a Serial Port (via Ports tab) when using GPS feature.

UBLOX ▼

Protocol

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Auto Baud

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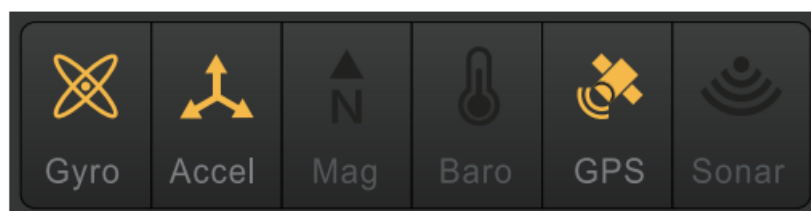
Auto Config

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Use Galileo

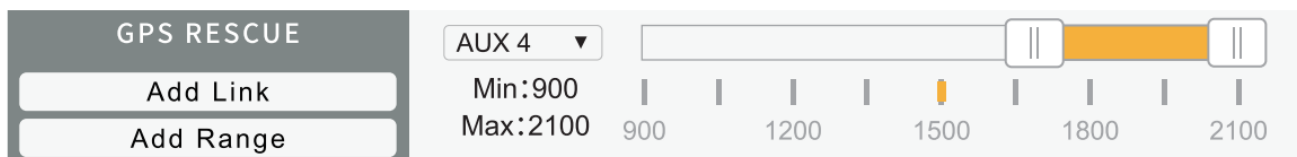
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3. After the setting is completed, restart the flight controller. After the flight controller recognizes the GPS, the GPS logo will light up.

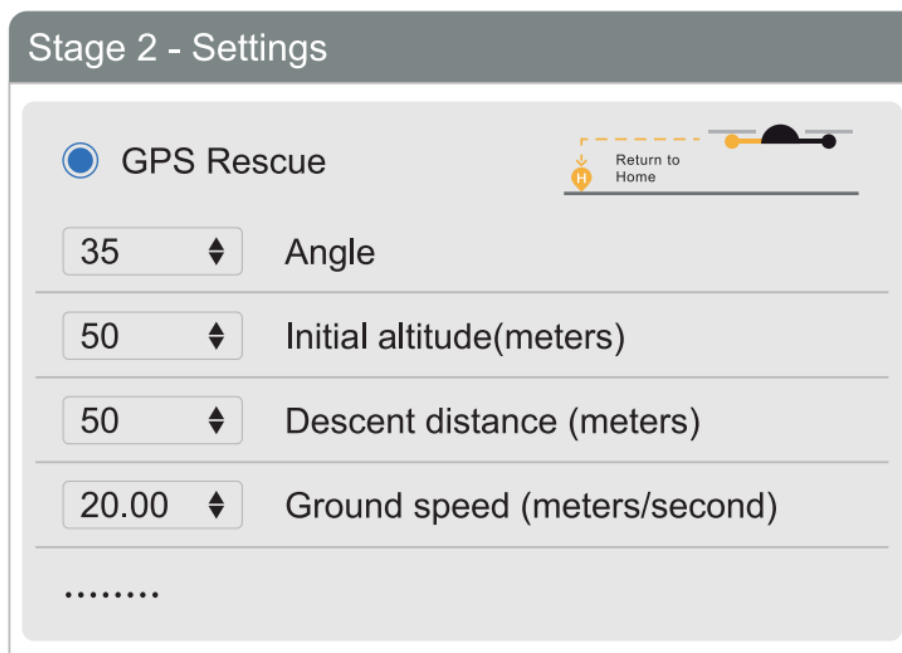


## Enable GPS RESCUE Settings:

1. Under the modes option, enable GPS RESCUE and set the trigger switch.



2. In the GPS RESCUE interface, set the options to be enabled.



### Test Rescue Mode:

1. Removing the propellers then plug in battery.
2. Triggering the rescue switch and observing whether the Betaflight activates the Rescue mode.

Info	
Arming Disable Flags:	MSP <b>RESC</b>
Battery voltage:	4.22 V
Capacity drawn:	3 mAh
Current draw:	0.00 A
RSSI:	100 %

3. Rescue mode is activated normally, You can fly safely.

### Enable Channel Fallback Settings:

1. Preset channel settings, and set the GPS rescue switch to the value that triggers the GPS RESCUE.
2. When the drone loses the receiver signal, the flight controller will switch to the Channel Fallback Setting, that is

enter into GPS RESCUE mode.

Channel Fallback Settings			
AUX 1	ARM	Hold	▼
AUX 2	ANGLE HORIZON	Hold	▼
AUX 3	BEEPER FLIP OVER AFTER CRASH	Hold	▼
AUX 4	GPS RESCUE	Set	▼ 1900 ⬆⬇⬆

#### Test Channel Fallback Settings:

1. Removing the propellers then plug in the battery.
2. Turn off the remote controller and observe whether the Betaflight activates the Rescue mode.

Info	
Arming Disable Flags:	RX_FAILSAFE MSP <b>RESC</b>
Battery voltage:	4.22 V
Capacity drawn:	3 mAh
Current draw:	0.00 A
RSSI:	100 %

3. Rescue mode is activated normally, You can fly safely.

#### Include:

- 1 x GPS module
- 1 x SH1.0-4Pin cable
- 1 x GPS user manual

Contact: Website: <http://geprc.com>

 	 Official website	 	 	 
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## Documents / Resources



[GEPRC GEP-M8U Stable Connection Dual Mode Reception Power Supply](#) [pdf] User Manual  
GEP-M8U Stable Connection Dual Mode Reception Power Supply, GEP-M8U, Stable Connection Dual Mode Reception Power Supply, Power Supply, 3.3V to 5V Power Supply