



GEOSLAM GS-610118 Initialisation Base for ZEB Go and ZEB Revo RT User Guide

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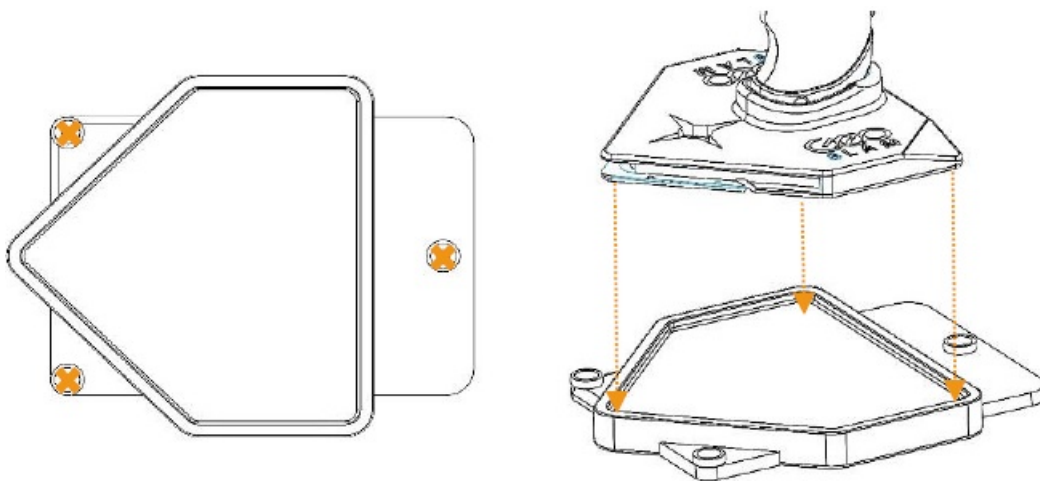
GEOSLAM GS-610118 Initialisation Base for ZEB Go and ZEB Revo RT



Initialisation Base for ZEB Go & ZEB Revo RT

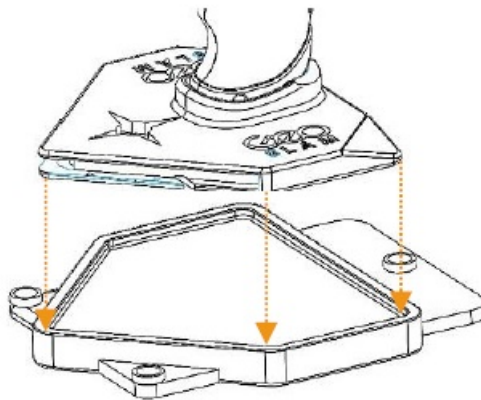
When surveying an ever-changing environment such as a construction site, it is important to accurately capture these changes over time. Therefore, GeoSLAM Construction Progress has a requirement that all scans within a given project are started from and end in the same position and orientation. This can be achieved using the ZEB Go and ZEB Revo RT initialization base as it provides a fixed reference point when starting and ending scans. This document guides you through the basic steps to install and use the initialization plate with a ZEB Go or ZEB Revo RT scanner.

STARTING A SCAN



- Secure the initialization base horizontally onto a permanent structure using 4mm/No.8 fixing screws.
- Position the scanner (with the reference plate attached) in the initialization base at the start of each scan.

ENDING A SCAN




- At the end of each scan, return the scanner to the initialization base before powering off the scanner.

FURTHER INFORMATION

Please refer to the GeoSLAM Construction Progress Software Guide to learn more about the scanning process and importing data into the software.

Documents / Resources

	<p>GEOSLAM GS-610118 Initialisation Base for ZEB Go and ZEB Revo RT [pdf] User Guide GS-610118 Initialisation Base for ZEB Go and ZEB Revo RT, GS-610118, Initialisation Base for ZEB Go and ZEB Revo RT</p>
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