

# Elephant Robotics mechArm pi 270 6-Axis Robot Arm User Manual

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# ELEPHANT

Elephant Robotics mechArm pi 270 6-Axis Robot Arm



### **Warning**

BEFORE USING MECHARM READ ALL INSTRUCTIONS AND CAUTIONARY MARKINGS IN THIS MANUAL

1. Do not expose the product to rain or moisture to reduce fire or shock hazard.
2. Do not place the product in or near fire.
3. Do not leave the product in a car in hot or humid weather.
4. Do not disassemble, crush or pierce the product.
5. Do not expose the product to excessive shock such as dropping from a high place.
6. Do not expose the product to high temperatures above 60 °C (140 °F).

### **Attention**

Regarding the operation and secondary development of me charm Pi, please read and download Giltbrook before using it.

Official Website

## **The most compact 6-axis articulated robot**

The mech Arm Pi 270 belongs to the “mech Arm” series of six-axis articulated robotic arms from Elephant Robot. It uses a Raspberry Pi microprocessor and supports ROS simulation software. It is an industrial-like configuration launched by Elephant Robot for maker innovation and robot industry-university-research services.

The body weight of mechArm270 Pi is 1kg, the load is 250g, and the working radius is 270mm. The design is compact and portable. It is small but powerful, easy to operate, and can work with people safely. As the first small six-axis robotic arm of Elephant Robot, it has three advantages of ease of use, safety and economy, and is a cost-effective choice.



**Classic industrial configuration, the first choice for robotic enthusiast**

- The most classic six-axis centrosymmetric structure of industrial robots, compact and robust.

- The preferred platform for universal and vocational education, colleges and individual development, applying what you have learned to break through the barriers of production, education and research.



#### **Embedded Raspberry Pi ecology, unlimited development possibilities**

- Raspberry Pi 4B, 1.5GHz 4-core microprocessor, running on Debian/Ubuntu platform.
- Support 4 USB, 2 HDMI, standardized GPIO interface, TF card pluggable.



#### **Highly opened source, compatible with massive software and API**

- Compatible with a various of API software, built-in ROS/Move it to simulate the operation state of the manipulator, super expansibility
- From introductory drag teaching and Blackly visual programming to industrial practical operation platform, one machine opens up the whole platform of industry, academia and research.



#### **High configuration, powerful performance**

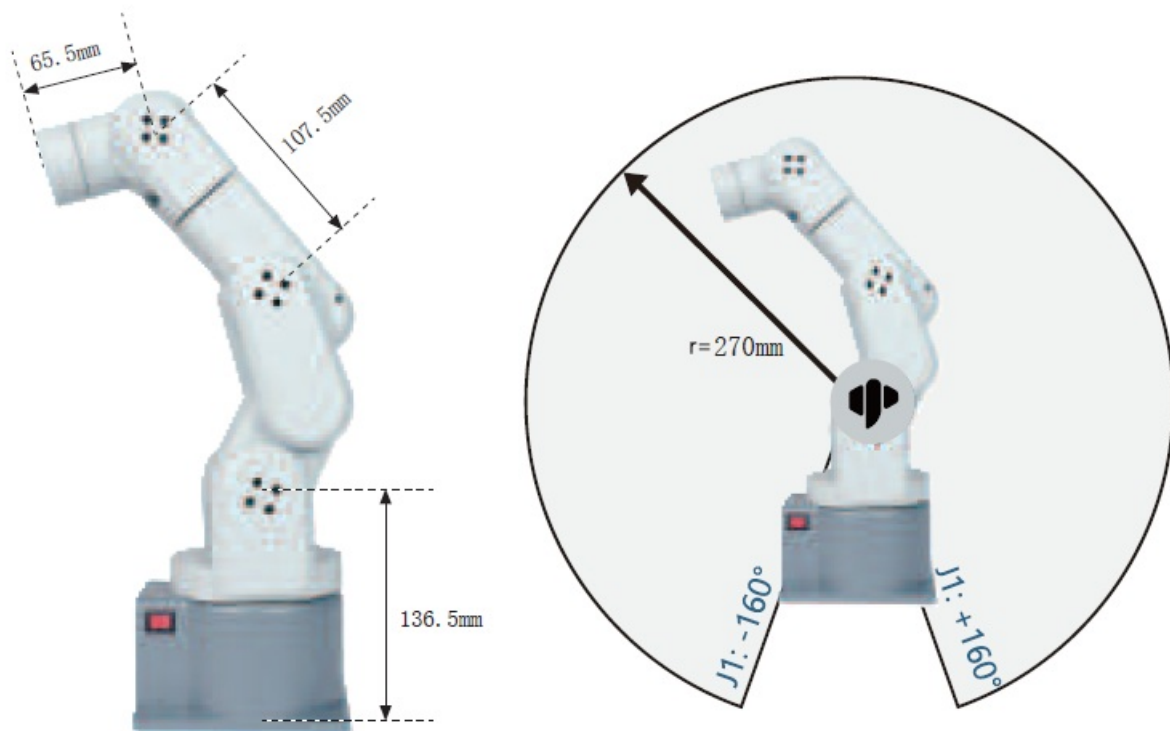
- The use of brushless DC servos can achieve a repeat positioning accuracy of  $\pm 0.5\text{mm}$ .
- The base and the end are equipped with installation interfaces, which are suitable for the development of various peripheral products and equipment.

### **Specifications**

Product Name	mechArm
model	mechArm Pi 270
DOF	6
Repeatability	$\pm 1\text{mm}$
Payload	250g
Weight	960g

Product Name	mechArm
Working radius	270mm
Material	Plastic
Power supply	8-12V 5A
Max speed	120°/s
Motor	High precision magnetic encoder servo moter

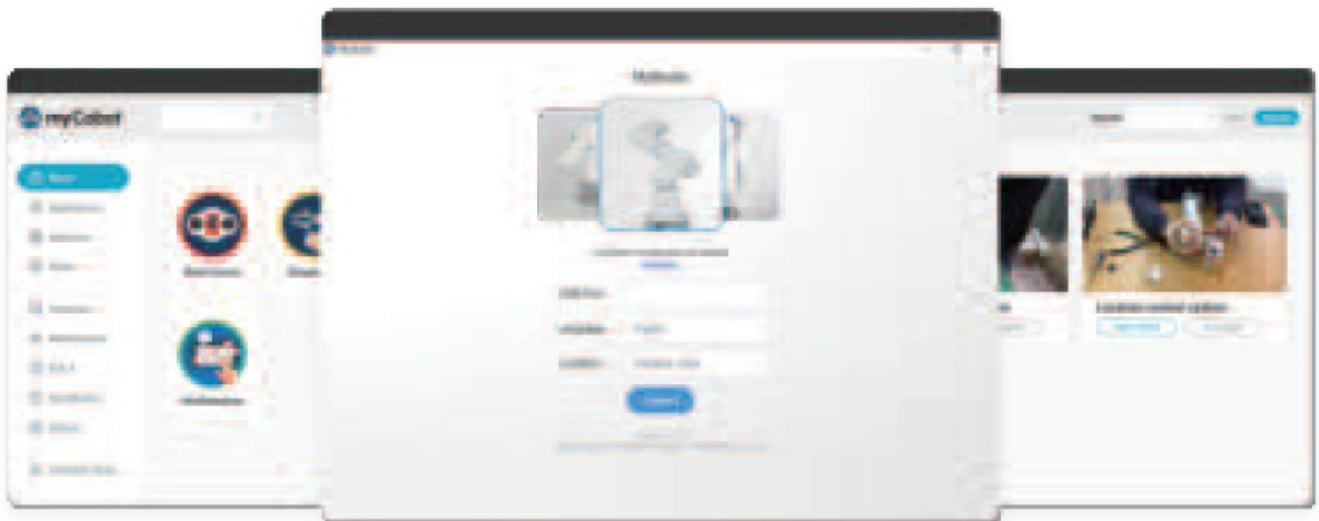
mechArm pi 270 – Size and Working Range Diagram



Control Board Pin Map



## myStudio



### myStudio is a one-stop platform for robots

myStudio integrates mechArm software and various materials.

### The main functions of myStudio are:

1. Update the firmware;
2. Provide video tutorials on how to use the robot;
3. Provide maintenance and repair information (such as video tutorials, Q&A, etc.).

Please download the latest version of myStudio to use.

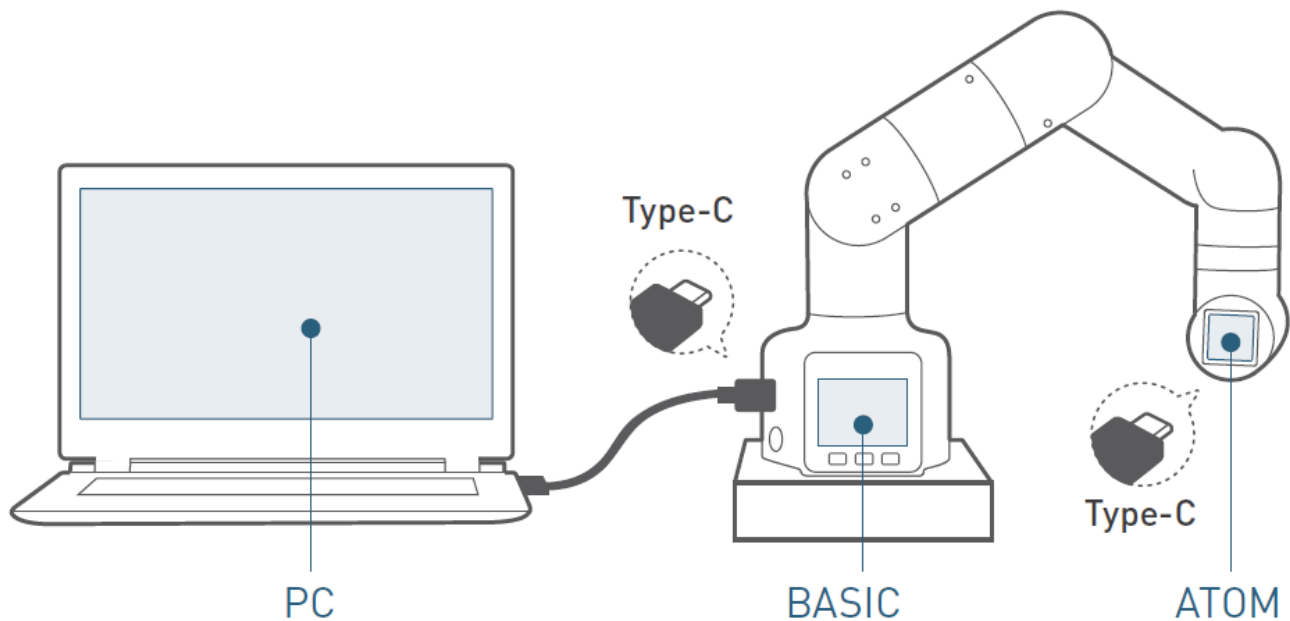
The download link is as follows:

Official website: <https://www.elephantrobotics.com/mechArm/>

Github: <https://github.com/elephantrobotics/MyStudio/>

## Burn Table

Development environments that support the secondary development mechArm are: myBlockly, RoboFlow, Arduino, ROS, python, etc.



Development Environment	Library on PC	Basic Firmware	Atom Firmware
Default Program	N/a	mainControl	atomMain
Visual Programming	myBlockly	myBlockly	atomMain
RoboFlow Industrial Programming Software	RoboFlow	Transponder	atomMain
Arduino Maker!	Arduino IDE + M5Stack Lib + MycobotBasic Lib	All Exapmles	atomMain
API on Desktop	Python/ C+	Transponder	atomMain
ROS Development	ROS	Transponder	atomMain
USB/TxRx0[G1/G3]	Read Protocol	Transponder	atomMain
BlueTooth	Read Protocol	BT_Transponder	atomMain
phoneApp	Mobile phone Android/iPhone	BT_Transponder	atomMain

## mechArm Accessory



Adaptive Gripper



Camera Flange



Suction Pump



G Base

Elephant Robotics are targeted at robotic collaboration applications, making “my-series” product line. For new information about the accessories, Follow us on Shopify and Twitter.

**Shopify:** <https://shop.elephantrobotics.com/>

**Twitter:** @cobotMy

## WARRANTY CARD

### Customer Information (Required)

- Purchaser
- Order No.
- Phone
- Address
- Logistics Receipt Date

### Product problem description(Required)

If you need to apply for warranty service, please contact our customer service to confirm the detailed information. After confirmation, please fill in the card and send it back together with the product and the attached invoice.

**Note:** Our company reserves the right to explain and modify the warranty card of this product within the scope of the law.

- Return service is limited to goods not opened within 7 days after the receipt date of logistics of the products. The freight or other risks incurred in return shall be borne by the customer.
- Customers should provide the purchasing invoice and warranty card as the warranty certification when a warranty is being asked.
- Elephant Robotics will be responsible for the hardware faults of products caused by the normal using during the warranty period.
- The warranty period starts from the date of purchase or the receipt date of the logistics.
- The faulty parts from the products will be owned by Elephant Robotics, and the appropriate cost will be charged



if necessary.

If you need to apply for warranty service, please contact our customer service first to confirm the detailed information.

#### Sever motor

Warranty Period	Warranty Services
≤1 months	Elephant Robotics offers a free new sever motor and bear the freight.
1-3 months	Elephant Robotics offers a free new sever motor, customs shall bear the freight.
≥3 months	Customers need to buy it themselves.
Electrical Parts (M5 Hardware)	
≤3 months	Customers need to send it back after disassembly, Elephant Robotics shall send a new one for free and bear the freight out and home.
3-6 months	Customers need to send it back after disassembly and bear the freight out and home, Elephant Robotics shall send a new one for free.
≥6 months	Customers need to buy it themselves.
Structure Parts, including Shell Parts	
≤1 year	Elephant Robotics offers free new components once, customs shall bear the freight.
≥1 year	Customers need to buy it themselves.

During the warranty period of the delivered product, the company only repairs the malfunctions that occur during normal use of the robot for free. However, in the following cases, the customer will be charged for repairs (even during the warranty period):

- Damage or malfunction caused by incorrect use and improper use different from the contents of the manual.
- Failure caused by unauthorized disassembly by the customer.
- Damage caused by improper adjustment or unauthorized repairs.
- Damage caused by natural disasters such as earthquakes and floods.

Therefore, please strictly follow the instructions in this manual and related manual to operate the robot.

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#### Documents / Resources

	<a href="#">Elephant Robotics mechArm pi 270 6-Axis Robot Arm</a> [pdf] User Manual mechArm pi 270 6-Axis Robot Arm, mechArm pi 270, 6-Axis Robot Arm, Robot Arm, Arm
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#### References

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-  [GitHub - elephantrobotics/myStudio: A comprehensive software for mycobot. Provides firmware burning, documentation, tutorials, etc](#)
-  [Elephant Robotics: Online Robotics Store | Buy Robots Arm for Small Bu](#)
-  [MechArm - Elephant Robotics](#)