

DELTA DVP04TC-H2 Temperature Measurement Module Instruction Manual

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DELTA DVP04TC-H2 Temperature Measurement Module



Product Information

The DVP04TC-H2 is an open-type temperature measurement module. It is designed to be installed in a control cabinet that is free of airborne dust, humidity, electric shock, and vibration. The module should be protected with a safeguard to prevent unauthorized access or accidents that may damage the module. It is important to ensure that AC power is not connected to any of the I/O terminals to avoid serious damage. The module should be properly grounded to prevent electromagnetic interference. Additionally, the correct setting of the thermocouple temperature sensor is crucial to avoid errors.

The product profile and dimensions are as follows:

- DIN rail (35mm)
- Connection port for extension module
- Model name
- POWER, ERROR, A/D indicator
- · DIN rail clip
- Terminals
- · Mounting hole
- I/O terminals
- Mounting port for extension module

The I/O terminal layout is as follows:

```
24 V
        0 V
                D+
                         SL D
                                   D-
                                            L+
                                                    L-
RS-485 CH1
ST. D
L+
CH2
SL D
          L+
CH3
-1-
SL D
L+
L-
CH4
```

The external wiring instructions are as follows:

- 1. For thermocouple wiring, use shielded cable and connect it to the appropriate terminals based on the thermocouple type.
- 2. Ensure proper grounding by connecting the system ground terminal to the system earth point and grounding the system contact or connecting it to the cover of the power distribution cabinet.
- 3. Separate the analog input wiring from other power cables or wirings that may cause interference.

The electrical specifications of the temperature measurement module are:

- Power supply voltage: 24VDC (20.4VDC ~ 28.8VDC) (-15% ~ +20%)
- Analog output channel: 4 channels/module

Product Usage Instructions

- 1. Ensure that the control cabinet where the DVP04TC-H2 module is installed is free of airborne dust, humidity, electric shock, and vibration.
- 2. Install a safeguard on the control cabinet to prevent unauthorized access and accidents that may damage the module.
- 3. Do not connect AC power to any of the I/O terminals to avoid serious damage.
- 4. Double-check all wiring before powering up the DVP04TC-H2 module.
- 5. After disconnecting the module, avoid touching any terminals for at least a minute.
- 6. Properly ground the ground terminal on the DVP04TC-H2 module to prevent electromagnetic interference.
- 7. Keep the wire as short as possible when wiring a platinum resistance thermometer (RTD) to the controller.
- 8. Route power wires as far as possible from load wires to prevent interference and induced noise.
- 9. Ensure that the setting of the thermocouple temperature sensor in CR#1 is correct to avoid serious errors.

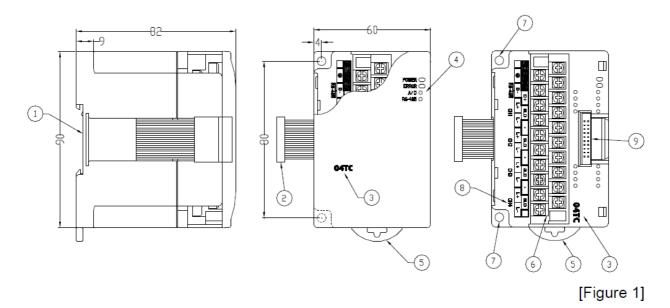
DVP04TC-H2 is able to receive 4 points 0~150mV voltage input of thermocouple temperature sensors (J-type, K-type, R-type, S-type, T-type, E-type, N-type) and convert them into 24-bit digital signals. Besides, through FROM/TO instructions in DVP-EH2 MPU program, the data in DVP04TC-H2 can be read or written. There are 49 16-bit control registers (CR) in it. DVP04TC-H2 displays temperatures in Celsius (resolution: 0.1°C) and Fahrenheit (resolution: 0.18°F).

• This Instruction Sheet only provides descriptions for electrical specifications, general specifications, installation & wiring. Other detail information about programming and instruction's, please see "DVP-PLC Application Manual: Programming". For more information about the optional peripherals, please see individual product

instruction sheet or "DVP-PLC Application Manual Special Modules".

- DVP04TC-H2 is an OPEN-TYPE device. It should be installed in a control cabinet free of airborne dust, humidity, electric shock and vibration. To prevent non-maintenance staff from operating DVP04TC-H2, or to prevent an accident from damaging DVP04TC-H2, the control cabinet in which DVP04TC-H2 is installed should be equipped with a safeguard. For example, the control cabinet in which DVP04TC-H2 is installed can be unlocked with a special tool or key.
- DO NOT connect AC power to any of I/O terminals, otherwise serious damage EN DO NOT connect AC power to any of I/O terminals, otherwise serious damage may occur. Please check all wiring again before DVP04TC-H2 is powered up. After DVP04TC-H2 is disconnected, Do NOT touch any terminals in a minute. Make sure that the ground terminal on DVP04TC-H2 is correctly grounded in order to prevent electromagnetic interference.
- Please keep the wire as short as possible when wiring a platinum resistance
 thermometer (RTD) to the controller and please route power wires as far as possible from load wires to prevent
 interference and induced noise.
- Please make sure the setting of thermocouple temperature sensor in CR#1 is correct, or it will cause serious
 errors.

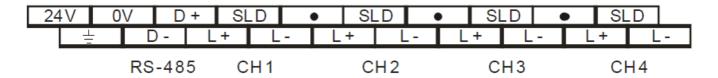
Product Profile & Dimension



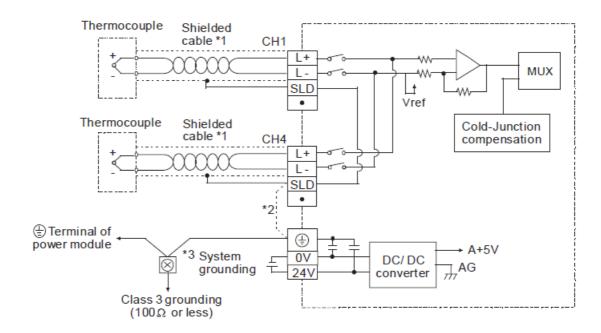
Unit: mm

- 1. DIN rail (35mm)
- 2. Connection port for extension module
- 3. Model name
- 4. POWER, ERROR, A/D indicator
- 5. DIN rail clip
- 6. Terminals
- 7. Mounting hole
- 8. I/O terminals
- 9. Mounting port for extension module

I/O Terminal Layout



External Wiring



- The wiring used for analog input should adopts the connection cable or shielding cable of thermocouple temperature sensor J-type / K-type / R-type / S-type / T-type / E-type / N-type and should be separated from other power cable or wirings that may cause interference. The screw torque of the terminal should be 1.95 kgcm (1.7 in-lbs).
- 2. Terminal SLD is the ground location for noise suppression.
- 3. Please connect the terminal on both the power module and DVP04TC-H2 to the system earth point and ground the system contact or connect it to the cover of power distribution cabinet.

Note: DO NOT wire empty terminal. Use 60/75°C copper conductor only.

Electrical Specifications

Temperature measurement module	Explanation						
Power supply voltage	24VDC (20.4VDC ~ 28.8VDC) (-15% ~ +20%)						
Analog output channel	4 channels/module						
Applicable sensor types	J-type, K-type, R-type, S-type, T-type, E-type, N-type Floating thermocouple sensor, 0~150mV voltage input.						
Range of input temp.	See the table in section Temperature / Digital Curve						
Range of digital conversio	See the table in section Temperature / Digital Curve						
Resolution	0.1°C/0.18°F*1						
Overall accuracy	±0.6% when in full scale within the range of 0 ~ 55°C, 32 ~ 131°F						
Response time	200ms × the number of channels						
Isolation	Isolation between digital circuits and analog circuits. Isolation between channels. 5 00VDC between digital circuits and Ground 500VDC between analog circuits and Ground 500VDC between analog circuits and digital circuits 500VDC between 24V DC and Ground						
Digital data format	15 significant bits out of 16 bits are available; in 2's complement						
Average function	Yes; available for setting up in CR#2 ~ CR#5; range: K1 ~ K100						
Self-diagnosis	Upper and lower bound detection/channel						
Communication mode (R S-485)	Supported, including ASCII/RTU mode. Default communication format: 9600, 7, E, 1, ASCII; refer to CR#32 for details on the communication format. Note1: RS-485 cannot be used when connected to CPU series PLCs. Note2: Use extension module wizard in ISPSoft to search or modify the control register (CR) in the modules.						
When connected to DVP- PLC MPU in	The modules are numbered from 0 to 7 automatically by their distance from MPU. No. 0 is the closest to MPU and No. 7 is the furthest.						
series	Maximum 8 modules are allowed to connect to MPU and will not occupy any digital I/O points.						

The unit of temperature would be displayed as 0.1° C/ 0.1° F. If the temperature unit is set to be Fahrenheit, the second decimal place would not be shown.

Other Specifications

Power supply	
Max. rated power consum ption	24VDC (20.4VDC ~ 28.8VDC) (-15% ~ +20%), 2.5W supplied by external power.

Environment							
Operation/storage	 Operation: 0°C~ 55°C (Temperature), 5 ~ 95% (Humidity), pollution degree 2 Storage: -25°C~ 70°C (Temperature), 5 ~ 95% Humidity 						
Vibration/shock immunity	Standard: IEC61131-2, IEC 68-2-6 (TEST Fc)/IEC61131-2 & IEC 68-2-27 (TEST E a)						

Control Register

CR#1: The working mode of the 4 channels in the sensors selected by the temperature measurement module. There are 8 modes (J-type, K-type, R-type, S-type, T-type, E-type, N-type, $0\sim150\text{mV}$) for each channel which can be set up separately. For example, if the user needs to set up CH1: mode 0 (b2 \sim b0 = 100); CH2: mode 1 (b5 \sim b3 = 001); CH3: mode 0 (b8 \sim b6 = 000) and CH4: mode 1 (b11 \sim b9 = 001), CR#1 has to be set as H0208 and the higher bits (b12 \sim b15) is CH1 \sim CH4 Disable/Enable. The default value = H'0000.

CR#	Attrib.		Register name	Explanation					
#0	O R		Model name	Set up by the system. DVP04TC-H2 model code = H'6403. You can read the model name from the program and s ee if the extension module exists.					
#1	0	R/W	Thermocouple type	CH1 Disable/Enable bit12 CH2 Disable/Enable bit13 CH3 Disable/Enable bit14 CH4 Disable/Enable bit15 1 =Disable 0 =Enable Take the setting of CH1 for example: 1. When (b2, b1, b0) is set as (0,0,0), choose J-type 2. When (b2, b1, b0) is set as (0,0,1), choose K-type 3. When (b2, b1, b0) is set as (0,1,0), choose R-type 4. When (b2, b1, b0) is set as (0,1,1), choose S-type 5. When (b2, b1, b0) is set as (1,0,0), choose T-type 6. When (b2, b1, b0) is set as (1,0,1), choose E-type 7. When (b2, b1, b0) is set as (1,1,0), choose N-type 8. When (b2, b1, b0) is set as (1,1,1), choose 0 ~ 150 mV					

CR#1: The working mode of the 4 channels in the sensors selected by the temperature measurement module. There are 8 modes (J-type, K-type, R-type, S-type, T-type, E-type,

N-type, $0\sim150$ mV) for each channel which can be set up separately. For example, if the user needs to set up C H1: mode 0 (b2 \sim b0 = 100); CH2: mode 1 (b5 \sim b3 = 001); CH3: mode 0 (b8

 \sim b6 = 000) and CH4: mode 1 (b11 \sim b9 = 001), CR#1 has to be set as H0208 and the higher bits (b12 \sim b15) is CH1 \sim CH4 Disable/Enable. The default value = H'0000.

#2	0	R/W	CH1 average time
#3	0	R/W	CH2 average time

Range of settings in CH1 ~ CH4: K1 ~ K100. Default

#4	0	R/W	CH3 average time	=K10.
#5	0	R/W	CH4 average time	
#6	Х	R	Average °C temp. meas ured at CH1	
#7	X	R	Average °C temp. meas ured at CH2	
#8	X	R	Average °C temp. meas ured at CH3	Average Celsius temperature measured at CH1 ~ CH4 . Unit: 0.1°C
#9	X	R	Average °C temp. meas ured at CH4	
	~ CR#9: Th CR#2 ~ CF	_	Celsius temperature meas	sured at CH1 ~ CH4 obtained from the average time setti
#10	X	R	Average °F temp. meas ured at CH1	Average Fahrenheit temperature measured at CH1 ~ C
#11	Х	R	Average °F temp. meas ured at CH2	Unit: 0.1°F
#12	Х	R	Average °F temp. meas ured at CH3	Average Fahrenheit temperature measured at CH3 ~ CH4.
#13	Х	R	Average °F temp. meas ured at CH4	Unit: 0.1°F
	~ CR#13: ngs in CR#		ge Fahrenheit temperature	measured at CH1 ~ CH4 obtained from the average tim
#14	х	R	Present °C temp. measured at CH1	
#15	Х	R	Present °C temp. measured at CH2	
#16	X	R	Present °C temp. measured at CH3	Present Celsius temperature measured at CH1 ~ CH4. Unit: 0.1°C
#17	X	R	Present °C temp. measured at CH4	
#19	X	R	Present °F temp. measu red at CH1	
#20	X	R	Present °F temp. measu red at CH2	
#21	X	R	Present °F temp. measu red at CH3	Present Fahrenheit temperature measured at CH1 ~ C H4. Unit: 0.1°F
#22	х	R	Present °F temp. measu red at CH4	
#24	0	R/W	OFFSET value of CH1	
#25	0	R/W	OFFSET value of CH2	Adjustable OFFSET settings at CH1 ~ CH4. Range: -1,
#26	0	R/W	OFFSET value of CH3	000 ~ +1,000 Default = K0 Unit: 0.1°C
				I.

#30	Х	R	Error status	Register for storing all error status. See the table of err or status for more information.			
#31	0	R/W	Communication address setting	For setting RS-485 communication address. Range: 01 ~ 254, Default = K1.			
#32	О	R/W	Communication format s etting	6 communication speeds: 4,800 bps /9,600 bps /19,20 0 bps / 38,400 bps /57,600 bps /115,200 bps. Data for mats include: ASCII: 7, E, 1/7,O,1 / 8,E,1 / 8,O,1 / 8,N,1 / 7,E,2 / 7,O,2 / 7,N,2 / 8,E,2 / 8,O,2 / 8,N,2 RTU: 8, E, 1 / 8,O,1 / 8,N,1 / 8,E,2 / 8,O,2 / 8,N,2 Default: ASCII,9600,7,E,1 CR#32=H'0002 Please refer to*CR#32 at the bottom of the page for m ore details.			
#33	O	R/W	Returning to default setti	Take the setting of CH1 for example: b0 is reserved. b1 is reserved. When b2 is set as 1, all the settings will return to default settings. ERR LED definition: default of b12 ~ b15 = 1111 1. When b12 = 1, CH1 wiring to empty external contact, ERR LED will flash. 2. When b13 = 1, CH2 wiring to empty external contact, ERR LED will flash. 3. When b14 = 1, CH3 wiring to empty external contact, ERR LED will flash. 4. When b15 = 1 CH2 wiring to empty external contact, ERR LED will flash.			
#34	0	R	Firmware version	Displaying the current firmware version in hex; e.g.			
				version 1.0A is indicated as H'010A			
				;			

Symbols: O: Latched. X: Non-latched.

R: Able to read data by FROM instruction or RS-485 communication. W: Able to write data by TO instruction or RS-485 communication.

- Reset Module (Firmware V4.08 or above): Having connected the external power 24V, write the reset code H'4352 in CR#0, then disconnect and reboot to complete the setup.
- CR#32 Communication Format Setting:
 - Firmware V4.06 (and lower): Data format (b11~b8) is not available, ASCII format is 7, E, 1 (code H'00xx), RTU format is 8, E, 1 (code H'C0xx/H'80xx).
 - Firmware V4.07 (and higher): Refer to the following table for setup. For new communication format,
 please take note that modules in the original code H'C0xx/H'80xx is changed to 8E1 for RTU.

b15 ~ b1	2	b11 ~ b8		b7 ~ b0			
ASCII/R ⁻ of CRC	ΓU & High/Low Bit Exchange	Data For	mat	Communication Speed			
Descripti	on						
H'0	ASCII	H'0	7,E,1*1	H'6	7,E,2*1	H'01	4800 bps
	RTU,	H'1	8,E,1	H'7	8,E,2	H'02	9600 bps
H'8	No High/Low Bit Exchange of CRC	H'2	-	H'8	7,N,2*1	H'04	19200 bps
	RTU,	H'3	8,N,1	H'9	8,N,2	H'08	38400 bps
H'C	High/Low Bit Exchange of	H'4	7,0,1*1	H'A	7,0,2*1	H'10	57600 bps
	CRC	H'5	8.O,1	H'B	8,0,2	H'20	115200 bps

ex: To setup 8N1 for RTU (High/Low Bit Exchange of CRC), communication speed is 57600 bps, write H'C310 in CR #32.

Note *1. Supports ASCII mode ONLY.

- CR#0 ~ CR#34: The corresponding parameter address H'4096 ~ H'40B8 are for users to read/write data by RS-485 communication. When using RS-485, the user has to separate the module with MPU first.
- Function: H'03 (read register data); H'06 (write 1 word datum into register); H'10 (write many word data into register).
- Latched CR should be written by RS-485 communication to stay latched. CR will not be latched if written by MPU through TO/DTO instruction; ; however, when using TO/DTO instruction to modify the PID control registers, all latched CR will stay latched.

CR#30: Error status (see the table below)

Error status	Valu e	b15 ~ b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0
Abnormal power	K1		0	0	0	0	0	0	0	0	0	0	0	1
supply	(H'1)													
Wiring to emp	K2		0	0	0	0	0	0	0	0	0	0	1	0
external conta	(H'2)		U	U	O	U	U	U	0	0	0	0	1	0
Memory self-t est	K16		0	0	0	0	0	0	0	1	0	0	0	0
Fail	(H'10)			J	O	O	O	O	O	'	O	O	O	O
CH1 wiring to	K256	_												
empty externa I contact	(H'10 0)	Reserv ed	0	0	0	1	0	0	0	0	0	0	0	0
CH2 wiring to empty externa I contact	K512 (H'20 0)		0	0	1	0	0	0	0	0	0	0	0	0
CH3 wiring to	K102													
empty externa I contact	4 (H' 400)		0	1	0	0	0	0	0	0	0	0	0	0
CH4 wiring to empty externa I contact	K204 8 (H' 800)		1	0	0	0	0	0	0	0	0	0	0	0

Note: Each error status is determined by the corresponding bit ($b0 \sim b11$) and there may be more than 2 errors occurring at the same time. 0 = normal; 1 = error.

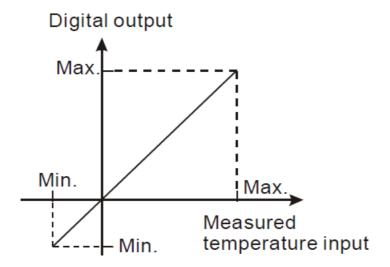
PID Control Registers

CR#			Latabad		Desister content	Evalenation		
CH1	CH2	СНЗ	CH4	Latched]	Register content	Explanation	
#51	#71	#91	#111	0	R/W	Temperature SV	Default = K0.	
#52	#72	#92	#112	0	R/W	Sampling time (s)	Range: K1 ~ K30 (s). Default = K2.	
#53	#73	#93	#113	0	R/W	KP	Default = K121.	
#54	#74	#94	#114	0	R/W	KI	Integral constant, Default = K2,098.	
#55	#75	#95	#115	0	R/W	KD	Derivative constant, Default = K-29.	
#56	#76	#96	#116	0	R/W	Upper limit of I valu	Range: K-32,760 ~ K32,760. Default = K0.	
#57	#77	#97	#117	О	R/W	Lower limit of I valu	Range: K-32,760 ~ K32,760. Default = K0.	
#58	#78	#98	#118	x	R	I value	Current accumulated offset value. D efault = K0.	
#59	#79	#99	#119	0	R/W	Heating/cooling control	0: Heater, 1: Cooler. Default = K0.	
#60	#80	#100	#120	О	R/W	Upper limit of outpu	Range: K-32,760 ~ K32,760. Default = K4,000.	
#61	#81	#101	#121	О	R/W	Lower limit of outpu	Range: K-32,760 ~ K32,760. Default = K0.	
#62	#82	#102	#122	x	R	Output percentage (%)	Range: K0 ~ K1,000 (Unit: 0.1%). Default = K0.	
#63	#83	#103	#123	x	R	Output width (ms)	Width of control output, Unit: ms. De fault = K0.	
#64	#84	#104	#124	x	R	Output cycle (ms)	Cycle of control output, Unit: ms. De fault = K0.	
#65	#85	#105	#125	Х	R	Output volume	Default = K0.	
#66	#86	#106	#126	Х	R/W	PID_Run/Stop	0: Stop, 1: Run. Default = K0.	
#67	#87	#107	#127	Х	R/W	Auto Tune	0: Disabled, 1: Auto-tuning. Default = K0.	

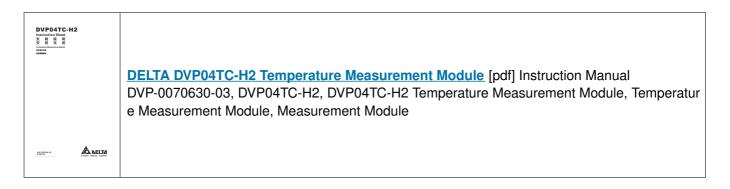
- \bullet The CR#51 $^{\sim}$ CR#127 listed above do not support RS-485 read/write.
- When using TO/DTO instruction to modify PID control registers, latched CR and PID control registers will stay latched.

Temperature / Digital Curve

Temperature Measurement Mode (°C/°F):



Documents / Resources



Manuals+,