



# Danfoss MA01c iC2-Micro Frequency Converters Installation Guide

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**Danfoss MA01c iC2-Micro Frequency Converters**



## Product Information: iC2-Micro Frequency Converters

The iC2-Micro Frequency Converters are AC drives that are designed for use by qualified personnel for installation and commissioning purposes. The product comes with an Operating Guide that provides essential information needed to use the drive safely and professionally. The product is not to be disposed of with domestic waste containing electrical components; it should be collected separately in accordance with local and currently valid legislation.

### Safety

It is important to pay particular attention to the safety instructions and general warnings provided in the Operating Guide to avoid the risk of death, serious injury, and equipment or property damage. The AC drives contain high voltage when connected to AC mains input, DC supply, or load sharing. Leakage currents of the drive exceed 3.5 mA, so it is important to ensure that the minimum size of the ground conductor complies with local safety regulations for high touch current equipment.

### Installation

The product has mechanical dimensions that include enclosure size, height, width, depth, and mounting holes. The product comes in different enclosure sizes and power options ranging from 1.0 kW (2.4 hp) to 1.6 kW (3.5 hp). The maximum weight of the product varies according to the enclosure size and power option selected. The product comes with a potentiometer on the local control panel that extends 6.5 mm (0.26 in) from the drive.

### Connecting to Mains and Motor

When connecting the product to mains and motor, use 6.3 mm (0.25 in) insulated connectors designed for high voltage for DC (load sharing and brake). Refer to the drive's Design Guide or contact Danfoss for further information on load sharing and brake. The product has terminals for load sharing and brake that require specific connector types. Ensure that the terminal cover is removed with a screwdriver before connecting the wires.

### Overview of Control Terminals

The product has a RJ45 port that complies with Modbus 485 protocol for connection to external devices. The product has control terminals that are configured in PNP-configuration with factory setting (speed control mode) and include +24 V OUT, Start, Reverse, Reset (DI), Jog, GND, 0-20 mA 1K Ohm, 0-10 V GND, Frequency output, Reference, and Function: Fault.

## Product Usage Instructions: iC2-Micro Frequency Converters

1. Read and follow the instructions provided in the Operating Guide to use the drive safely and professionally.
2. Do not dispose of equipment containing electrical components together with domestic waste. Collect it separately in accordance with local and currently valid legislation.
3. Pay particular attention to the safety instructions and general warnings provided in the Operating Guide to avoid the risk of death, serious injury, and equipment or property damage.
4. When connecting the product to mains and motor, use 6.3 mm (0.25 in) insulated connectors designed for high voltage for DC (load sharing and brake).
5. Refer to the drive's Design Guide or contact Danfoss for further information on load sharing and brake.
6. Ensure that the minimum size of the ground conductor complies with local safety regulations for high touch current equipment when connecting the product.
7. Remove the terminal cover with a screwdriver before connecting the wires.
8. Use specific connector types for load sharing and brake terminals.
9. The product has a RJ45 port that complies with Modbus 485 protocol for connection to external devices.
10. The product has control terminals that are configured in PNP-configuration with factory setting (speed control mode) and include +24 V OUT, Start, Reverse, Reset (DI), Jog, GND, 0-20 mA 1K Ohm, 0-10 V GND, Frequency output, Reference, and Function: Fault.

## **iC2-Micro Frequency Converters**

### **Introduction**

Danfoss A/S © 2022.02 AQ379331704297en-000101 / 130R1215 | 1 iC2-Micro Frequency Converters \*M0033001\* This Operating Guide provides necessary information for qualified personnel to install and commission the AC drive. Read and follow the instructions to use the drive safely and professionally.



Do not dispose of equipment containing electrical components together with domestic waste. Collect it separately in accordance with local and currently valid legislation.

### **Safety**

Pay particular attention to the safety instructions and general warnings to avoid the risk of death, serious injury, and equipment or property damage.

### **WARNING**

- **HIGH VOLTAGE**

AC drives contain high voltage when connected to AC mains input, DC supply, or load sharing.

- **UNINTENDED START**

The motor may start from control panel, I/O inputs, fieldbus, or MyDrive® Insight at any time, when the drive is connected to the AC mains, DC supply, or load sharing.

- **DISCHARGE TIME**

The drive contains DC-link capacitors, which can remain charged even when the drive is not powered. High voltage can be present even when the warning indicator lights are off.

- Stop the motor, and disconnect AC mains, permanent magnet type motors, and remove DC-link supplies, including battery back-ups, UPS, and DC-link connections to other drives.
- Wait for the capacitors to discharge fully and measure it before performing any service or repair work.

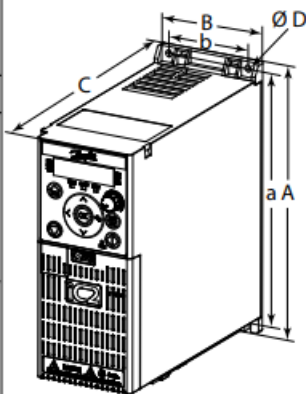
The minimum waiting time is 4 minutes for MA01c, MA02c, MA01a, and MA02a drives, and 15 minutes for MA03a, MA04a, and MA05a drives.

## • LEAKAGE CURRENT

Leakage currents of the drive exceed 3.5 mA. Make sure that the minimum size of the ground conductor complies with the local safety regulations for high touch current equipment.

## Installation

### Mechanical Dimensions

Enclosure size	Height [mm (in)]			Width [mm (in)]		Depth [mm (in)] <sup>2a</sup>	Mounting holes [mm (in)]	
	A	A <sup>(1)</sup>	a	B	b	C	D	
MA01c	150 (5.9)	216 (8.5)	140.4 (5.5)	70 (2.8)	55 (2.2)	143 (5.6)	4.5 (0.18)	
MA02c	176 (6.9)	232.2 (9.1)	150.5 (5.9)	75 (3.0)	59 (2.3)	157 (6.2)	4.5 (0.18)	
MA01a	150 (5.9)	202.5 (8.0)	140.4 (5.5)	70 (2.8)	55 (2.2)	158 (6.2)	4.5 (0.18)	
MA02a	186 (7.3)	240 (9.4)	176.4 (6.9)	75 (3.0)	59 (2.3)	175 (6.9)	4.5 (0.18)	
MA03a	Data for MA03a to MA05a will be available in next release.							
MA04a								
MA05a								
Enclosure size	Power [kW (hp)]						Maximum weight <sup>(3)</sup> [kg (lb)]	
	1x200–240 V			3x380–480 V				
MA01c	0.37–0.75 (0.5–1.0)			–			1.0 (2.4)	
MA02c	1.5 (2.0)			–			1.3 (2.9)	
MA01a	–			0.37–1.5 (0.5–2.0)			1.1 (2.4)	
MA02a	2.2 (3.0)			2.2–4.0 (3.0–5.4)			1.6 (3.5)	
MA03a	Data for MA03a to MA05a will be available in next release.							
MA04a								
MA05a								

### Note:

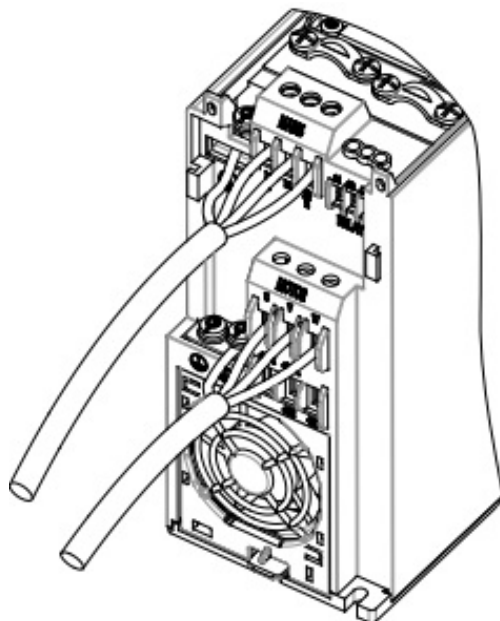
1. Including decoupling plate.
2. The potentiometer on the local control panel extends 6.5 mm (0.26 in) from the drive.
3. Not including decoupling plate.

### Connecting to Mains and Motor

- Mount the ground wires to the PE terminal.
- Connect motor to terminals U, V, and W.
- Mount mains supply to terminals L1/L, L2, and L3/N (3-phase) or L1/L and L3/N (single-phase) and tighten.
- For required maximum screwing torque, see the back of terminal cover.

### Load Sharing/Brake

Use 6.3 mm (0.25 in) insulated connectors designed for high voltage for DC (load sharing and brake). Contact Danfoss or refer to the drive's Design Guide.



**Illustration 1: Mounting of Ground Cable, Mains, and Motor Wires**

**Table 1: Connect Terminals**

<b>Load sharing</b>	-UDC and +UDC/+BR
<b>Brake</b>	-BR and +UDC/+BR

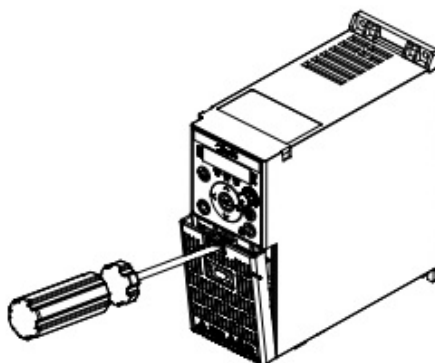
Recommended connector type (only for drives below 7.5 kW/10 hp): Ultra-Pod Fully Insulated FASTON Receptacles and Tabs, 521366-2, TE connectivity.

### NOTICE

Voltage levels of up to 850 V DC may occur between terminals +UDC/+BR and -UDC. Not short-circuit protected.

### Control Terminals

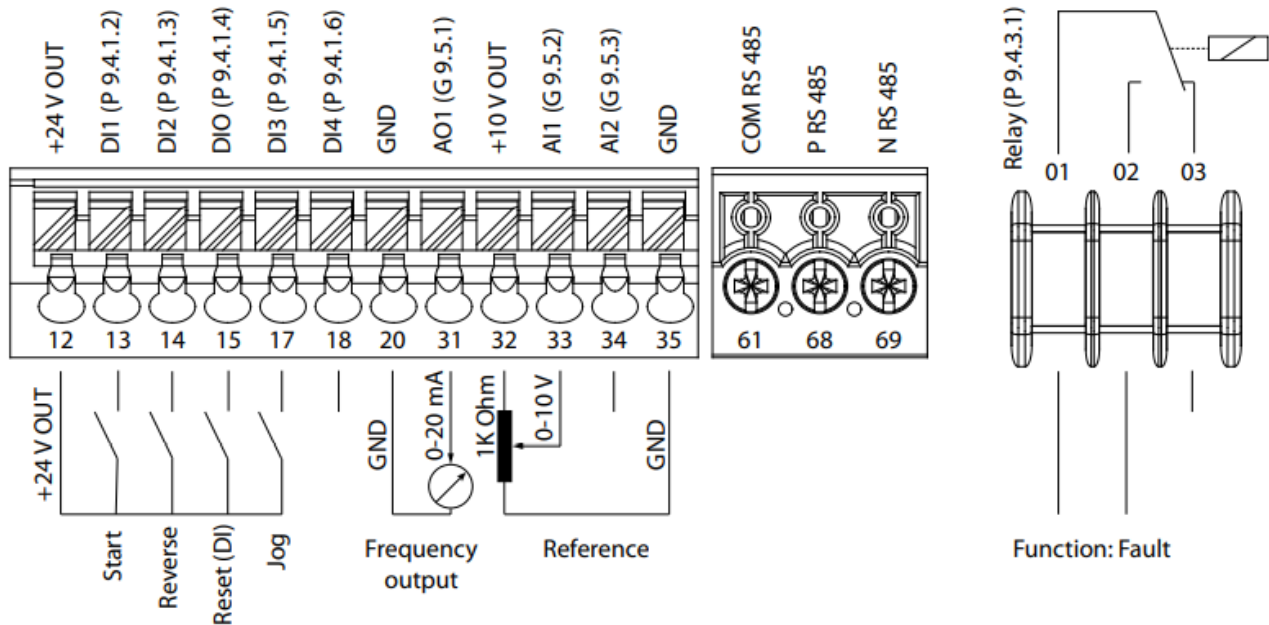
- All control cable terminals are located underneath the terminal cover in front of the drive.
- See the back of the terminal cover for outlines of control terminals and switches.



**Illustration 2: Removing Terminal Cover**

### NOTICE

Remove the terminal cover with a screwdriver, see illustration 2.



**Illustration 3: Overview of Control Terminals in PNP-configuration with Factory Setting (Speed Control Mode)**

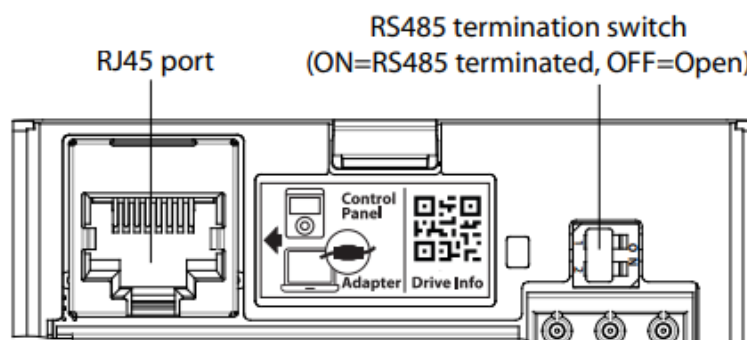
### RJ45 Port and RS485 Termination Switch

- iC2-Micro drive has a RJ45 port which complies with Modbus 485 protocol.

#### The RJ45 port is used for connecting:

- External control panel.(1)
- PC tool (MyDrive® Insight) via an adapter.(1)
- Offline configuration tool for parameter settings when the drive is not powered on.(1)

**Note:** (1) The tool is not available currently.



**Illustration 4: RJ45 Port and RS485 Termination Switch**

### NOTICE

- The RJ45 port supports up to 3 m (9.8 ft) of shielded CAT5e cable which is NOT used to directly connect the drive to a PC. Failure to follow this notice causes damage to the PC.
- RS485 termination switch should be set to ON if the drive is at the end of the fieldbus.
- Do not operate RS485 termination switch when the drive is powered on.



## Programming

### Control Panel

#### 4.1 Control Panel

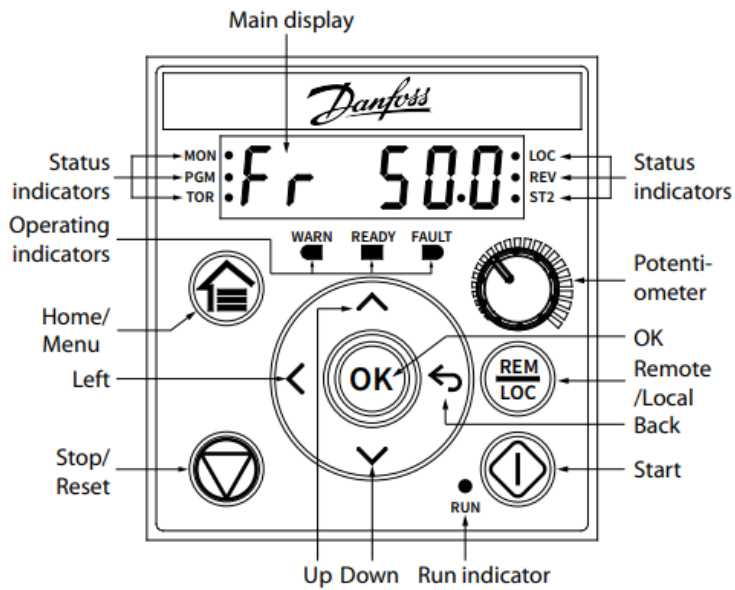


Illustration 5: Indicators and Operation Keys

Table 2: Operation Keys and Potentiometer

Name	Function
Home/Menu	(1) Toggles between status display and main menu. (2) Long press to access the shortcut menu for quickly reading and editing parameters. <sup>(1)</sup>
Up/Down	Switches status/parameter group/parameter numbers, and tunes the parameter values.
Left	Moves the cursor 1 bit to the left.
Back	Navigates to the previous step in the menu structure or cancels the setting during tuning parameter values.
OK	Confirms the operation.
Remote/Local	Toggles between remote and local mode.
Start	Starts the drive in local mode.
Stop/Reset	Stops the drive in local mode, or resets the drive to clear a fault.
Potentiometer	Changes the reference value when the reference value is selected as potentiometer.

Note: (1) The shortcut menu is not available currently.

Table 3: Status and Operating Indicator Lights

Table 3: Status and Operating Indicator Lights

Name	Function		Name	Function	
MON	On	Shows the drive status.	REV	On	The drive is in reverse direction.
PGM	On	The drive is in programming status.		Off	The drive is in forward direction.
TOR	On	The drive is in torque mode.	ST2	Refer to <i>Table 5 Multiple Setups</i> .	
	Off	The drive is in speed mode.	WARN	Steadily lit when a warning occurs.	
LOC	On	The drive is in local mode.	READY	Steadily lit when the drive is ready.	
	Off	The drive is in remote mode.	FAULT	Flashes when a fault occurs.	

Table 4: Run Indicator Lights

Name	Function	
RUN	On	The drive is in normal operation.
	Off	The drive has stopped.
	Flash	In the motor-stopping process; or the drive received a <i>RUN</i> command, but no frequency output.

Table 5: Multiple Setups

ST2	Off	On	Flash	Flash quickly
Active setup <sup>(1)</sup>	Setup 1	Setup 2	Setup 1	Setup 2
Programming setup <sup>(2)</sup>	Setup 1	Setup 2	Setup 2	Setup 1

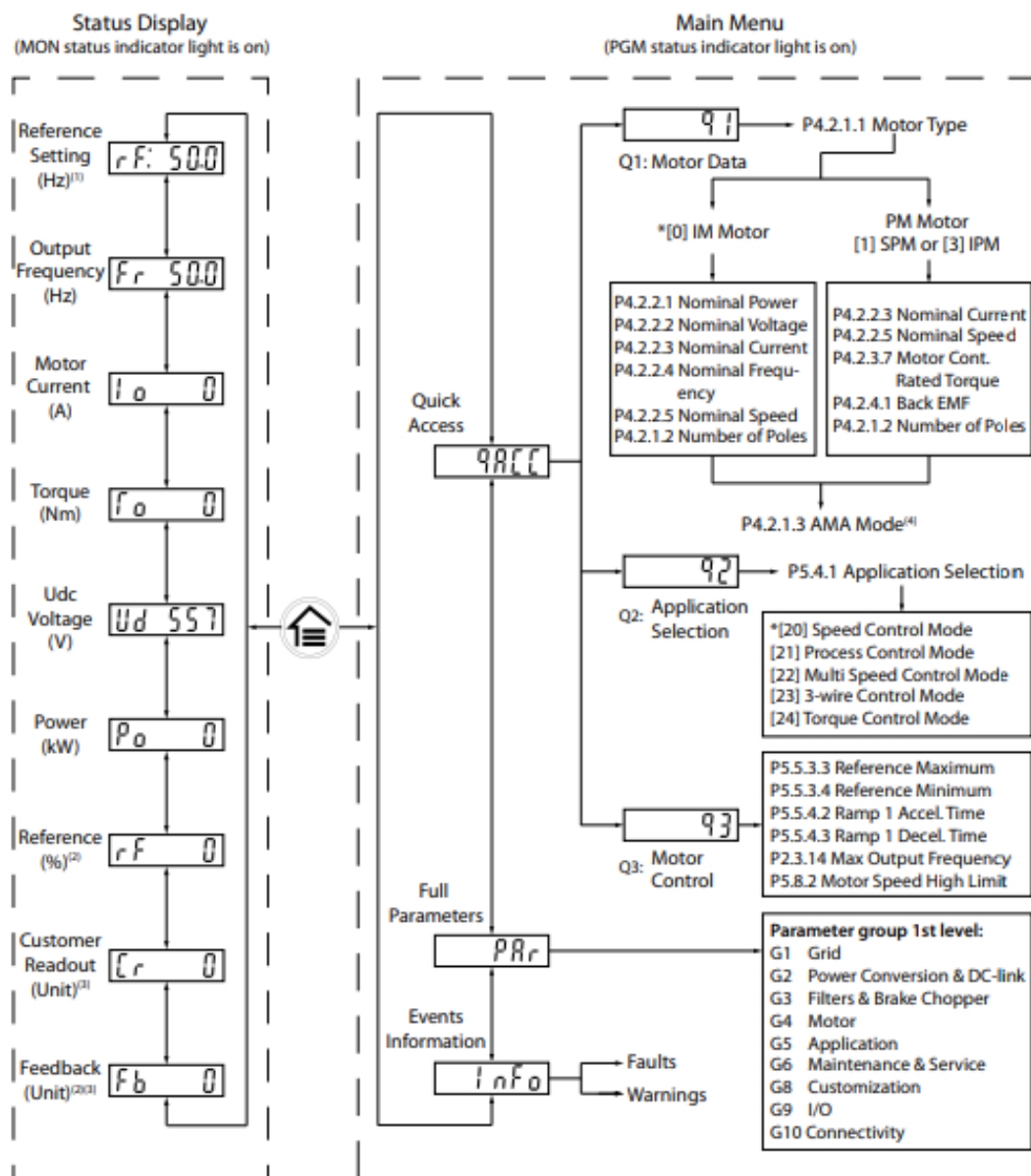
Note:

(1) Select active setup in *parameter P6.6.1 Active Setup*.

(2) Select programming setup in *parameter P6.6.2 Programming Setup*.

### Operation with Control Panel

After the drive is powered up, press the Home/Menu key to toggle between status display and main menu. Use the Up/Down keys to select items, and press the OK key to confirm selection.



#### Note:

- (1) Local mode only.
- (2) Remote mode only.
- (3) The status is only shown when the corresponding function is enabled.
- (4) For AMA execution, refer to chapter Automatic Motor Adaptation (AMA). If parameter P5.4.3 Motor Control Principle is set as [0] U/f, no need to execute AMA.

Illustration 6: Operation with Control Panel

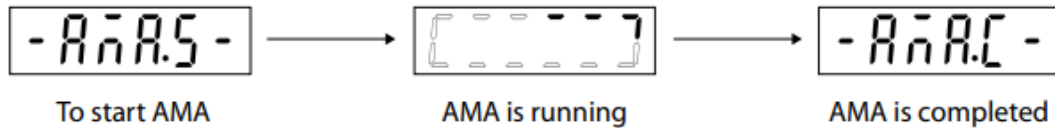
#### Automatic Motor Adaptation (AMA)

- Via running AMA in VVC+ mode, the drive builds a mathematical model of the motor to optimize compatibility between drive and motor, and thus enhances the motor control performance.
- Some motors may be unable to run the complete version of the test. In that case, select [2] Enable Reduced AMA in parameter P4.2.1.3 AMA Mode.
- AMA completes within 5 minutes. For best results, run the following procedure on a cold motor.



## Procedure:

1. Set motor data according to the motor nameplate.
2. If needed, set motor cable length in parameter P4.2.1.4 Motor Cable Length.
3. Set [1] Enable Complete AMA or [2] Enable Reduced AMA for parameter P4.2.1.3 AMA Mode, the main display shows To start AMA, see illustration 7.
4. Press the Start key, the test runs automatically and the main display indicates when it is completed.
5. When AMA is completed, press any key to exit and return to normal operation mode.



**Illustration 7: AMA Status Indications**

## Troubleshooting

Table 6: Warning and Fault Events Summary

Number	Description	Warning	Fault	Trip lock	Cause
2	Live zero error	X	X	–	Signal on terminal 33 or 34 is less than 50% of the value set in <i>parameter P9.5.2.3 T33 Low Voltage</i> , <i>parameter P9.5.2.5 T33 Low Current</i> , <i>parameter P9.5.3.3 T34 Low Voltage</i> , and <i>parameter P9.5.3.5 T34 Low Current</i> .
3	No motor	X	–	–	No motor has been connected to the output of the drive.
4	Mains phase loss <sup>(1)</sup>	X	X	X	Missing phase on the supply side, or the voltage imbalance is too high. Check the supply voltage.
7	DC overvoltage <sup>(1)</sup>	X	X	–	DC-link voltage exceeds the limit.
8	DC undervoltage <sup>(1)</sup>	X	X	–	DC-link voltage drops below the voltage warning low limit.
9	Inverter overloaded	X	X	–	More than 100% load for too long.
10	Motor ETR overtemperature	X	X	–	Motor is too hot due to more than 100% load for too long.
11	Motor thermistor overtemperature	X	X	–	Thermistor or thermistor connection is disconnected, or the motor is too hot.
12	Torque limit	X	X	–	Torque exceeds the value set in either <i>parameter P5.10.1 Motor Torque Limit</i> or <i>parameter P5.10.2 Regenerative Torque Limit</i> .
13	Overcurrent	X	X	X	Inverter peak current limit is exceeded. If this fault occurs on power-up, check whether power cables are mistakenly connected to the motor terminals.
14	Ground fault	–	X	X	Discharge from output phases to ground.
16	Short circuit	–	X	X	Short circuit in motor or on motor terminals.
17	Control word timeout	X	X	–	No communication to the drive.
25	Brake resistor short-circuited	–	X	X	Brake resistor is short-circuited, thus the brake function is disconnected.
26	Brake overload	X	X	–	The power transmitted to the brake resistor over the last 120 s exceeds the limit. Possible corrections: Decrease brake energy via lower speed or longer ramp time.
27	Brake IGBT/Brake chopper short-circuited	–	X	X	Brake transistor is short-circuited, thus brake function is disconnected.
28	Brake check	–	X	–	Brake resistor is not connected/working.
30	U phase loss	–	X	X	Motor phase U is missing. Check the phase.
31	V phase loss	–	X	X	Motor phase V is missing. Check the phase.
32	W phase loss	–	X	X	Motor phase W is missing. Check the phase.

36	Mains failure	X	X	–	This warning/fault is only active if the supply voltage to the drive is less than the value set in <i>parameter P2.3.7 Power Loss Controller Limit</i> , and <i>parameter P2.3.6 Power Loss Action</i> is NOT set to [0] No Function.
38	Internal fault	–	X	X	Contact the local supplier.
40	Overload T15	X	–	–	Check the load connected to terminal 15 or remove short-circuit connection.
46	Gate drive voltage fault	–	X	–	–
47	24 V supply low	X	X	X	24 V DC may be overloaded.
50	AMA calibration failed	–	X	–	A calibration error has occurred.
51	AMA check $U_{nom}$ and $I_{nom}$	–	X	–	Wrong setting for motor voltage and/or motor current.
52	AMA low $I_{nom}$	–	X	–	Motor current is too low. Check the settings.
53	AMA big motor	–	X	–	The power size of the motor is too large for the AMA to operate.
54	AMA small motor	–	X	–	The power size of the motor is too small for the AMA to operate.
55	AMA parameter range	–	X	–	The parameter values of the motor are outside of the acceptable range. AMA does not run.
56	AMA interrupt	–	X	–	The AMA is interrupted.
57	AMA timeout	–	X	–	–
58	AMA internal	–	X	–	Contact the local supplier.
59	Current limit	X	X	–	The drive is overloaded.
60	External Interlock	–	X	–	External interlock has been activated.
61	Feedback error	X	X	–	–
63	Mechanical brake low	–	X	–	Actual motor current has not exceeded release brake current within start delay time window.
69	Power card temp	X	X	X	The cutout temperature of the power card has exceeded the upper limit.
80	Drive initialized to default value	–	X	–	All parameter settings are initialized to default settings.
87	Auto DC brake	X	–	–	Occurs in IT mains when the drive coasts, and the DC voltage is higher than 830 V for 400 V units and 425 V for 200 V units. The motor consumes energy on the DC link. This function can be enabled/disabled in <i>parameter P2.3.13 Auto DC Braking</i> .
95	Broken belt	X	X	–	–
99	Locked rotor	–	X	–	Rotor is blocked.
126	Motor rotating	–	X	–	PM motor is rotating when AMA is performed.
127	Back EMF too high	X	–	–	The back EMF of PM motor is too high before starting.
Err. 89	Parameter read only	–	–	–	Parameters cannot be changed.
Err. 95	Not while running	–	–	–	Parameters can only be changed when the motor is stopped.
Err. 96	A wrong password was entered	–	–	–	Occurs when using a wrong password for changing a password-protected parameter.

**Note:** (1) These faults may be caused by mains distortions. Installing a Danfoss line filter may rectify this problem.

## Specifications

**Table 7: Mains Supply 1x200–240 V AC**

Normal overload 150% for 1 minute				
Drive	02A2	04A2	06A8	09A6
Typical shaft output [kW (hp)]	0.37 (0.5)	0.75 (1.0)	1.5 (2.0)	2.2 (3.0)
Enclosure protection rating IP20	MA01c	MA01c	MA02c	MA02a
Output current				
Continuous (3x200–240 V) [A]	2.2	4.2	6.8	9.6
Intermittent (3x200–240 V) [A]	3.3	6.3	10.2	14.4
Maximum cable size (Mains, motor) [mm²/AWG]	4/10			
Maximum input current				
Continuous (1x200–240 V) [A]	6.1	11.6	18.7	26.4
Intermittent (1x200–240 V) [A]	8.3	15.6	26.4	37

**Table 8: Mains Supply 3x380–480 V AC MA01a–MA02a**

Normal overload 150% for 1 minute						
Drive	01A2	02A2	03A7	05A3	07A2	09A0
Typical shaft output [kW (hp)]	0.37 (0.5)	0.75 (1.0)	1.5 (2.0)	2.2 (3.0)	3.0 (4.0)	4.0 (5.5)
Enclosure protection rating IP20	MA01a	MA01a	MA01a	MA02a	MA02a	MA02a
Output current						
Continuous (3x380–440 V) [A]	1.2	2.2	3.7	5.3	7.2	9.0
Intermittent (3x380–440 V) [A]	1.8	3.3	5.6	8.0	10.8	13.7
Continuous (3x440–480 V) [A]	1.1	2.1	3.4	4.8	6.3	8.2
Intermittent (3x440–480 V) [A]	1.7	3.2	5.1	7.2	9.5	12.3
Maximum cable size (Mains, motor) [mm²/AWG]	4/10					
Maximum input current						
Continuous (3x380–440 V) [A]	1.9	3.5	5.9	8.5	11.5	14.4
Intermittent (3x380–440 V) [A]	2.6	4.7	8.7	12.6	16.8	20.2
Continuous (3x440–480 V) [A]	1.7	3.0	5.1	7.3	9.9	12.4
Intermittent (3x440–480 V) [A]	2.3	4.0	7.5	10.8	14.4	17.5

**Table 9: Mains Supply 3x380–480 V AC MA03a–MA05a**

**Table 9: Mains Supply 3x380–480 V AC MA03a–MA05a**

Normal overload 150% for 1 minute						
Drive	12A0	15A5	23A0	31A0	37A0	43A0
Typical shaft output [kW (hp)]	5.5 (7.5)	7.5 (10)	11 (15)	15 (20)	18.5 (25)	22 (30)
Enclosure protection rating IP20	MA03a	MA03a	MA04a	MA04a	MA05a	MA05a
Output current	Data for MA03a to MA05a will be available in next release.					
Continuous (3x380–440 V) [A]						
Intermittent (3x380–440 V) [A]						
Continuous (3x440–480 V) [A]						
Intermittent (3x440–480 V) [A]						
Maximum cable size (Mains, motor) [mm²/AWG]						
Maximum input current						
Continuous (3x380–440 V) [A]						
Intermittent (3x380–440 V) [A]						
Continuous (3x440–480 V) [A]						
Intermittent (3x440–480 V) [A]						

## Ambient Conditions

<b>Protection rating</b>		IP20 (IP21/Type 1 conversion kit as option).
<b>Temperature during operation</b>		-10 °C to 50 °C (14 °F to 122 °F), up to 55 °C (131 °F) with derating.
<b>Temperature during storage/transport</b>		-25 °C to 65/70 °C (-13 °F to 149/158 °F).
<b>Relative humidity</b>		5–95%, non-condensing during operation.
<b>Altitude</b>		0–1000 m (3280 ft) without derating.
		1000–3000 m (3280–9243 ft) with derating of 1%/100 m (328 ft).
<b>Contamination level</b>	Storage	IEC 60721-3-1, Class 1C2 (aggressive gases), Class 1S11 (dust/sand).
	Transportation	IEC 60721-3-2, Class 2C2 (aggressive gases), Class 2S5 (dust/sand).
	Operation	IEC 60721-3-3, Class C4 (aggressive gases), Class 3S6 (dust/sand).
<b>Mechanical conditions</b>	Storage	IEC 60721-3-1, Class 1M11.
	Transportation	IEC 60721-3-2, Class 2M5.
	Operation	IEC 60721-3-3, Class 3M11.

## Mounting Clearance

**Table 10: Minimum Mounting Clearance**

Enclosure size	Minimum mounting clearance [maximum temperature 50 °C (122 °F)]
All enclosure sizes	Above and below: 100 mm (3.9 in).
MA01a–MA05a, MA02c	Sides: 0 mm (0 in).
MA01c (natural cooling)	Sides: 0 mm (0 in) for 40 °C (104 °F), 10 mm (0.39 in) and above for 50 °C (122 °F).

## EMC Compatibility and Motor Cable Length

iC2-Micro drive has 2 versions based on different EMC filter types:

(1) Drive with built-in EMC filter. (2) Drive with non built-in EMC filter

**Table 11: EMC Compatibility Motor Cable Length**

Drive with built-in EMC filter	Maximum motor cable length (shielded), @4kHz	
	C1 (Conducted)	C2 (Conducted)
1x200–240 V	5 m (16.4 ft)	–
3x400–480 V	–	15 m (49.2 ft)

**Table 12: Maximum Motor Cable Length**

Maximum motor cable length	Shielded	50 m (164 ft)
	Unshielded	75 m (246 ft)

- Drive with built-in EMC filter fulfills radiated emission C2 limits.
- Drive with non built-in EMC filter fulfills conducted/radiated emission C4 requirements, and shielded motor cable is recommended.
- The drive is designed to operate with optimum performance within the maximum motor cable lengths defined in Table 12 Maximum Motor Cable Length.

## Fuses and Circuit Breakers



iC2-Micro	Non cabinet					Cabinet						
	UL fuse				CE fuse	UL circuit breaker	CE circuit breaker	Test cabinet size [Height x Width x Depth] [mm (in)]	Minimum cabinet volume [L]			
kW (hp)	RK1	T	J	CC	gG	ABB	EATON					
Standard fault	Standard fault current rating 5 kA				–	5 kA	–					
High fault	–				–	65 kA	–					
1x200-240 V												
0.37 (0.5)	25 A					MS165-25	PKZM4-25	500 x 400 x 260 (19.7 x 15.7 x 10.2)	52			
0.75 (1.0)												
1.5 (2.0)	35 A					MS165-32	PKZM4-32					
2.2 (3.0)	40 A				50 A	MS165-42	PKZM4-50					
3x380-480 V												
0.37 (0.5)	15 A					16 A	MS165-16	PKZM0-16	500 x 400 x 260 (19.7 x 15.7 x 10.2)	52		
0.75 (1.0)												
1.5 (2.0)												
2.2 (3.0)	30 A					40 A	MS165-32	PKZM4-32				
3.0 (4.0)												
4.0 (5.5)												
5.5 (7.5)												
7.5 (10)	Data for MA03a to MA05a will be available in next release.											
11 (15)												
15 (20)												
18.5 (25)												
22 (30)												

## Accessories and Spare Parts

Accessories	Code number	Accessories	Code number
IP21/Type 1 conversion kit, MA01c	132G0188	Decoupling plate mounting kit, MA01c	132G0202
IP21/Type 1 conversion kit, MA02c	132G0189	Decoupling plate mounting kit, MA02c	132G0203
IP21/Type 1 conversion kit, MA01a	132G0190	Decoupling plate mounting kit, MA01a	132G0204
IP21/Type 1 conversion kit, MA02a	132G0191	Decoupling plate mounting kit, MA02/03a	132G0205
IP21/Type 1 conversion kit, MA03a	132G0192	Decoupling plate mounting kit, MA04/05a	132G0206
IP21/Type 1 conversion kit, MA04a	132G0193	Connector for common DC/brake resistor	132G0207
IP21/Type 1 conversion kit, MA05a	132G0194	HMI and related accessories	Not available currently.
NEMA 1 conversion kit, MA01c	132G0195		
NEMA 1 conversion kit, MA02c	132G0196		
NEMA 1 conversion kit, MA01a	132G0197		
NEMA 1 conversion kit, MA02a	132G0198		
NEMA 1 conversion kit, MA03a	132G0199	Harmonic and EMC filter	Refer to the Design Guide.
NEMA 1 conversion kit, MA04a	132G0200	Brake resistors	
NEMA 1 conversion kit, MA05a	132G0201	dU/dt filter	

Spare parts	Code number
Cooling fan	Refer to the Design Guide.
Spare parts kit	

## Technical Documentation

Scan the QR code (or, after scanning the QR code, click Global English to select your local region's website), and

search iC2 to access more technical documents.



## Danfoss A/S


Ulsnaes 1

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## Documents / Resources

	<a href="#">Danfoss MA01c iC2-Micro Frequency Converters</a> [pdf] Installation Guide MA01c iC2-Micro Frequency Converters, MA01c, iC2-Micro Frequency Converters, Frequency Converters
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## References

- [Global AC drive manufacturer - Danfoss Drives | Danfoss](#)