

# **CNC4PC C82 Multifunction Cnc Board User Manual**

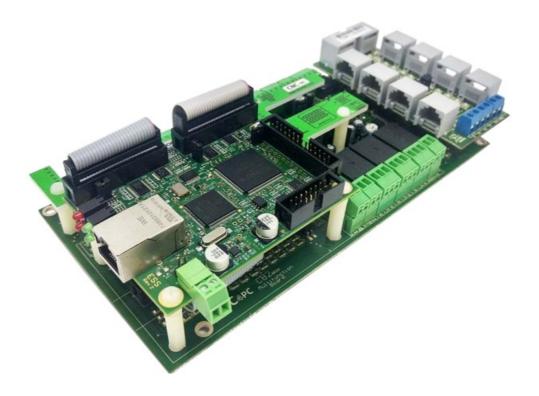
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**CNC4PC C82 Multifunction Cnc Board** 



#### **FEATURES**

- Designed for ESS AND ETHER-MACH motion controller.
- Built-in PWM-Based Speed Control and Two Built-in Electromechanical Relays with NO and NC positions for spindle control.
- The system monitors:
  - E-Stop.
  - Safety Charge Pump.
  - VFD Fault.
  - Driver Fault.
- Optoisolated inputs working at 5-24VDC.
- Outputs can be 500mA open collector or +5vdc at 50mA TTL.
- · Buffered outputs.
- Electromechanical Relay with NO and NC positions for general purpose (Port\_2 16 or 17, jumper-selectable).
- Microcontroller-based SCHP.
- Can be powered with a voltage +24VDC.
- Status LEDs on all input and Output connections.
- DIN Rail mountable.
- Pluggable Screw-On Terminals.
- It is compatible with family of C34 connector boards that allow quickly connecting to popular drives connecting not just the step and direction signals, but also the fault and enable signals.
- High speed input \*New

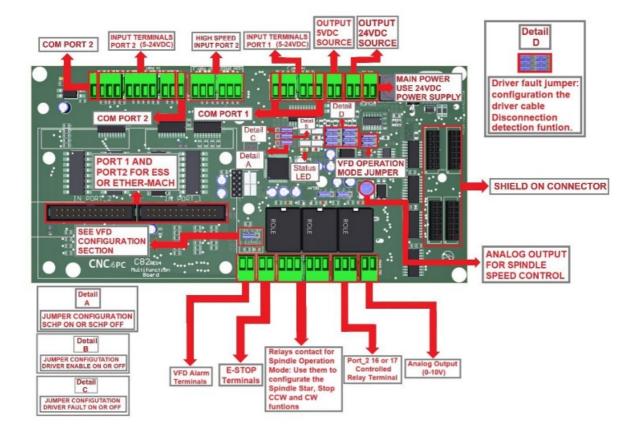
### I/O SPECIFICATIONS

OPTOISOLATED DIGITAL INPUT TTL SPECIFICATIONS				
On-state voltage range	5 to 24VDC			
Maximum off-state voltage	0.8V			
Typical signal delay	2.8uS			

DIGITAL OUTPUT TTL SPECIFICATIONS					
Maximum output voltage	5VDC				
Maximum output current	24mA				
Maximum off-state voltage	0.44 V				
Maximum supported frequency	400KHz				
Typical signal delay	10nS				
Time of transition to high impedance state	12nS				

OPEN COLLECTOR OUTPUT SPECIFICATIONS					
Number of outputs	4				
Maximum Supported output voltage	50VDC				
Typical output current (general purpose pins)	500mA				
Maximum supported frequency	250KHz				
Typical signal delay	Less than 8nS				

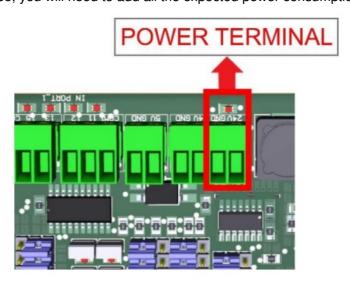
ENCODER INPUT	
On-state voltage	5 VDC
Maximum off-state voltage	0.8V
Typical signal delay	2.8uS
Rise / Fall Time (Typ)	50ns – 12ns



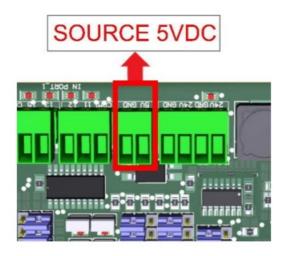
### **POWER TERMINALS AND CONFIGURATION JUMPERS**

#### **Power terminal**

The board requires an external power supply which can deliver 24VDC@700mA to power the logic of the board and the ESS or ETHER-MACH, but keep in mind that each output can deliver up to 500mA and if powering other breakout or relays boards. So, you will need to add all the expected power consumption.

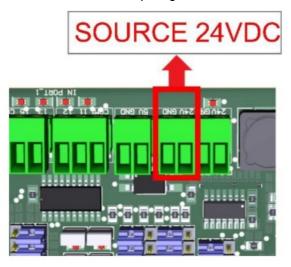


## **Source Output 5VDC**



## **Source Output 24VDC**

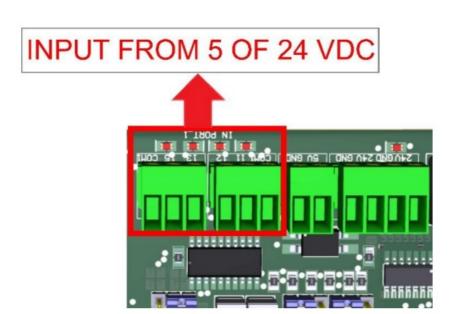
10-24VDC can be sourced to sensors or other cards requiring it.

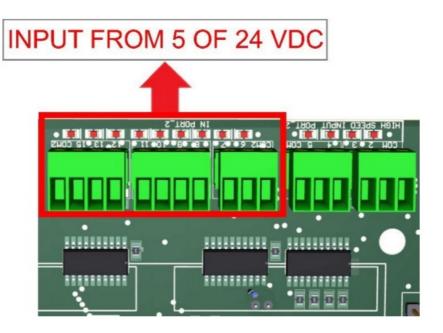


## Input terminals for port\_1 and port\_2

These terminals support signals 5-24VDC, you can connect sensors NPN, PNP, switches, capacitive sensors, etc.

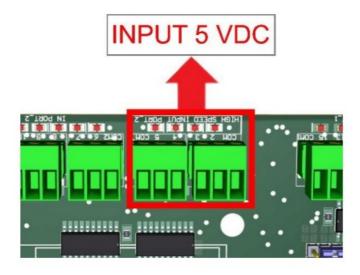
## PORT\_1



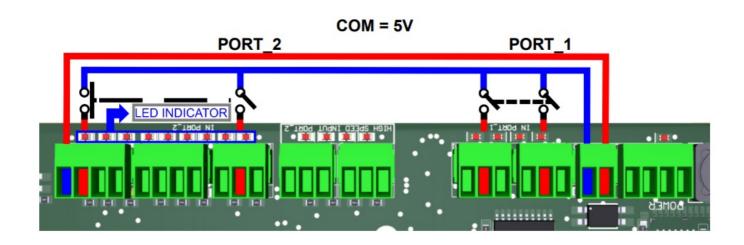


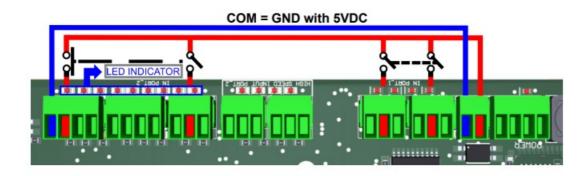
# HIGH SPEED INPUT PORT\_2 PIN 2, 3, 4 AND 5

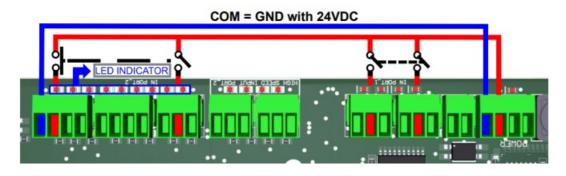
These terminals support signals 5VDC

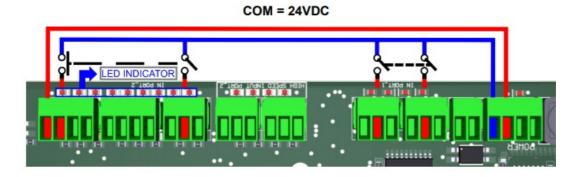


Select inputs of port\_1 and port\_2

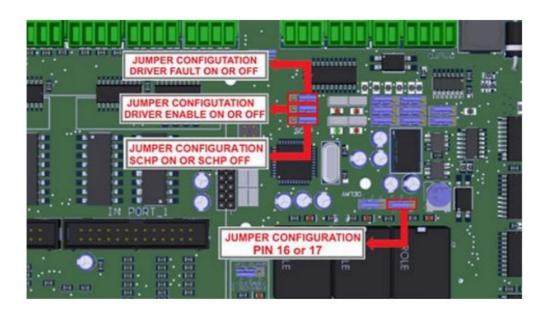








### **JUMPER POSITION**

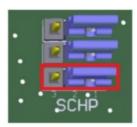


# Selecting the SCHP operation mode

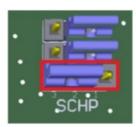
The Safety Charge Pump uses pin 17 on port 2. When the SCHP is enabled on the board, then the output of the terminals will be active while the Safety Charge Pump signal is present and inactive while the SCHP is not

present.

1-2: SCHP ON



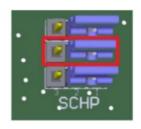
2-3: SCHP OFF



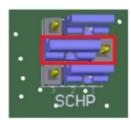
**Note:** also, that Relay3 on can also be tied to pin 17 or 16 on port 2. If the jumper is set to be tied to pin 17, then the relay will activate while the system is active. This can be ideal to control power to DC servos or to handle servo brakes. Or enable/disable any other feature that is associated to the system been active.

Jumper configuration driver enable

1-2: Driver enable ON

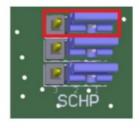


2-3: Driver enable OFF

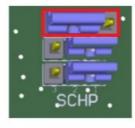


Jumper configuration driver fault

1-2: Driver fault ON



2-3: Driver fault OFF

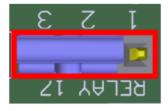


Configuration jumper pin 16 or 17

1-2: PIN17



2-3: PIN16

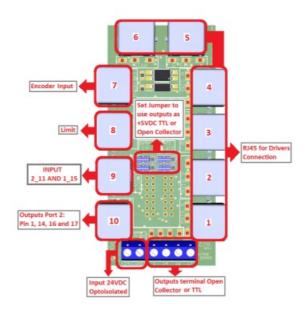


## **CONNECTION EXAMPLE FOR SHIELD C78**

RJ45 shield C78 connection for axes, Limits and Encoder



# RJ45 shield board description



# **Pinout**



RJ45_1 RJ45_2		145_2	RJ45_3		RJ45_4		RJ45_5		RJ45_6		
RJ45 PIN	P.P. PIN	RJ45 PIN	P.P. PIN	RJ45 PIN	P.P. PIN	RJ45 PIN	P.P. PIN	RJ45 PIN	P.P. PIN	RJ45 PIN	P.P. PIN
1	NC	1	NC	1	NC	1	NC	1	NC	1	NC
2	1_2(Step X)	2	1_4(Step Y)	2	1_6(Step Z)	2	1_8(Step A)	2	1_1(Step 5)	2	1_14(Step 6)
3	NC	3	NC	3	NC	3	NC	3	NC	3	NC
4	GND	4	GND	4	GND	4	GND	4	GND	4	GND
5	Error/res X	5	Error/res Y	5	Error/res Z	5	Error/res A	5	Error/res 5	5	Error/res 6
6	1_3(Dir X)	6	1_5(Dir Y)	6	1_7(Dir Z)	6	1_9(Dir A)	6	1_17(Dir 5)	6	1_16(Dir 6)
7	12/24VDC	7	12/24VDC	7	12/24VDC	7	12/24VDC	7	12/24VDC	7	12/24VDC
8	5VDC	8	5VDC	8	5VDC	8	5VDC	8	5VDC	8	5VDC

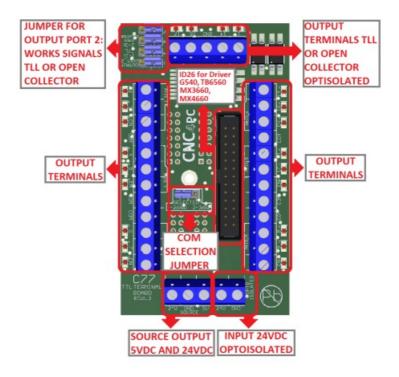
RJ45_7		RJ45_8		RJ45_9		RJ45_10		
RJ45 PIN	P.P. PIN	RJ45 PIN	P.P. PIN	RJ45 PIN	P.P. PIN	RJ45 PIN	P.P. PIN	
1	GND	1	GND	1	GND	1	GND	
2	5VDC	2	1_13	2	NC	2	2_17	
3	NC	3	1_12	3	NC	3	2_16	
4	2_4(INDEX)	4	1_11	4	2_11	4	2_1	
5	NC	5	1_15	5	1_15	5	2_14	
6	2_2(enc. A)	6	2_11	6	NC	6	NC	
7	NC	7	12/24VDC	7	12/24VDC	7	5VDC	
8	2_3(enc. B)	8	NC	8	NC	8	12/24VD0	

# **CONNECTION EXAMPLE FOR SHIELD C77**

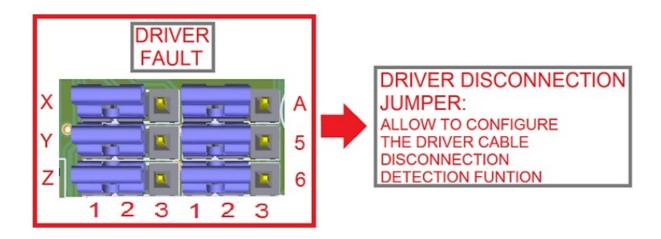
## **Terminal Shield Screw-on**



### Shield board description



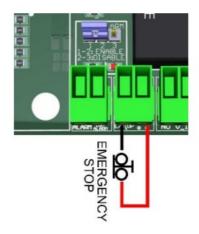
### **DRIVER DISCONNECTION JUMPERS**



**Nota:** 1-2: Cable disconnection detection. 2-3: No cable disconnection detection. This configures how cable disconnect is to work. Set according to C34 board manual.

### **E-STOP TERMINAL**

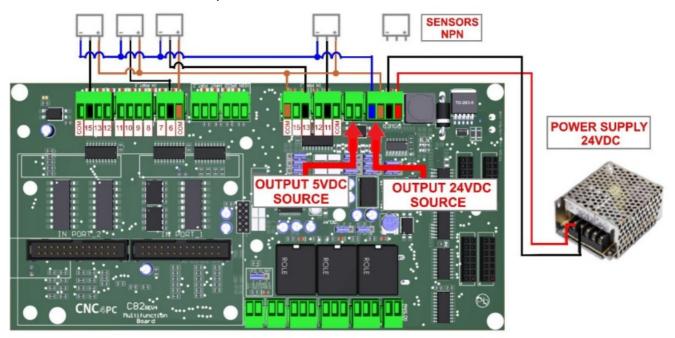
Connect an E-STOP push button as is shown in the below images.



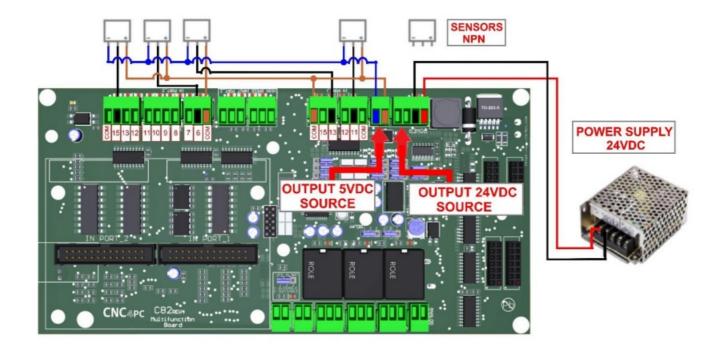
Pin 10 port 1 is used for E-Stop. Since this board controls the enable line, and the enable line is the one responsible for notifying the controller of the e-stop condition, the user does not have a direct access to the pin itself, just to the e-stop terminal on the board. The E-Stop terminal is tied to the enable line and will trigger the e-stop. A fault or E-Stop triggers a low for 5 seconds to notify the controller of the fault condition, then resets to high again.

### **TYPICAL CONNECTIONS**

· Connection with the terminal of output source of 24VDC

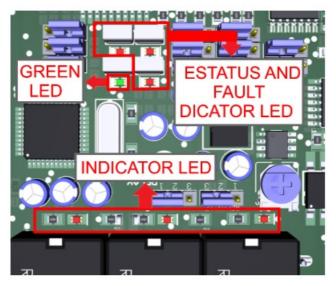


· Connection with the terminal of output source of 5VDC



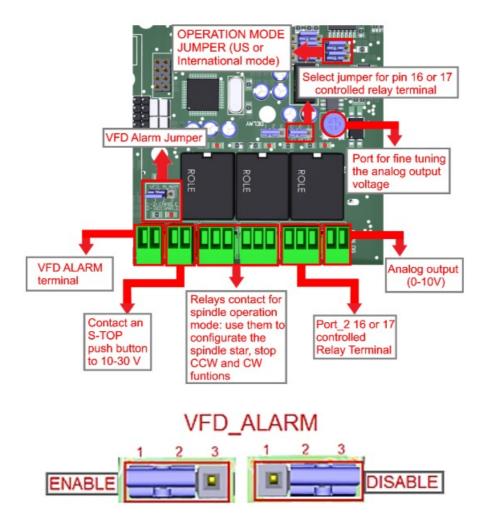
### **LED INDICATOR**

The standby LED lights indicate that the system is ready but disabled. When Status LED, (Green LED) lights, it indicates that the system is enabled. There are 4 possible error sources: a driver fault, E-STOP error, SCHP error or VFD alarm. A LED will light close to the source of the fault.



## VFD Connection and configuration jumper

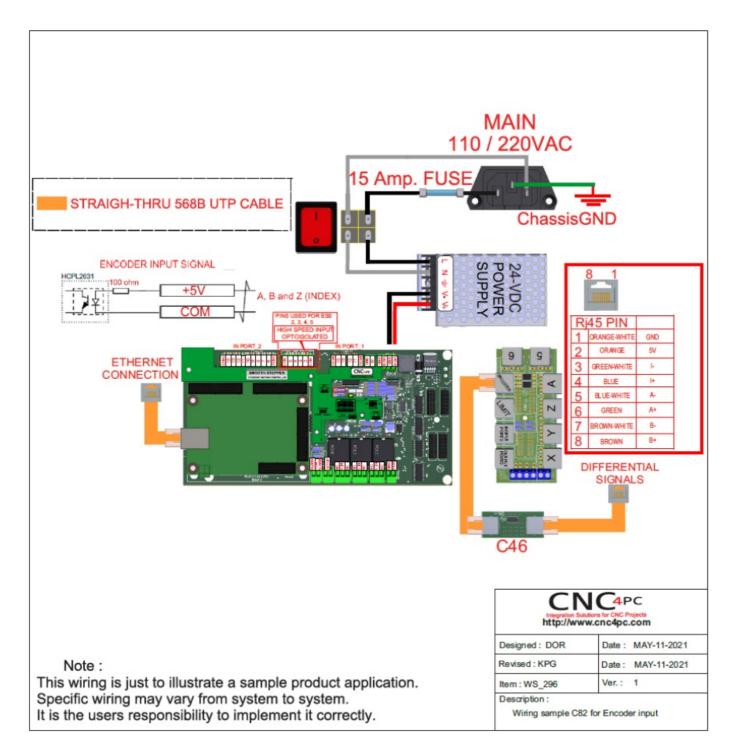
The VFD Alarm monitoring feature can be enabled or disabled:



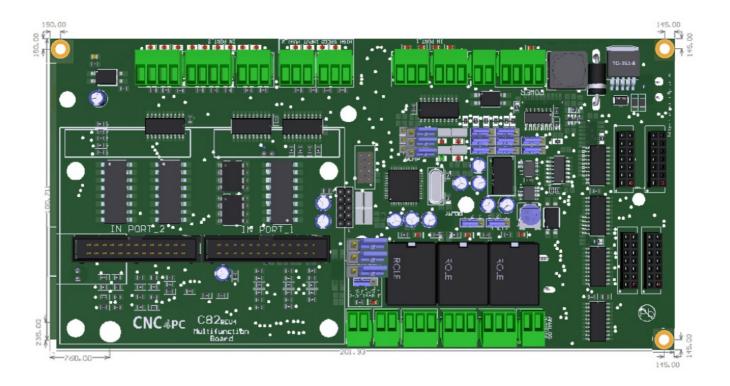
The VFD Alarm will trigger when the contacts are open and the VFD Alarm is enabled.

- For the Variable speed control go to http://cnc4pc.com/Tech\_Docs/VARIABLE\_SPEED\_CONTROL.pdf
- For Configure the control software go to http://cnc4pc.com/Tech\_Docs/CONFIGURATION\_OF\_CONTROL\_SOFWARE.pdf
- For Replacing Potentiometer go to http://cnc4pc.com/Tech\_Docs/Replacing%20a%20Potentiometer.pdf
- ESS MOTHER BOARD https://cnc4pc.com/ethernet-smooth-stepper-board.html

### **SAMPLE ENCODER WIRING**



#### **DIMENSIONS**



All dimensions are in Millimeters. Fixing holes (4mm).

#### Disclaimer:

Use caution. CNC machines can be dangerous machines. Neither DUNCAN USA, LLC nor Arturo Duncan is liable for any accidents resulting from the improper use of these devices. This product is not a fail-safe device and it should not be used in life support systems or in other devices where its failure or possible erratic operation could cause property damage, bodily injury or loss of life.

#### **Documents / Resources**



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