

# **BROWAN DW10 MerryloT Open/Close Sensor User Manual**

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**BROWAN DW10 MerryloT Open/Close Sensor** 



# **Description**

The MerryloT Open/Close sensor utilizes LoRaWAN connectivity to communicate the proximity or not of a magnet. The intended use is to place the sensor and magnet on separate elements of a door or window to determine if the door or window is open or closed. The sensor is composed of two parts. The main body contains active electronics to measure magnetic fields and transmit any changes to a LoRaWAN network. The second part is a permanent magnet of sufficient field strength to be detected by the Hall Effect sensor on the main body. There are also vibration and tilt detectors in case of tampering.

Once the event is detected, the sensor will send an uplink and keep a buzzer alarm (Optional).

# **Specifications**

#### Mechanical



Sensor

Length x Width x Height	90mm x 28mm x 40mm	
Weight	51g without battery 69g with battery	
Sensor	This sensor is designed for in- home and in-building usage for consum er or facility management applications.      Tamper detection (Vibration or tilt detection)	
	I Temperature/Humidity	

- Environmental
- Power
- Radio
- User Interface
- Certifications and Conformity
- Additional Features

Temperature	0°C to +50°C	Source	3.6V ½ AA Li-SOCI2 1200 mAH batt ery x2		
IP Rating	IP 40 equivalent	System Maximum Voltage	3.6V TBD		
2.4 Radio		System Minimum Voltage	3.1V TBD		
	Either 863-870 MHz for	Current	135mA maximum TBD		
	the EU model and 902-				
Frequency	928 MHz for North				
	America 2.5 User Interface				
		LED	One blue LED		
Rx Sensitivity (Conducted)	-140dBm	Hall Effect 14 Gauss trigger typi cal	1 CM		
Antenna Gain	-2dBi Peak, -5dBi Avg	Button	Test Button		
2.6 Certifications and Conformity		Buzzer	78 dB, 0 cm		

# Operation

#### **Installation Mode**

• Users need to press the button over 5 seconds to activate the operation into installation mode. When the Sensor tries to join the network, it will keep blinking for 3 seconds.

- Once the sensor joins the network, the LED will keep on for 3 seconds and send an uplink
- Users can press the button for over 5 seconds to try to join the network again.

#### **Default Operation**

- While in default operation the device will immediately send a message any time there is a transition and buzzer alarm (Optional) in the below event
  - Open to Close (No buzzer alarm)
  - Close to Open (Buzzer alarm)
  - Tamper detected (Vibration or tilt detected) (Buzzer alarm)
  - Button pressed (No buzzer alarm)
  - Keepalive message (No buzzer alarm)
- Users can press the button to send a test message to the network
- The device will send a message saying it has been inactive for 6 hours.
- While in default mode the device will flash the LED 3 times within 100ms only when the user presses the test button

#### Messages

LoRaWAN Packets for this device use port 120

#### **Status Triggers**

#### **Door Window Sensor Packet Triggers:**

- 360-minute inactivity
- · Switch Open
- · Switch Close

#### **Vibration Trigger:**

Immediately send a message

#### Tilt Trigger:

Immediately send a message

#### **Button Pressed Trigger:**

Immediately send a message

### **Uplink Payload**

Port	120
Payload Length	9 bytes

Bytes	0	1	2	3	4	5	6	7	8
Field	Status	Battery	Temp.	RH	Time		Count		

	Sensor's status		
	Bit [0]	1 - open, 0 - closed	
Status	Bit [1]	1 - Button pressed, 0 - Button released	
Status	Bit [2]	1 - Vibration detected, 0 - No Vibration detected	
	Bit [3]	1 - Tilt detected, 0 - No Tilt detected	
	Bits [7:4]	RFU	
	Battery level		
Battery	Bits [3:0]	unsigned value v, range 1 – 14. battery voltage in $V = (25 + v) \div 10$ .	
	Bits [7:4]	RFU	
	Environment Temperature		
Temp	Bits [7:0]	sign integer temperature in °C	
	-20~50 °C		
	Relative humidity a	as measured by the digital sensor	
RH	Bits [6:0]	unsigned value in %, range 0-100.	
	Bit [7]	RFU	
	Time elapsed since last event trigger		
Time	Bits [15:0]	unsigned value in minutes, range 0 – 65,535.	

	Total count of event triggers		
Count	Bits [23:0]	unsigned value, range 0 – 16,777,215.	
	Note: This value is n wer-cycled or reboot	ot stored persistently on the device and may reset whenever the device is poed.	

# **Configuration Downlink Command**

# **Configuration Command Payload**

Bytes	0	1	2
Field	Cmd	Config	

# Command 1 byte

Bit [7:0]

0x00 – Set keepalive interval. default: 21600 sec. (Min: 15 sec) 0x01 – Set sensor vibration detection on/off and set the tilt

detection on/off default: enable vibration low sensitivity, disable tilt detection 0x02 – Set buzzer alarm period(seconds) default: 0

Command	Command Description	Data Length
	Get Sensor Configuration	
0x00	(Only for unconfirmed downlink)	0 bytes
	*Note: little-endian format.	
	Set keepalive interval.	
0x00	*Note: little-endian format.	2 bytes
	Bit[1:0] =	
	00: Disable vibration detection	
	01: Enable vibration detection in low sensitivity 10: Enable vibration detect ion in medium sensitivity,	
	11: Enable vibration detection in high sensitivity Bit[3:2] = RFU	
	Bit[5:4] =	
0x01	00: Disable tilt detection	1 byte
	01: Enable tilt detection in high sensitivity (15) TBD Bit[7:6] = RFU	

0x02	Buzzer alarm period in seconds	1 byte
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# **Response Content**

# (Only for unconfirmed downlink)

- Port 204
- Payload Length 7 bytes
- Payload Content Response content
- Example:
- 00100e 0100 0200
- 00 100e => Keepalive interval: 0x0E10 -> 3600 (sec)
- 01 00 => Disable vibration detection and tilt detection
- 02 00 => Buzzer alarm period in 0 seconds

#### **Frame Count 1 Content**

- Payload Length 9 bytes
- Payload Content Frame count 1 content Ex:
- 01 03200000 7ff1f102
- 01 => command ID
- 00060000 => HW ID: 0x00002003 (little-endian format)
- 7ff1f102 => FW Version: 0x02f1f17f (little-endian format)

#### **Documents / Resources**



BROWAN DW10 MerryloT Open/Close Sensor [pdf] User Manual DW10, MerryloT Open Close Sensor, DW10 MerryloT Open Close Sensor

Manuals+, home privacy