

# AVNET i.MX 8M Plus Edge Board Al Kit User Manual

Home » AVNET » AVNET i.MX 8M Plus Edge Board Al Kit User Manual

# AVNET i.MX 8M Plus Edge Board Al Kit User Manual



# **Contents**

- **1 Revision History**
- 2 Summary
- 3 The BSP
- **4 Build Instructions**
- **5 Camera Development**
- 6 Appendix
- **7 Contact Information**
- 8 Documents /

**Resources** 

- 8.1 References
- 9 Related Posts

# **Revision History**

Version	Note	Author	Release Date
V1.0	Initial version	Monica	02/09/2023
V1.1	Updated support links and fixed formatting	Monica	05/12/2023

# Summary

The Avnet Edge AI Kit is a development kit created by Avnet. It includes the Avnet Embedded SMARC SoM based NXP's i.MX8M+ processor, Avnet Embedded's EP5 Carrier, and the SMARC camera adapter, which features dual onsemi image sensors and the AP1302 ISP. It also comes with a power supply and 10.1" touch display.



This document describes the basic Yocto development process for the Edge Al Kit.

# The BSP

The Edge AI Kit Yocto image is created using the i.MX8M+ BSP (board support package) developed by Avnet Embedded for their SMARC Carrier and SOM. In addition to the BSP, Avnet Embedded provides tools to make building an image and developing an application easier. These include:

- **SimpleSwitch:** A Software Development Kit (SDK) that makes it easy to develop an application (using C, Qt, Rust, Python, or Flutter) and test it on multiple Avnet Embedded platforms
- Scotty: A Yocto Development tool that uses Docker containers to provide a reproducible build environment
- SimpleCore Distro: Linux Distribution that includes all the configuration files to build a complete image.
- SimpleCore BSP: The full board support package that expert developers can configure

Avnet Embedded's BSPs are typically updated twice a year. The Edge AI Kit meta layer will be updated less frequently. Kirkstone is the earliest Yocto version that is supported. Please post on the forum at <a href="http://avnet.me/imx8mplus-support">http://avnet.me/imx8mplus-support</a> to request an update to the Edge AI Kit BSP

# Accessing the BSP

Currently, the BSP is hosted in private repositories on Avnet Embedded's Github. To access the board support package (BSP) to build your own Yocto image for the Edge Al Kit, please reach out on the forum: <a href="http://avnet.me/imx8mplus-support">http://avnet.me/imx8mplus-support</a>

In your post, please clearly state that you are working with the Edge Al Kit and would like the BSP.

## **Build Instructions**

# **Configure Build Machine**

Because the Avnet Embedded BSP uses Scotty, there is no need to install lots of dependencies on your build machine. Scotty makes the process of building on any Linux computer. It can also be run on Windows computers using WSL2.

# **Prerequisites**

I've shown the installation steps below using a desktop running Ubuntu 20.04 as my build machine. You'll need to install Docker, Python3, and Pip on your build machine.

# **Install Scotty**

These are the abbreviated steps. The complete steps to install Scotty are detailed in the SimpleCore Site Documentation.

Scotty requires OpenSSL

# sudo apt install docker.io openssl

You will likely be prompted to restart the Docker daemon.

Make sure your user is added to the group Docker with the following command:

# sudo gpasswd -a \${USER} docker

To allow scotty to download the associated docker image, you will need to run a docker login command, as documented on <a href="https://docs.github.com/en/packages/working-with-a-github-packages-registry/workingwith-the-container-registry/authenticating-to-the-container-registry/working-with-the-container-registry/authenticating-to-the-container-registry/working-with-the-container-registry/authenticating-to-the-container-registry/working-with-the-container-registry/authenticating-to-the-container-registry/working-with-the-container-registry/authenticating-to-the-container-registry/working-with-the-container-registry/authenticating-to-the-container-registry/working-with-

Install the Scotty tool with Pip:

# pip install -user avnet-scotty

You can also use Pip to update an existing installation:

pip install -user -upgrade avnet-scotty

# **Image Setup**

These steps are also documented on the README for the Edge Al Kit repo: <a href="https://github.com/avnetembedded/meta-avnet-edge-ai-kit/tree/kirkstone">https://github.com/avnetembedded/meta-avnet-edge-ai-kit/tree/kirkstone</a>

# Initialize the build repo

First, make sure that you are logged into Docker:

# docker login

Create a new directory to work from: <a href="https://www.avnet.com">https://www.avnet.com</a>

# mkdir edgeai-kit cd edgeai-kit

Update your credentials:

repo init -config-name\_ssh://git@github.com/avnet-embedded/simplecore-manifest.git

Make sure that the email you are using matches the one you used when signing up for Avnet Embedded's github.

Setup the repo to track remote branch to keep your version up to date:

## repo init -repo-rev=stable

Run scotty update to get the build files:

scotty update — <u>extra-download=git@github.com/avnet-embedded/meta-avnet-edge-ai-kit.git</u>

This creates a build folder with all relevant build files from Avnet Embedded's github.

# **Image Configuration with Scotty**

The Yocto configuration is created with the command:

# scotty setup

This will take you through numerically setting your machine, distro, layers, overlays, and image to build and accepting the licensing agreement.

Alternatively, you can set up with command line options by exporting your configuration:

Then run scotty setup with the layers set to edge ai kit:

# scotty setup -features-layers-set edge\_ai\_kit

Running scotty setup creates conf/local.conf and conf/bblayers.conf.

You are now ready to build the image (to build, skip to section 2.3).

# Notes about configuration options

Scotty provides several configuration options. These are meant to make it easy to build Yocto Linux images for a variety of Avnet Embedded boards using the same tool. Not all of the configuration options are relevant for the Edge AI Kit. These are noted below.

## **MACHINE**

The Edge Al Kit uses the sm2s-imx8plus machine. This machine is used for hardware based on Avnet Embedded i.MX8M Plus SoM. It allows support for all SoC features and includes DTBs for all variant and reference main

boards.

#### **DISTRO**

There are two available distros, SimpleCore, Avnet Embedded's distro, and Poky, the Yocto Project's Reference Distro. Currently, SimpleCore is the only distro that works with the Edge Al Kit.

#### **LAYERS**

In Scotty, the available set of layers are:

- BSP
- SimpleCore
- SimpleSwitch (not relevant to the Edge Al Kit)
- example (not relevant to the Edge Al Kit)
- edge\_ai\_kit this includes both the BSP and SimpleCore distro layers.

## **IMAGE**

There are four image configurations for the Edge Al Kit. These are selected for build when running bitbake:

Name	Comment	
demo	This is the base image. It doesn't include the Tensorflow Lite examples or other demos	
eiq-apps	This image includes eIQ framework as well as the Tensorflow Lite examples and Gstream er Neural Network inference examples	
qt	This is just the base image with Qt to run the Qt camera app to open Qt camera and strea m AP1302 video stream on Qt Camera app	
stereo-vision	This is built on top of QT and includes the sample application found here: <a href="https://github.c.om/Avnet/stereovision-app">https://github.c.om/Avnet/stereovision-app</a> More notes on the stereovision application can be found in the <a href="http://avnet.me/edgeaikit-stereovision">https://github.c.om/Avnet/stereovision-app</a> More notes on the stereovision application can be found in the <a href="http://avnet.me/edgeaikit-stereovision">https://avnet.me/edgeaikit-stereovision</a>	

## **OVERLAYS**

The device tree overlays allow for cameras, displays, and other accessories. There are several to choose from

# **Build the image**

Run the scotty bitbake command to build your desired image. In this case, we are building the demo image:

# scotty command bitbake -k avnet-edge-ai-kit-demo

To build the eiq-apps image, you would run the command:

# scotty command bitbake -k avnet-edge-ai-kit-eiq-apps

The image as well as the overlays will be built in the folder:

/build/build/tmp/deploy/images/sm2s-imx8plus

The SD card bootable image with the root file system included has the naming convention:

"avnet-edge-ai-kit-[image name]-sm2s-imx8plus-[date string].rootfs.wic"

E.G. avnet-edge-ai-kit-qt-sm2s-imx8plus-20230210230256.rootfs.wic

For image flashing, system power on, boot up, and the features of the Edge Al Kit, please refer to i.MX\_8M\_Plus\_Edge\_Al\_Kit-Linux-Yocto-UserManual-V\*.\*.pdf.

# **Camera Development**

The driver and firmware for the AP1302 are available publicly on Avnet's github:

- https://github.com/Avnet/ap1302-driver
- https://github.com/Avnet/ap1302-firmware

#### The AP1302 Driver

The Edge AI Kit BSP depends on the driver and firmware for the AP1302 ISP. The recipe ap1302- module-firmware.bb pulls the driver in from Avnet's github.

The compiled AP1302 firmware XML files are incorporated in the driver repo to keep them in sync. They can be found in the fw directory. They are converted from XML to BIN using the python script included in this directory.

This driver is responsible of loading a firmware into the ap1302 chip and configures a v4l subsytem.

The driver will load the firmware corresponding to the camera sensor model configured in the device tree. Then it will configure a v4l subsystem with one source pad and a fixed resolution.

# The AP1302 Firmware

The AP1302 firmware repo includes sources needed to generate AP1302 firmware.

To generate firmware, the DevWareX tool is required. The software along with documentation can be found on onsemi's Atlassian page: <a href="https://aptina.atlassian.net/wiki/spaces/DEVS/pages">https://aptina.atlassian.net/wiki/spaces/DEVS/pages</a>

Firmware can either be generated as a binary (BIN) or XML files

## **Appendix**

# **Hardware**

For the detail hardware introduction, please refer to Edge Al Kit Hardware User Manual found on the Avnet Boards page here: <a href="http://avnet.me/imx8mplus-edgeai">http://avnet.me/imx8mplus-edgeai</a>

## Software

For the detail software introduction, please refer to the Edge Al Kit Yocto Linux Software User Manual found on the Avnet Boards page here: <a href="http://avnet.me/imx8mplus-edgeai">http://avnet.me/imx8mplus-edgeai</a>

#### **Yocto Linux**

- Edge Al Kit Yocto Linux Software User Manual
- · Edge Al Kit Yocto Linux Software Development Guide

## **Contact Information**

· Website:

http://avnet.me/imx8mplus-edgeai

Forum:

http://avnet.me/imx8mplus-support



#### **Documents / Resources**

i.MX 8M Plus Edge Al Kit Linux Yocto Developer Guide V1.1

AVNET i.MX 8M Plus Edge Board Al Kit [pdf] User Manual i.MX 8M Plus Edge Board Al Kit, i.MX 8M Plus, Edge Board Al Kit, Kit, Kit

## References

- ▲ Stereo Vision Depth Perception on the Edge Al Kit Hackster.io
- ▲ Avnet i.MX 8M Plus Edge Al Kit | Avnet Boards
- <u>∆i.MX 8M+ Edge Al Kit element14 Community</u>
- <u>Docker: Accelerated Container Application Development</u>
- O Confluence
- • Working with the Container registry GitHub Docs
- △ i.MX8 BSP Layer SimpleCore documentation
- Δ <u>SimpleCore distribution layers</u> <u>SimpleCore documentation</u>
- △ SimpleSwitch SimpleCore documentation
- Δ The Scotty tool SimpleCore documentation
- GitHub Avnet/ap1302-driver: Driver files needed for AP1302 driver module
- I GitHub Avnet/stereovision-app: Stereo Vision QT app created for Edge Al Kit demo
- Avnet: Quality Electronic Components & Services
- Avnet i.MX 8M Plus Edge Al Kit | Avnet Boards
- Single-Board Computers element14 Community

- OS /index.html
- User Manual

Manuals+,