

Autonics EP50 Series 50mm Diameter Absolute Single Turn Rotary Encoders Instruction Manual

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Manual

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50 mm Diameter Absolute Single-Turn Rotary Encoders (Optical)

EP50 Series

INSTRUCTION MANUAL

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc. are subject to change without notice for product improvement. Some models may be discontinued without notice.

Follow Autonics website for the latest information.

Safety Considerations

- Observe all `Safety Considerations' for safe and proper operation to avoid hazards.
- \triangle symbol indicates caution due to special circumstances in which hazards may occur.



Warning Failure to follow instructions may result in serious injury or death.

01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.)

Failure to follow this instruction may result in personal injury, economic loss or fire.

02. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

03. Install on a device panel to use.

Failure to follow this instruction may result in fire.

04. Do not connect, repair, or inspect the unit while connected to a power source.

Failure to follow this instruction may result in fire.

05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.

06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire.



Caution Failure to follow instructions may result in injury or product damage.

01. Use the unit within the rated specifications.

Failure to follow this instruction may result in fire or product damage.

02. Do not short the load.

Failure to follow this instruction may result in fire.

03. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.

Failure to follow this instruction may result in product damage.

Cautions during Use

- Follow instructions in `Cautions during Use'.
 - Otherwise, It may cause unexpected accidents.
- 5 VDC ____, 12 24 VDC ____ power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.),
 ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.

- When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments.
 - Indoors (in the environment condition rated in `Specifications')
 - Altitude max. 2,000 m
 - Pollution degree 2
 - Installation category II

Cautions during Installation

- Install the unit correctly with the usage environment, location, and the designated specifications.
- Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft.
 Failure to follow this instruction may result in product damage.
- When fixing the product or coupling with a wrench, tighten under 0.15 N m.
- If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be shorten.
- Do not apply tensile strength over 30 N to the cable.

Ordering Information

This is only for reference, the actual prodcut does not support all combinations. For selecting the specified model, follow the Autonics website.

EP50 S 8 - **0** - **2 3** - **3**

1 Resolution

Number: Refer to resolution in 'Output

Phase / Output Angle'

2 Output code

- 1: BCD code
- 2: Binary code
- 3: Gray code

3 Rotating direction

F: Increase output when the rotating direction is clockwise base on facing the shaft

R: Increase output when the rotating direction is counter-clockwise base on facing the shaft

4 Control output

N: NPN open collector output

P: PNP open collector output

5 Power supply

5: 5 VDC ±5%

24: 12 - 24 VDC ±5%

Product Components

- Product
- · Instruction manual
- Bolt × 8
- Coupling × 1
- Bracket × 2

Connections

- Unused wires must be insulated.
- The metal case and shield cable of encoders must be grounded (F.G.).
- F.G. (Frame Ground) must be grounded separately.
- Since exclusive driver IC is used for output circuit, be aware of short circuits when wiring each output wires.
- N·C: not connected

BCD code

Color	Function	Refer
White	+V	Power
Black	GND	Fower
Brown	2°	
Red	21	
Orange	22	
Yellow	23	
Blue	2° × 10	
Purple	21 × 10	
Gray	2 ² × 10	
White / Brown	2 ³ × 10	TP1 (≤40 division)
White / Red	2° × 10²	TP2 (≤40 division)
White / Orange	21 × 102	EP (≤40 division)
White / Yellow	2 ² × 10 ²	
White / Blue	2 ³ × 10 ²	
White / Purple	2° × 10³	
Shield	F.G.	Signal shield

Binary / Gray code

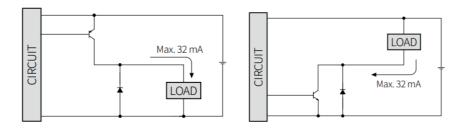
Color	Function	Refer	
White	+V	Power	
Black	GND		
Brown	2°		
Red	21		
Orange	22		
Yellow	23		
Blue	24		
Purple	25		
Gray	26		
White / Brown	27	TP1 (≤40 division)	
White / Red	28	TP2 (≤40 division)	
White / Orange	29	EP (≤40 division)	
White / Yellow	N.C		
White / Blue	N.C		
White / Purple	N.C		
Shield	F.G.	Signal shield	

Inner Circuit

- The output circuit is identical for each output bit.
- Be aware of circuit break in case of overload or short beyond the specifications.

PNP open collector output

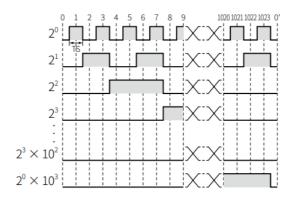
NPN open collector output



Output Waveform

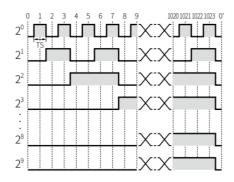
Following waveform is based on the positive logic.
 (In case of negative logic, the waveform is opposite to corresponding waveform.)

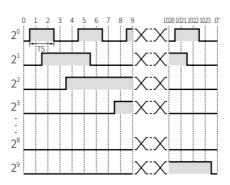
BCD code output



Binary code output

Gray code output





Specifications

Model	EP50S8 –	EP50S8-	
Resolution ⁰¹⁾	≤1024 division		
Output code	BCD / Binary / Gray code model		
Control output	NPN open collector output PNP open collector output		
Inflow current	≤ 32 mA	-	
Residual voltage	≤ 1 VDC ====	-	
Outflow current	-	≤ 32 mA	
Output voltage	-	≥ (power supply -1.5) VDC ===	
Response speed ⁰²⁾	T _{on} ≤800 nsec, T _{off} ≤800 nsec		
Max. response freq.	35 kHz		
Max. allowable revolution ⁰³⁾	3,000 rpm		
Starting torque	≤ 0.0069 N m		
Inertia moment	≤ 40 g·cm² (4 × 10 ⁻⁶ kg·m²)		
Allowable shaft load	Radial: 10 kgf, Thrust: 2.5 kgf		
Unit weight (packaged)	≈398 g (≈ 482 g)		
Approval	C € ERI		

⁰¹⁾Refer to resolution in 'Output Phase / Output Angle'.

[max. response revolution (rpm) = max. response frequency/ resolution \times 60 sec]

⁰²⁾Based on cable length: 2 m, I sink = 32 mA

⁰³⁾Select resolution to satisfy Max. allowable revolution ≥Max. response revolution

Power supply	5 VDC === ± 5% (ripple P-P. ≤ 5%) / 12 – 24 VDC === ± 5% (ripple P-P ≤ 5%) model	
Current consumpti on	≤ 100 mA (no load)	
Insulation resistan	Between all terminals and case. ≥ 100 MΩ (500 VDC === megger)	
Dielectric strength	Between all terminals and case: 750 VAC~50 / 60 Hz for 1 minute	
Vibration	1 mm double amplitude at frequency 10 to 55 Hz (for 1 minute) in each X, Y, Z direction f or 2 hours	
Shock	≲ 50 G	
Ambient temp.	-10 to 70 °C, storage: -25 to 85 °C (no freezing or condensation)	
Ambient humi.	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)	
Protection rating	IP64 (IEC standard)	
Connection	Axial cable type (cable gland)	
Cable spec.	Ø 7 mm, 15-wire, 2m, shield cable	
Wire spec.	AWG28 (0.08 mm, 40-core), insulator diameter: Ø 0.8 mm	

Output Phase / Output Angle

- TP = Timing Pulse
- TS = Signal Pulse
- EP = Even Parity

Resolution	BCD code	Binary code	Gray code
1024	TS: 0.3515° ±15′ (13 bit)	TS: 0.3515° ±15′ (10 bit)	TS: 0.703° ±15′ (10 bit)
720	TS: 0.5° ±25′ (11 bit)	TS: 0.5° ±25′ (10 bit)	TS: 1° ±25′ (10 bit)
512	TS: 0.703° ±15′ (11 bit)	TS: 0.703° ±15′ (9 bit)	TS: 1.406° ±15′ (9 bit)
360	TS: 1° ±25′ (10 bit)	TS: 1° ±25′ (9 bit)	TS: 2° ±25′ (9 bit)

256	TS: 1.406° ±15′ (10 bit)	TS: 1.406° ±15′ (8 bit)	TS: 2.8125° ±15′ (8 bit)
180	TS: 2° ±25′ (9 bit)	TS: 2° ±25′ (8 bit)	TS: 4° ±25′ (8 bit)
128	TS: 2.8125° ±15′ (9 bit)	TS: 2.8125° ±15′ (7 bit)	TS: 5.625° ±15′ (7 bit)
90	TS: 4° ±25′ (8 bit)	TS: 4° ±25′ (7 bit)	TS: 8° ±25′ (7 bit)
64	TS: 5.625° ±15′ (7 bit)	TS: 5.625° ±15′ (6 bit)	TS: 11.25° ±15′ (6 bit)
48	TS: 7.5° ±25′ (7 bit)	TS: 7.5° ±25′ (6 bit)	TS: 15° ±25′ (6 bit)
45	TS: 8° ±25′ (7 bit)	TS: 8° ±25′ (6 bit)	TS: 16° ±25′ (6 bit)
40	TP1: 5° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 9° ±60′ (6 bit) EP: 9° ±60′ (1 bit)	TP1: 5° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 9° ±60′ (6 bit) EP: 9° ±60′ (1 bit)	TP1: 5° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 18° ±60′ (6 bit) EP: 9° ±60′ (1 bit)
32	TP1: 7° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 11.25° ±60′ (6 bit) EP: 11.25° ±60′ (1 bit)	TP1: 7° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 11.25° ±60′ (5 bit) EP: 11.25° ±60′ (1 bit)	TP1: 7° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 22.5° ±60′ (5 bit) EP: 11.25° ±60′ (1 bit)
24	TP1: 8° ±60′ (1 bit) TP2: 3° ±60′ (1 bit) TS: 15° ±60′ (6 bit) EP: 15° ±60′ (1 bit)	TP1: 8° ±60′ (1 bit) TP2: 3° ±60′ (1 bit) TS: 15° ±60′ (5 bit) EP: 15° ±60′ (1 bit)	TP1: 8° ±60′ (1 bit) TP2: 3° ±60′ (1 bit) TS: 30° ±60′ (5 bit) EP: 15° ±60′ (1 bit)

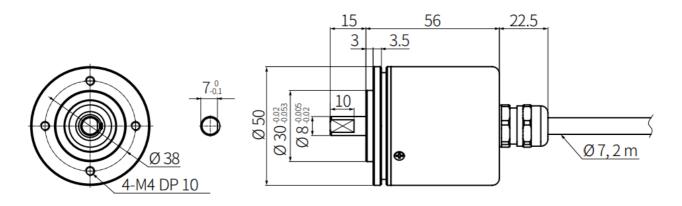
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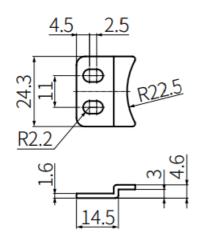
20	TP1: 12° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 18° ±60′ (5 bit) EP: 18° ±60′ (1 bit)	TP1: 12° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 18° ±60′ (5 bit) EP: 18° ±60′ (1 bit)	TP1: 12° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 36° ±60′ (5 bit) EP: 18° ±60′ (1 bit)
16	TP1: 15° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 22.5° ±60′ (5 bit) EP: 22.5° ±60′ (1 bit)	TP1: 15° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 22.5° ±60′ (4 bit) EP: 22.5° ±60′ (1 bit)	TP1: 15° ±60′ (1 bit) TP2: 2° ±60′ (1 bit) TS: 45° ±60′ (4 bit) EP: 22.5° ±60′ (1 bit)
12	TP1: 15° ±60′ (1 bit) TP2: 3° ±60′ (1 bit) TS: 30° ±60′ (5 bit) EP: 30° ±60′ (1 bit)	TP1: 15° ±60′ (1 bit) TP2: 3° ±60′ (1 bit) TS: 30° ±60′ (4 bit) EP: 30° ±60′ (1 bit)	TP1: 15° ±60′ (1 bit) TP2: 3° ±60′ (1 bit) TS: 60° ±60′ (4 bit) EP: 30° ±60′ (1 bit)
10	TP1: 30° ±60′ (1 bit) TP2: 12° ±60′ (1 bit) TS: 36° ±60′ (4 bit) EP: 36° ±60′ (1 bit)	TP1: 30° ±60′ (1 bit) TP2: 12° ±60′ (1 bit) TS: 36° ±60′ (4 bit) EP: 36° ±60′ (1 bit)	TP1: 30° ±60′ (1 bit) TP2: 12° ±60′ (1 bit) TS: 72° ±60′ (4 bit) EP: 36° ±60′ (1 bit)
8	TP1: 39° ±60′ (1 bit) TP2: 15° ±60′ (1 bit) TS: 45° ±60′ (3 bit) EP: 45° ±60′ (1 bit)	TP1: 39° ±60′ (1 bit) TP2: 15° ±60′ (1 bit) TS: 45° ±60′ (3 bit) EP: 45° ±60′ (1 bit)	TP1: 39° ±60′ (1 bit) TP2: 15° ±60′ (1 bit) TS: 90° ±60′ (3 bit) EP: 45° ±60′ (1 bit)
6	TP1: 53° ±60′ (1 bit) TP2: 15° ±60′ (1 bit) TS: 60° ±60′ (3 bit) EP: 60° ±60′ (1 bit)	TP1: 53° ±60′ (1 bit) TP2: 15° ±60′ (1 bit) TS: 60° ±60′ (3 bit) EP: 60° ±60′ (1 bit)	TP1: 53° ±60′ (1 bit) TP2: 15° ±60′ (1 bit) TS: 120° ±60′ (3 bit) EP: 60° ±60′ (1 bit)

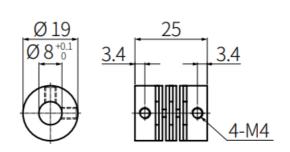
Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.



Bracket Coupling





• Parallel misalignment: ≤ 0.25 mm

• Angular misalignment: ≤ 5°

• End-play: ≤ 0.5 mm

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Autonics

Documents / Resources



<u>Autonics EP50 Series 50mm Diameter Absolute Single Turn Rotary Encoders</u> [pdf] Instruct ion Manual

EP50S series, EP50 Series 50mm Diameter Absolute Single Turn Rotary Encoders, EP50 Series, 50mm Diameter Absolute Single Turn Rotary Encoders, Absolute Single Turn Rotary Encoders, Single Turn Rotary Encoders, Encoders

References

• A autonics.com

Manuals+,