



# AUTONICS E50 Series Incremental Rotary Encoders Instruction Manual

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# Autonics

**E50 Series Incremental Rotary Encoders**



## Product Information

- **Product Name:** Transparent Guide 50 mm Diameter Incremental Rotary Encoders E50 Series
- **Model Number:** TCD210020AA
- **Output Phases:** 2 (A, B), 3 (A, B, Z), 4 (A, A, B, B), 6 (A, A, B, B, Z, Z)
  - Control Output: Totem pole output (T), NPN open collector output (N), Voltage output (V), Line driver output (L)
- **Max Load:** Totem pole output and Voltage output (30 mA), NPN open collector output and Line driver output (10 mA)

## Usage Instructions

- **Safety Considerations**
  1. Install a fail-safe device when using the encoder with machinery that may cause serious injury or substantial economic loss.
  2. Avoid using the encoder in places where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present.
  3. Install the encoder on a device panel to use it.
  4. Do not connect, repair, or inspect the encoder while it is connected to a power source.
  5. Check connections before wiring the encoder.
  6. Do not disassemble or modify the encoder.
- **Cautions**
  1. Use the encoder within its rated specifications.
  2. Do not short the load.
  3. Avoid using the encoder near equipment that generates strong magnetic force or high-frequency noise and strong alkaline/strong acidic substances.
- **Cautions during Use**
  1. Refer to the specifications and select the specified model from the Autonics website.
- **Cautions during Installation**

1. Refer to the M17 6-pin layout or M17 9-pin layout for the connections.

## Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- symbol indicates caution due to special circumstances in which hazards may occur.

Warning: Failure to follow instructions may result in serious injury or death.

1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime / disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
2. Do not use the unit in the place where flammable / explosive / corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present. Failure to follow this instruction may result in explosion or fire.
3. Install on a device panel to use. Failure to follow this instruction may result in fire.
4. Do not connect, repair, or inspect the unit while connected to a power source. Failure to follow this instruction may result in fire.
5. Check 'Connections' before wiring. Failure to follow this instruction may result in fire.
6. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire.

**Caution:** Failure to follow instructions may result in injury or product damage.

1. Use the unit within the rated specifications. Failure to follow this instruction may result in fire or product damage.
2. Do not short the load. Failure to follow this instruction may result in fire.
3. Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists. Failure to follow this instruction may result in product damage.

## Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.
- 5 VDC, 12 – 24 VDC power supply should be insulated and limited voltage / current or Class 2, SELV power supply device.
- For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.
- When supplying power with SMPS, ground the F.G. terminal and connect the noise canceling capacitor between the 0 V and F.G. terminals.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- For Line driver unit, use the twisted pair wire which is attached seal and use the receiver for RS-422A communication.

- Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc. by line resistance or capacity between lines.
- This unit may be used in the following environments.
  - Indoors (in the environment condition rated in `Specifications`)
  - Altitude max. 2,000 m
  - Pollution degree 2
  - Installation category II

## Cautions during Installation

- Install the unit correctly with the usage environment, location, and the designated specifications.
- Do not load overweight on the shaft.
- Do not put strong impact when insert a coupling into shaft. Failure to follow this instruction may result in product damage.
- When fixing the product or coupling with a wrench, tighten under 0.15 N m.
- If the coupling error (parallel misalignment, angular misalignment) between the shaft increases while installation, the life cycle of the coupling and the encoder can be shorten.
- Do not apply tensile strength over 30 N to the cable.

## Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.



### Resolution

Number: Refer to resolution in `Specifications`

### Output phase

- 2: A, B
- 3: A, B, Z
- 4: A, A, B, B
- 6: A, A, B, B, Z, Z

### Control output

- T: Totem pole output
- N: NPN open collector output
- V: Voltage output
- L: Line driver output

### Power supply

- 5: 5 VDC  $\pm$  5%
- 24: 12 – 24 VDC  $\pm$  5%

### Connection

- No mark: Axial cable type
- C: Axial cable connector type
- CR: Axial connector type
- CS: Radial connector type

### Product Components

- Product
- Instruction manual
- Bolt  $\times$  7
- Coupling  $\times$  1
- Bracket  $\times$  1

### Sold Separately

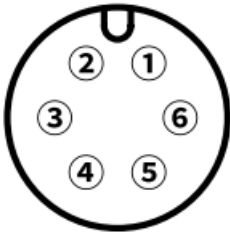
- Connector cable: CID6S-, CID9S-

### Connections

- Unused wires must be insulated.
- The metal case and shield cable of encoders must be grounded (F.G.).
- F.G. (Frame Ground) must be grounded separately.

### Totem pole / NPN open collector / Voltage output

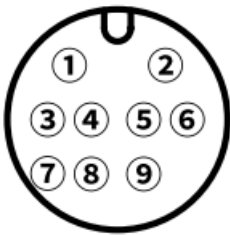
#### • M17 6-pin layout



Pin	Color	Function	Pin	Color	Function
1	Black	OUT A	4	Brown	+V
2	White	OUT B	5	Blue	GND
3	Orange	OUT Z	6	Shield	F.G.

Line driver output

• M17 9-pin layout

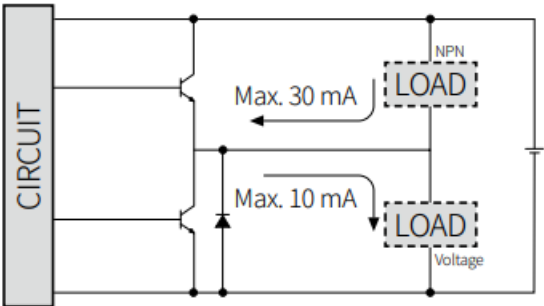


Pin	Color	Function	Pin	Color	Function
1	Black	OUT A	5	White	OUT B
2	Red	OUT A	6	Gray	OUT B
3	Brown	+V	7	Orange	OUT Z
4	Blue	GND	8	Yellow	OUT Z
–			9	Shield	F.G.

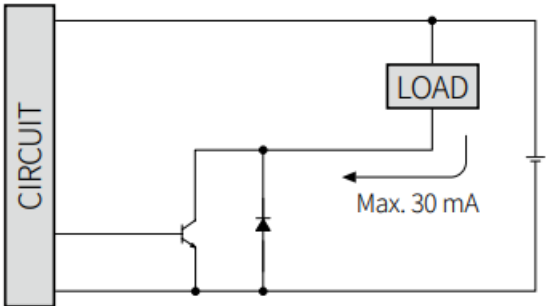
Inner Circuit

- Output circuits are identical for all output phase.

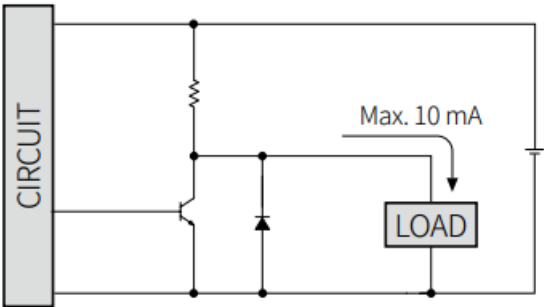
■ Totem pole output



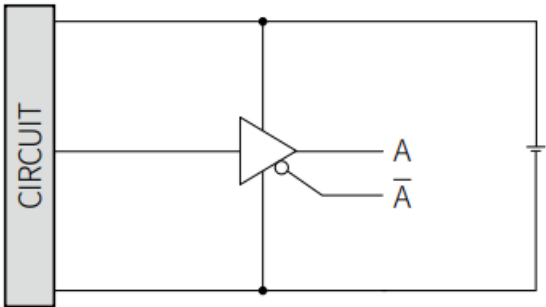
■ NPN open collector output



■ Voltage output

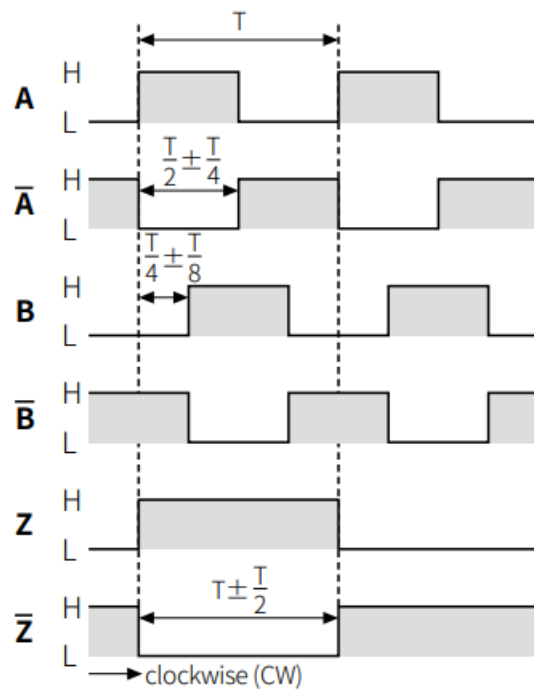
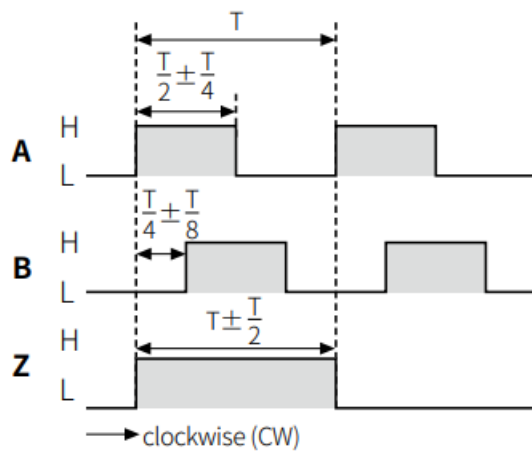


■ Line driver output



Output Waveform

- The rotation direction is based on facing the shaft, and it is clockwise (CW) when rotating to the right. T T
- Phase difference between A and B: 4±8 (T = 1 cycle of A)



## Specifications

Model	E50S8-□-□-T-□-□	E50S8-□-□-N-□-□	E50S8-□-□-V-□-□	E50S8-□-□-L-□-□
Resolution	1 / 2 / 5 PPR <sup>01)</sup> 10 to 8,000 PPR model			
Control output	Totem pole output	NPN open collector output	Voltage output	Line driver output
Output phase	A, B, Z	A, B, Z	A, B, Z	A, A, B, B, Z, Z
Inflow current	≤ 30 mA	≤ 30 mA	—	≤ 20 mA
Residual voltage	≤ 0.4 VDC	≤ 0.4 VDC	≤ 0.4 VDC	≤ 0.5 VDC
Outflow current	≤ 10 mA	—	≤ 10 mA	≤ -20 mA
Output voltage (5 VDC )	≥ (power supply -2.0) VDC	—	—	≥ 2.5 VDC
Output voltage (12 – 24 VDC )	≥ (power supply -3.0) VDC	—	—	≥ (power supply -3.0) VDC
Response speed <sup>02)</sup>	≤ 1			≤ 0.5
Max. response freq.	300 kHz			
Max. allowable revolution <sup>03)</sup>	5,000 rpm			
Approval				

1. Depending on the control output, only A, B or A, A, B, B are output.
2. Based on cable length: 2 m, I sink: 20 mA
3. Select resolution to satisfy Max. allowable revolution Max. response revolution

[max. response revolution (rpm) = max. response frequency/resolution × 60 sec]

Connection	Axial cable type	Axial cable connector type	Axial connector type	Radial connector type
Starting torque	≤ 0.007 N m		≤ 0.078 N m	
Inertia moment	≤ 80 g·cm <sup>2</sup> (8 × 10 <sup>-6</sup> kg·m <sup>2</sup> )		≤ 400 g·cm <sup>2</sup> (4 × 10 <sup>-5</sup> kg·m <sup>2</sup> )	
Allowable shaft load	Radial: ≤ 10 kgf, Thrust: ≤ 2.5 kgf			
Unit weight (packaged)	≈ 275 g (≈ 363 g)		≈ 180 g (≈ 268 g)	

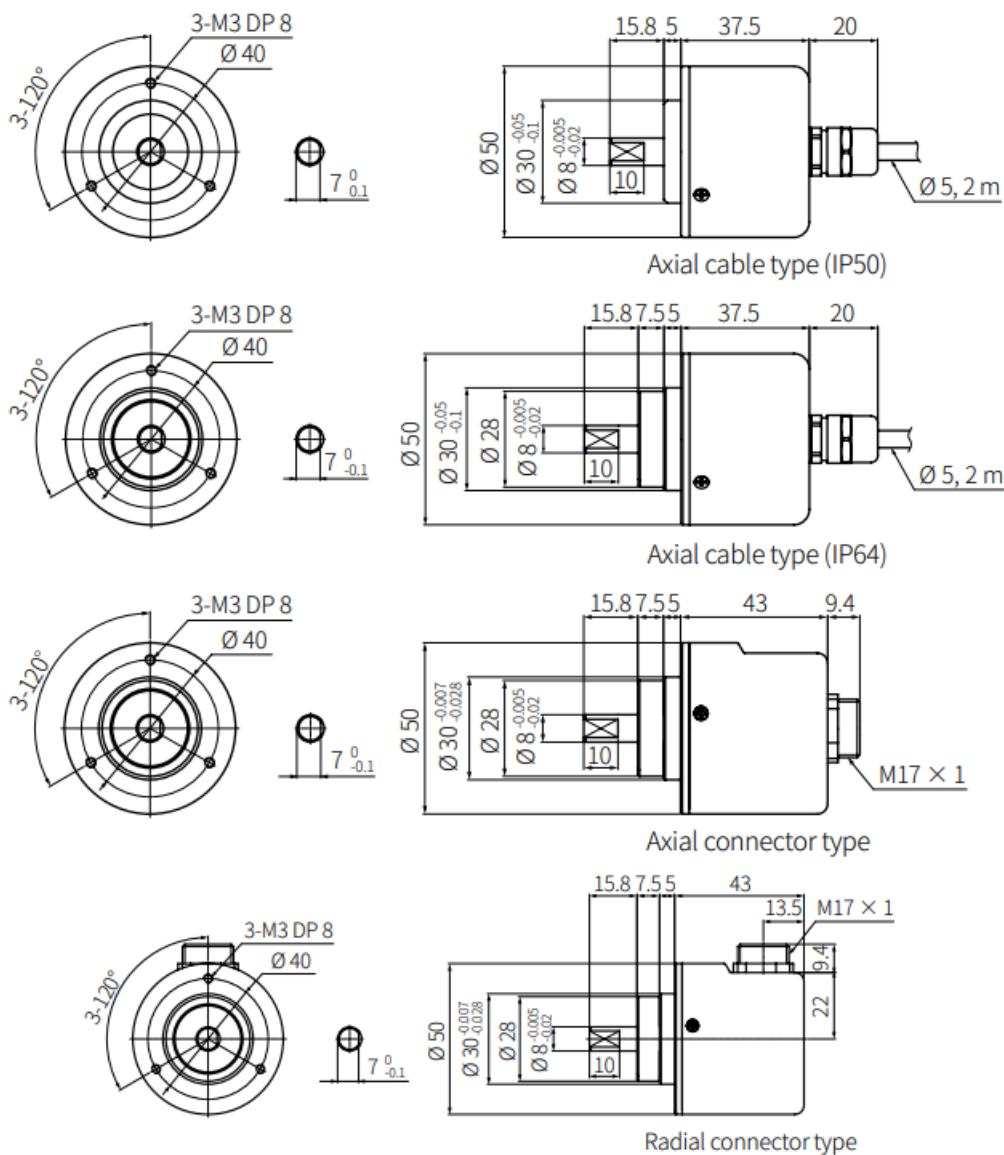
Power supply	5 VDC ± 5% (ripple P-P: ≤ 5%) / 12 – 24 VDC ± 5% (ripple P-P: ≤ 5%) model
Current consumption	Totempole, NPN open collector, Voltage output: ≤ 80 mA (no load) Line driver output: ≤ 50 mA (no load)
Insulation resistance	Between all terminals and case: ≥ 100 MΩ (500 VDC megger)
Dielectric strength	Between all terminals and case: 750 VAC 50 / 60 Hz for 1 minute
Vibration	1 mm double amplitude at frequency 10 to 55 Hz (for 1 minute) in each X, Y, Z direction for 2 hours
Shock	≤ 75 G
Ambient temp.	-10 to 70 °C, storage: -25 to 85 °C (no freezing or condensation)
Ambient humi.	35 to 85%RH, storage: 35 to 90%RH (no freezing or condensation)
Protection rating	Axial cable type / cable connector type: IP50 (IEC standard) <sup>01)</sup> Axial / Radial connector type: IP65 (IEC standard)
Cable spec.	Ø 5 mm, 5-wire (Line driver output: 8-wire), shield cable cable type: 2 m, cable connector type: 250 mm
Wire spec.	AWG24 (0.08 mm, 40-core), insulator diameter: Ø 1 mm
Connector spec.	Totempole, NPN open collector, Voltage output: M17 6-pin socket type Line driver output: M17 9-pin socket type



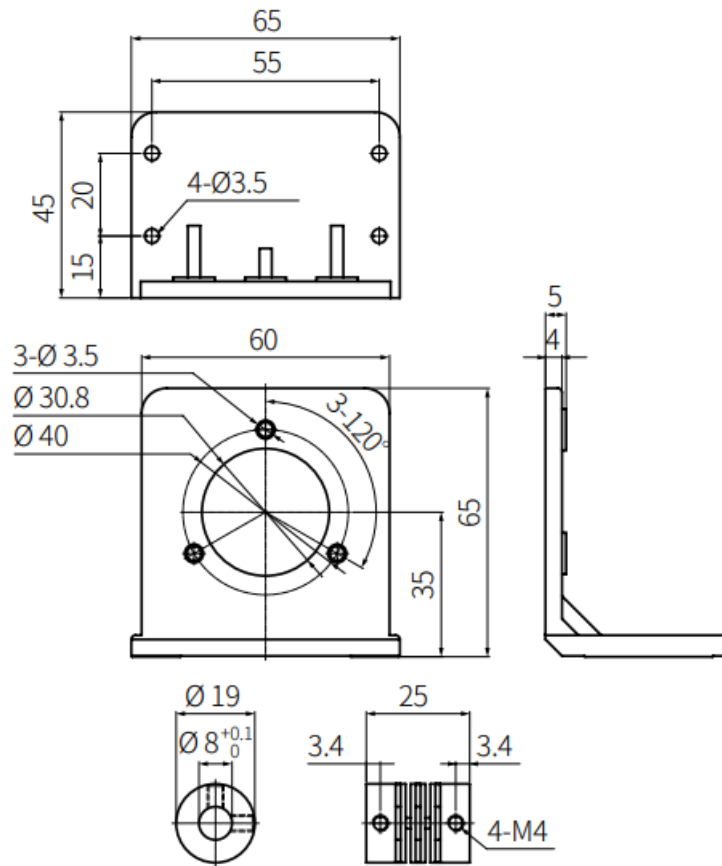
1. Protection structure IP64 option is also available to order. (starting torque: 0.078 N m, inertia moment: 400 g·cm<sup>2</sup> ( $4 \times 10^{-5}$  kg·m<sup>2</sup>))

## Dimensions

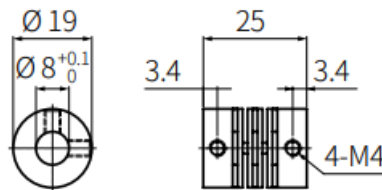
- Unit: mm, For the detailed drawings, follow the Autonics website.
- Following items are based on cable type, connector type. Refer to 'Specifications' for detailed specifications of cable, wire and connector.



## Bracket



## Coupling



- Parallel misalignment:  $\leq 0.25$  mm
- Angular misalignment:  $\leq 5^\circ$
- End-play:  $\leq 0.5$  mm

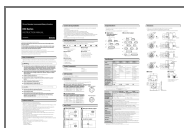
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## Documents / Resources



[AUTONICS E50 Series Incremental Rotary Encoders](#) [pdf] Instruction Manual  
E50 Series Incremental Rotary Encoders, E50 Series, Incremental Rotary Encoders, Rotary Encoders, Encoders

## References

- [www.autonics.com](http://www.autonics.com)

