



ATMEL AT90CAN32-16AU 8bit AVR Microcontroller User Guide

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ATMEL AT90CAN32-16AU 8bit AVR Microcontroller User Guide



8-bit **AVR**[®] Microcontroller with 32K/64K/128K Bytes of ISP Flash and CAN Controller

AT90CAN32
AT90CAN64
AT90CAN128

Summary

Features

- **High-performance, Low-power AVR® 8-bit Microcontroller**
- **Advanced RISC Architecture**
 - 133 Powerful Instructions – Most Single Clock Cycle Execution
 - 32 x 8 General Purpose Working Registers + Peripheral Control Registers
 - Fully Static Operation
 - Up to 16 MIPS Throughput at 16 MHz
 - On-chip 2-cycle Multiplier
- **Non volatile Program and Data Memories**
 - 32K/64K/128K Bytes of In-System Reprogrammable Flash (AT90CAN32/64/128)
 - Endurance: 10,000 Write/Erase Cycles
 - Optional Boot Code Section with Independent Lock Bits
 - Selectable Boot Size: 1K Bytes, 2K Bytes, 4K Bytes or 8K Bytes
 - In-System Programming by On-Chip Boot Program (CAN, UART, ...)
 - True Read-While-Write Operation
 - 1K/2K/4K Bytes EEPROM (Endurance: 100,000 Write/Erase Cycles) (AT90CAN32/64/128)
 - 2K/4K/4K Bytes Internal SRAM (AT90CAN32/64/128)
 - Up to 64K Bytes Optional External Memory Space
 - Programming Lock for Software Security
- **JTAG (IEEE std. 1149.1 Compliant) Interface**
 - Boundary-scan Capabilities According to the JTAG Standard
 - Programming Flash (Hardware ISP), EEPROM, Lock & Fuse Bits
 - Extensive On-chip Debug Support
- **CAN Controller 2.0A & 2.0B – ISO 16845 Certified ⁽¹⁾**
 - 15 Full Message Objects with Separate Identifier Tags and Masks
 - Transmit, Receive, Automatic Reply and Frame Buffer Receive Modes
 - 1Mbits/s Maximum Transfer Rate at 8 MHz
 - Time stamping, TTC & Listening Mode (Spying or Autobaud)
- **Peripheral Features**
 - Programmable Watchdog Timer with On-chip Oscillator
 - 8-bit Synchronous Timer/Counter-0
 - 10-bit Prescaler
 - External Event Counter
 - Output Compare or 8-bit PWM Output
 - 8-bit Asynchronous Timer/Counter-2
 - 10-bit Prescaler
 - External Event Counter
 - Output Compare or 8-Bit PWM Output
 - 32Khz Oscillator for RTC Operation
 - Dual 16-bit Synchronous Timer/Counters-1 & 3
 - 10-bit Prescaler

- Input Capture with Noise Canceler
- External Event Counter
- 3-Output Compare or 16-Bit PWM Output
- Output Compare Modulation
- 8-channel, 10-bit SAR ADC
 - 8 Single-ended Channels
 - 7 Differential Channels
 - 2 Differential Channels With Programmable Gain at 1x, 10x, or 200x
- On-chip Analog Comparator
- Byte-oriented Two-wire Serial Interface
- Dual Programmable Serial USART
- Master/Slave SPI Serial Interface
 - Programming Flash (Hardware ISP)
- Special Microcontroller Features
 - Power-on Reset and Programmable Brown-out Detection
 - Internal Calibrated RC Oscillator
 - 8 External Interrupt Sources
 - 5 Sleep Modes: Idle, ADC Noise Reduction, Power-save, Power-down & Standby
 - Software Selectable Clock Frequency
 - Global Pull-up Disable
- I/O and Packages
 - 53 Programmable I/O Lines
 - 64-lead TQFP and 64-lead QFN
- Operating Voltages: 2.7 – 5.5V
- Operating temperature: Industrial (-40°C to +85°C)
- Maximum Frequency: 8 MHz at 2.7V, 16 MHz at 4.5V

Note: 1. Details on section 19.4.3 on page 242.

Description

Comparison Between AT90CAN32, AT90CAN64 and AT90CAN128

AT90CAN32, AT90CAN64 and AT90CAN128 are hardware and software compatible. They differ only in memory sizes as shown in Table 1-1.

Table 1-1. Memory Size Summary

Device	Flash	EEPROM	RAM
AT90CAN32	32K Bytes	1K Byte	2K Bytes
AT90CAN64	64K Bytes	2K Bytes	4K Bytes
AT90CAN128	128K Bytes	4K Byte	4K Bytes

Part Description

The AT90CAN32/64/128 is a low-power CMOS 8-bit microcontroller based on the AVR enhanced RISC architecture. By executing powerful instructions in a single clock cycle, the AT90CAN32/64/128 achieves throughputs approaching 1 MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

The AVR core combines a rich instruction set with 32 general purpose working registers. All 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one single instruction executed in one clock cycle. The resulting architecture is more code efficient while achieving throughputs up to ten times faster than conventional CISC microcontrollers.

The AT90CAN32/64/128 provides the following features: 32K/64K/128K bytes of In-System Programmable Flash with Read-While-Write capabilities, 1K/2K/4K bytes EEPROM, 2K/4K/4K bytes SRAM, 53 general purpose I/O lines, 32 general purpose working registers, a CAN controller, Real Time Counter (RTC), four flexible Timer/Counters with compare modes and PWM, 2 USARTs, a byte oriented Two-wire Serial Interface, an 8-channel 10-bit ADC with optional differential input stage with programmable gain, a programmable Watchdog Timer with Internal Oscillator, an SPI serial port, IEEE std. 1149.1 compliant JTAG test interface, also used for accessing the On-chip Debug system and programming and five software selectable power saving modes.

The Idle mode stops the CPU while allowing the SRAM, Timer/Counters, SPI/CAN ports and interrupt system to continue functioning. The Power-down mode saves the register contents but freezes the Oscillator, disabling all other chip functions until the next interrupt or Hardware Reset. In Power-save mode, the asynchronous timer continues to run, allowing the user to maintain a timer base while the rest of the device is sleeping. The ADC Noise Reduction mode stops the CPU and all I/O modules except Asynchronous Timer and ADC, to minimize switching noise during ADC conversions. In Standby mode, the Crystal/Resonator Oscillator is running while the rest of the device is sleeping. This allows very fast start-up combined with low power consumption.

The device is manufactured using Atmel's high-density nonvolatile memory technology. The Onchip ISP Flash allows the program memory to be reprogrammed in-system through an SPI serial interface, by a conventional nonvolatile memory programmer, or by an On-chip Boot program running on the AVR core. The boot program can use any interface to download the application program in the application Flash memory. Software in the Boot Flash section will continue to run while the Application Flash section is updated, providing true Read-While-Write operation. By combining an 8-bit RISC CPU with In-System Self-Programmable Flash on a monolithic chip, the Atmel AT90CAN32/64/128 is a powerful microcontroller that provides a highly flexible and cost effective solution to many embedded control applications.

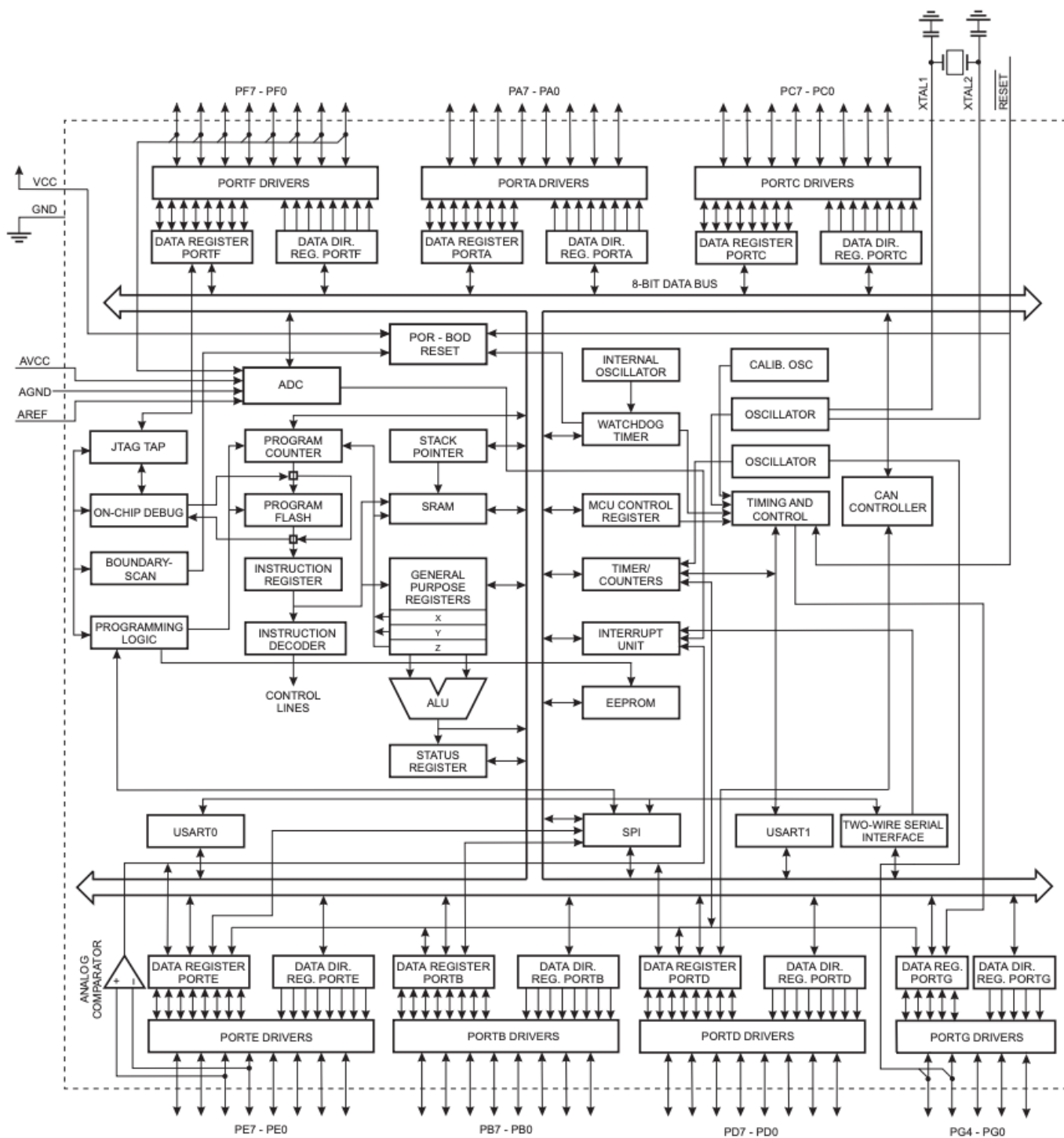
The AT90CAN32/64/128 AVR is supported with a full suite of program and system development tools including: C compilers, macro assemblers, program debugger/simulators, in-circuit emulators, and evaluation kits.

Disclaimer

Typical values contained in this datasheet are based on simulations and characterization of other AVR microcontrollers manufactured on the same process technology. Min and Max values will be available after the device is characterized.

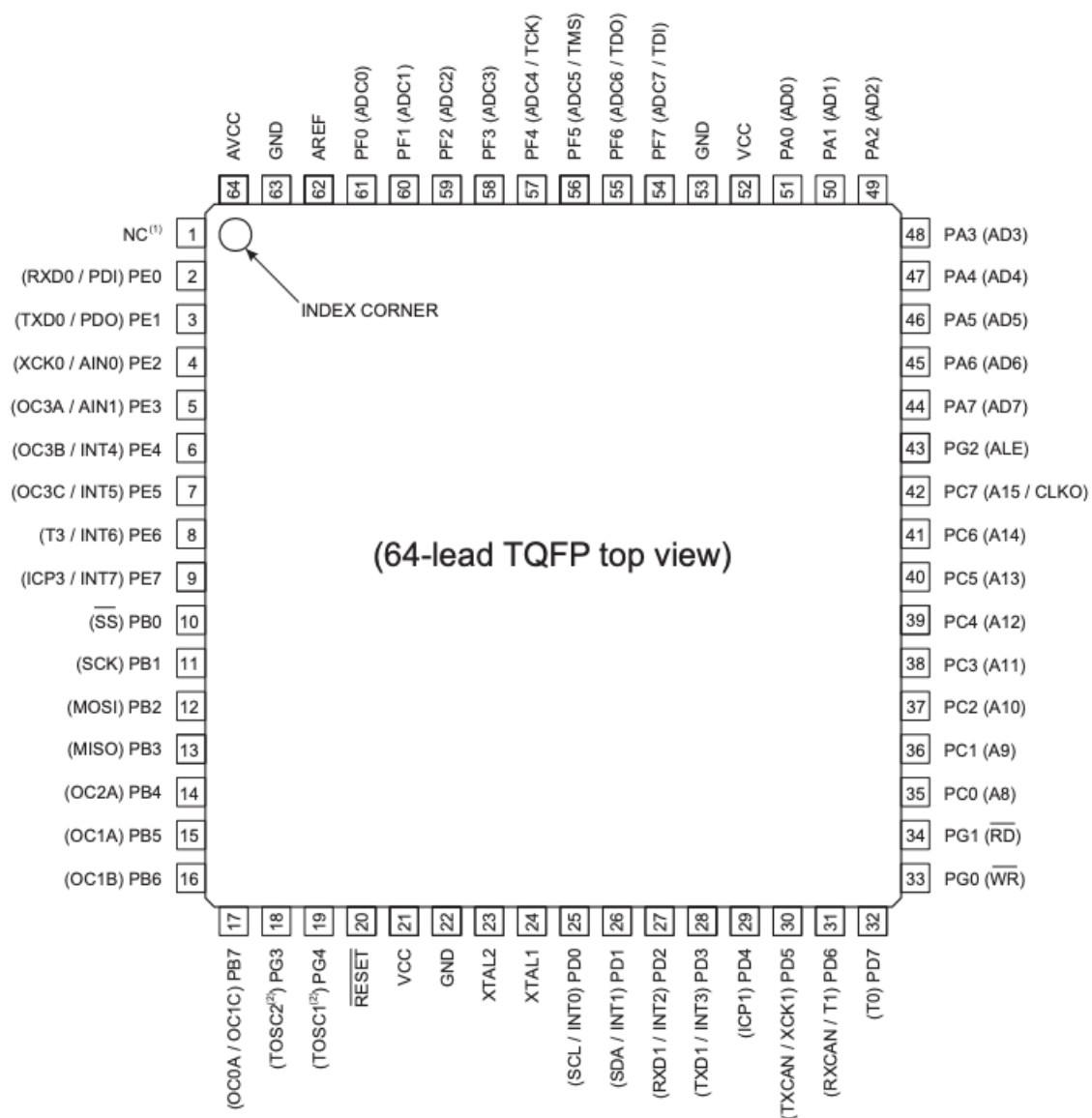
Block Diagram

Figure 1-1. Block Diagram



Pin Configurations

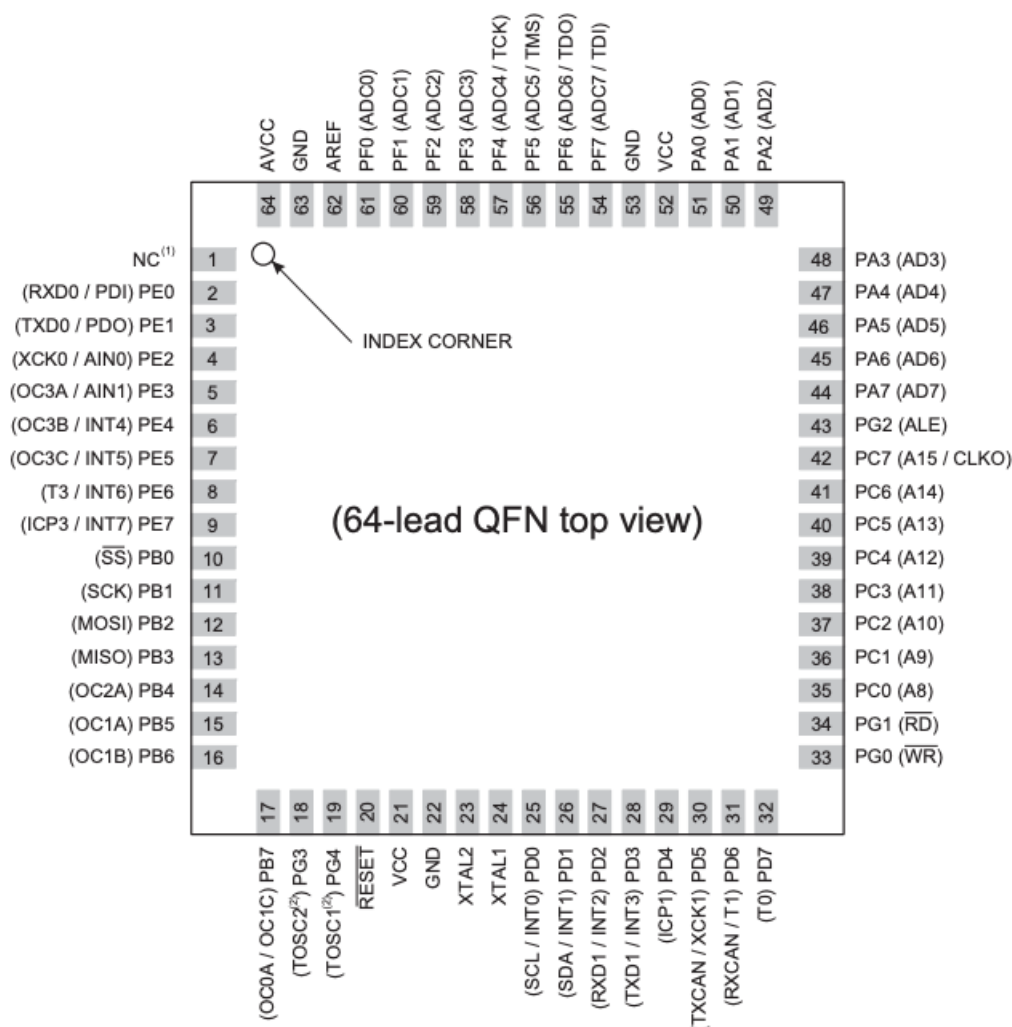
Figure 1-2. Pinout AT90CAN32/64/128 – TQFP



(1) NC = Do not connect (May be used in future devices)

(2) Timer2 Oscillator

Figure 1-3. Pinout AT90CAN32/64/128 – QFN



⁽¹⁾ NC = Do not connect (May be used in future devices)

⁽²⁾ Timer2 Oscillator

Note: The large center pad underneath the QFN package is made of metal and internally connected to GND. It should be soldered or glued to the board to ensure good mechanical stability. If the center pad is left unconnected, the package might loosen from the board.

1.6.3 Port A (PA7..PA0)

Port A is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port A pins that are externally pulled low will source current if the pull-up resistors are activated. The Port A pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port A also serves the functions of various special features of the AT90CAN32/64/128 as listed on page 74.

1.6.4 Port B (PB7..PB0)

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port B also serves the functions of various special features of the AT90CAN32/64/128 as listed on page 76.

1.6.5 Port C (PC7..PC0)

Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port C also serves the functions of special features of the AT90CAN32/64/128 as listed on page 78.

1.6.6 Port D (PD7..PD0)

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the AT90CAN32/64/128 as listed on page 80.

1.6.7 Port E (PE7..PE0)

Port E is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port E output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port E pins that are externally pulled low will source current if the pull-up resistors are activated. The Port E pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port E also serves the functions of various special features of the AT90CAN32/64/128 as listed on page 83.

1.6.8 Port F (PF7..PF0)

Port F serves as the analog inputs to the A/D Converter.

Port F also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port F output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port F pins that are externally pulled low will source current if the pull-up resistors are activated. The Port F pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port F also serves the functions of the JTAG interface. If the JTAG interface is enabled, the pullup resistors on pins PF7(TDI), PF5(TMS), and PF4(TCK) will be activated even if a reset occurs.

1.6.9 Port G (PG4..PG0)

Port G is a 5-bit I/O port with internal pull-up resistors (selected for each bit). The Port G output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port G pins that are externally pulled low will source current if the pull-up resistors are activated. The Port G pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port G also serves the functions of various special features of the AT90CAN32/64/128 as listed on page 88.

1.6.10 RESET

Reset input. A low level on this pin for longer than the minimum pulse length will generate a reset. The minimum pulse length is given in characteristics. Shorter pulses are not guaranteed to generate a reset. The I/O ports of the AVR are immediately reset to their initial state even if the clock is not running. The clock is needed to reset the rest of the AT90CAN32/64/128.

1.6.11 XTAL1

Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

1.6.12 XTAL2

Output from the inverting Oscillator amplifier.

1.6.13 AVCC

AVCC is the supply voltage pin for the A/D Converter on Port F. It should be externally connected to V_{CC} , even if the ADC is not used. If the ADC is used, it should be connected to V_{CC} through a low-pass filter.

1.6.14 AREF

This is the analog reference pin for the A/D Converter.

About Code Examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C compiler documentation for more details.

Register Summary

0x1A (0x3A)	Reserved									
0x19 (0x39)	Reserved									
0x18 (0x38)	TIFR3	–	–	ICF3	–	OCF3C	OCF3B	OCF3A	TOV3	page 143
0x17 (0x37)	TIFR2	–	–	–	–	–	–	OCF2A	TOV2	page 162
0x16 (0x36)	TIFR1	–	–	ICF1	–	OCF1C	OCF1B	OCF1A	TOV1	page 143
0x15 (0x35)	TIFR0	–	–	–	–	–	–	OCF0A	TOV0	page 112
0x14 (0x34)	PORTG	–	–	–	PORTG4	PORTG3	PORTG2	PORTG1	PORTG0	page 92
0x13 (0x33)	DDRG	–	–	–	DDG4	DDG3	DDG2	DDG1	DDG0	page 92
0x12 (0x32)	PING	–	–	–	PING4	PING3	PING2	PING1	PING0	page 92
0x11 (0x31)	PORTF	PORTF7	PORTF6	PORTF5	PORTF4	PORTF3	PORTF2	PORTF1	PORTF0	page 91
0x10 (0x30)	DDRF	DDF7	DDF6	DDF5	DDF4	DDF3	DDF2	DDF1	DDF0	page 91
0x0F (0x2F)	PINF	PINF7	PINF6	PINF5	PINF4	PINF3	PINF2	PINF1	PINF0	page 92
0x0E (0x2E)	PORTE	PORTE7	PORTE6	PORTE5	PORTE4	PORTE3	PORTE2	PORTE1	PORTE0	page 91
0x0D (0x2D)	DDRE	DDE7	DDE6	DDE5	DDE4	DDE3	DDE2	DDE1	DDE0	page 91
0x0C (0x2C)	PINE	PINE7	PINE6	PINE5	PINE4	PINE3	PINE2	PINE1	PINE0	page 91
0x0B (0x2B)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTD0	page 91
0x0A (0x2A)	DDR	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	page 91
0x09 (0x29)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	page 91
0x08 (0x28)	PORTC	PORTC7	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	page 90
0x07 (0x27)	DDRC	DDC7	DDC6	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	page 90
0x06 (0x26)	PINC	PINC7	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	page 90
0x05 (0x25)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	page 90
0x04 (0x24)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	page 90
0x03 (0x23)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	page 90
0x02 (0x22)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	page 89
0x01 (0x21)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	page 90
0x00 (0x20)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	page 90

Notes:

1. Address bits exceeding PCMSB (Table 25-11 on page 341) are don't care.
2. Address bits exceeding EEAMSB (Table 25-12 on page 341) are don't care.
3. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.
4. I/O Registers within the address range 0x00 – 0x1F are directly bit-accessible using the SBI and CBI instructions. In these registers, the value of single bits can be checked by using the SBIS and SBIC instructions.
5. Some of the status flags are cleared by writing a logical one to them. Note that, unlike most other AVR's, the CBI and SBI instructions will only operate on the specified bit, and can therefore be used on registers containing such status flags. The CBI and SBI instructions work with registers 0x00 to 0x1F only.
6. When using the I/O specific commands IN and OUT, the I/O addresses 0x00 – 0x3F must be used. When addressing I/O Registers as data space using LD and ST instructions, 0x20 must be added to these addresses. The AT90CAN32/64/128 is a complex microcontroller with more peripheral units than can be supported within the 64 location reserved in Opcode for the IN and OUT instructions. For the Extended I/O space from 0x60 – 0xFF in SRAM, only the ST/STS/STD and LD/LDS/LDD instructions can be used.

Ordering Information

Ordering Code ⁽¹⁾	Speed (MHz)	Power Supply (V)	Package	Operation Range	Product Marking
AT90CAN32-16AI	16	2.7 - 5.5	A2 64	Industrial (-40° to +85°C)	AT90CAN32-16AI
AT90CAN32-16MI	16	2.7 - 5.5	Z64-1	Industrial (-40° to +85°C)	AT90CAN32-16MI
AT90CAN32-16AU	16	2.7 - 5.5	A2 64	Industrial (-40° to +85°C) Green	AT90CAN32-16AU
AT90CAN32-16MU	16	2.7 - 5.5	Z64-1	Industrial (-40° to +85°C) Green	AT90CAN32-16MU
AT90CAN64-16AI	16	2.7 - 5.5	A2 64	Industrial (-40° to +85°C)	AT90CAN64-16AI
AT90CAN64-16MI	16	2.7 - 5.5	Z64-2	Industrial (-40° to +85°C)	AT90CAN64-16MI
AT90CAN64-16AU	16	2.7 - 5.5	A2 64	Industrial (-40° to +85°C) Green	AT90CAN64-16AU
AT90CAN64-16MU	16	2.7 - 5.5	Z64-2	Industrial (-40° to +85°C) Green	AT90CAN64-16MU
AT90CAN128-16AI	16	2.7 - 5.5	A2 64	Industrial (-40° to +85°C)	AT90CAN128-16AI
AT90CAN128-16MI	16	2.7 - 5.5	Z64-2	Industrial (-40° to +85°C)	AT90CAN128-16MI
AT90CAN128-16AU	16	2.7 - 5.5	A2 64	Industrial (-40° to +85°C) Green	AT90CAN128-16AU
AT90CAN128-16MU	16	2.7 - 5.5	Z64-2	Industrial (-40° to +85°C) Green	AT90CAN128-16MU

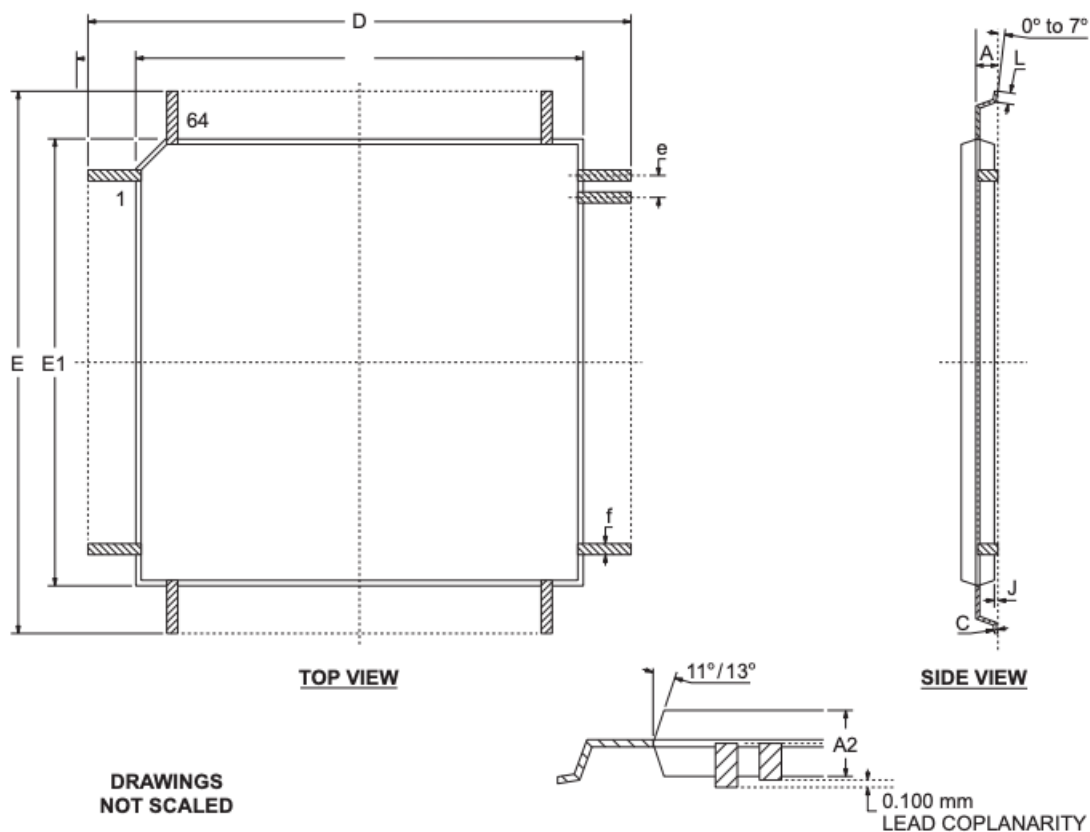
Notes: 1. These devices can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

Packaging Information

Package Type	
A2 64	64-Lead, Thin (1.0 mm / 0.03937 in) Plastic Gull Wing Quad Flat Package.
Z64-1	64-Lead, QFN, Exposed Die Attach Pad D2/E2: 5.4 ± 0.1mm / 0.212 ± 0.004 in.
Z64-2	64-Lead, QFN, Exposed Die Attach Pad D2/E2: 6.0 ± 0.1mm / 0.236 ± 0.004 in.

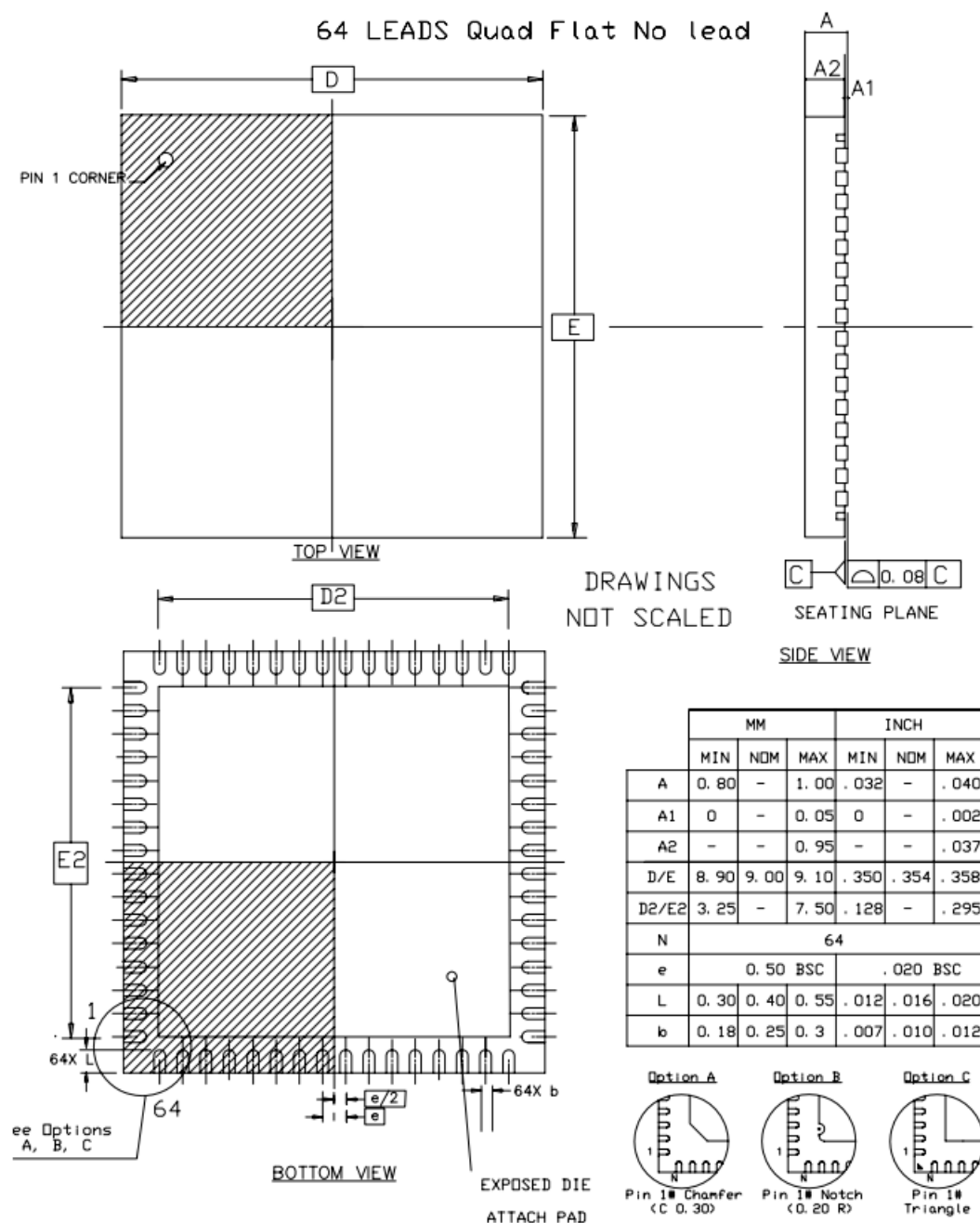
TQFP64

64 PINS THIN QUAD FLAT PACK



	MM		INCH	
	Min	Max	Min	Max
A	----	1.20	----	0.047
A2	0.95	1.05	0.037	0.041
C	0.09	0.20	0.004	0.008
D	16.00 BSC		0.630 BSC	
D1	14.00 BSC		0.551 BSC	
E	16.00 BSC		0.630 BSC	
E1	14.00 BSC		0.551 BSC	
J	0.05	0.15	0.002	0.006
L	0.45	0.75	0.018	0.030
e	0.80 BSC		0.0315 BSC	
f	0.30	0.45	0.012	0.018

QFN64



Compliant JEDEC Standard MO-220 variation VMMD-3

NOTES: QFN STANDARD NOTES

1. DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M. – 1994.
2. DIMENSION b APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.15 AND 0.30 mm FROM TERMINAL TIP. IF THE TERMINAL HAS THE OPTIONAL RADIUS ON THE OTHER END OF THE TERMINAL, THE DIMENSION b SHOULD NOT BE MEASURED IN THAT RADIUS AREA.
3. MAX. PACKAGE WARPAGE IS 0.05mm.
4. MAXIMUM ALLOWABLE BURRS IS 0.076 mm IN ALL DIRECTIONS.
5. PIN #1 ID ON TOP WILL BE LASER MARKED.
6. THIS DRAWING CONFORMES TO JEDEC REGISTERED OUTLINE MO-220.
7. A MAXIMUM 0.15mm PULL BACK (L1) MAY BE PRESENT.
L MINUS L1 TO BE EQUAL TO OR GREATER THAN 0.30 mm
8. THE TERMINAL #1 IDENTIFIER ARE OPTIONAL BUT MUST BE LOCATED WITHIN THE ZONE INDICATED
THE TERMINAL #1 IDENTIFIER BE EITHER A MOLD OR MARKED FEATURE

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7679HS-CAN-08/08

Documents / Resources

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