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FLIPSKY FSESC 110100

FLIPSKY FSESC 110100 High Voltage 110V Electronic Speed Controller User Manual

1. Introduction

This manual provides comprehensive instructions for the safe and efficient operation of your FLIPSKY FSESC 110100 High Voltage Electronic Speed Controller (ESC). Please read this manual thoroughly before use to ensure proper setup and to prevent damage to the device or connected components.

2. PRODUCT OVERVIEW

The FLIPSKY FSESC 110100 is a high-performance electronic speed controller designed for demanding applications such as fighting robots, electric surfboards, and AGV robots. It features an aluminum PCB for enhanced heat dissipation and supports high voltage inputs.



Figure 2.1: Front view of the FLIPSKY FSESC 110100 High Voltage ESC, showing the main power input and motor phase wires.

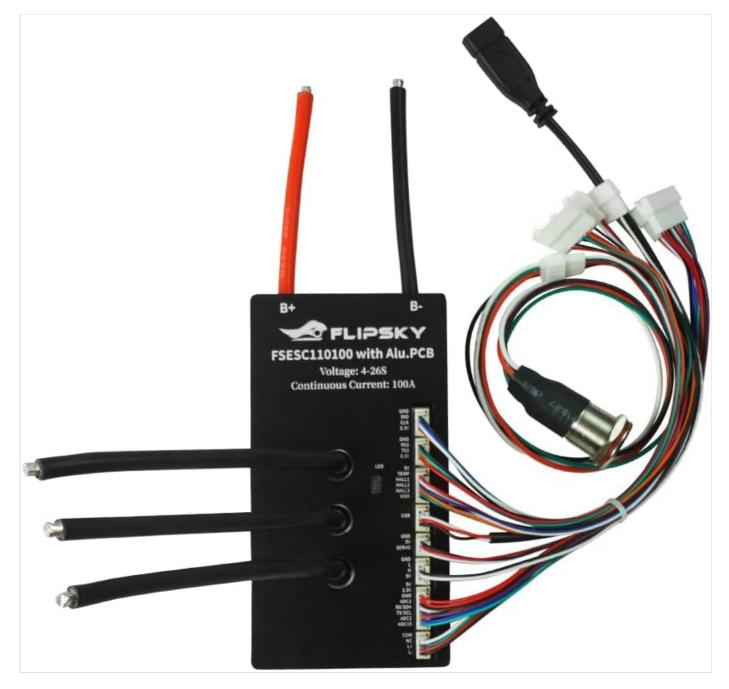


Figure 2.2: The FSESC 110100 ESC along with its various connection cables and accessories, including a USB cable and sensor wires.

3. SPECIFICATIONS

FSESC110100 with Alu. PCB Manual Specs: · Firmware: 6.05 (or above in the future) Voltage: 14-110V (safe for 4-26S) . Continuous current: 50V/120A; 110V/100A (Values depend on the mounting, ambient temperature and air/water circulation around the device!); Burst: 250A BEC: 5V@3A . Support Modes: BLDC, FOC (sinusoidal) ERPM: 150000 . Communication Ports: USB, CAN, UART, SPI, IIC Supported Sensors: ABI, HALL, AS5047, AS5048A · Input Source Support: PPM, ADC, NRF, UART · Supported Sensorless: Yes · Regenerative capacity: Yes · Programmable via VESC_TOOL: Yes Size: 117.70x62.40x21.70mm Motor/power wire size: 10AWG · Phase Filter: Yes · Power Switch Button: Red Feature: Adjustable protection against; low voltage protection, high voltage protection, over current protection. temperature abnormal protection, mosfets / motor over temperature protection. · Support various control modes: Current / Duty cycle / Speed / PID control modes. · CPU: SMT32F405 with frequency 168MHz . Design with Aluminum PCB with good heat dissipation to expand life span. · FSESC110100 with aluminum pcb: supports single serial port function, and built with power on/off switch. Wiring diagram: 100 130 MOTOR

Figure 3.1: Manufacturer's detailed specifications for the FSESC 110100.

• Firmware: 6.05 (or above)

• Voltage: 14-110V (safe for 4-26S battery configurations)

• Continuous Current: 50V/120A; 110V/100A (Note: Values depend on mounting, ambient temperature, and air/water circulation)

• Burst Current: 250A

• BEC: 5V@3A

• Supported Modes: BLDC, FOC (sinusoidal)

• ERPM: 150000

Communication Ports: USB, CAN, UART, SPI, IIC
 Supported Sensors: ABI, HALL, AS5047, AS5048A

• Input Source Support: PPM, ADC, NRF, UART

Sensorless Operation: YesRegenerative Capacity: Yes

• Programmable: Via VESC_TOOL

• **Dimensions:** 117.70 x 62.40 x 21.70 mm

• Motor/Power Wire Size: 10AWG

• Phase Filter: Yes

• Power Switch Button: Red

• CPU: SMT32F405 with 168MHz frequency

• Material: Aluminum Alloy (for PCB)

• Weight: 0.3 Kilograms

Key Features:

- Adjustable protection against: low voltage, high voltage, over current, temperature abnormalities, MOSFETs/motor over-temperature.
- Supports various control modes: Current, Duty cycle, Speed, PID control.
- Designed with Aluminum PCB for good heat dissipation and extended lifespan.
- Integrates single serial port function and Bluetooth module for convenient parameter connection and real-time data reading.
- Built-in power on/off switch.

4. COMPONENT IDENTIFICATION AND WIRING

Understanding the various ports and connections is crucial for correct setup. Refer to the diagrams below for detailed identification.



Figure 4.1: Comprehensive wiring diagram illustrating connections for battery, motor, and various communication/sensor ports.



Figure 4.2: Close-up view of the various communication and sensor ports on the FSESC 110100, with labels for each connection.

Port Descriptions:

- B+ / B-: Main battery positive and negative connections.
- Motor Phase Wires (A, B, C): Connect to the motor's three phase wires.
- LED: Status indicator light.
- **USB:** For connecting to a computer for configuration via VESC_TOOL.
- **UART:** Universal Asynchronous Receiver/Transmitter port for communication with external devices (e.g., Bluetooth module, display).
- CAN: Controller Area Network bus for multi-ESC setups.
- SPI: Serial Peripheral Interface.
- IIC: Inter-Integrated Circuit (I2C) bus.
- HALL: Hall sensor input for sensored motor operation.
- PPM: Pulse Position Modulation input for remote control.
- ADC: Analog-to-Digital Converter input for analog controls.
- NRF: Nordic Radio Frequency module support.
- Power Switch: Red button for power control.

5. SETUP INSTRUCTIONS

- 1. **Safety First:** Ensure all power sources are disconnected before making any connections. Wear appropriate safety gear.
- 2. **Mounting:** Securely mount the FSESC 110100 in a location with adequate airflow for heat dissipation. The aluminum PCB is designed for good heat transfer, but proper mounting is still essential.
- 3. **Battery Connection:** Connect your battery pack (4-26S, 14-110V) to the B+ (positive) and B- (negative) terminals. Ensure correct polarity.
- 4. **Motor Connection:** Connect the three phase wires from your motor to the A, B, and C terminals on the ESC. If using a sensored motor, connect the Hall sensor cable to the HALL port.
- 5. Control Input: Connect your chosen control input (e.g., PPM receiver, UART device) to the corresponding port.
- 6. Initial Configuration (VESC TOOL):

Download and install the latest VESC_TOOL software from the official VESC project website or FLIPSKY support page.

Connect the FSESC 110100 to your computer via the USB port.

Launch VESC_TOOL and follow the motor setup wizard to configure your motor and ESC parameters. This includes motor detection, battery voltage limits, current limits, and control mode settings.

Save your configuration to the ESC.

7. **Bluetooth Module (Optional):** If using the integrated Bluetooth module, you can connect to the ESC via a mobile app (e.g., VESC Tool app) for real-time data monitoring and parameter adjustment.

6. OPERATING INSTRUCTIONS

- 1. **Power On:** After completing all connections and configuration, press the red power switch button to power on the ESC. The LED indicator will illuminate.
- 2. **Control:** Operate your device using the configured input source (e.g., remote control, joystick). The ESC will translate your commands into motor control.
- 3. **Monitoring:** Use VESC_TOOL or a connected Bluetooth app to monitor real-time data such as motor RPM, current, voltage, and temperature during operation.
- 4. **Protection Features:** The ESC is equipped with various protection features (low/high voltage, over current, over temperature). If a protection limit is reached, the ESC may reduce power or shut down to prevent damage. Identify and resolve the cause of the protection activation.
- 5. **Power Off:** When finished, press the red power switch button to power off the ESC.

7. MAINTENANCE

- Regular Inspection: Periodically inspect all wiring and connections for signs of wear, damage, or loose contacts.
- Cleaning: Keep the ESC clean and free from dust, dirt, and moisture. Use a soft, dry cloth for cleaning. Avoid using solvents or harsh chemicals.
- Heat Management: Ensure the ESC has adequate ventilation during operation. Avoid operating in excessively hot
 environments.
- **Firmware Updates:** Check the FLIPSKY website or VESC project for firmware updates. Updating firmware can improve performance and add new features. Follow update instructions carefully.

8. TROUBLESHOOTING

Problem	Possible Cause	Solution

Problem	Possible Cause	Solution
ESC does not power on.	No battery connection, incorrect polarity, faulty power switch, discharged battery.	Check battery connections and polarity. Ensure battery is charged. Test power switch.
Motor not spinning or erratic behavior.	Incorrect motor wiring, Hall sensor issue, incorrect VESC_TOOL configuration, motor fault.	Verify motor phase and Hall sensor connections. Re-run motor detection in VESC_TOOL. Check motor for damage.
ESC overheating.	Insufficient cooling, excessive load, incorrect current limits.	Improve ventilation. Reduce load. Adjust current limits in VESC_TOOL.
Communication issues with VESC_TOOL.	Incorrect USB driver, faulty USB cable, incorrect port selection in VESC_TOOL.	Install correct USB drivers. Try a different USB cable. Select the correct COM port in VESC_TOOL.
Unexpected shutdowns.	Protection limits triggered (voltage, current, temperature).	Check VESC_TOOL logs for fault codes. Address the underlying cause (e.g., low battery, overcurrent, overheating).

9. WARRANTY AND SUPPORT

The FLIPSKY FSESC 110100 comes with a **2-month warranty** from the date of purchase. This warranty covers manufacturing defects under normal use conditions.

For technical support, troubleshooting assistance, or warranty claims, please contact FLIPSKY customer service through their official website or the retailer from whom you purchased the product. Please have your purchase receipt and product serial number available.

For the latest VESC_TOOL software and documentation, please visit the official VESC project website:www.vesc-project.com



Related Documents - FSESC 110100

The state of the s	Flipsky 75100 Pro V2.0 ESC with Aluminum PCB - Technical Datasheet Detailed specifications and wiring diagram for the Flipsky 75100 Pro V2.0 Electronic Speed Controller (ESC) with an aluminum PCB, featuring VESC 75 series compatibility, high voltage support, and multiple control interfaces.
	Flipsky VX5 Waterproof Remote Controller User Manual User manual for the Flipsky VX5 waterproof remote controller, detailing its features, wiring diagrams for PPM and UART control modes, and screen display icon explanations.
	FLIPSKY VX5 Waterproof Remote Controller User Manual - Features, Wiring, and Operation Comprehensive user manual for the FLIPSKY VX5 waterproof remote controller. Details features, button layouts, display screen information, wiring diagrams for PPM and UART modes, and operational guidance.

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Flipsky FT85BS ESC Manual V1.4

Detailed specifications, features, and wiring diagram for the Flipsky FT85BS ESC (Electronic Speed Controller) V1.4, designed for electric vehicles and robotics.

Flipsky FT85BS V2.0 ESC: Technical Specifications and Features

Detailed technical specifications, features, and application fields for the Flipsky FT85BS V2.0 ESC, an electronic speed controller for electric vehicles and robotics.



Flipsky VX4 Pro Remote Controller User Manual

Comprehensive user manual for the Flipsky VX4 Pro remote controller, detailing its features, wiring diagrams for PPM and UART control modes, and operation instructions for electric skateboards.