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› [MP3 Player, Music Player with 32GB Micro SD Card, Earphone, Build-in Speaker/Photo/Video Play/FM Radio/Voice Recorder/E-Book Reader, Supports up to 128GB for Kids, Running, Walking Black](#)

VR-robot build-in

VR-robot MP3 Player User Manual

Model: build-in

INTRODUCTION

Thank you for purchasing the VR-robot MP3 Player. This device is designed to provide a versatile and portable entertainment experience, featuring music playback, video viewing, FM radio, voice recording, and e-book reading capabilities. With its compact design and expandable storage, it is ideal for various activities such as running, walking, or simply enjoying your favorite media on the go. This manual will guide you through the setup, operation, maintenance, and troubleshooting of your new MP3 player.



Image: The VR-robot MP3 Player, showcasing its compact design, screen, control buttons, and the included 32GB Micro SD card and wired earphones.

SETUP

1. Charging the Device

Before first use, fully charge the MP3 player. Connect the device to a USB power adapter (not included) or a computer's USB port using the provided USB cable. The battery indicator on the screen will show charging progress. A full charge typically takes 2-3 hours and provides up to 10 hours of music playback.

2. Inserting the Micro SD Card

Your MP3 player comes with a 32GB Micro SD card. Locate the Micro SD card slot on the side of the device. Gently insert the Micro SD card into the slot until it clicks into place. The device supports Micro SD cards up to 128GB for expanded storage.

Expandable Storage Up to 128G

Built-in micro SD / TF slot allows you to expand device storage



Image: A hand inserting a blue Micro SD card into the dedicated slot on the side of the VR-robot MP3 Player, illustrating the expandable storage feature.

3. Connecting to a Computer for File Transfer

To transfer music, videos, photos, or e-books to your MP3 player, connect it to your computer using the USB cable. The device will appear as a removable disk drive. You can then drag and drop files into the appropriate folders on the device or the inserted Micro SD card.

OPERATING INSTRUCTIONS

Basic Navigation

The MP3 player features a central control pad with directional buttons and a central play/pause button. The 'M' button typically serves as a menu or back button, while 'VOL' controls volume. Navigate through menus and select options using these buttons.

Music Playback

The player supports multiple audio formats including MP3, WMA, APE, WAV, and FLAC. For optimal sound quality, the device incorporates a professional intelligent digital noise reduction chip. Connect the included earphones or use the built-in speaker for audio output.



Image: A person wearing headphones, illustrating the high-fidelity sound experience provided by the MP3 player, with text indicating support for various audio formats.

- **Playing Music:** Select "Music" from the main menu, then browse by artist, album, song, or folder.
- **Volume Control:** Use the 'VOL' button to adjust the playback volume.
- **A-B Repeat:** This function allows you to loop a specific segment of an audio track. Select the start point (A) and end point (B) during playback.

Video Playback

The MP3 player supports video playback. Ensure your video files are in a compatible format for smooth playback. Refer to the device specifications for supported video formats.

FM Radio

To use the FM radio function, connect wired headphones to the device, as they serve as the antenna. Navigate to the "FM Radio" option in the main menu. You can then auto-scan for stations or manually tune to a specific frequency (87.5 MHz - 108 MHz).



Image: A person with an earphone in, surrounded by circular graphics indicating various FM radio frequencies, demonstrating the FM radio capability of the MP3 player.

Voice Recorder

The built-in voice recorder allows you to capture audio notes or lectures. Select "Record" from the main menu to start a new recording. Recordings are typically saved in WAV format.

Support for recording functions



Image: The VR-robot MP3 Player displaying a recording interface, with a child studying in the background, highlighting its use as a voice recorder.

E-Book Reader

Load compatible e-book files onto your device to read on the go. Navigate to the "E-Book" section to access your digital library.

Alarm Function

The device includes an alarm function. Set alarms through the settings menu for reminders or as a wake-up call.

Folder Browsing

Access files directly by browsing folders. This is useful for organizing different types of media or for audiobooks where tracks are separated into specific folders.

Multifunctional MP3 Player



Image: The VR-robot MP3 Player screen displaying icons for E-Book, Alarm, Record, Music, Folder, FM Radio, A-B Repeat, and Video, illustrating its diverse functionalities.

MAINTENANCE

- Cleaning:** Use a soft, dry cloth to clean the device. Avoid using liquid cleaners or abrasive materials.
- Storage:** Store the MP3 player in a cool, dry place away from direct sunlight and extreme temperatures.
- Battery Care:** To prolong battery life, avoid fully discharging the battery frequently. Charge the device regularly, even if not in use for extended periods.
- Software Updates:** Check the manufacturer's website periodically for any available firmware updates to ensure optimal performance.

TROUBLESHOOTING

Problem	Possible Cause / Solution
Device does not turn on.	Battery is depleted. Charge the device for at least 30 minutes. If still unresponsive, try a different USB cable or charging port.
Cannot transfer files to the device.	Ensure the USB cable is securely connected. Try a different USB port on your computer. The device might be in charging mode; check if it needs to be set to "Media Device (MTP)" or "USB Storage" mode.
Music files are not playing or are corrupted.	Verify that the music files are in a supported format (MP3, WMA, APE, WAV, FLAC). Ensure files are not corrupted. Re-transfer the files if necessary.
FM Radio signal is weak or non-existent.	Ensure wired headphones are properly plugged in, as they act as the antenna. Try moving to an area with better signal reception.
Albums/folders are not separated correctly.	Ensure your music files have correct ID3 tags and are organized into distinct folders on the device's storage. Some players may combine tracks if metadata is inconsistent.
Voice recording not working.	Check if there is sufficient storage space. Ensure the microphone is not obstructed.

SPECIFICATIONS

Brand: VR-robot

Model Name: build-in

Memory Storage Capacity: 32 GB (Micro SD card included), supports up to 128 GB

Connectivity Technology: Bluetooth, USB

Special Features: Video Playback, Voice Recorder, FM Radio, E-Book Reader, Built-in Speaker

Screen Size: 3.5 inches

Color: Black

Item Weight: 2.89 ounces

Batteries: 1 Lithium Ion battery required (included)

Package Dimensions: 4.84 x 2.87 x 1.42 inches

Included Components: MP3 Player, 32GB Micro SD Card, Earphone, USB Cable

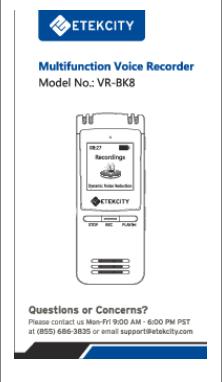
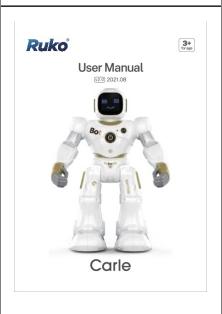
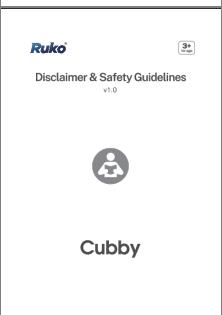
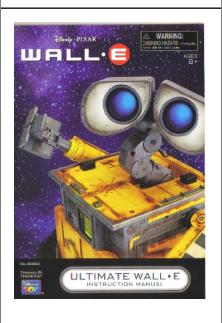
WARRANTY AND SUPPORT

Your VR-robot MP3 Player comes with a **12-month warranty** from the date of purchase. This warranty covers manufacturing defects and ensures the quality of your product.

If you encounter any problems or have questions regarding your device, please do not hesitate to contact our professional after-sales service team. You can typically find contact information on the seller's page or through your purchase platform. We are committed to providing a quick and satisfactory response to ensure your satisfaction.

For further assistance, please refer to the VR-robot store on Amazon: [VR-robot Store](#)

Related Documents - build-in

	<p>BOOCOSA VR-001 Multifunction Voice Recorder User Manual Comprehensive user manual for the BOOCOSA VR-001 Multifunction Voice Recorder. Learn about its features, specifications, operation instructions, and maintenance.</p>
	<p>ETEKCITY VR-BK8 Multifunction Voice Recorder User Manual Comprehensive user manual for the ETEKCITY VR-BK8 Multifunction Voice Recorder, detailing features, operation, settings, and specifications for recording audio and playing music.</p>
	<p>Ruko Carle Robot User Manual: Setup, Features, and Troubleshooting Comprehensive user manual for the Ruko Carle robot (Model 1088), covering package contents, safety precautions, charging, remote and app control, smart dialogue, troubleshooting, and more. Learn how to operate your interactive robot toy.</p>
	<p>Ruko Cubby Robot: Disclaimer & Safety Guidelines Comprehensive disclaimer and safety guidelines for the Ruko Cubby Robot, covering usage, charging, maintenance, and troubleshooting.</p>
	<p>Ultimate WALL-E Instruction Manual - Thinkway Toys Comprehensive instruction manual for the Ultimate WALL-E toy by Thinkway Toys. Learn how to set up, operate, and program your WALL-E robot, including battery instructions, play modes, and remote control functions.</p>



Ruko Cubby Robot NX01 User Manual - Features, Operation, and Troubleshooting

Comprehensive user manual for the Ruko Cubby robot (Model NX01). Learn about package contents, safety guidelines, charging instructions, robot diagram and functions, app control, voice commands, coding mode, Bluetooth player, specifications, and common problems and solutions.

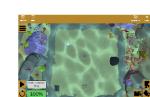
Documents - VR-robot – build-in

Coral Reef Cleanup Coding Activity

This Teacher Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the Coral Reef Cleanup Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implementation to best suit your students. The activity is designed to be flexible so that you can meet students where they are, giving them the time, space, and instruction necessary to make the most of their learning.

Overview of the Coral Reef Cleanup Activity

In the Coral Reef Cleanup activity, students will code the VR Ocean Cleaning Robot in an immersive underwater playground to collect and remove as much trash as possible from the floor of the Margrove Reef. The VR Ocean Cleaning Robot's battery will only last for a few minutes, so students will have to plan their strategy to collect as much trash as possible before the VR Robot's battery is empty. During the robot's operation, it will keep track of the weight of the trash it collects and display the total on the screen so students can see how much trash they have collected. After the VR Robot's battery is empty or the robot is manually stopped, whichever comes first, After the VR Robot's battery is empty or the robot is stopped, the total weight collected will be displayed. Encourage students to try again to improve their project and collect more trash!



CS3 Standard
• 1B.AP.12: Modify, remix, or incorporate portions of an existing program into one's own program, to develop something new or add more advanced features

Prepare for the Activity

- Prior to beginning the activity, have your materials and resources organized ready.
- **Materials Needed**
 - A VR headset or computer that supports VR (such as VR ready VR or VR ready VR頭戴式顯示器)
 - [Teacher page](#) for information about accessing VEXcode VR
 - [Coral Reef Cleanup Activity](#)
 - [Teacher page](#) for certificates at the end of the activity
- **Determine student groups.** You may want to use a Pair Programming train-the-train to help students organize turn-taking while they code. [To learn more about pair programming, see this article.](#)

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Coral Reef Cleanup Coding Activity: Teacher Facilitation Guide for VEXcode VR

A comprehensive guide for educators on facilitating the Coral Reef Cleanup Coding Activity using VEXcode VR, designed to teach students programming concepts through an engaging virtual reality experience.

lang:en score:26 filesize: 452.14 K page_count: 4 document date: 0000-00-00

Teacher Facilitation Guide

This Teacher Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the Coral Reef Cleanup Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implementation to best suit your students. The activity is designed to be flexible so that you can meet students where they are, giving them the time, space, and instruction necessary to make the most of their learning.

Overview of Universal Design for Learning (UDL)

The [UDL Guidelines](#), created by CAST, provide a comprehensive framework for Universal Design for Learning (UDL) that can be applied to all areas of education, incorporating UDL into all lesson plans and learning experiences is a powerful way to support learning for all.

Throughout this document, you'll find **UDL Never** callouts that highlight specific areas where UDL principles can't be applied to increase student agency and help provide an equitable learning experience. While many UDL Never callouts are placed in the Teacher Facilitation Guide, there are other specific actions you can take as a teacher to improve all students' learning as you implement this activity.

For deeper exploration of specific UDL principles, you can access detailed resources through embedded links (such as [Engagement, Optimize choice and autonomy \(7.1T\)](#)).

Overview of the Coral Reef Cleanup Activity

In the Coral Reef Cleanup activity, students will code the VR Ocean Cleaning Robot in an immersive underwater playground to collect and remove as much trash as possible from the floor of the Margrove Reef. The VR Ocean Cleaning Robot's battery will only last for a few minutes, so students will have to plan their strategy to collect as much trash as possible before the VR Robot's battery is empty. During the robot's operation, it will keep track of the weight of the trash it collects and display the total on the screen so students can see how much trash they have collected. After the VR Robot's battery is empty or the robot is manually stopped, whichever comes first, After the VR Robot's battery is empty or the robot is stopped, the total weight collected will be displayed. Encourage students to try again to improve their project and collect more trash!



CS3 Standard
• 1B.AP.12: Modify, remix, or incorporate portions of an existing program into one's own program, to develop something new or add more advanced features

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[pdf] Guide

VEXcode VR Coral Reef Cleanup Coding Activity Teacher Facilitation Guide Hour of Code

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Teacher Facilitation Guide Coral Reef Cleanup Coding Activity This Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the Coral Reef Cleanup Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implementation to best su...

lang:en score:25 filesize: 597.12 K page_count: 5 document date: 2024-12-09

Teacher Portal VEX EducationVR Computer Science Level 1 Pacing Guide

This Pacing Guide is designed to help you plan for VEX EducationVR Computer Science Level 1. The Pacing Guide is organized by course and includes a summary of the course, a list of concepts, and a summary of the concepts covered.

Summary	Computer Science Level 1 - Blocks Course	Computer Science Level 1 - Scratch Course	Computer Science Level 1 - Python Course
Block 1: Introduction to Computer Science	1 hour	Introduction to Computer Science	Introduction to Computer Science
Block 2: Variables and Data Types	1 hour	Variables and Data Types	Variables and Data Types
Block 3: Loops	1 hour	Loops	Loops
Block 4: Functions	1 hour	Functions	Functions
Block 5: Conditionals	1.5 hours	Conditionals	Conditionals
Block 6: Lists	1.5 hours	Lists	Lists
Block 7: Dictionaries	2.5 hours	Dictionaries	Dictionaries
Block 8: Functions with Parameters	2.5 hours	Functions with Parameters	Functions with Parameters
Block 9: Conditionals with Lists	2.5 hours	Conditionals with Lists	Conditionals with Lists
Block 10: Conditionals with Dictionaries	2.5 hours	Conditionals with Dictionaries	Conditionals with Dictionaries
Block 11: Advanced Variables	1 hour	Advanced Variables	Advanced Variables
Block 12: Advanced Functions	1 hour	Advanced Functions	Advanced Functions
Block 13: Advanced Conditionals	1 hour	Advanced Conditionals	Advanced Conditionals
Block 14: Advanced Lists	1 hour	Advanced Lists	Advanced Lists
Block 15: Advanced Dictionaries	1 hour	Advanced Dictionaries	Advanced Dictionaries
Total Time: 18 hours			

[pdf] Guide

Teacher Portal VEX EducationVR Computer Science Level 1 Pacing Guidecontent vexrobotics assets
education stem labs docs cs Courses VR Guide |||

Intermediate/Advanced ----- Beginner Summary: This Pacing Guide is intended to offer a possible organization for a hybrid or remote learning robotics class, using the Computer Science Level 1 - Blocks course. This list is organized in a trajectory from beginner to advanced, in t...

lang:en score:23 filesize: 88.65 K page_count: 3 document date: 2023-11-21

Teacher Facilitation Guide
VIQC Pitching In Coding Activity

This facilitation guide offers a step-by-step guide for how to facilitate as your students complete the VEX IQ Competition (VIQC) Pitching In Coding Activity. This facilitation guide is a powerful tool to support your teaching and implementation to best suit your students. The activity is designed to be flexible so that you can meet students where they are, giving them the time, space, and instruction necessary to make the most of their learning.

Overview of Universal Design for Learning (UDL)
The UDL Guidelines, created by CAST, provide a comprehensive framework for Universal Design for Learning—an approach that enhances teaching and learning for everyone. Incorporating UDL into all lesson plans and teaching experiences is a powerful tool to support learning for all.

Throughout this document, you'll find UDL Move™ calculate and right-click specific areas where UDL principles can be applied to increase student agency and help provide an equitable learning experience. While many UDL Moves are integrated into the Activity itself, these UDL Move calculate offer specific actions you can take as a teacher to improve all students' learning as you implement this activity.

For deeper exploration of specific UDL principles, you can access detailed resources through embedded links (such as "Engagement," "Learning choice and outcomes (7.1)"

Code Fling, the robot, to score balls in the Low and High Goals! Earn as many points as possible within 1 minute! To learn more about the challenges for the VIQC Pitching In activity, [see this reference sheet.](#)

CSSTA Standard



• 1B-AP-12 Identify, remix, or incorporate portions of an existing code into one's own program, and/or design a new program using more advanced features

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VEXcode VR VIQC Pitching In Coding Activity Teacher Facilitation Guide Hour of Code Activitiesviqc pitching in teacher facilitation guidecontent vexrobotics assets hoc s vr viqc guide v 2 |||

Teacher Facilitation Guide VIQC Pitching In Coding Activity This Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the VEX IQ Competition VIQC Pitching In Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implement...

lang:en score:22 filesize: 1.71 M page_count: 6 document date: 2024-12-09

VR Activities

Teacher Facilitation Guide
VIQC Pitching In Coding Activity

This facilitation guide offers a step-by-step guide for how to facilitate as your students complete the VIQC Pitching In Coding Activity. This facilitation guide is a powerful tool to support your teaching and implementation to best suit your students. The activity is designed to be flexible so that you can meet students where they are, giving them the time, space, and instruction necessary to make the most of their learning.

Overview of VIQC Pitching In

Code Fling, the robot, to score balls in the Low and High Goals! Earn as many points as possible within 1 minute! To learn more about the challenges for the VIQC Pitching In activity, [see this reference sheet.](#)

CSSTA Standard



• 1B-AP-12 Identify, remix, or incorporate portions of an existing code into one's own program, and/or design a new program using more advanced features

[pdf] Guide

VR Cumulative Pacing Guide United States Teacher Portal VEX Educationcontent vexrobotics assets education stem labs docs cs Courses |||

VR Activities Summary: VEXcode VR activities can be implemented to supplement student learning on the concepts Computer Science CS . These activities are geared toward new users as well as experienced programmers. VEXcode VR activities can be adapted in various ways to fit into any learning enviro...

lang:en score:22 filesize: 89.17 K page_count: 4 document date: 2023-11-21

Teacher Facilitation Guide
Rover Rescue Coding Activity

This facilitation guide offers a step-by-step guide for how to facilitate as your students complete the Rover Rescue Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implementation to best suit your students. The activity is designed to be flexible so that you can meet students where they are, giving them the time, space, and instruction necessary to make the most of their learning.

Overview of Rover Rescue

Code the VR Rover to complete the longest mission by collecting minerals and neutralizing infrared alien mines! To learn more about the challenge for the Rover Rescue activity, [see this reference sheet.](#)

CSSTA Standard



• 2-AP-17 Design and iteratively develop programs to control hardware, including nested loops and compound conditionals

Overview of Universal Design for Learning (UDL)

The UDL Guidelines, created by CAST, provide a comprehensive framework for Universal Design for Learning—an approach that enhances teaching and learning for everyone. Incorporating UDL into all lesson plans and teaching experiences is a powerful tool to support learning for all.

Throughout this document, you'll find UDL Move™ calculate and right-click specific areas where UDL principles can be applied to increase student agency and help provide an equitable learning experience. While many UDL Moves are integrated into the Activity itself, these UDL Move calculate offer specific actions you can take as a teacher to improve all students' learning as you implement this activity.

For deeper exploration of specific UDL principles, you can access detailed resources through embedded links (such as "Engagement," "Learning choice and outcomes (7.1)"

Prepare for the Activity

- Be sure you have access to a printer so that students can print their certificates at the completion of the activity.
- Try the activity yourself: A brief experience with the activity will allow you to field questions and answer students' questions.

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VEXcode VR Rover Rescue Coding Activity Teacher Facilitation Guide Hour of Code Activitiesvexcode vr rover rescue coding activity teacher facilitation guidecontent vexrobotics assets hoc s vexcode guide v 2 |||

Teacher Facilitation Guide Rover Rescue Coding Activity This Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the Rover Rescue Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implementation to best suit your stud...

lang:en score:22 filesize: 1.51 M page_count: 7 document date: 2024-12-09

The potential of emerging technology in the Netherlands: Winning Strategies for Dutch Deep Tech

The potential of emerging technology in the Netherlands

Analysis of Dutch deep tech ecosystems' potential impact to determine winning strategies

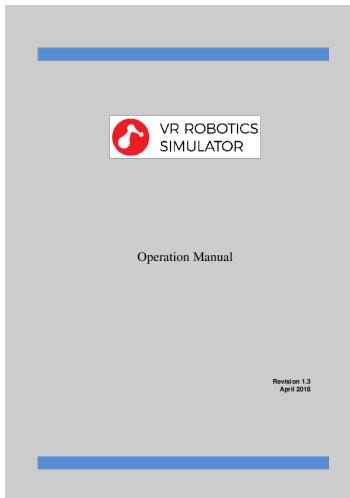
techleap.nl



The Potential of Emerging Technology in the Netherlands: Winning Strategies for Dutch Deep Tech

An analysis of Dutch deep tech ecosystems' potential impact to determine winning strategies, focusing on research questions related to promising deep technology-industry areas and effective public interventions.

lang:en score:22 filesize: 2.44 M page_count: 48 document date: 2021-06-24



Operation Manual

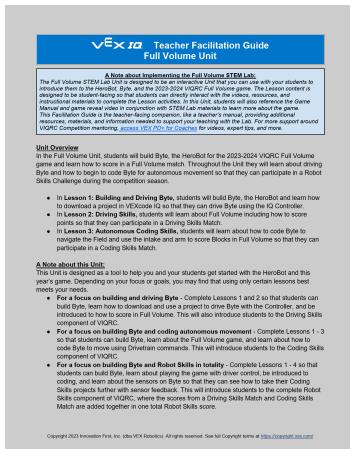
Revision 1
April 2011

[pdf] User Manual

Richard Stokes Operation Manual steamcdn a akamaihd net Synopsis VR Robotics Simulator Contact rjs@mindrend Revision History Date Comments 1 0 2 18 Document Creation 5 Added new sections on object placement 4 23 Updated all for Early Access release Distribution Copy Company Position Name 3 t 1566654913 steam apps 683880 manuals

Operation Manual Revision 1.3 April 2018 Synopsis Contact: Document Control VR
Robotics Simulator Operation Manual rjs mindrend.com Revision 1.0 1.1 1.2 Revision
Date 2-1-18 2-5-18 4-23-18 Revision History Revision Comments Document Creation
Added new sections on object placement Updated all s...

lang:en score:21 filesize: 2.79 M page_count: 41 document date: 2018-04-24



[pdf] User Manual Guide

IQ VIQRC Virtual Skills Full Volume Teacher Facilitation Guide STEM Lab Unit content vexrobotics assets education stem labs docs iq VIQC Unit Mokytojų portalas VEX Education IQ Unit IQ ||| ||| Teacher Facilitation Guide Full Volume Unit A Note about Implementing the Full Volume STEM Lab: The Full Volume STEM Lab Unit is designed to be an interactive Unit that you can use with your students to introduce them to the HeroBot, Byte,

Teacher Facilitation Guide Full Volume Unit A Note about Implementing the Full Volume STEM Lab: The Full Volume STEM Lab Unit is designed to be an interactive Unit that you can use with your students to introduce them to the HeroBot, Byte, and the 2023-2024 VQRC Full Volume game. The lesson content

lang:en score:20 filesize: 310.66 K page_count: 13 document_date: 2023-11-07



VEXcode VR Mars Math Expedition Coding Activity: Teacher Facilitation Guide

A comprehensive teacher's guide for facilitating the Mars Math Expedition Coding Activity using VEXcode VR. This guide provides step-by-step instructions, activity details, preparation steps, and engagement strategies to help students code a virtual robot for scientific exploration on Mars.

lang:en score:19 filesize: 694.63 K page_count: 6 document_date: 0000-00-00

vEX vs Teacher Facilitation Guide Over Under Unit

A Note about Implementing the Over Under STEM Lab:
The Over Under STEM Lab Unit is designed to be an interactive Unit that you can use with your students to introduce them to the HeroBot, Striker, and the 2023-2024 VRC Over Under game. Depending on your focus or goals, you may find that using certain lessons best meets your needs.

• In Lesson 1: Building and Driving Striker, students will build Striker, the HeroBot and learn how to code it to move using VEXcode VR. This will introduce them to the game and how to begin to code Striker for autonomous movement so that they can participate in a Robot Skills Challenge during the competition season.

Unit Overview
In the Over Under Unit, students will build Striker, the HeroBot for the 2023-2024 VRC Over Under game and learn how to score in an Over Under match. Throughout the Unit they will learn about coding Striker and how to begin to code Striker for autonomous movement so that they can participate in a Robot Skills Challenge.

• In Lesson 1: Building and Driving Striker, students will build Striker, the HeroBot and learn how to code it to move using VEXcode VR. This will introduce them to the game and how to begin to code Striker for autonomous movement so that they can participate in a Robot Skills Challenge.

• In Lesson 2: Driving Skills, students will learn about Over Under including how to score points so that they can participate in a Driving Skills Match.

• In Lesson 3: Autonomous Skills, students will learn about how to code Striker to navigate the Field and score the intake and score in an Over Under that they can participate in a Robot Skills Challenge.

• In Lesson 4: Sensors on Striker, students will learn about some V5 sensors that could be incorporated into Striker including the Rotational, Infrared, Optical, and GPS Sensors. They will apply what they learned from the previous Lessons and participate in a Robot Skills Challenge.

A Note about this Unit:
This Unit is designed as a tool to help you and your students get started with the HeroBot and this year's game. Depending on your focus or goals, you may find that using certain lessons best meets your needs.

• For a focus on building and driving Striker - Complete Lessons 1 and 2 so that students can learn how to code Striker for autonomous movement so that they can participate in a Robot Skills Challenge.

• For a focus on building Striker and Driving Skills - Complete Lessons 1 and 2 so that students can learn how to code Striker for autonomous movement so that they can participate in a Robot Skills Challenge.

• For a focus on building Striker and Coding Autonomous Movement - Complete Lessons 1 - 3 so that students can learn how to code Striker for autonomous movement so that they can participate in a Robot Skills Challenge.

• For a focus on building Striker and Robot Skills in Totality - Complete Lessons 1 - 4 so that students can learn Striker, learn about Over Under, the game rules, how to code Striker for coding, and learn how to code Striker for autonomous movement so that they can participate in a Robot Skills Challenge.

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[pdf] User Manual Guide

Teacher Facilitation Guide Over Under STEM Lab Unit Portail de l'enseignant VEX EducationV5

Guidecontent vexrobotics assets education stem labs docs v5 VRC 2023 24 V5 |||

Teacher Facilitation Guide Over Under Unit A Note about Implementing the Over Under STEM Lab: The Over Under STEM Lab Unit is designed to be an interactive Unit that you can use with your students to introduce them to the HeroBot, Striker, and the 2023-2024 VRC Over Under game. The Lesson content is...

lang:en score:19 filesize: 273.42 K page_count: 13 document date: 2023-11-15

Teacher Facilitation Guide GO Competition - Mars Math Expedition Coding Activity

This Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the Mars Math Expedition Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and learning experiences to support them in the most effective way possible. Incorporating UDL into lesson plans and learning experiences is a powerful way to support learning.

Overview of Universal Design for Learning (UDL)

The **UDL Guidelines**, created by CAST, provide a comprehensive framework for Universal Design for Learning—an approach that enhances teaching and learning for everyone. Incorporating UDL into lesson plans and learning experiences is a powerful way to support learning.

Throughout this document, you will find **UDL Moves** calls that highlight specific areas where UDL principles can be applied to increase student engagement and provide a more positive learning experience.

UDL Moves are integrated into the Activity Best, these UDL Move calls offer specific actions you can take as a teacher to improve all students' learning as you implement this Activity.

For deeper exploration of specific UDL principles, you can access detailed resources through embedded links to [CAST's Universal Design and Accessibility \(UDL\)](#).

Overview of the Mars Math Expedition Activity

In the Mars Math Expedition Activity, students will code the Competition Autonomous HeroBot to complete a series of tasks that can be completed in order to earn points. The HeroBot follows a set of pre-programmed moves that can be completed in one minute. There are four Field stages included with the playground, and the students can code the HeroBot to complete the tasks in the order they choose. In this activity, students will begin by engaging in a subset of these tasks. Should they complete them and need an additional challenge, the remaining tasks can be completed.

CSTA Standard

• 1B-AP-12: Modify, revise, or incorporate portions of an existing program into one's own work, or create something new or add more practical features

Activity Tasks

These tasks are the same as the tasks in the Mars Math Expedition GO Competition (EDU Lab). To see an example of how to complete each task, select the task in each description, and watch the video. If we are short on time, skip to the end of the video to view a short clip of the robot completing the task. Although they are being completed by a physical robot in the video, the tasks are the same during the virtual robot.

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VEXcode VR Mars Math Expedition Coding Activity Teacher Facilitation Guide Hour of Code

Activitiesvexcode vr mars math expedition teacher notescontent vexrobotics assets hoc s vexcode notes v

3 |||

Teacher Facilitation Guide GO Competition - Mars Math Expedition Coding Activity
This Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the Mars Math Expedition Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implementation to best suit your students. The activity is designed to be flexible so that you can meet students where they are, engage them, and provide the necessary support and motivation to move to meet your learning goals.

lang:en score:18 filesize: 824.73 K page_count: 7 document date: 2024-12-09

Teacher Facilitation Guide VRC Spin Up Coding Activity

This Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the VEX Robotics Competition (VRC) Spin Up Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implementation to best suit your students. The activity is designed to be flexible so that you can meet students where they are, engage them, and provide the necessary support and motivation to move to meet your learning goals.

Overview of Universal Design for Learning (UDL)

The **UDL Guidelines**, created by CAST, provide a comprehensive framework for Universal Design for Learning—an approach that enhances teaching and learning for everyone. Incorporating UDL into lesson plans and learning experiences is a powerful way to support learning.

Throughout this document, you will find **UDL Moves** calls that highlight specific areas where UDL principles can be applied to increase student engagement and provide a more positive learning experience.

UDL Moves are integrated into the Activity Best, these UDL Move calls offer specific actions you can take as a teacher to improve all students' learning as you implement this Activity.

For deeper exploration of specific UDL principles, you can access detailed resources through embedded links to [CAST's Universal Design and Accessibility \(UDL\)](#).

Overview of VRC Spin Up

Code Dash, the robot, to score Dashes in the Low and High Goals and own Field E as many as possible within 1 minute.

• To learn more about the challenges for the VRC Spin Up activity see [the reference sheet](#).

CSTA Standard

• 2-AP-15: Edit and incorporate feedback from team members and users to refine a solution that meets user needs

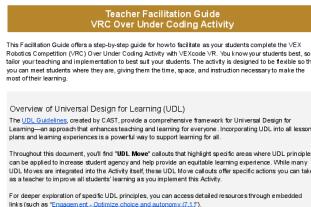


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VEXcode VR VRC Spin Up Coding Activity Teacher Facilitation Guide Hour of Code Activitiesvc spin up teacher notescontent vexrobotics assets hoc s vr vrc notes v 2 |||

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lang:en score:18 filesize: 1.43 M page_count: 7 document date: 2024-12-09



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lang:en score:17 filesize: 1.43 M page_count: 5 document date: 2024-12-05



[pdf] User Manual Quick Start Guide Instructions Troubleshooting Guide

Specifications Guide

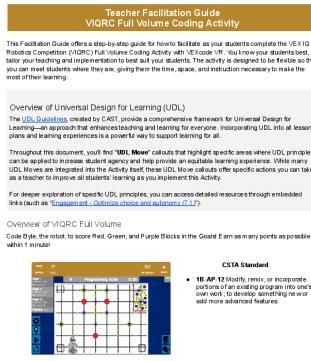
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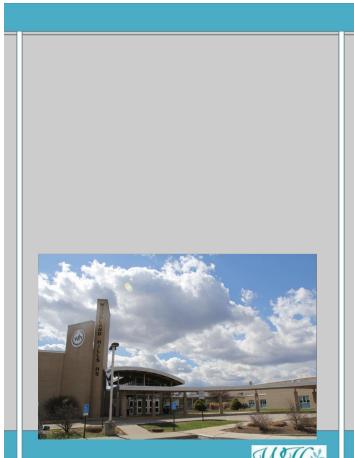
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VEXcode VR VIQRC Full Volume Coding Activity Teacher Facilitation Guide Hour of Code

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Teacher Facilitation Guide VIQRC Full Volume Coding Activity This Facilitation Guide offers a step-by-step guide for how to facilitate as your students complete the VEX IQ Robotics Competition (VIQRC) Full Volume Coding Activity with VEXcode VR. You know your students best, so tailor your teaching and implementation to best suit your students. The activity is designed to be flexible so that you can meet students where they are, giving them the time, space, and instruction necessary to make the most of their learning.

lang:en score:17 filesize: 961.37 K page_count: 6 document date: 2024-12-05



[\[pdf\] Guide](#)

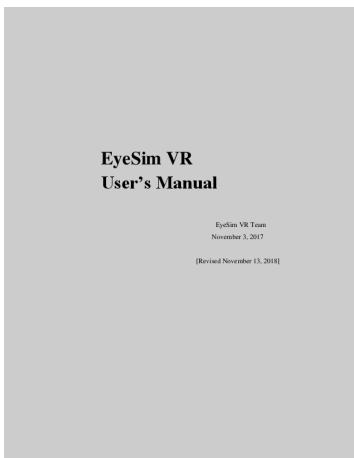
Albert Willson Curriculum Planning Guide 2Hr Delay Bell Schedule Students Woodland Hills High School 25 26 APPROVED drive google file d 1w64v3zmwwYufEpQzPG5UG9PCAqk IS1T view usp sharing ||| Woodland Hills School District Curriculum Planning Guide Woodland Hills School District Intermediate Secondary Curriculum Planning Guide 2025-2026 School Year Dickson Preparatory STEAM Academy Grades 6-8 7301 Schoyer Avenue Swissvale, PA 15218 412-731-5816 Woodland Hills High School Grades 9-12 ... lang:en **score:14** filesize: 7 M page_count: 98 document date: 2025-02-06



[\[pdf\] Vileda Robot VR 101: Your Guide to Effortless Home Cleaning](#)

Discover the Vileda Robot VR 101, an automated cleaning solution designed to efficiently remove dirt, dust, and hair from your home. This guide provides essential information on setup, operation, maintenance, and safety.

lang:en **score:13** filesize: 1.38 M page_count: 108 document date: 2017-06-22



[\[pdf\] User Manual](#)

Le Zhang EyeSim VR Robotics User's Manual Team November 3 2017 Revised 13 2018 1 GENERAL INFORMATION This simulator will let users simulate the robots execution of functions specified in RoBIOS-7 file. It accepts and runs customized script files UserManual robotics ee uwa edu au eyesim ftp 80 |||

EyeSim VR User's Manual EyeSim VR Team November 3, 2017 Revised November 13, 2018 1 GENERAL INFORMATION This simulator will let users simulate the robots execution of functions specified in RoBIOS-7 file. It accepts and runs customized script files written in C, and simulates robot behaviors of...

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Digital technology and advanced analytics in Roche Tobin Gerard FXN ~Basel Investor Relations Event
May 2020 Program to replace manual Patients with HD the RG6042 global development programme
receive a smartphone smartwatch first complete active tests using these tools teaching session clinic The
are then done ipr20200507 roche dam jcr 899be975 4578 4b1c b512 b1e5e566a30c en 3 mag — This
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lang:en score:11 filesize: 4.73 M page_count: 67 document_date: 2020-05-07

Name: _____	Date: _____
Computer Science Level 1 - Python Course	
Unit 3 - Lesson 2: If Else & Conditional Statements Quiz	
<p>1. Which of the following best describes an <code>if</code> statement?</p> <ol style="list-style-type: none"> A non-returning command that runs simultaneously with other commands. A conditional statement that runs all branches based on the numeric values reported. A conditional statement that runs different branches of code based on the Boolean value reported. A command that runs both branches simultaneously based on the numeric values reported. 	
<p>2. Which of the following is TRUE of an <code>if</code> statement?</p> <ol style="list-style-type: none"> The <code>if</code> branch and <code>else</code> branch of the project can run simultaneously in a project. The <code>else</code> statement forces a decision to be made, as only one branch of the project can be true at a given time. The <code>else</code> statement is a loop that checks if a condition continuously. The <code>else</code> branch will be executed every time the project is run. 	
<p>3. Which loops are normally used with an <code>if</code> statement to check the condition more than once?</p> <ol style="list-style-type: none"> <code>while</code> loop or <code>for</code> loop <code>while</code> loop or <code>else</code> <code>for</code> or <code>heavily</code> or <code>for</code> loop <code>else</code> <code>for</code> or <code>while</code> loop with a <code>not</code> condition 	
<p>4. What is the best description of why you would nest an <code>if</code> / <code>else</code> statement inside of an <code>infinity</code> loop?</p> <ol style="list-style-type: none"> The <code>if</code> / <code>else</code> statement runs the entire <code>infinity</code> <code>while</code> loop one time to check if the condition is met before the loop continues. The <code>if</code> while loop checks the <code>if</code> / <code>else</code> statement to check if the condition is being reported. Yes or False. The <code>if</code> while loop checks the <code>if</code> / <code>else</code> statement TWICE to check if the condition is being reported. True or False. The <code>if</code> while loop continuously runs through the <code>if</code> / <code>else</code> statement to check if the condition is being reported True or False, until the project is stopped. 	

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Python Quizcontent vexrobotics assets education stem labs docs cs Courses Quizzes Exams Level 1 VR

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Name: _____ Date: _____

Computer Science Level 1 - Python Course Unit 9 - Lesson 2: If Else Conditional Statements Quiz 1. Which of the following best describes an if else statement a. A non-waiting command that runs simultaneously with...

[pdf] Instructions

CS Level 1 Where and How CSTA Standards are Reached VR Reached content vexrobotics assets education stem labs docs cs Courses Teacher Portal VEX Education VR Reached VR ||| Identifier 1A-AP-10 Concept Subconcept Description Unit Algorithms and Programming Control Develop programs with sequences and simple loops, to express ideas or address a problem. Unit 2 Moving Your Robot 1A-AP-11 Algorithms and Programming

Identifier 1A-AP-10 Concept Subconcept Description Unit Algorithms and

Programming Control Develop programs with sequences and simple loops, to express ideas or address a problem. Unit 2 Moving Your Robot 1A-AP-11 Algorithms and Programming Modularity Decompose break down the steps nee...

lang:en score:10 filesize: 110.07 K page_count: 10 document date: 2023-11-21

Playground: Dynamic Castle Crusher Challenges:

Level 1: Create an algorithm to knock over all five buildings in one Castle layout using the VR Robot.

Level 2: Improve your algorithm to knock over all buildings in three different Castle layouts.

Level 3: Improve your algorithm to knock over all buildings in five Castle Layouts in eight minutes or less.

Helpful Hints:

- Each time the Playground is reset, the layout of the buildings randomly change. There are ten total Castle Crusher Playground layouts.
- Keep in mind that the algorithm should be written so that the VR Robot can knock over all five buildings regardless of the Playground layout.
- Castle building pieces will be detected as objects by the Distance sensor.
- Be careful not to fall off the size of the table. Building these are not for the wails!

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Crash the Castle VEXcode VR VEX Activities Education content vexrobotics assets education stem labs docs cs Playgrounds Dynamic Crasher |||

AlgoAdvanced here. Want to make edits Make a copy first Learn more Crash the Castle Playground: Dynamic Castle Crasher Challenges: Level 1: Create an algorithm to knock over all five buildings in one Castle layout using the VR Robot. Level 2: Improve your algorithm to knock over all buildings ...

lang:en score:9 filesize: 308.87 K page_count: 2 document_date: 2023-11-20

Name: _____	Date: _____
Computer Science Level 1 - Blocks with VEXcode VR Course	
Unit 2 Exam	
<p>1. What of these best describes a programming language?</p> <ol style="list-style-type: none"> A set of rules where symbols represent actions. A set of spoken commands for a robot. An action performed by a robot. A list of behaviors the robot already completed. 	
<p>2. What is the name for an action performed by the VR Robot?</p> <ol style="list-style-type: none"> Command Behavior Program Programming Language 	
<p>3. How do you change the behavior of the VR Robot?</p> <ol style="list-style-type: none"> Change the programming language Name and save your project Change the programming blocks called commands Change the playground 	

Page 1 of 5

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Unit 2 Exam VEX CS Moving Your Robot ExamVR Blocks Examcontent vexrobotics assets education stem labs docs cs Courses Quizzes and Exams Level 1 VR |||

Name: _____ Date: _____

Computer Science Level 1 - Blocks with VEXcode VR

Course Unit 2 Exam 1. Which of these best describes a programming language a. A set of rules where symbols represent actions. b. A set of spoken commands for a robot...

lang:en **score:9** filesize: 340.27 K page_count: 5 document date: 2023-11-21

Name: _____	Date: _____
Computer Science Level 1 - Python Course	
Unit 8 Exam	
<p>1. What creates the magnetic field for the Electromagnet?</p> <ol style="list-style-type: none"> An electric current An electrical outlet A button on the VR Robot An additional magnet 	
<p>2. What objects on the VR Playground can the Electromagnet on the VR Robot pick up?</p> <ol style="list-style-type: none"> Dots Buildings Balls Pin drives 	
<p>3. What is one use of the Electromagnet on the VR Robot?</p> <ol style="list-style-type: none"> To lift the metal objects To pull the metal objects To pick up and put down dots with metal cores To find metal in the walls of playgrounds 	
<p>4. What is the best description of the <code>move</code> command?</p> <ol style="list-style-type: none"> Sets the Electromagnet to two different modes: Left or Right Creates the Electromagnet to press both bumper buttons Creates the Electromagnet to affect all metal objects in the playground Sets the Electromagnet to two different modes: <code>GO/STOP</code> or <code>DROP</code> 	

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vEXcode VR Activities

Sweep the Castle



Playground: Dynamic Castle Crasher

Challenges:

- Level 1: Create an algorithm to knock all castle pieces off of one Playground layout using the VR Robot.
- Level 2: Improve your algorithm to clear all castle building pieces off of three different Playground layouts.
- Level 3: Improve your algorithm to clear all castle building pieces off of five different Playground layouts in under ten minutes.

Helpful Hints:

- Each time the Playground is reset, the layout of the buildings randomly changes. There are ten total Castle Crasher Playground layouts.
- Keep in mind that the algorithm should be written so that the VR Robot can knock over all five buildings regardless of the Playground layout.

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Sweep the Castle VEXcode VR VEX Activities Educationcontent vexrobotics assets education stem labs docs cs Playgrounds Dynamic Crasher |||

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VEXcode VR Activities



Playground: Hidden Pixel Art

Discover the Hidden Pixel Art by navigating around the entire Playground surface under the gold colored roof. Each pixel in the Hidden Pixel Art is 1 grid square in size, and the entire Hidden Pixel Art is 8 pixels by 8 pixels in size. Filled pixels will report to the Down Eye Sensor as 'Green' and empty pixels will report to the Down Eye Sensor as 'Blue'.

Challenges:

Level 1: Using a pattern of colors, create an 8 x 8 grid. Program the VR Robot to navigate across the entire Pixel Art Playground. When the VR Robot is driving, use the 'Record' button to observe and record the color value of the Down Eye Sensor on the paper. It is 8 x 8 grid. The colors recorded on your 8 x 8 grid will reveal the Hidden Pixel Art. Once the VR Robot has traveled every square, use the Reveal Answer button to check your solution.

Level 2: In VEXcode VR, create a 12x12 grid with 8 rows and 12 columns. Program the VR Robot to navigate around the Hidden Pixel Art in the 2D List. Once the VR Robot has navigated around the entire Playground surface under the gold colored roof, use the Reveal Answer button to check your solution.

Level 3: Building from the Level 2 project, extend your project to display a representation of the Hidden Pixel Art using data from the 2D List to the Print Console. Once the VR Robot has navigated around the entire Playground surface under the gold colored roof, use the Reveal Answer button to check your solution.

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Hidden Pixel Art VEXcode VR Activities VEX Education content vexrobotics assets education stem labs docs cs Playgrounds |||

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Playground: Hidden Pixel Art Discover the Hidden Pixel Art by navigating around the entire Playground surface under the gold colored roof. Each pixel in the Hidden Pixel Art is 1 grid square in size, and the entire H...

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VEXcode VR Activities



Playground: Grid Map

Challenge:

Level 1: Program the VR Robot to drive forward 1 grid square. Next, program the VR robot to drive in reverse to the beginning point. Continue this pattern for 2 grid squares.

Level 2: Program the VR Robot to drive forward 1 grid square, stop, and then drive in reverse 1 grid square. Once the VR Robot has started driving using the reverse block, the VR Robot will need to turn around and drive back to the first position. Continue this pattern for 2 grid squares, then 4 grid squares.

Level 3: Build an algorithm (a process or set of rules) to move through all 1 to 1 grid squares in sequential order. The VR Robot should move to 1 to 1 grid to start, move to 2, go back to start. Continue this pattern for all 8 grid squares.

Helpful Hints:

- Each square in the Grid Map measures 200mm by 200mm.
- Want to make your project shorter? Try using the *Repeat* block from the Control category.



• Matching Python command:

`for repeat_count in range(10):`

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Basketball Drills VEXcode VR VEX Activities Education content vexrobotics assets education stem labs docs cs Playgrounds Grid Map |||

Movement Want to make edits Make a copy first Learn more here. Playground: Grid

Map Basketball Drills Challenge: Level 1: Program the VR Robot to drive forward 1 grid square. Next, program the VR robot to drive in reverse to the beginning point. Continue this pattern for 2 grid squares, then ...

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