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Waveshare Dust Sensor

Waveshare Dust Sensor Detector Module User Manual

Model: Dust Sensor

1. INTRODUCTION

This manual provides detailed instructions for the Waveshare Dust Sensor Detector Module, featuring the Sharp GP2Y1010AU0F sensor. This module is designed for accurate detection of fine particles, including those found in cigarette smoke, with a diameter larger than 0.8 μ m. It outputs an analog voltage directly proportional to the dust density, making it an essential component for various air quality monitoring and control systems.



Figure 1: Waveshare Dust Sensor Detector Module.

2. KEY FEATURES

- **Sharp GP2Y1010AU0F Onboard:** Detects fine particles larger than $0.8\mu\text{m}$ in diameter, including cigarette smoke.
- **Low Power Consumption:** Efficient operation for extended use.
- **Analog Voltage Output:** Provides an output level that is linear with dust density, simplifying data interpretation.
- **Embedded Voltage Boost Circuit:** Supports a wide range of power supply inputs (2.5V to 5.5V).

3. TECHNICAL SPECIFICATIONS

Parameter	Value
Sensitivity	$0.5\text{V}/(100\mu\text{g}/\text{m}^3)$
Measurement Range	$500\mu\text{g}/\text{m}^3$
Power Supply	2.5V ~ 5.5V
Operating Current	20mA (max)

Operating Temperature	-10°C ~ 65°C
Storage Temperature	-20°C ~ 80°C
Life Time	5 years
Dimensions (L×W×H)	63.2mm × 41.3mm × 21.1mm
Mounting Hole Size	2.0mm
Air Hole Size	9.0mm



Figure 2: Overview diagram showing key specifications and connection details.

4. PACKAGE CONTENTS

The Waveshare Dust Sensor Detector Module package typically includes:

- 1x Waveshare Dust Sensor Detector Module (with Sharp GP2Y1010AU0F)
- 1x 6-pin connection cable



Figure 3: Included 6-pin connection cable.

5. SETUP AND CONNECTION

To integrate the Waveshare Dust Sensor Detector Module with a microcontroller unit (MCU), follow these connection guidelines:

1. **VCC:** Connect to the power supply of your MCU. The module supports a voltage range of 2.5V to 5.5V. Ensure your power supply is within this range to prevent damage.
2. **GND:** Connect to the ground (GND) of your MCU.
3. **AOUT:** Connect to an analog input pin on your MCU. This pin provides the analog voltage output, which is proportional to the dust density.
4. **ILED:** Connect to a digital I/O pin on your MCU. This pin is used to drive the internal infrared LED of the sensor. Refer to the sensor's datasheet or Waveshare's documentation for specific timing requirements for pulsing this pin to take readings.

Overview

- Sharp GP2Y1010AU0F onboard, detecting fine particle larger than $0.8\mu\text{m}$ in diameter, even like the cigarette smoke
- Low power consumption, analog voltage output, the output level is linear with dust density
- Embedded voltage boost circuit to support wide range of power supply

Specifications

- Sensitivity : $0.5\text{V}/(100\mu\text{g}/\text{m}^3)$
- Measurement range : $500\mu\text{g}/\text{m}^3$
- Power : 2.5V~5.5V
- Operating current : 20mA(max)
- Operating temperature : $-10^\circ\text{C}\sim 65^\circ\text{C}$
- Storage temperature : $-20^\circ\text{C}\sim 80^\circ\text{C}$
- Life time : 5 years
- Dimension : $63.2\text{mm}\times 41.3\text{mm}\times 21.1\text{mm}$
- Mounting holes size : 2.0mm
- Air hole size : 9.0mm

Applications

- Air purifier
- Air conditioner
- Air monitor
- PM2.5 Detector

How to Use

In the case of working with a MCU:

- VCC ↔ 2.5V ~ 5.0V
- GND ↔ GND
- AOUT ↔ MCU.IO (analog output)
- ILED ↔ MCU.IO (module driving pin)

Photos



As shown in the first picture above, you can add the bottom pinheaders (not soldered by default) for easily connecting the module to your application board.

Figure 4: Dust Sensor Module with connection cable.

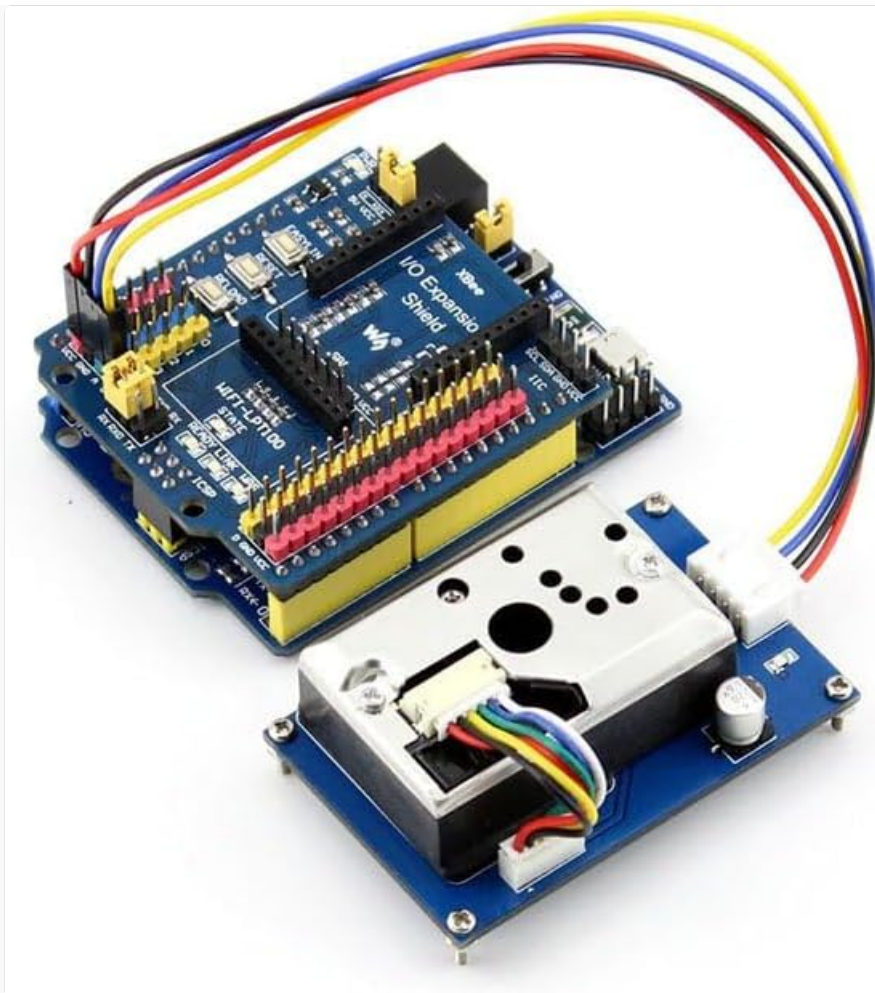


Figure 5: Example connection of the Dust Sensor Module to an Arduino expansion shield.



Figure 6: Pinout diagram on the bottom of the module for reference.

6. OPERATION PRINCIPLES

The Sharp GP2Y1010AU0F sensor operates by detecting scattered light from dust particles. An infrared emitting diode (ILED) periodically pulses light into a detection area. If dust particles are present, they scatter this light, which

is then detected by a phototransistor. The amount of scattered light is converted into an analog voltage output (AOUT).

The output voltage is directly proportional to the concentration of dust in the air. Higher dust concentrations result in a higher analog output voltage. To obtain accurate readings, it is crucial to pulse the ILED pin according to the sensor's specifications (e.g., a 0.32ms pulse width within a 10ms cycle, with sampling at 0.28ms into the pulse).

7. MAINTENANCE

To ensure optimal performance and longevity of your dust sensor module, consider the following maintenance tips:

- **Keep Clean:** Periodically inspect the sensor's air intake and optical path for dust accumulation. Gently blow dust away using compressed air. Avoid using liquids or abrasive materials.
- **Avoid Physical Contact:** Do not touch the internal components of the sensor, especially the optical elements.
- **No Adjustments:** The potentiometer on the module is factory-calibrated. Do not attempt to adjust it, as this can negatively impact sensor accuracy.

8. TROUBLESHOOTING

If you encounter issues with your Waveshare Dust Sensor Detector Module, refer to the following common problems and solutions:

- **No Output or Erratic Readings:**
 - Verify all connections (VCC, GND, AOUT, ILED) are secure and correctly wired to your MCU.
 - Ensure the power supply voltage is within the specified range of 2.5V to 5.5V. Supplying higher voltages can damage the module.
 - Check your microcontroller code for correct timing and analog reading procedures for the ILED and AOUT pins. Refer to Waveshare's official documentation for example code.
- **Inconsistent or Fluctuating Readings:**
 - Ensure the sensor is placed in an area with stable airflow, free from direct drafts or stagnant air pockets. Consider adding a small fan to ensure consistent air sampling if needed.
 - Environmental factors such as humidity and temperature can influence readings. Ensure the operating environment is within the specified temperature range.
- **Module Not Powering On / Damaged:**
 - Reconfirm that the input voltage does not exceed 5.5V. Overvoltage is a common cause of damage.
 - Inspect the module for any visible physical damage or loose solder joints.

9. WARRANTY AND SUPPORT

For technical support, additional documentation, and software examples, please visit the official Waveshare website. Information regarding product warranty and return policies can typically be found on the product page where the item was purchased or on the Waveshare support portal.

Related Documents - Dust Sensor

2.4inch LCD Module

Overview

Introduction

This 2.4 inch TFT display module with a resolution of 320 x 240, is based on SPI interface for communication. LCD has an internal controller with built-in drivers, which can work with color panels, mono, color, and transparent, and can display English, Chinese as well as pictures. The product is available in different sizes: 1.8 inch (240x320 pixels), 2.0 inch (320x480 pixels), 2.2 inch (320x480 pixels), 2.4 inch (320x480 pixels), 2.8 inch (480x800 pixels), and 3.5 inch (800x480 pixels).

Specification

- Display screen: 2.4inch TFT color display, 320 pixels width, 480 pixels height
- Resolution: 320 x 480
- LCD Type: TFT
- Controller: SPI
- Interface: SPI (VCC) / GND (GND)
- Display Size: 2.4" (63.5mm) x 3.9" (99.1mm)
- Panel Size: 3.25" (82.5mm) x 4.5" (114.3mm)
- Dimensions: 32.5 x 45.5 (mm)

Interface Description

Raspberry Pi hardware connection

Please connect the LCD to your Raspberry Pi by the SPI pins according to the table below.

If you use the pin header or PH2.0 SPI interface, you need to connect according to the following table.

LCD	Pin	Raspberry Pi	Pin
GND	1	GND	6
VCC	2	VCC	1
CS	3	CS	24
DC	4	DC	27
SDA	5	SDA	21
SCL	6	SCL	22
RES	7	RES	18
BL	8	BL	5

The 2.4 inch LCD uses PH2.0 SPI interface, which can be connected to the Raspberry Pi according to the above table. Please connect according to the pin definition table. The color of the wires is the same as the color of the pins.

STM32 hardware connection

The example is provided based on STM32F103C8T6, and the connection method provides a reference for other STM32F103C8T6. If you need to transplant the program, please connect according to the table below.

STM32F103C8T6	Pin	LCD	Pin
GND	1	GND	6
VCC	2	VCC	1
CS	3	CS	24
DC	4	DC	27
SDA	5	SDA	21
SCL	6	SCL	22
RES	7	RES	18
BL	8	BL	5

The 2.4 inch LCD uses PH2.0 SPI interface, which can be connected to the Raspberry Pi according to the above table. Please connect according to the pin definition table. The color of the wires is the same as the color of the pins.

Arduino hardware connection

Arduino Uno Controller pin communication

LCD	Pin	Arduino Uno	Pin
GND	1	GND	6
VCC	2	VCC	1
CS	3	CS	24
DC	4	DC	27
SDA	5	SDA	21
SCL	6	SCL	22
RES	7	RES	18
BL	8	BL	5

The controller chip is an Arduino Uno R3.

Hardware Description

LCD and the controller

The LCD supports 1.8", 2.0", 2.2", 2.4", 2.8" and 3.5" size color TFTs per panel, mainly RGB666, RGB565, and RGB565. The LCD uses RGB666 color format, which is a more common and RGB format.

The LCD controller, the communication mode of the controller can be configured, mainly with an I2C and SPI modes. The LCD uses SPI and other communication methods. The LCD uses the SPI communication interface, which can provide SPI (VCC), and the communication speed and the data.

Communication Protocol

1. CS: CS is active-low signal. When CS is low, the LCD is selected.

2. DC: DC is active-low signal. When DC is low, the LCD is selected. When DC is high, the LCD is in command mode. When DC is low, the LCD is in data mode.

3. DC: DC is active-low signal. When DC is low, the LCD is selected. When DC is high, the LCD is in command mode. When DC is low, the LCD is in data mode.

4. DC: DC is active-low signal. When DC is low, the LCD is selected. When DC is high, the LCD is in command mode. When DC is low, the LCD is in data mode.

5. DC: DC is active-low signal. When DC is low, the LCD is selected. When DC is high, the LCD is in command mode. When DC is low, the LCD is in data mode.

6. DC: DC is active-low signal. When DC is low, the LCD is selected. When DC is high, the LCD is in command mode. When DC is low, the LCD is in data mode.

Working with Raspberry Pi

Enable SPI interface

1. Open terminal, use command to enter the configuration page.

```
sudo raspi-config
```

2. Select "Interface Options" (I) -> SPI -> Yes.

3. Reboot Raspberry Pi.

```
sudo reboot
```

4. After reboot, the SPI is not occupied by other devices, you can check in the middle of Raspberry Pi.

Install SPI interface

1. Install SPI interface.

```
sudo apt-get install python-smbus
```

2. Run the following command to check the SPI interface.

```
python3 -c 'import smbus; s = smbus.SMBus(1); s.read_byte(0x00); print("SPI is working")'
```

3. If the output is "SPI is working", it means the SPI interface is installed successfully.

Initial SPI interface

1. Run the following command to check the SPI interface.

```
python3 -c 'import smbus; s = smbus.SMBus(1); s.read_byte(0x00); print("SPI is working")'
```

2. If the output is "SPI is working", it means the SPI interface is installed successfully.

3. Run the following command to check the SPI interface.

```
python3 -c 'import smbus; s = smbus.SMBus(1); s.read_byte(0x00); print("SPI is working")'
```

4. If the output is "SPI is working", it means the SPI interface is installed successfully.

Install System Binaries

```
sudo apt-get install libx11-dev
sudo apt-get install libxext-dev
sudo apt-get install libxrender-dev
sudo apt-get install libxrandr-dev
sudo apt-get install libxss-dev
sudo apt-get install libxft-dev
sudo apt-get install libxkbfile-dev
sudo apt-get install libxkbutil-dev
sudo apt-get install libxkbcommon-dev
sudo apt-get install libxkbcommon-x11-dev
sudo apt-get install libxkbcommon-dev
sudo apt-get install libxkbcommon-x11-dev
sudo apt-get install libxkbcommon-dev
sudo apt-get install libxkbcommon-x11-dev
```

Download Examples

```
cd /tmp
git clone https://github.com/0x00sec/0x00sec.git
cd 0x00sec
cp *.sh /usr/bin/
```

Run the demo codes

Make sure the Raspberry Pi device is fully booted and run the commands in terminal

C codes

```
ls
ls -la
ls -ld /usr/bin
```

The first program of all examples can be loaded already by entering the corresponding file

```
sudo ./0x00sec_001.sh
```

Depending on the CPU, use of the following commands should be entered:

```
ls -ld /usr/bin
ls -ld /usr/bin/0x00sec_001.sh
ls -ld /usr/bin/0x00sec_002.sh
ls -ld /usr/bin/0x00sec_003.sh
ls -ld /usr/bin/0x00sec_004.sh
ls -ld /usr/bin/0x00sec_005.sh
ls -ld /usr/bin/0x00sec_006.sh
ls -ld /usr/bin/0x00sec_007.sh
ls -ld /usr/bin/0x00sec_008.sh
ls -ld /usr/bin/0x00sec_009.sh
ls -ld /usr/bin/0x00sec_010.sh
ls -ld /usr/bin/0x00sec_011.sh
ls -ld /usr/bin/0x00sec_012.sh
ls -ld /usr/bin/0x00sec_013.sh
ls -ld /usr/bin/0x00sec_014.sh
ls -ld /usr/bin/0x00sec_015.sh
ls -ld /usr/bin/0x00sec_016.sh
ls -ld /usr/bin/0x00sec_017.sh
ls -ld /usr/bin/0x00sec_018.sh
ls -ld /usr/bin/0x00sec_019.sh
ls -ld /usr/bin/0x00sec_020.sh
```

python

Enter the python program directory and run the command ls

```
cd /usr/bin/0x00sec
ls
```

```
ls -ld /usr/bin/0x00sec_001.sh
ls -ld /usr/bin/0x00sec_002.sh
ls -ld /usr/bin/0x00sec_003.sh
ls -ld /usr/bin/0x00sec_004.sh
ls -ld /usr/bin/0x00sec_005.sh
ls -ld /usr/bin/0x00sec_006.sh
ls -ld /usr/bin/0x00sec_007.sh
ls -ld /usr/bin/0x00sec_008.sh
ls -ld /usr/bin/0x00sec_009.sh
ls -ld /usr/bin/0x00sec_010.sh
ls -ld /usr/bin/0x00sec_011.sh
ls -ld /usr/bin/0x00sec_012.sh
ls -ld /usr/bin/0x00sec_013.sh
ls -ld /usr/bin/0x00sec_014.sh
ls -ld /usr/bin/0x00sec_015.sh
ls -ld /usr/bin/0x00sec_016.sh
ls -ld /usr/bin/0x00sec_017.sh
ls -ld /usr/bin/0x00sec_018.sh
ls -ld /usr/bin/0x00sec_019.sh
ls -ld /usr/bin/0x00sec_020.sh
```

```
ls -ld /usr/bin/0x00sec_001.sh
ls -ld /usr/bin/0x00sec_002.sh
ls -ld /usr/bin/0x00sec_003.sh
ls -ld /usr/bin/0x00sec_004.sh
ls -ld /usr/bin/0x00sec_005.sh
ls -ld /usr/bin/0x00sec_006.sh
ls -ld /usr/bin/0x00sec_007.sh
ls -ld /usr/bin/0x00sec_008.sh
ls -ld /usr/bin/0x00sec_009.sh
ls -ld /usr/bin/0x00sec_010.sh
ls -ld /usr/bin/0x00sec_011.sh
ls -ld /usr/bin/0x00sec_012.sh
ls -ld /usr/bin/0x00sec_013.sh
ls -ld /usr/bin/0x00sec_014.sh
ls -ld /usr/bin/0x00sec_015.sh
ls -ld /usr/bin/0x00sec_016.sh
ls -ld /usr/bin/0x00sec_017.sh
ls -ld /usr/bin/0x00sec_018.sh
ls -ld /usr/bin/0x00sec_019.sh
ls -ld /usr/bin/0x00sec_020.sh
```

FBCP Porting

The FBCP is currently not compatible with the Raspberry Pi system's 64-bit architecture.

Therefore, you need a custom kernel to use a 32-bit architecture from a memory buffer containing complete kernel data. This is a complex task to do for the Raspberry Pi, and the kernel code can be found in the repository for the Pi.

There is an open source project on GitHub, [FBCP](#). Compared with other FBCP projects, this project can start faster and DMA to achieve a speed of up to 100MB/s.

Download Drivers

```
sudo apt-get install libx11-dev
sudo apt-get install libxext-dev
sudo apt-get install libxrender-dev
sudo apt-get install libxrandr-dev
sudo apt-get install libxss-dev
sudo apt-get install libxft-dev
sudo apt-get install libxkbfile-dev
sudo apt-get install libxkbutil-dev
sudo apt-get install libxkbcommon-dev
sudo apt-get install libxkbcommon-x11-dev
```

Method 1: Use a script (recommended)

Here we will use a script that allows you to quickly use the script and run the corresponding commands according to the script.

If you use a script and do not need to modify it, you can use the script without modification. If you need to modify the script, you can use the script and modify it according to your needs.

```
ls -ld /usr/bin/0x00sec_001.sh
ls -ld /usr/bin/0x00sec_002.sh
ls -ld /usr/bin/0x00sec_003.sh
ls -ld /usr/bin/0x00sec_004.sh
ls -ld /usr/bin/0x00sec_005.sh
ls -ld /usr/bin/0x00sec_006.sh
ls -ld /usr/bin/0x00sec_007.sh
ls -ld /usr/bin/0x00sec_008.sh
ls -ld /usr/bin/0x00sec_009.sh
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ls -ld /usr/bin/0x00sec_014.sh
ls -ld /usr/bin/0x00sec_015.sh
ls -ld /usr/bin/0x00sec_016.sh
ls -ld /usr/bin/0x00sec_017.sh
ls -ld /usr/bin/0x00sec_018.sh
ls -ld /usr/bin/0x00sec_019.sh
ls -ld /usr/bin/0x00sec_020.sh
```

Method 2: Manual Configuration

Environment Configuration

Raspberry Pi will not start if you use the script, so we need to check the script before installing it in the Pi.

```
ls -ld /usr/bin/0x00sec_001.sh
```

Run the script according to the instructions.

```
#!/bin/bash
# Enable DRM V4L2 V3D driver
#dtoverlay=v4l-kms-v3d
#max_framebuffers=2
```

Complete and run

```
ls -ld /usr/bin/0x00sec_001.sh
```

Run the script according to the instructions.

```
ls -ld /usr/bin/0x00sec_001.sh
```

Run the script according to the instructions.

Run the script according to the instructions.

Run the script according to the instructions.

Run the script according to the instructions.

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Run the script according to the instructions.

Run the script according to the instructions.

Run the script according to the instructions.

Run the script according to the instructions.

- Image error fix: Add the error fix of the attached image. You can choose to rotate, horizontal mirror, vertical mirror or image color reverse.

Head: `Head_PictureImageErrorFix` Name: `Head_PictureImageErrorFix` Description: `Head_PictureImageErrorFix` Parameters: `Head_PictureImageErrorFix` (Type: `enum`) `Head_PictureImageErrorFix` (Type: `enum`) `Head_PictureImageErrorFix` (Type: `enum`) `Head_PictureImageErrorFix` (Type: `enum`)

- Set priority of display number and color in the buffer. You can choose to use 24-bit color, 16-bit color, 8-bit color, or 1-bit color.

Head: `Head_PictureImagePriority` Name: `Head_PictureImagePriority` Description: `Head_PictureImagePriority` Parameters: `Head_PictureImagePriority` (Type: `enum`) `Head_PictureImagePriority` (Type: `enum`) `Head_PictureImagePriority` (Type: `enum`)

- Image buffer color: Fill the image buffer with a color, usually used to fill the image background.

Head: `Head_PictureImageColor` Name: `Head_PictureImageColor` Description: `Head_PictureImageColor` Parameters: `Head_PictureImageColor` (Type: `enum`) `Head_PictureImageColor` (Type: `enum`) `Head_PictureImageColor` (Type: `enum`)

- Image buffer part of the window filling color: The image buffer part of the window that can control color, providing a better windowing function, usually used for the display window background.

Head: `Head_PictureImageColorPart` Name: `Head_PictureImageColorPart` Description: `Head_PictureImageColorPart` Parameters: `Head_PictureImageColorPart` (Type: `enum`) `Head_PictureImageColorPart` (Type: `enum`) `Head_PictureImageColorPart` (Type: `enum`)

- Draw points: In the image buffer, draw points or figures. You can choose to use the color of the buffer or the color of the figure.

Head: `Head_PictureImageDrawPoints` Name: `Head_PictureImageDrawPoints` Description: `Head_PictureImageDrawPoints` Parameters: `Head_PictureImageDrawPoints` (Type: `enum`) `Head_PictureImageDrawPoints` (Type: `enum`) `Head_PictureImageDrawPoints` (Type: `enum`)

- Draw strings: In the image buffer, draw strings or figures. You can choose to use the color of the buffer or the color of the string.

Head: `Head_PictureImageDrawStrings` Name: `Head_PictureImageDrawStrings` Description: `Head_PictureImageDrawStrings` Parameters: `Head_PictureImageDrawStrings` (Type: `enum`) `Head_PictureImageDrawStrings` (Type: `enum`) `Head_PictureImageDrawStrings` (Type: `enum`)

- Draw circles: In the image buffer, draw circles or figures. You can choose to use the color of the buffer or the color of the circle.

Head: `Head_PictureImageDrawCircles` Name: `Head_PictureImageDrawCircles` Description: `Head_PictureImageDrawCircles` Parameters: `Head_PictureImageDrawCircles` (Type: `enum`) `Head_PictureImageDrawCircles` (Type: `enum`) `Head_PictureImageDrawCircles` (Type: `enum`)

- Write digital strings: In the image buffer, use `StartWrite` to write the left series, write a group of digital characters on the right side of the buffer, and fill the background color.

Head: `Head_PictureImageWriteDigitalStrings` Name: `Head_PictureImageWriteDigitalStrings` Description: `Head_PictureImageWriteDigitalStrings` Parameters: `Head_PictureImageWriteDigitalStrings` (Type: `enum`) `Head_PictureImageWriteDigitalStrings` (Type: `enum`) `Head_PictureImageWriteDigitalStrings` (Type: `enum`)

- Write digital strings: In the image buffer, use `StartWrite` to write the left series, write a group of digital characters on the right side of the buffer, and fill the background color.

Head: `Head_PictureImageWriteDigitalStrings2` Name: `Head_PictureImageWriteDigitalStrings2` Description: `Head_PictureImageWriteDigitalStrings2` Parameters: `Head_PictureImageWriteDigitalStrings2` (Type: `enum`) `Head_PictureImageWriteDigitalStrings2` (Type: `enum`) `Head_PictureImageWriteDigitalStrings2` (Type: `enum`)

- Write Chinese strings: In the image buffer, use `StartWrite` to write the left series, write a group of Chinese characters on the right side of the buffer, and fill the background color.

Head: `Head_PictureImageWriteChineseStrings` Name: `Head_PictureImageWriteChineseStrings` Description: `Head_PictureImageWriteChineseStrings` Parameters: `Head_PictureImageWriteChineseStrings` (Type: `enum`) `Head_PictureImageWriteChineseStrings` (Type: `enum`) `Head_PictureImageWriteChineseStrings` (Type: `enum`)

- Write Chinese strings: In the image buffer, use `StartWrite` to write the left series, write a group of Chinese characters on the right side of the buffer, and fill the background color.

Head: `Head_PictureImageWriteChineseStrings2` Name: `Head_PictureImageWriteChineseStrings2` Description: `Head_PictureImageWriteChineseStrings2` Parameters: `Head_PictureImageWriteChineseStrings2` (Type: `enum`) `Head_PictureImageWriteChineseStrings2` (Type: `enum`) `Head_PictureImageWriteChineseStrings2` (Type: `enum`)

Arduino software description

Note: The device is not listed in Arduino IDE. If you need other types of Arduino, you need to determine whether the connected pins are correct.

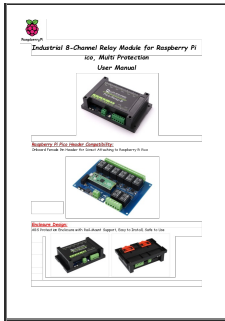
1. Run program
2. The printed output appears in the serial monitor, and then click it. The Arduino program is loaded on the Arduino.

Pin	Function	IO	Power
1	5V		5V
2	GND		GND
3	GND		GND
4	5V		5V
5	GND		GND
6	GND		GND
7	5V		5V
8	GND		GND
9	5V		5V
10	GND		GND
11	5V		5V
12	GND		GND
13	5V		5V
14	GND		GND
15	5V		5V
16	GND		GND
17	5V		5V
18	GND		GND
19	5V		5V
20	GND		GND
21	5V		5V
22	GND		GND
23	5V		5V
24	GND		GND
25	5V		5V
26	GND		GND
27	5V		5V
28	GND		GND
29	5V		5V
30	GND		GND
31	5V		5V
32	GND		GND
33	5V		5V
34	GND		GND
35	5V		5V
36	GND		GND
37	5V		5V
38	GND		GND
39	5V		5V
40	GND		GND
41	5V		5V
42	GND		GND
43	5V		5V
44	GND		GND
45	5V		5V
46	GND		GND
47	5V		5V
48	GND		GND
49	5V		5V
50	GND		GND
51	5V		5V
52	GND		GND
53	5V		5V
54	GND		GND
55	5V		5V
56	GND		GND
57	5V		5V
58	GND		GND
59	5V		5V
60	GND		GND
61	5V		5V
62	GND		GND
63	5V		5V
64	GND		GND

You can view test programs for all smart devices, which is as follows:

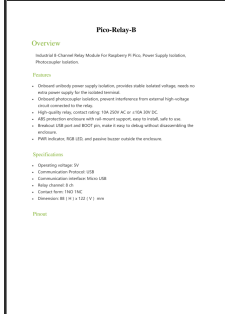
For example, I selected CC-Media. Open the CC_Media.ino file and use the IDE to download it.





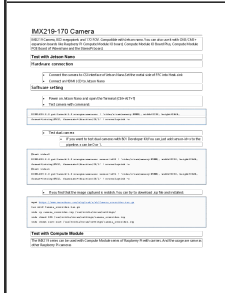
[Waveshare Industrial 8-Channel Relay Module for Raspberry Pi Pico User Manual](#)

User manual for the Waveshare Industrial 8-Channel Relay Module for Raspberry Pi Pico (Pico-Relay-B). Details features, compatibility, enclosure, and pinout for industrial control applications.



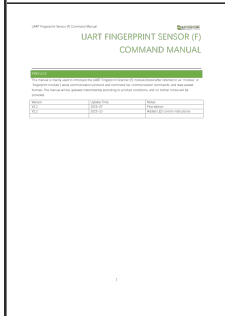
[Pico-Relay-B: 8-Channel Relay Module User Guide](#)

User guide for the Waveshare Pico-Relay-B, an industrial 8-channel relay module for Raspberry Pi Pico. Learn about its features, specifications, setup, and programming with detailed instructions and examples.



[IMX219-170 Camera User Guide for Jetson Nano and Compute Module](#)

A guide to using the IMX219-170 camera with Jetson Nano and Raspberry Pi Compute Modules, including hardware connection, software setup, and troubleshooting.



[WAVESHARE UART Fingerprint Sensor \(F\) Command Manual: Protocol and Command Reference](#)

This manual details the serial communication protocol, command list, and data packet formats for the WAVESHARE UART Fingerprint Sensor (F) module. It serves as a comprehensive guide for developers integrating fingerprint recognition capabilities into their projects.