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## Clementoni MC 4.0

# Clementoni Galileo My Robot MC 4.0 Instruction Manual

## INTRODUCTION

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Welcome to the world of robotics with your new Clementoni Galileo My Robot MC 4.0! This manual provides detailed instructions for assembling, operating, and maintaining your robot. Please read all instructions carefully before beginning assembly or operation to ensure proper function and safety.

## SAFETY INFORMATION

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- This product is intended for users aged 8 years and older. Adult supervision is recommended during assembly and initial operation.
- Keep small parts away from young children to prevent choking hazards.
- Do not expose the robot to water or extreme temperatures.
- Ensure batteries are inserted with correct polarity. Do not mix old and new batteries, or different types of batteries.
- Remove batteries if the robot will not be used for an extended period.
- Do not attempt to modify the robot's electronic components.

## PACKAGE CONTENTS

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Before you begin assembly, verify that all components are present in your kit. Refer to the image below for a visual guide to the parts.



Image: All components of the Clementoni Galileo My Robot MC 4.0 laid out, including the main body, wheels, circuit board, motors, ultrasonic sensor, battery compartment, and various small parts for assembly.

Your kit should include:

- Main robot chassis components
- Wheels and tires
- Electronic circuit board
- Two electric motors
- Ultrasonic sensor
- Battery compartment
- Head and arm components
- Small parts (screws, connectors, etc.)
- Illustrated instruction manual (this document)

## SETUP AND ASSEMBLY

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Follow these steps carefully to assemble your Galileo My Robot MC 4.0. It is recommended to work on a clean, flat surface.

1. **Prepare the Chassis:** Begin by connecting the main chassis parts according to the illustrated diagrams in your physical manual. Ensure all connections are secure.

2. **Install Motors:** Insert the two electric motors into their designated slots within the chassis. Make sure they are firmly seated.
3. **Connect Wiring:** Carefully connect the motor wires to the electronic circuit board. Pay close attention to the polarity and connection points as indicated in the diagrams.
4. **Attach Ultrasonic Sensor:** Mount the ultrasonic sensor to the front of the robot's chassis and connect its wires to the circuit board. This sensor allows the robot to detect obstacles.
5. **Assemble Wheels:** Attach the wheels to the motor shafts. Ensure they spin freely and are securely fastened.
6. **Install Battery Compartment:** Secure the battery compartment to the robot's body. This will house the power source for your robot.
7. **Attach Head and Arms:** Assemble and attach the robot's head and arm components. These are often decorative but can also house additional sensors or functions.



Image: A partially assembled Clementoni Galileo My Robot MC 4.0, viewed from the side, clearly showing the exposed electronic circuit board with buttons and the transparent orange battery compartment attached to the robot's body.

## BATTERY INSTALLATION

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The Clementoni Galileo My Robot MC 4.0 requires 3 AA batteries (not included). To install the batteries:

1. Locate the battery compartment on the robot.
2. Using a small screwdriver, open the battery compartment cover.
3. Insert 3 AA batteries, ensuring the correct polarity (+/-) as indicated inside the compartment.
4. Replace the battery compartment cover and secure it with the screw.

## OPERATING INSTRUCTIONS

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Your Galileo My Robot MC 4.0 offers various interactive functions and programming modes. The robot is controlled via buttons on its circuit board.

## Powering On/Off

Locate the ON/OFF switch on the robot's circuit board. Slide the switch to 'ON' to power up the robot. Slide it to 'OFF' to power down.

## Programming Modes

The robot features several programmable modes, allowing it to perform different actions:

- **Manual Control:** Use the directional buttons on the circuit board to control the robot's movement directly.
- **Obstacle Avoidance Mode:** In this mode, the robot uses its ultrasonic sensor to detect objects in its path and navigate around them.
- **Line Following Mode:** The robot can be programmed to follow a black line on a light surface. (Requires specific setup, refer to physical manual for details).
- **Drawing Mode:** Attach a pen to the robot's arm, and program it to draw patterns or shapes.
- **Object Collection Mode:** The robot can be programmed to approach and pick up small metallic objects using its magnetic arm.



Image: The fully assembled Clementoni Galileo My Robot MC 4.0, a white and orange robot with large wheels, is shown on a white surface. Its magnetic arm is extended downwards, successfully picking up a small silver paperclip.

Refer to the detailed programming sequences in your physical instruction manual for specific button presses and mode activations.

## MAINTENANCE

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Proper care will extend the life of your robot.

- **Cleaning:** Wipe the robot with a dry, soft cloth. Do not use water or cleaning solutions.
- **Storage:** Store the robot in a cool, dry place away from direct sunlight when not in use.
- **Battery Care:** Always remove batteries if the robot will be stored for a long period.
- **Component Check:** Periodically check that all screws and connections are secure.

## TROUBLESHOOTING

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If you encounter issues with your robot, consult this table for common problems and solutions.

Problem	Possible Cause	Solution
Robot does not turn on.	Batteries are dead or incorrectly installed.	Check battery polarity and replace with fresh AA batteries.
Robot moves erratically or not at all.	Loose wiring or motor connection.	Check all wire connections to the circuit board and ensure motors are securely in place.
Obstacle avoidance not working.	Ultrasonic sensor is blocked or disconnected.	Ensure the sensor is clean and clear, and its wires are properly connected.
Robot does not respond to programming.	Incorrect programming sequence or mode selection.	Refer to the physical manual for correct programming steps for each mode. Ensure the robot is in the correct mode.

## SPECIFICATIONS

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Feature	Detail
Model Number	59054
Product Dimensions (L x W x H)	45.1 x 31.1 x 7 cm
Item Weight	1.12 Kilograms
Recommended Age	8 years and up
Educational Value	Learning robotics and engineering interactively and practically
Power Source	3 AA batteries (not included)
Material	Metal and plastic components
Special Features	Interactive functions, programmable, ultrasonic sensor, magnetic arm

## WARRANTY AND SUPPORT

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For warranty information, please refer to the documentation included in your product packaging or visit the official Clementoni website. If you require technical assistance or have questions not covered in this manual, please contact

Clementoni customer support through their official channels.

