

# ams-OSRAM AS5040 10 bit Rotary Position Sensor with Digital Angle Instruction Manual

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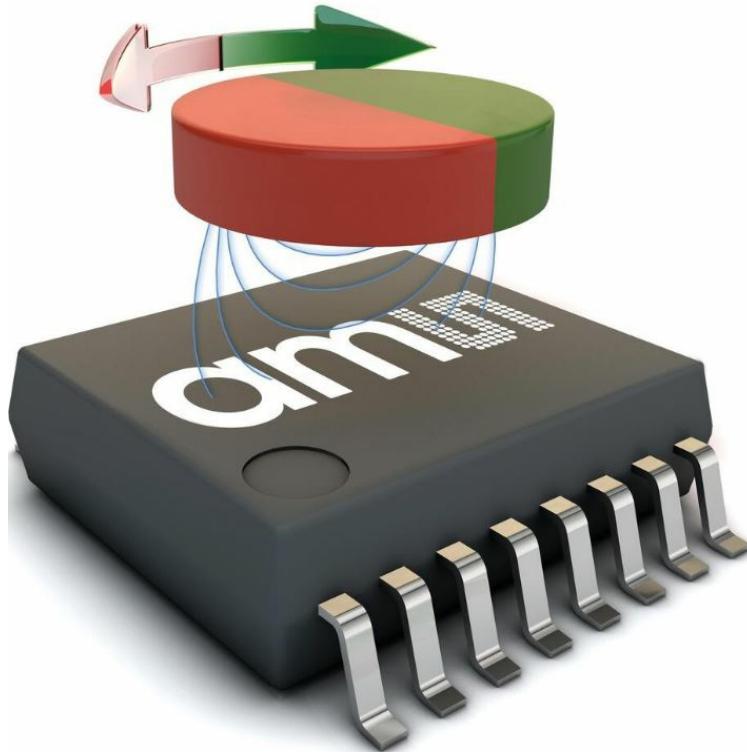


## Contents

- [1 ams-OSRAM AS5040 10-bit Rotary Position Sensor with Digital Angle](#)
- [2 Product Information](#)
- [3 Product Usage Instructions](#)
- [4 Revision History](#)
- [5 Revision History](#)
- [6 General Description](#)
- [7 The AS5040 adapter board](#)
- [8 AS5040 Adapterboard and pinout](#)
- [9 Operation cases](#)
- [10 Programming the AS5040](#)
- [11 AS5040 AB-Hardware](#)
- [12 Disclaimer](#)
- [13 Contact Information](#)
- [14 Documents / Resources](#)
  - [14.1 References](#)
- [15 Related Posts](#)



**ams-OSRAM AS5040 10-bit Rotary Position Sensor with Digital Angle**



## Product Information

- **Product Name:** AS5x40/AS5x45
- **Type:** 10-bit Rotary Position Sensor
- **Features:** Digital Angle (Interface), ABI, UVW and PWM output
- **Manufacturer:** ams OSRAM Group
- **Website:** [www.ams.com](http://www.ams.com)
- **Downloaded from:** [Arrow.com](http://Arrow.com)
- **Revision:** 1.4 / 09.08.2013

## Product Usage Instructions

### General Description

- The AS5x40/AS5x45 is a 10-bit rotary position sensor with digital angle (interface), ABI, UVW, and PWM output.

### The AS5040 adapter board

- The AS5040 adapter board is a simple circuit that allows the test and evaluation of the AS5x40/AS5x45 position sensor without building a test fixture or PCB.

### Board description

- The PCB can be used as a standalone unit or attached to a microcontroller. The standalone operation requires a 5V power supply only. The magnet's angle can be read on the PWM or analog output.
- **Note:** Refer to Figure 2 for a visual representation of the AS5040 adapter board.

## **AS5040 Adapterboard and pinout**

- Refer to the documentation for detailed information on the AS5040 Adapterboard and its pinout.

## **Operation cases**

- The AS5040 sensor can operate in different modes:

### **Standalone SSI output mode**

- In this mode, the AS5040 provides SSI output. Refer to the documentation for instructions on using the AS5040 in standalone SSI output mode.

### **Standalone PWM output mode**

- In this mode, the AS5040 provides PWM output. Refer to the documentation for instructions on using the AS5040 in standalone PWM output mode.

### **Standalone incremental Output**

- In this mode, the AS5040 provides incremental output. Refer to the documentation for instructions on using the AS5040 in standalone incremental output mode.

### **Daisy chain mode**

- In this mode, multiple AS5040 sensors can be connected in a daisy chain configuration. Refer to the documentation for instructions on using the AS5040 in daisy chain mode.

## **Programming the AS5040**

- Refer to the documentation for instructions on programming the AS5040.

## **AS5040 differences from AS5045**

- Refer to the documentation for information on the differences between AS5040 and AS5045.

## **AS5040 AB-Hardware**

- Refer to the documentation for detailed schematics of the AS5040-AB-2.1 hardware.

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## **Disclaimer**

- The information provided in the product document is for reference purposes only. The manufacturer does not guarantee the accuracy or completeness of the information.

## Contact Information

- For further assistance or inquiries, please refer to the contact information provided in the product document.

## Revision History

Revision	Date	Owner	Description
1.0	01.10.2009	azen	Initial revision
1.3	05.07.2013	azen	Updated to new template
1.4	09.08.2013	azen	Minor corrections

**Note:** The above information is based on the product document published by ams OSRAM Group and downloaded from [Arrow.com](http://Arrow.com).

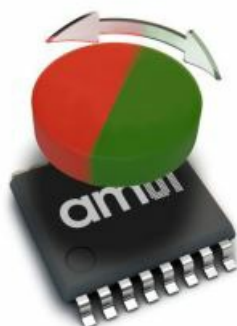
## Revision History

Revision	Date	Owner	Description
1.0	01.10.2009		Initial revision
1.3	05.07.2013	azen	Updated to new template
1.4	09.08.2013	azen	Minor corrections

## General Description

- The AS5x40/AS5x45 series are contactless magnetic position sensors for accurate angular measurement over a full turn of 360°. They are system-on-chip, combining integrated Hall elements, analog front end and digital signal processing in a single device.
- To measure the angle, only a simple two-pole magnet, rotating over the center of the chip, is required. The magnet may be placed above or below the IC. (See Figure 1:)

**Figure 1: Rotary Position Sensor AS5040 + Magnet**



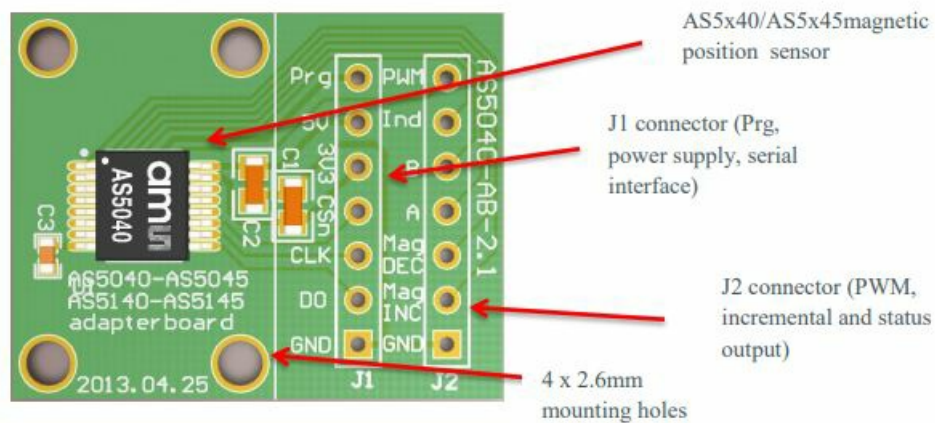
## The AS5040 adapter board

- The AS5040 adapter board is a simple circuit allowing the test and evaluation of the AS5x40/AS5x45 position sensor without building a test fixture or PCB.

### Board description

- The PCB can be used as a standalone unit or attached to a microcontroller. The standalone operation requires a 5V power supply only; the magnet's angle can be read on the PWM or analog output. (See Figure 2:).

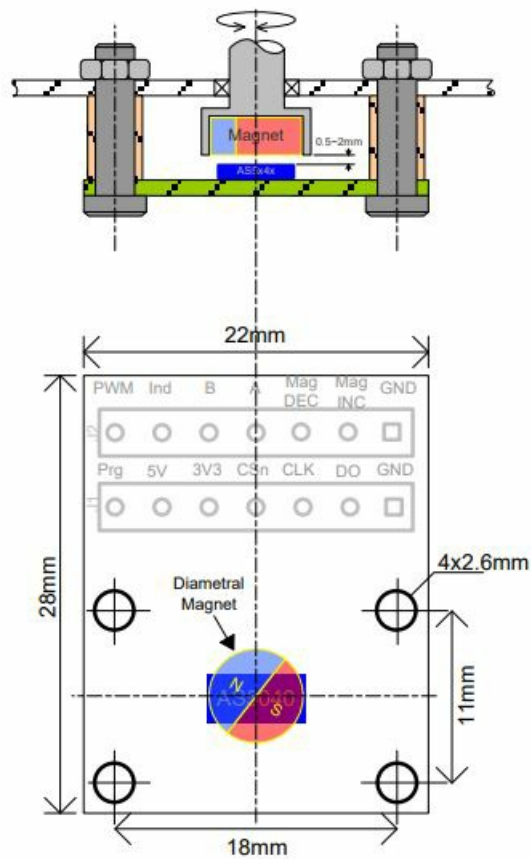
Figure 2:  
AS5040 Adapterboard



### Mounting the AS5040 adapter board

- A diametric magnet must be placed over on under the AS5x40/AS5x45 sensor and should be centered on the middle of the package with a tolerance of 0.5mm.
- The airgap between the magnet and the sensor casing should be maintained in the range 0.5mm~2mm. The magnet holder must not be ferromagnetic. Materials as brass, copper, aluminum, stainless steel are the best choices to make this part. (See Figure 3:)

Figure 3:  
AS5040 adapter board mounting and dimension



## AS5040 Adapterboard and pinout

- The Adapterboard Pinout is shown below.

Figure 4:  
AS5040 adapter board connectors and sensor pinout

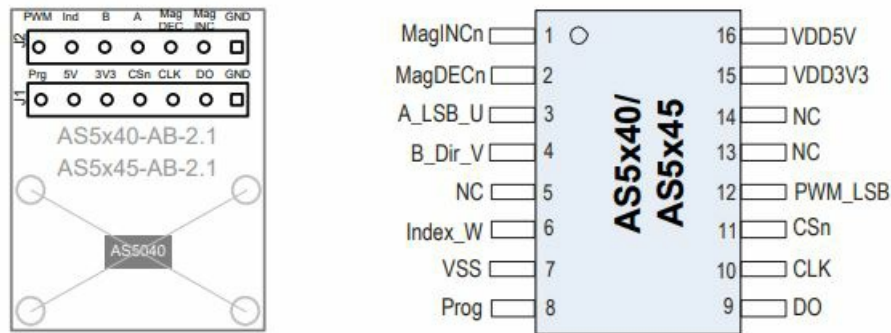


Table 1:  
Pin description

Pin# Board	Pin# AS5x40 AS5x45	Symbol Board	Type	Description
JP1 - 1	7	GND	S	Supply ground
JP1 - 2	9	DO	DO_T	Data Output of Synchronous Serial Interface
JP1 - 3	10	CLK	DI_ST	Clock Input of Synchronous Serial Interface; Schmitt-Trigger input
JP1 - 4	11	CSn	DI_PU_ST	Chip Select, active low; Schmitt-Trigger input, internal pull-up resistor (~50kΩ) connect to VSS in incremental mode
JP1 - 5	15	3V3	S	3V-Regulator Output
JP1 - 6	16	5V	S	5V Supply
JP1 - 7	8	Prg	DI_PD	OTP Programming Input and Data Input for Daisy Chain mode. Internal pull-down resistor (~74kΩ). May be connected to VSS if programming is not used
JP2 - 1	7	GND	S	Supply ground
JP2 - 2	1	MagINC	DO_OD	Magnet Field <b>M</b> agnitude <b>I</b> Ncrease; active low, indicates a distance reduction between the magnet and the device surface.
JP2 - 3	2	MagDEC	DO_OD	Magnet Field <b>M</b> agnitude <b>D</b> Ecrease; active low, indicates a distance increase between the device and the magnet
JP2 - 4	3	A	DO	AS5040 – AS5140 – AS5145 (programmed) only Mode1.x: Quadrature <b>A</b> channel Mode2.x: Least Significant Bit
Mode3.x: U signal (phase1)				
JP2 - 5	4	B	DO	AS5040 – AS5140 – AS5145 (programmed) only Mode1.x: Quadrature <b>B</b> channel quarter period shift to channel A. Mode2.x: Direction of Rotation Mode3.x: V signal (phase2)
JP2 - 6	6	Ind	DO	AS5040 – AS5140 – AS5145 (programmed) only Mode1.x and Mode2.x : <b>I</b> ndex signal indicates the absolute zero position Mode3.x: W signal (phase3) AS5045 – AS5145 (unprogrammed) Mode input, connect to VDD5 (Fast mode) or GND (Slow mode); do not change during operation
JP2 - 7	12	PWM	DO	Pulse Width Modulation of approx. 1kHz; <b>L</b> SB in Mode3.x

Pin types:	DO_OD	digital output open drain	S	supply pin
	DI_PD	digital input pull-down	DO_T	digital output /tri-state
	DI_PU	digital input pull-up	ST	schmitt-trigger input
	DI	digital input	DO	digital output

## Operation cases

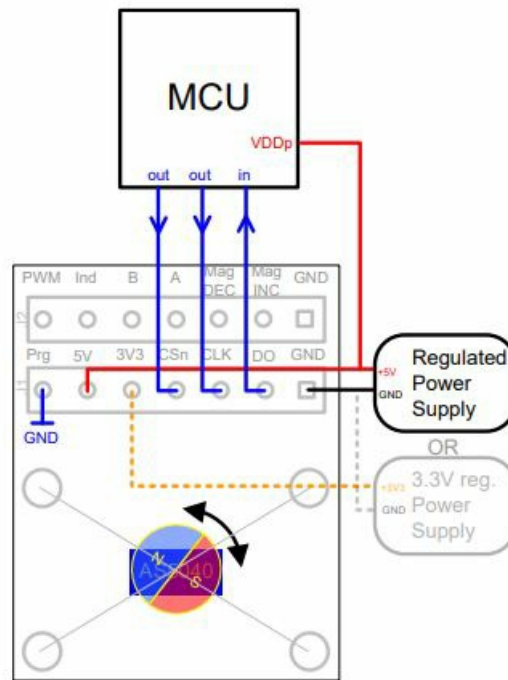
The most complete and accurate solution for a MCU to read the angle of a magnet is the serial interface.

### Standalone SSI output mode

The serial word contains 16 bits for AS5x40 or 18 bits for AS5x45 and consists of 10 bit (AS5x40) or 12 bit

(AS5x45) angle value and some other indicator bits like MagINC, MagDEC, which can be read at the same time.

Figure 5:  
Using the analog output with the adapter board



### Standalone PWM output mode

The AS5040 provides a pulse width modulated output (PWM), whose duty cycle is proportional to the measured angle.

The PWM signal (J2 pin #7) with a period of 1025us (1us step) and 5V pulse voltage can be connected to the capture/timer input of a microcontroller in order to decode the angle value.

Figure 6:  
Using the PWM output with the adapter board

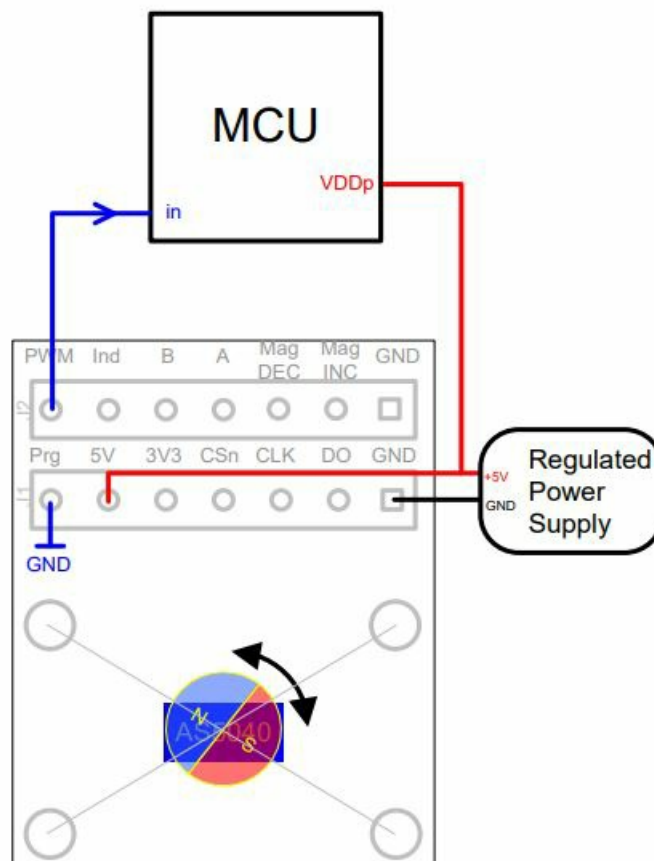
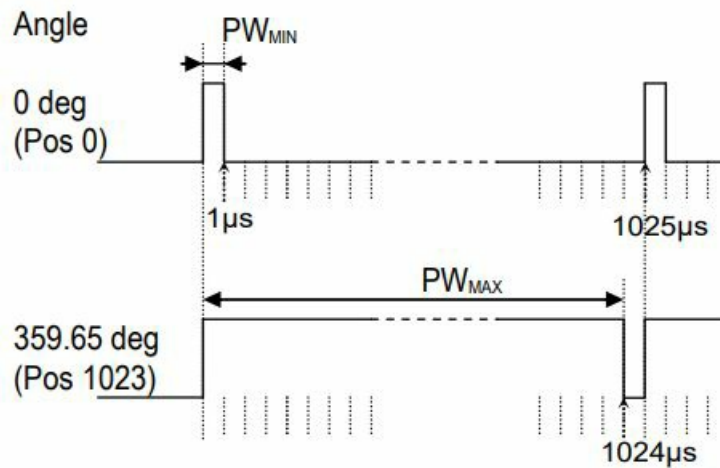




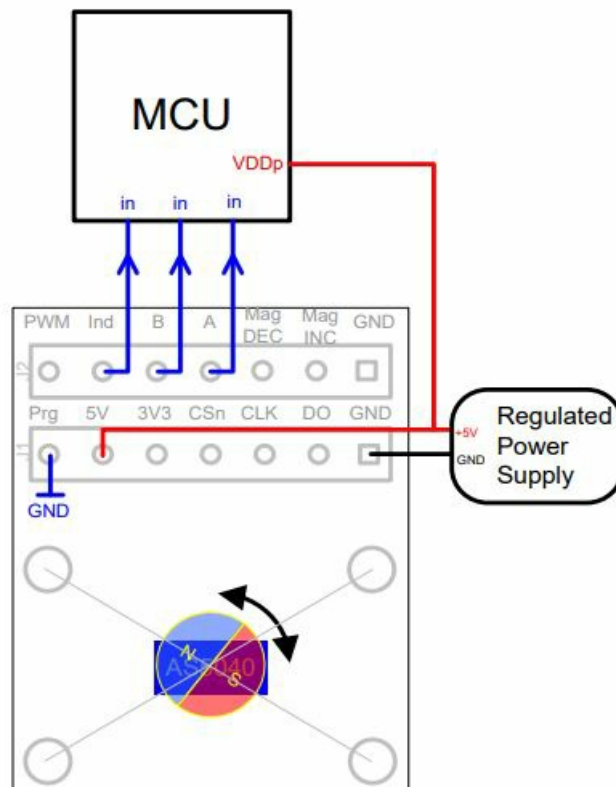
Figure 7:  
PWM duty cycle depending on magnet position



### Standalone incremental Output

- Three different incremental output modes are possible with quadrature A/B being the default mode (two-channel quadrature, step / direction incremental signal (LSB) and the direction bit in clockwise (CW) and counter-clockwise (CCW) direction.
- The pre-programmed version AS5145-I10 provides a 10bit and AS5145-I12 a 12bit incremental output.
- The AS5045 doesn't provide an incremental output.
- For further information, please refer to the datasheet.

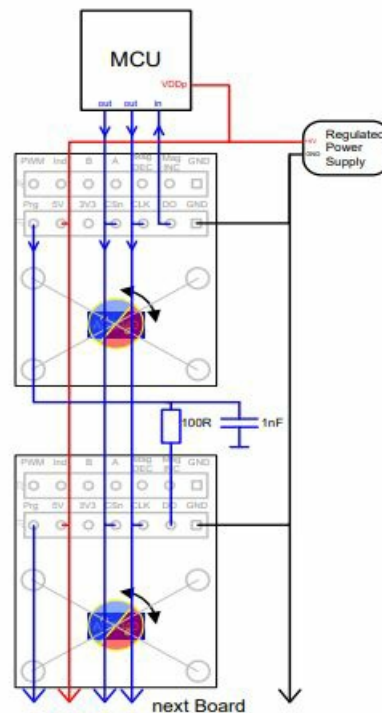
Figure 8:  
Using the Incremental output with the adapter board



### Daisy chain mode

- By using more than one adapter board, a setup in daisy chain mode is possible.
- **Note:** In this mode capacitor C3 (refer to Fig.12) must be disconnected when using the 1nF capacitor shown in Fig.9 or directly replaced by this capacitor.
- The serial data of all connected devices is read from the DO pin of the first device in the chain. The Prog pin of the last device in the chain should be connected to VSS. The length of the serial bit stream increases with every connected device (board) by  $n * (16+1)$  bits.
- Due to  $R = 100\Omega$  and  $C = 1\text{nF}$ , the CLK is limited the maximum 1MHz.

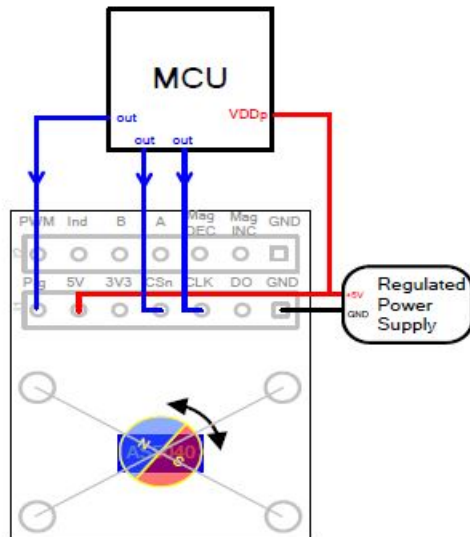
Figure 9:  
Using Daisy-Chain mode with the adapter board



## Programming the AS5040

- After power-on, programming the AS5040 is enabled with the rising edge of CSn with Prog = high and CLK = low. 16 bit configuration data must be serially shifted into the OTP register via the Prog-pin. The first “CCW” bit is followed by the zero position data (MSB first / 10 bit for AS5x40 and 12 bit for AS5x45) and some mode settings (please refer to datasheet). Data must be valid at the rising edge of CLK.
- After writing data into the OTP register it can be permanently programmed by rising the Prog pin to the programming voltage VPROG of 7.3-7.5V. 16 CLK pulses must be applied to program the fuses.
- For exiting the programming mode, the chip must be reset by a power-on-reset. The programmed data is available after the next power-up.

Figure 10:  
Programming the AS5040



## AS5040 differences from AS5045

The Table below shows the differences between AS5040 and AS5045

**Table 2: Differences AS5040/ AS5045**

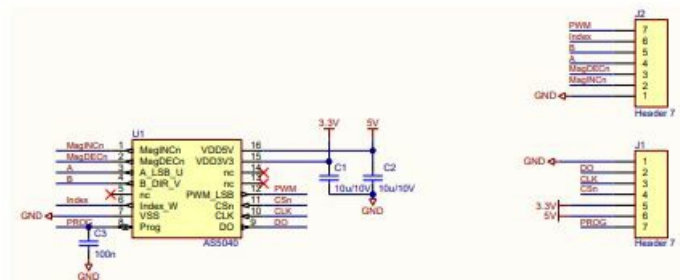
Building Block	AS5045	AS5040
Resolution	12bits, 0.088°/step.	10bit, 0.35°/step
Data length	read: 18bits	read: 16bits
	(12bits data + 6 bits status)	(10bits data + 6 bits status)
	OTP write: 18 bits	OTP write: 16 bits
	(12bits zero position + 6 bits mode	(10bits zero position + 6 bits mode
	selection)	selection)
incremental	Not used	quadrature, step/direction and BLDC
encoder	Pin 3: not used	motor commutation modes
	Pin 4: not used	Pin 3: incremental output A_LSB_U
		Pin 4: incremental output B_DIR_V
Pins 1 and 2	MagINCn, MagDECn: same feature as	MagINCn, MagDECn indicate in-range
	AS5040, additional OTP option for red-	or out-of-range magnetic field plus
	yellow-green magnetic range	movement of magnet in z-axis
Pin 6	MODE pin, switch between fast and	Pin 6: Index output
	slow mode	
Pin 12	PWM output: frequency selectable by	PWM output:
	OTP:	1µs / step, 1024 steps per revolution,
	1µs / step, 4096 steps per revolution,	976Hz PWM frequency
	f=244Hz 2µs/ step, 4096 steps per	
	revolution, f=122Hz	
sampling	selectable by MODE input pin:	fixed at 10kHz @10bit resolution
frequency	2.5kHz, 10kHz	
Propagation	384µs (slow mode)	48µs
delay	96µs (fast mode)	
Transition noise	0.03 degrees max. (slow mode)	0.12 degrees
(rms; 1sigma)	0.06 degrees max. (fast mode)	
OTP	zero position, rotational direction,	zero position, rotational direction,
programming	PWM disable, 2 Magnetic Field	incremental modes, index bit width
options	indicator modes, 2 PWM frequencies	

## AS5040 AB-Hardware

Below the schematic and layout can be found.

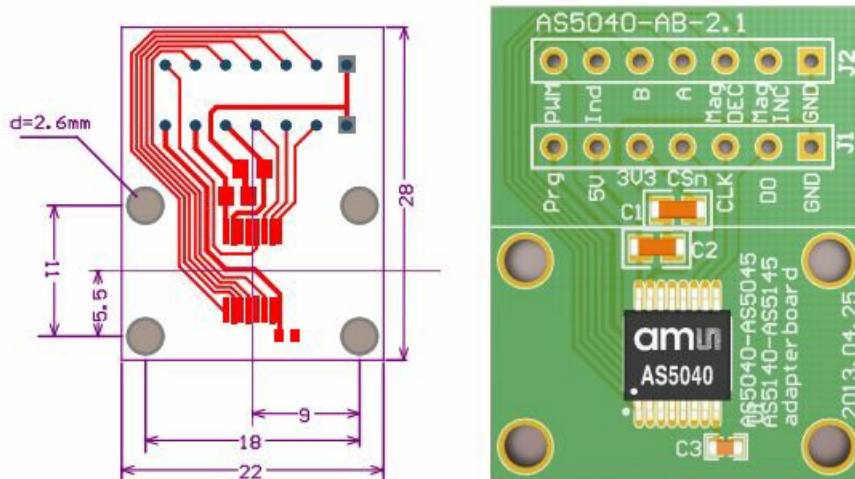
### AS5040-AB-2.1 schematics

Figure 11:  
AS5040-AB-2.1-Schematics



## AS5040 – AB – 2.1 PCB layout

Figure 12:  
AS5040-AB-2.1-Layout



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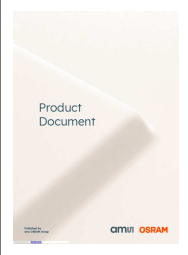
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## Documents / Resources

	<p><a href="#">ams-OSRAM AS5040 10 bit Rotary Position Sensor with Digital Angle</a> [pdf] Instruction Manual</p> <p>AS5040 10 bit Rotary Position Sensor with Digital Angle, AS5040 10 bit Rotary Position Sensor with Digital Angle, Rotary Position Sensor with Digital Angle, Sensor with Digital Angle, Digital Angle</p>
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## References

- [Sensor Solutions | ams](#)
- [Contact us | ams OSRAM](#)