

ALTERA Cyclone V SoC Development Kit User Guide

[Home](#) » [ALTERA](#) » ALTERA Cyclone V SoC Development Kit User Guide 



**Cyclone V SoC Development Kit
Reference Platform Porting Guide**

Contents

- [1 Cyclone V SoC Development Kit](#)
- [2 Overview of the Cyclone V SoC Development Kit Reference Platform](#)
- [3 Porting the Reference Platform to Your SoC Board](#)
- [4 Software Support for Shared Memory](#)
- [5 FPGA Reconfiguration](#)
- [6 Building an SD Flash Card Image](#)
- [7 Known Issues](#)
- [8 Document Revision History](#)
- [9 Documents / Resources](#)
 - [9.1 References](#)
- [10 Related Posts](#)

Cyclone V SoC Development Kit

The Altera Cyclone V SoC Development Kit Reference Platform Porting Guide describes the hardware and software design of the Altera® Cyclone® V SoC Development Kit Reference Platform (c5soc) for use with the Altera Software Development Kit (SDK) for OpenCL™ (1) (AOCL) (2).

Before you begin, Altera strongly recommends that you familiarize yourself with the contents of the following documents:

1. Altera SDK for OpenCL Cyclone V SoC Getting Started Guide
2. Altera SDK for OpenCL Custom Platform Toolkit User Guide

3. Cyclone V Device Handbook, Volume 3: Hard Processor System Technical Reference Manual

In addition, refer to the Cyclone V SoC Development Kit and SoC Embedded Design Suite page of the Altera website for more information.

Attention: Altera assumes that you have an in-depth understanding of the Altera SDK for OpenCL Custom Platform Toolkit User Guide. The Altera Cyclone V SoC Development Kit Reference Platform Porting Guide does not describe the usage of the AOCL Custom Platform Toolkit to implement a Custom Platform for the Cyclone V SoC Development Kit. It only describes the differences between the AOCL support on the Cyclone V SoC Development Kit and a generic AOCL Custom Platform.

Related Information

- [PSG Documentation \(altera.com\)](#)
- [PSG Documentation \(altera.com\)](#)
- [PSG Documentation \(altera.com\)](#)
- [Cyclone® V SX SoC Development Kits \(intel.com\)](#)

Overview of the Cyclone V SoC Development Kit Reference Platform

The Cyclone V SoC Development Kit Reference Platform is available with the Altera SDK for OpenCL.

1. OpenCL and the OpenCL logo are trademarks Apple Inc. used by permission of the Khronos Group™.
2. The Altera SDK for OpenCL is based on a published Khronos Specification, and has passed the Khronos Conformance Testing Process. Current conformance status can be found at www.khronos.org/conformance.

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AOCL support for the Cyclone V SoC Development Kit takes advantage of the following board features to maximize the performance of the Cyclone V SoC:

1. FPGA device that contains the FPGA core logic.
2. Hard processor system (HPS) with dual core ARM® Cortex® -A9 CPU.
3. Shared physical memory between the CPU and the FPGA core fabric.

Cyclone V SoC Development Kit Reference Platform Board Variants

The Altera SDK for OpenCL Cyclone V SoC Development Kit Reference Platform includes two board variants.

- c5soc board

This default board provides access to two DDR memory banks. The HPS DDR is accessible by both the FPGA and the CPU. The FPGA DDR is only accessible by the FPGA.

- c5soc_sharedonly board

This board variant contains only HPS DDR connectivity. The FPGA DDR is not accessible. This board variant

is more area efficient because less hardware is necessary to support one DDR memory bank. The c5soc_sharedonly board is also a good prototyping platform for a final production board with a single DDR memory bank.

To target this board variant when compiling your OpenCL kernel, include the `–board c5soc_sharedonly` option in your aoc command.

For more information on the `–board <board_name>` option of the aoc command, refer to the Altera SDK for OpenCL Programming Guide.

Related Information

Compiling a Kernel for a Specific FPGA Board (`–board <board_name>`)

Content of the Cyclone V SoC Development Kit Reference Platform

The Cyclone V SoC Development Kit Reference Platform consists of the following files and directories:

File or Directory	Description
board_env.xml	eXtensible Markup Language (XML) file that describes c5soc to the Altera SDK for OpenCL.
linux_sd_card_image.tgz	Compressed SD flash card image file that contains everything an AOCL user needs to use the Cyclone V SoC Development Kit with the AOCL.
arm32	Directory that contains the following: 1. A bin subdirectory containing AOCL utilities that are specific to the Cyclone V SoC Development Kit (that is program and diagnose). 2. A lib subdirectory containing the memory-mapped device (MMD) library that is pre compiled to 32-bit Linux on ARM Cortex-A9 environment.
c5soc	Directory that contains the hardware template for the board variant that includes two DDR SDRAM.
c5soc_sharedonly	Directory that contains the hardware template for the board variant that includes one DDR SDRAM.
driver	Directory that contains the source codes for the Linux kernel driver, and the program and diagnose utilities.

Relevant Features of the Cyclone V SoC Development Kit

The following list highlights the Cyclone V SoC Development Kit components and features that are relevant to the Altera SDK for OpenCL:

- Dual-core ARM Cortex-A9 CPU running 32-bit Linux.
- Advanced eXtensible Interface (AXI) bus between the HPS and the FPGA core fabric.
- Two hardened DDR memory controllers, each connecting to a 1 gigabyte (GB) DDR3 SDRAM.
 - One DDR controller is accessible to the FPGA core only (that is, FPGA DDR).
 - The other DDR controller is accessible to both the HPS and the FPGA (that is, HPS DDR). This shared controller allows free memory sharing between the CPU and the FPGA core.
- The CPU can reconfigure the FPGA core fabric.

Cyclone V SoC Development Kit Reference Platform Design Goals and Decisions

Altera bases the implementation of the Cyclone V SoC Development Kit Reference Platform on several design goals and decisions. Altera recommends that you consider these goals and decisions when you port this Reference Platform to your SoC board.

Below are the c5soc design goals:

1. Provide the highest possible bandwidth between kernels on the FPGA and the DDR memory system(s).
2. Ensure that computations on the FPGA (that is, OpenCL kernels) do not interfere with other CPU tasks that might include servicing peripherals.
3. Leave as much FPGA resources as possible for kernel computations instead of interface components.

Below are the high-level design decisions that are the direct consequences of Altera's design goals:

1. The Reference Platform only uses hard DDR memory controllers with the widest-possible configuration (256 bits).
2. The FPGA communicates with the HPS DDR memory controller directly, without involving the AXI bus and the L3 switch inside the HPS. The direct communication provides the best possible bandwidth to DDR, and keeps FPGA computations from interfering with communications between the CPU and its periphery.
3. Scatter-gather direct memory access (SG-DMA) is not part of the FPGA interface logic. Instead of transferring large amounts of data between DDR memory systems, store the data in the shared HPS DDR. Direct access to CPU memory by the FPGA is more efficient than DMA. It saves hardware resources (that is, FPGA area) and simplifies the Linux kernel driver.

Warning: Memory transfer between the shared HPS DDR system and the DDR system that is accessible only to the FPGA is very slow. If you choose to transfer memory in this manner, use it for very small amounts of data only.

4. The host and the device perform non-DMA data transfer between each other via the HPS-to-FPGA (H2F) bridge, using only a single 32-bit port. The reason is, without DMA, the Linux kernel can only issue a single 32-bit read or write request, so it is unnecessary to have a wider connection.
5. The host sends control signals to the device via a lightweight H2F (LH2F) bridge. Because control signals from the host to the device are low-bandwidth signals, an LH2F bridge is ideal for the task.

Porting the Reference Platform to Your SoC Board

To port the Cyclone V SoC Development Kit Reference Platform to your SoC board, perform the following tasks:

1. Select the one DDR memory or the two DDR memories version of the c5soc Reference Platform as the starting point of your design.
2. Update the pin locations in the ALTERAOCLSDKROOT/board/c5soc/<board_variant>/top.qsf file, where ALTERAOCLSDKROOT is the path to the location of the Altera SDK for OpenCL installation, and <board_variant> is the directory name of the board variant. The c5soc_sharedonly directory is for the board variant with one DDR memory system. The c5soc directory is for the board variant with two DDR memory systems.
3. Update the DDR settings for the HPS and/or FPGA SDRAM blocks in the ALTERAOCLSDKROOT/board/c5soc/<board_variant>/system.qsys file.
4. All Altera preferred board designs must achieve guaranteed timing closure. As such, the placement of the design must be timing clean. To port the c5soc board partition (acl_iface_partition.qxp) to your SoC board, perform the following tasks:

For detailed instructions on modifying and preserving the board partition, refer to the Quartus Prime Incremental Compilation for Hierarchical and Team-Based Design chapter of the Quartus Prime Standard

Edition Handbook.

- a. Remove the `acl_iface_partition.qxp` from the `ALTERAOCLSDKROOT/board/c5soc/c5soc` directory.
- b. Enable the `acl_iface_region` LogicLock® region by changing the Tcl command `set_global_assignment -name LL_ENABLED OFF -section_id acl_iface_region™` to `set_global_assignment -name LL_ENABLED ON -section_id acl_iface_region`
- c. Compile an OpenCL kernel for your board.
- d. If necessary, adjust the size and location of the LogicLock region.
- e. When you are satisfied that the placement of your design is timing clean, export that partition as the `acl_iface_partition.qxp` Quartus Prime Exported Partition File.

As described in the Establishing Guaranteed Timing Flow section of the Altera SDK for OpenCL Custom Platform Toolkit User Guide, by importing this .qxp file into the top-level design, you fulfill the requirement of providing a board design with a guaranteed timing closure flow.

For factors that might impact the quality of results (QoR) of your exported partition, refer to the General Quality of Results Considerations for the Exported Board Partition section in the Altera SDK for OpenCL Custom Platform Toolkit User Guide.

- f. Disable the `acl_iface_region` LogicLock region by reverting the command in Step 2 back to `set_global_assignment -name LL_ENABLED OFF -section_id acl_iface_region`.
5. If your SoC board uses different pins and peripherals of the HPS block, regenerate the preloader and the device tree source (DTS) file. If you change the HPS DDR memory controller settings, regenerate the preloader.
 6. Create the SD flash card image.
 7. Create your Custom Platform, which includes the SD flash card image.

Consider creating a runtime environment version of your Custom Platform for use with the Altera Runtime Environment (RTE) for OpenCL. The RTE version of your Custom Platform does not include hardware directories and the SD flash card image. This Custom Platform loads onto the SoC system to allow host applications to run. In contrast, the AOCL version of the Custom Platform is necessary for the AOCL to compile OpenCL kernels.

Tip: You may use the AOCL version of your Custom Platform for the Altera RTE for OpenCL. To save space, remove the SD flash card image from the RTE version of your Custom Platform.

8. Test your Custom Platform.

Refer to the Testing the Hardware Design section of the Altera SDK for OpenCL Custom Platform Toolkit User Guide for more information.

Related Information

- [1.4.6. Testing the Hardware Design \(intel.com\)](#)
- [Intel® Quartus® Prime Software User Guides](#)
- [1.4.1.2. Establishing Guaranteed Timing Flow \(intel.com\)](#)
- [1.4.1.1.1. General Quality of Results Considerations for the Exported... \(intel.com\)](#)

Updating a Ported Reference Platform

In the current version of the Cyclone V SoC Development Kit Reference Platform, the HPS block is inside the partition that defines all nonkernel logic. However, you cannot export the HPS as part of the .qxp file. To update an existing Custom Platform that you modified from a previous version of c5soc, implement the QXP preservation flow, update the SD flash card image to obtain the latest runtime environment, and update the `board_spec.xml` file

to enable automigration.

The Altera SDK for OpenCL version 14.1 and beyond probes the board_spec.xml file for board information, and implements automatic updates. Because you modify the design by implementing the QXP preservation flow, you must update the board_spec.xml file to its format in the current version. Updating the file allows the AOCL to distinguish between unpreserved Custom Platforms and the current QXP-based Custom Platforms. Refer to Custom Platform Automigration for Forward Compatibility in the Altera SDK for OpenCL Custom Platform Toolkit User Guide for more information.

1. To implement the QXP preservation flow in a Cyclone V SoC hardware design that is ported from a previous version of c5soc, perform the following steps to create a subpartition to exclude the HPS from the .qxp file:
 - a. Before creating a partition around the nonkernel logic, create a partition around the HPS in the .qsf Quartus Prime Settings File.

For example:

Manually partition the instance that models the HPS-dedicated I/O

```
set_instance_assignment -name PARTITION_HIERARCHY borde_18261 -to
```

```
"system:the_system|system_acl_iface:acl_iface|system_acl_iface_hps_0:hps_0|
```

```
system_acl_iface_hps_0_hps_io:hps_io|
```

```
system_acl_iface_hps_0_hps_io_border:border" -section_id
```

```
"system_acl_iface_hps_0_hps_io_border:border"
```

Set partition to be an HPS_PARTITION type to be processed correctly by the rest of Quartus

```
set_global_assignment -name PARTITION_TYPE HPS_PARTITION -section_id
```

```
"system_acl_iface_hps_0_hps_io_border:border"
```

Modify the setting accordingly because your design hierarchy might be different from the example.

- b. When exporting the partition for acl_iface_partition, include the `–incremental_compilation_export_flatten=off` option to leave the HPS partition as a blackbox.

```
quartus_cdb top -c top
```

```
–incremental_compilation_export=acl_iface_partition.qxp
```

```
–incremental_compilation_export_partition_name=acl_iface_partition
```

```
–incremental_compilation_export_post_synth=on
```

```
–incremental_compilation_export_post_fit=on
```

```
–incremental_compilation_export_routing=on
```

```
–incremental_compilation_export_flatten=off
```

After you exclude the HPS from the partition, you may import the .qxp file and compile your design.

2. Update the SD flash card image with the current version of the Altera RTE for OpenCL by performing the following tasks:
 - a. Mount the file allocation table (fat32) and extended file system (ext3) partitions in the existing image as loop-back devices. For detailed instructions, refer to Step 2 in Building an SD Flash Card Image.
 - b. In the /home/root/opencl_arm32_rte directory, remove the files from the previous version of the RTE.
 - c. Download and unpack the current version of the RTE into the /home/root/opencl_arm32_rte directory.
 - d. In the <path_Custom_Platform>/driver/version.h file of your Custom Platform, update the ACL_DRIVER_VERSION assignment to <AOCL_version>.<driver_version> (for example, 15.1.x, where 15.1 is the AOCL version, and x is the driver version that you set).
 - e. Rebuild the driver.
 - f. Delete the hardware folder(s) of your Custom Platform. Copy the Custom Platform, along with the updated driver, to the /home/root/opencl_arm_rte/board directory.

- g. Copy the Altera.icd file from the /home/root/opencl_arm32_rte directory and add it to the /etc/OpenCL/vendors directory.
- h. Unmount and test the new image. For detailed instructions, refer to Steps 8 to 11 in Building an SD Flash Card Image.

Related Information

- Building an SD Flash Card Image on page 1-10
- [1.3. Custom Platform Automigration for Forward Compatibility \(intel.com\)](#)

Software Support for Shared Memory

Shared physical memory between FPGA and CPU is the preferred memory for OpenCL kernels running on SoCs. Because the FPGA accesses shared physical memory, as opposed to shared virtual memory, it does not have access to the CPU's page tables that map user virtual addresses to physical page addresses.

With respect to the hardware, OpenCL kernels access shared physical memory through direct connection to the HPS DDR hard memory controller. With respect to the software, support for shared physical memory involves the following considerations:

1. Typical software implementations for allocating memory on the CPU (for example, the malloc() function) cannot allocate a memory region that the FPGA may use. Memory that the malloc() function allocates is contiguous in the virtual memory address space, but any underlying physical pages are unlikely to be contiguous physically. As such, the host must be able to allocate physically contiguous memory regions. However, this ability does not exist in user-space applications on Linux.

Therefore, the Linux kernel driver must perform the allocation.

2. The OpenCL SoC Linux kernel driver includes the mmap() function to allocate shared physical memory and map it into the user space. The mmap() function uses the standard Linux kernel call dma_alloc_coherent() to request physically-contiguous memory regions for sharing with a device.
3. In the default Linux kernel, dma_alloc_coherent() does not allocate physically-contiguous memory more than 0.5 megabytes (MB) in size. To allow dma_alloc_coherent() to allocate large amounts of physically-contiguous memory, enable the contiguous memory allocator (CMA) feature of the Linux kernel and then recompile the Linux kernel.

For the Cyclone V SoC Development Kit Reference Platform, CMA manages 512 MB out of 1 GB of physical memory. You may increase or decrease this value, depending on the amount of shared memory that the application requires. The dma_alloc_coherent() call might not be able to allocate the full 512 MB of physically-contiguous memory; however, it can routinely obtain approximately 450 MB of memory.

4. The CPU can cache memory that the dma_alloc_coherent() call allocates. In particular, write operations from the host application are not visible to the OpenCL kernels. The mmap() function in the OpenCL SoC Linux kernel driver also contains calls to the pgprot_noncached() or remap_pfn_range() function to disable caching for this region of memory explicitly.
5. After the dma_alloc_coherent() function allocates the physically-contiguous memory, the mmap() function returns the virtual address to the beginning of the range, which is the address span of the memory you allocate. The host application requires this virtual address to access the memory. On the other hand, the OpenCL kernels require physical addresses. The Linux kernel driver keeps track of the virtual-to-physical address mapping. You can map the physical addresses that mmap() returns to actual physical addresses by

adding a query to the driver.

The `aocl_mmd_shared_mem_alloc()` MMD application programming interface (API) call incorporates the following queries:

- a. The `mmap()` function that allocates memory and returns the virtual address.
- b. The extra query that maps the returned virtual address to physical address.

The `aocl_mmd_shared_mem_alloc()` MMD API call then returns two addresses—the actual returned address is the virtual address, and the physical address goes to `device_ptr_out`.

Note: The driver can only map the virtual addresses that the `mmap()` function returns to physical addresses. If you request for the physical address of any other virtual pointer, the driver returns a NULL value.

Warning: The Altera SDK for OpenCL runtime libraries assume that the shared memory is the first memory listed in the `board_spec.xml` file. In other words, the physical address that the Linux kernel driver obtains becomes the Avalon® address that the OpenCL kernel passes to the HPS SDRAM.

With respect to the runtime library, use the `clCreateBuffer()` call to allocate the shared memory as a device buffer in the following manner:

- For the two-DDR board variant with both shared and nonshared memory, `clCreateBuffer()` allocates shared memory if you specify the `CL_MEM_USE_HOST_PTR` flag. Using other flags causes `clCreateBuffer()` to allocate buffer in the nonshared memory.
- For the one-DDR board variant with only shared memory, `clCreateBuffer()` allocates shared memory regardless of which flag you specify.

Currently, 32-bit Linux support on ARM CPU governs the extent of shared memory support in the AOCL runtime libraries. In other words, runtime libraries compiled to other environments (for example, x86_64 Linux or 64-bit Windows) do not support shared memory.

C5soc did not implement heterogeneous memory to distinguish between shared and nonshared memory for the following reasons:

1. History—Heterogeneous memory support was not available when shared memory support was originally created.
2. Uniform interface—Because OpenCL is an open standard, Altera must maintain consistency between heterogeneous computing platform vendors. Therefore, Altera used the same interface as other board vendors' architectures to allocate and use shared memory.

FPGA Reconfiguration

For Altera SoCs, the CPU can reconfigure the FPGA core fabric without interrupting the CPU's operation. The FPGA Manager hardware block that straddles the HPS and the core FPGA performs the reconfiguration. The Linux kernel includes a driver that enables easy access to the FPGA Manager.

- To view the status of the FPGA core, invoke the `cat /sys/class/fpga/fpga0/status` command.

The Altera SDK for OpenCL program utility available with the Cyclone V SoC Development Kit Reference Platform uses this interface to program the FPGA. When reprogramming an FPGA core with a running CPU, the program utility performs all of the following tasks:

1. Prior to reprogramming, disable all communication bridges between the FPGA and the HPS, both H2F and LH2F bridges.

Reenable these bridges after reprogramming completes.

Attention: The OpenCL system does not use the FPGA-to-HPS (F2H) bridge. Refer to the HPS-FPGA Interfaces section in the Cyclone V Device Handbook, Volume 3: Hard Processor System Technical Reference Manual for more information.

2. Ensure that the link between the FPGA and the HPS DDR controller is disabled during reprogramming.
3. Ensure that the FPGA interrupts on the FPGA are disabled during reprogramming. Also, notify the driver to reject any interrupts from the FPGA during reprogramming.

Consult the source code of the program utility for details on the actual implementation.

Warning: Do not change the configuration of the HPS DDR controller when the CPU is running. Doing so might cause a fatal system error because you might change the DDR controller configuration when there are outstanding memory transactions from the CPU. This means that when the CPU is running, you may not reprogram the FPGA core with an image that uses HPS DDR in a different configuration.

Remember that the OpenCL system, and the Golden Hardware reference design available with the SoC Embedded Design Suite (EDS), sets the HPS DDR into a single 256-bit mode.

CPU system parts such as the branch predictor or the page table prefetcher might issue DDR commands even when it appears that nothing is running on the CPU. Therefore, boot time is the only safe time to set the HPS DDR controller configuration. This also implies that U-boot must have a raw binary file (.rbf) image to load into memory. Otherwise, you might be enabling the HPS DDR with unused ports on the FPGA and then potentially changing the port configurations afterwards. For this reason, the OpenCL Linux kernel driver no longer includes the logic necessary to set the HPS DDR controller configuration.

The SW3 dual in-line package (DIP) switches on the Cyclone V SoC Development Kit control the expected form of the .rbf image (that is, whether the file is compressed and/or encrypted). C5soc, and the Golden Hardware Reference Design available with the SoC EDS, include compressed but unencrypted .rbf images. The SW3 DIP switch settings described in the Altera SDK for OpenCL Cyclone V SoC Getting Started Guide match this .rbf image configuration.

Related Information

- [1. Cyclone® V Hard Processor System Technical Reference Manual... \(intel.com\)](#)
- [2.7.2. Configuring the SW3 Switches \(intel.com\)](#)

FPGA System Architecture Details

Support for the Cyclone V SoC Development Kit Reference Platform is based on the Stratix® V Reference Platform (s5_ref), available with the Altera SDK for OpenCL. The overall organization of the c5soc Qsys system and the kernel driver are very similar to those in s5_ref.

The following FPGA core components are the same in both c5soc and s5_ref:

- VERSION_ID block
- Rest mechanism
- Memory bank divider
- Cache snoop interface
- Kernel clock
- Control register access (CRA) blocks

Building an SD Flash Card Image

Because the Altera Cyclone V SoC is a full system on a chip, you are responsible for delivering the full definition of the system. Altera recommends that you deliver it in the form of an SD flash card image. The Altera SDK for OpenCL user can simply write the image to the micro SD flash card and the SoC board is ready for use.

You may build your SD flash card image by following the instructions outlined on the GSRD – SD Card page on the RocketBoards.org website. However, it might be easier to modify the image available with the Cyclone V SoC

Development Kit Reference Platform.

The `c5soc linux_sd_card_image.tgz` image file is available in `ALTERAOCLSDKROOT/board/c5soc`, where `ALTERAOCLSDKROOT` points to the path of the AOCL installation.

Attention: To modify the SD flash card image, you must have root or sudo privileges.

The steps below describe the procedure for creating the `linux_sd_card_image.tgz` image from the Golden System Reference Design (GSRD) SD flash card image:

Note: To create the image from the c5soc image, perform all applicable tasks outlined in this procedure.

1. Begin with the [Index of / \(rocketboards.org\)](https://rocketboards.org/).
2. Mount the file allocation table (fat32) and extended file system (ext3) partitions in this image as loopback devices. To mount a partition, perform the following steps:
 - a. Determine the byte start of the partition within the image by invoking the `/sbin/fdisk -lu image_file` command. For example, partition number 1 of type W95 FAT has a block offset of 2121728. With 512 bytes per block, the byte offset is 512 bytes x 2121728 = 1086324736 bytes.
 - b. Identify a free loop device (for example, `/dev/loop0`) by typing the `losetup -f` command.
 - c. Assuming `/dev/loop0` is the free loop device, assign your flash card image to the loop block device by invoking the `losetup /dev/loop0 image_file -o 1086324736` command.
 - d. Mount the loop device by invoking the `mount /dev/loop0 /media/disk1` command.
Within the image file, `/media/disk1` is now a mounted fat32 partition.
 - e. Repeat steps a to d for the ext3 partition.
3. Place the unpacked `aclrte_arm32` package into the `/home/root/openc1_arm32_rte` directory on the ext3 partition of the image file.
4. Delete the hardware folder(s) of your Custom Platform, and then place the Custom Platform into the board subdirectory of `openc1_arm32_rte`.
5. Create the `init_openc1.sh` file in the `/home/root` directory with the following content:

```
export ALTERAOCLSDKROOT=/home/root/openc1_arm32_rte
export AOCL_BOARD_PACKAGE_ROOT=$ALTERAOCLSDKROOT/board/<board_name>
export PATH=$ALTERAOCLSDKROOT/bin:$PATH
export LD_LIBRARY_PATH=$ALTERAOCLSDKROOT/host/arm32/lib:$LD_LIBRARY_PATH
insmod $AOCL_BOARD_PACKAGE_ROOT/driver/aclsoc_drv.ko
```

The AOCL user runs the source `./init_openc1.sh` command to load the environment variables and the OpenCL Linux kernel driver.
6. If you need to update the preloader, the DTS files, or the Linux kernel, follow the instructions outlined in the Altera SoC Embedded Design Suite User Guide to recompile them, and update the relevant files on the mounted fat32 partition.

Attention: It is most likely that you need to update the preloader if your Custom Platform has different pin usages than those in c5soc.

Remember: If you recompile the Linux kernel, recompile the Linux kernel driver with the same Linux kernel source files. If there is a mismatch between the Linux kernel driver and the Linux kernel, the driver will not load. Also, you must enable the CMA.

Refer to Recompiling the Linux Kernel and the OpenCL Linux Kernel Driver for more information.
7. Compile the `hello_world` OpenCL example design using your Custom Platform support. Rename the `.rbf` file that the Altera Offline Compiler generates as `openc1.rbf`, and place it on the fat32 partition within the SD flash card image.

You can download the `hello_world` example design from the OpenCL Design Examples page on the Altera

website.

8. After you store all the necessary files onto the flash card image, invoke the following commands:

- a. sync
- b. umount /media/disk1
- c. umount <ext3_partition_directory>

where <ext3_partition_directory> is the directory name you use for mounting the ext3 partition in step 2 (for example, /media/disk2).

- d. losetup -d /dev/loop0
- e. losetup -d /dev/loop1

9. Compress the SD flash card image by invoking the following command:

```
tar cvfz <my_linux_sd_card_image>.tgz linux_sd_card_image
```

10. Deliver the <my_linux_sd_card_image>.tgz file inside the root directory of your Custom Platform.

11. To test your SD flash card image, perform the following tasks:

- a. Write the resulting uncompressed image onto a micro SD flash card.
- b. Insert the micro SD flash card into the SoC board.
- c. Power up the board.
- d. Invoke the aocl diagnose utility command.

Related Information

- [GSRD v14.0.2 – SD Card | Documentation | RocketBoards.org](#)
- [1. Introduction to the Intel® SoC FPGA Embedded Development Suite...](#)
- [Intel FPGA SDK for OpenCL Support Resources and Guides | Intel](#)
- Recompiling the Linux Kernel and the OpenCL Linux Kernel Driver on page 1-11
- [4.3. Querying the Device Name of Your FPGA Board \(diagnose\) \(intel.com\)](#)

Recompiling the Linux Kernel and the OpenCL Linux Kernel Driver

To run OpenCL applications on the Cyclone V SoC board, you must first compile the OpenCL Linux kernel driver and the Linux kernel. Kernel recompilation is necessary to enable the CMA.

1. Click the [GSRD v14.0 – Compiling Linux | Documentation | RocketBoards.org](#) link on the Resources page of the RocketBoards.org website to access instructions on downloading and rebuilding the Linux kernel source code.

For use with the Altera SDK for OpenCL, specify socfpga-3.13-rel14.0 as the <test_branch_name>.

2. The building process creates the arch/arm/configs/socfpga_defconfig file. Add the following lines to the bottom of this file:

```
CONFIG_MEMORY_ISOLATION=y
CONFIG_CMA=y
CONFIG_DMA_CMA=y
CONFIG_CMA_DEBUG=y
CONFIG_CMA_SIZE_MBYTES=512
CONFIG_CMA_SIZE_SEL_MBYTES=y
CONFIG_CMA_ALIGNMENT=8
CONFIG_CMA_AREAS=7
```

The `CONFIG_CMA_SIZE_MBYTES` configuration value sets the upper limit on the total number of physically contiguous memory available. You may increase this value if you require more memory.

Attention: The total amount of physical memory available to the ARM processor on the SoC board is 1 GB. Altera does not recommend that you set the CMA manager close to 1 GB.

3. Run the `make ARCH=arm socfpga_deconfig` command.
4. Run the `make ARCH=arm zImage` command. The resulting image is available in the `arch/arm/boot/ zImage` file.
5. Run the `export CROSS_COMPILE=arm-linux-gnueabi-` command.
6. Place the `zImage` file into the `fat32` partition of the flash card image.
7. To recompile the OpenCL Linux kernel driver, set the `KDIR` value in the driver's `Makefile` to the directory containing the Linux kernel source files.
8. Type the `make` command.
9. To verify that you enable the CMA successfully in the kernel, power up the SoC board and then run the `grep init_cma /proc/kallsyms` command.
CMA is enabled if the output is non-empty.

Known Issues

Currently, there are certain limitations on the usage of the Altera SDK for OpenCL with the Cyclone V SoC Development Kit Reference Platform.

1. You cannot override the vendor and board names reported by the `CL_DEVICE_VENDOR` and `CL_DEVICE_NAME` strings of the `clGetDeviceInfo()` call.
2. If the host allocates constant memory in shared DDR system (that is, HPS DDR) and it modifies the constant memory after kernel execution, the data in memory might become outdated. This issue arises because the FPGA core cannot snoop on CPU-to-HPS DDR transactions.

To prevent subsequent kernel executions from accessing outdated data, implement one of the following workarounds:

- Do not modify constant memory after its initialization.
 - If you require multiple `__constant` data sets, create multiple constant memory buffers.
 - If available, allocate constant memory in the FPGA DDR on your accelerator board.
3. The AOCL utility on ARM only supports the program and diagnose utility commands.

The flash, install and uninstall utility commands are not applicable to the Cyclone V SoC Development Kit for the following reasons:

- a. The install utility has to compile the `aclosoc_drv` Linux kernel driver and enable it on the SoC. The development machine has to perform the compilation; however, it already contains Linux kernel sources for the SoC. The Linux kernel sources for the development machine are different from those for the SoC. The location of the Linux kernel sources for the SoC is likely unknown to the AOCL user. Similarly, the uninstall utility is also unavailable to the Cyclone V SoC Development Kit.

Also, delivering `aclosoc_drv` to the SoC board is challenging because the default distribution of the Cyclone V SoC Development Kit does not contain Linux kernel include files or the GNU Compiler Collection (GCC) compiler.

- b. The flash utility requires placing a `.rbf` file of an OpenCL design onto the `FAT32` partition of the micro SD flash card. Currently, this partition is not mounted when the AOCL user powers up the board. Therefore, the

best way to update the partition is to use a flash card reader and the development machine.

4. When switching between the Altera Offline Compiler Executable files (.aocx) that correspond to different board variants (that is, c5soc and c5soc_sharedonly), you must use the AOCL program utility to load the .aocx file for the new board variant for the first time. If you simply run the host application using a new board variant but the FPGA contains the image from another board variant, a fatal error might occur.
5. The .qxp file does not include the interface partition assignments because the Quartus Prime software consistently meets timing requirements of this partition.
6. When you power up the board, its media access control (MAC) address is set to a random number. If your LAN policy does not allow this behavior, set the MAC address by performing the following tasks:
 - a. During U-Boot power-up, press any key to enter the U-Boot command prompt.
 - b. Type `setenv ethaddr 00:07:ed:00:00:03` at the command prompt.
You may choose any MAC address.
 - c. Type the `saveenv` command.
 - d. Reboot the board.

Document Revision History

Date	Version	Changes
November 2015	2015.11.02	<ul style="list-style-type: none">• Maintenance release, and changed instances of Quartus II to Quartus Prime.
May-15	15.0.0	<ul style="list-style-type: none">• In FPGA Reconfiguration, removed instruction to reprogram the FPGA core with a .rbf image by invoking the <code>cat <image_filename>.rbf > /dev/fpga0</code> command because this method is not recommended.
December 2014	14.1.0	<ul style="list-style-type: none">• Renamed the document as Altera Cyclone V SoC Development Kit Reference Platform Porting Guide.• Updated the reprogram utility to the <code>aocl program <device_name> <your_kernel_filename>.aocx</code> utility command.• Updated the diagnostic utility to the <code>aocl diagnose</code> and <code>aocl diagnose <device_name></code> utility command.• Updated the procedure in the Porting the Reference Platform to Your SoC Board section to include instructions on porting and modifying the c5soc board partition to create a timing-clean partition for the guaranteed timing closure flow.• Inserted the topic Updating a Ported Reference Platform to outline the procedures for the following tasks:<ol style="list-style-type: none">1. Excluding the hard processor system (HPS) block in the board partition2. Updating the SD flash card image• Updated the Building an SD Flash Card Image section. Recommended using version 14.0 of the Golden System Reference Design (GSRD) image as the starting point instead of the image available with SoC Embedded Design Suite (EDS).• Updated the Recompiling the Linux Kernel and the OpenCL Linux Kernel Driver section:<ol style="list-style-type: none">1. Added instruction to set the <code>CROSS_COMPILE</code> variable.2. Changed the command you run to verify that the CMA is enabled successfully.
Jul-14	14.0.0	<ul style="list-style-type: none">• Initial Release.



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References

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