

AIM ROBOTICS AimPath Simplifies Robot Teaching User Manual

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AIM ROBOTICS AimPath Simplifies Robot Teaching



Product Name: ROBOTAICIMS AIM PATH

User Manual Version: 1.0

Manufacturer: AIM Robotics APS

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Technical Data

Model: AimPath 1.3

Features

- · Easy programming of the robot
- Can be used for any purpose and all end-effectors
- · For URe series
- Convert to way-points and populate program tree

Notes

- Ensure the robot has tool on. The program requires weight on robots to function.
- Avoid touching the robot before pressing 'record'. The programming might include this small movement in the program.

Product Usage Instructions

Programming Overview

Maximum velocity for recording: Select robot speed for recording movement. This limits the speed at which the user can push or move the robot to make it easier to maintain the same speed.

Icons: The icons will be grayed out when they are irrelevant.

- record
- pause
- play
- stop

Generate Waypoints: Select this after-recording path to populate the program tree with waypoints. These points will make it easy to add small changes to the path.

Resolution: From 0.0-1.0. This should be higher the more complex the path is.

Programming Step-by-Step

- Install URCap
- 2. Install an end-effector (needed to ensure the intended operation of the program)
- 3. Enter the setting in AimPath (movement speed, fixed planes, etc.)
- 4. Press 'record'
- 5. Move the robot along part/path
- 6. Press 'stop'
- 7. Press 'play' to review and it's ready

Contact Information

Designed in Denmark by AIM Robotics APS

Website: aim-robotics.com

Email: contact@aim-robotics.com

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TECHNICAL DATA

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Model # AimPath URCap version ≥1.3

PROGRAMMING

OVERVIEW

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record

pause

play

ston

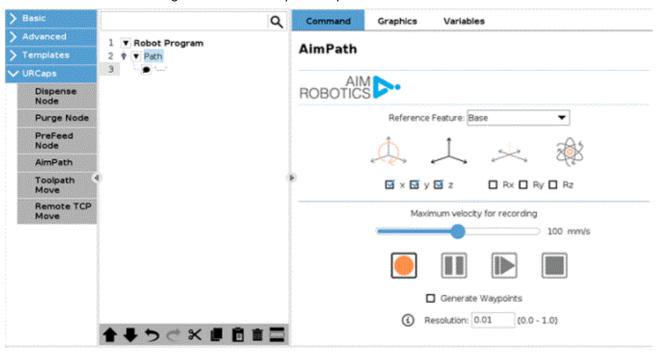
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STEP BY STEP

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DESIGNED IN DENMARK BY AIM ROBOTICS APS

AIM-ROBOTICS.COM / CONTACT@AIM-ROBOTICS.COM

Documents / Resources



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References

- Automated Robotic Dispensing Systems Aim Robotics
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- User Manual

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