

ACI I0000927 BACnet-Modbus Duct Series Instruction Manual

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ACI 10000927 BACnet-Modbus Duct Series



GENERAL INFORMATION

The BACnet MS/TP / Modbus RTU Duct Series sensor is designed for use with electronic controllers in commercial heating and cooling building management systems. The ACI BACnet MS/TP /Modbus RTU Duct Series sensor can be ordered to monitor temperature, RH, or temp/RH in commercial HVAC ductwork. It uses BACnet MS/TP or Modbus RTU for physical connection to a BAS or controller has dip switches to set addresses and baud rate, parity and stop bits (Modbus RTU only) and has onboard end-of-line termination. There is no analog output.

WIRING INSTRUCTIONS

The BACnet/Modbus Duct Series temperature sensor has a depluggable terminal block located on the front of the PCB. For ease of wiring, we recommend removing the block, wiring, and reattaching before mounting. 16 to 22 AWG two-conductor shielded cable is recommended for powering the sensors.

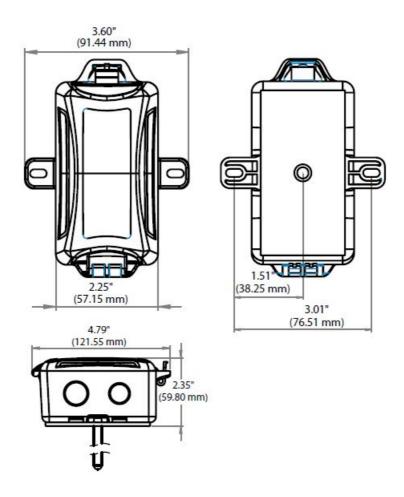
ACI recommends using Belden 3105 or a compatible cable for RS-485 communication wiring. This wire has 120 ohm input impendence. The terminal blocks allow for (1) or (2) wires to be connected in each position for daisy chaining. Daisy chain the RS-485 wiring and do not use "Star" or "T" wiring. Avoid running communication wires next to AC line voltage wires. These can be sources of noise that can affect signal quality.

PRECAUTIONS

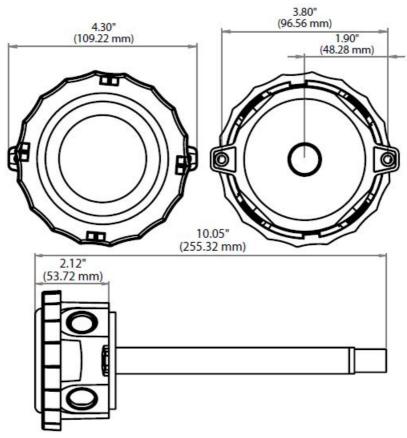
- Remove power before wiring. Never connect or disconnect wiring with power applied.
- It is recommended you use an isolated UL-listed class 2 transformer when powering the unit with 24 VAC.
 Failure to wire the devices with the correct polarity when sharing transformers may result in damage to any device powered by the shared transformer.

FIGURE 1: ENCLOSURE DIMENSIONS

PLASTIC BOX (-PB): TEMP. ONLY



EURO (-EH): RH and RH/TEMP.



- DO NOT RUN THE WIRING IN ANY CONDUIT WITH LINE VOLTAGE (24/120/230 VAC).
- If the 24 VDC or 24VAC power is shared with devices that have coils such as relays, solenoids, or other inductors, each coil must have a MOV, DC/AC Transport, Transient Voltage Suppressor (ACI Part: 142583), or diode placed across the coil or inductor. The cathode, or banded side of the DC Transorb or diode, connects to

the positive side of the power supply. Without these snubbers, coils produce very large voltage spikes when de-energizing which can cause malfunction or destruction of electronic circuits.

MOUNTING INSTRUCTIONS

For optimal readings, follow these tips:

- The sensor should be mounted in the middle of the duct where air circulation is well mixed (no stratification), and not blocked by obstructions. Stratification and obstructions can cause sensing errors. An example is downstream from a heating or cooling coil.
- Duct probe should be placed (3) to (4) duct segments down from any bend or obstructions and away from 90° bends.
- Mount the sensor on the top or sides of ductwork; mounting on the bottom risks damage due to moisture.

FIGURE 2: LAYOUT

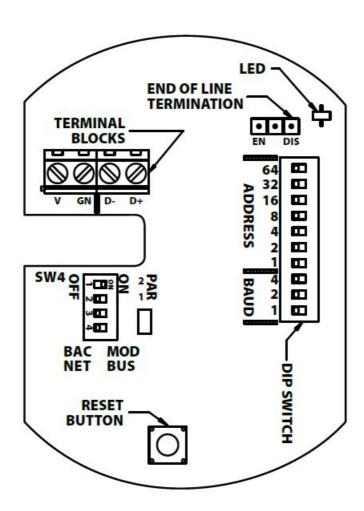


TABLE 1: WIRING CONNECTIONS

TERMINAL BLOCKS	CONNECTIONS	
+V	Power Supply Positive 8-34VDC / 10-28VAC	
GN	Power Supply Common or Ground	
D-	EIA-485 Data Negative	
D+	EIA-485 Data Positive	

The BACnet/Modbus RTU Duct Temperature-only sensor uses the Plastic Box (-PB) enclosure. Alternatively, the Euro (-EH) enclosure is used for the Relative Humidity (RH) sensor and RH/Temperature Combo sensor (see FIGURE 1). Be sure to follow the instructions listed for your enclosure.

PLASTIC BOX (-PB) ENCLOSURE INSTALLATION

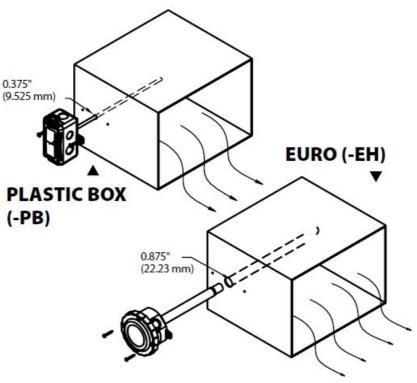
Drill a 3/8" hole in the duct and insert the probe through the hole until the foam pad is tight to the duct. Drill pilot holes for the (2) mounting screws. Use the enclosure flange as a guide, or use the dimensions listed on page 1 to measure out. Now fasten and insert (2) screws #8 x ¾" TEK (provided and recommended) through the mounting holes in the flange and tighten until the unit is held firmly to the duct. Refer to the wiring instructions (p. 2) to make the necessary connections. After wiring, shut the cover of the enclosure. *Reference FIGURE 2

EURO (-EH) ENCLOSURE INSTALLATION

Drill a 7/8" hole in the duct and insert the probe through the hole until the foam pad is tight to the duct. Drill pilot holes for the (2) mounting screws. Use the enclosure flange as a guide, or use the dimensions listed on page 1 to measure out.

Now fasten and insert (2) screws #8 x $\frac{3}{4}$ " TEK (provided and recommended) through the mounting holes in the flange and tighten until the unit is held firmly to the duct.

FIGURE 3: DUCT MOUNTING



MOUNTING INSTRUCTIONS

Refer to the wiring instructions (p. 2) to make the necessary connections. After wiring, twist the cover until the

BACnet MS/TP and Modbus RTU INTERFACE

The BACnet Master-Slave/Token-Passing (MS/TP) and Modbus Remote Terminal Unit (RTU) data link protocol uses EIA-485 as a two-wire, daisy chain network. A branch is a discrete chain of devices connected to a controller. The max number of devices per segment is 32, as per the BACnet and Modbus specifications. 4000 ft (1219.2 m) is the maximum recommended length for a segment, which includes all devices from the controller to the last device in the daisy chain.

BACnet or Modbus RTU protocol selection is done via SW4 switch. Place dipswitch #4 to the OFF position for BACnet and the ON position for Modbus. Refer to FIGURE 4. ACI's BACnet sensors are master devices. Only master nodes are allowed to send and receive tokens on the MSTP network. ACI's Modbus RTU sensors are slave devices. Only one master is connected to the bus and several slave nodes are connected to the same trunk. The Master initiates communication. The slave nodes only respond to a request from the Master. Slave nodes do not communicate with each other.

Each branch must have all devices connected with (+) connected to (+) and (-) connected to (-). If a shielded cable is used, this is not to be connected to the devices. The shielded cable should only be connected on one end to earth ground, usually at the controller. The start and end of each branch should have a termination resistor at the device level or at the controller. Each device must be configured for the correct baud rate and have a unique address in each branch. The baud rate for the branch is set by the controller. This product has auto-baud for ease of network configuration but setting the baud rate using the DIP switches is recommended. Note: Auto-baud feature does not function when Modbus is the selected protocol.

FIGURE 4: SW4 DIPSWITCH SETTINGS

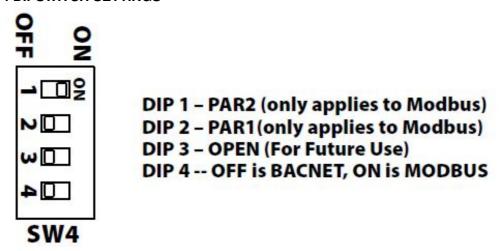


TABLE 2: BAUD RATE SELECTION

BAUD RATE	SW 8	SW 9	SW 10
Auto-Baud	0	0	0
9600	0	0	1
19200	0	1	0
38400	0	1	1
57600	1	0	0
76800	1	0	1
Reserved	1	1	0

Note: Auto-Baud not available for Modbus RTU.

BAUD RATE SELECTION

By default, BACnet Protocol and Auto-Baud is factory set. If the sensor is field adjusted for Modbus RTU, the baud rate should be selected at this time to match the Master configuration. If Modbus RTU protocol is selected it is recommended the sensor's unique address is selected at this time. Switches 8-10 are used to set the BACnet and Modbus baud rate. Refer to TABLE 2 for switch settings. Where (0) is OFF and (1) is ON. If the system's baud rate is known, it is recommended to set the specific baud rate to match the system. If the device is powered when a change is made, the device must be power cycled or reset for changes in baud rate to be made.

EOL TERMINATION RESISTANCE SELECTION

RS-485 requires that the last device in a chain have a termination resistor. This is controlled using a jumper in the EN (enabled) position marked on FIGURE 5. When the jumper is set to EN (enabled), a 120Ω resistance is added in parallel to the data line. When the jumper is set to DIS (disabled), the resistance is not added. By default, the jumper is placed in the DIS (disabled) position.

FIGURE 5: EOL TERMINATION JUMPERS





END OF LINE TERMINATION DISABLED



RESET

The reset button can be used to reset the device without disconnecting power. The location of this button is shown in FIGURE 2 ~P.2°.

LED INFORMATION

One LED indicates four statuses. Solid green shows that power is good, but no data is transmitting. A solid Amber indicates that auto-baud is set and no data has been received to set a baud rate. Green/Amber flashing indicates data is being transmitted or received. Solid Red LED status indicates an error state, usually loss of communication on the network. If BACnet is the selected protocol, and this status remains for 10 times the APDU timeout, the device will automatically reset. If this state remains longer than that, reset the device.

ADDRESS SELECTION

Switches 1-7 are used to set the BACnet and Modbus addressing. Refer to TABLE 3 for switch settings. Each device in a network branch must have a unique address. The value of each position is printed on the board. By default, the address is (0). Note: (0) cannot be used if Modbus RTU protocol is selected and will require a unique address. If the device is powered when a change is made, the device must be power cycled or reset for changes in address to be made.

TABLE 3: ADDRESS SELECTION

	SW 1	SW 2	SW 3	SW 4	SW 5	SW 6	SW 7
ADDRESS	(64)	(32)	(16)	(8)	(4)	(2)	(1)
0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	1
12	0	0	0	1	1	0	0

DEVICE CONFIGURATION THROUGH BACnet

DEVICE INSTANCE

The Device Instance, by default, is 1035000 plus the Address. For example, an Address of 21 results in a default address of 1035021. This can be changed once the device is connected to the network, but each device instance must be unique within the network, not just this segment.

DEVICE NAME

By default, the device name is based on the type of device and the address. The device name can be a character string up to (32) characters in length. This can be changed once the device is connected to the network. For example: Temperature Sensor - 034. The device name must be unique throughout the entire BACnet network, not just this segment.

TABLE 4: UNIT SETTING

UNITS	VALUE
°F	64
К	63
°C	62

TEST MODE BACnet

For the Sensor objects (Al0 and Al1), a test mode can be set by writing the Boolean value true to the "out-of-service" property. Then the present value can be set to any valid test value the user requires. This allows a user to test reactions to specific values returned by this device.

DEVICE LOCATION

The device location is optional but is intended to allow for a further definition of the device's location. The device location can be a character string up to 64 characters in length.

DEVICE DESCRIPTION

By default, the device description is optional but is intended to allow for further information about the device or its environment. The device location can be a character string up to 64 characters in length.

TEMPERATURE UNITS CONFIGURATION

For temperature, the units of measure can be configured using BACnet. By writing to the units property of the temperature sensor (AI0), the reported temperature units can be changed. TABLE 4 shows the values to write.

TEMPERATURE AND RH OFFSET

This device allows for a temperature offset of +/-5C (9F) and an RH offset of +/-10%. By default, these values are

set to 0, meaning no offset is added. These are set by writing to the present value of the Temperature Calibration Offset (AV0) or RH Calibration Offset (AV1). The value written must be within the specified range or an error will be returned. To set back to factory settings, write any changed values to 0.

TABLE 5: BACnet OBJECT TABLE

OBJECT T YPE	OBJECT I	OBJECT NAME	RANGE	BACnet ENGINEERING UNI TS	PIC STATEMENT QR
Device		BN211x0	0-419430 2		
Analog	AI-0	Temperature Sens or	34.7 – 12 2.0	degrees-Fahrenheit (64) – def ault	同學學學同
Inputs	AI-1	RH Sensor	0.0 – 95. 0	percent-relative-humidity (29)	
Analog Values	AV-0	Temperature Calibration Offset	-9.0 – 9.0	delta-degrees-Fahrenheit (12 0)	
	AV-1	RH Calibration Off set	-10.0 - 10.0	percent-relative-humidity (29)	

Note:

The table shows all objects for Temperature and RH. If you have a Temperature only model, the RH objects(Al-1 and AV-1) will not be present. If you have a RH-only model, the Temperature objects (Al-0 and AV-0) will not be present.

DEVICE CONFIGURATION THROUGH MODBUS RTU

MODBUS RTU DATA BITS, PARITY, AND STOP BITS SELECTION

Confirm Modbus Protocol is selected via dipswitch #4 on SW4 – see FIGURE 4. The device that requests information is called the Modbus Master and the devices giving the information are Modbus Slaves. The Modbus sensors are slave devices and the number of Data Bits needs to be the same as in the Master device configuration. ACI's Modbus RTU sensors utilize 8 data bits during communication exchange.

Parity and stop-bit selection is performed via the SW4 switch located on the board. Dispatches #1 and #2 are adjusted to select the parity and stop bits – see TABLE 6. Where (0) is OFF and (1) is ON. If the BACnet protocol is selected these dipswitches are irrelevant.

TEST MODE Modbus RTU

There are 5 data values in test mode. Coil 1001, Holding Registers (HR) 1001 and 1002, and the Input Registers (IR) 0003 and 0004 for Temp and RH values. When Coil 1001 is enabled, reading IR 0003 and 0004 will respond with the values in HR 1001 and 1002, otherwise, they will respond with the actual sensor values. The general process for this is to write initial test values to HR 1001 and 1002, Enable Coil 1001, and then read as normal from IR 0003 and 0004. While Coil 1001 is enabled, it is possible to write a change of value to IR 1001 and 1002, which will be reflected in the next read from IR 0003 and 0004. When testing is completed, disable Coil 1001. The status of Coil 1001 and HR 1001 and 1002 are not persistent between reset/power cycle.

TABLE 6: PARITY AND STOP BITS

PAR 2	PAR 1	Mode (Databits-Parity-Stop Bits)
0	0	8-Even-1
0	1	8-Odd-1
1	0	8-None-2
1	1	8-None-1 (Non-Standard)

MODBUS RTU MODEL

Modbus data model:

Four (4) primary data tables (addressable registers)

- Discrete Input (read-only bit).
- Coil (read/write bit).
- Input register (read-only 16-bit word, interpretation is up to application).
- Holding register (read/write the 16-bit word).

MODBUS RTU MAP

REFERENC E	ADDRES S	NAME	DESCRIPTION
COILS (CL)			
1001	1000	Test Mode Enable	0 = Disable Test Mode. IR3 and IR4 will read with current Sens or Value. 1 = Enable Test Mode. IR3 and IR4 will read with the values st ored in HR1001 and HR1002.
INPUT REGIS	STER (IR)	•	
1	0	Sensors Present	For each bit location: 0 = Sensor not present 1 = Sensor present Bit 0 - Temperature Sensor Bit 1 - RH sensor
2	1	Reserved	N/A
3	2	Temperature Sens or Value	For example, a value of 312 would represent 31.2 Degrees of t he units selected in HR1. Signed Integer.
4	3	RH Sensor Value	For Example: A value of 429 would represent 42.9% Relative Humidity.

INPUT REGISTER °IR,

INPUT REGISTER (IR)

2001	2000	Temperature Rang e Min	Temperature range Minimum value (Tenths). Signed Integer.
2002	2001	Temperature Rang e Max	Temperature range Maximum value (Tenths). Signed Integer.
2003	2002	RH Range Min	Relative Humidity range Minimum value (Tenths)
2004	2003	RH Range Max	Relative Humidity range Maximum value (Tenths)
9001	9000	Unsigned Integer Test Value	Always reads a value of 54321. For testing proper communicat ion and interpretation of values.
9002	9001	Signed Integer Te st	Always reads a value of -12345. For testing proper communication and interpretation of values.
9003 Thru 9006	9002 Thru 9005	Test String Test Va	Always reads a string value of "-123.45" (Null terminated). For testing proper communication and interpretation of values.
9007 Thru 9010	9006 Thru 9009	Serial Number	Non-null terminated character string of the Serial Number. For example, "12345678"
9011 Thru 9016	9010 Thru 9015	Firmware Version	Non-null terminated character string of the Firmware Version. For example, "02.00.000.90"
HOLDING R	⊥ EGISTER (HI	ן	<u> </u>
1	0	Temperature Units	Value – Units: 62 – Degrees Celsius 63 – Degrees Kelvin 64 – Degrees Fahrenheit
2	1	Temperature Offse t Value	Temperature Offset Value (Tenths) Signed Integer. User can set an offset that will be added to Temperature senso r and reflected in IR3. Range of -5.0 to 5.0 degrees Celsius/de grees Kelvin (-9.0 to 9.0 degrees Fahrenheit). For example, writing -16 would add an offset of -1.6 degrees.
3	2	RH Offset Value	Relative Humidity Offset (Tenths) User can set an offset that will be added to RH sensor and reflected in IR4. Range of -10.0 to 10.0 %RH. For example, writing -16 would add an offset of -1.6 %RH.
1001	1000	Test Mode Temper ature Value	User can set what temperature value (Tenths) that would be re turned when reading IR3 and Test Mode is Enabled in CL1001. For Example -400 would be -40.0.
1002	1001	Test Mode RH Value	User can set what RH value (Tenths) that would be returned w hen reading IR4 and Test Mode is Enabled in CL1001.

9000 Thru 9015	Device Name	Device Name, Device Location, and Device Description are us er settable character strings (Null terminated) that can be used to allow for system customization and device identification.
9016 Thru		For example:
9047	Device Location	Device Name (Modbus 9001 thru 9016) could be set to a syste m ID: "S2253"
9048 Thru	Device	Device Location (Modbus 9017 thru 9048) could be set to: "Building 5, Floor 2, Duct 3"
9079	Description	Device Description (Modbus 9049 thru 9080) could be set to: "Cold air return sensor"
	9015 9016 Thru 9047 9048 Thru	9015 Device Name 9016 Thru 9047 Device Location 9048 Thru Device

PRODUCT SPECIFICATIONS

Supply Voltage:	12 to 36 VDC / 24 VAC +/- 10%, 50/60 Hz (Reverse Polarity Protected)
Current Consumption:	25 mA maximum (0.67 VA)
Number Temperature Sensing Points:	One
Operating Temperature Range: Tra nsmitter:	-22 to 176°F (-30 to 80°C)
Sensor (Temp-Only):	-40 to 302°F (-40 to 150°C)
Sensor (RH and Temp/RH):	-40 to 176°F (-40 to 80°C)
Temperature Measurement Accura cy:	@ 77°F (25°C): +/- 1.0°F (+/- 0.5°C)
Temperature Calibration Offset:	+/- 9°F (+/- 5°C) (Field Configurable)
Number RH Sensing Points:	One
RH Measurement Range:	0 to 100%
RH Measurement Accuracy:	@ 77°F (25°C): +/- 2% from 10 to 90% RH
RH Calibration Offset:	+/- 10% RH (Field Configurable)
Temperature / RH Update Rate:	4 seconds
Communication Protocol:	BACnet MS/TP or Modbus RTU = Field Selectable; EIA RS-485
Sensor Addresses:	0 to 127 (0 (Default – Must be changed if Modbus RTU is selected prot ocol); Field Selectable)

Supported Baud Rates:	Auto Baud (Default, BACnet Only), 9600, 19200, 38400, 57600, 76800, 115200 (Field Selectable)
Device Instance Number:	1035000 + Address (example: Address 127 = 1035127; Field Configura ble)
Parity (Modbus RTU)	None/Even/Odd = Field Selectable
Stop Bits (Modbus RTU)	1 or 2 = Field Selectable
Data Bits (Modbus RTU)	8
Connections / Wire Size:	Screw Terminal Blocks / 16 AWG (1.31 mm2) to 22 AWG (0.33 mm2)
Terminal Block Torque Rating:	0.45 lbf-in (0.5 Nm) nominal
Storage Temperature Range:	-40 to 185°F (-40 to 85°C)
Operating Humidity Range:	10 to 95% RH, non-condensing
Sensing Probe & Filter Material:	304 Stainless Steel Diameter: 0.750" (19.05 mm)
Enclosure Specifications:	"-PB" Enclosure: ABS Plastic, UL94-HB, Plenum Rated "-EH" Enclosure: ABS Plastic with UV Protectant, UL94-V0
Foam Pad Material / Flammability:	Neoprene/EPDM/SBR Polymer / UL94-HBF; FMVSS-302; MIL-R-6130 C

WARRANTY

The ACI BACnet and Modbus RTU Room Series temperature sensors are covered by ACI's Five (5) Year Limited Warranty, which is located in the front of ACI'S SENSORS & TRANSMITTERS CATALOG or can be found on ACI's website: www.workaci.com.

W.E.E.E. DIRECTIVE

At the end of their useful life, the packaging and product should be disposed of via a suitable recycling center. Do not dispose of with household waste. Do not burn.

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Documents / Resources



ACI 10000927 BACnet-Modbus Duct Series [pdf] Instruction Manual 10000927 BACnet-Modbus Duct Series, 10000927, BACnet-Modbus Duct Series, Modbus Duct Series, Modbus

References

- MorkACI | Engineering a better sensor solution.
- @ Building Automation Sensors | Automation Components, Inc.

Manuals+,